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Sheet: /IMU/

File: IMU.kicad_sch

Title: MCU Controller

Size: B

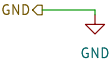
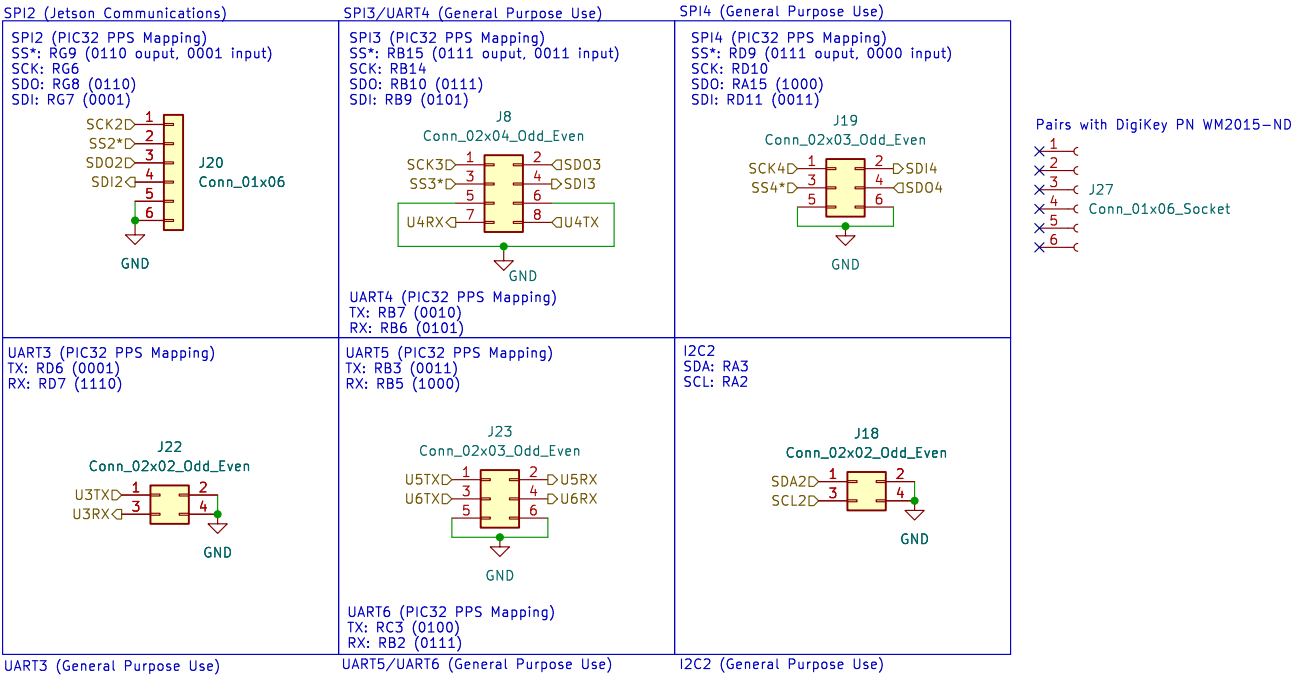
Date:

