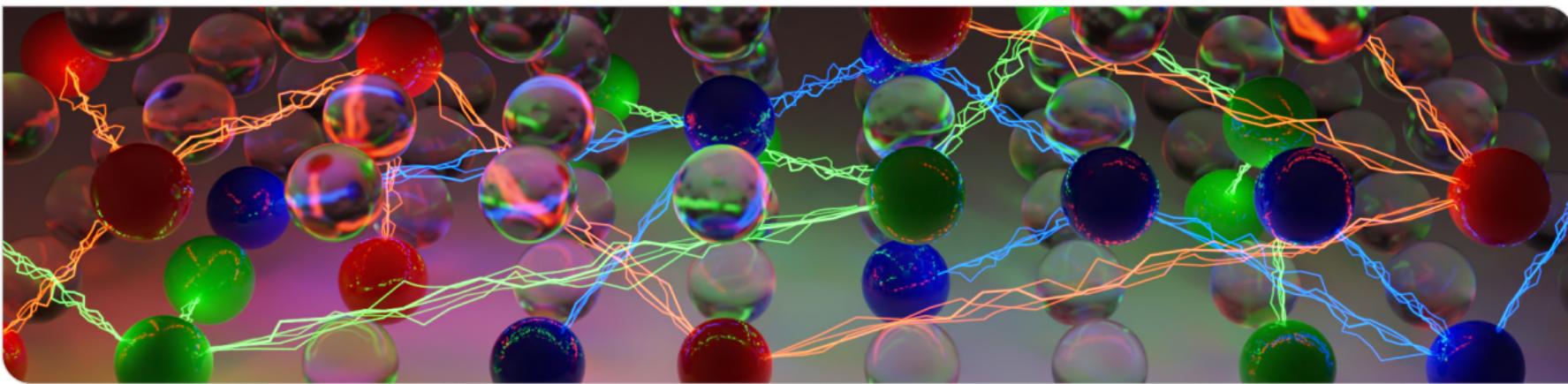


Practical SAT Solving

Lecture 9: Parallel SAT Solving

T. Balyo, M. Iser, D. Schreiber | May 13, 2024



Outline

Parallel SAT solving approaches

- Basic search space splitting
- Clause sharing
- Cube&Conquer
- Portfolio solvers (without and with clause sharing)

A deep dive into Mallob

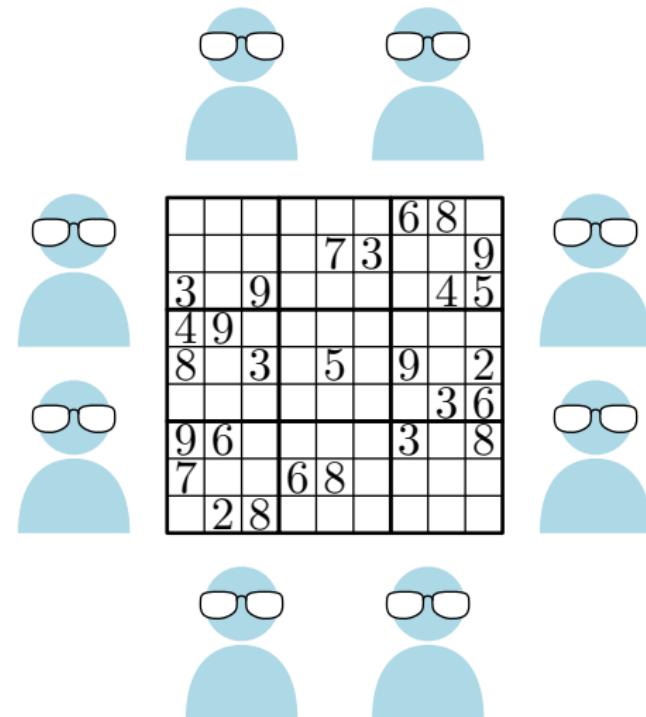
- Overview
- Scalable clause sharing
- Experiments and results

Parallel Portfolios: An analogy

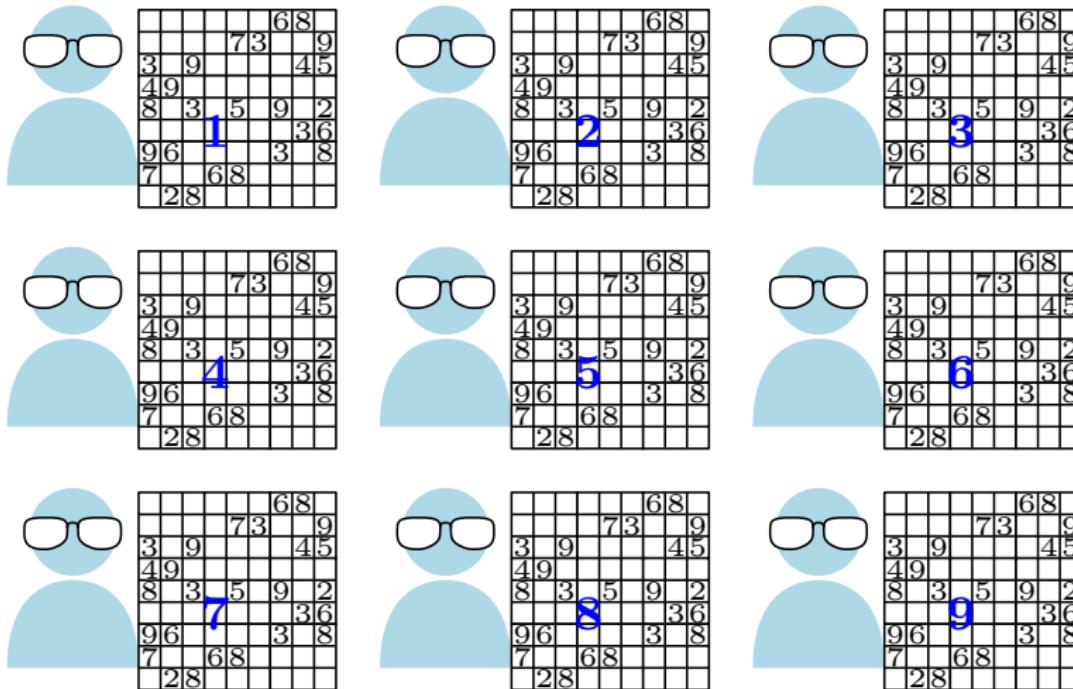
The Assembly of Nerds

- Complex and large logic puzzle
- n puzzle experts at your disposition

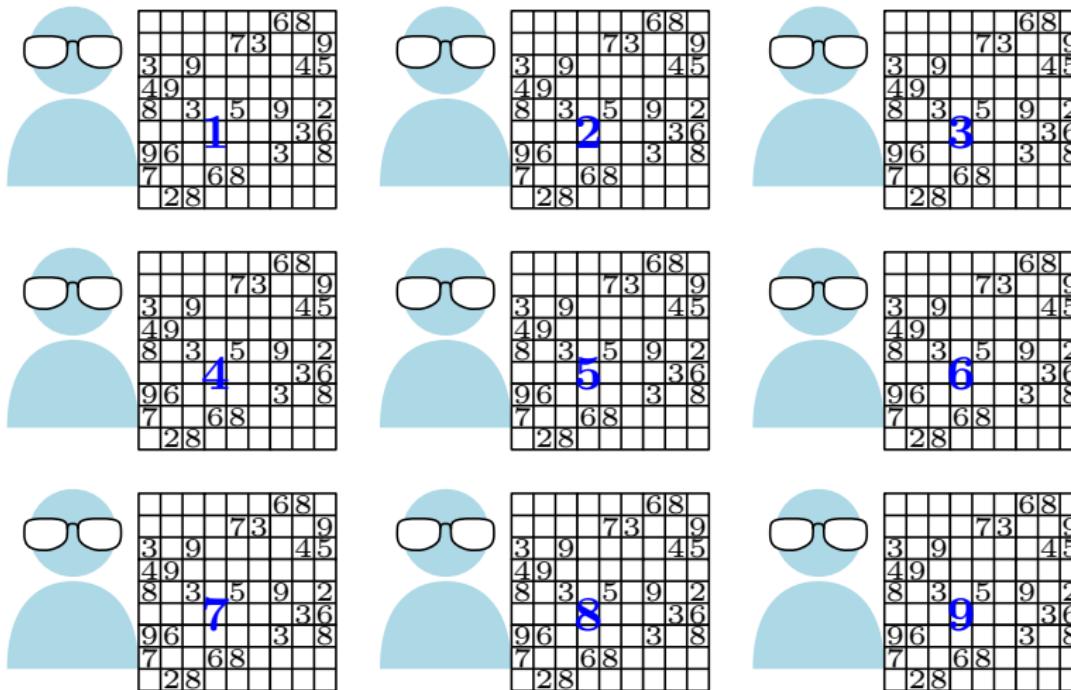
How do we employ and “orchestrate” our experts?



Approach I: Search Space Partitioning



Approach I: Search Space Partitioning



- Partition search space at some decisions
⇒ Independent subproblems

Explicit Partitioning

1st Parallel DPLL Implementation by Böhm & Speckenmeyer (1994)

Explicit Load Balancing

- Completely distributed (no leader / worker roles)
- A list of **partial assignments** is generated
- Each process receives the entire formula and **a few partial assignments**
- Each process can be worker or balancer:
 - **Worker**: solve or split the formula, use the partial assignments
 - **Balancer**: estimate workload, communicate, stop
- Switch to balancer whenever worker is finished

Explicit Partitioning

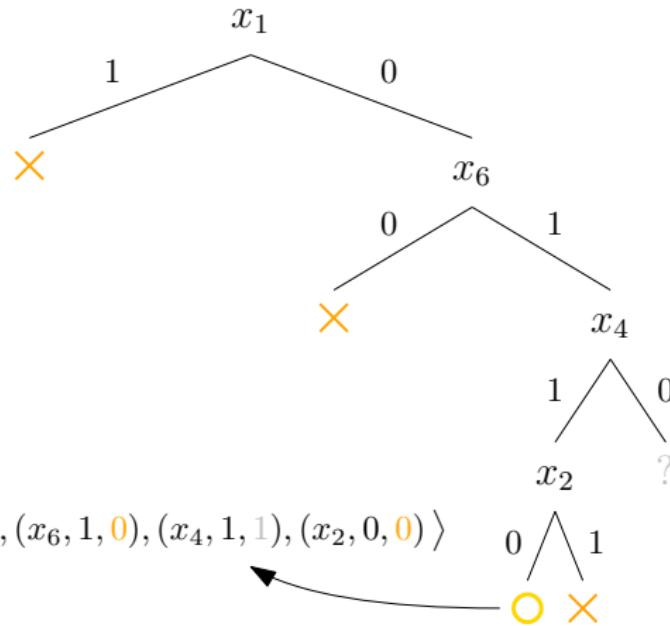
“PSATO: a Distributed Propositional Prover and its Application to Quasigroup Problems”, Zhang et al., 1996

Centralized leader-worker architecture

- Communication only between leader and workers
- Leader assigns partial assignments using Guiding Path
 - Each node in the search tree is open or closed
 - closed = branch is explored / proven unsat
 - Leader splits open nodes and assigns job to workers
- Workers return Guiding Path when terminated by leader
- Modern features of fault tolerance, preemption of solving tasks

Explicit Partitioning

Guiding Path: List of triples (variable, branch, open)



Explicit Partitioning

SATZ (Jurkowiak et al., 2001) improves PSATO

Work stealing for workload balancing

- An idle worker **requests work** from the leader
- The leader **splits the work** of the most loaded worker
- The idle worker and most loaded worker get the parts

Clause Sharing Parallel Solvers

PaSAT (Blochinger et al., 2001)

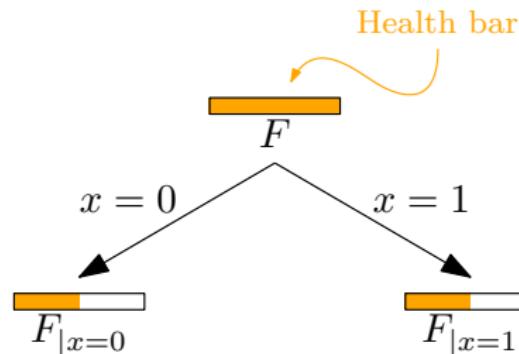
- First parallel CDCL with clause sharing
- Similar to PSATO/SATZ: leader/worker, guiding path, work stealing

ySAT (Feldman et al., 2004)

- First shared-memory parallel solver
- Multi-core processors started to be popular
- uses same techniques as the previous solvers (guiding path etc.)

... and many many more similar solvers

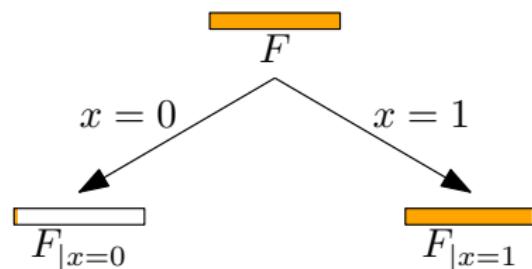
Problems with Partitioning



What we want: **Even splits**

- Split yields sub-formulas of **similar difficulty**
- Balanced partitioning of work
- Few or no dynamic (re-)balancing needed

Problems with Partitioning



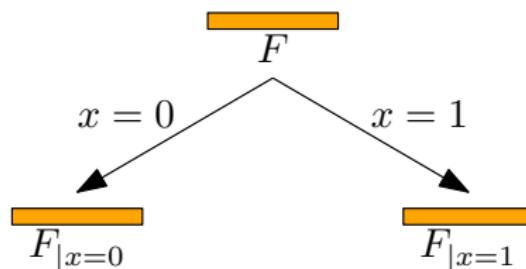
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- Balanced partitioning of work
- Few or no dynamic (re-)balancing needed

Uneven splits

- One subformula is **trivial**, the other is **just as hard as F**
- **Ping-pong effect** for workers processing trivial formulae, communication / synchronization dominates run time

Problems with Partitioning



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- Split yields sub-formulas of **similar difficulty**
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Bogus splits

- Both $F_{|x=0}$ and $F_{|x=1}$ are **just as hard as F**
- **Divide&Conquer** becomes **Multiply&Surrender!**

Cube and Conquer

The Cube&Conquer paradigm (Heule & Biere, 2011)

Generate a large amount ([millions](#)) of [partial assignments](#) ("**cubes**")
and [randomly assign](#) them to workers.

Cube and Conquer

The Cube&Conquer paradigm (Heule & Biere, 2011)

Generate a large amount (**millions**) of **partial assignments** ("**cubes**")
and **randomly assign** them to workers.

- Unlikely that any of the workers will run out tasks
⇒ Hope of **good load balancing** in practice
- Partial assignments are generated using a **look-ahead solver**
(breadth-first search up to a limited depth)
- Best performance mostly with **problem-specific decision heuristics**

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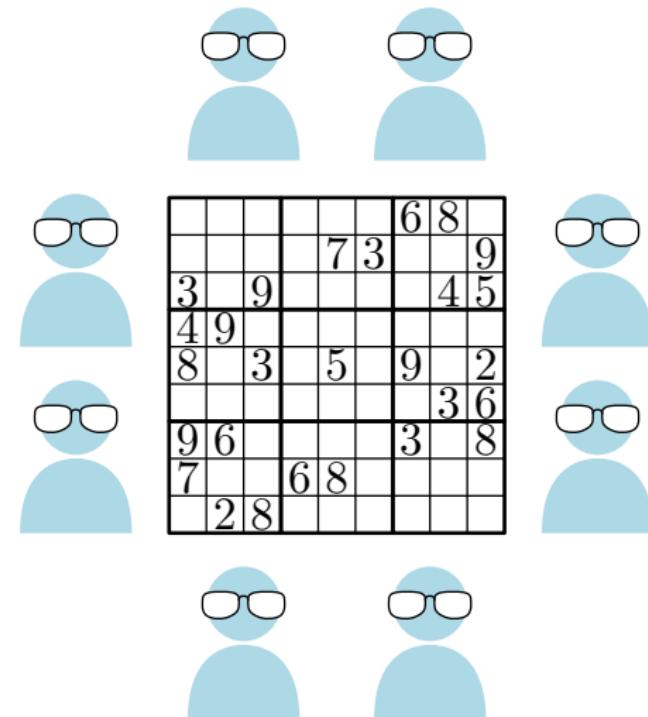
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⇒ Hope of **good load balancing** in practice
- Partial assignments are generated using a **look-ahead solver**
(breadth-first search up to a limited depth)
- Best performance mostly with **problem-specific decision heuristics**
- State-of-the-art for **hard combinatorial problems**
 - Used to solve the "Pythagorean Triples" problem (~200TB proof)
 - ... or more recently "Schur Number 5" (~2PB proof)
- Examples: March (Heule) + iLingeling (Biere) introduced in 2011; Treengeling (Biere)

Parallel Portfolios: An analogy

The Assembly of Nerds

- Complex and large logic puzzle
- n puzzle experts at your disposition
 - individual mindsets, approaches, strengths & weaknesses
 - anti-social: work best if left undisturbed

How do we employ and “orchestrate” our experts?



Approach II: Pure Portfolio



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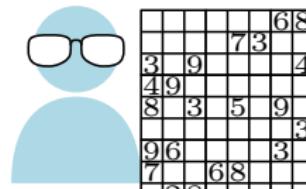
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Pure Portfolio: Oracle view vs. Speedup view

Virtual Best Solver (VBS) / Oracle

Consider n algorithms A_1, \dots, A_n where for each input x , algorithm A_i has run time $T_{A_i}(x)$.

The [Virtual Best Solver](#) (VBS) for A_1, \dots, A_n has run time $T^*(x) = \min\{T_{A_1}(x), \dots, T_{A_n}(x)\}$.

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Optimist: A pure portfolio **simulates the VBS** using parallel processing!

- On idealized hardware, we “select” best sequential solver for each instance

Pure Portfolio: Oracle view vs. Speedup view

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Parallel speedup

Given parallel algorithm P and input x , the **speedup** of P is defined as $s_P(x) = T_Q(x)/T_P(x)$ where Q is the **best available sequential algorithm**.

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Pessimist: A pure portfolio **never achieves actual speedups**!

- There is always a sequential algorithm performing **at least as well**
- Consequence: **Not resource efficient, not scalable**

Pure SAT Portfolios

ppfolio: Winner of Parallel Track in the 2011 SAT Competition

- Just a bash script combining the **best sequential solvers from 2010**:
~\$./solver1 f.cnf & ./solver2 f.cnf & ./solver3 f.cnf & ./solver4 f.cnf
- Bits by O. Roussel, the author of ppfolio:
 - “*by definition the best solver on Earth*”
 - “*probably the laziest and most stupid solver ever written*”

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 - “*by definition the best solver on Earth*”
 - “*probably the laziest and most stupid solver ever written*”
- Rationale: Different solvers are designed differently, excel on different instances
 - hope of **orthogonal search behavior**
- Pure portfolios **no longer permitted** in SAT Competitions

Approach II+: Cooperative Portfolio



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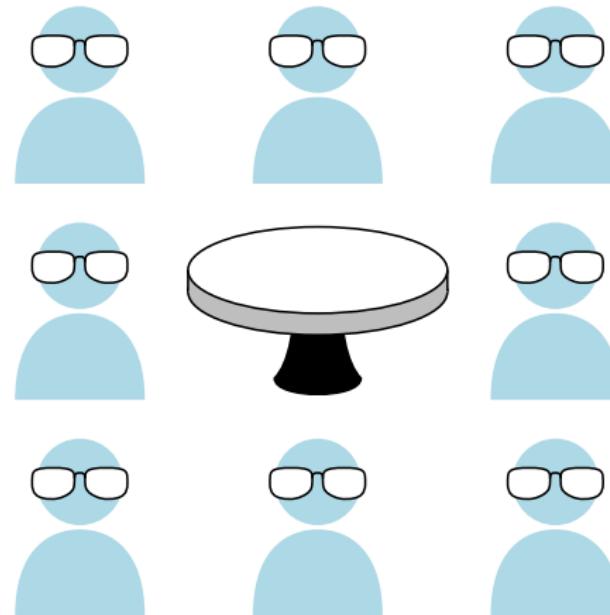


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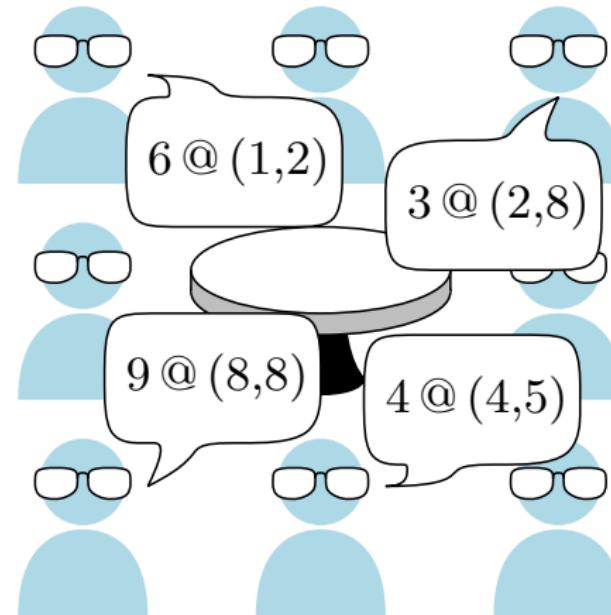


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Cooperative Portfolio

Assembly of Nerds, enhanced

- The experts periodically gather for brief standup meetings
- Via some protocol, the experts exchange the most valuable insights gained since the last meeting
- Solving continues — each expert may use the shared insights at their own discretion

Equivalent to “insights” in SAT solving:

Cooperative Portfolio

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- Via some protocol, the experts exchange the most valuable insights gained since the last meeting
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Equivalent to “insights” in SAT solving: **learnt (conflict) clauses**

- Explored branch of search space — safe to prune
- Potential step for deriving unsatisfiability

Clause Sharing Portfolios: Design Space

Portfolio considerations

- Which sequential solvers to employ?
- How to diversify solvers?
 - different search algorithms, selection heuristics, restart intervals, ...
 - different random seeds, initial phases, input permutations, ...

```
void Cadical::diversify(int seed) {
    solver->set(name: "seed", val: seed);
    switch (getDiversificationIndex() % getNumOriginalDiversifications()) {
        case 0: okay = solver->set(name: "phase", val: 0); break;
        case 1: okay = solver->configure("sat"); break;
        case 2: okay = solver->set(name: "elim", val: 0); break;
        case 3: okay = solver->configure("unsat"); break;
        case 4: okay = solver->set(name: "condition", val: 1); break;
        case 5: okay = solver->set(name: "walk", val: 0); break;
        case 6: okay = solver->set(name: "restartint", val: 100); break;
        case 7: okay = solver->set(name: "cover", val: 1); break;
        case 8: okay = solver->set(name: "shuffle", val: 1) && solver->set(name: "inprocessing", val: 0); break;
        case 9: okay = solver->set(name: "inprocessing", val: 0); break;
    }
}
```

Clause Sharing Portfolios: Design Space

Portfolio considerations

- Which sequential solvers to employ?
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 - different search algorithms, selection heuristics, restart intervals, ...
 - different random seeds, initial phases, input permutations, ...

Clause exchange considerations

- How often to share? (immediate/eager? delayed/lazy? periodic?)
- How many clauses to share? (fixed volume? fixed quality criteria?)
- Which clauses to share? (shortest? lowest LBD?)
- How to implement sharing? (all-to-all? leader-worker? some communication graph?)

Early Clause Sharing Portfolios

ManySAT (Hamadi, Jabbour, and Sais 2009)

- Hand-crafted diversification of four solver configurations
 - Restart policy, variable + polarity selection heuristic, ...
- Eager exchange of clauses of length ≤ 8 via lockless queues

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Plingeling (Biere 2010)

- Portfolio over Lingeling configurations (shared-memory parallelism)
- Lazy exchange of information over “boss thread”
 - 2010: Unit clauses only
 - 2011: Unit clauses + equivalences
 - Since 2013: Unit clauses + equivalences + clauses of length ≤ 40 , LBD ≤ 8
- Best parallel solver for many years

Massively parallel hardware?

Distributed computing

In distributed computing, several machines (with no shared main memory) run together. On each machine we run a number of processes, each of which runs on a number of cores. Processes commonly communicate by exchanging messages.



SuperMUC-NG: 6 336 nodes × 48 cores

Massively parallel hardware?

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SuperMUC-NG: 6 336 nodes × 48 cores

Large distributed systems (hundreds to thousands of cores) impose new requirements, challenges:

- No shared memory — communication protocols required
- Diminishing returns due to exhausted diversification of solvers

Massively parallel hardware?

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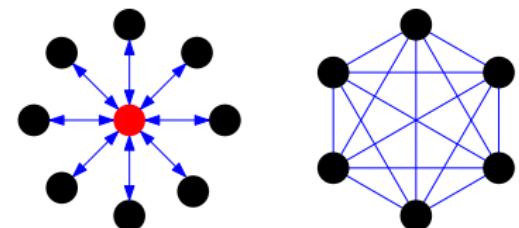
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SuperMUC-NG: 6 336 nodes × 48 cores

Large distributed systems (hundreds to thousands of cores) impose new requirements, challenges:

- No shared memory — communication protocols required
- Diminishing returns due to exhausted diversification of solvers
- Some exchange schemes are conceptually not scalable
 - “Star graph”: Master process collects, serves all exported clauses
 - Naïve (quadratic) all-to-all exchange of clauses



Massively parallel SAT portfolio

HordeSat (Balyo, Sanders, Sinz 2015)

- Decentralization: No single leader node / process
- Two-level (“hybrid”) parallelization
 - One or several processes on each machine
 - Multiple solver threads (+ communication thread) on each process

Massively parallel SAT portfolio

HordeSat (Balyo, Sanders, Sinz 2015)

- Decentralization: No single leader node / process
- Two-level (“hybrid”) parallelization
 - One or several processes on each machine
 - Multiple solver threads (+ communication thread) on each process
- Diversification options:
 - Native diversification (set of hand-crafted solver configurations)
 - Modifying some initial variable phases
 - Random seeds
- Periodic all-to-all clause exchange

HordeSat: Results

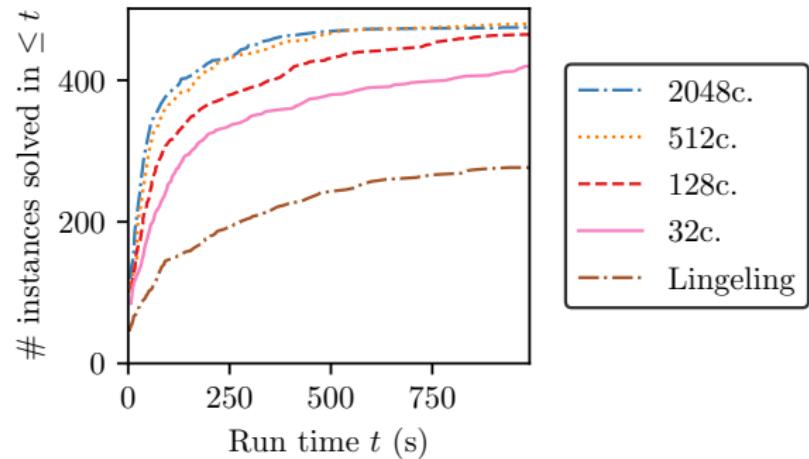
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 - UNSAT: distributed memory accommodates more clauses than any sequential solver

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 - SAT: “NP luck” – some solver got lucky
 - UNSAT: distributed memory accommodates more clauses than any sequential solver
- Median speedup: 3 at 16 cores, 11.5 at 512 cores
 - Efficiency: $11.5/512 \approx 2.2\%$
 - Deploying HordeSat is often not worth it
- No improvement beyond ≈ 500 cores



Data extracted from HordeSat paper

From HordeSat to Mallob

Research Question

How can we improve performance, (resource-)efficiency, and average response times of SAT solving in **modern distributed environments**?

