

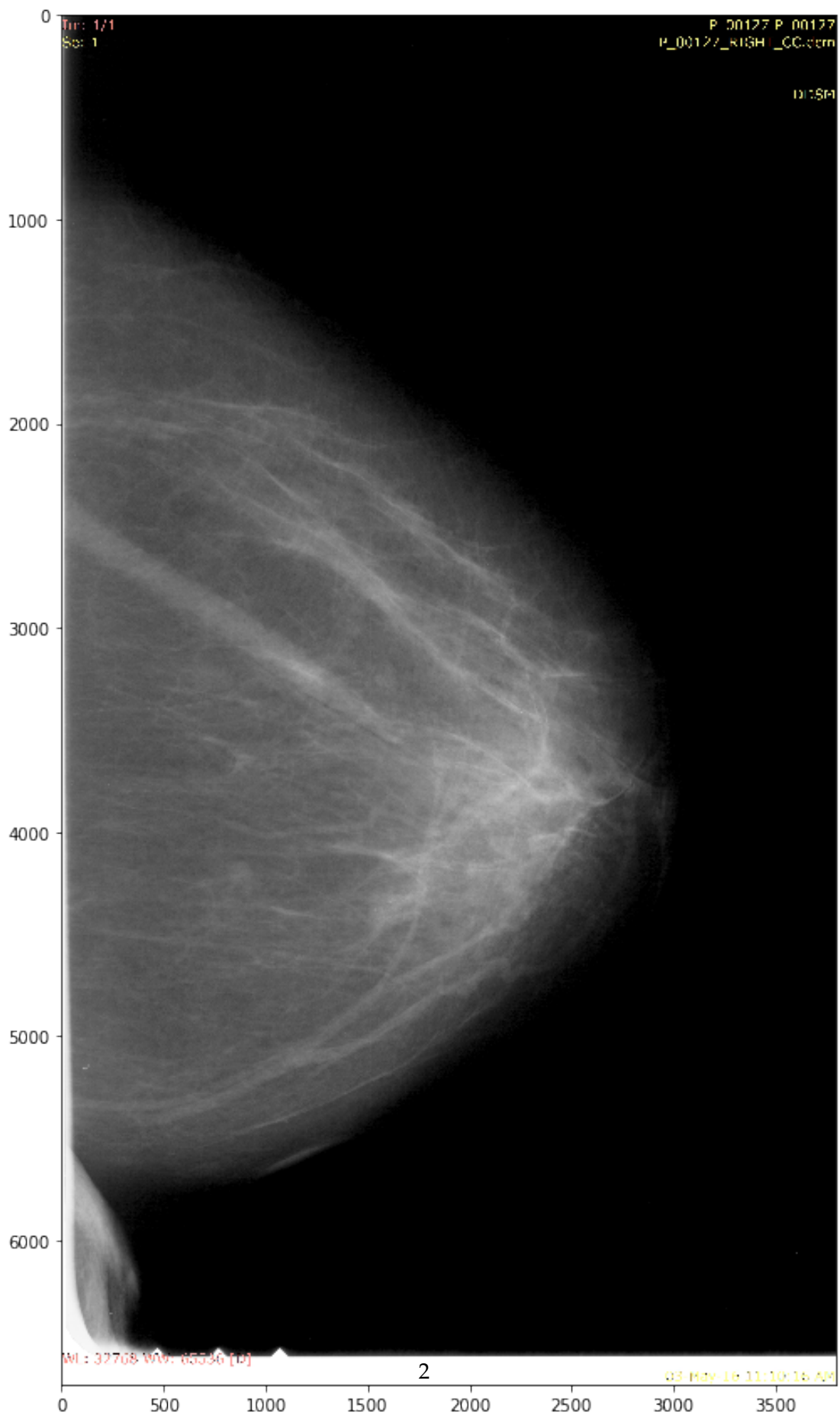
MedicalFeatureExtraction

October 3, 2018

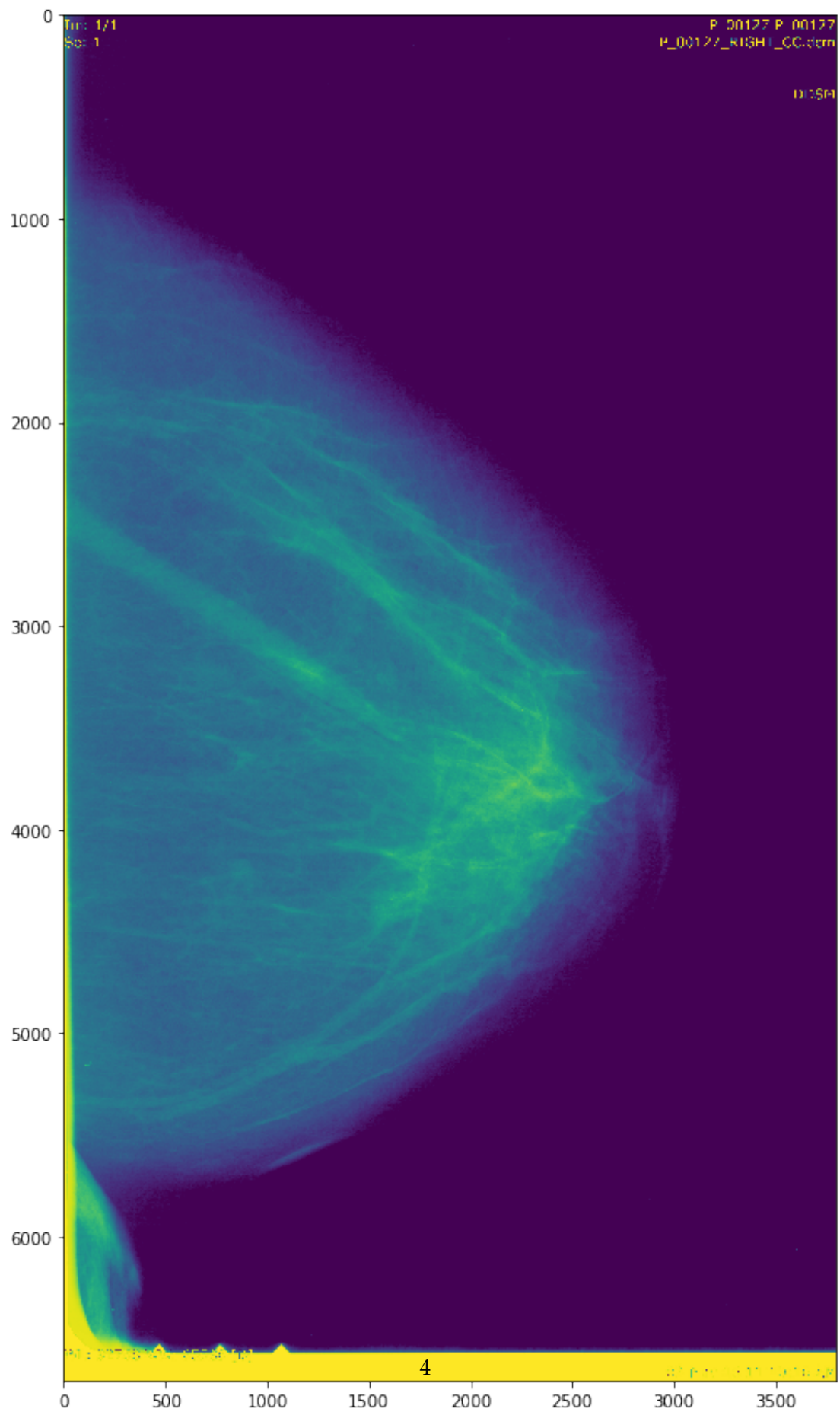
1 Medical Feature Extraction

```
In [6]: import matplotlib.pyplot as plt
import matplotlib.image as mpimg
import numpy as np

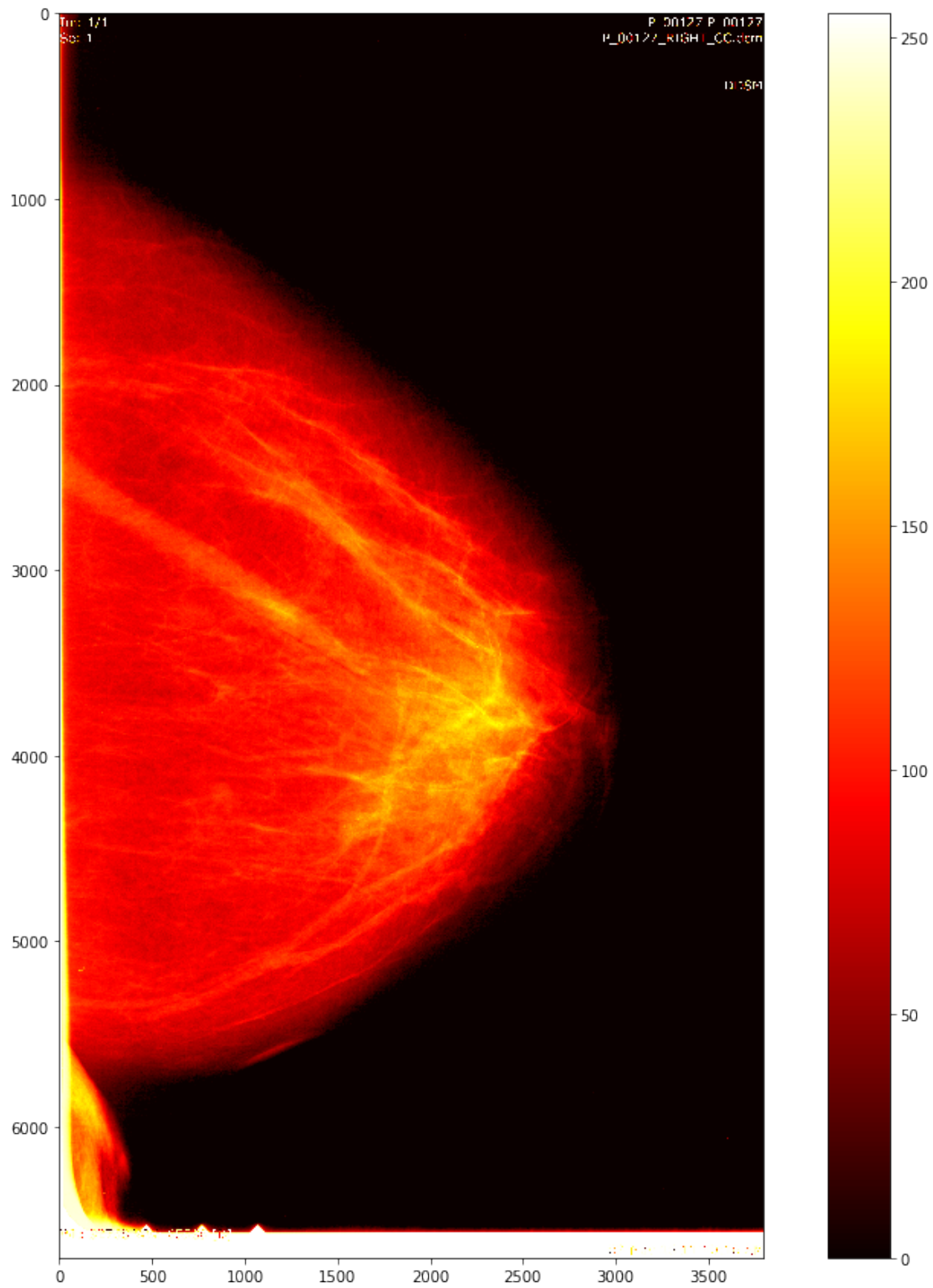