Rev: 0.3

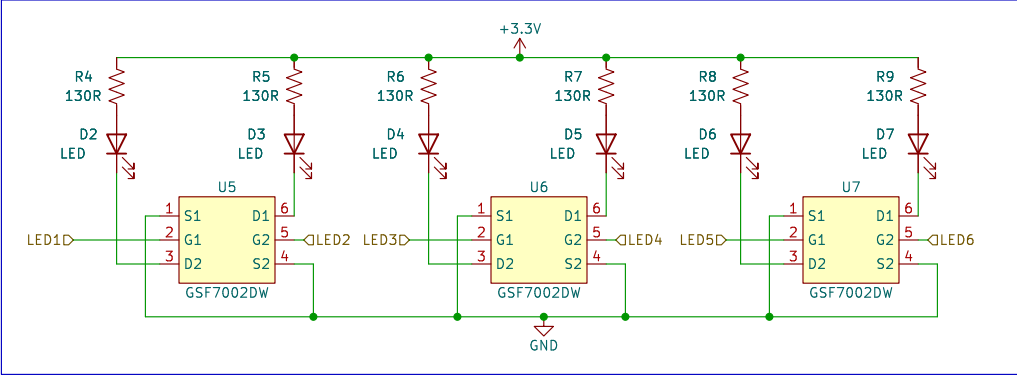
KiCad E.D.A. 9.0.2

Id: 3/12

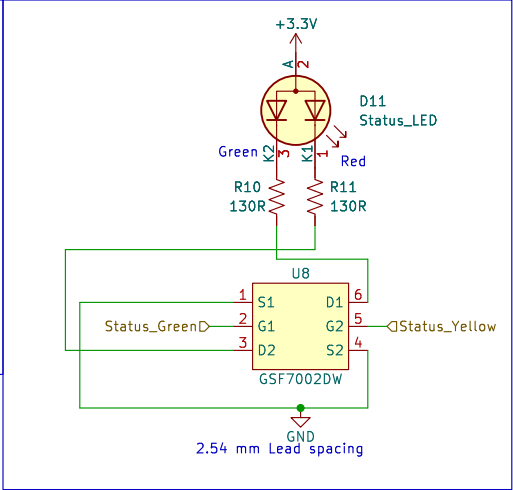
Groups pins together for SPI/UART/I2C for Jetson communication and for future use.