From HordeSat to Mallob

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Result: Mallob

Mallob is a **platform for SAT solving** (*and other NP-hard problems*) with:

- multi-user, **on-demand**, malleable scheduling and solving of **many problems at once**
- the HordeSat paradigm **re-engineered** and made efficient
- state-of-the-art SAT performance **from dozens to thousands of cores**

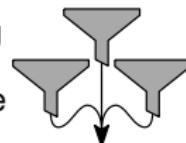
Engineering a Scalable SAT Solver

Succinct clause sharing



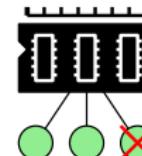
Hierarchical merging + duplicate detection
Global and adaptive admission criteria

Distributed clause filtering



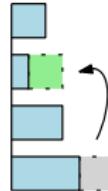
Exact filtering of clauses shared before / from self

Memory Awareness



Reduction of solver threads
Negotiated memory panic

Adaptive buffering



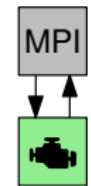
Keep best clauses at expense of worse clauses
For export + import

Diversification



Glucose, Lingeling, CaDiCaL, Kissat
Clause shuffling
Noisy parameters

Controlling

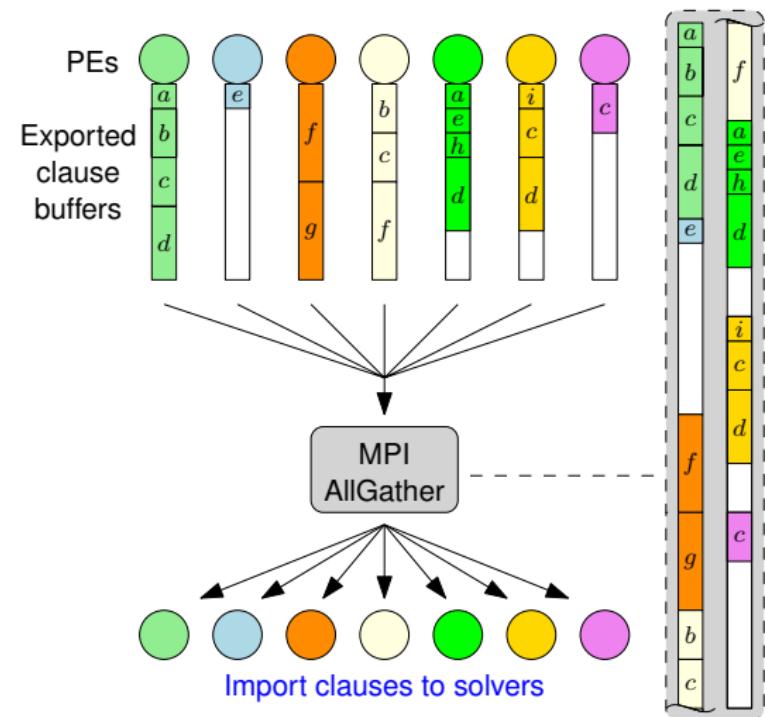


Subprocess for solvers
Seamless preemption and termination
Fault tolerance

Clause Exchange in HordeSat

Periodic collective operation **AllGather**

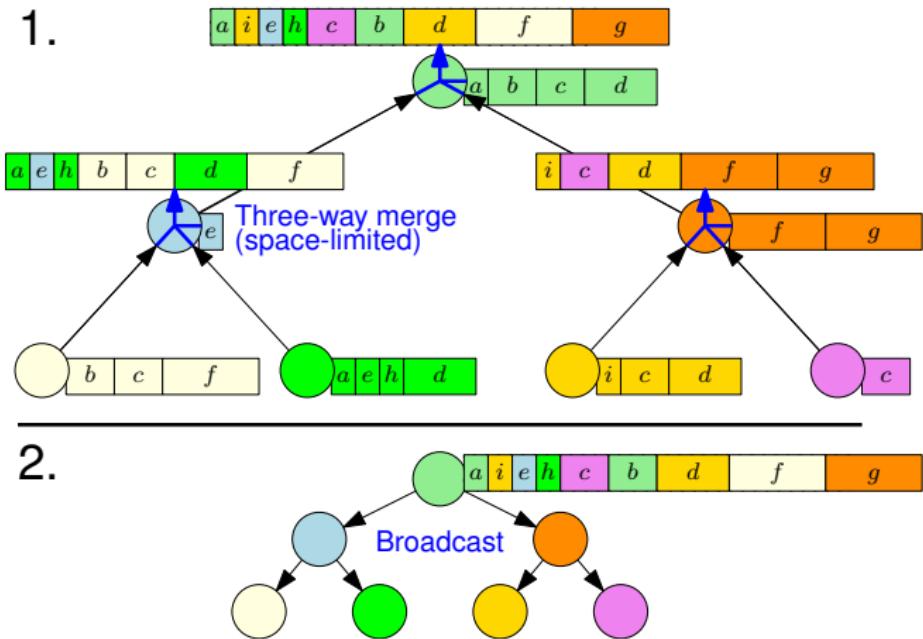
- Locally best clauses are shared with everyone
- Duplicate clauses
- “Holes” in buffer carrying no information
- Buffer grows proportionally with # proc.
⇒ Bottleneck w.r.t communication *and* local work



Clause Exchange in Mallob

Custom collective operation [SAT'21]

- Aggregate information along binary tree of processors
- Detect duplicates during merge
- Result is of compact shape
- Sublinear buffer size growth:
Discard longest clauses as necessary



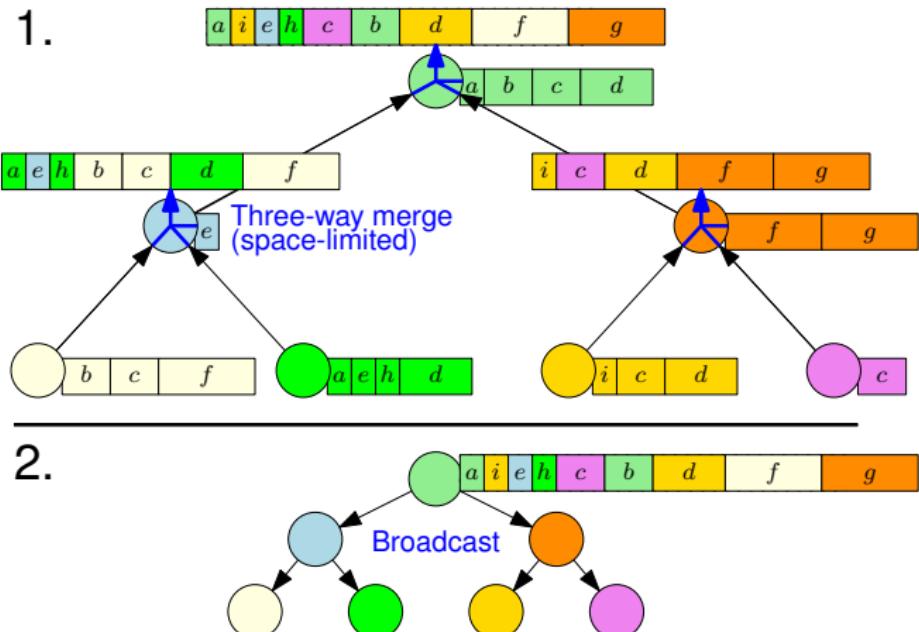
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Observations

- Clause needs to meet global quality threshold to be shared successfully
- Quality threshold adapts to state of solving



Clause Filtering

The Problem

Given a **shared clause** c and a solver S , decide if S has **received or produced** c before (recently).

Previously: [HordeSat] [SAT'21]

- Bloom filters: **fixed size**, risk of **false positives**

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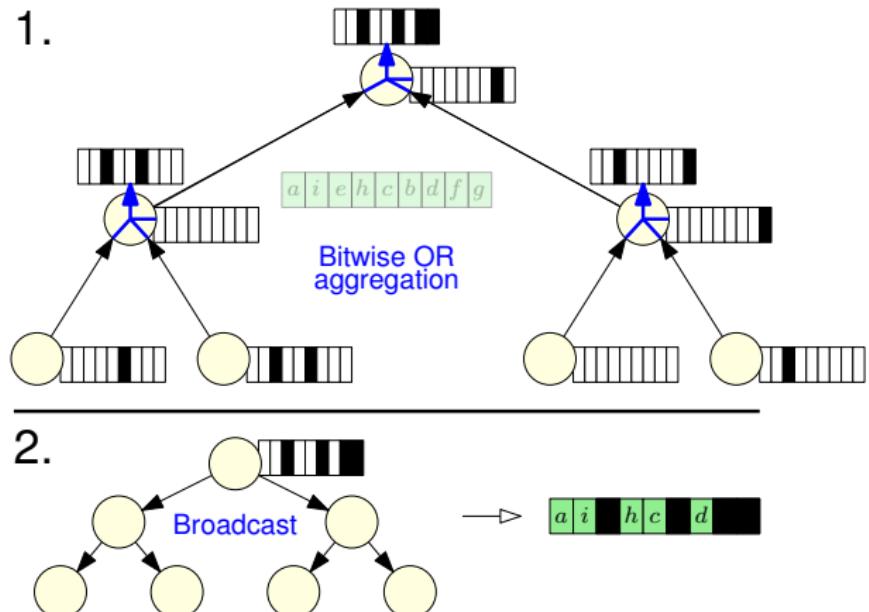
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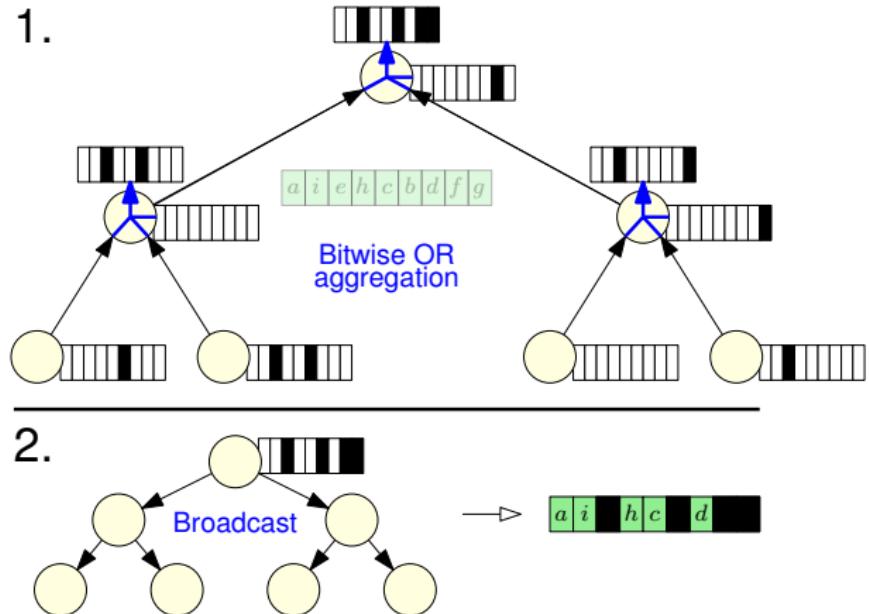
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- Compensate for filtered clauses next sharing!



LBD Values

- Clause quality metric, central for whether to keep a clause
- Some solvers keep clauses with LBD 2 indefinitely
 - but expect a single solver's clause volume!

LBD Values

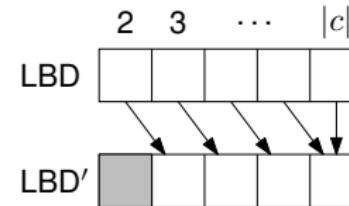
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- Use original LBD values of imported clauses? [HordeSat]
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Our current approach: Increment each LBD before import

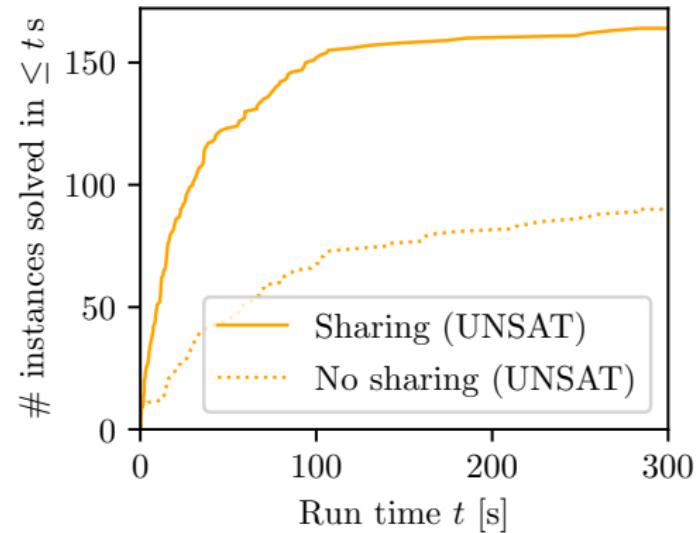
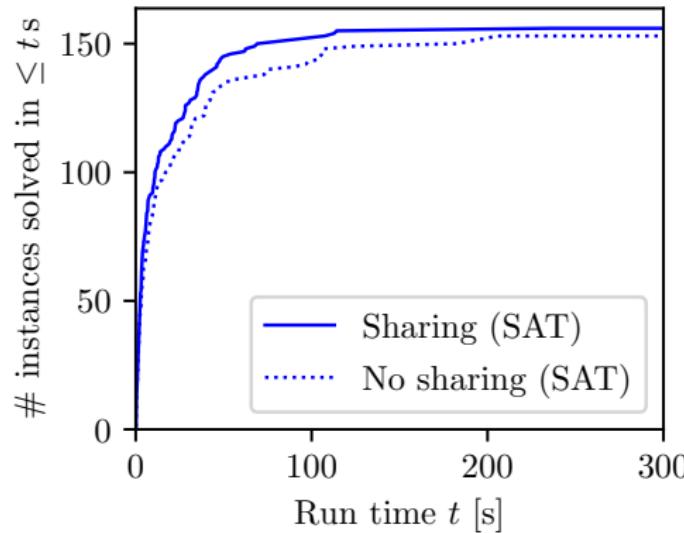
- Maintains LBD-based prioritization of clauses
- Solver keeps full control over its LBD-2-clauses
- “Regional clauses are the best!”



	Median RAM	PAR-2
Orig. LBD	108.8 GiB	75.7
Reset LBD	95.6 GiB	74.3
LBD++	97.3 GiB	72.9

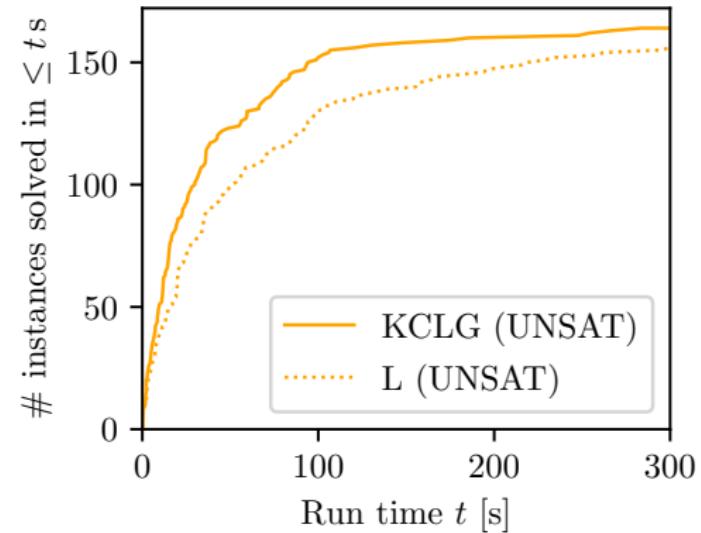
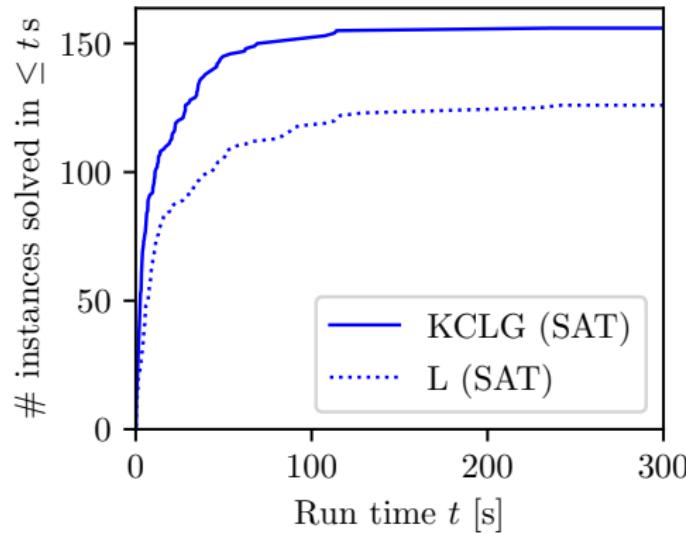
768 cores × 349 instances × 300 s

Merit of Clause Sharing, SAT vs. UNSAT



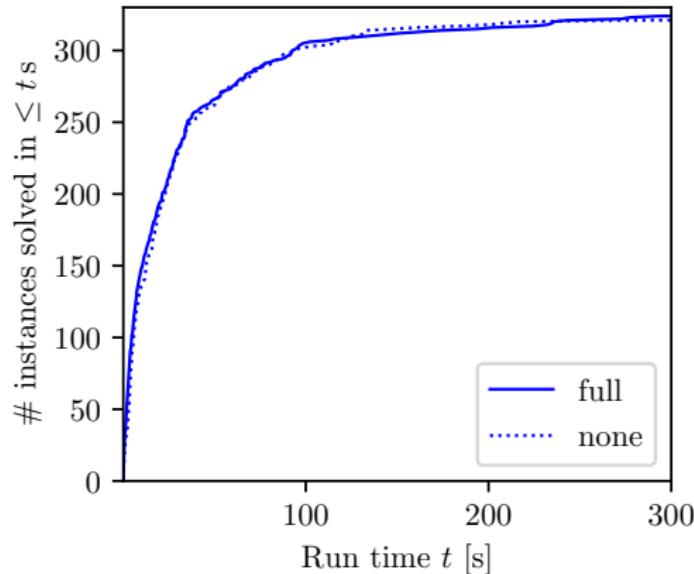
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Merit of Diverse Portfolio, SAT vs. UNSAT



768 cores \times 349 “solvable” instances from ISC 2022 \times 300 s, with clause sharing

Merit of Diversification ... None??

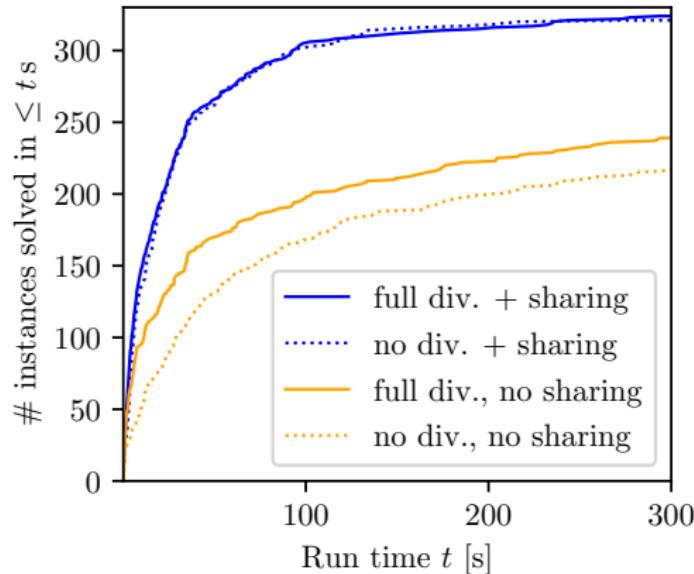


- “full”: 36 solver configs + random seeds + noisy parameters + input permutation + a few solvers not importing clauses
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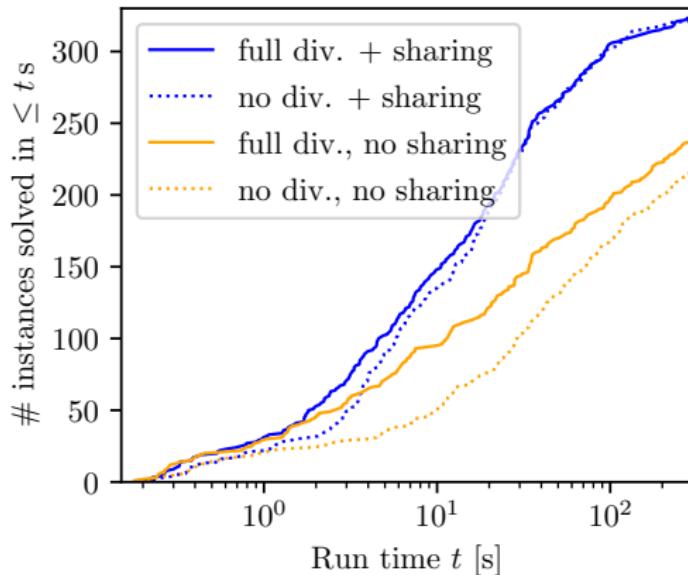
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- Without clause sharing diversification helps a lot!
- Clause sharing appears to **absorb common diversification techniques!** How?
- Hypothesis:
 - ➊ Shared clauses arrive at solvers at different times
 - ➋ Solvers vary in when (and what) they import
 - ➌ “Butterfly effect”
 - ➍ **Clause sharing as search space pruning:** solvers won’t re-explore pruned branches!

Scaling and Speedups

Updated HordeSat
(Lingeling)

vs.

Mallob
(Kissat-CaDiCaL-Lingeling)

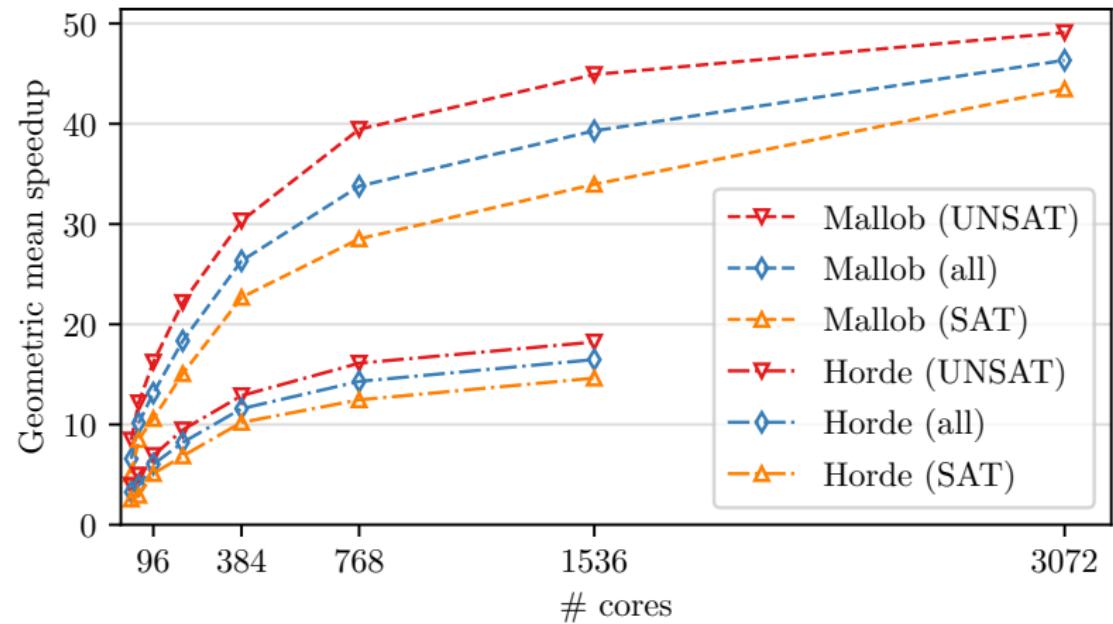
Sat Comp. 2021 benchmarks

Sequential baseline:

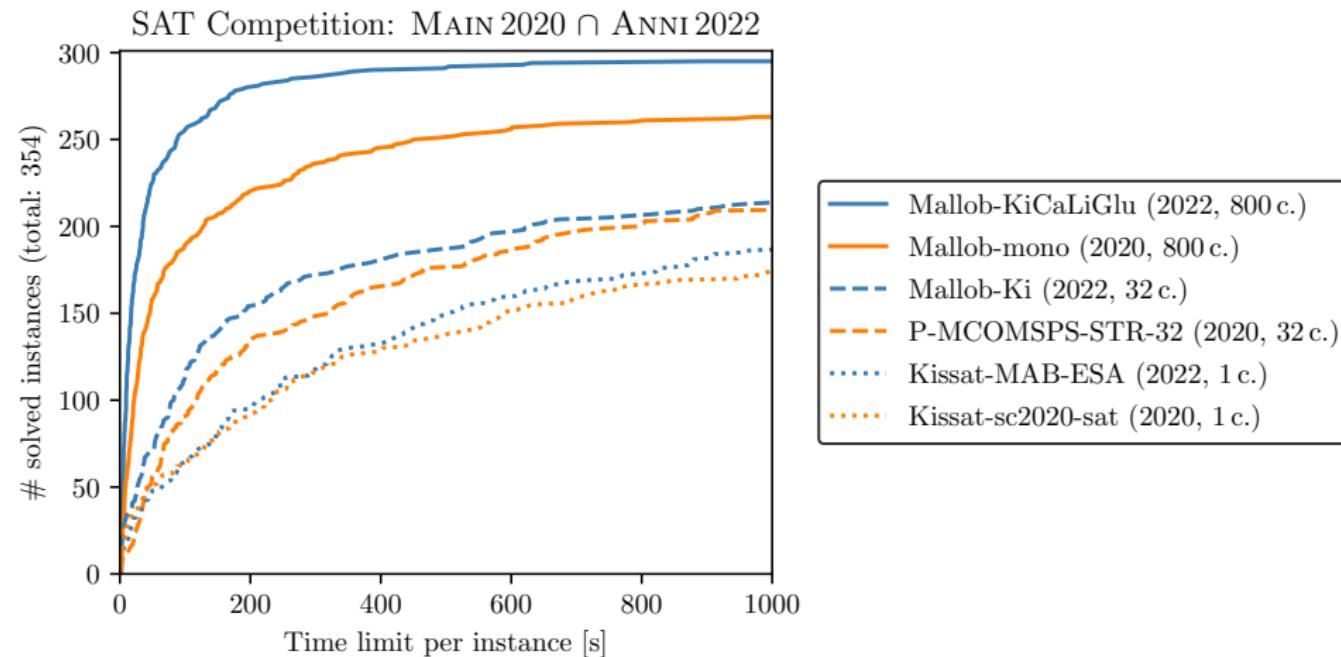
Kissat_MAB_HyWalk

Seq. time limit: 115200 s

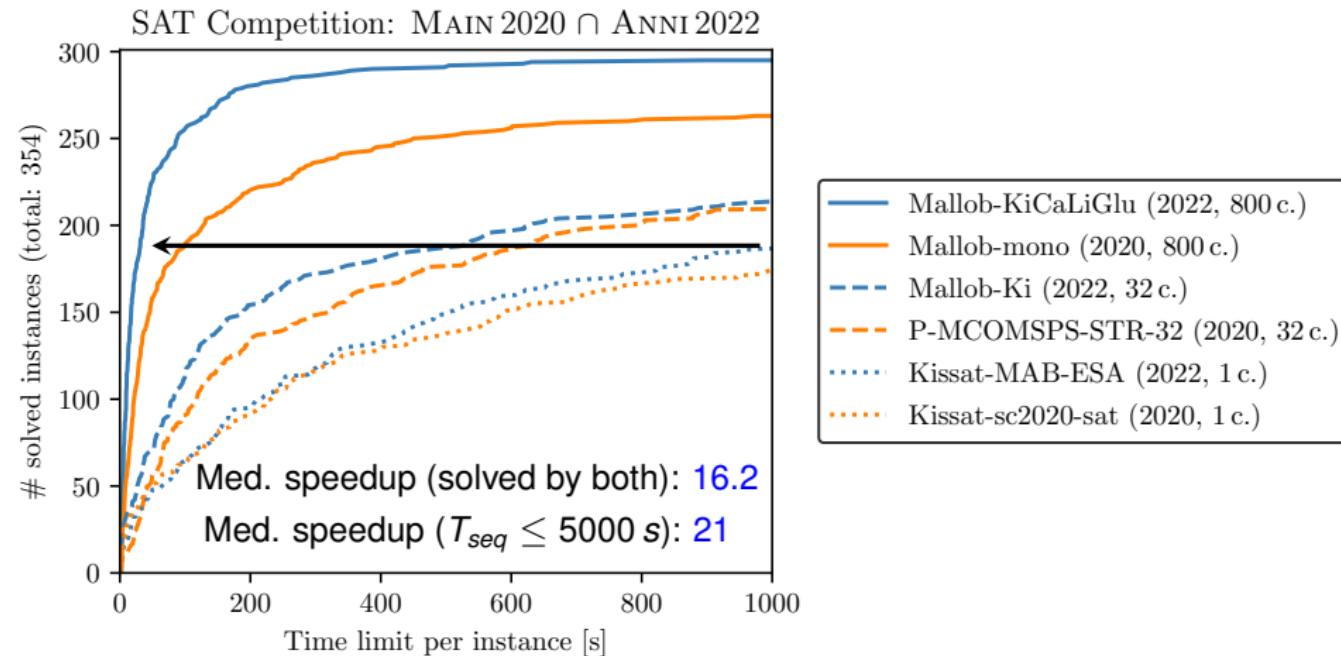
Par. time limit: 300 s



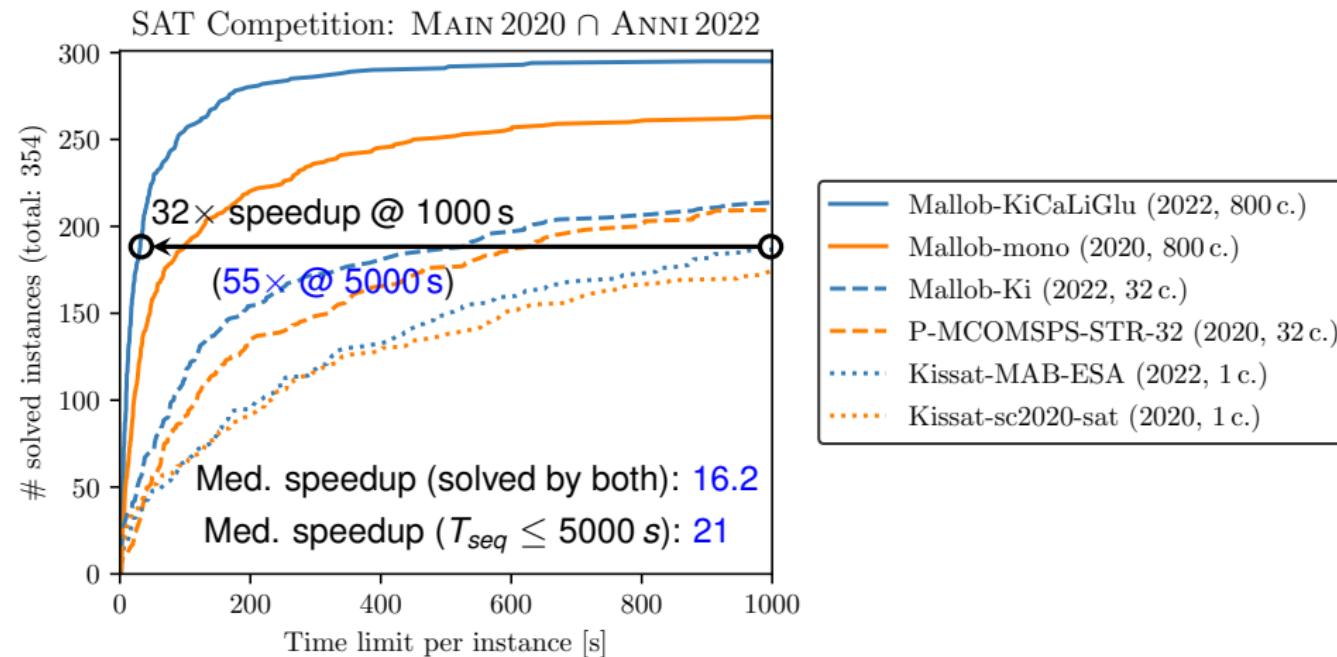
SAT Competition 2022



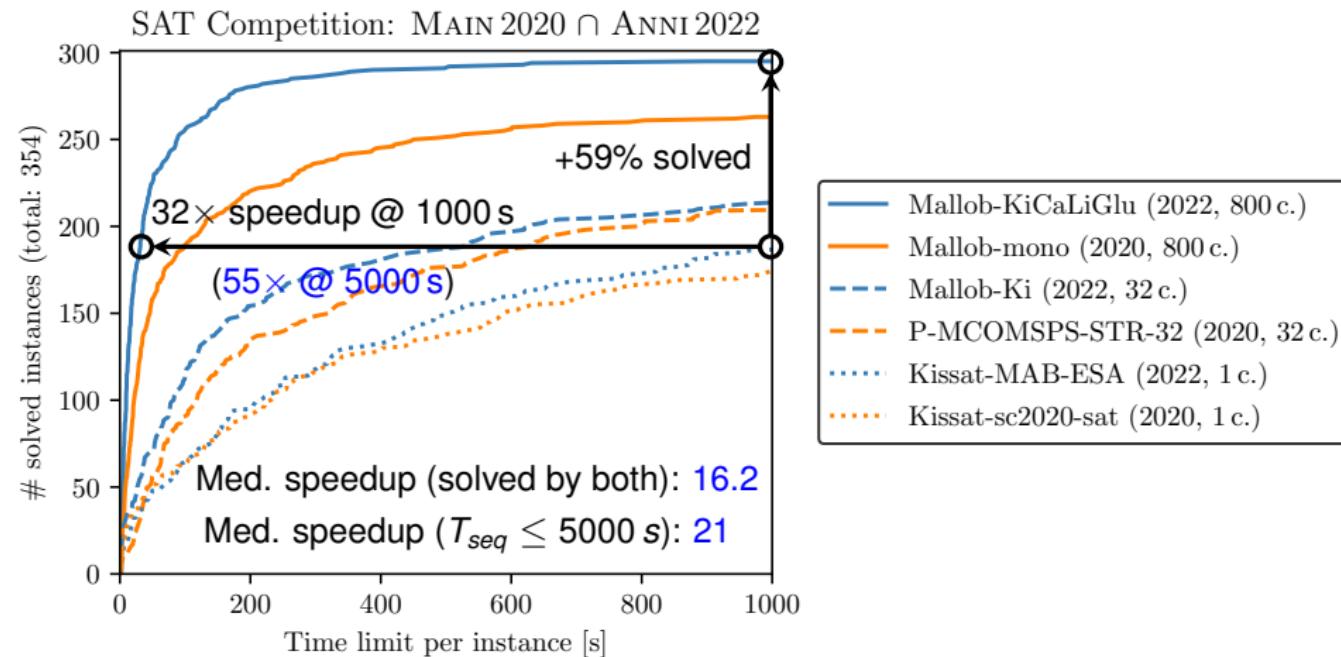
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Better Efficiency?

Massive parallelism for a single formula

- Faster solving times
- Can resolve problems out of reach for sequential solvers
- Not that resource efficient (on average)

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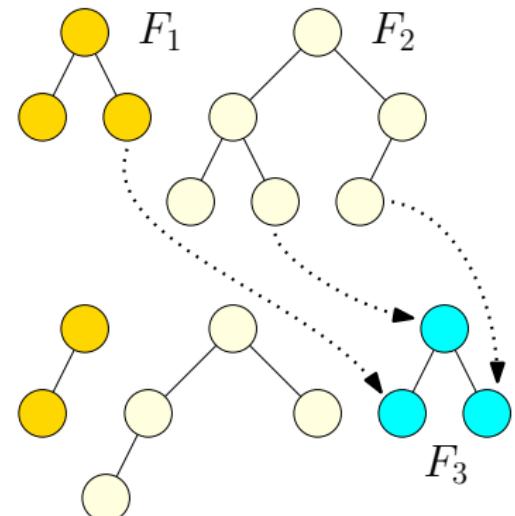
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Solving many formulas in parallel

- Embarrassingly parallel
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Best of both worlds? [EuroPar'22]

- On demand scheduling of incoming (SAT) jobs
- Resize jobs during their execution as needed
- Few milliseconds to schedule an incoming job,
full utilization whenever sufficient demand is present



Solving 400 Formulae on up to 6400 Cores

Problem statement

You allocate $x \in \{400, 1600, 6400\}$ cores for 2 h.

You have 400 formulae (SAT Comp. '21) to solve. Go.

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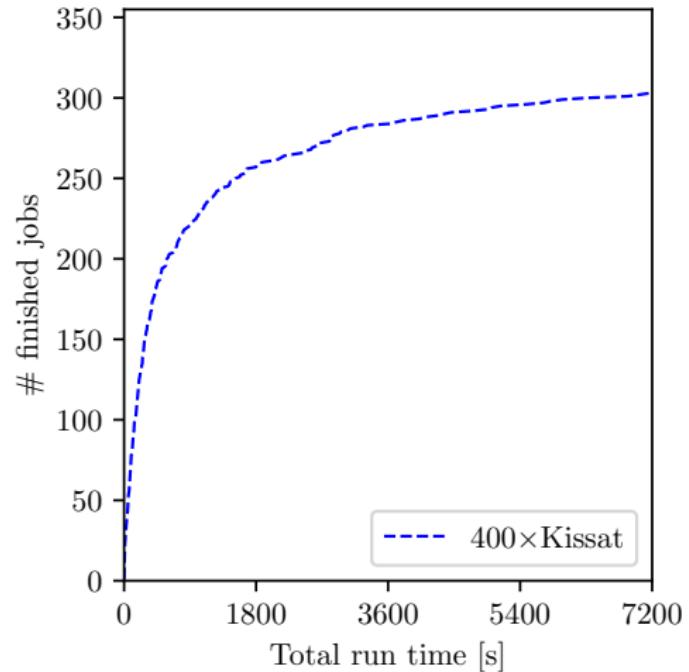
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Extreme 1: 400 Kissats in a trenchcoat

- No intra-job parallelism
- Embarrassingly parallel job processing
(inter-job parallelism)
- Great resource efficiency



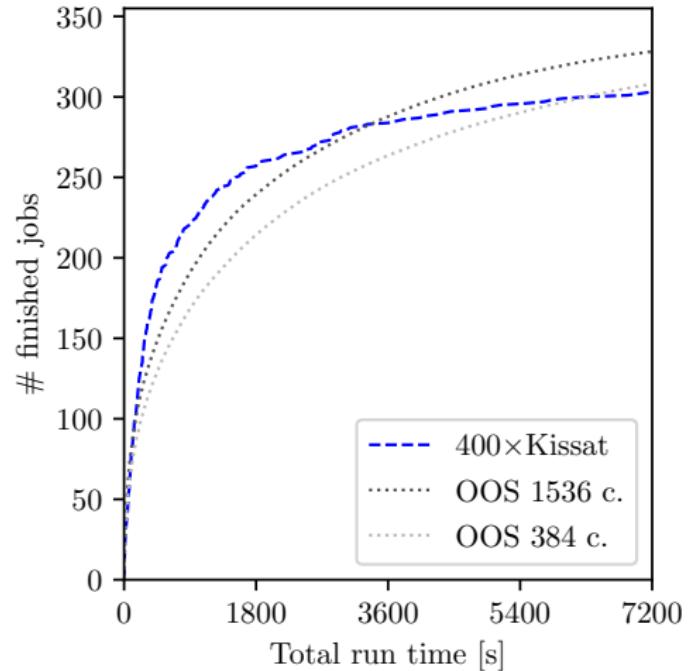
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Extreme 2: Massively parallel solving of each job

- One job at a time
- Assumption: Optimal Offline Schedule (OOS)
— instances sorted by run time ascendingly
- No inter-job parallelism
- Maximum speedups from parallel SAT
- Poor resource efficiency



Solving 400 Formulae on up to 6400 Cores

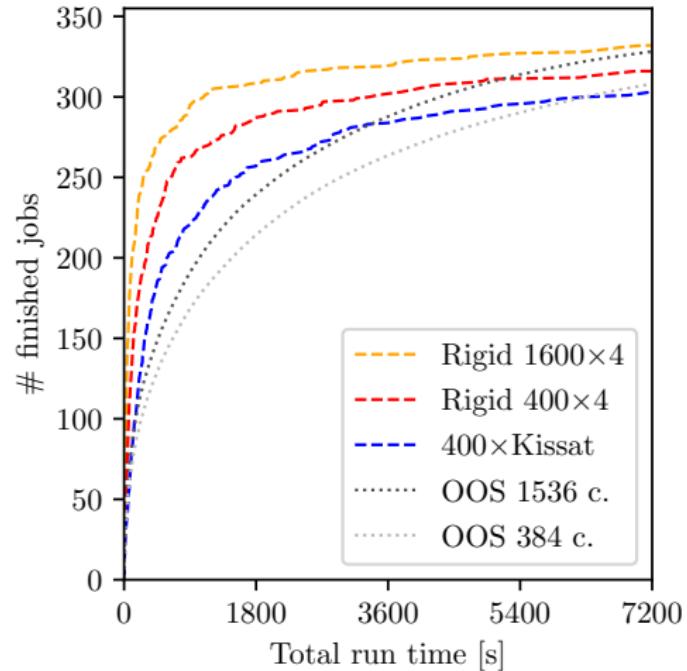
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Middle ground 1: Divide cores evenly among jobs

- Solid speedups at low-degree parallel SAT
- At the beginning, all cores are used
- After < 15 min, < 50% of cores are used



Solving 400 Formulae on up to 6400 Cores

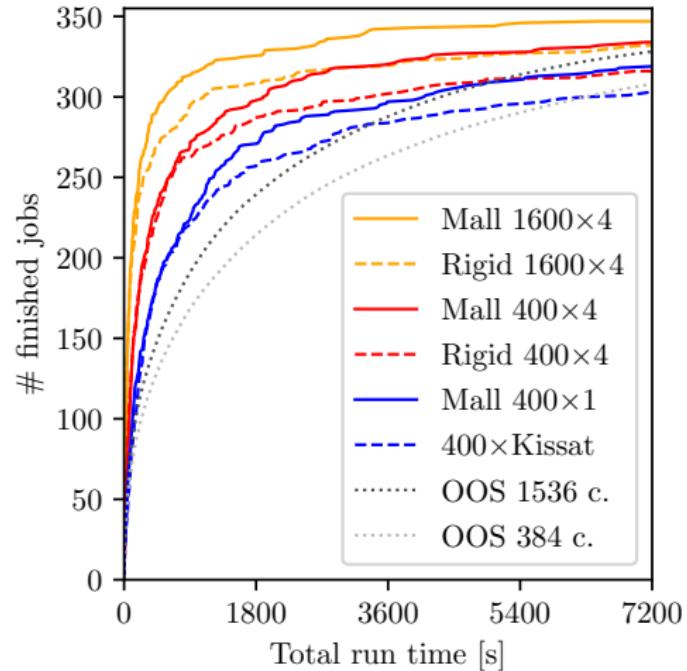
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Middle ground 2: Divide cores **dynamically** among jobs

- Finishing jobs **yield resources** to remaining jobs
 - eventually exceeding **$4 \times$ their initial resources**
- Uses 100% of resources 100% of the time
- At 400 cores: Dominates $400 \times$ Kissat!
 - shows low overhead of scheduling



Mallob: Harvest



TACAS'23: UNSAT Proofs for Distributed Solvers

Issue

Parallel clause-sharing solvers do not support the production of unsatisfiability proofs.

- Real, practical issue
 - Some competition results of cloud solvers proved to be incorrect later!
 - Growing scale of computation ⇒ Growing probability of failures
- Prior approaches unsatisfactory
 - Limited to single machine
 - Not scalable at all

Objective

Introduce scalable production of unsatisfiability proofs for distributed clause-sharing SAT solvers, allowing to fully trust their results and exploit their power for critical applications.

Background: Distributed Clause-Sharing SAT Solving

Process #1

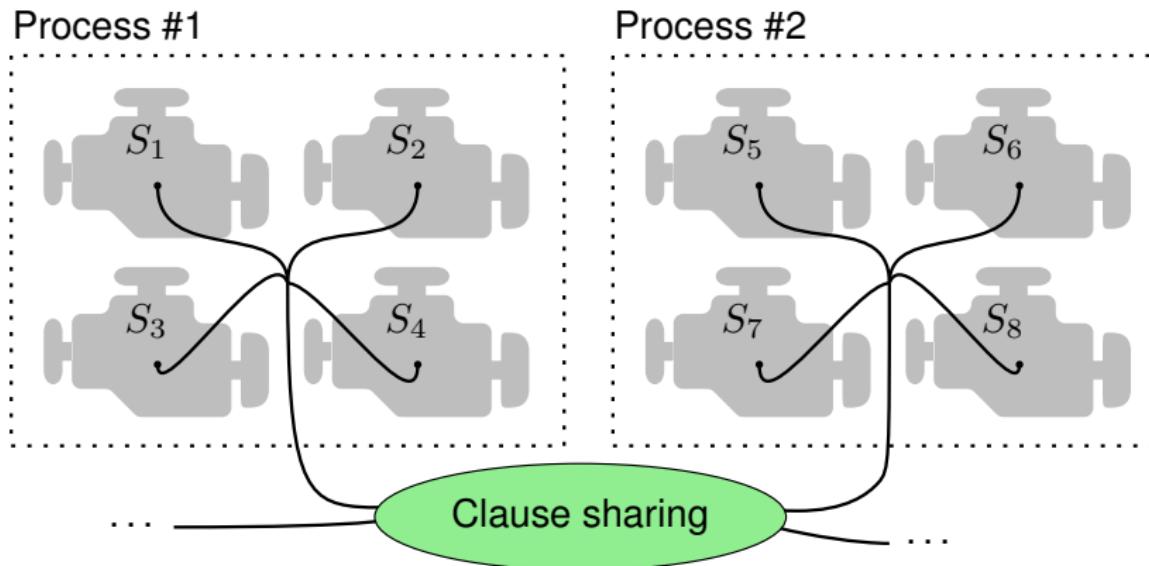


Process #2

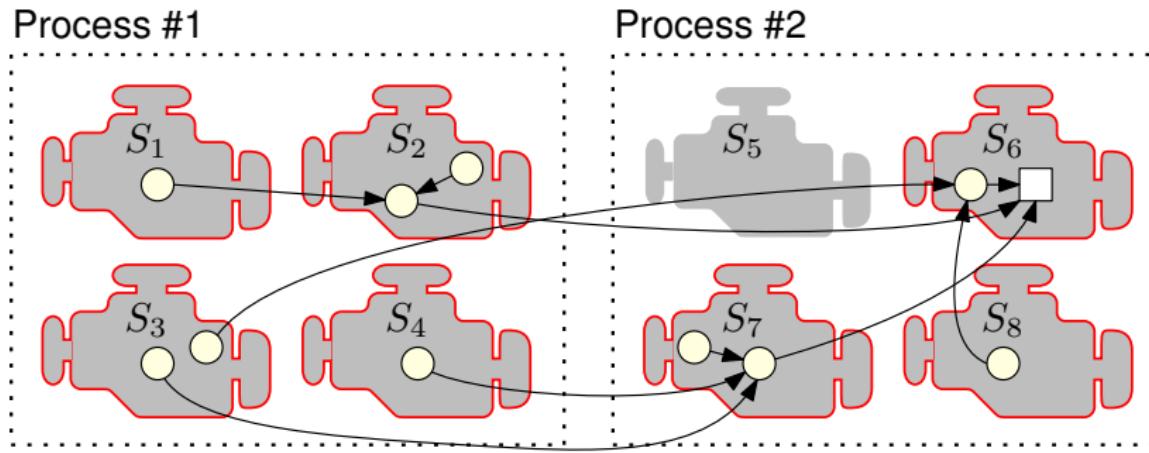


Portfolio of different CDCL solver configurations
≈ producers of conflict clauses

Background: Distributed Clause-Sharing SAT Solving



Background: Distributed Clause-Sharing SAT Solving



Which Proof Format?

DRAT proof format

add $\overline{x_3}$

add x_1x_2

add $\overline{x_1}$

delete $\overline{x_3}$

add $x_3\overline{x_4}$

add x_1x_3

add \square

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- + **compact** format
- + **prevalent** in solvers
- **costly** checking

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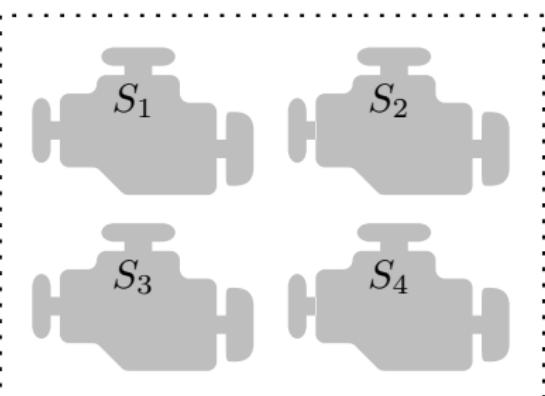
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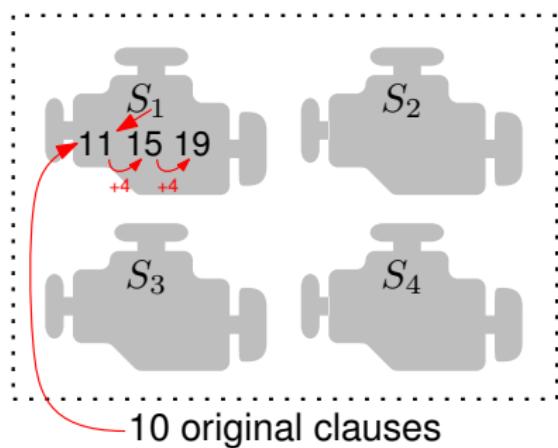
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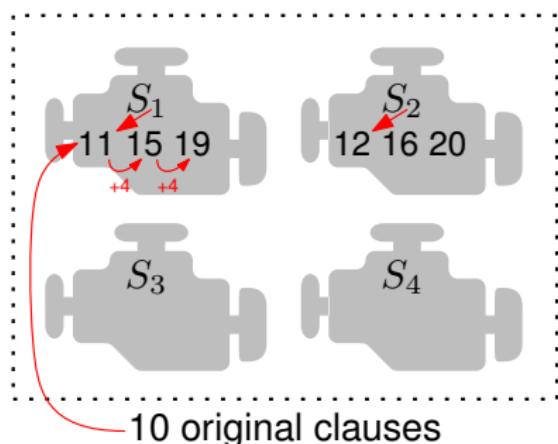
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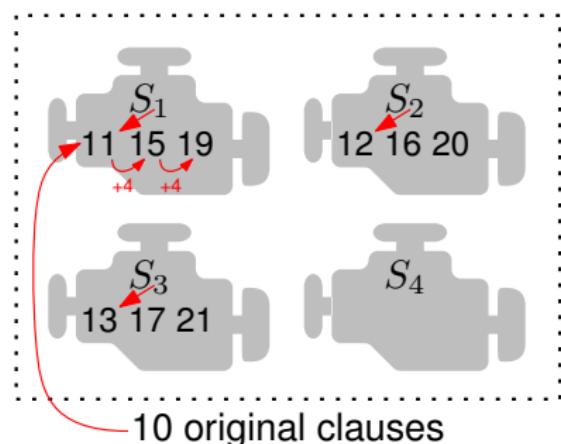
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 delete $\overline{x_3}$
 add $x_3\overline{x_4}$
 add x_1x_3
 add \square

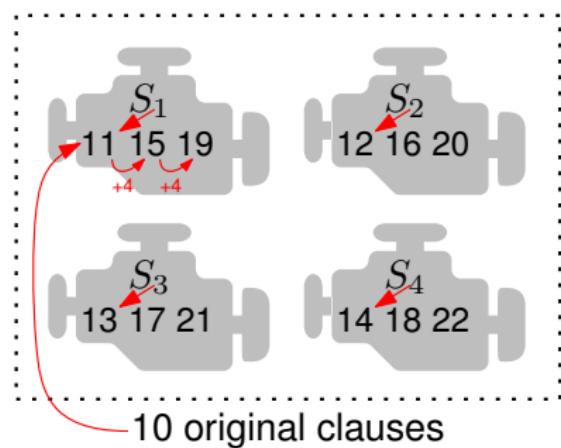
- + compact format
- + prevalent in solvers
- costly checking

LRAT proof format

add $c_9 := \overline{x_3}$ via c_5, c_4
 add $c_{10} := x_1x_2$ via c_3, c_2
 add $c_{11} := \overline{x_1}$ via c_6, c_9
 delete c_9
 add $c_{12} := x_3\overline{x_4}$ via c_7, c_{11}
 add $c_{13} := x_1x_3$ via c_8, c_{12}
 add $c_{14} := \square$ via c_{11}, c_{10}, c_1

- + more efficient checking
- + unique IDs for clauses
- + explicit dependencies!

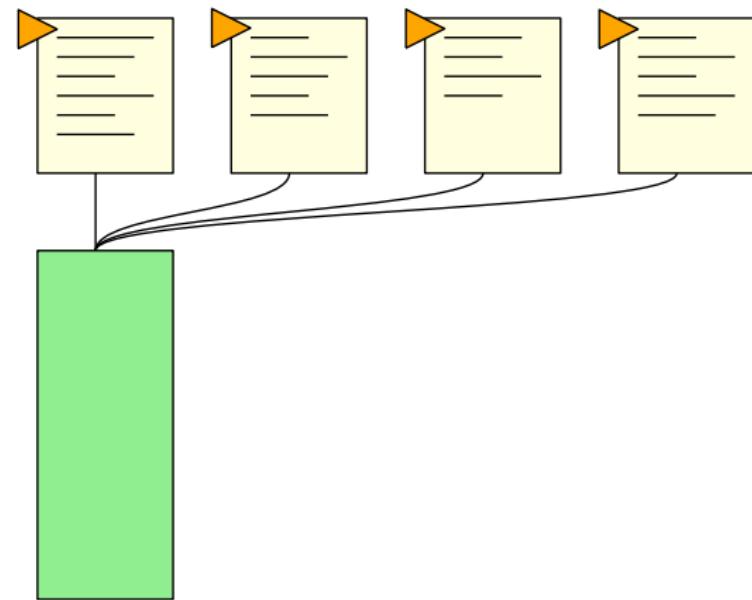
Unique LRAT IDs across solvers?



