

1. Image Thresholding

Task1

Code

```
import cv2
from google.colab.patches import cv2_imshow
import numpy as np

# Thresholding function
def threshold():
    threshold= int(input("Enter threshold value: "))
    name = input("enter image path: ")
    img = cv2.imread(name,0)
    m, n = img.shape
    img_thresholded = np.zeros((m, n))
    for i in range(m):
        for j in range(n):
            if img[i, j] < threshold:
                img_thresholded[i, j] = 0
            else:
                img_thresholded[i, j] = 255

    cv2_imshow(img_thresholded)
    cv2_imshow(img)

threshold()
```

Input: high_contrast.tif



Output



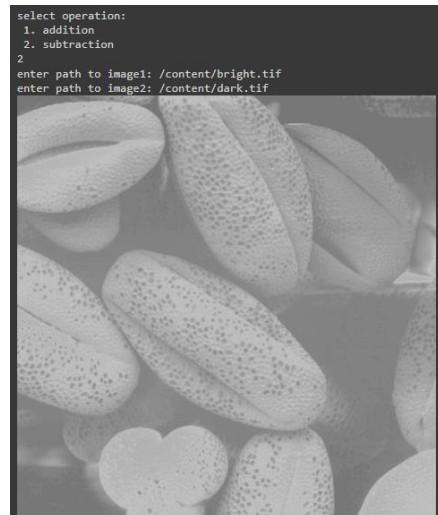
2. Image Arithmetic Operation

Lab task 2

Code

```
def arithmetic():
    op = int(input('select operation: \n 1. addition\n 2. subtraction\n'))
    if(op==1):
        path1= input('enter path to image1: ')
        path2 = input('enter path to image2: ')
        img1= cv2.imread(path1,0)
        img2 = cv2.imread(path2,0)
        add_img = cv2.add(img1,img2)
        cv2.imshow(add_img)
    elif(op==2):
        path1= input('enter path to image1: ')
        path2 = input('enter path to image2: ')
        img1= cv2.imread(path1,0)
        img2 = cv2.imread(path2,0)
        sub_img= cv2.subtract(img1,img2)
        cv2.imshow(sub_img)
    else:
        Print('invalid input')
    arithmetic()
```

Output



3. Spatial Filtering

1. A) Log Transform

Code

```
def log_transform():
    path = input('Enter image path: ')
    image = cv2.imread(path,0)

    c = 255 / np.log(1 + np.max(image))
    log_image = c * (np.log(image + 1))

    log_image = np.array(log_image, dtype = np.uint8)

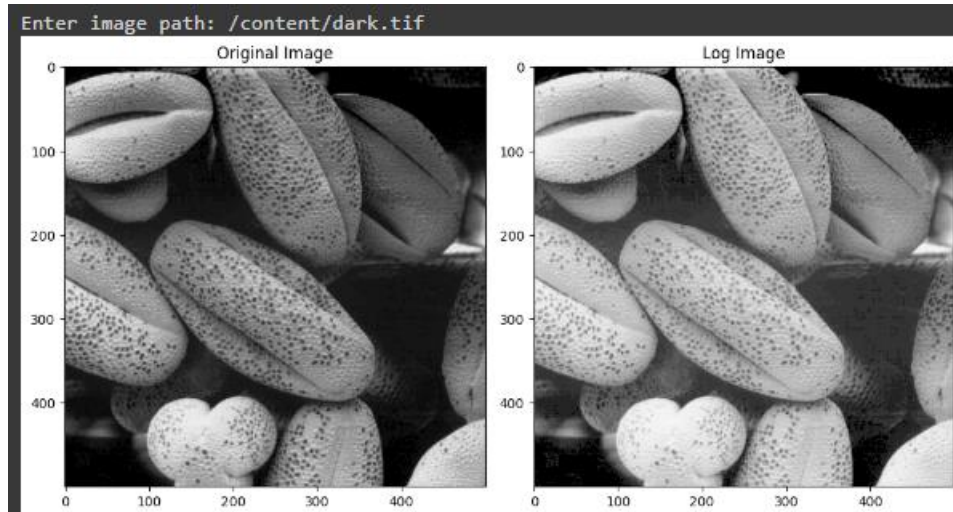
    plt.figure(figsize=(10, 5))

    plt.subplot(1, 2, 1)
    plt.imshow(image ,cmap= 'gray')
    plt.title('Original Image')

    plt.subplot(1, 2, 2)
    plt.imshow(log_image, cmap= 'gray')
    plt.title('Log Image')

    plt.tight_layout()
    plt.show()
```