General Purpose LEDs

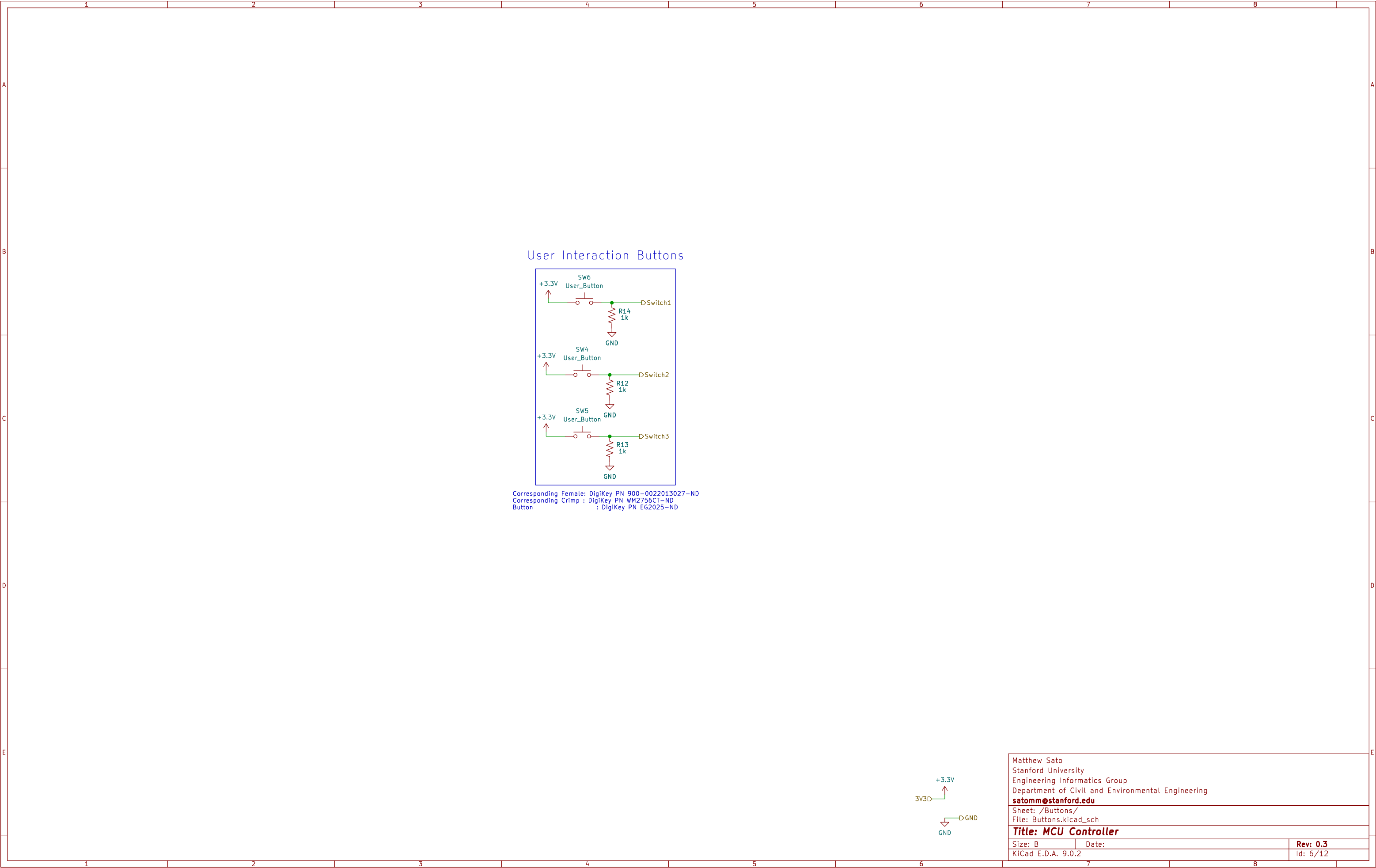


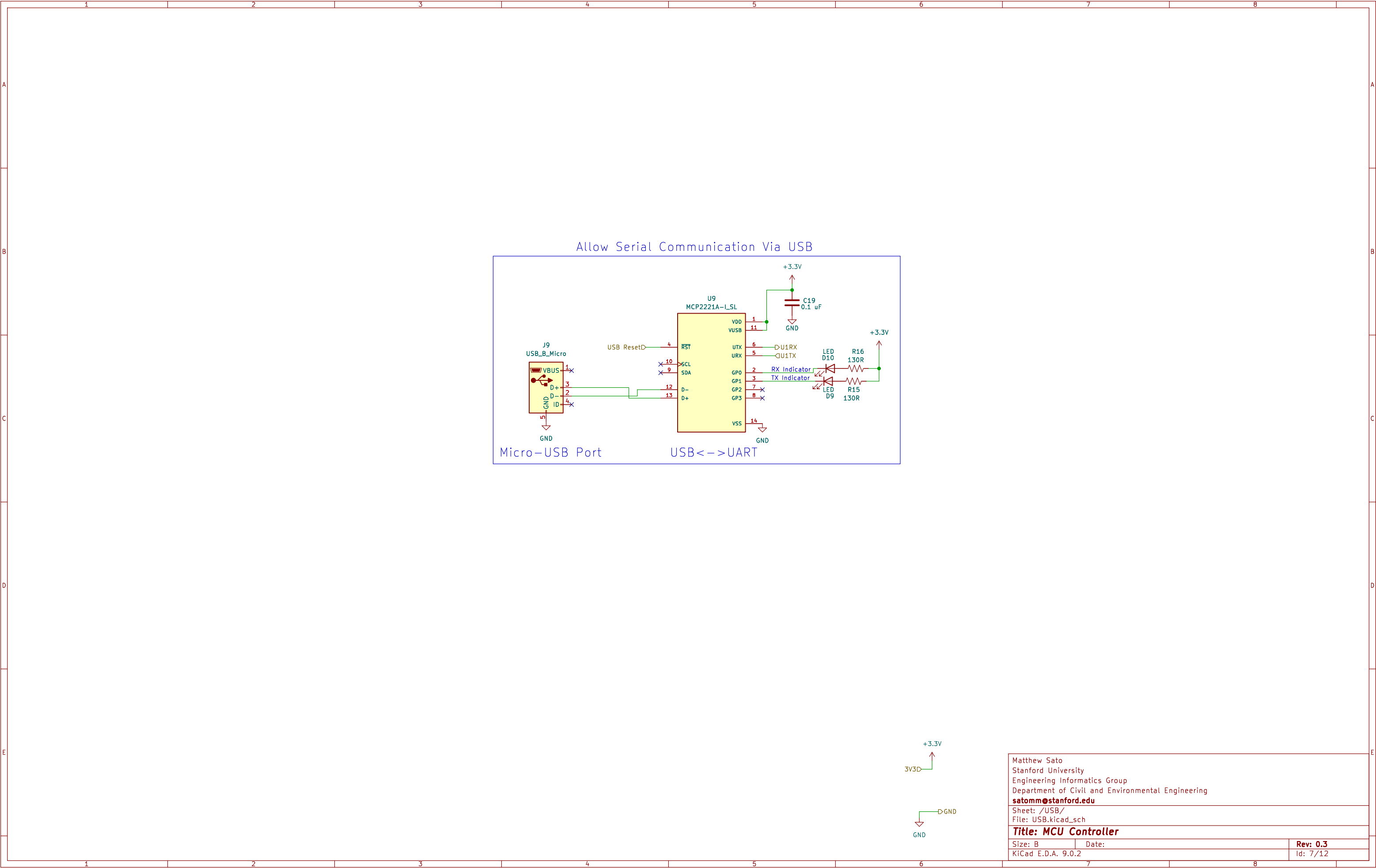
Robot Active/Inactive LED



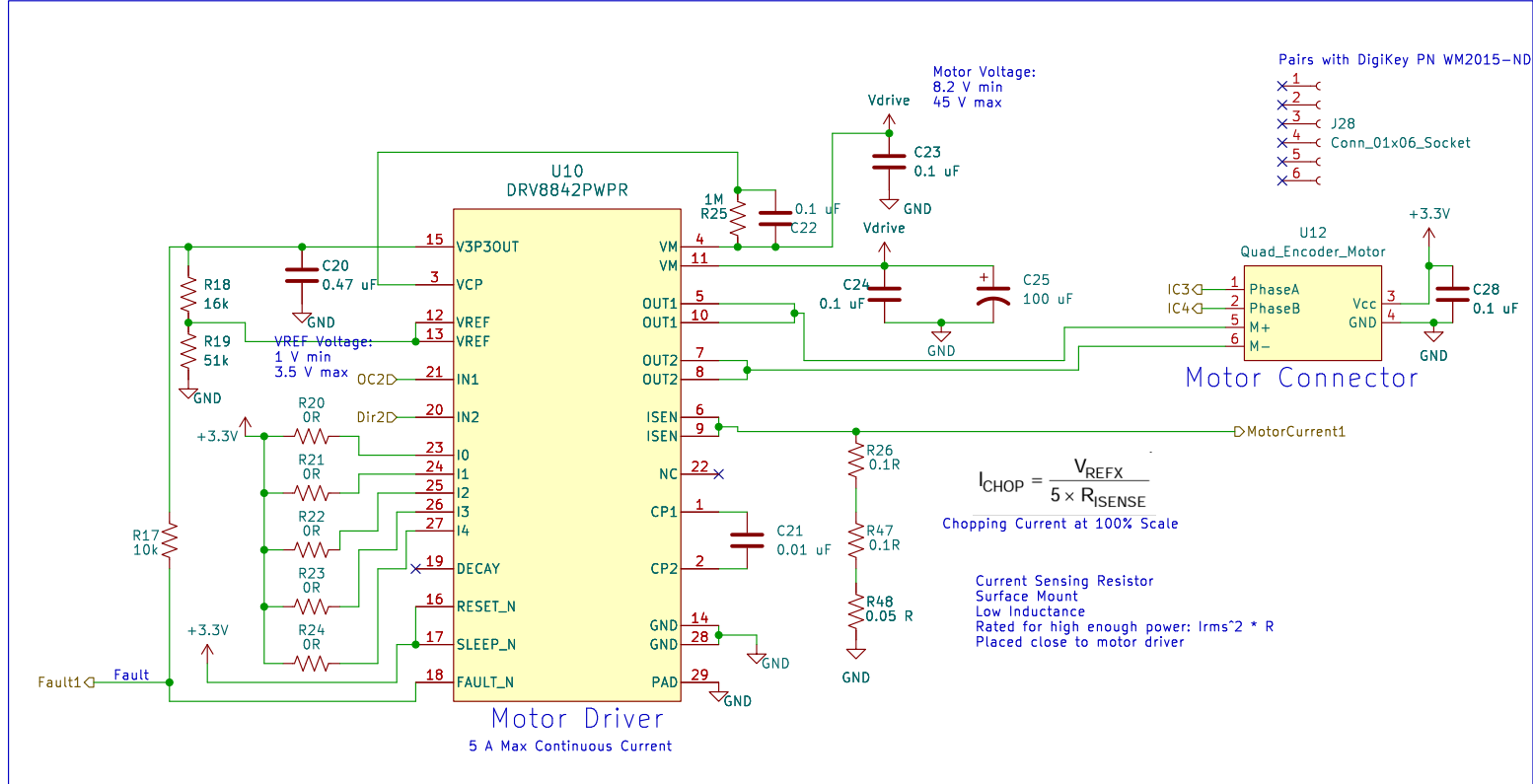
Corresponding Male : DigiKey PN WM4201-ND
Corresponding Female: DigiKey PN 900-0022013037-ND
Corresponding Crimp : DigiKey PN WM2756CT-ND



