

## Project: Real time drowsiness Detection.

step →

- Game plan:
- ① installing ultralytics yolo (Latest version of yolo ultralytics YOLOV8)
  - ② making detections
  - ③ Fine tuning a drowsiness model
  - ④ Real time performance.

code: 1) Install dependencies like numpy, matplotlib, cv2

2) Load model → ultralytics / YOLOv8 from torchhub.

3) Real time detection.

4) we will store some real time images and label them. (till now)

5) goal → real time video drowsiness detection (will show in final phase).

6) Improvement scope: ma'am will suggest + time for drowsiness (like what you thought).

### // classification vs object detection

- classification → one object and label per image.
- detection → multiple objects per image }  
determine location

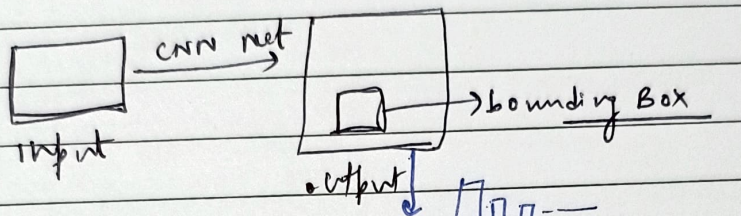
// wake approach

IP image  $\xrightarrow{\text{CNN}}$  label.



## YOLO (How Works)

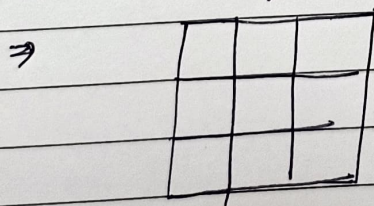
instead of making predictions on many regions of an image, YOLO passes the entire image at once.



### Steps:

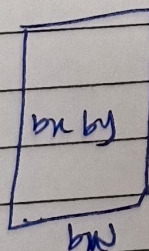
- ① Divide the image into cells with  $S \times S$  grid.
- ② Each cell produces  $B$  bounding boxes.
- ③ Return bounding boxes above confidence threshold. (All other bounding boxes have a confidence probability less than threshold say 0.90)

How Bounding boxes are encoded?



Suppose have  $3 \times 3$  image & Each cell produces one bounding box.

For each cell the CNN predicts a vector  $y$



$b_h$

$y =$

$p_c$	$\rightarrow P(\text{bounding box contain object})$
$b_x$	$\left\{ \begin{array}{l} \text{coordinate of bounding box} \end{array} \right.$
$b_y$	
$b_h$	$\left\{ \begin{array}{l} \text{width of bounding box} \\ \text{as a cell \% of the cell} \end{array} \right.$
$b_w$	
$c_1$	$\left\{ \begin{array}{l} \text{width/height} \end{array} \right.$
$c_2$	$\rightarrow P(\text{object contain class } c_i)$

④ Note: What happens if we predicts multiple bounding boxes/cell  $\rightarrow$  the argument  $y$ .