Output

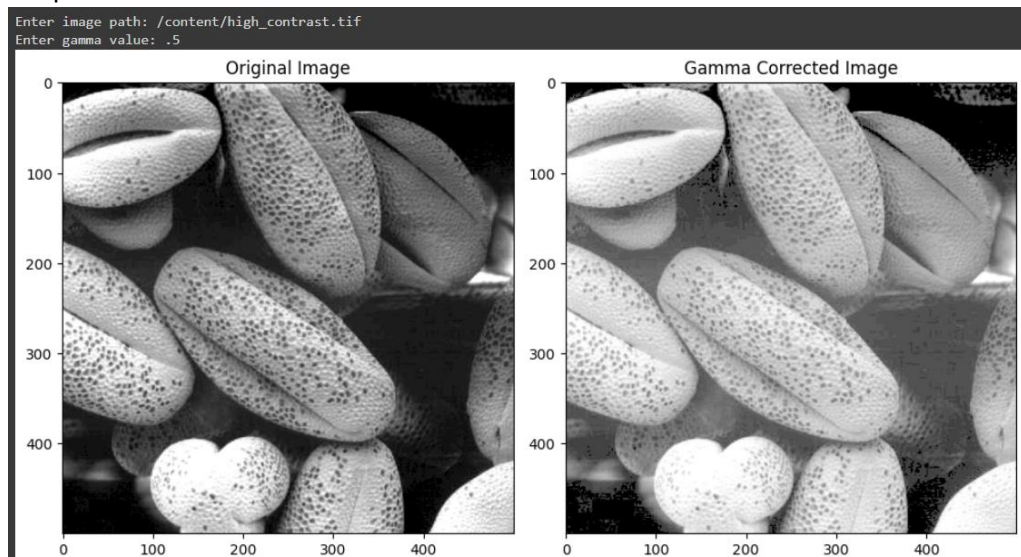


B) Power Transform

Code

```
def power_transform():  
    path = input('Enter image path: ')  
    gamma = float(input('Enter gamma value: '))  
    img = cv2.imread(path,0)  
    gamma_corrected = np.array(255*(img / 255) ** gamma, dtype = 'uint8')  
  
    plt.figure(figsize=(10, 5))  
    plt.subplot(1, 2, 1)  
    plt.imshow(cv2.cvtColor(img, cv2.COLOR_BGR2RGB))  
    plt.title('Original Image')  
  
    plt.subplot(1, 2, 2)  
    plt.imshow(cv2.cvtColor(gamma_corrected, cv2.COLOR_BGR2RGB))  
    plt.title('Gamma Corrected Image')  
  
    plt.tight_layout()  
    plt.show()
```