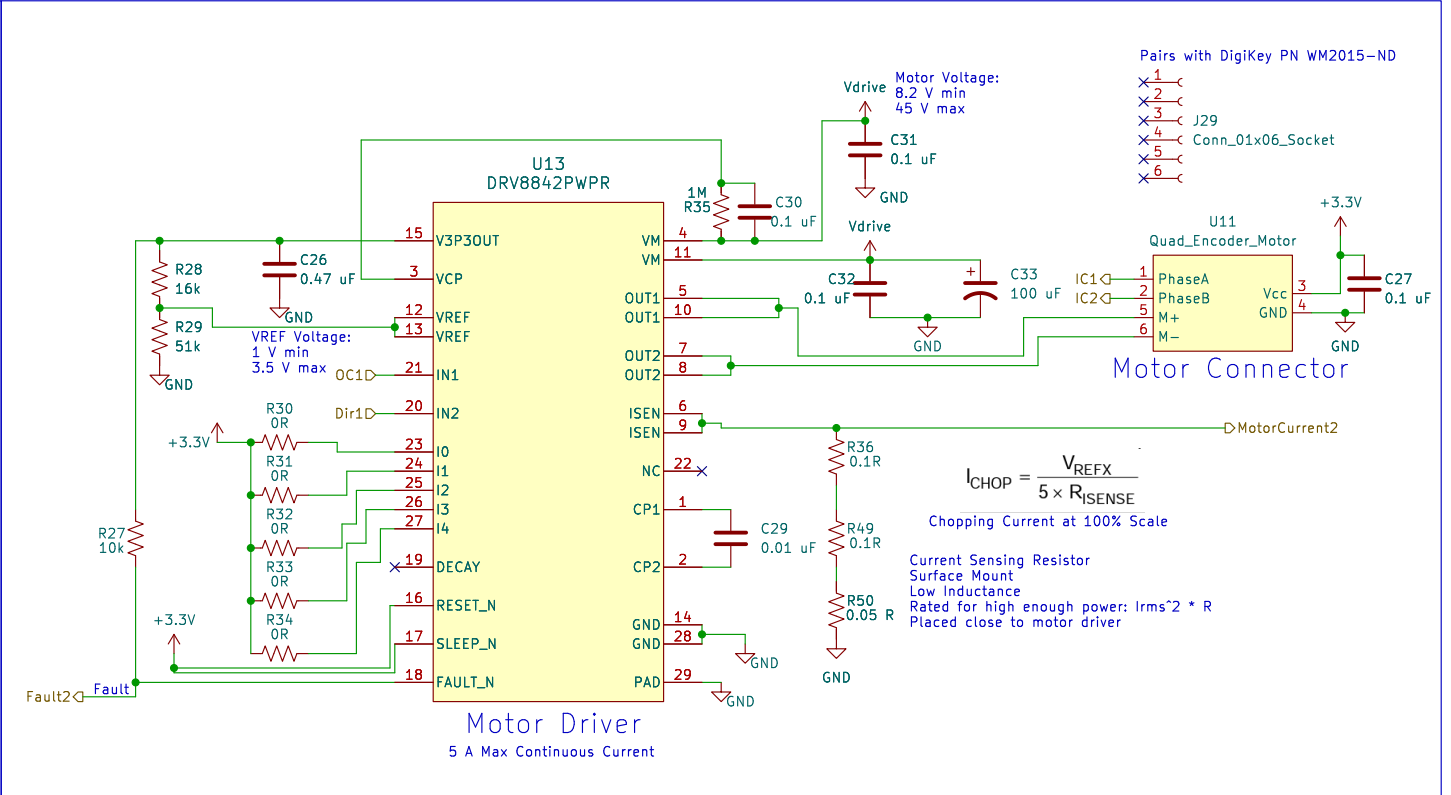




Left Motor Driver



Right Motor Driver



Corresponding Molex for Motor Connector:
Corresponding Female: DigiKey PN WM2002-ND
Corresponding Crimp : DigiKey PN WM2756CT-ND

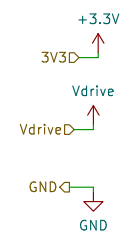
xIN1	xIN2	xOUT1	xOUT2
0	0	L	L
0	1	L	H
1	0	H	L
1	1	H	H

PWM Frequency:
100 kHz max

Slow Decay: Logic low
Mixed Decay: Open
Fast Decay: Logic high

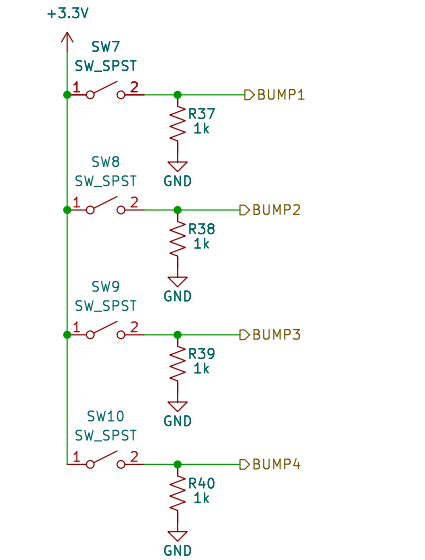
10 – 14 Function

[4-q]	RELATIVE CURRENT (% FULL-SCALE CHOPPING CURRENT)
0a00h	0%
0a01h	5%
0a02h	10%
0a03h	15%
0a04h	20%
0a05h	24%
0a06h	29%
0a07h	34%
0a08h	38%
0a09h	43%
0a0ah	47%
0a0bh	51%
0a0Ch	56%
0a0Dh	60%
0a0Eh	63%
0a0Fh	67%
0a10h	71%
0a11h	74%
0a12h	77%
0a13h	80%
0a14h	83%
0a15h	86%
0a16h	88%
0a17h	90%
0a18h	92%
0a19h	94%
0a1Ah	96%
0a1Bh	97%
0a1Ch	98%
0a1Dh	99%
0a1Eh	100%
0a1Fh	100%