A Sequential Approach

1. Combination

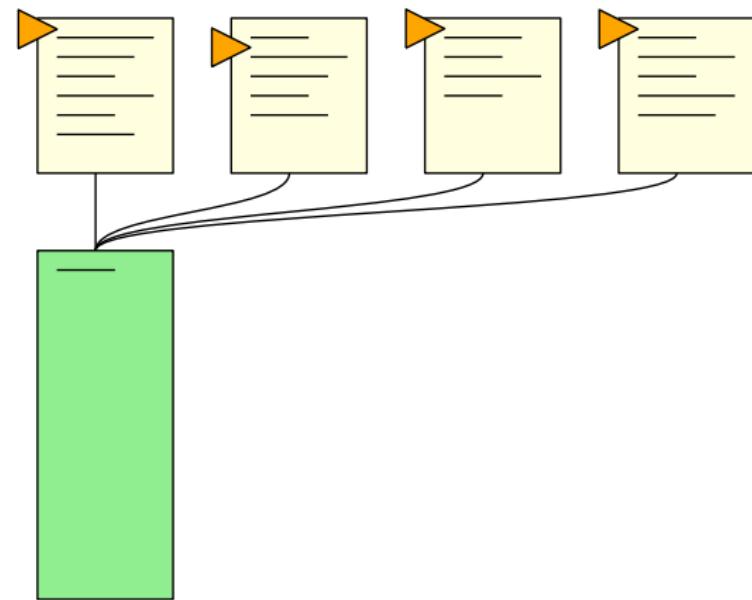
- Read all partial proofs simultaneously
- Output line \Leftrightarrow all dependencies d output



A Sequential Approach

1. Combination

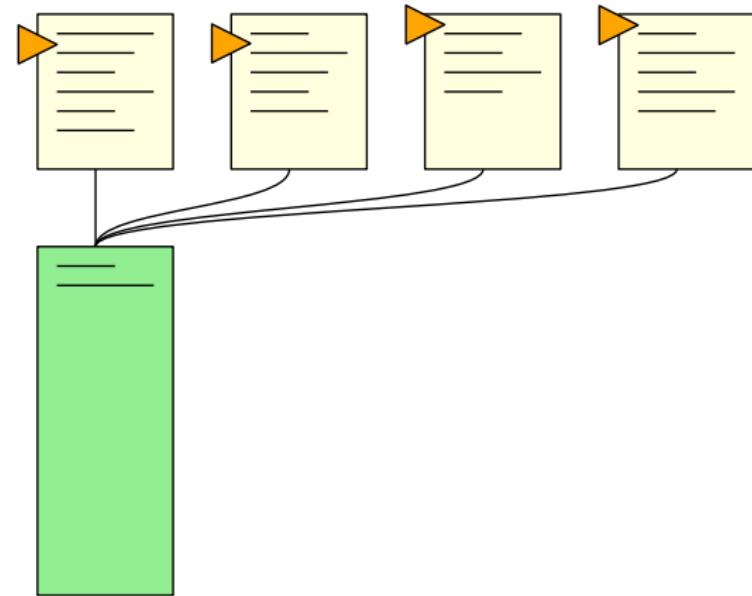
- Read all partial proofs simultaneously
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A Sequential Approach

1. Combination

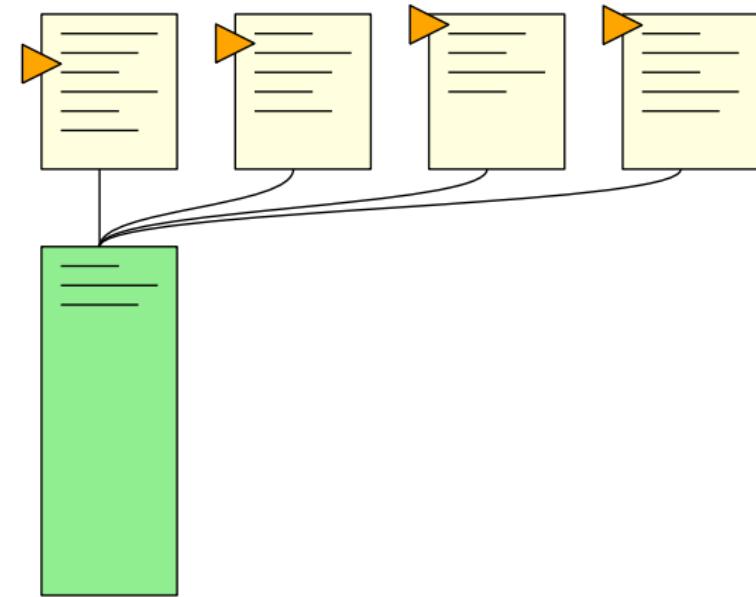
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A Sequential Approach

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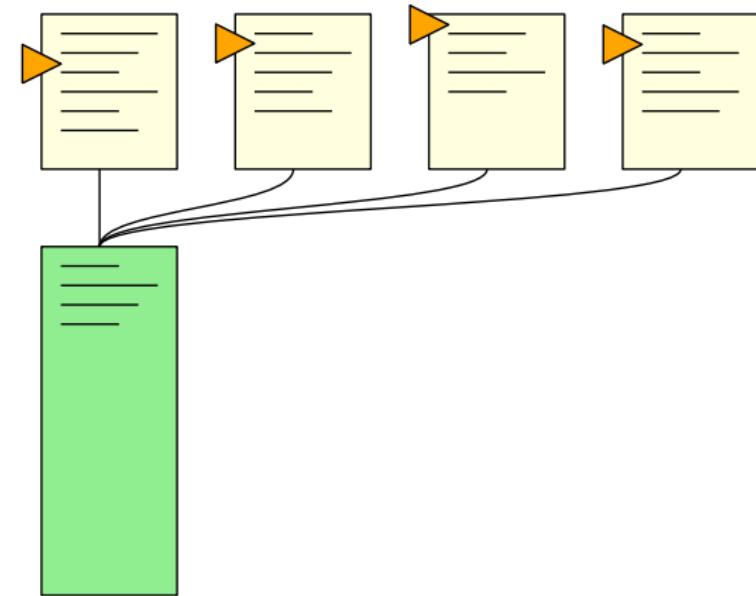
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A Sequential Approach

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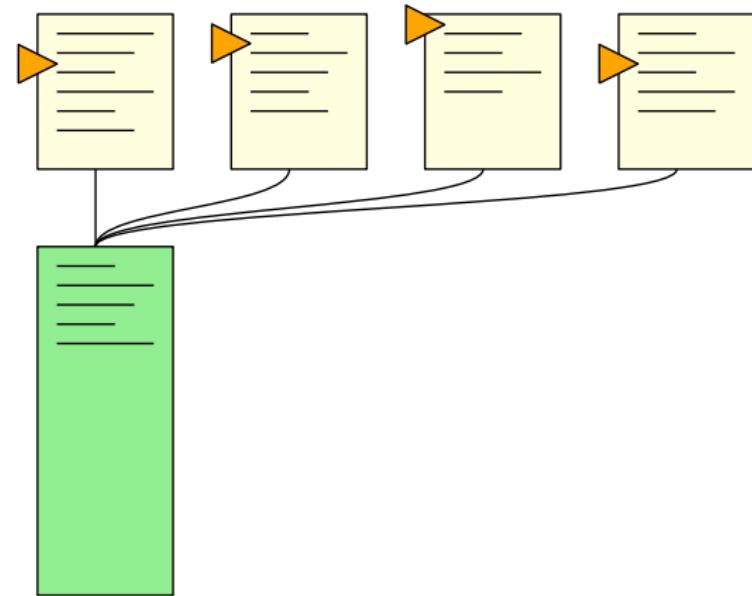
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A Sequential Approach

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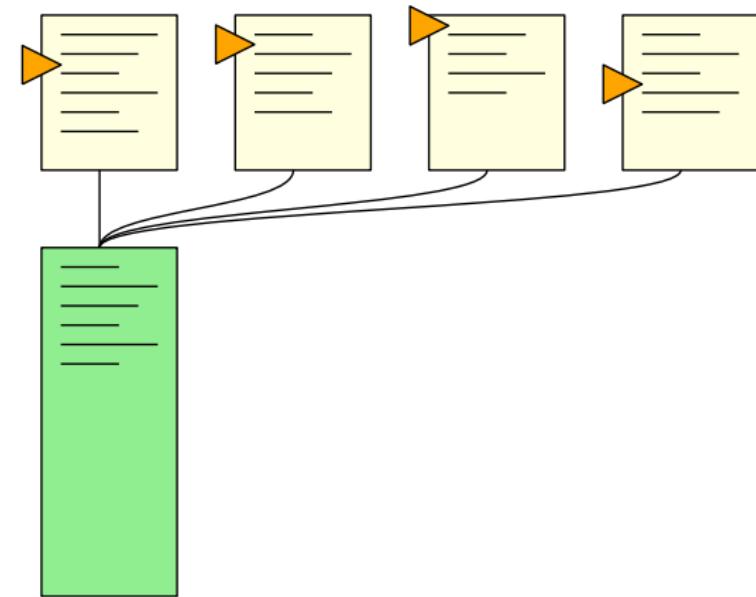
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A Sequential Approach

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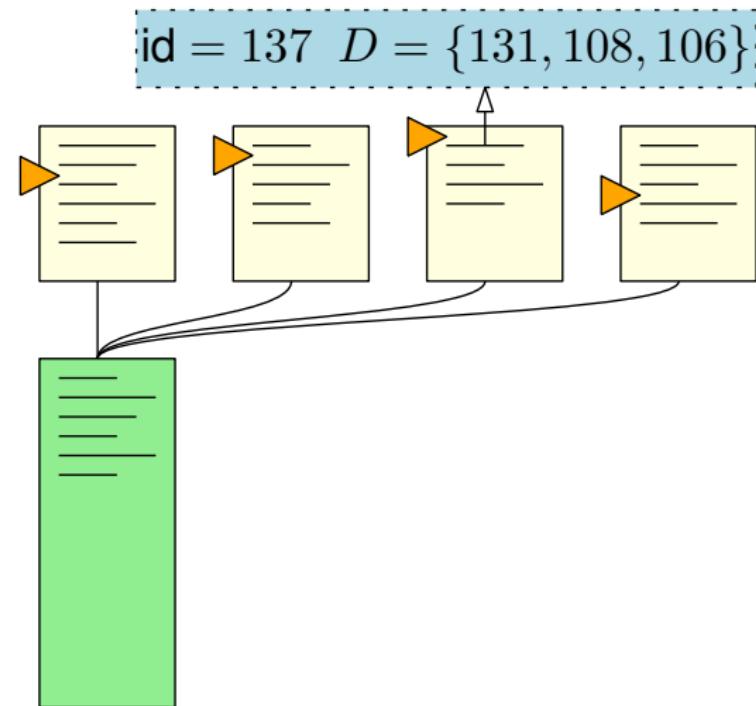
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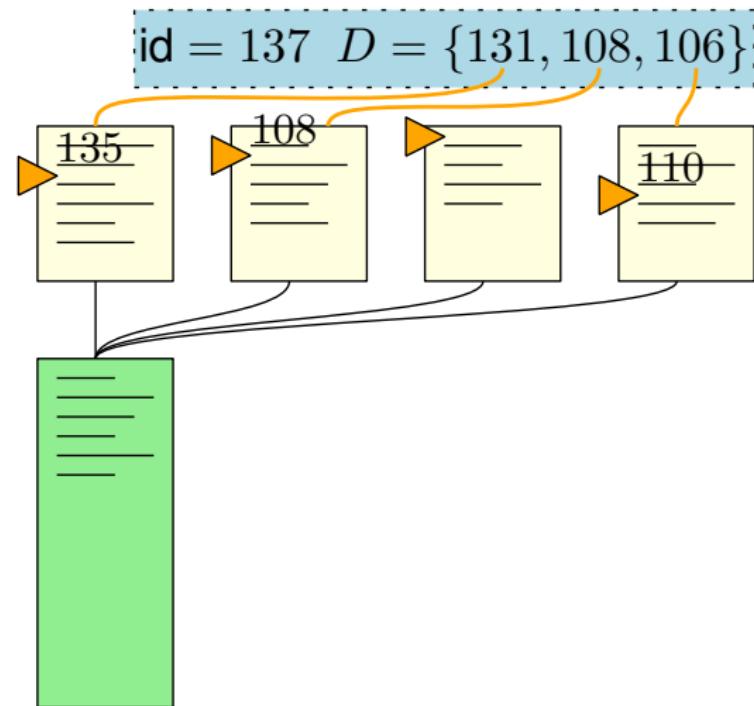
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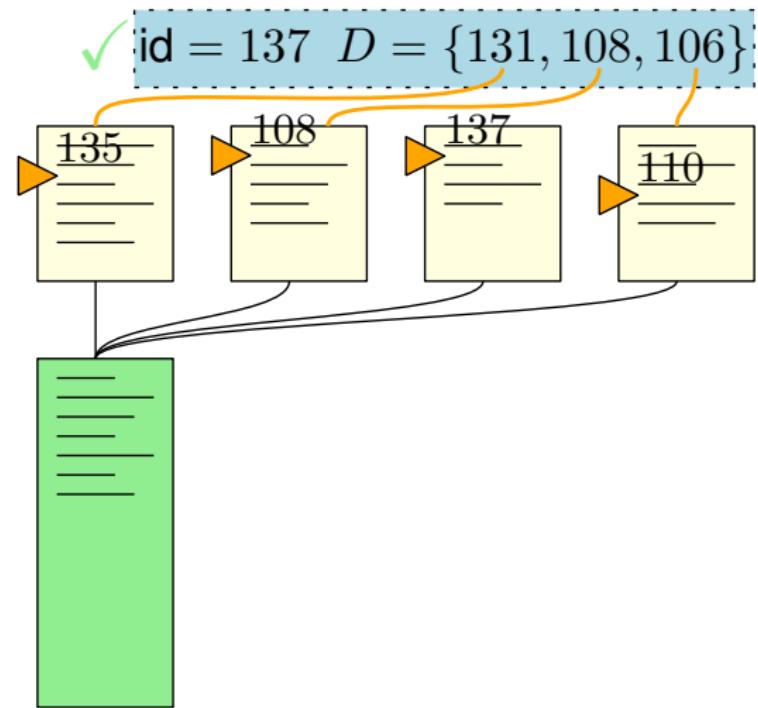
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A Sequential Approach

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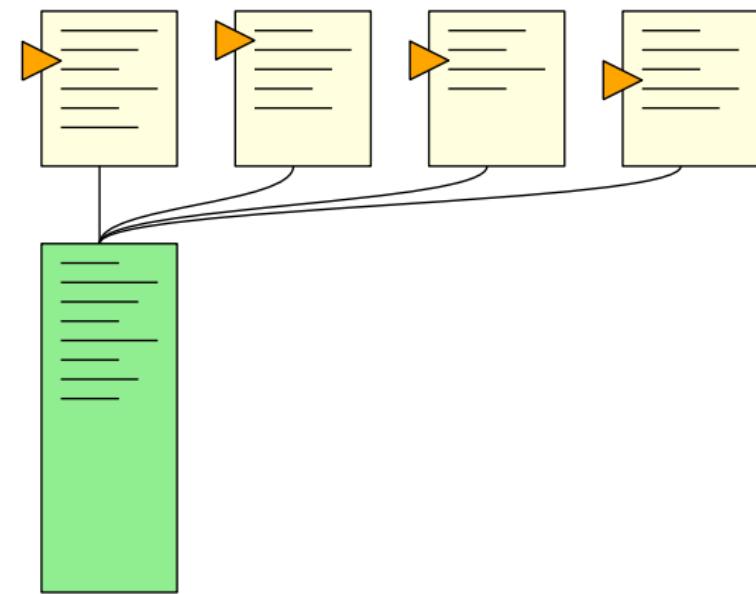
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A Sequential Approach

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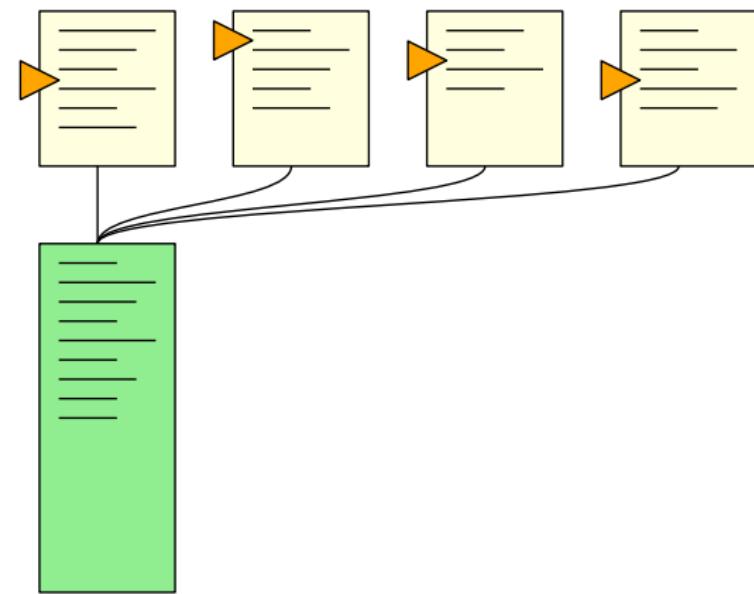
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A Sequential Approach

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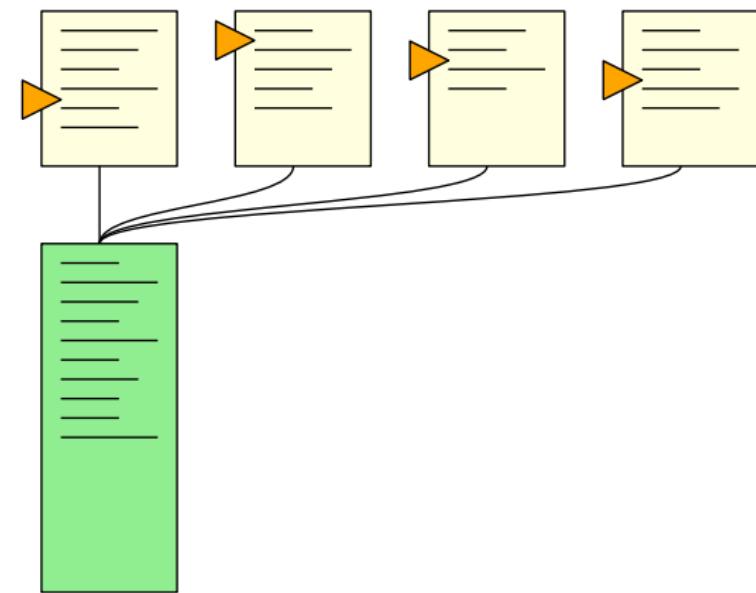
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A Sequential Approach

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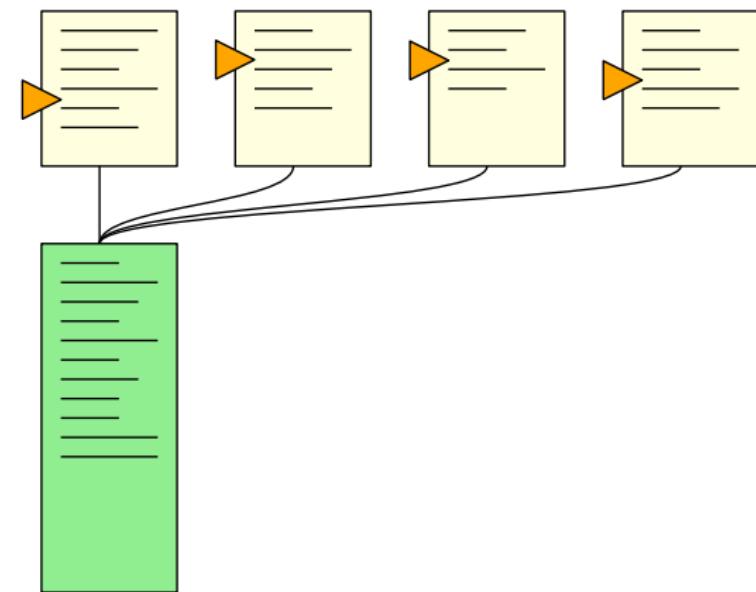
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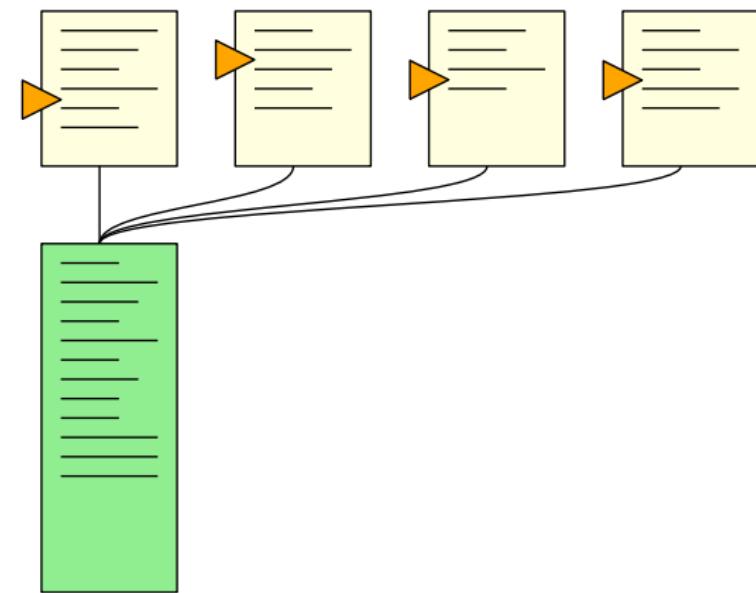
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A Sequential Approach

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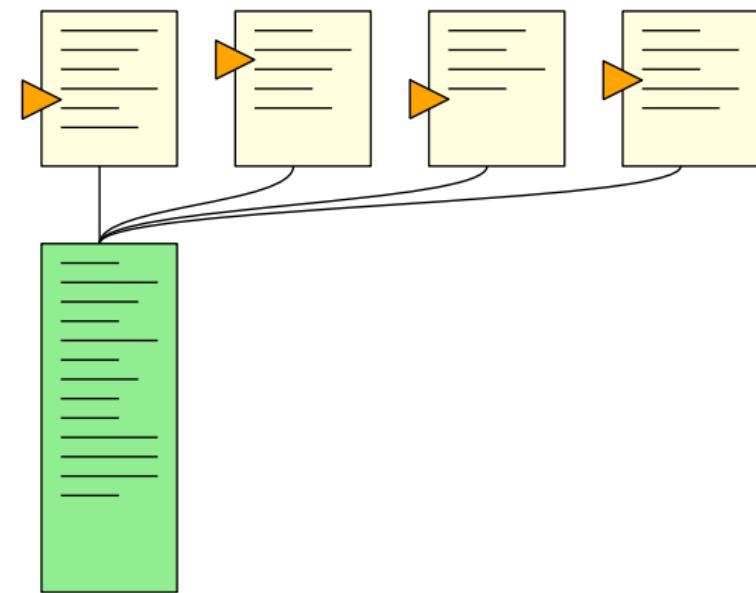
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A Sequential Approach

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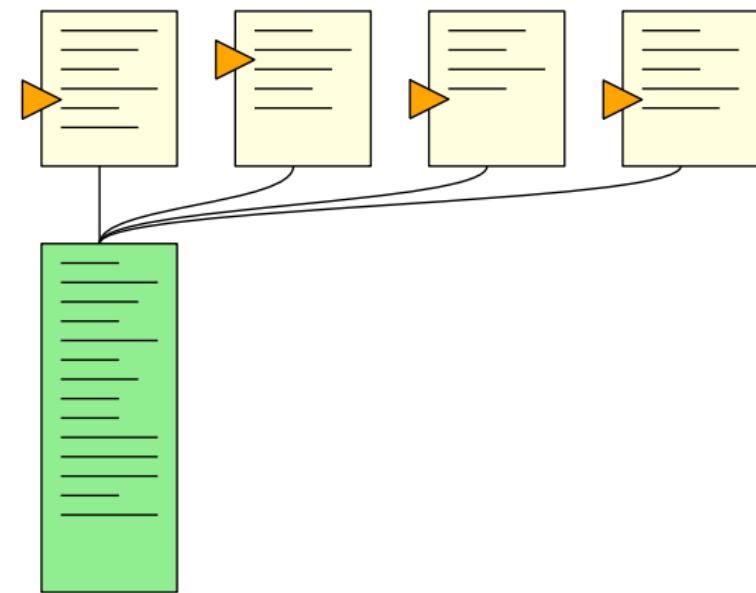
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A Sequential Approach

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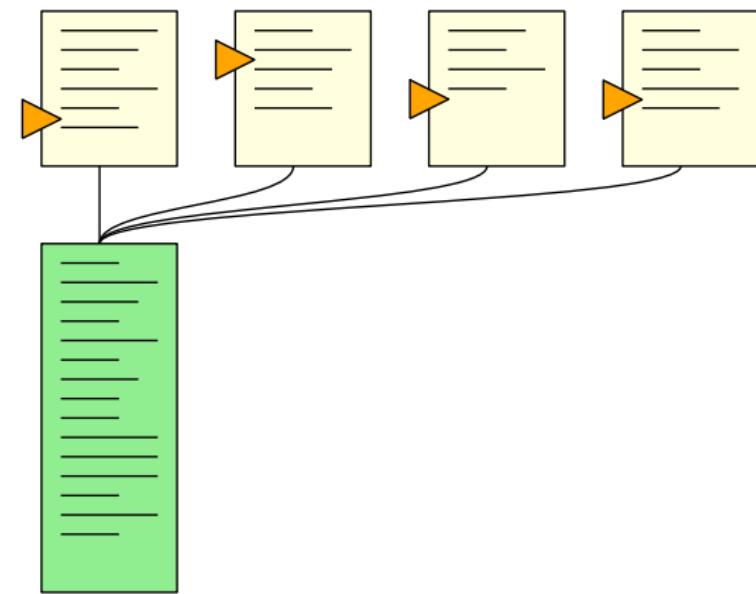
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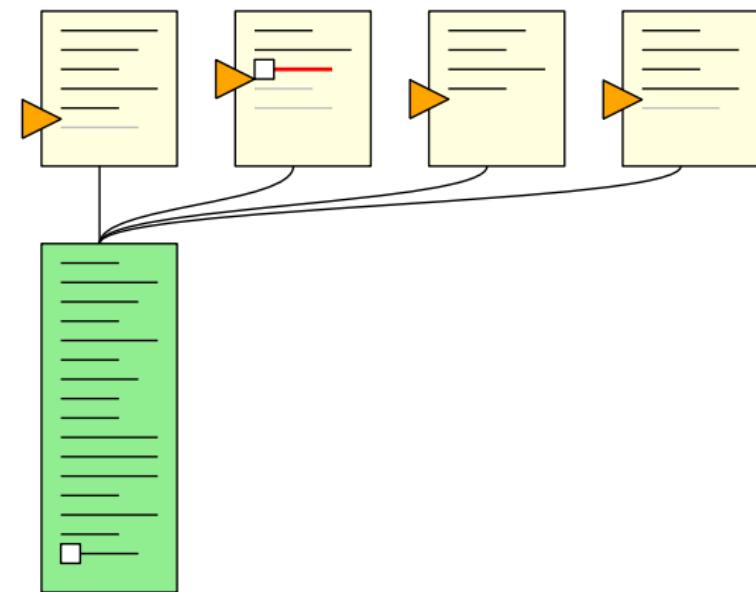
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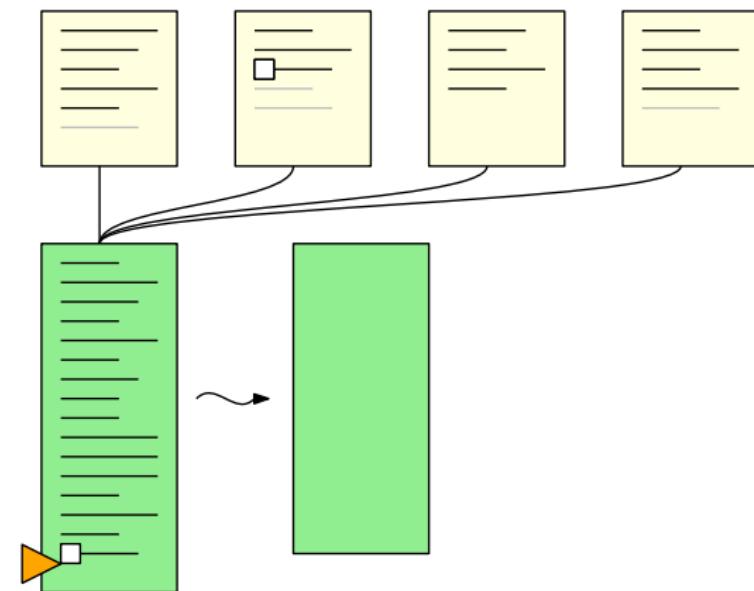
A Sequential Approach

1. Combination

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2. Pruning

- Required clauses $R := \{id(\square)\}$
- Read combined proof from back to front