Output



C) Contrast Stretching

Code

```
def contrast_stretch():
    def pixelVal(pix, r1, s1, r2, s2):
        if (0 <= pix and pix <= r1):
            return (s1 / r1)*pix
        elif (r1 < pix and pix <= r2):
            return ((s2 - s1)/(r2 - r1)) * (pix - r1) + s1
        else:
            return ((255 - s2)/(255 - r2)) * (pix - r2) + s2

    path = input('enter image path: ')
    img = cv2.imread(path,0)

    r1 = int(input('r1: '))
    s1 = int(input('s1: '))
    r2 = int(input('r2: '))
    s2 = int(input('s2: '))

    pixelVal_vec = np.vectorize(pixelVal)
    contrast_stretched = pixelVal_vec(img, r1, s1, r2, s2)

    contrast_stretched = np.uint8(contrast_stretched)

    plt.figure(figsize=(10, 5))
    plt.subplot(1, 2, 1)
    plt.imshow(cv2.cvtColor(img, cv2.COLOR_BGR2RGB))
    plt.title('Original Image')

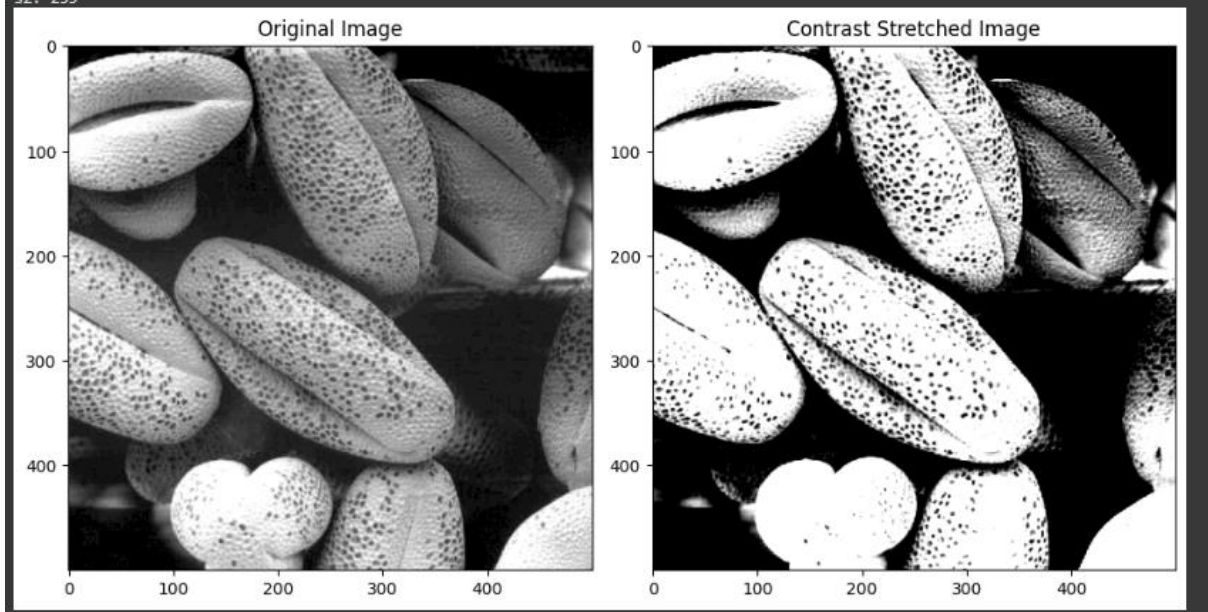
    plt.subplot(1, 2, 2)
    plt.imshow(cv2.cvtColor(contrast_stretched, cv2.COLOR_BGR2RGB))
    plt.title('Contrast Stretched Image')

    plt.tight_layout()
    plt.show()

contrast_stretch()
```

Output

```
enter image path: /content/high_contrast.tif
r1: 70
s1: 0
r2: 140
s2: 255
```