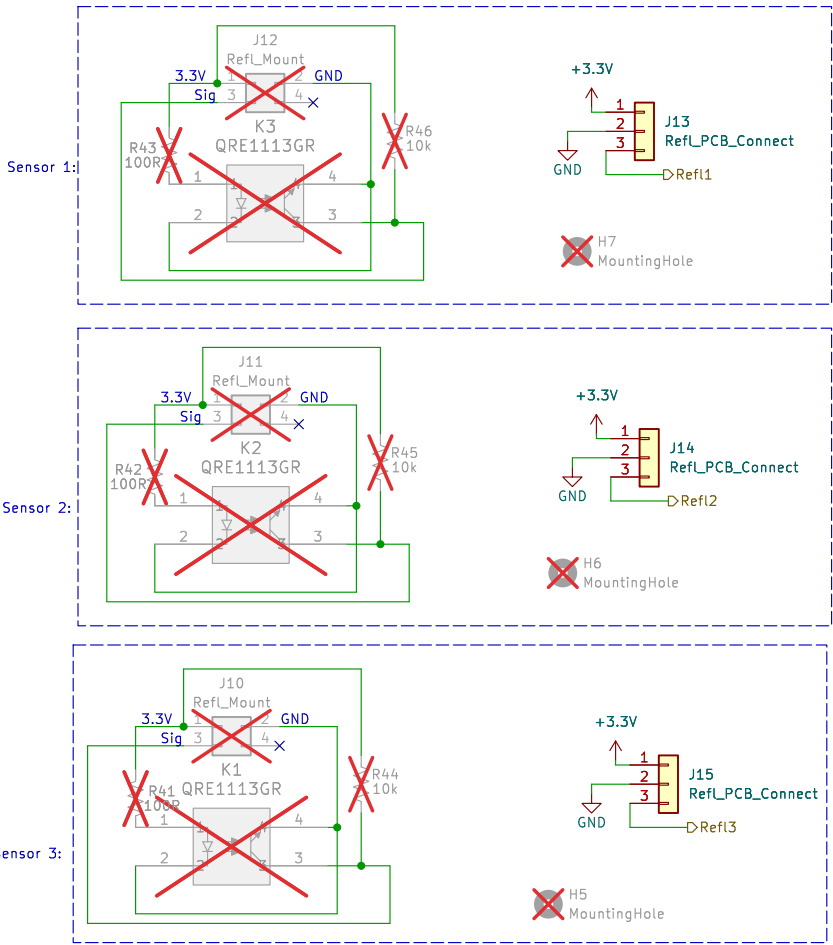
Matthew Sato	
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Sheet: /Motor/	
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Bumper Sensors



