SERVOMOTORS

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WHAT IS SERVO MOTOR?

- It is a special type of motor.
- Automatically operated up to certain limit for a given command.
- It uses error sensing feedback to correct the performance.

TYPES OF SERVO MOTORS

- AC SERVOMOTORS
- DC SERVOMOTORS

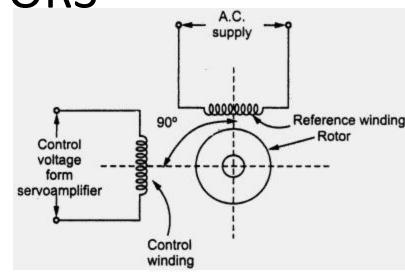
AC SERVOMOTORS

- Induction motor with low (X/R) ratio.
- Consists of two main parts as follows,

STATOR

Two windings displaced by 90 degree.

- Reference winding ______ constant AC supply.
- Control winding control voltage from servo amplifier.

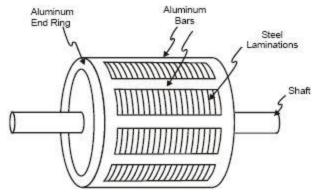


ROTOR

✓ It is classified into two types as follows

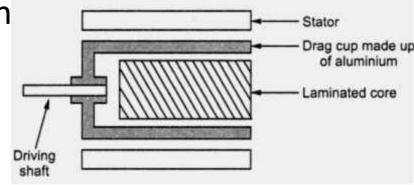
SQUIRREL CAGE ROTOR

- ✓ Use of aluminium reduces weight.
- ✓ Low inertia.
- ✓ Air gap is small.
- ✓ High resistance.



DRAG CUP ROTCh

- ✓ Two air gaps.
- ✓ Used in low power application
- ✓ Made up of aluminium.



WORKING

- The voltage applied to stator creates RMF which makes rotor shaft to rotate.
- Torque-Speed characteristics.
 - ✓ Linear for low (X/R) ratio.
 - ✓ Non-linear for high (X/R) ratio.
- Linear characteristics depends on control voltage.
- It is operated in low speed range.

AC SERVO MOTOR FEATURES

- Small (X/R) ratio & high efficiency.
- Smooth, Less weight & low cost.
- Robust construction & noise free working.

APPLICATIONS OF AC SERVO MOTORS

o Recorders, Computers and Robotics.

DC SERVOMOTORS

- o It is classified as,
- o Electromagnetic field motor.
- o Permanent motor.

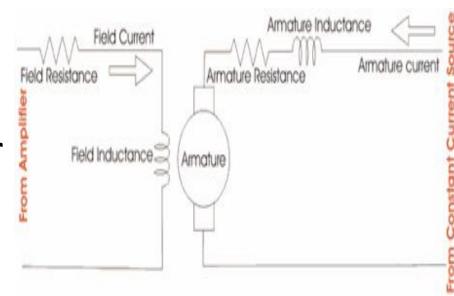
ELETROMAGNETIC FIELD MOTORS

FIELD CONTROLLED MOTORS:-

- Field winding control signal.
- Armature winding constant current.

FEATURES

- Large time constant.
- Open loop system.
- Preferred for smaller rate motors.

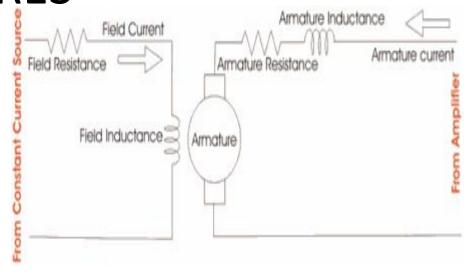


ARMATURE CONTROLLED DC SERVO MOTORS

- Armature winding control signal.
- Field winding constant current source.

FEATURES

- Small time constant.
- Closed loop system.
- Preferred for large rate motors.

