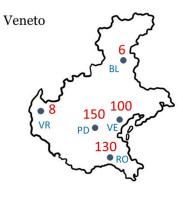
HOMEWORK 2

k-center with outliers: motivation



Red numbers = potential customers

If you must open 3 stores, where would you open them?

If you used k-center (with k=3) to select the store locations, what would be the result?

k-center with outliers: problem

Input Set P of N points from (M, d), integers $k, z \in [1, N)$

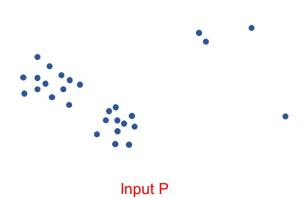
Output Set $S \subset P$ of k centers which minimize

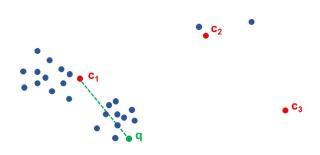
$$\bigoplus_{k \in P-Z_{c}} \Phi_{k \in P-Z_{$$

where $Z_S = z$ points of P farthest from S.

Remarks:

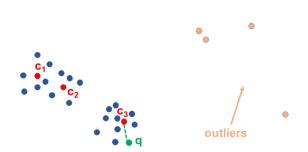
- It is the k-center problem where the objective function is allowed to disregard the distances of the z points farthest from the center. For noisy datasets, this yields a better center selection.
- The objective function is uniquely determined by P and S
- . with 2=0 we have the standard k-center problem





Optimal solution with k=3 centers

Value of objective function = $d(c_1,q)$



Optimal solution with k=3 centers and z=4 outliers

typically much less than the value of the specieve function with z=0

k-center with outliers: weighted variant

Input Set $(P, w(\cdot))$ of N weighted points from (M, d), integers $k, z \in [1, N)$

Output Set $S \subset P$ of k centers which minimize

$$\Phi_{\text{kcenter}}(P-Z_S,S),=\max_{\mathbf{x}\in P-Z_S}d(\mathbf{x},S)$$

where

 $Z_S =$ largest set of points farthest from S of total weight $\leq z$

Remark: if we consider P sorted by distance from S, then Z_S is the longest suffix of points, in the sorted sequence, of total weight $\leq z$.



										_			
	Points sorted by distance 4154 5												
distance	0	0	0	0	1.3	1.6	1.9	(2.4)	2.5	(2.7)	4.1	6.3	
weight	9	11	6	4	13	2	12	3	4	2	1	2	
=								\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	45=	fund fund e	10, 4	of o with 4	
							with >= 8 to 11						

k-center with outliers: algorithm kcenterOUT

For a radius > 0, a set $Z \subset P$, and a point x, define the ball of Z with radius r centered at x as

$$= B_{Z}(x,r) = \{ y \in Z : d(x,y) \leq r \}.$$

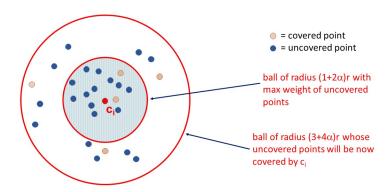
Overview of the algorithm:

- Geometric sequence of guesses $r = r_{min} \cdot 2^j$ for j = 0, 1, ..., where r_{min} is a lower bound to the optimal objective function.
 - S = current centers, Z = uncovered points, $\alpha =$ parameter.



- For each guess r, initialize $S = \emptyset$ and Z = P, and execute k iterations. In the i-th iteration:
 - add to S the point $c_i \in P$ which maximizes the total weight in $B_Z(c_i, (1+2\alpha)r)$.
 - remove from Z the points of $B_Z(c_i, (3+4\alpha)r)$

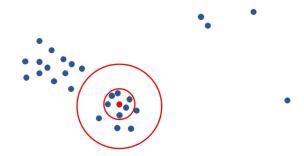
Selection of *i*-th center

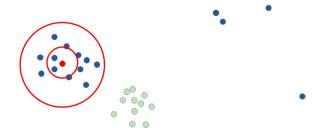


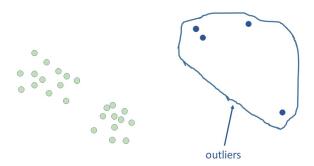
kcenterOUT (P, k, z, α) : pseudocode

```
r \leftarrow (\min \text{ distance between first } k + z + 1 \text{ points})/2; // \mathsf{t_{min}}
while (true) do
     Z \leftarrow P; S \leftarrow \emptyset; W_Z = \sum_{x \in P} w(x);
    while ((|S| < k) \text{ AND } (W_Z > 0)) do
          \max \leftarrow 0;
          foreach x \in P do
                ball-weight \leftarrow \sum_{y \in B_{\mathcal{T}}(x,(1+2\alpha)r)} w(y);
              if (ball-weight > max) then
          S \leftarrow S \cup \{\text{newcenter}\};
          foreach (y \in B_Z(\text{newcenter}, (3+4\alpha)r)) do
                remove y from Z;
              subtract w(y) from W_Z;
     if (W_Z \le z) then return S;
     else r \leftarrow 2r;
```









Quality of solution

- The value of the objective function for the returned solution S is at most $(3 + 4\alpha)r$, where r is the last guess. However, it can be smaller.
- If kcenterOUT is executed on the entire dataset with unit weights and $\alpha = 0$, then it returns a 3-approximation.
- If kcenterOUT is executed on a weighted coreset $T \subseteq P$ obtained by using k+z-center on P (or on each of L partitions of P), with $\alpha=2$, then it returns a 13-approximation.

Homework 2

Write a sequential program that:

- ① Contains a method that implements sequentially kcenterOUT (weighted variant and Euclidean points!)
- **2** Reads P, k, z input parameters and runs kcenterOUT $(P, k, z, \alpha = 0)$ using unit weights.
- **3** Computes the value of the objective function.
- 4 Reports several statistics.

Detailed specification in Moodle Exam

Homework 2: hints

- Representation of points (arbitrary dimensionality):
 - Java: class org.apache.spark.mllib.linalg.Vector, which can be manipulated through static methods offered by class org.apache.spark.mllib.linalg.Vectors.
 - Python: tuple of float
- You will not use Spark (except for the points representation in Java)
- Distance computations are the bottleneck (especially in Python!).
 You may precompute all distances: up to 10⁴ they are likely to fit it RAM, and for the MapReduce implementation (Homework 3) we won't need to run it on larger instances.
- Carefully select the representation for Z.
- Debug your code for correctness and efficiency (try to identify sources of inefficiency!)

Homework 3

In Homework 3 you will implement a 2-round MR-algorithm for k-center with outliers, where Round 1 computes a weighted coreset of size $(k+z) \cdot L$ using Farthest-First Traversal in each of L partitions, and Round 2 runs kcenterOUT on the weighted coreset.

We will provide a template for the homework and you must:

- 1 write the code for FFT (Round 1);
- 2 add code for kcenterOUT (Round 2), recycled from Homework 2;
- 3 run the algorithm on CloudVeneto, assessing running time, scalability with respect to parallelism, and quality of solution.

Details will be given soon.