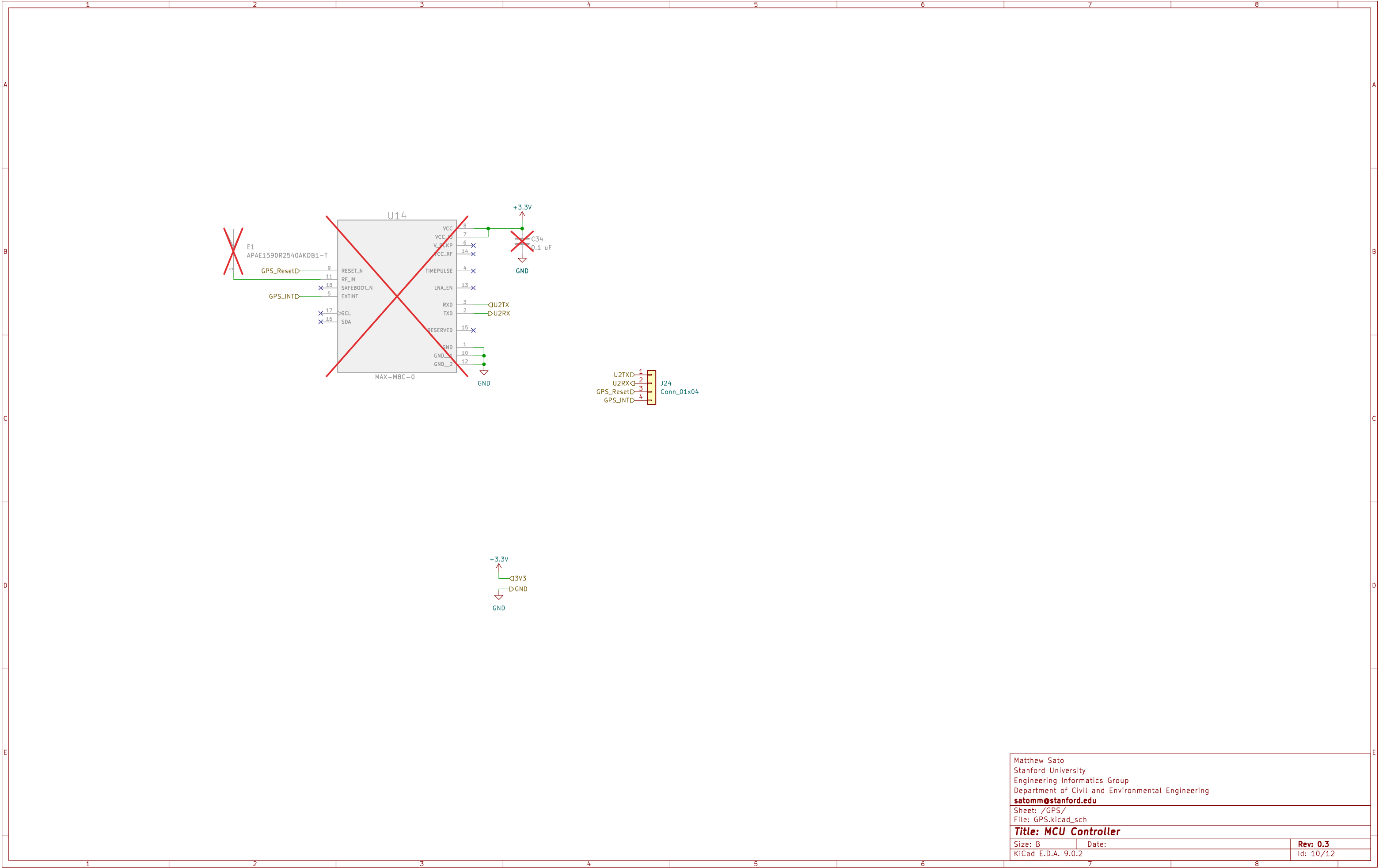
Corresponding Female: DigiKey PN 900-0022013027-ND
Corresponding Crimp : DigiKey PN WM2756CT-ND
Limit Switch : DigiKey PN _____

Reflective Optical Sensors
(Cliff Sensor)

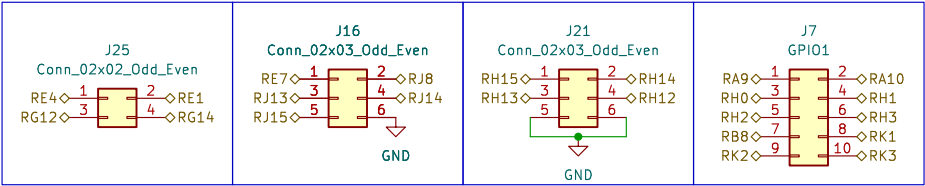


Corresponding Female: DigiKey PN 900-0022013037-ND
Corresponding Crimp : DigiKey PN WM2756CT-ND

