

Learning Spatial-Temporal Surrounding - Aware Correlation Filter with Mutation Sensitive Regularization via Adaptive Hybrid Label.

① Baseline Tracker (BAEF) :-

$$E(h, r) = \frac{1}{2} \sum_{k=1}^C \left\| r^k - \sum_{k=1}^C (Ph_t^k) \odot X_t^k \right\|_{2,1} + \frac{\lambda_1}{2} \sum_{k=1}^C \|h_t^k\|_F^2.$$

② Enhanced Spatial Feature Detection :-

$$E(h, r) = \frac{1}{2} \sum_{k=1}^C \left\| r^k - \sum_{k=1}^C (Ph_t^k) \odot X_t^k \right\|_{2,1} + \frac{\lambda_1}{2} \sum_{i=1}^M \|h_{i:}\|_F + \frac{\lambda_2}{2} \sum_{j=1}^N \|h_{:j}\|_F.$$

③ Surrounding - Aware :-

$$E(h, r) = \frac{1}{2} \sum_{k=1}^C \left\| r^k - \sum_{k=1}^C (Ph_t^k) \odot X_t^k \right\|_{2,1} + \frac{\lambda_1}{2} \sum_{i=1}^M \|h_{i:}\|_F + \frac{\lambda_2}{2} \sum_{j=1}^N \|h_{:j}\|_F + \frac{1}{2} \sum_{k=1}^K \left\| \sum_{d=1}^D \alpha^k X_{dt}^k \odot h_t^k \right\|_F^2$$

④ Temporal Regularization :-

$$E(h, r) = \frac{1}{2} \sum_{k=1}^C \left\| r^k - \sum_{k=1}^C (Ph_t^k) \odot X_t^k \right\|_{2,1} + \frac{\lambda_1}{2} \sum_{i=1}^M \|h_{i:}\|_F + \frac{\lambda_2}{2} \sum_{j=1}^N \|h_{:j}\|_F + \frac{1}{2} \sum_{k=1}^K \left\| \sum_{d=1}^D \alpha^k X_{dt}^k \odot h_t^k \right\|_F^2 + \frac{\lambda_3}{2} \sum_{k=1}^C \|h_t^k - h_{t-1}^k\|_F^2$$

⑤ Optimal Adaptive Hybrid Label :-

$$E(h, r) = \frac{1}{2} \sum_{k=1}^C \left\| r^k - \sum_{k=1}^C (Ph_t^k) \odot X_t^k \right\|_{2,1} + \frac{\lambda_1}{2} \sum_{i=1}^M \|h_{i:}\|_F + \frac{\lambda_2}{2} \sum_{j=1}^N \|h_{:j}\|_F + \frac{1}{2} \sum_{k=1}^K \left\| \sum_{d=1}^D \alpha^k X_{dt}^k \odot h_t^k \right\|_F^2 + \frac{\lambda_3}{2} \sum_{k=1}^C \|h_t^k - h_{t-1}^k\|_F^2 + \frac{\lambda_4}{2} \sum_{k=1}^C \|\Omega_t^k - r_t^k\|_F^2.$$

⑥ Adaptive Hybrid Label with Temporal Regularization :-

$$E(h, r) = \frac{1}{2} \sum_{k=1}^C \left\| r^k - \sum_{k=1}^C (Ph_t^k) \odot X_t^k \right\|_{2,1} + \frac{\lambda_1}{2} \sum_{i=1}^M \|h_{i:}\|_F + \frac{\lambda_2}{2} \sum_{j=1}^N \|h_{:j}\|_F + \frac{1}{2} \sum_{k=1}^K \left\| \sum_{d=1}^D \alpha^k X_{dt}^k \odot h_t^k \right\|_F^2 + \frac{\lambda_3}{2} \sum_{k=1}^C \|h_t^k - h_{t-1}^k\|_F^2 + \frac{\lambda_4}{2} \sum_{k=1}^C \|\Omega_t^k - r_t^k\|_F^2 + \frac{\phi}{2} \sum_{k=1}^C \|r_t^k - r_{t-1}^k\|_F^2.$$