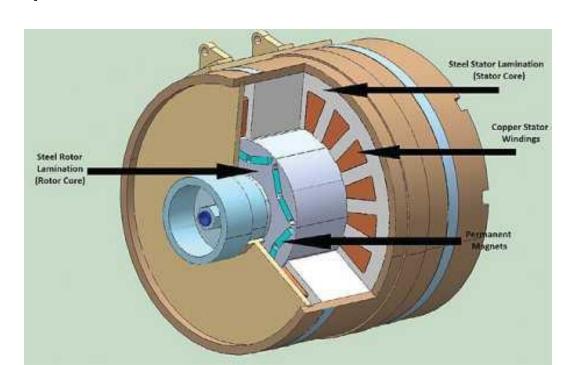


PERMANENT MAGNET MOTORS

- Field winding Permanent magnet.
- Armature winding voltage.

FEATURES

- No field supply is required.
- Highly efficient.
- Less affected by temperature rise.
- Less heating.



SYNCHROS

Synchros

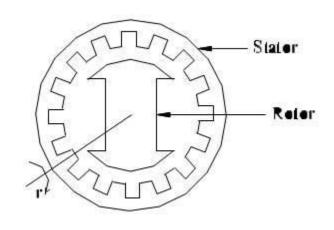
Synchros is a name for a family of inductive devices which works on the principle of a rotating transformer.

They can be used in following two ways

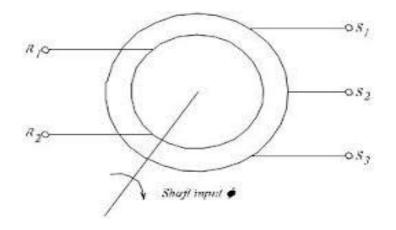
- To control the angular position of load from a remote place.
- For automatic correction of changes due to disturbance in the angular position of the load.

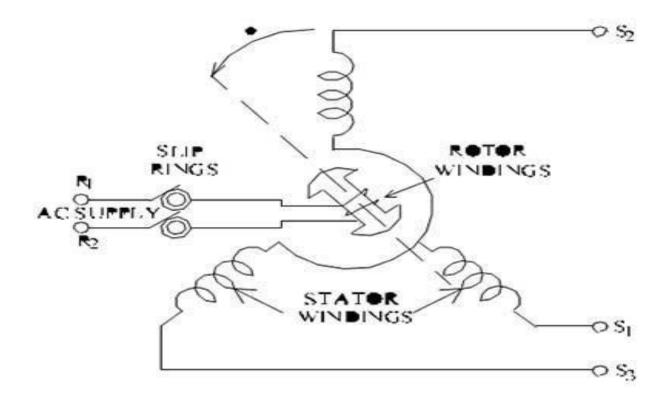
Synchro Transmitter

When the rotor is excited by ac voltage, the rotor current flows, and a magnetic field is produced.



The rotor magnetic field induces an emf in the stator coils by transformer action.

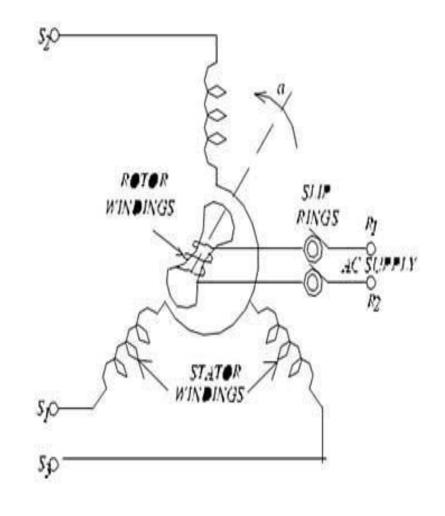




- The input to the synchro transmitter is the angular position of its rotor shaft.
- By measuring and identifying the set of voltages at the stator terminal

Synchro control Transformer

- ➤ The generated emf of the synchro is applied as input to the stator coils of control transformer.
- > This emf can be measured used to drive a motor so that the position of the load is corrected.



Synchro as Error Detector

 The synchro error detector is formed by interconnection of a synchro transmitter and synchro control transformer.

 Initially the shafts of transmitter and control transformer are assumed to be in aligned position.

Synchro control

transformer

The null position of a control transformer in a servo system is that position of its rotor for which the output voltage on the rotor winding is zero

