

All Resources

iSchool

MCMC Robot | Paul O. Lewis Lab

← → ↻ phylogeny.uconn.edu/mcmc-robot/

100 Steps/foray

50 Step length mean

1 Step length sd/mean

1 Number of chains

all Show chain

0 Bias mean

unbiased Bias std. dev.

Hide fails

Hide trajectory

No swapping

Metropolis within Gibbs

OK

Settings

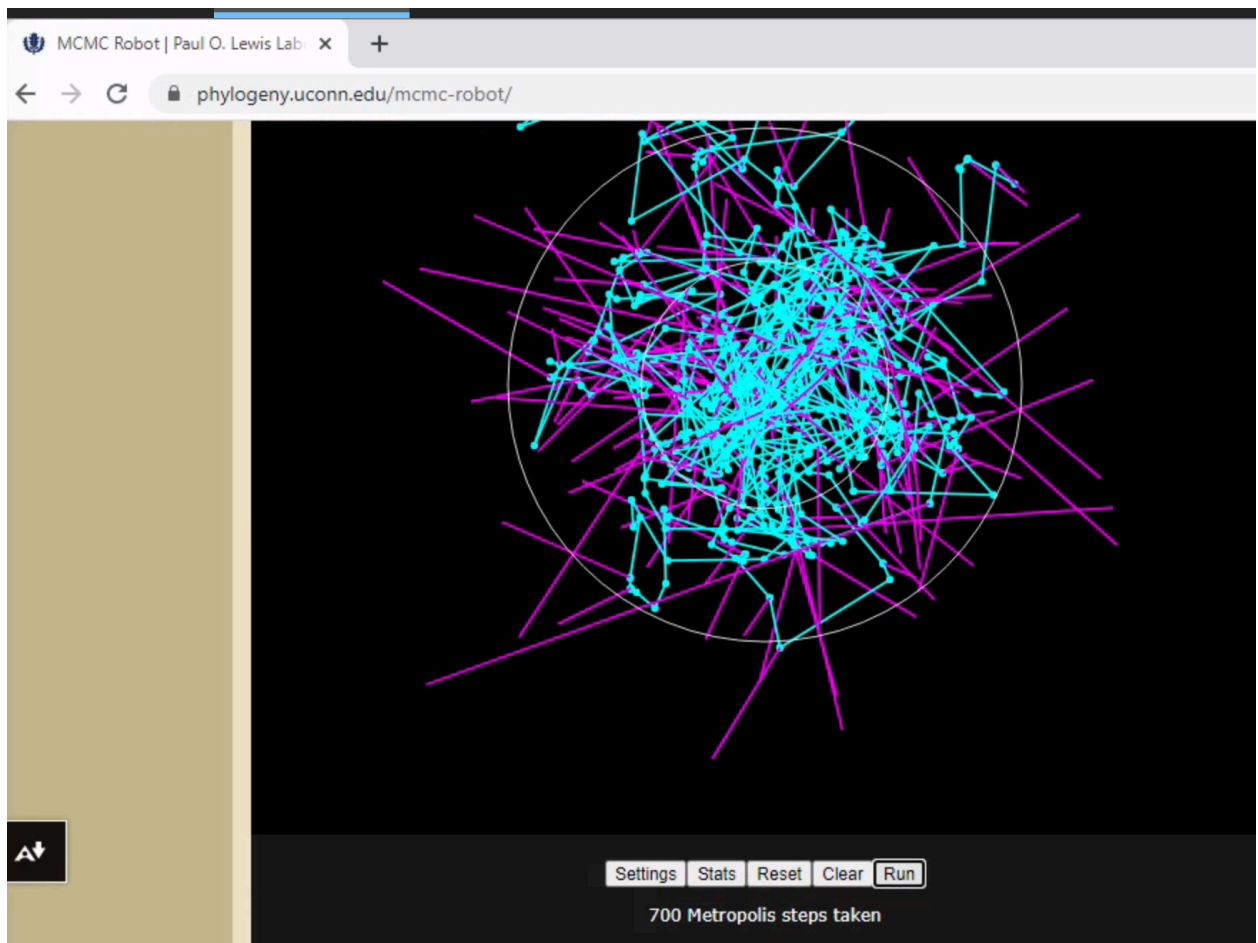
Stats

Reset

Clear

Run

Ready

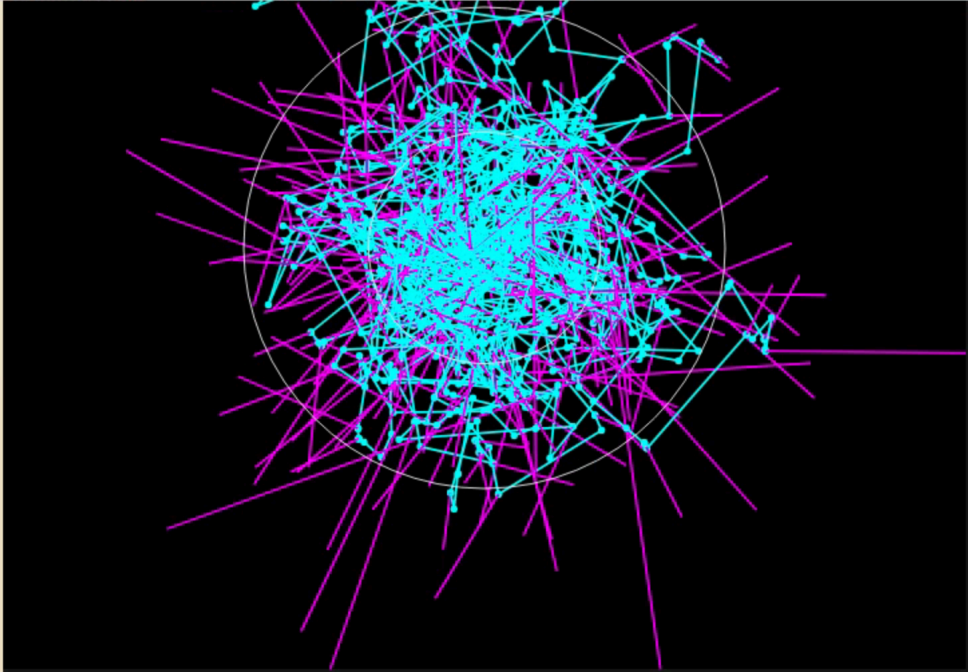


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SettingsStatsResetClearRun

1200 Metropolis steps taken