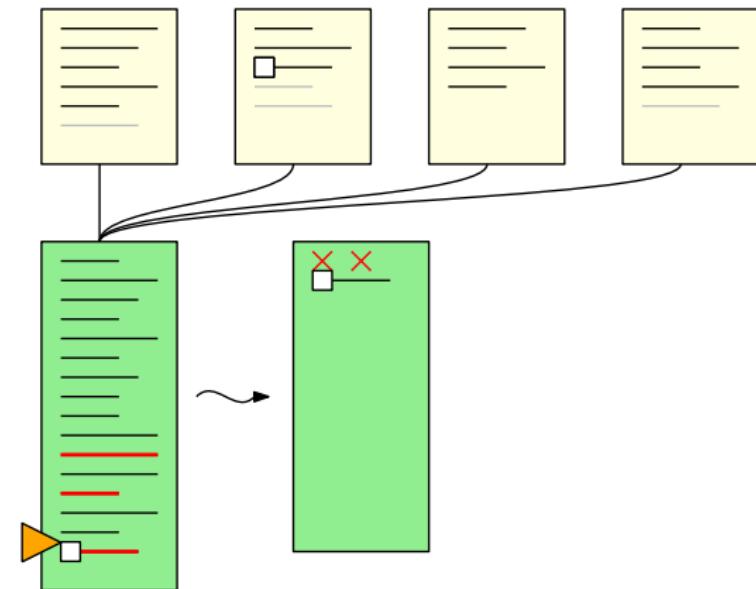
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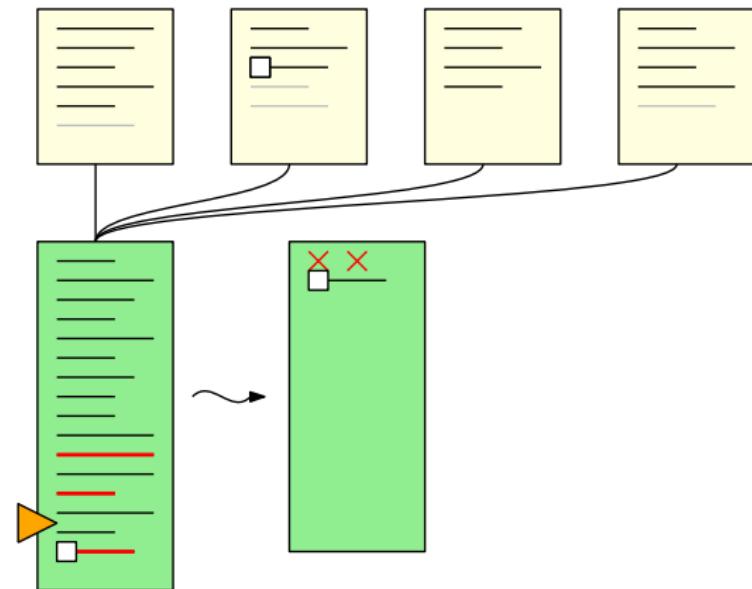
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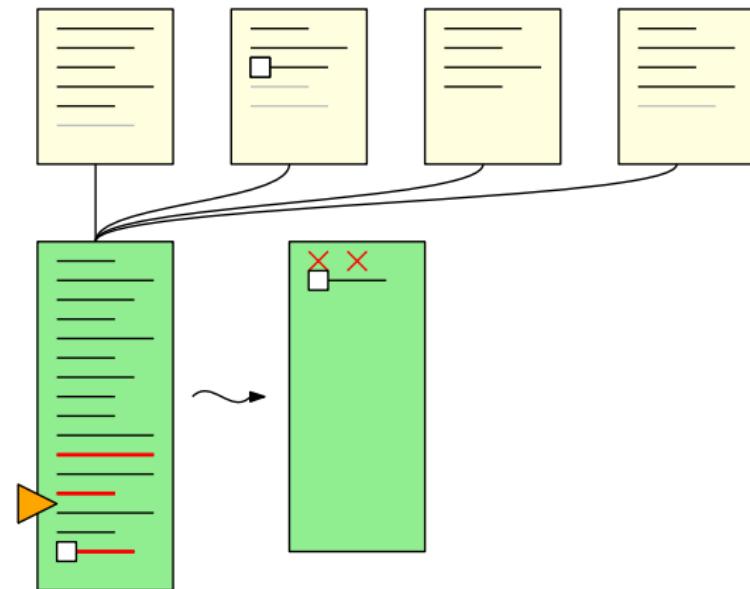
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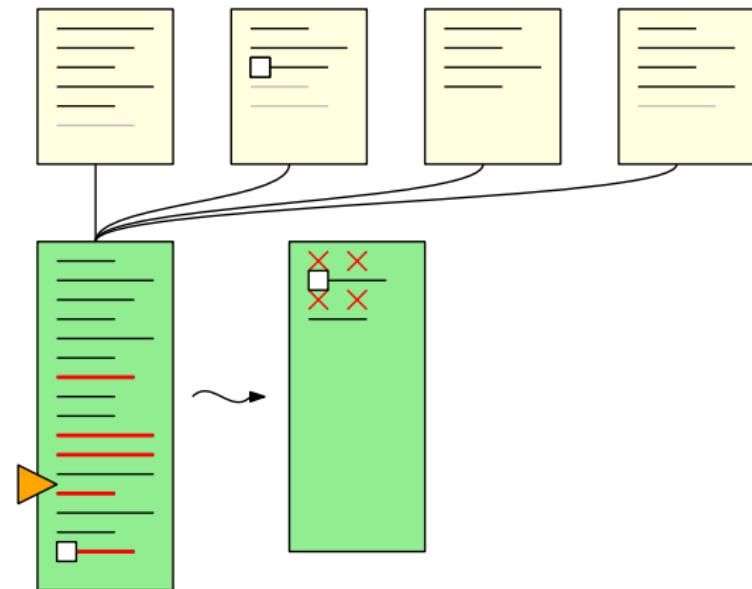
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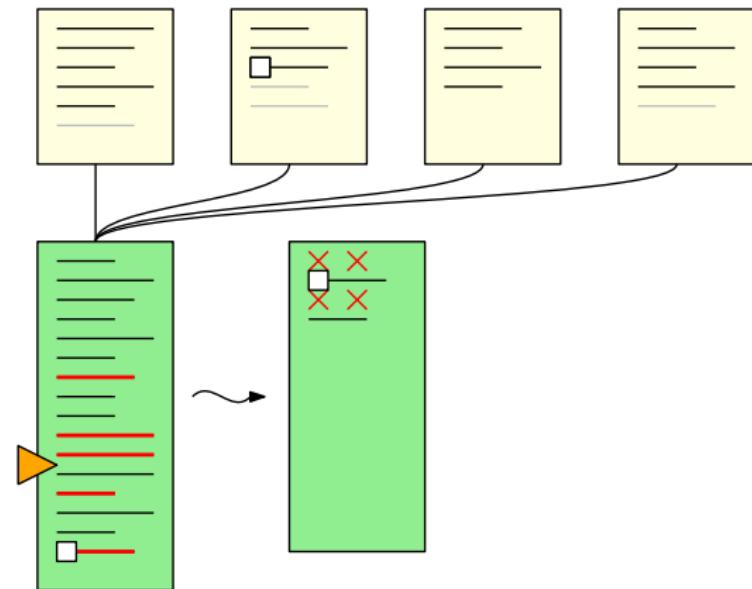
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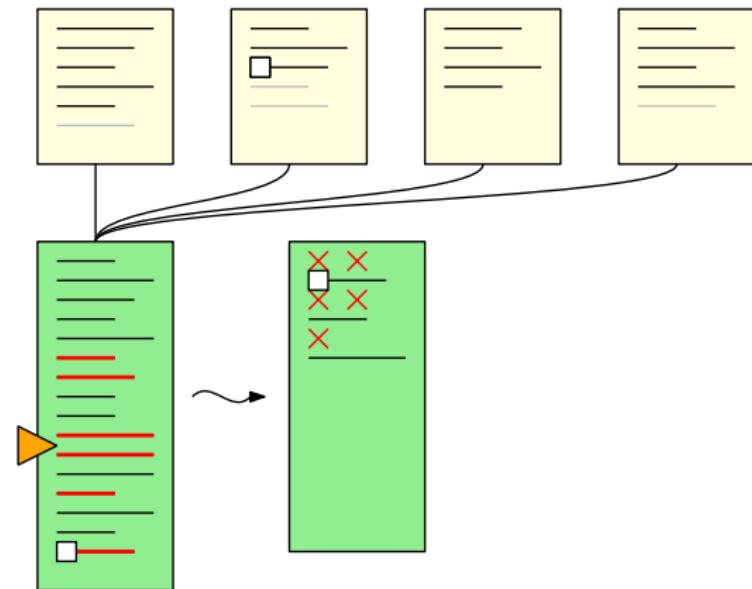
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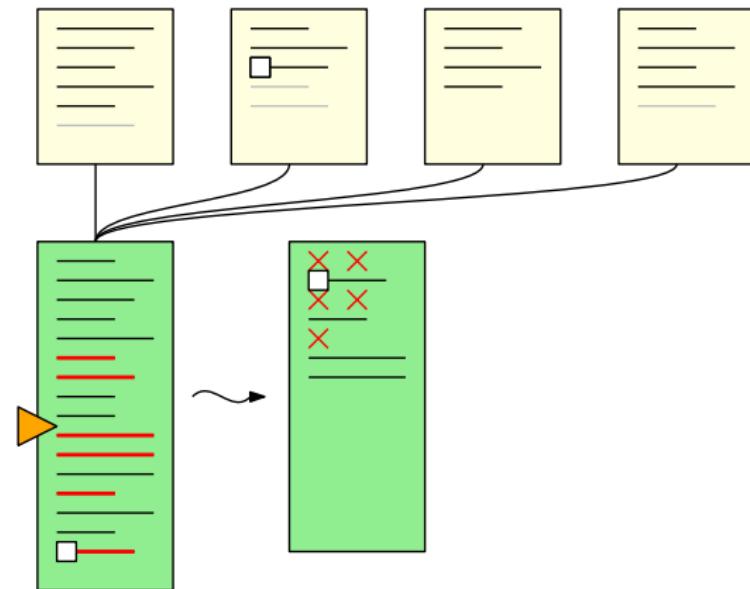
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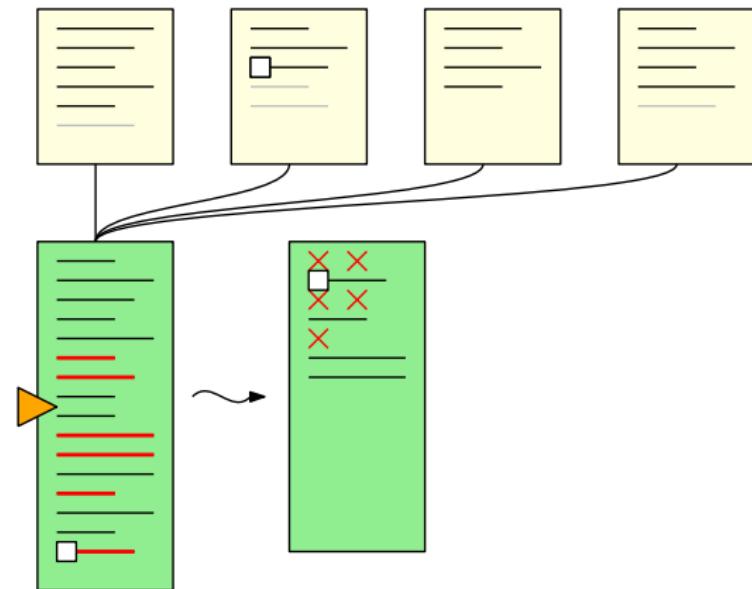
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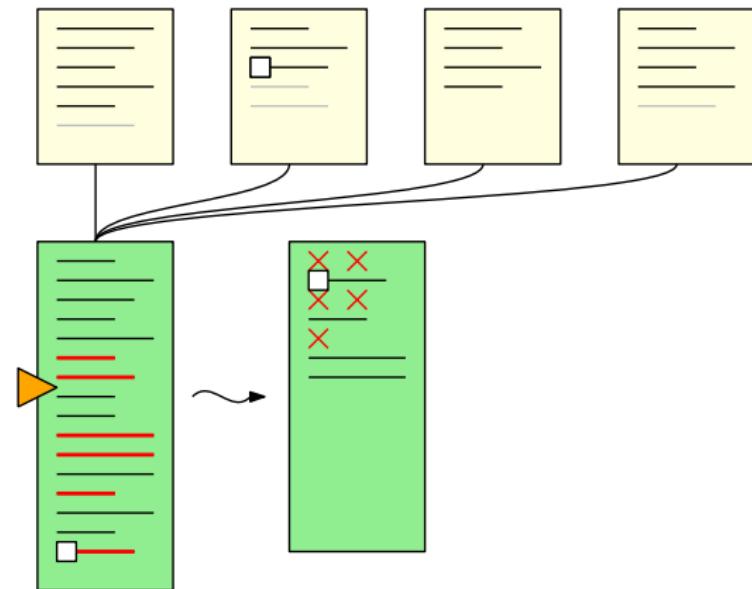
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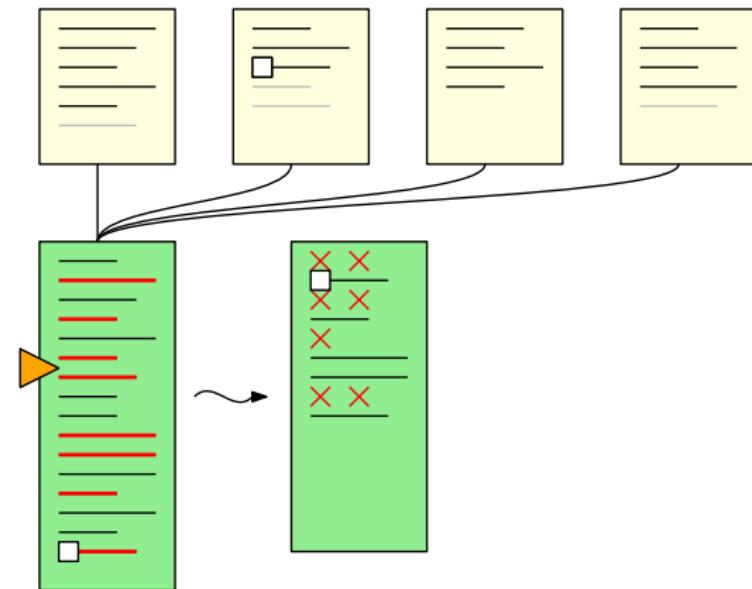
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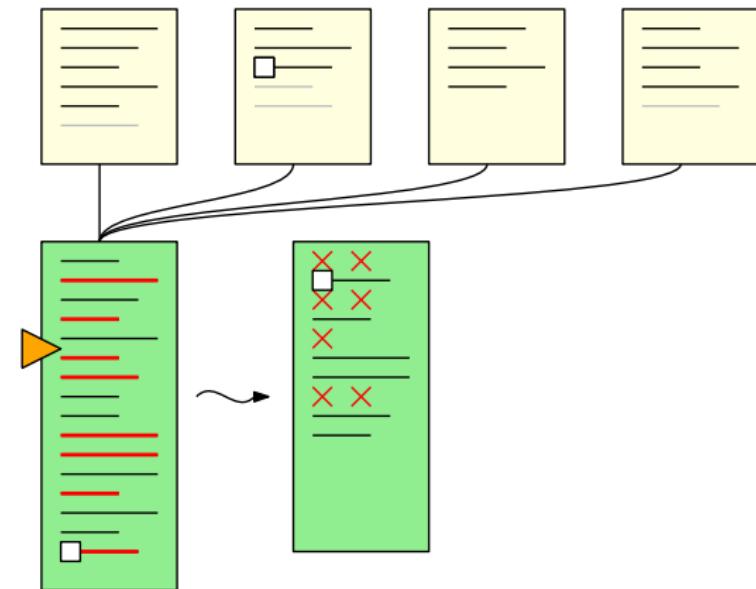
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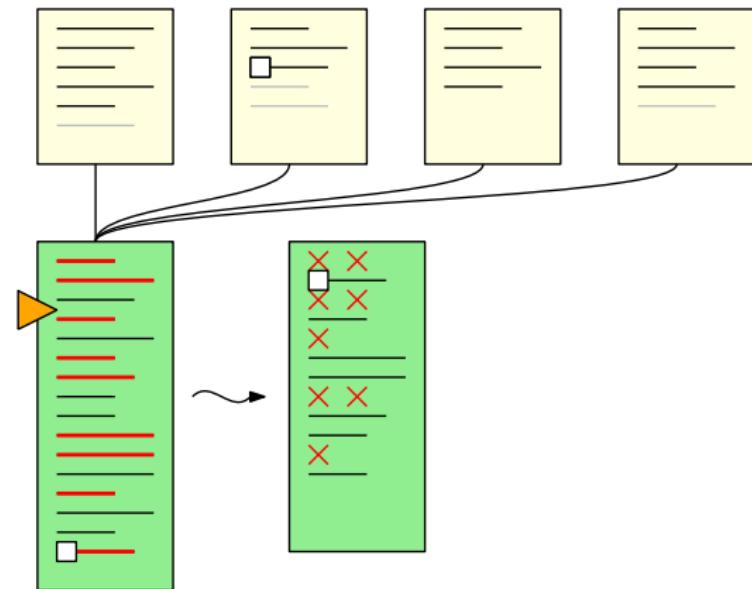
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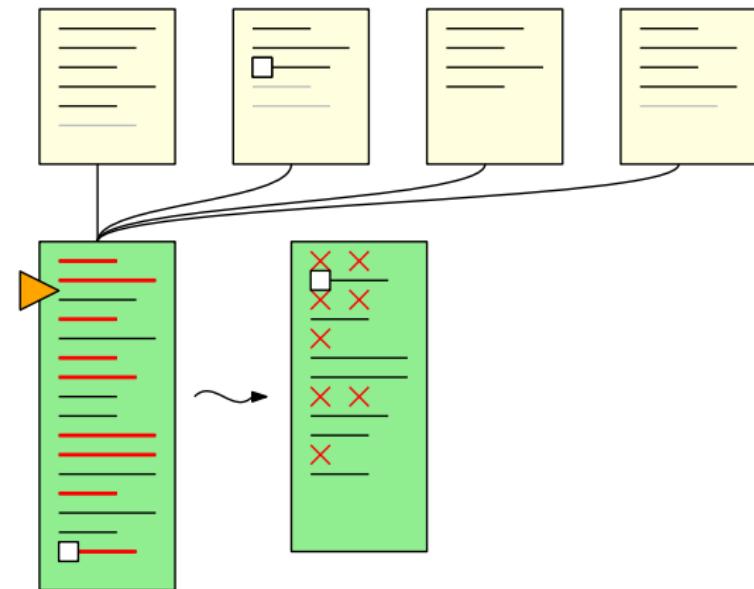
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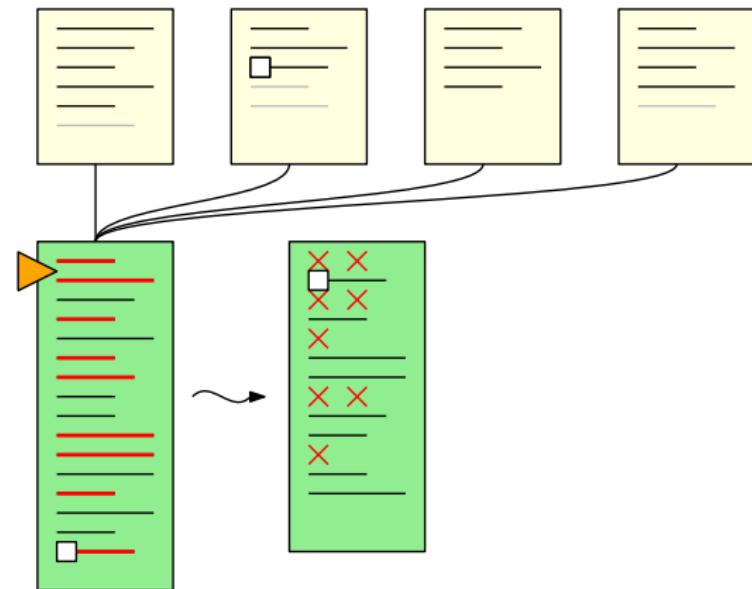
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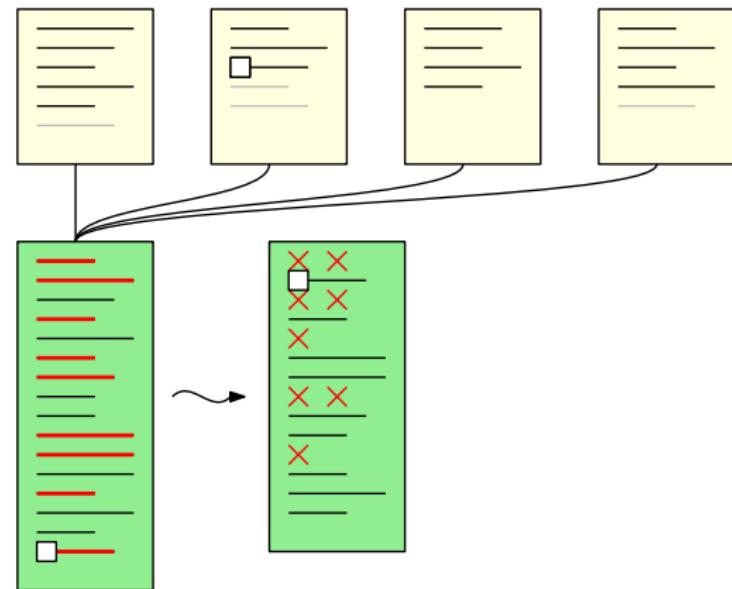
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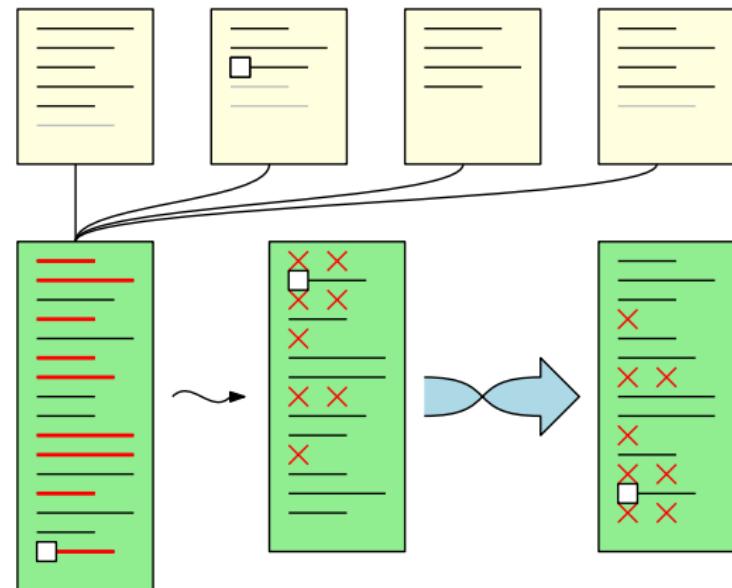
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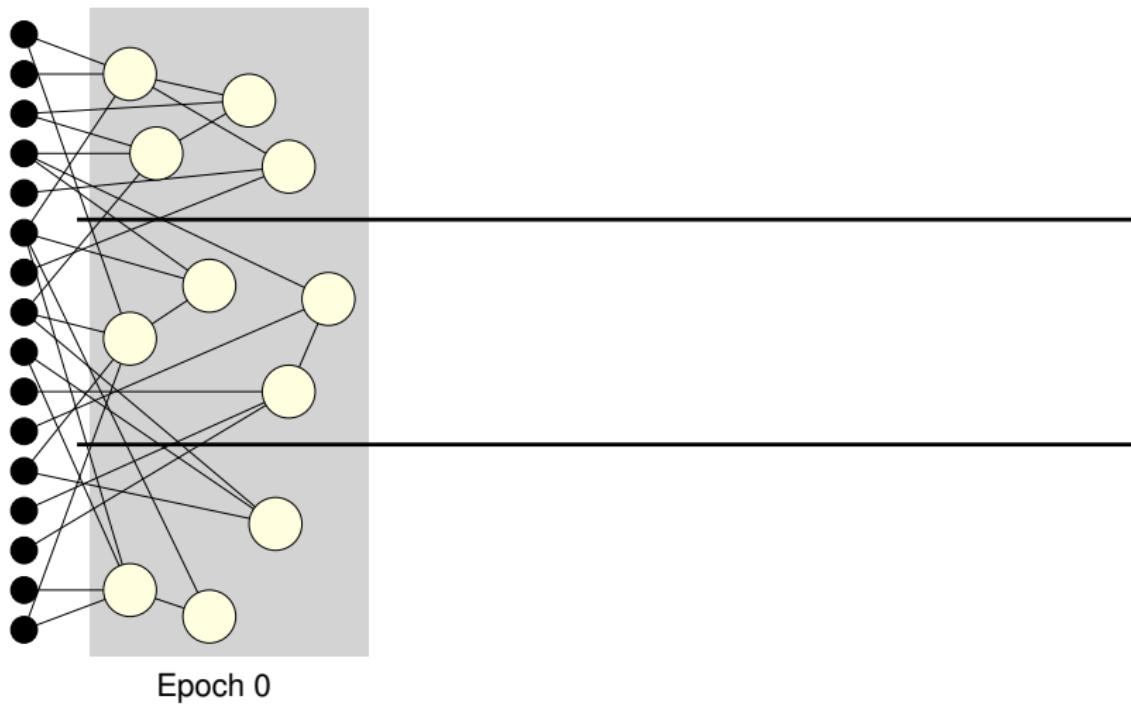
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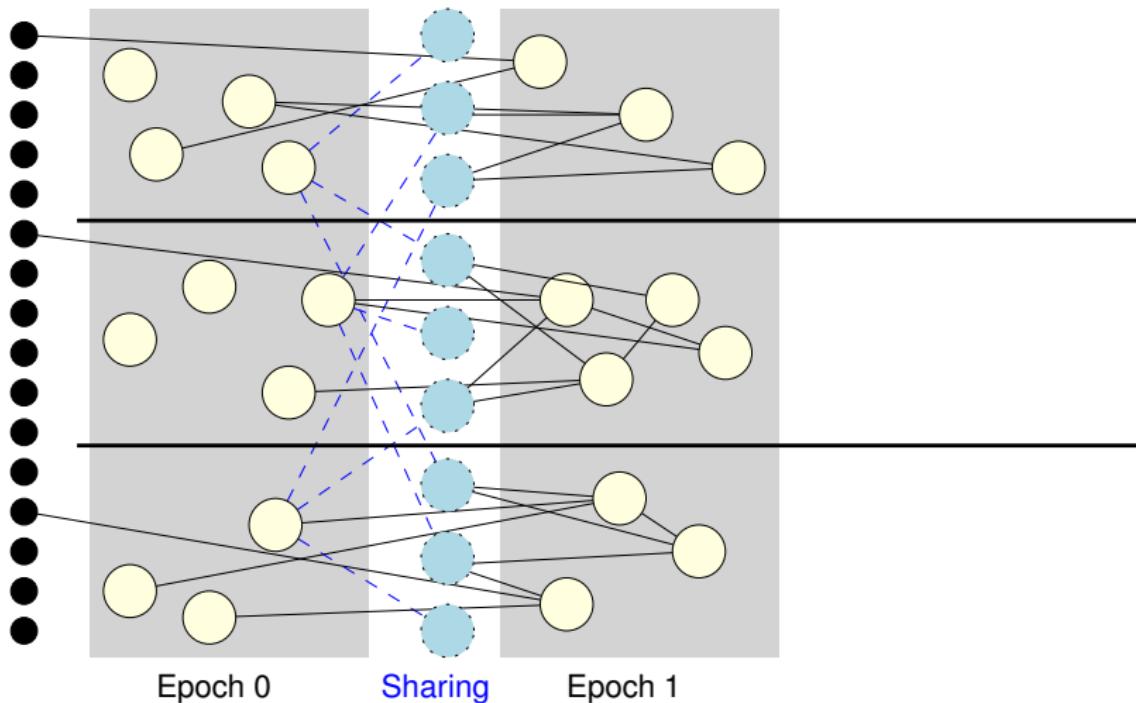
3. Reverse lines of pruned proof



