大数据与机器智能

```
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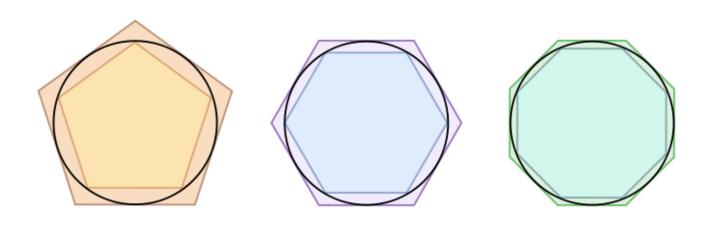
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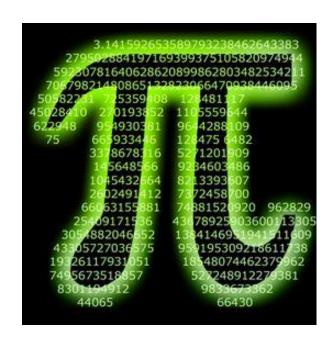
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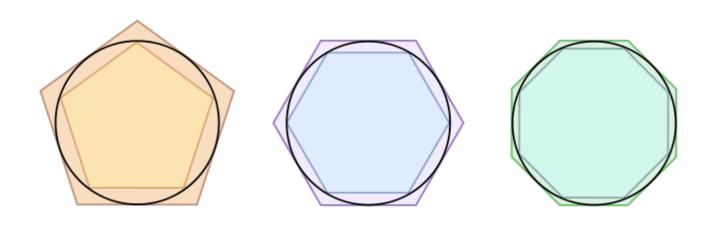
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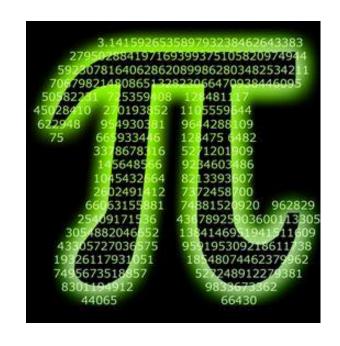
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```











π可以透过计算圆的外切多边形及内接多边形周长来估算

祖冲之在公元480年利用割圆术计算12,288形的边长,得到 $\pi \approx \frac{355}{113}$ (现在称为密率),其数值为3.141592920,小数点后的前六位数都是正确值。在之后的八百年内,这都是准确度最高的 π 估计值。为纪念祖冲之对圆周率发展的贡献,日本数学家三上义夫将这一推算值命名为"祖冲之圆周率",简称"祖率"。

$$rctan(x) = \sum_{k=0}^{\infty} (-1)^k rac{x^{2k+1}}{2k+1} = x - rac{1}{3}x^3 + rac{1}{5}x^5 - rac{1}{7}x^7 + \cdots$$

反正切泰勒级数

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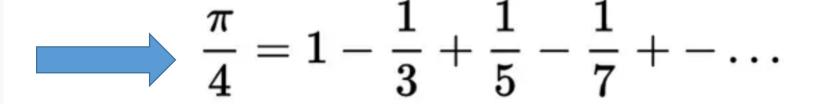
反正切泰勒级数

当
$$x=1$$
时, $arctanx = \pi/4$

$$rac{\pi}{4} = \sum_{n=0}^{\infty} \, rac{(-1)^n}{2n+1}$$

arctan1

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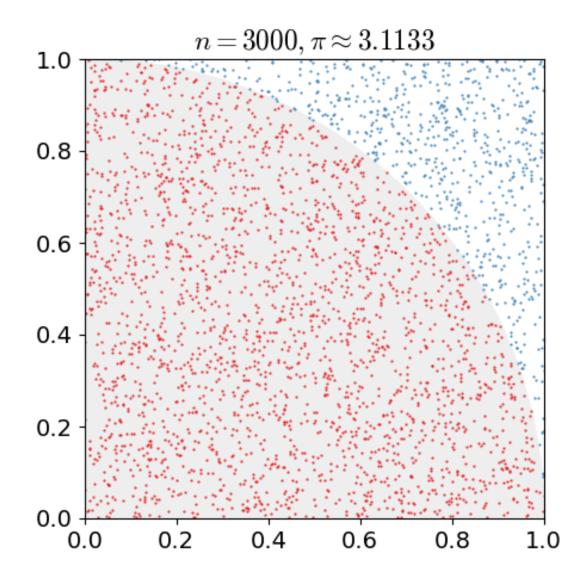


arctan1

$$\frac{\pi}{4} = 1 - \frac{1}{3} + \frac{1}{5} - \frac{1}{7} + - \dots$$

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```
module TaylorPi (main) where
series xs = foldl step 0 xs
    where step acc x
            (odd x) && (odd(truncate(fromIntegral(x)/2)))
            = acc - 1 / fromIntegral(x)
            (odd x) && (odd(truncate(fromIntegral(x)/2)+1))
            = acc + 1 / fromIntegral(x)
            otherwise
            = acc
series_length = 100000
main = print(series([0..series_length]) * 4)
```