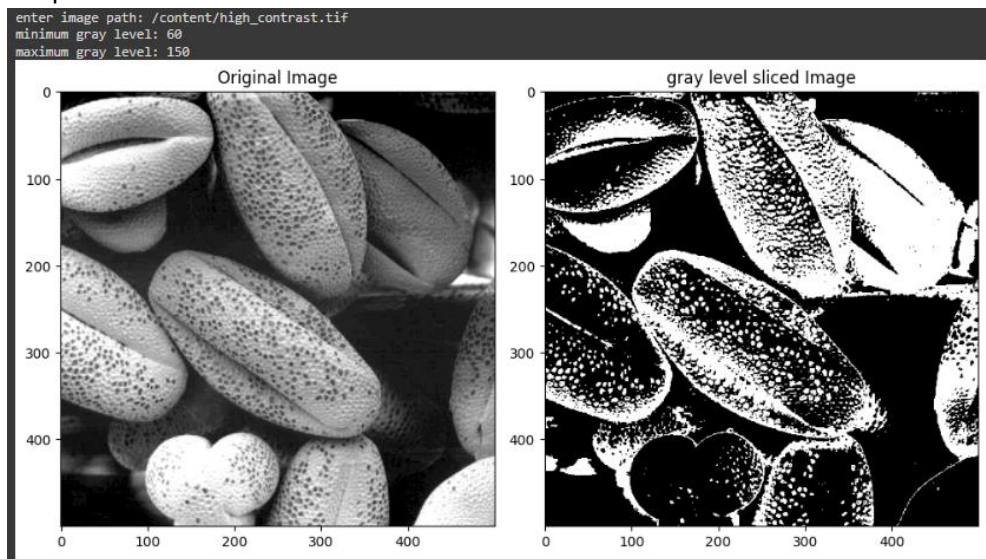


D) Gray level slicing

Code

```
def gray_lvl():  
    path = input('enter image path: ')  
    img = cv2.imread(path,cv2.IMREAD_GRAYSCALE)  
    min_gray_level = int(input("minimum gray level: "))  
    max_gray_level = int(input('maximum gray level: '))  
    gray_slice_img = np.where((img >= min_gray_level) & (img <= max_gray_level), 255, 0)  
    gray_slice_img = np.uint8(gray_slice_img)  
    plt.figure(figsize=(10, 5))  
    plt.subplot(1, 2, 1)  
    plt.imshow(cv2.cvtColor(img, cv2.COLOR_BGR2RGB))  
    plt.title('Original Image')  
  
    plt.subplot(1, 2, 2)  
    plt.imshow(cv2.cvtColor(gray_slice_img, cv2.COLOR_BGR2RGB))  
    plt.title('gray level sliced Image')  
  
    plt.tight_layout()  
    plt.show()  
  
gray_lvl()
```

Output



E) Bit Plane slicing

Code

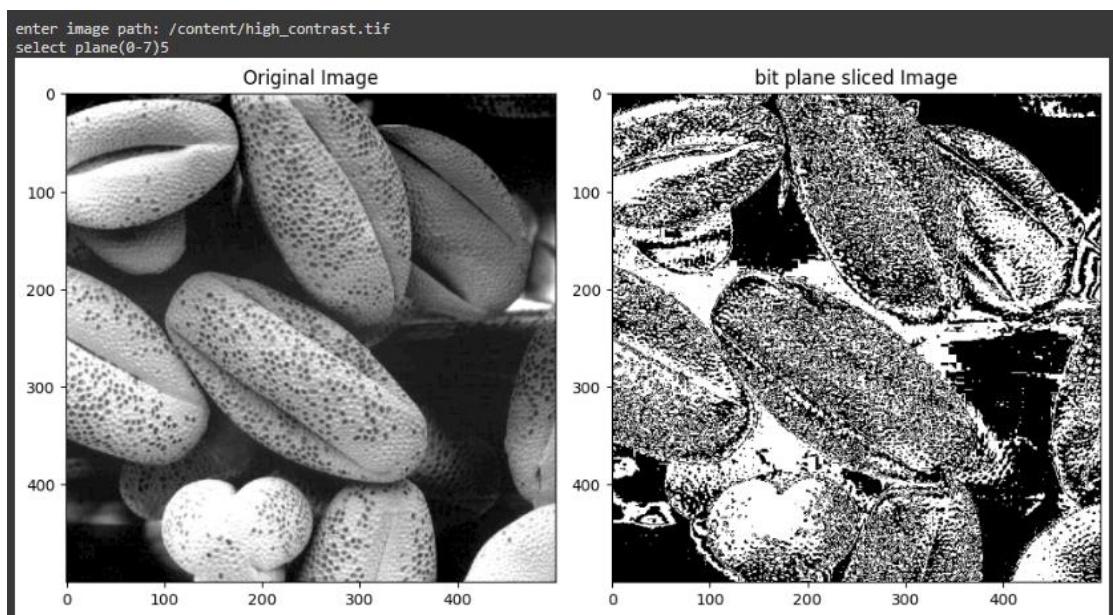
```
def bit_plane_slicing():
    path = input('enter image path: ')
    img = cv2.imread(path, cv2.IMREAD_GRAYSCALE)
    bit_plane_img = np.zeros(img.shape, dtype=np.uint8)
    bit_plane = int(input('select plane(0-7)'))
    bit_plane_img = ((img >> bit_plane) & 1) * 255

    plt.figure(figsize=(10, 5))
    plt.subplot(1, 2, 1)
    plt.imshow(cv2.cvtColor(img, cv2.COLOR_BGR2RGB))
    plt.title('Original Image')

    plt.subplot(1, 2, 2)
    plt.imshow(cv2.cvtColor(bit_plane_img, cv2.COLOR_BGR2RGB))
    plt.title('bit plane sliced Image')

    plt.tight_layout()
    plt.show()
```

