

Approximate PD Decomposition of Covariance Matrix

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1 The Problem

We consider the problem of approximately decomposing a covariance matrix Σ into a lowrank component \mathbf{L} and a sparse component \mathbf{S} , both needs to be positive definite (PD). [Xue et al. \(2012\)](#) consider the task of approximate Σ by a sparse PD matrix using ADMM algorithm. Following the idea, consider the following objective

$$\begin{aligned} \min_{\mathbf{L}, \mathbf{S}} \quad & \frac{1}{2} \|\Sigma - \mathbf{L} - \mathbf{S}\|_F^2 + \lambda_L \|\mathbf{L}\|_* + \lambda_S \|\mathbf{S}\|_- \\ \text{s.t.} \quad & \mathbf{L} \succeq \epsilon \mathbf{I}, \quad \mathbf{S} \succeq \epsilon \mathbf{I}, \end{aligned}$$

where ϵ is a fixed scalar to enforce positive definiteness, $\|\cdot\|_F$ is Frobenious norm, $\|\cdot\|_*$ is nuclear norm, $\|\cdot\|_-$ is ℓ_1 norm imposed on off-diagonal elements, i.e. $\|\mathbf{X}\|_- = \sum_{i \neq j} |\mathbf{X}_{ij}|$. For notational convenience, denote by $\mathcal{S}^{p \times p}$ the space of symmetric matrices and define $\mathcal{S}_\epsilon^{p \times p} = \{\mathbf{X} \in \mathcal{S}^{p \times p} : \mathbf{X} \succeq \epsilon \mathbf{I}\}$.

2 Augmented Lagrangian

To use ADMM, we introduce two coupling variables $\mathring{\mathbf{L}}$ and $\mathring{\mathbf{S}}$ for \mathbf{L} and \mathbf{S} , respectively. Imposing PD constraints on coupling variables and requiring “coupling” conditions give the following equivalent problem,

$$\begin{aligned} \min_{\mathbf{L}, \mathbf{S}, \mathring{\mathbf{L}}, \mathring{\mathbf{S}}} \quad & \frac{1}{2} \|\mathbf{\Sigma} - \mathbf{L} - \mathbf{S}\|_{\text{F}}^2 + \lambda_{\text{L}} \|\mathbf{L}\|_* + \lambda_{\text{S}} \|\mathbf{S}\|_* \\ \text{s.t.} \quad & \mathring{\mathbf{L}} \in \mathcal{S}_{\epsilon}^{p \times p}, \quad \mathring{\mathbf{S}} \in \mathcal{S}_{\epsilon}^{p \times p} \\ & \mathbf{L} = \mathring{\mathbf{L}}, \quad \mathbf{S} = \mathring{\mathbf{S}}. \end{aligned}$$

Further relax equality constraints, the augmented Lagrangian is written as

$$\begin{aligned} \mathcal{L}(\mathbf{L}, \mathbf{S}, \mathring{\mathbf{L}}, \mathring{\mathbf{S}}; \mathbf{\Lambda}_{\text{L}}, \mathbf{\Lambda}_{\text{S}}) = & \frac{1}{2} \|\mathbf{\Sigma} - \mathbf{L} - \mathbf{S}\|_{\text{F}}^2 + \lambda_{\text{L}} \|\mathbf{L}\|_* + \lambda_{\text{S}} \|\mathbf{S}\|_* \\ & + \frac{1}{2\mu_{\text{L}}} \|\mathbf{L} - \mathring{\mathbf{L}}\|_{\text{F}}^2 + \frac{1}{2\mu_{\text{S}}} \|\mathbf{S} - \mathring{\mathbf{S}}\|_{\text{F}}^2 \\ & + \langle \mathbf{\Lambda}_{\text{L}}, \mathbf{L} - \mathring{\mathbf{L}} \rangle + \langle \mathbf{\Lambda}_{\text{S}}, \mathbf{S} - \mathring{\mathbf{S}} \rangle, \end{aligned}$$

which serves as the “augmented” objective with two PD constraints on $\mathring{\mathbf{L}}$ and $\mathring{\mathbf{S}}$.

3 Algorithm

We omit details of deriving ADMM and obtain the abstract version of the algorithm by mimicking the algorithm given in [Xue et al. \(2012\)](#) and alternating between two blocks $(\mathbf{L}, \mathring{\mathbf{L}}, \mathbf{\Lambda}_{\text{L}})$ and $(\mathbf{S}, \mathring{\mathbf{S}}, \mathbf{\Lambda}_{\text{S}})$.