$$\frac{S_1}{S_2} = \frac{\pi/4}{1} = \frac{\pi}{4} \approx \frac{N_1}{N_2}$$

$$\therefore \pi \approx \frac{4N_1}{N_2}$$

当 N_2 =30000时, π 的估计值与真实值只相差0.07%

```
import random
3 ▼ if __name__ == '__main__':
    N2 = 30000
  N1 = 0.
6 ▼ for i in range(N2):
    x = random.random()
8
    y = random.random()
    if x*x+y*y<=1:
10
    N1+=1
    print("PI:",4*N1/N2)
11
```

$$\frac{S_1}{S_2} = \frac{\pi/4}{1} = \frac{\pi}{4} \approx \frac{N_1}{N_2}$$

$$\therefore \pi \approx \frac{4N_1}{N_2}$$

当 N_2 =30000时, π 的估计值与真实值只相差0.07%

当N₂=30000时,π的 相差0.07%

```
module MonPi (main) where
import System.Random
random times = 1000000
xcoor = take random_times $ randoms (mkStdGen 100) :: [Double]
ycoor = take random_times $ randoms (mkStdGen 101) :: [Double]
myzip :: [Double] -> [Double] -> [(Double, Double)]
myzip xs [] = []
myzip [] ys = []
myzip (x:xs) (y:ys) = (x, y) : myzip xs ys
xycoor = myzip xcoor ycoor
filtered_xycoor = filter (\s -> (fst s)^2 + (snd s)^2 < 1) xycoor
main = print(fromIntegral(length filtered_xycoor) / fromIntegral(random_times) * 4.0)
```

Chudnovsky公式

$$\pi = \frac{426880\sqrt{10005}}{\sum_{k=0}^{\infty} \frac{(6k)!(13591409 + 545140134k)}{(3k)!(k!)^{3}(-640320)^{3k}}}$$

这个公式可以做到每计算一项得出15位有效数字! 1994年,人们利用这个公式,得到了圆周率小数点后40.44亿位。

Chudnovsky公式

Chudnovsky公式

```
module ChudnovskyPi (main) where
factorial :: Integer -> Integer
factorial 0 = 1
factorial n = n * factorial (n - 1)
series xs = foldl step 0 xs
    where step acc x = acc + (fromIntegral(factorial(6*x)) *
    fromIntegral(13591409 + (545140134 * x)))/fromIntegral(factorial(x+x))
    +x)) / (fromIntegral(factorial(x)))^3 / (-640320)^fromIntegral(3*x)
series_length = 10
main = print(426880.0 * sqrt(10005) / series([0..series_length]))
```

迭代算法:

1. 设置初始值:

$$a_0=1 \qquad b_0=rac{1}{\sqrt{2}} \qquad t_0=rac{1}{4} \qquad p_0=1.$$

2. 反复执行以下步骤直到 a_n 与 b_n 之间的误差到达所需精度:

$$egin{aligned} a_{n+1}&=rac{a_n+b_n}{2},\ b_{n+1}&=\sqrt{a_nb_n},\ t_{n+1}&=t_n-p_n(a_n-a_{n+1})^2,\ p_{n+1}&=2p_n. \end{aligned}$$

3. 则π的近似值为:

$$\pi pprox rac{(a_{n+1} + b_{n+1})^2}{4t_{n+1}}.$$

迭代算法:

```
def Iterative_cal(number):
a_now = 1.
b_now = 1./math.sqrt(2)
t_now = .25
p_now = 1.
for i in range(number):
· · · · · · · a = (a_now+b_now)/2
b = math.sqrt(a_now*b_now)
t = t_now-p_now*math.pow((a_now-a),2)
----p = 2*p_now
 ---- a_now = a
----b_now = b
· · · · · · · t_now = · t
---- p_now = p
print("Iterative PI:", math.pow(a_now+b_now, 2)/(4*t_now))
```

迭代算法:

```
module IterativePi (main) where
iter_times = 25
fib a b c d = a:b:c:d:fib ((a+b)/2) (sqrt(a*b)) (c-d*(a-(a+b)/2)^2) (2*d)
x = iter_times * 4
series = take x (fib 1.0 (1/sqrt(2.0)) 0.25 1.0)
s1 = series !! (x-4)
s2 = series !! (x-3)
s3 = series !! (x-2)
s4 = series !! (x-1)
main = putStrLn (show (((s1+s2)^2)/(4*s3)))
```