In [145]: img = mpimg.imread('IMG-0001-00001.jpg')
plt.figure(figsize=(15, 15))
plt.imshow(img)
plt.show()
```



```
In [8]: lum_img = img[:, :, 0]
plt.figure(figsize=(15, 15))
plt.imshow(lum_img)
plt.show()
```

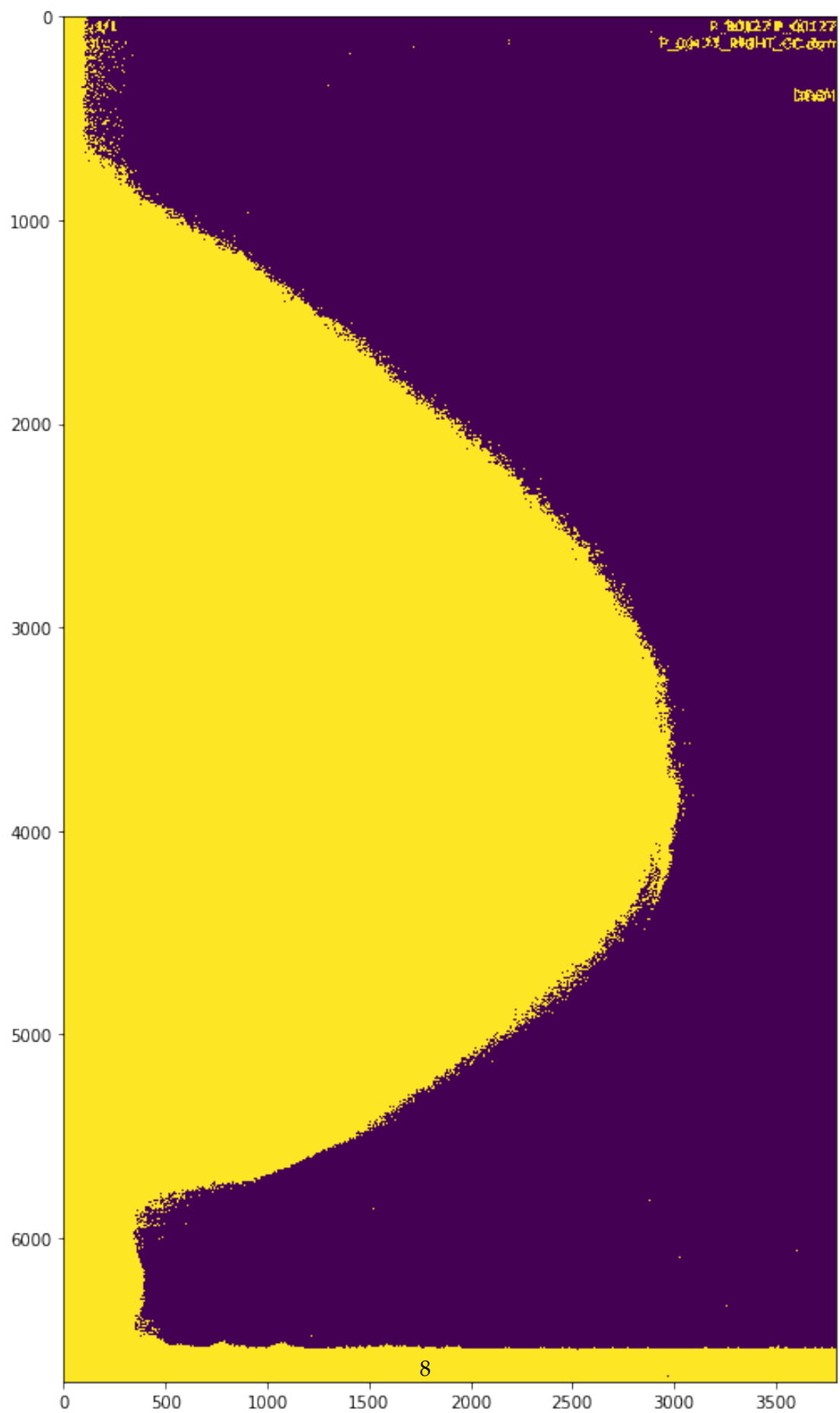


```
In [9]: plt.figure(figsize=(15, 15))  
        plt.imshow(lum_img, cmap='hot')  