Objective Function:-

$$E(\mathbf{r}) = \frac{\lambda_1}{2} \sum_{k=1}^C \left\| \mathbf{r}^k - \sum_{k=1}^C (\mathbf{P} \mathbf{h}_t^k) \odot \mathbf{x}_t^k \right\|_{2,1} + \frac{\lambda_2}{2} \sum_{i=1}^M \left\| \mathbf{h}_{i:} \right\|_F + \frac{\lambda_2}{2} \sum_{j=1}^N \left\| \mathbf{h}_{:j} \right\|_F + \frac{1}{2} \sum_{k=1}^C \left\| \sum_{d=1}^D \alpha^k \mathbf{x}_{dt}^k \odot \mathbf{h}_t^k \right\|_F^2 + \frac{\lambda_3}{2} \sum_{k=1}^C \left\| \mathbf{h}_t^k - \mathbf{h}_{t-1}^k \right\|_F^2 + \frac{\lambda_4}{2} \sum_{k=1}^C \left\| \hat{\Omega}_t^k - \mathbf{r}_t^k \right\|_F^2 + \frac{\phi}{2} \sum_{k=1}^C \left\| \mathbf{r}_t^k - \mathbf{r}_{t-1}^k \right\|_F^2.$$

We introduced the auxiliary variable $\hat{\mathbf{g}}^k = \sqrt{\tau} (\mathbf{I}_D \otimes \mathbf{F} \mathbf{P}^T) \mathbf{h}^k$.

① Subproblem - \mathbf{g} :-

$$\hat{\mathbf{g}} = \frac{1}{2} \sum_{k=1}^C \left\| \hat{\mathbf{r}}^k - \sum_{k=1}^C \hat{\mathbf{g}}_t^k \odot \hat{\mathbf{x}}_t^k \right\|_{2,1} + \frac{1}{2} \sum_{k=1}^C \left\| \sum_{d=1}^D \alpha^k \hat{\mathbf{x}}_{dt}^k \odot \hat{\mathbf{g}}_t^k \right\|_F^2 + \frac{\lambda_3}{2} \sum_{k=1}^C \left\| \hat{\mathbf{g}}_t^k - \hat{\mathbf{g}}_{t-1}^k \right\|_F^2 + \frac{\mu}{2} \left\| \hat{\mathbf{g}}_t^k - \hat{\mathbf{h}}_t^k + \frac{\hat{\Gamma}_t^k}{\mu} \right\|_F^2.$$

② Subproblem - \mathbf{h} :-

$$\mathbf{h}_i^k = \frac{\lambda_1}{2} \sum_{i=1}^M \left\| \mathbf{h}_{i:} \right\|_F + \frac{\mu}{2} \sum_{k=1}^M \left\| \mathbf{g}_{t,i}^k - \mathbf{h}_{t,i}^k + \frac{\hat{\Gamma}_{t,i}^k}{\mu} \right\|_F^2.$$

$$\mathbf{h}_j = \frac{\lambda_2}{2} \sum_{j=1}^N \left\| \mathbf{h}_{:j} \right\|_F + \frac{\mu}{2} \sum_{j=1}^N \left\| \mathbf{g}_{:j}^k - \mathbf{h}_{:j}^k + \frac{\hat{\Gamma}_{:j}^k}{\mu} \right\|_F^2.$$

③ Subproblem - \mathbf{r} :-

$$\mathbf{r} = \frac{1}{2} \sum_{k=1}^C \left\| \hat{\mathbf{r}}^k - \sum_{k=1}^C \hat{\mathbf{g}}_t^k \odot \hat{\mathbf{x}}_t^k \right\|_{2,1} + \frac{(1+\psi^2)\lambda_2}{2} \left\| \hat{\Omega}_t^k - \hat{\mathbf{r}}_t^k \right\|_2^2 + \frac{(1-\psi^2)\phi}{2} \left\| \mathbf{r}_t^k - \mathbf{r}_{t-1}^k \right\|_2^2$$

$\hat{\Omega}_t^k \rightarrow$ Optimal Adaptive Hybrid Label

$\hat{\mathbf{r}}_t^k \rightarrow$ Adaptive Hybrid Label.