Algorithm 1. (Abstract Version)

- Coupling Update Step

$$\begin{aligned}
\mathring{\mathbf{L}} &= \operatorname{argmin}_{\mathring{\mathbf{L}} \in \mathcal{S}_\epsilon^{p \times p}} \frac{1}{2\mu_L} \|\mathbf{L} - \mathring{\mathbf{L}}\|_F^2 - \langle \mathbf{\Lambda}_L, \mathring{\mathbf{L}} \rangle \\
&= \operatorname{argmin}_{\mathring{\mathbf{L}} \in \mathcal{S}_\epsilon^{p \times p}} \|(\mathbf{L} + \mu_L \mathbf{\Lambda}_L) - \mathring{\mathbf{L}}\|_F^2 \\
\mathring{\mathbf{S}} &= \operatorname{argmin}_{\mathring{\mathbf{S}} \in \mathcal{S}_\epsilon^{p \times p}} \|(\mathbf{S} + \mu_S \mathbf{\Lambda}_S) - \mathring{\mathbf{S}}\|_F^2
\end{aligned}$$

- Main Update Step

$$\begin{aligned}
\mathbf{L} &= \operatorname{argmin}_{\mathbf{L}} \frac{1}{2} \|\mathbf{\Sigma} - \mathbf{L} - \mathbf{S}\|_F^2 + \lambda_L \|\mathbf{L}\|_* + \frac{1}{2\mu_L} \|\mathbf{L} - \mathring{\mathbf{L}}\|_F + \langle \mathbf{\Lambda}_L, \mathbf{L} \rangle \\
&= \operatorname{argmin}_{\mathbf{L}} \frac{1}{2} \left\| \frac{\mu_L(\mathbf{\Sigma} - \mathbf{S} - \mathbf{\Lambda}_L) + \mathring{\mathbf{L}}}{1 + \mu_L} - \mathbf{L} \right\|_F^2 + \frac{\lambda_L \mu_L}{1 + \mu_L} \|\mathbf{L}\|_* \\
\mathbf{S} &= \operatorname{argmin}_{\mathbf{S}} \frac{1}{2} \left\| \frac{\mu_S(\mathbf{\Sigma} - \mathbf{L} - \mathbf{\Lambda}_S) + \mathring{\mathbf{S}}}{1 + \mu_S} - \mathbf{S} \right\|_F^2 + \frac{\lambda_S \mu_S}{1 + \mu_S} \|\mathbf{S}\|_*
\end{aligned}$$

- Dual Update Step

$$\begin{aligned}
\mathbf{\Lambda}_L &= \mathbf{\Lambda}_L + \mu_L^{-1}(\mathbf{L} - \mathring{\mathbf{L}}) \\
\mathbf{\Lambda}_S &= \mathbf{\Lambda}_S + \mu_S^{-1}(\mathbf{S} - \mathring{\mathbf{S}})
\end{aligned}$$

4 Closed-form Update Rules

Projection Updating the coupling variables is essentially computing the projection onto the closed and convex subset $\mathcal{S}_\epsilon^{p \times p} \subset \mathcal{S}^{p \times p}$. The projector

$\mathcal{P} : \mathcal{S}^{p \times p} \rightarrow \mathcal{S}_\epsilon^{p \times p}$ is simply given by

$$\mathcal{P}_\epsilon(\mathbf{X}) = \mathbf{U} \max(\mathbf{D}, \epsilon \mathbf{I}) \mathbf{U}^\top,$$

where $\mathbf{X} = \mathbf{U} \mathbf{D} \mathbf{U}^\top$ and $\max(\cdot, \cdot)$ defines the element-wise max.

Proximal Operators The main update step is of form (effectively up to a scalar)

$$\min_{\mathbf{X}} \quad \frac{1}{2} \|\mathbf{X} - \mathbf{Y}\|_{\text{F}}^2 + \lambda \|\mathbf{X}\|,$$

whose solution is defined as

$$\text{prox}_{\lambda \|\cdot\|}(\mathbf{Y}) = \underset{\mathbf{X}}{\text{argmin}} \quad \frac{1}{2} \|\mathbf{X} - \mathbf{Y}\|_{\text{F}}^2 + \lambda \|\mathbf{X}\|.$$

Luckily, the proximal operators associated with nuclear norm and ℓ_1 norm are available in closed forms as

$$\begin{aligned} \text{prox}_{\lambda \|\cdot\|_*}(\mathbf{Y}) &= \mathcal{T}_\lambda^{\text{SVT}}(\mathbf{Y}) = \mathbf{U}(\mathbf{D} - \lambda \mathbf{I})_+ \mathbf{U}^\top \\ \text{prox}_{\lambda \|\cdot\|_1}(\mathbf{Y}) &= \mathcal{T}_\lambda^{\text{Soft}}(\mathbf{Y}) = (|\mathbf{Y}| - \lambda)_+ \odot \text{sgn}(\mathbf{Y}) \end{aligned}$$

where $\mathbf{Y} = \mathbf{U} \mathbf{D} \mathbf{U}^\top$ and all functions apply in an element-wise manner. However, in our scenario, the soft-thresholding operator needs to be adapted on only off-diagonal elements.

References

Xue, L., S. Ma, and H. Zou (2012). Positive-definite ℓ_1 -penalized estimation of large covariance matrices. *Journal of the American Statistical Association* 107(500), 1480–1491.