Output



2. a) When $r1 = s1$ and $r2 = s2$, the contrast stretching function becomes a linear function that doesn't change the image. This is because the pixel values remain the same, i.e., the output pixel value is the same as the input pixel value. In other words, no contrast stretching is performed.
- b) When $r1 = r2$, $s1 = 0$ and $s2 = L-1$ (where L is the maximum pixel value, typically 255 for an 8-bit image), the contrast stretching function becomes undefined because mapping all pixel values to either 0 or $L-1$ is not possible. This scenario doesn't make sense in the context of contrast stretching because it doesn't provide a valid range of pixel values to stretch the contrast

4. Masking

Lab Task 04

Code

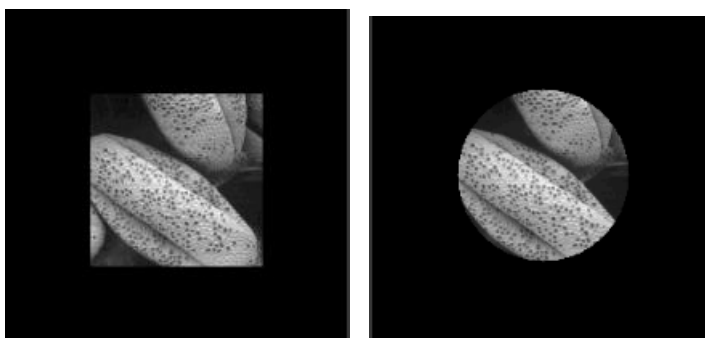
```
import cv2
import numpy as np
from google.colab.patches import cv2_imshow
def mask():
    path= input('enter input path: ')
    img = cv2.imread(path,cv2.IMREAD_GRAYSCALE)
    resized_img = cv2.resize(img, (256, 256))
    square_mask = np.zeros((256, 256), dtype="uint8")
    cv2.rectangle(square_mask, (64, 64), (192, 192), 255, -1)
    square_masked = cv2.bitwise_and(resized_img, resized_img, mask=square_mask)
    circle_mask = np.zeros((256, 256), dtype="uint8")
    cv2.circle(circle_mask, (128, 128), 64, 255, -1)
    circle_masked = cv2.bitwise_and(resized_img, resized_img, mask=circle_mask)

    cv2_imshow( resized_img)
    cv2.waitKey(0)
    cv2_imshow(square_masked)
    cv2.waitKey(0)
    cv2_imshow( circle_masked)
    cv2.waitKey(0)
    print(circle_masked.shape)
    cv2.destroyAllWindows()
```

Input



Output



5. Brightness

Lab Task 05

Code

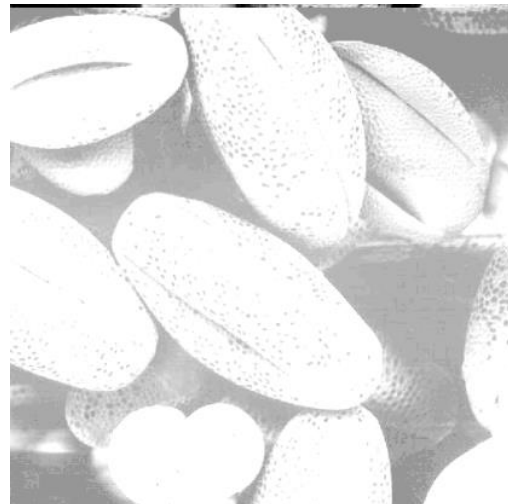
```
import cv2
import numpy as np

def addbrightness():
    path= input('Enter image path: ')
    img = cv2.imread(path, cv2.IMREAD_COLOR)
    brightness = int(input("Enter brightness value: "))
    bright_img = img.astype(np.int16) + brightness
    bright_img = np.clip(bright_img, 0, 255)
    bright_img = bright_img.astype(np.uint8)
    cv2.imshow( img)
    cv2.imshow(bright_img)
```