        plt.colorbar()  
        plt.show()
```

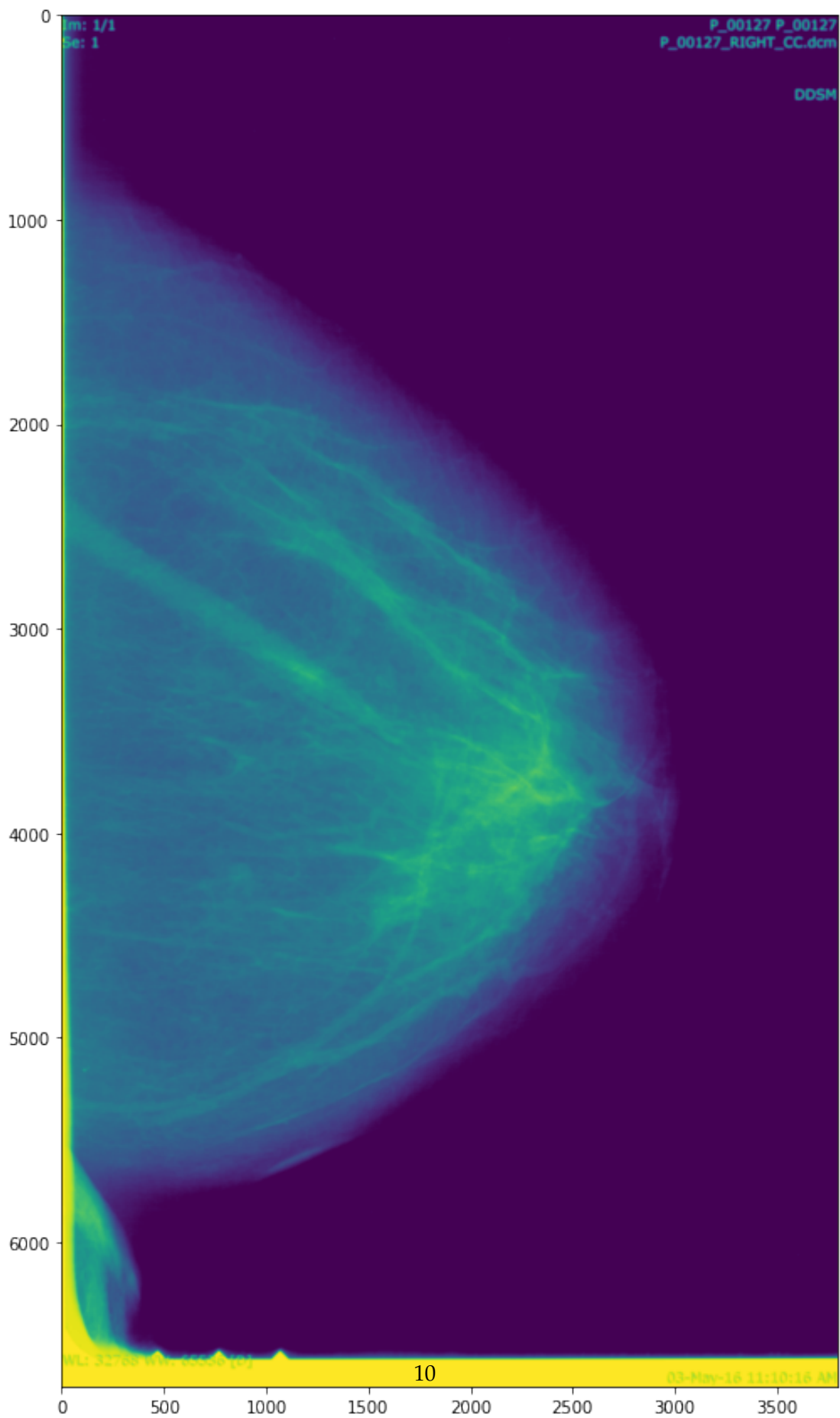


```
In [10]: plt.figure(figsize=(15, 15))
```

```
plt.imshow(lum_img, clim=(0.0, 0.7))  
plt.show()
```




```
In [11]: plt.figure(figsize=(15, 15))
plt.imshow(lum_img, interpolation='bicubic')
plt.show()
```