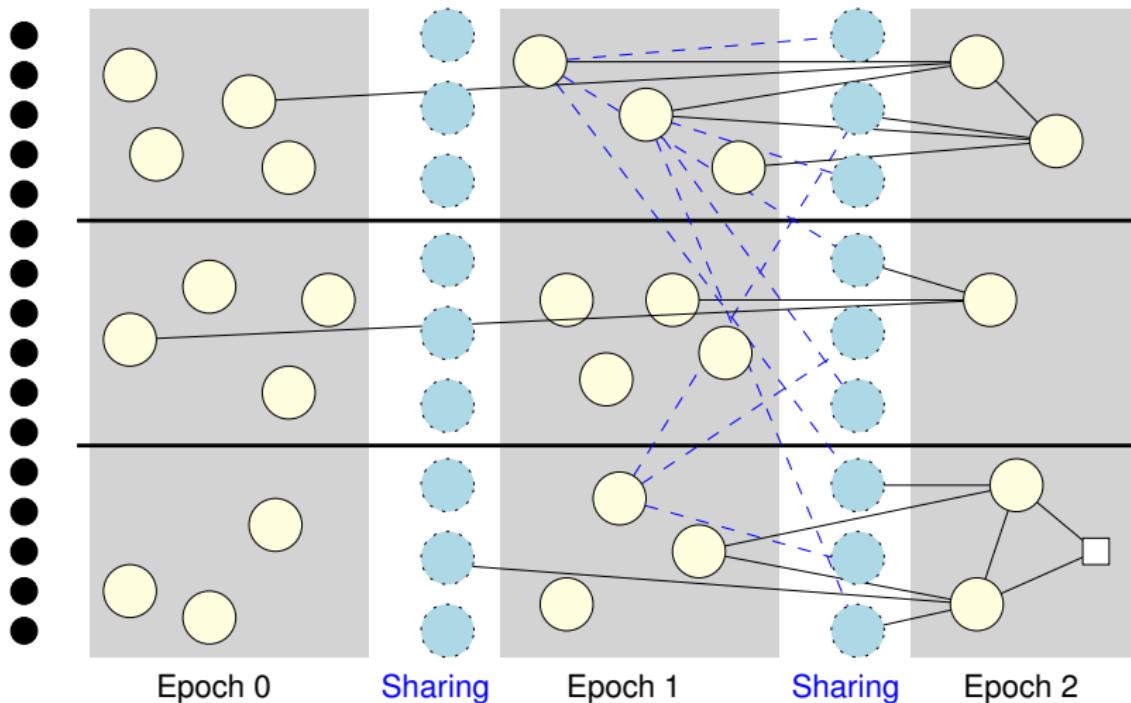
Distributed Pruning: Schematic Overview



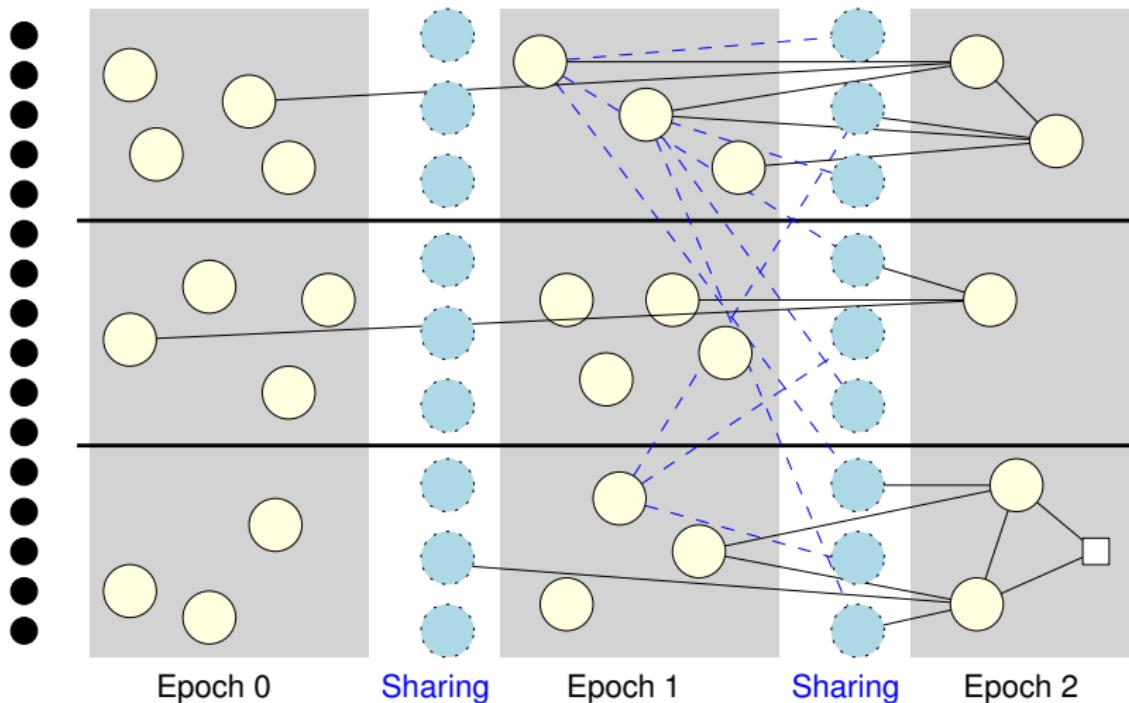
Distributed Pruning: Schematic Overview



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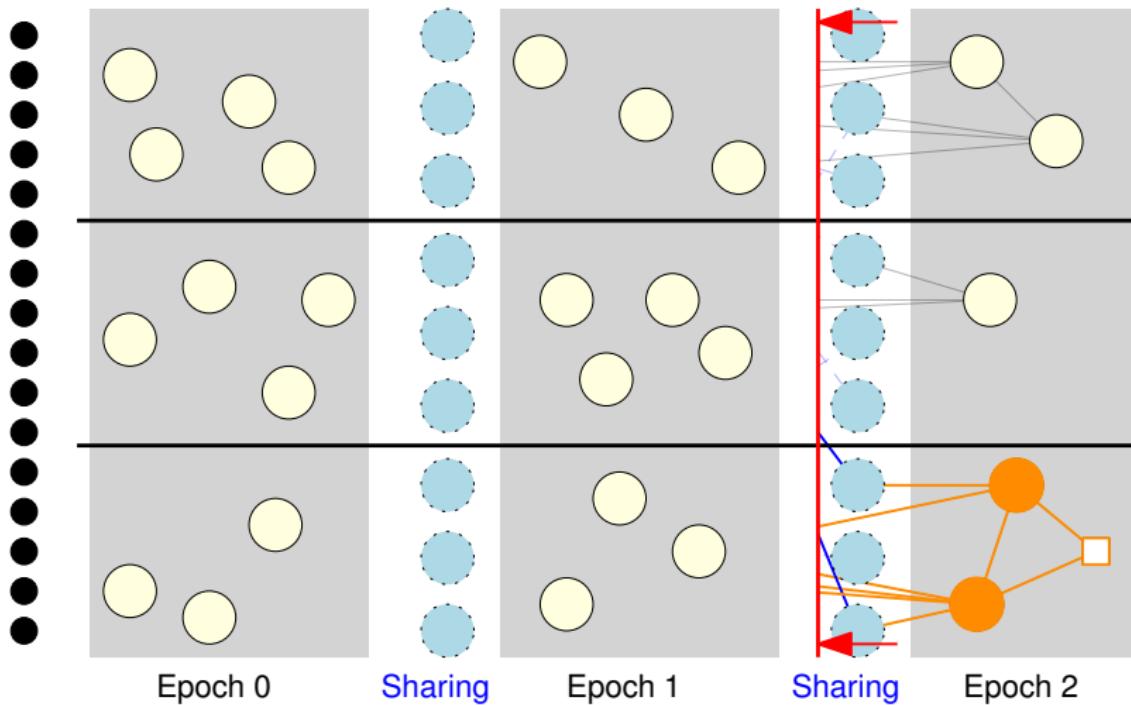


Distributed Pruning: Schematic Overview



First “prune”,
then combine!

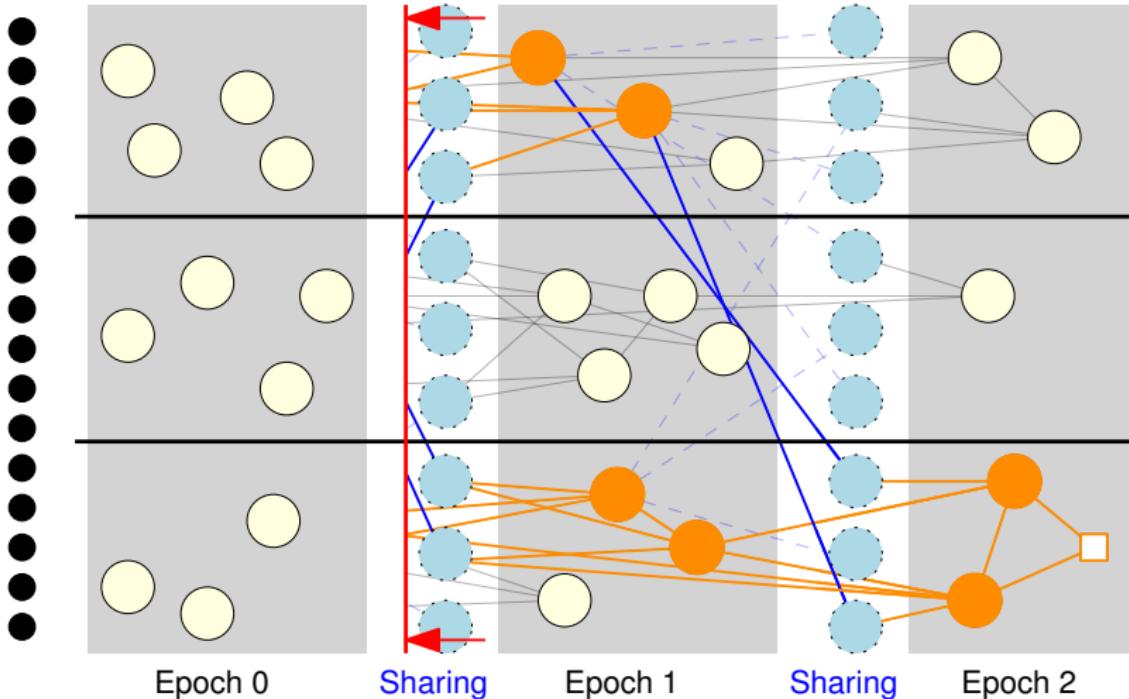
Distributed Pruning: Schematic Overview



First “prune”,
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Trace dependencies
epoch by epoch

Distributed Pruning: Schematic Overview

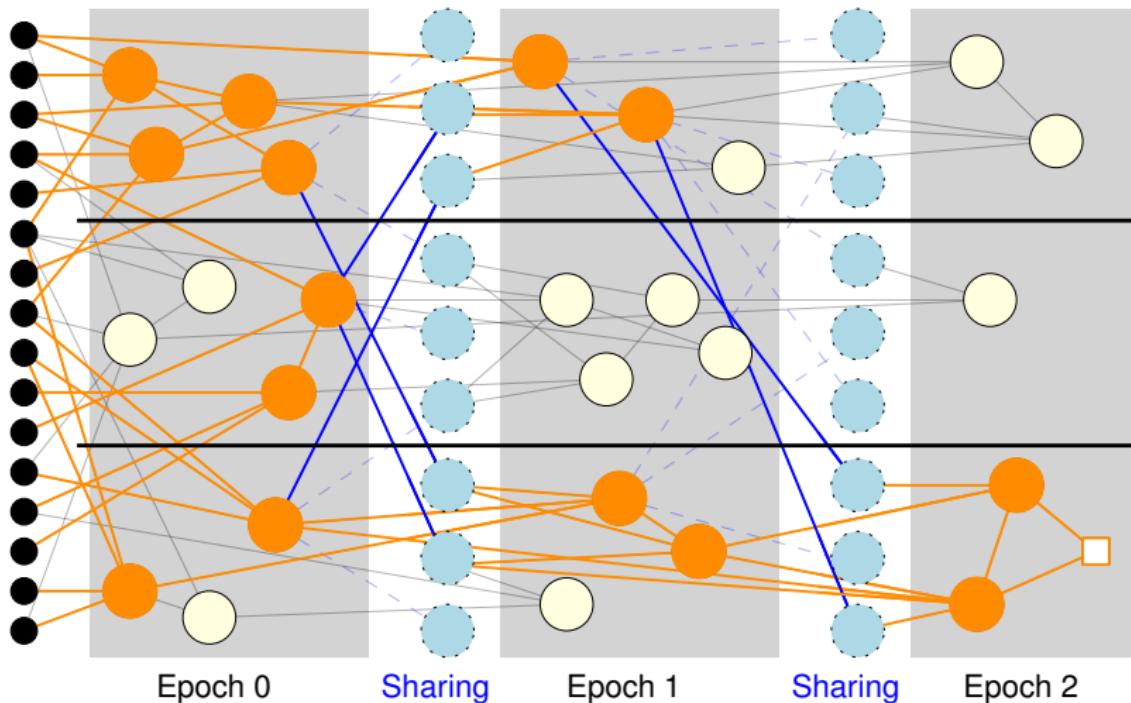


First “prune”,
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Trace dependencies
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Redistribute remote IDs
at epoch borders

Distributed Pruning: Schematic Overview



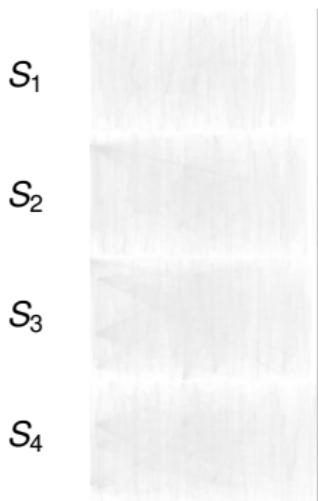
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Distributed Pruning: Real Data

— Derived clause IDs →



180-variable random 3-SAT formula. 4 notebook cores \times 1.7 s. 300k dependencies (orig. clauses omitted).

Solving: Align clause IDs at each sharing epoch

Distributed Pruning: Real Data

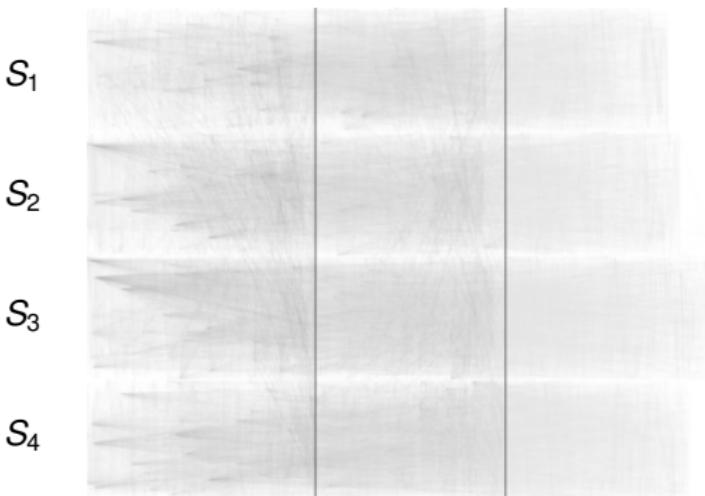
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Solving: Align clause IDs at each **sharing epoch**

Distributed Pruning: Real Data

— Derived clause IDs →

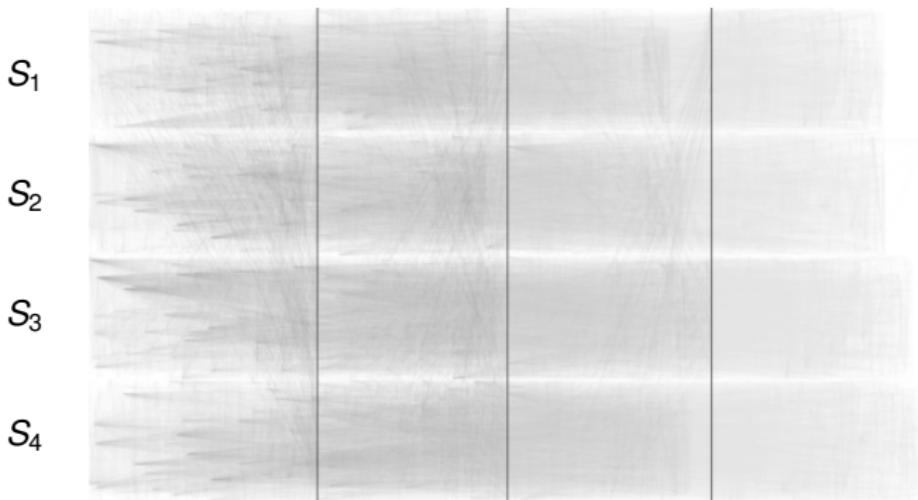


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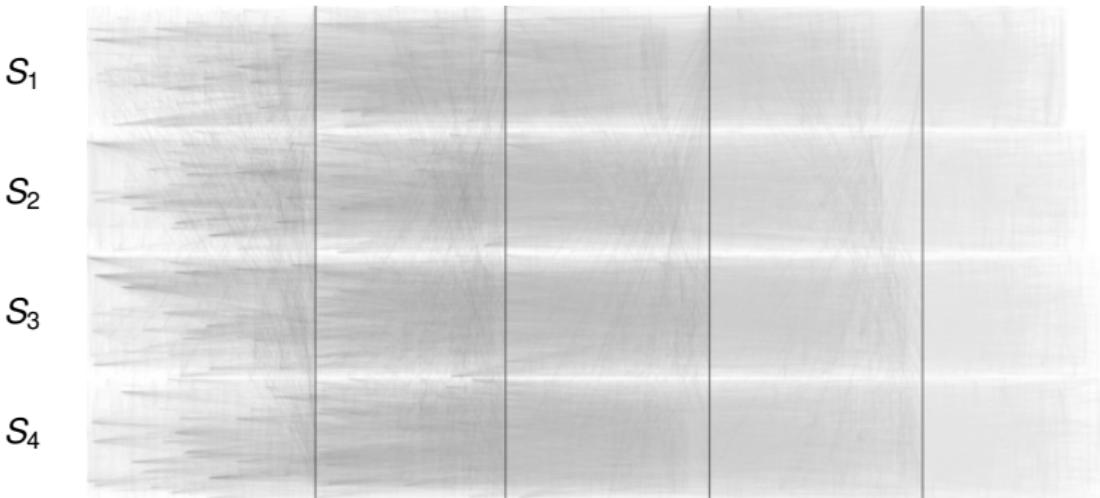


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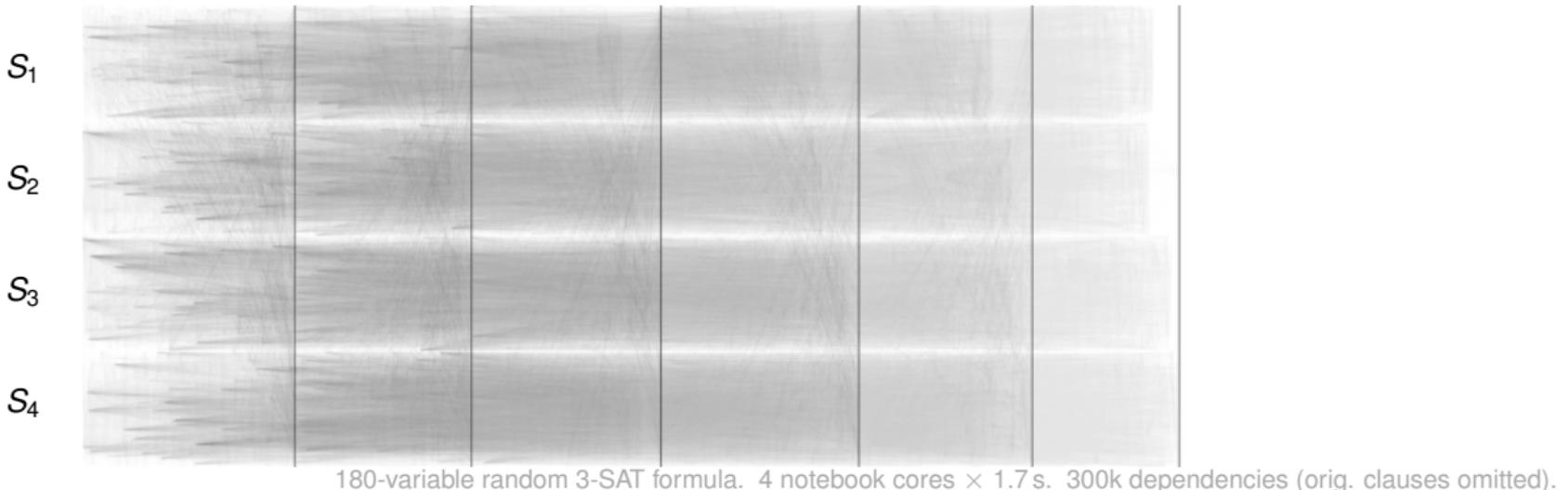


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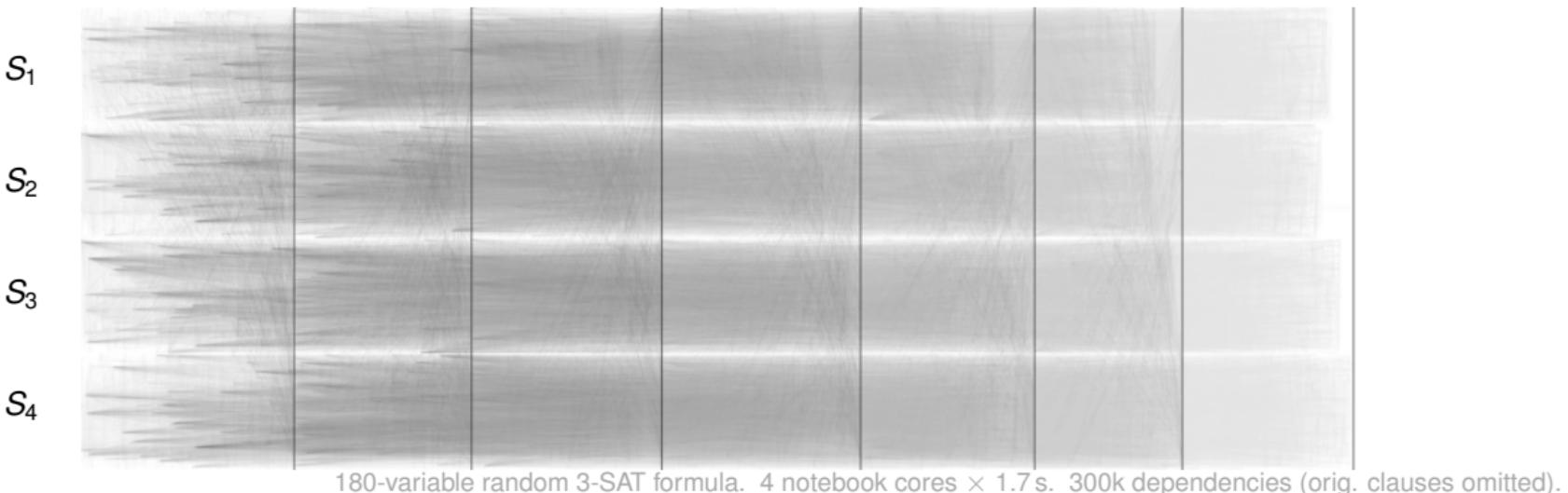
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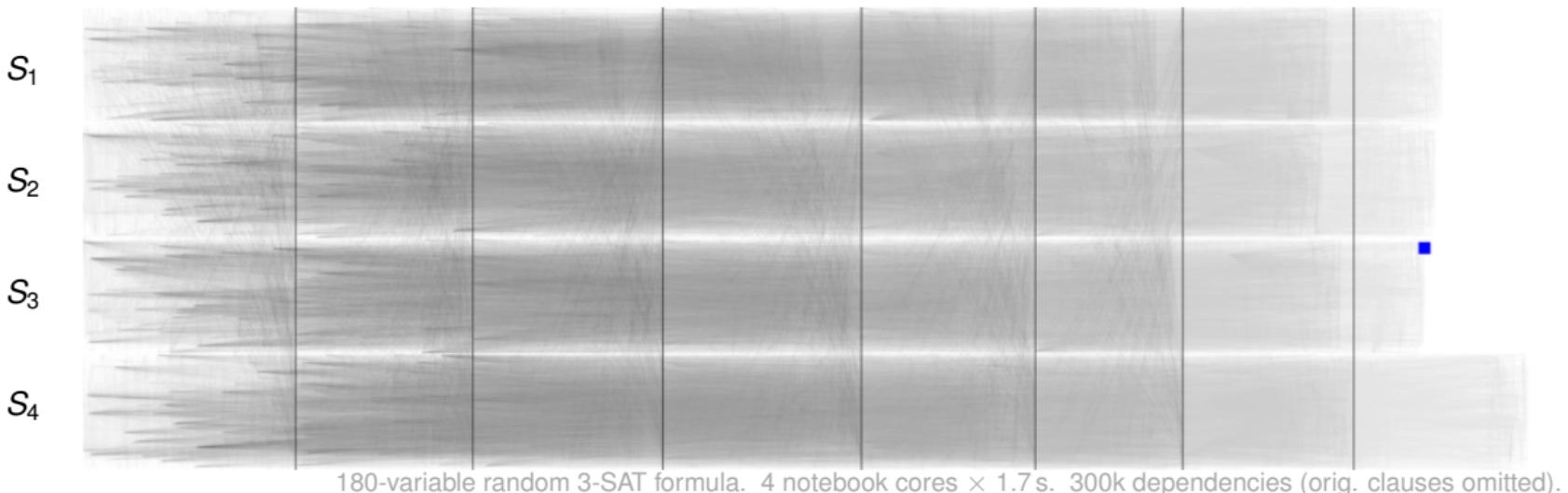
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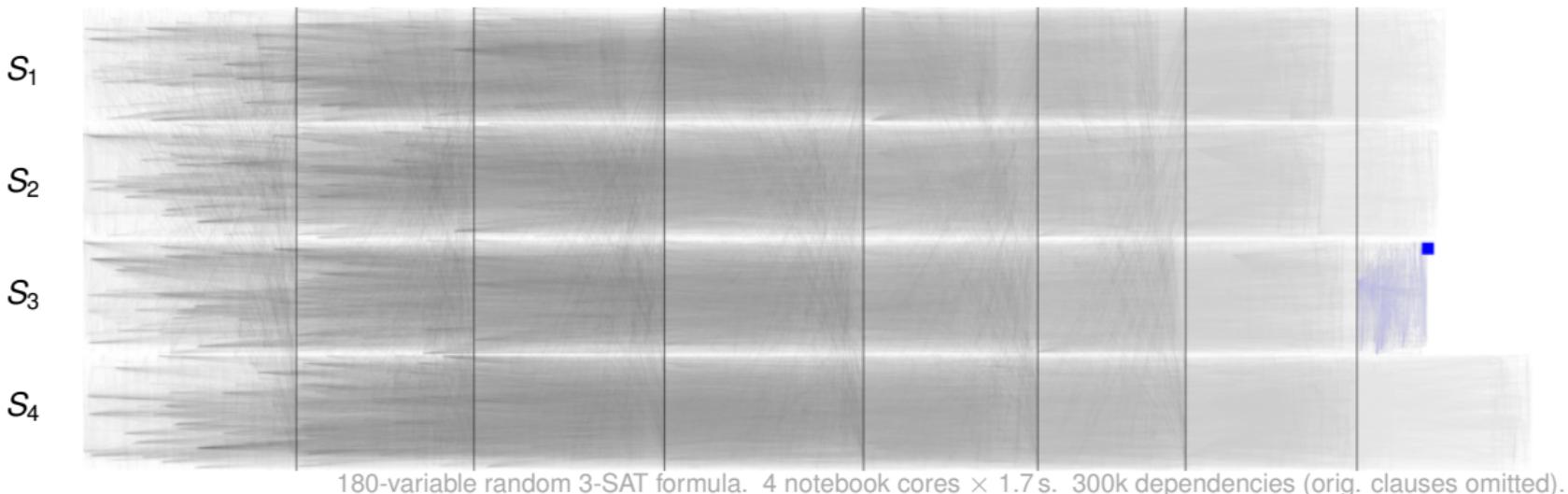
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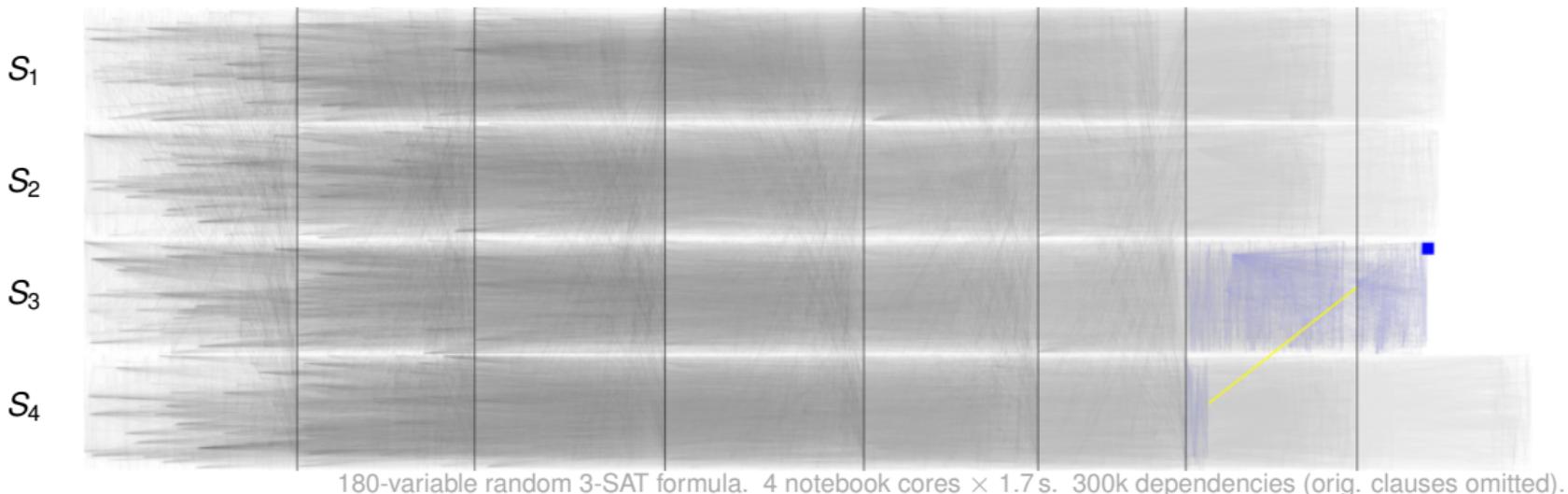
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Rewind: Trace local required clause IDs, **redistribute remote IDs** just before reading their epoch of origin