Input



Output



6. Histogram Processing

Lab Task 06

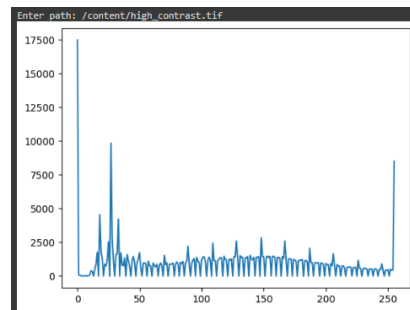
1. Histogram Calculation in OpenCV
Code

```
import cv2
import matplotlib.pyplot as plt

def cv2_histogram():
    path= input("Enter path: ")
    img = cv2.imread(path, cv2.IMREAD_GRAYSCALE)
    hist = cv2.calcHist([img], [0], None, [256], [0, 256])

    plt.plot(hist)
    plt.show()
```

Output



2. Histogram Calculation in NumPy
Code

Code

```
import numpy as np
import matplotlib.pyplot as plt

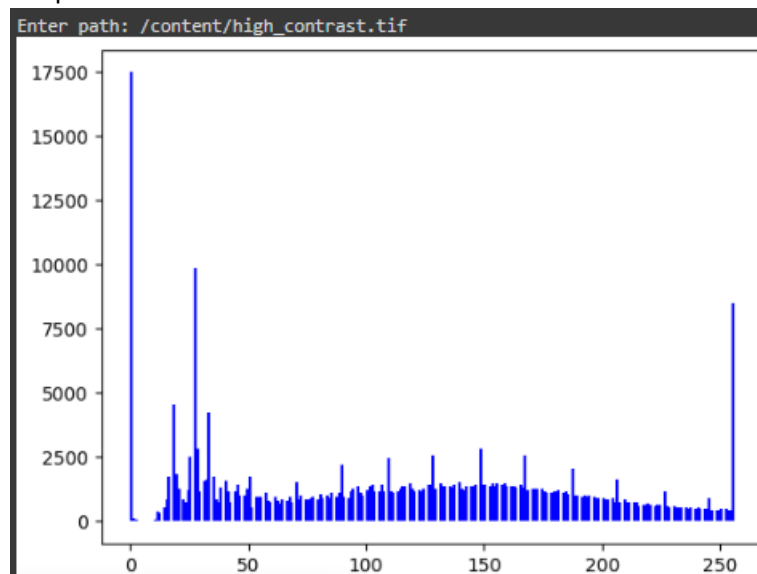
def np_histogram():
    path= input("Enter path: ")
    img = cv2.imread(path, cv2.IMREAD_GRAYSCALE)
    hist_values, bin_edges = np.histogram(img.flatten(), bins=256, range=[0,256])

    bin_centers = (bin_edges[:-1] + bin_edges[1:]) / 2

    for i in range(len(hist_values)):
        plt.vlines(bin_centers[i], ymin=0, ymax=hist_values[i], color='blue')

    plt.show()
```

Output



3.