① Subproblem-g:

$$g = \frac{1}{2} \sum_{k=1}^c \left\| \hat{r}^k - \sum_{k=1}^c \hat{x}_t^k \odot \hat{g}_t^k \right\|_2^2 + \frac{1}{2} \sum_{k=1}^c \left\| \sum_{d=1}^D \alpha^k \hat{x}_{dt}^k \odot \hat{g}_t^k \right\|_2^2 + \frac{\lambda_3}{2} \sum_{k=1}^c \left\| \hat{g}_t^k - \hat{g}_{t-1}^k \right\|_2^2 + \frac{\mu}{2} \sum_{k=1}^c \left\| \hat{g}_t^k - \hat{h}_t^k + \frac{\hat{r}^k}{\mu} \right\|_2^2$$

Solution:

$$\Rightarrow \frac{1}{2} \left\| \hat{r}^k - \hat{x}_t^k \hat{g}_t^k \right\|_2^2 + \frac{1}{2} \left\| \alpha^k \hat{x}_{dt}^k \odot \hat{g}_t^k \right\|_2^2 + \frac{\lambda_3}{2} \left\| \hat{g}_t^k - \hat{g}_{t-1}^k \right\|_2^2 + \frac{\mu}{2} \left\| \hat{g}_t^k - \hat{h}_t^k + \frac{\hat{r}^k}{\mu} \right\|_2^2$$

Taking derivative wrt \hat{g}_t^k & equal to zero.

$$\Rightarrow \frac{1}{2} \hat{x}_t^T \frac{\partial}{\partial \hat{g}_t^k} (\hat{x}_t^k \hat{g}_t^k - \hat{r}_t^k) + \frac{1}{2} \frac{\partial}{\partial \hat{g}_t^k} (\alpha^k \hat{x}_{dt}^k \hat{g}_t^k) + \frac{\lambda_3}{2} \frac{\partial}{\partial \hat{g}_t^k} (\hat{g}_t^k - \hat{g}_{t-1}^k) + \frac{\mu}{2} \frac{\partial}{\partial \hat{g}_t^k} (\hat{g}_t^k - \hat{h}_t^k + \frac{\hat{r}^k}{\mu}) = 0$$

$$\Rightarrow \hat{x}_t^T (\hat{x}_t^k \hat{g}_t^k - \hat{r}_t^k) + (\alpha^k \hat{x}_{dt}^k \hat{g}_t^k) + \lambda_3 (\hat{g}_t^k - \hat{g}_{t-1}^k) + \mu (\hat{g}_t^k - \hat{h}_t^k + \frac{\hat{r}^k}{\mu}) = 0$$

$$\Rightarrow \hat{x}_t^T \hat{x}_t^k \hat{g}_t^k - \hat{x}_t^T \hat{r}_t^k + \alpha^k \hat{x}_{dt}^k \hat{g}_t^k + \lambda_3 \hat{g}_t^k - \lambda_3 \hat{g}_{t-1}^k + \mu \hat{g}_t^k - \mu \hat{h}_t^k + \hat{r}^k = 0$$

Take the \hat{g}_t^k term as common.

$$\Rightarrow \hat{g}_t^k (\hat{x}_t^T \hat{x}_t^k + \alpha^k \hat{x}_{dt}^k + \lambda_3 + \mu) = \hat{x}_t^T \hat{r}_t^k + \lambda_3 \hat{g}_{t-1}^k + \mu \hat{h}_t^k - \hat{r}^k$$

$$\hat{g}_t^k = \frac{\hat{x}_t^T \hat{r}_t^k + \lambda_3 \hat{g}_{t-1}^k + \mu \hat{h}_t^k - \hat{r}^k}{\hat{x}_t^T \hat{x}_t^k + \alpha^k \hat{x}_{dt}^k + \lambda_3 + \mu}$$

② Subproblem - h_i :

(i)

$$h_i = \frac{\lambda_1}{2} \sum_{i=1}^M \|h_{i:}\|_2 + \mu/2 \sum_{i=1}^M \left\| g_{i:}^k - h_{i:}^k + \frac{\Gamma_{i:}^k}{\mu} \right\|_2^2.$$