Distributed Pruning: Real Data

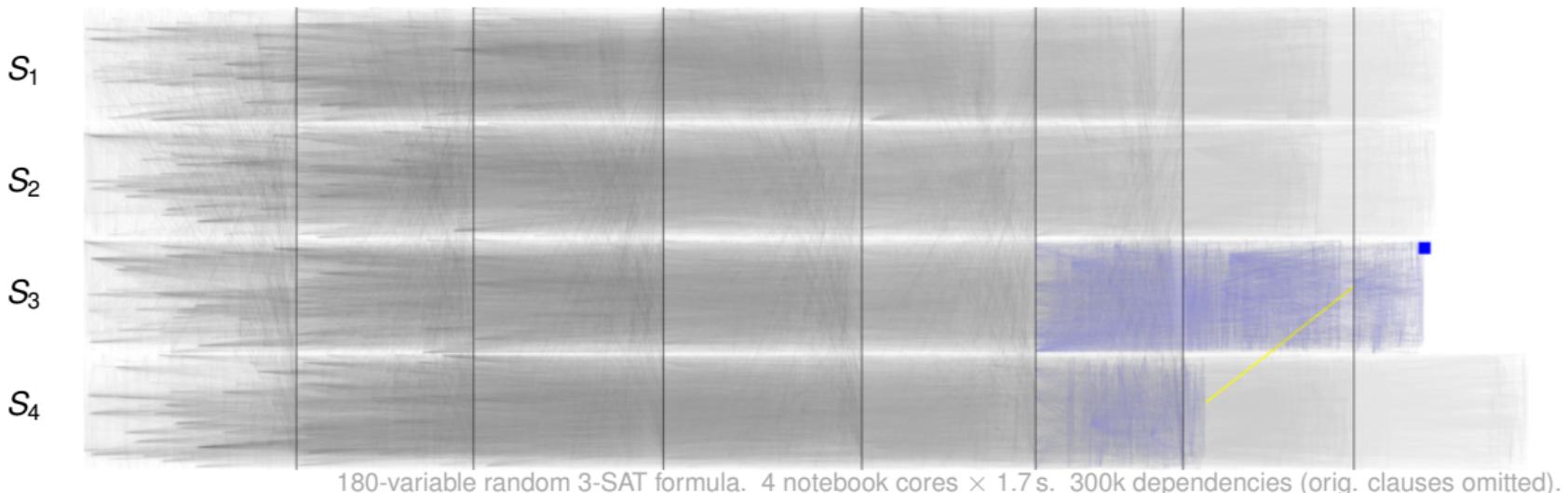
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Distributed Pruning: Real Data

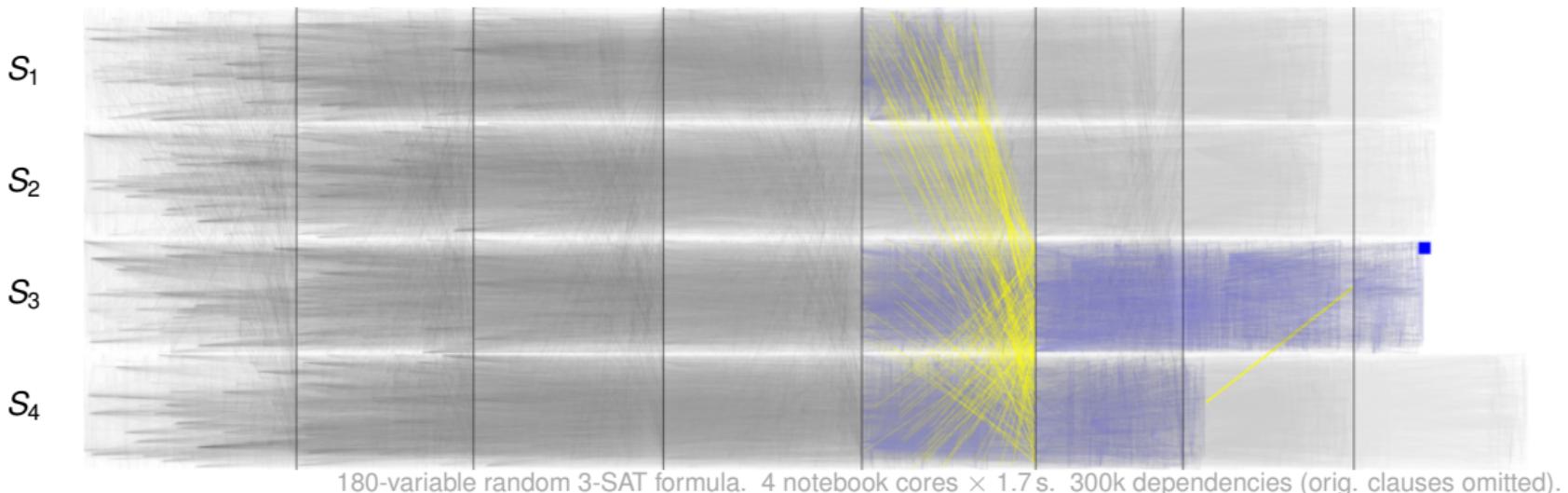
— Derived clause IDs →



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Distributed Pruning: Real Data

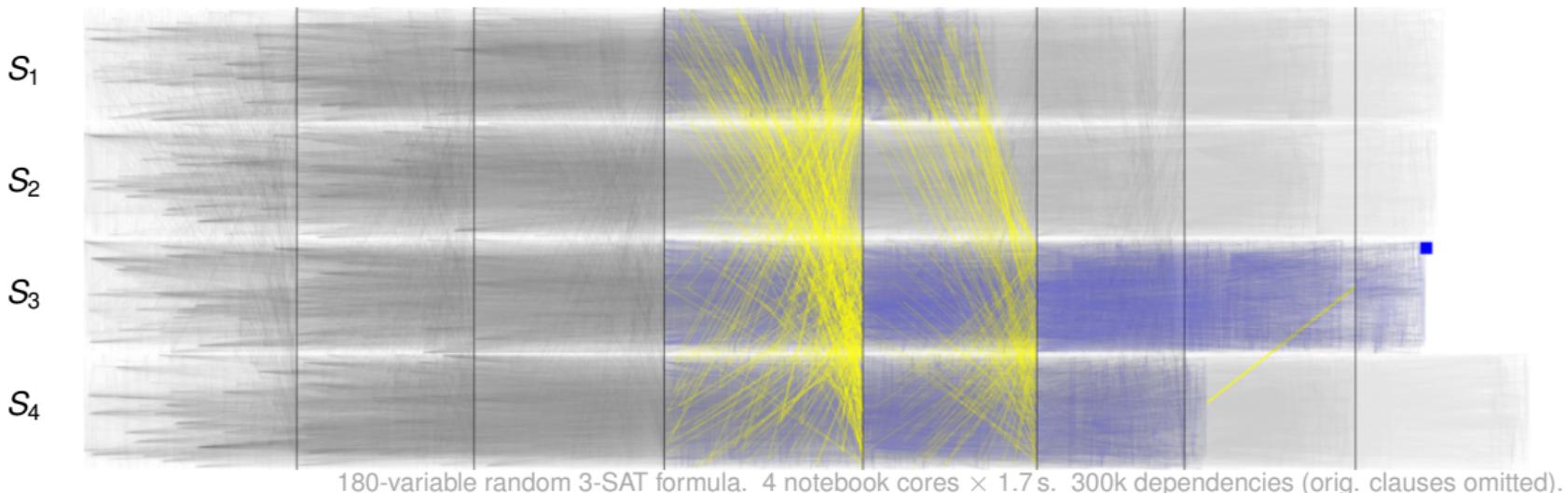
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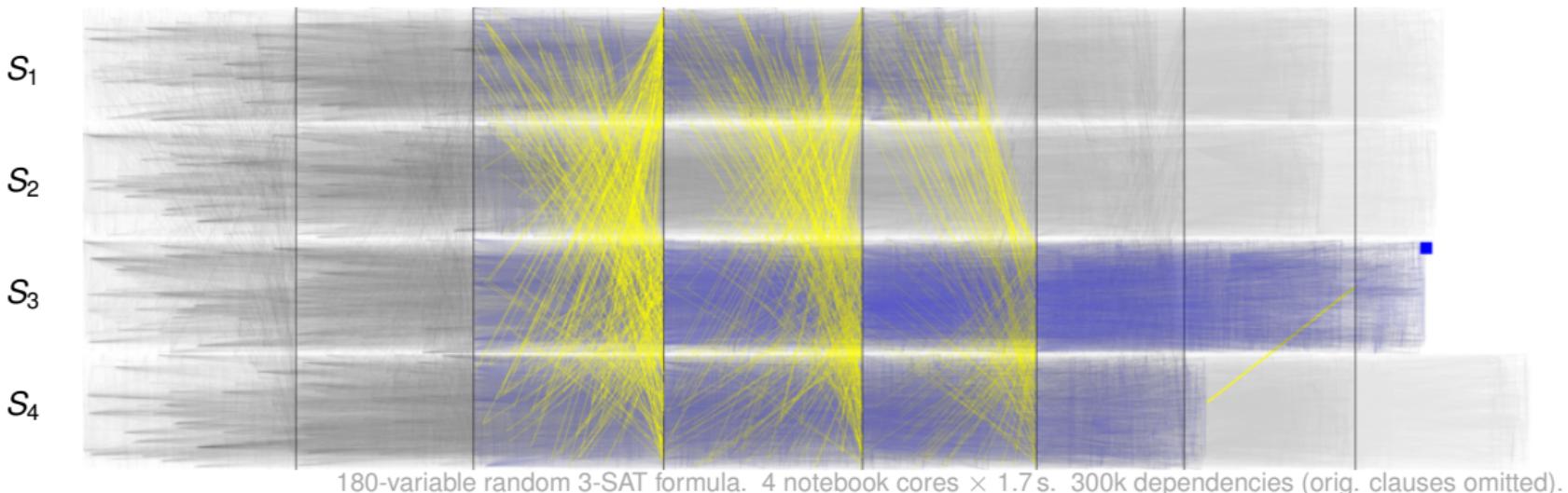
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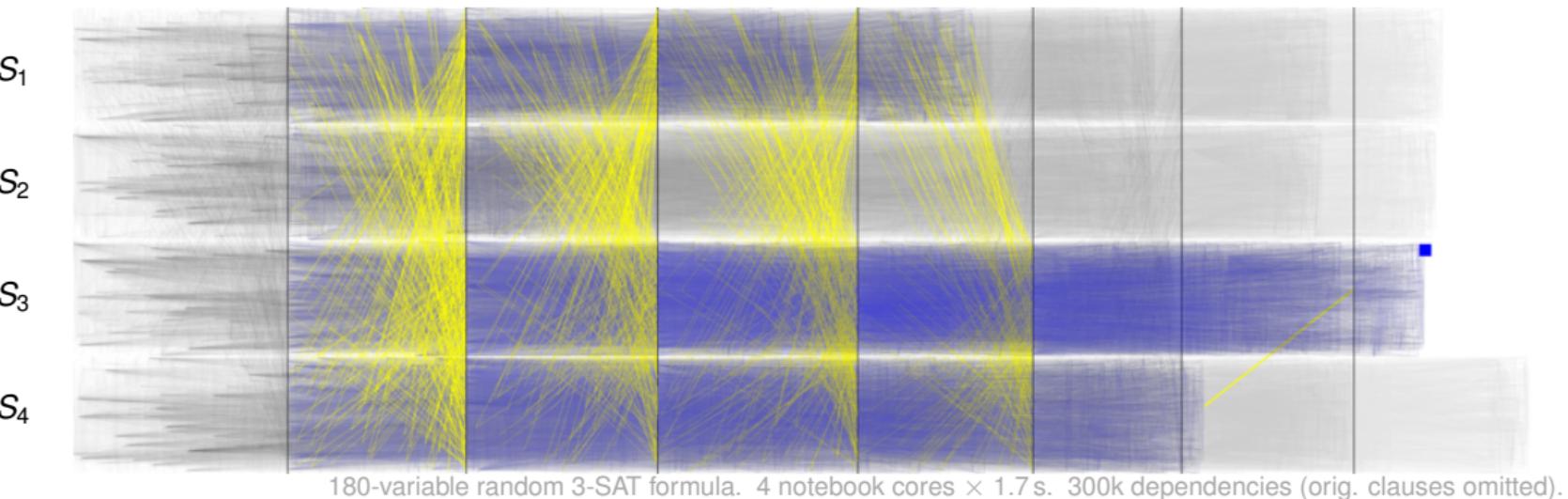
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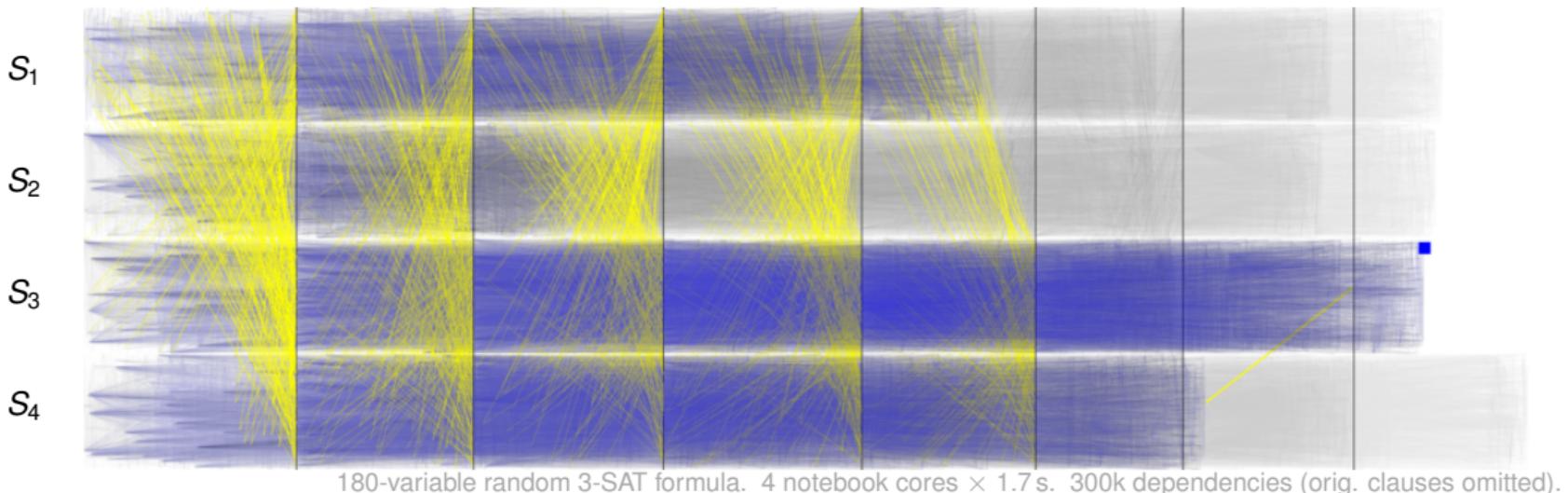
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Distributed Pruning: Real Data

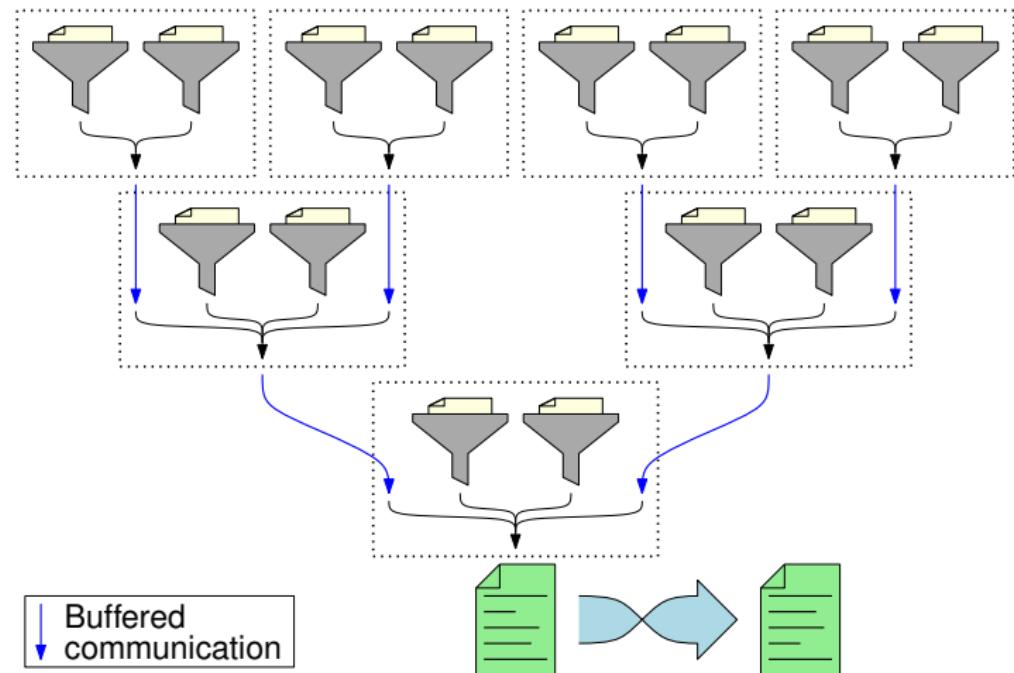
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Distributed Combination

- Hierarchically merge pruning output along **tree of processors**
- Root processor
 - 1 adds approximated “delete” lines
 - 2 writes stream into file
 - 3 reverses file



Experimental Setup (1/2)

Technology

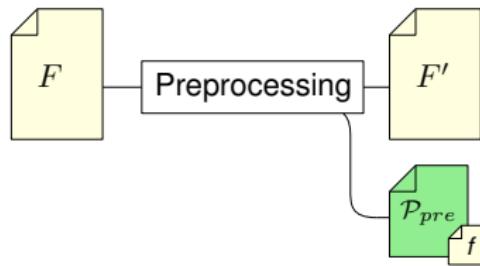
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Pipeline

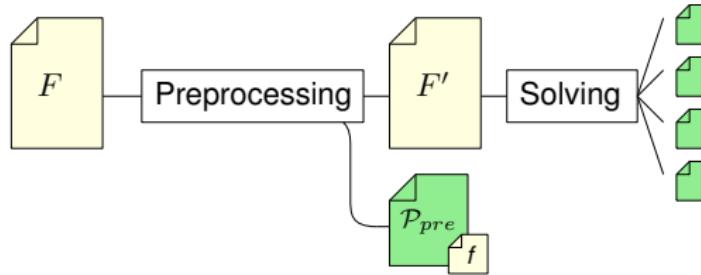


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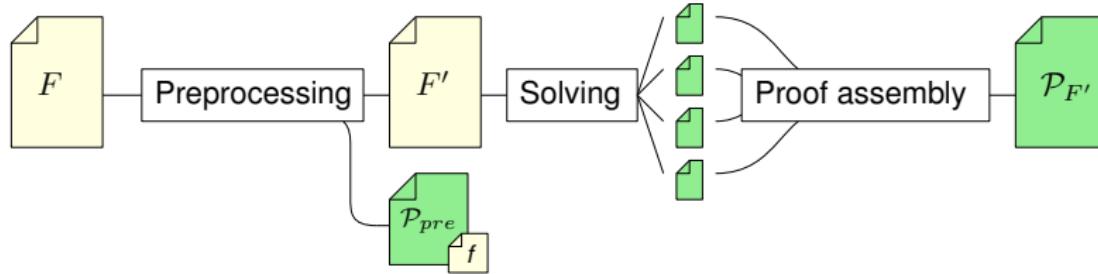


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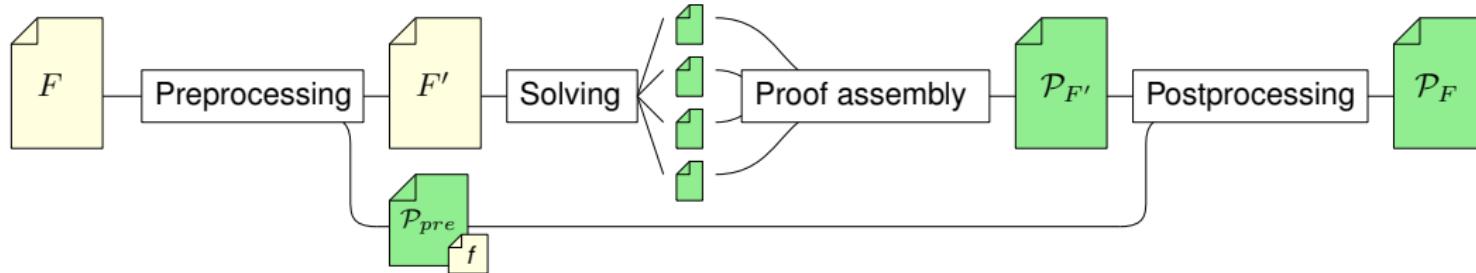


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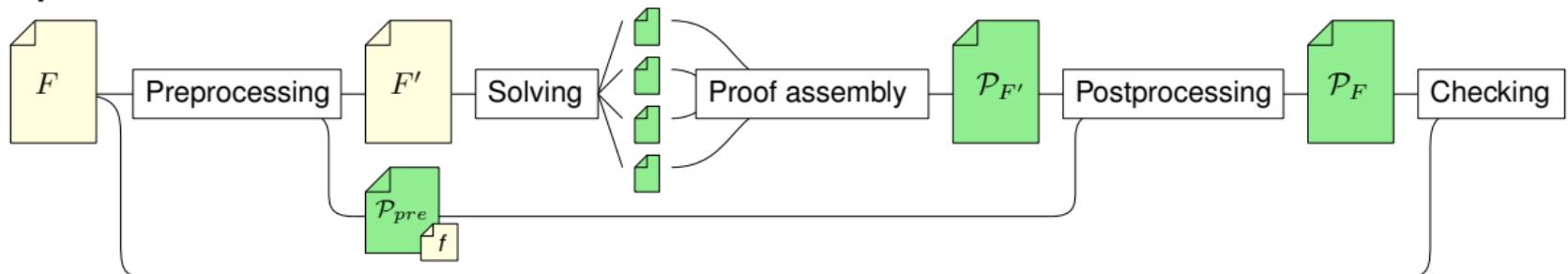


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Pipeline



Experimental Setup (2/2)

Comparison to prior work

- Shared-memory clause-sharing portfolios: [Heule, Manthey, Philipp @ POS'14](#)
 - Synchronized, **moderated** logging into shared **DRAT** proof
 - Solver not competitive ⇒ Simulate proof output, compare **checking times only**
- Sequential SAT solving: [Kissat_MAB-HyWalk @ SAT Comp. 2022](#)

Experimental Setup (2/2)

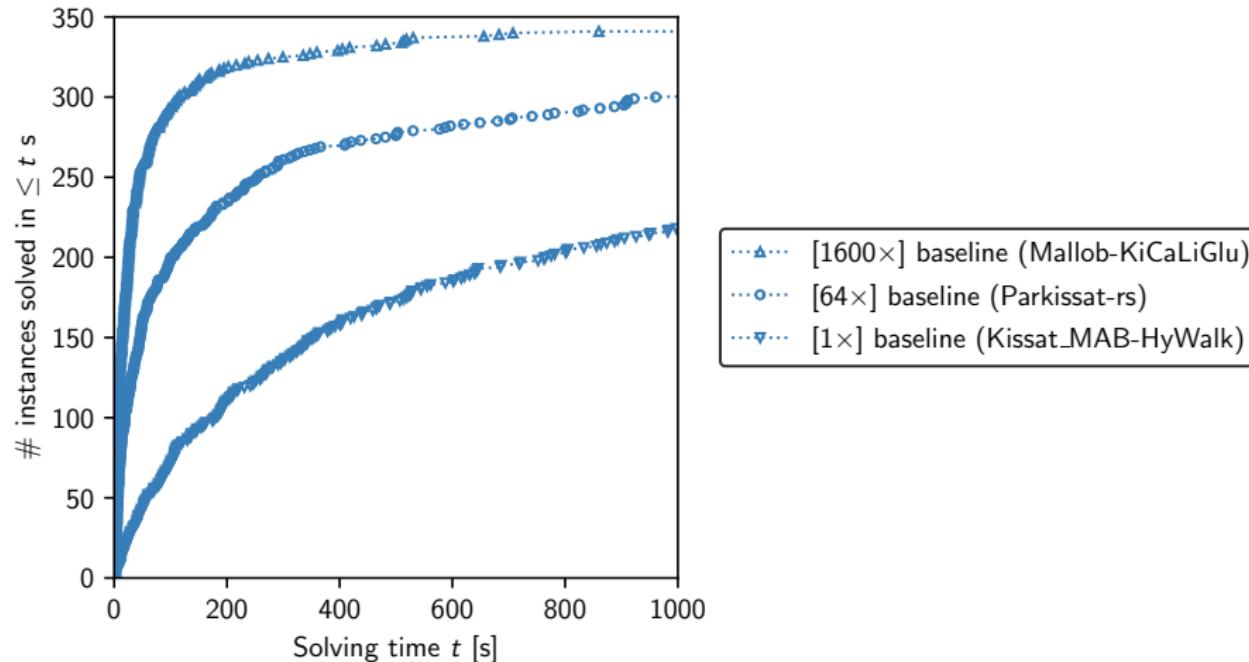
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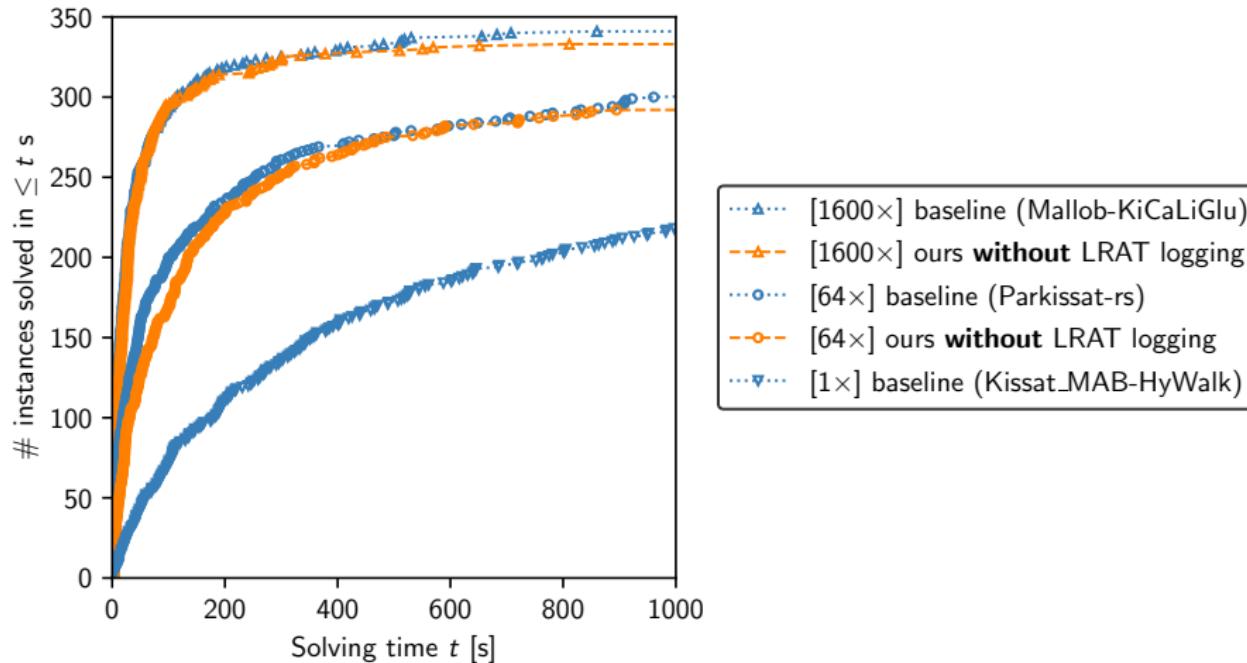
Resources

