

| xIN1 | xIN2 | xOUT1 | xOUT2 |
|------|------|-------|-------|
| 0    | 0    | L     | L     |
| 0    | 1    | L     | Н     |
| 1    | 0    | Н     | L     |
| 1    | 1    | Н     | Н     |

PWM Frequency: 100 kHz max

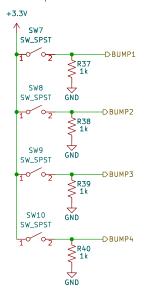
Slow Decay: Logic low Mixed Decay: Open Fast Decay: Logic high

## 10 - 14 Function

| I[40] | RELATIVE CURRENT<br>(% FULL-SCALE CHOPPING CURRENT) |  |  |
|-------|---|--|--|
| 0x00h | 0%  |  |  |
| 0x01h | 5%  |  |  |
| 0x02h | 10%   |  |  |
| 0x03h | 15%   |  |  |
| 0x04h | 20%   |  |  |
| 0x05h | 24%   |  |  |
| 0x06h | 29%   |  |  |
| 0x07h | 34%   |  |  |
| 0x08h | 38%   |  |  |
| 0x09h | 43%   |  |  |
| 0x0Ah | 47%   |  |  |
| 0x0Bh | 51%   |  |  |
| 0x0Ch | 56%   |  |  |
| 0x0Dh | 60%   |  |  |
| 0x0Eh | 63%   |  |  |
| 0x0Fh | 67%   |  |  |
| 0x10h | 71%   |  |  |
| 0x11h | 74%   |  |  |
| 0x12h | 77%   |  |  |
| 0x13h | 80%   |  |  |
| 0x14h | 83%   |  |  |
| 0x15h | 86%   |  |  |
| 0x16h | 88%   |  |  |
| 0x17h | 90%   |  |  |
| 0x18h | 92%   |  |  |
| 0x19h | 94%   |  |  |
| 0x1Ah | 96%   |  |  |
| 0x1Bh | 97%   |  |  |
| 0x1Ch | 98%   |  |  |
| 0x1Dh | 99%   |  |  |
| 0x1Eh | 100%  |  |  |
| 0x1Fh | 100%  |  |  |

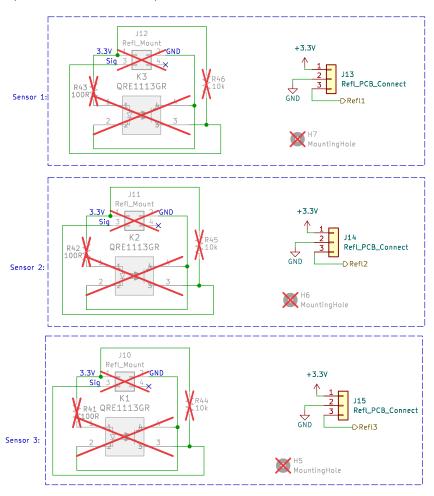
+3.3V 3V3D Matthew Sato Stanford University Engineering Informatics Group Vdrive Department of Civil and Environmental Engineering VdriveD\_\_\_\_\_ satomm@stanford.edu Sheet: /Motor/ GND File: Motor.kicad\_sch Title: MCU Controller Size: B Date: Rev: 0.2 KiCad E.D.A. kicad 7.0.6 ld: 8/12

## Bumper Sensors



Corresponding Female: DigiKey PN 900-0022013027-ND Corresponding Crimp : DigiKey PN WM2756CT-ND Limit Switch : DigiKey PN \_\_\_\_\_

## Reflective Optical Sensors (Cliff Sensor)



Corresponding Female: DigiKey PN 900-0022013037-ND Corresponding Crimp : DigiKey PN WM2756CT-ND



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Sheet: /OtherSensors/ File: OtherSensors.kicad\_sch

Title: MCU Controller
Size: B Date:
KiCad E.D.A. kicad 7.0.6 Rev: 0.2