Solution:

$$\Rightarrow h_i = \frac{\lambda_1}{2} \|h_{i:}\|_2 + \mu/2 \left\| g_{i:}^k - h_{i:}^k + \frac{\Gamma_{i:}^k}{\mu} \right\|_2^2.$$

Now taking derivative w.r.t h_i & equal to zero.

$$\Rightarrow \frac{\lambda_1}{2} \mathcal{L}(h_{i:}) + \mu/2 \mathcal{L}\left(g_{i:}^k - h_{i:}^k + \frac{\Gamma_{i:}^k}{\mu}\right) (-1) = 0$$

$$\Rightarrow \lambda_1 h_{i:}^k - \mu g_{i:}^k + \mu h_{i:}^k - \Gamma_{i:}^k = 0$$

Now take the $h_{i:}^k$ term as common.

$$\Rightarrow \mu h_{i:}^k = \mu g_{i:}^k + \Gamma_{i:}^k - \lambda_1$$

$$\Rightarrow h_{i:} = \frac{\mu g_{i:}^k}{\mu} + \frac{\Gamma_{i:}^k}{\mu} - \frac{\lambda_1}{\mu}$$

$$\Rightarrow h_{i:} = \left(g_{i:}^k + \frac{\Gamma_{i:}^k}{\mu} \right) \left(1 - \frac{\lambda_1}{\mu (g_{i:}^k + \Gamma_{i:}^k / \mu)} \right) \dots$$

$$\Rightarrow h_i = \max \left(0, 1 - \frac{\lambda_1}{\mu (g_{i:}^k + \Gamma_{i:}^k / \mu)} \right) \left(g_{i:}^k + \frac{\Gamma_{i:}^k}{\mu} \right)$$

② Subproblem - h_j :

(ii)

$$h_j = \frac{\lambda_2}{2} \sum_{j=1}^N \|h_{:j}\|_2 + \frac{\mu}{2} \sum_{j=1}^N \left\| g_{:j}^k - h_{:j}^k + \frac{\tau_{:j}^k}{\mu} \right\|_2^2.$$

Solution:

$$\Rightarrow h_j = \frac{\lambda_2}{2} \|h_{:j}\|_2 + \frac{\mu}{2} \left\| g_{:j}^k - h_{:j}^k + \frac{\tau_{:j}^k}{\mu} \right\|_2^2.$$

Now taking derivative with.r.t h_j equal to zero.

$$\Rightarrow \frac{\lambda_2}{2} \frac{d}{dh_{:j}} (h_{:j}) + \frac{\mu}{2} \frac{d}{dh_{:j}} \left(g_{:j}^k - h_{:j}^k + \frac{\tau_{:j}^k}{\mu} \right)^2 = 0$$

$$\Rightarrow \cancel{\frac{\lambda_2}{2}} \lambda_2 (h_{:j}) + \mu \left(g_{:j}^k - h_{:j}^k + \frac{\tau_{:j}^k}{\mu} \right) (-1) = 0$$

$$\Rightarrow \lambda_2 h_{:j} + \mu g_{:j}^k + \mu h_{:j}^k - \tau_{:j}^k = 0$$

Now take the $h_{:j}^k$ term as common.

$$\Rightarrow \mu h_{:j}^k = \mu g_{:j}^k + \tau_{:j}^k - \lambda_2$$

$$\Rightarrow h_{:j} = \frac{\mu g_{:j}^k}{\mu} + \frac{\tau_{:j}^k}{\mu} - \frac{\lambda_2}{\mu}$$

$$\Rightarrow h_{:j} = \left(g_{:j}^k + \frac{\tau_{:j}^k}{\mu} \right) \left(1 - \frac{\lambda_2}{\mu \left(g_{:j}^k + \frac{\tau_{:j}^k}{\mu} \right)} \right)$$

$$\Rightarrow h_j = \max \left(0, 1 - \frac{\lambda_2}{\left(g_{:j}^k + \frac{\tau_{:j}^k}{\mu} \right)} \right) \left(g_{:j}^k + \frac{\tau_{:j}^k}{\mu} \right)$$