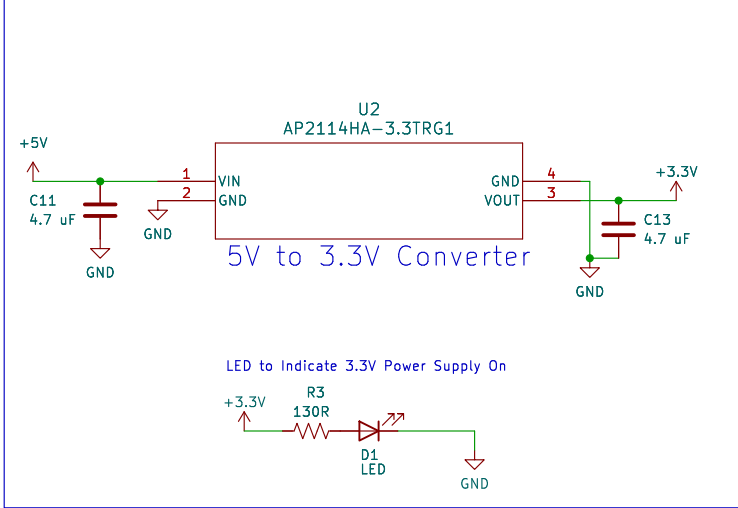




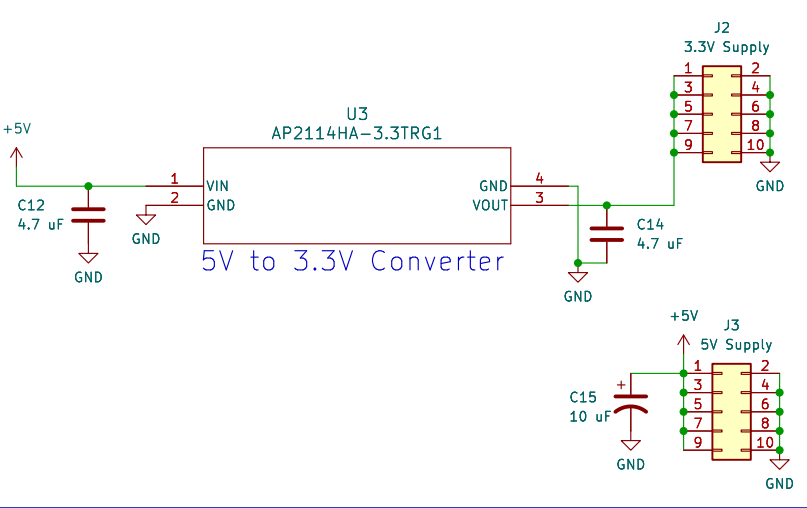
Provide Access to Unused Pins



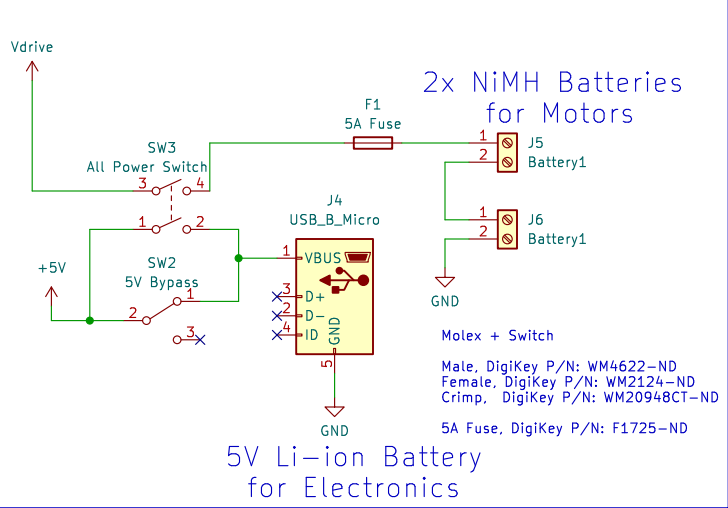
3.3V Converter for ICs



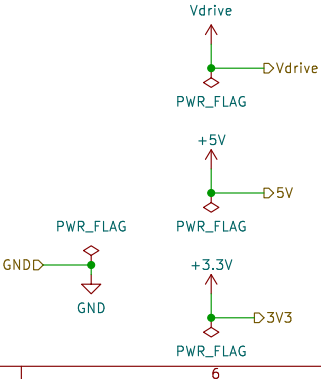
Auxilliary Power Pins



Power Switches

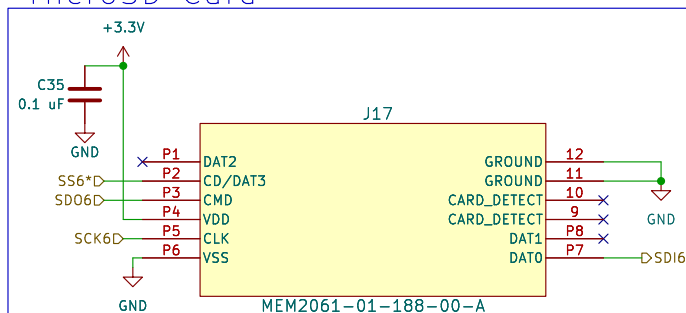


Inputs:
1) Motor Battery: 2x NiMH Battery, 7.2 V Each
2) Battery for MCU: 5 V

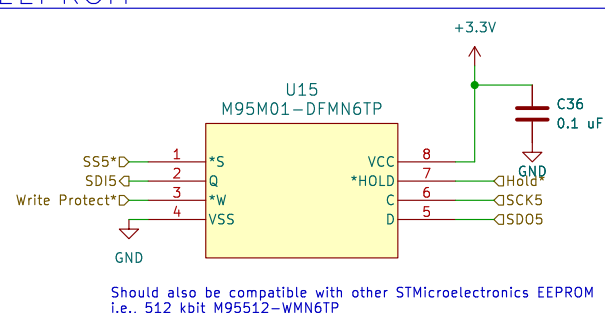


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KiCad E.D.A. 9.0.2		Id: 12/12

MicroSD Card



EEPROM



Matthew Sato Stanford University Engineering Informatics Group Department of Civil and Environmental Engineering satomm@stanford.edu		
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KiCad E.D.A. 9.0.2		Id: 12/12