Code

```
import cv2
import numpy as np
import matplotlib.pyplot as plt

def plot_histogram_gray(image):
    hist_values, bin_edges = np.histogram(image.flatten(), bins=256, range=[0,256])
    bin_centers = (bin_edges[:-1] + bin_edges[1:]) / 2
    for i in range(len(hist_values)):
        plt.vlines(bin_centers[i], ymin=0, ymax=hist_values[i], color='black')
    plt.show()

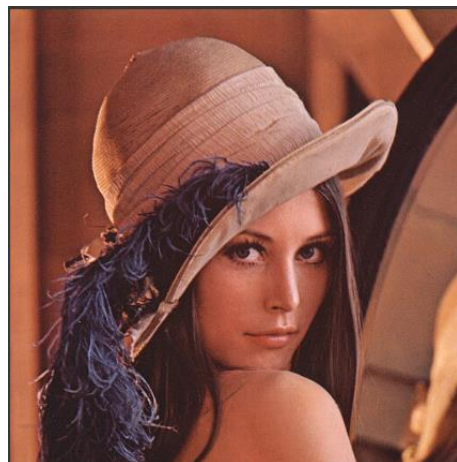
def plot_histogram_rgb(image):
    # Compute histogram for each channel
    color = ('b', 'g', 'r')
    for i, col in enumerate(color):
        hist_values, _ = np.histogram(image[:, :, i].flatten(), bins=256, range=[0,256])
        bin_centers = (np.arange(256) + 0.5)
        plt.vlines(bin_centers, 0, hist_values, color=col, lw=2)
    plt.show()
```

Inputs

Grayscale

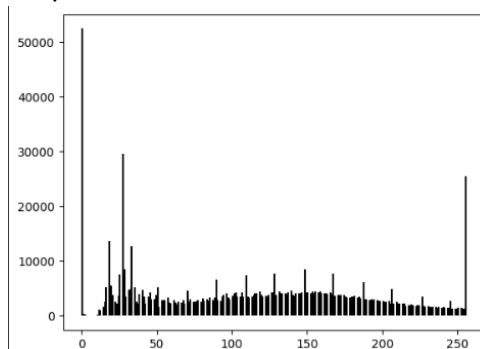


RGB

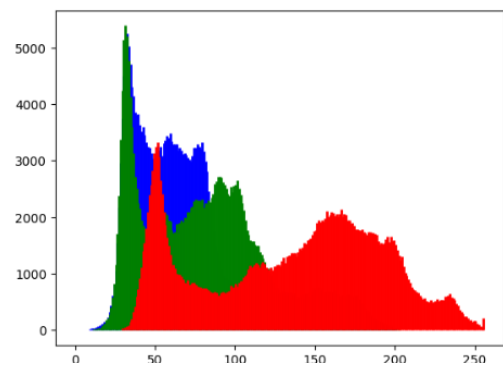


Histograms

Grayscale

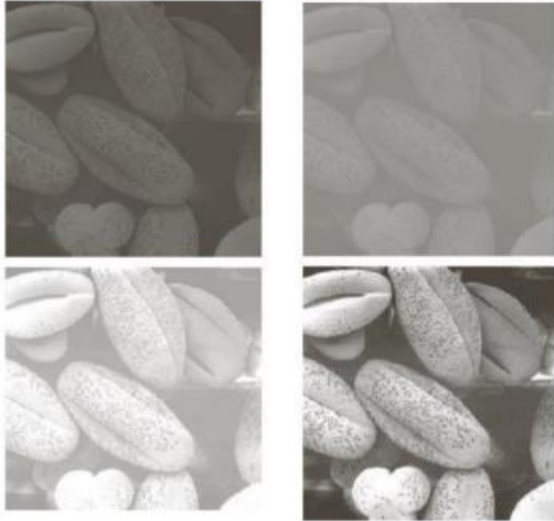


RGB



4.

Inputs



Code

```
def four_images():  
    img1= cv2.imread('/content/bright.tif',0)  
    img2= cv2.imread('/content/dark.tif',0)  
    img3= cv2.imread('/content/high_contrast.tif',0)  
    img4= cv2.imread('/content/low_contrast.tif',0)  
    plt.title('bright.tif')  
    plot_histogram_gray(img1)  
    plt.title('dark.tif')  
    plot_histogram_gray(img2)  
    plt.title('high_contrast.tif')  
    plot_histogram_gray(img3)  
    plt.title('low_contrast.tif')  
    plot_histogram_gray(img4)
```

Outputs