③ Sub problem - r!

$$\frac{1}{2} \|\hat{r}_t - \hat{x}_t^T \hat{g}_t\|_2^2 + \frac{(1+\psi^2)\lambda_2}{2} \|\hat{\Omega} - \hat{r}\|_2^2 + \frac{(1-\psi^2)\phi}{2} \|\hat{r}_t^k - \hat{r}_{t-1}^k\|_2^2.$$

Solution:

$$\Rightarrow \frac{1}{2} \|\hat{r}_t - \hat{x}_t^T \hat{g}_t\|_2^2 + \frac{(1+\psi^2)\lambda_2}{2} \|\hat{\Omega} - \hat{r}\|_2^2 + \frac{(1-\psi^2)\phi}{2} \|\hat{r}_t^k - \hat{r}_{t-1}^k\|_2^2.$$

Now we taking derivative w.r.t \hat{r}_t^k & equal to zero.

$$\Rightarrow \frac{1}{2} (\hat{r} - \hat{x} \hat{g})^T (\hat{r} - \hat{x} \hat{g}) + \frac{(1+\psi^2)\lambda_2}{2} (\hat{\Omega} - \hat{r})^T (\hat{\Omega} - \hat{r}) + \frac{(1-\psi^2)\phi}{2} (\hat{r}_t - \hat{r}_{t-1})^T (\hat{r}_t - \hat{r}_{t-1}) = 0$$

$$\Rightarrow \frac{1}{2} (\hat{r}^T - \hat{x}^T \hat{g}^T) (\hat{r} - \hat{x} \hat{g}) + \frac{(1+\psi^2)\lambda_2}{2} (\hat{\Omega}^T - \hat{r}^T) (\hat{\Omega} - \hat{r}) + \frac{(1-\psi^2)\phi}{2} (\hat{r}_t^T - \hat{r}_{t-1}^T) (\hat{r}_t - \hat{r}_{t-1}) = 0$$

$$\Rightarrow \frac{1}{2} (\hat{r}^T \hat{r} - \hat{r}^T \hat{x} \hat{g} - \hat{x}^T \hat{g}^T \hat{r} + \hat{x}^T \hat{g}^T \hat{x} \hat{g}) + \frac{(1+\psi^2)\lambda_2}{2} (\hat{\Omega}^T \hat{\Omega} - \hat{\Omega}^T \hat{r} - \hat{r}^T \hat{\Omega} + \hat{r}^T \hat{r}) + \frac{(1-\psi^2)\phi}{2} (\hat{r}_t^T \hat{r}_t - \hat{r}_t^T \hat{r}_{t-1} - \hat{r}_{t-1}^T \hat{r}_t + \hat{r}_{t-1}^T \hat{r}_{t-1}) = 0$$

$$\Rightarrow \frac{1}{2} [\hat{r}^T - \hat{x}^T \hat{g}^T] + \frac{(1+\psi^2)\lambda_2}{2} [\hat{r}^T - 2\hat{\Omega}^T] + \frac{(1-\psi^2)\phi}{2} [\hat{r}^T - 2\hat{r}_{t-1}^T] = 0 \quad \left[\begin{array}{l} \text{Take derivative} \\ \text{w.r.t } \hat{r}_t \end{array} \right]$$

$$\Rightarrow \hat{r} - \hat{x} \hat{g} + (1+\psi^2)\lambda_2 (\hat{r} - \hat{\Omega}) + (1-\psi^2)\phi (\hat{r} - \hat{r}_{t-1}) = 0$$

$$\Rightarrow \hat{r} (1 + (1+\psi^2)\lambda_2 + (1-\psi^2)\phi) = \hat{x} \hat{g} + (1+\psi^2)\lambda_2 \hat{\Omega} + (1-\psi^2)\phi \hat{r}_{t-1}$$

$$\Rightarrow \hat{r} = \frac{\hat{x} \hat{g} + (1+\psi^2)\lambda_2 \hat{\Omega} + (1-\psi^2)\phi \hat{r}_{t-1}}{1 + (1+\psi^2)\lambda_2 + (1-\psi^2)\phi}$$