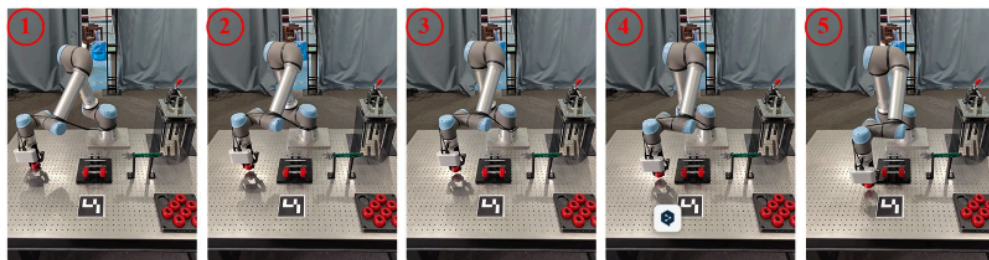
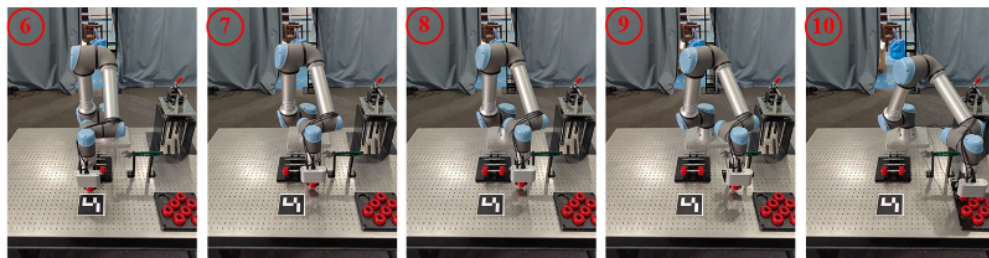


Action

Robot Model



$O_{t-10:t-6}$



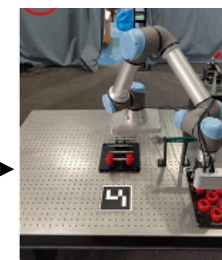
$O_{t-5:t-1}$

Interaction  
with env

"Put red ring  
on tray"

EBM

Reward



$O_t$