- 1600× setup: 100× m6i.4xlarge EC2 instances (16 hwthreads, 64 GB RAM)
 - 64× setup: 1× m6i.16xlarge EC2 instance (64 hwthreads, 256 GB RAM)
 - Sequential setup: One m6i.4xlarge EC2 instance
- $\left. \begin{array}{l} \leq 1000 \text{ s solving} \\ \leq 4000 \text{ s proof prod.} \end{array} \right\}$

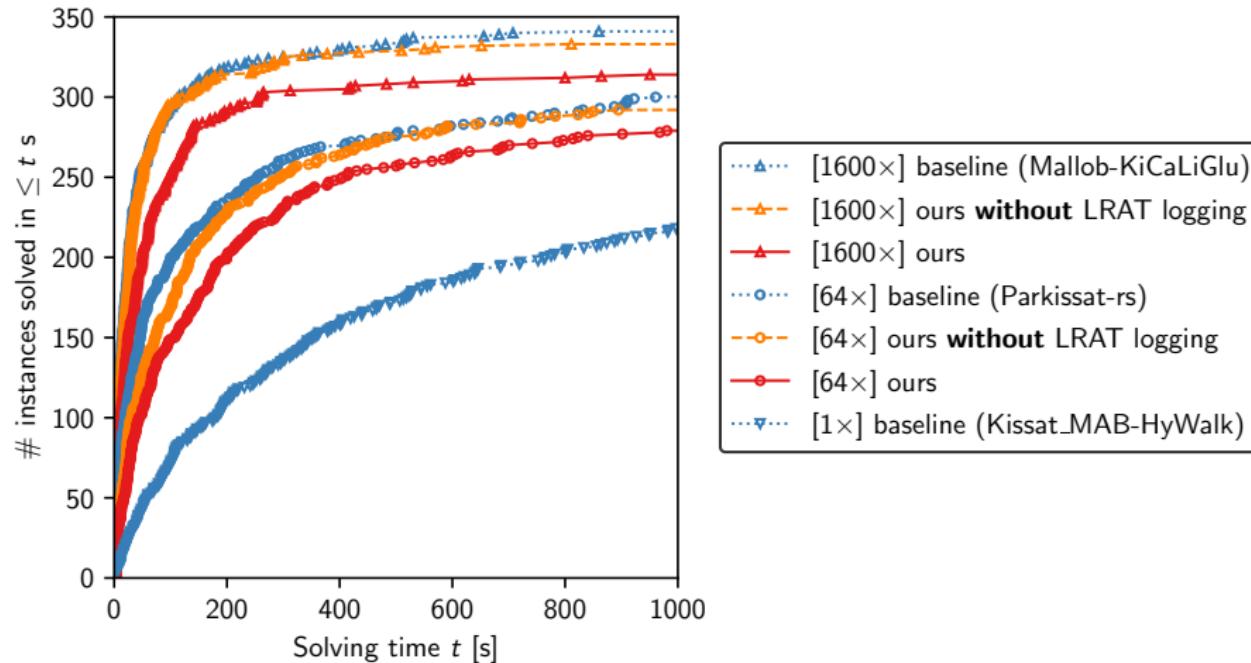
Evaluation: Solving Times



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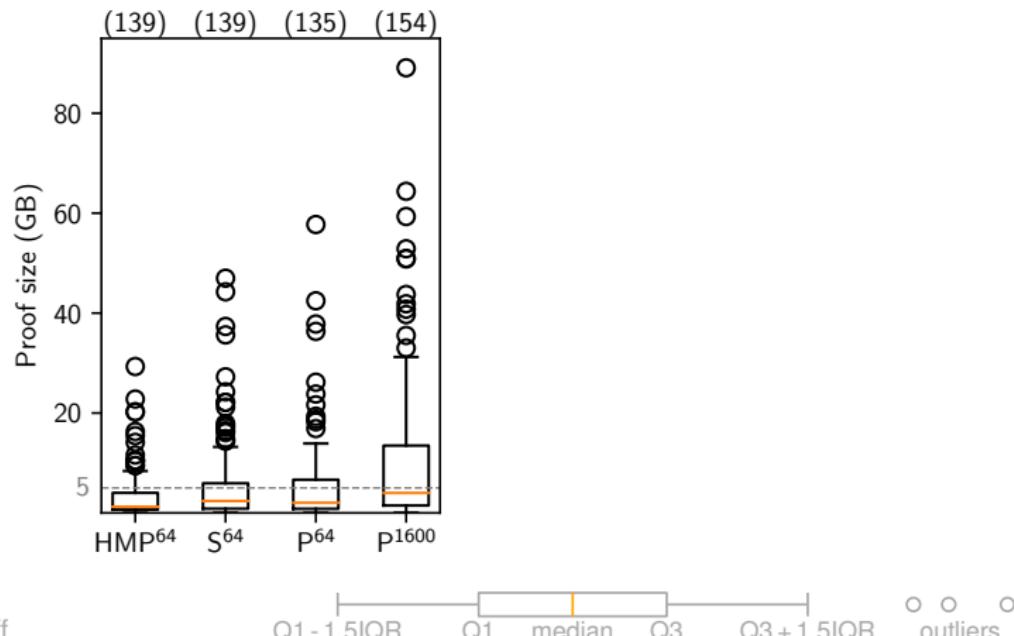


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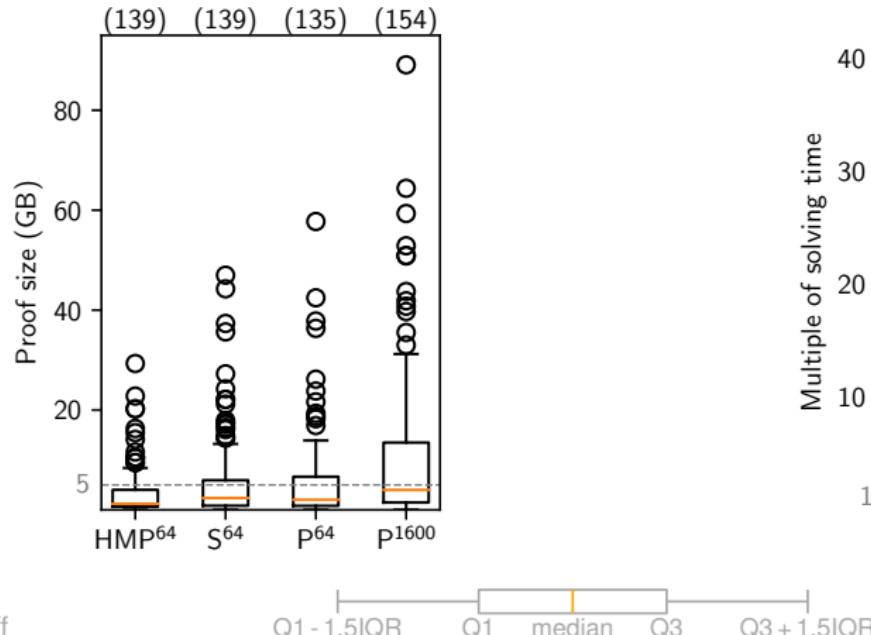
Evaluation: Proof Output

How large are the resulting proofs?

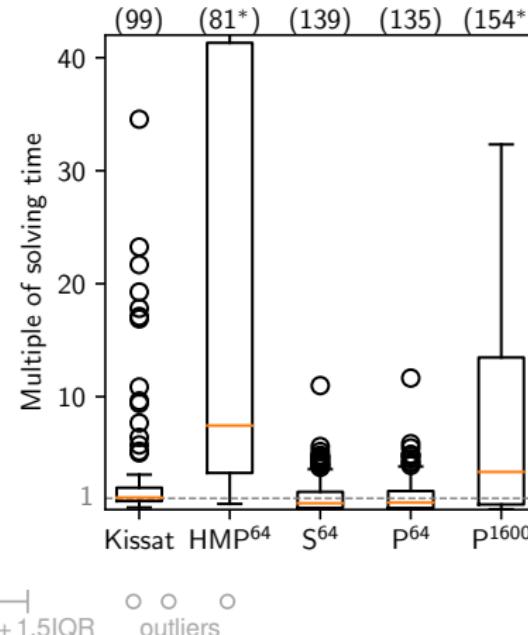


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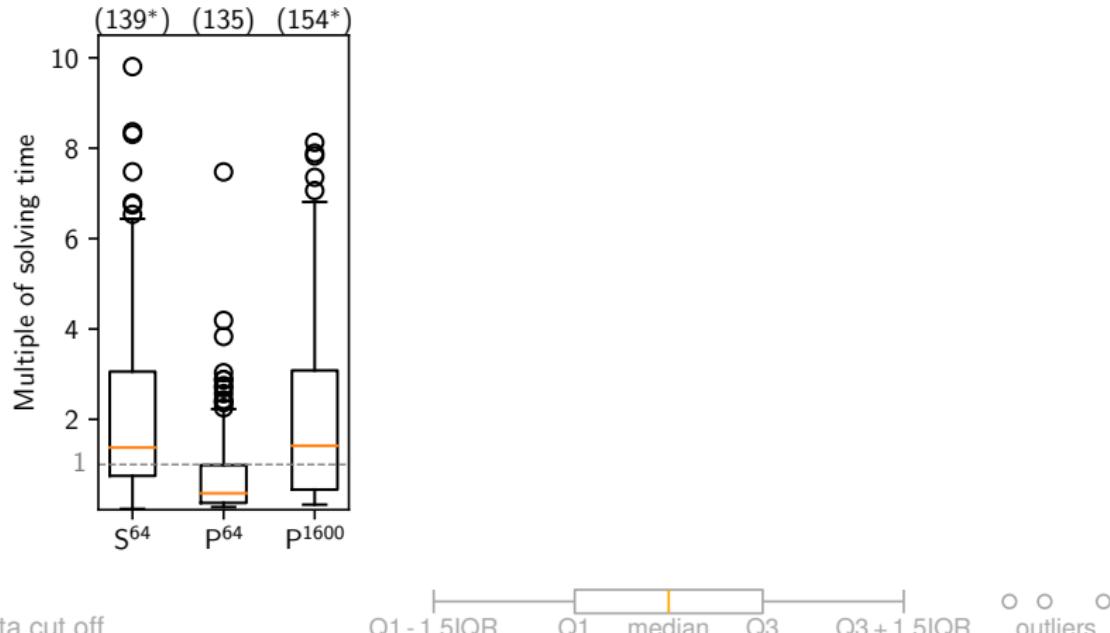


How fast can we check the proofs?



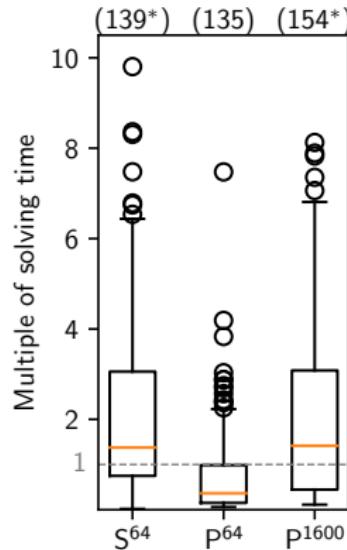
Evaluation: Overhead

Proof assembly

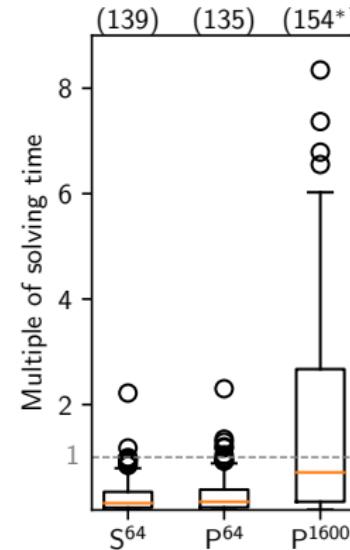


Evaluation: Overhead

Proof assembly



Postprocessing



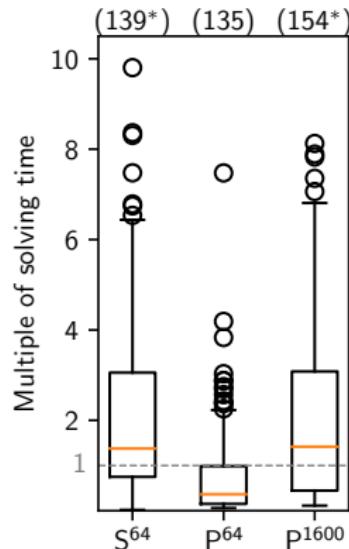
*Some data cut off

Q1 - 1.5IQR Q1 median Q3 Q3 + 1.5IQR

○ ○ ○
outliers

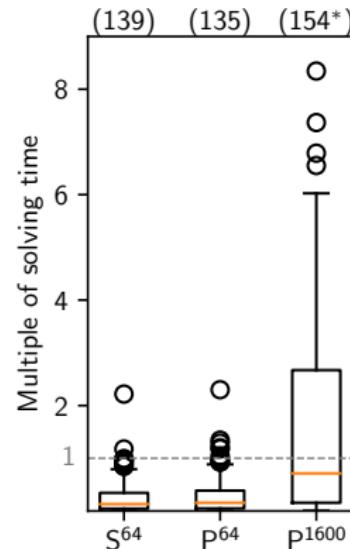
Evaluation: Overhead

Proof assembly

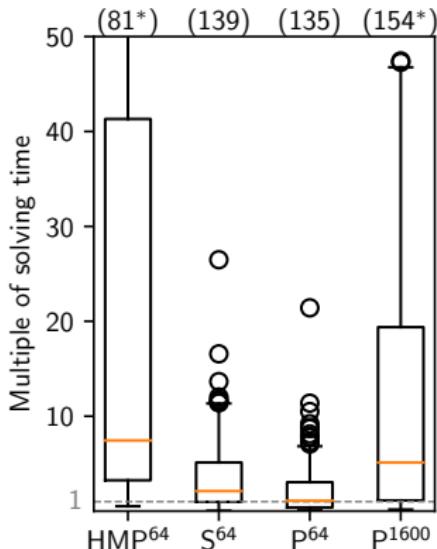


*Some data cut off

Postprocessing



Total (HMP: checking only)



Q1 - 1.5IQR Q1 median Q3 Q3 + 1.5IQR

○ ○ outliers

Conclusion

Takeaways

- Popular parallelization approaches for SAT (“antisocial nerds” analogy)
 - Search space splitting, Cube&Conquer
 - Pure portfolio
 - Clause sharing portfolio
- All-to-all clause sharing can be very useful and scalable (up and down) if implemented well
 - huge for unsatisfiable, nice-to-have for satisfiable problems
 - diversifies solvers effectively in and of itself
- Exploit embarrassingly parallel job processing for interactive solving & best efficiency
- Emitting proofs of unsatisfiability is nontrivial and requires careful engineering

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Recent and ongoing work

- Distributed incremental SAT solving with Mallob
- QBF solving with Mallob

<https://github.com/domschrei/mallob>

References

Publications

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- Schreiber, D. (2022). **Mallob in the SAT competition 2022**. Proc. SAT Competition, 38.
- Schreiber, D., & Sanders, P. (2021). **Scalable SAT solving in the cloud**. In Theory and Applications of Satisfiability Testing—SAT 2021: 24th International Conference, 2021, Proceedings 24 (pp. 518-534).

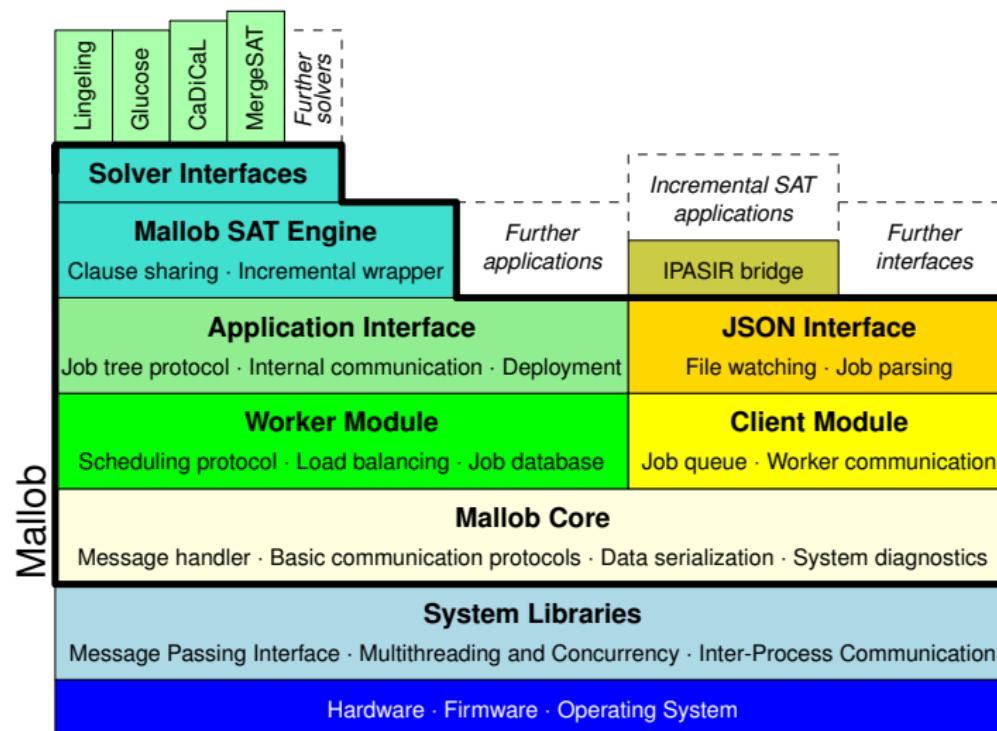
External images

Slide 12, SuperMUC-NG: https://doku.lrz.de/files/10745965/10745966/1/1684599593177/image2019-11-15_12-48-5.png

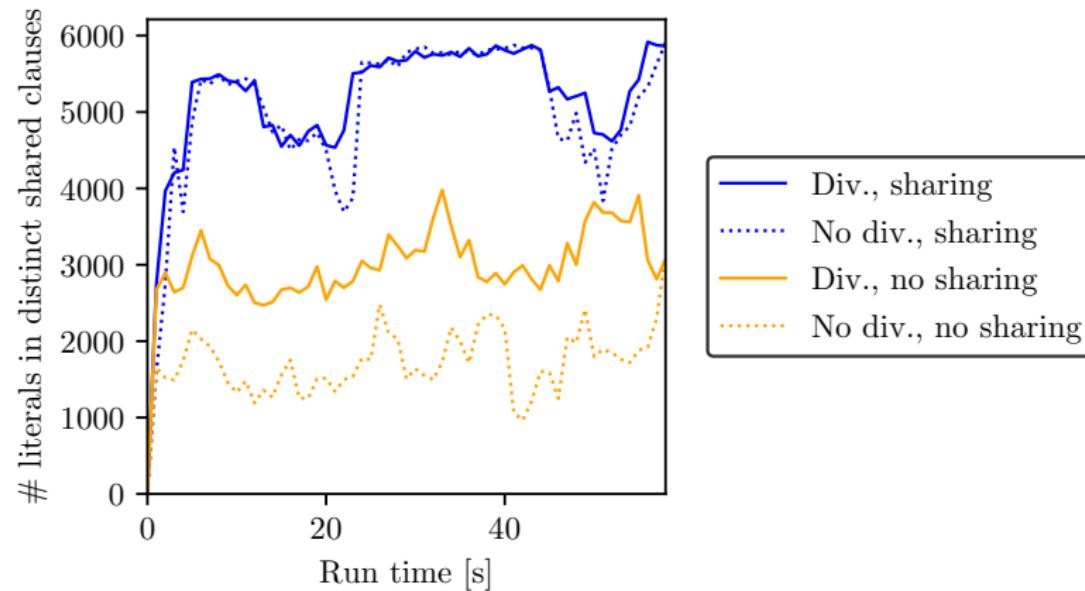
Slide 23, "They're the same picture." meme:

<https://cdn.eldeforma.com/wp-content/uploads/2020/08/theyre-the-same-picture-pam-the-office-meme-1024x580.png>

Mallob



Sharing vs. diversification



4× default-configured Lingeling, random 3-SAT @ PT, 400 vars, no unused volume compensation

Scaling Experiments (2021)

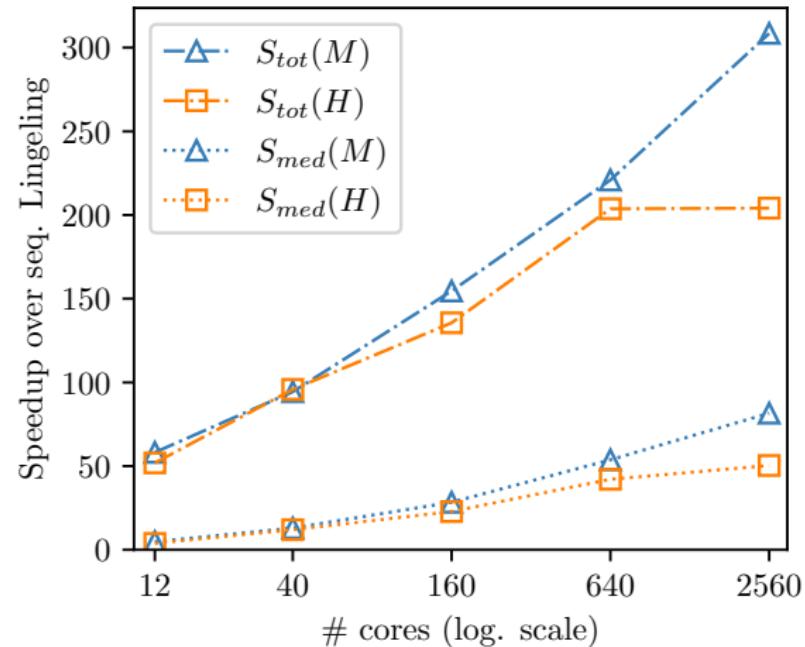
Mallob-mono^{AnyLBD}_{sublin} vs. HordeSat_{new}

Speedups

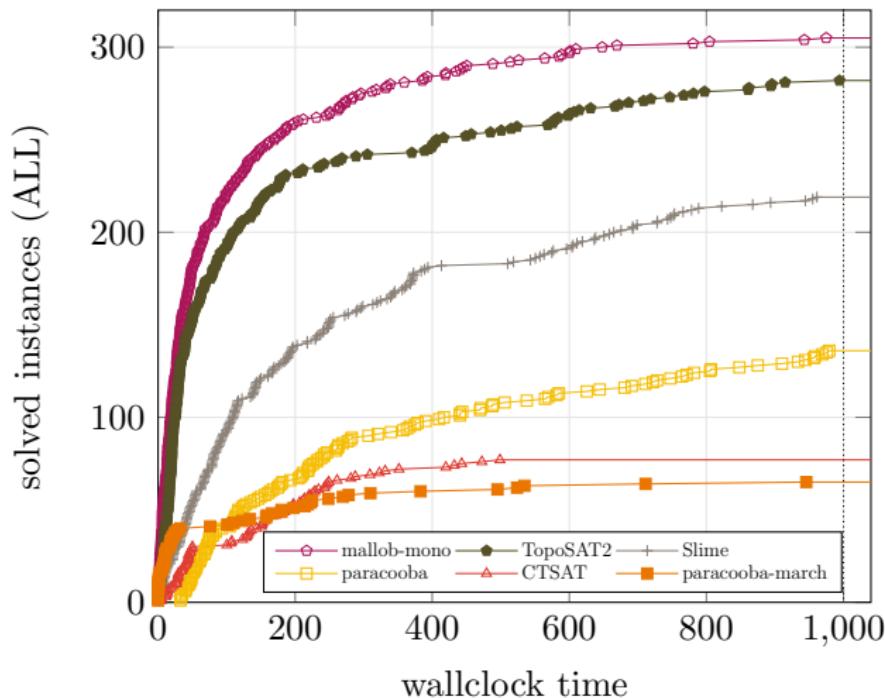
Instance F solved by parallel approach
 \Rightarrow Par. run time $T_{par}(F) \leq 300$ s
 \Rightarrow Seq. run time $T_{seq}(F) \leq 50\,000$ s
 $(T_{seq}(F) := 50\,000$ s if unsolved)

Total speedup S_{tot} :
 $\sum_F T_{seq}(F) / \sum_F T_{par}(F)$

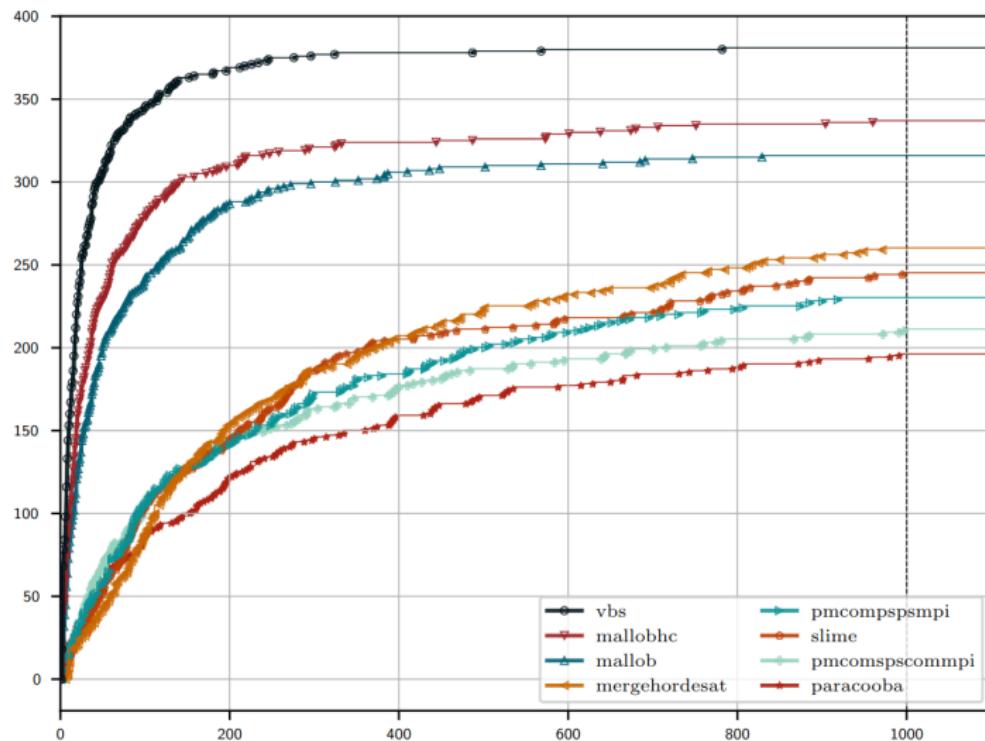
Median speedup S_{med} :
 $median_F\{T_{seq}(F)/T_{par}(F)\}$



SAT Competition 2020 (Cloud Track)



SAT Competition 2021 (Cloud Track)



- MallobHC: [mixed solver portfolio](#)
- VBS of [all Main track solvers](#) solved 325 instances within 5000 s