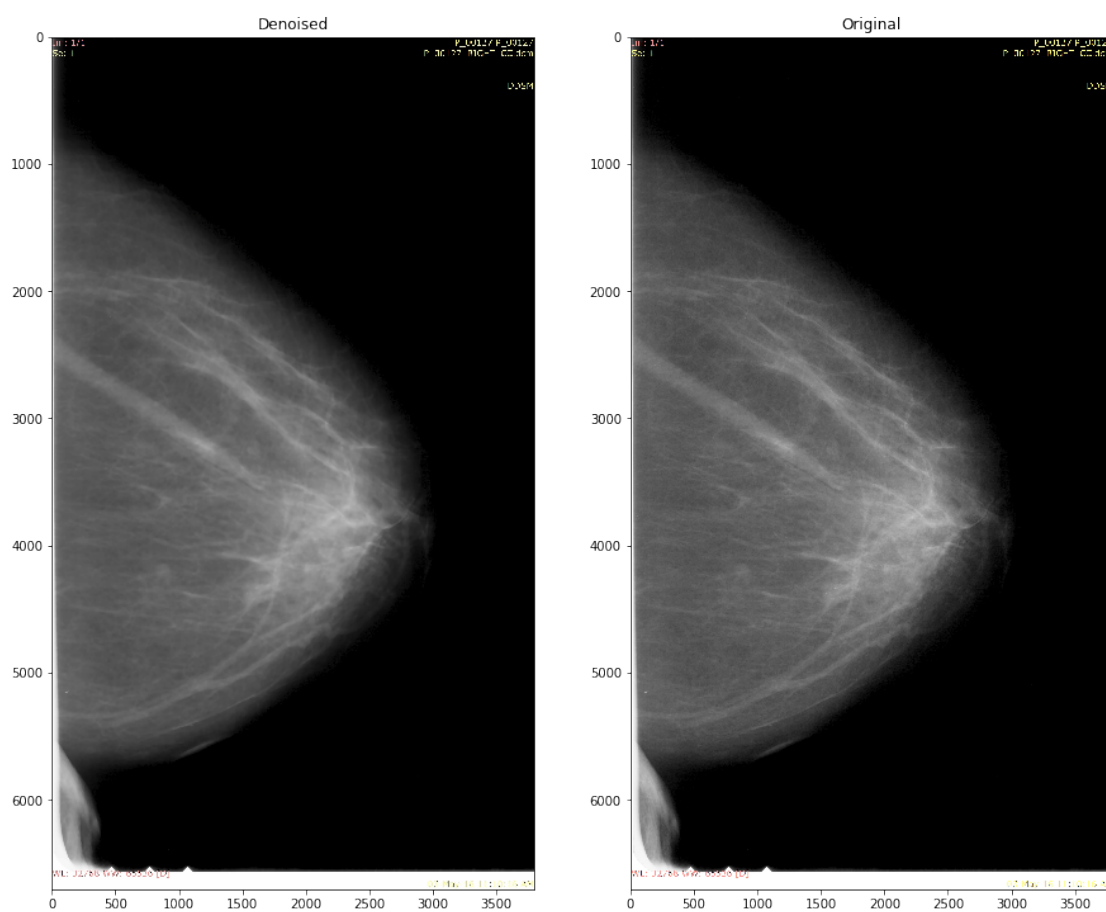


1.1 Processing the Image

```
In [146]: import cv2
```

```
In [148]: dst = cv2.fastNlMeansDenoisingColored(img, None, 10, 10, 7, 21)
```

```
In [16]: plt.figure(figsize=(15, 15))  
plt.subplot(121), plt.imshow(dst), plt.title('Denoised')  
plt.subplot(122), plt.imshow(img), plt.title('Original')  
plt.show()
```



1.2 GLCM - Gray Level Co-Occurrence Matrix

```
In [21]: from skimage.feature import greycomatrix, greycoprops  
from skimage import data
```

```

PATCH_SIZE = 21

# open the camera image
# image = data.camera()
image = lum_img

# select some patches from grassy areas of the image
grass_locations = [(474, 291), (440, 433), (466, 18), (462, 236)]
grass_patches = []
for loc in grass_locations:
    grass_patches.append(image[loc[0]:loc[0] + PATCH_SIZE,
                              loc[1]:loc[1] + PATCH_SIZE])

# select some patches from sky areas of the image
sky_locations = [(54, 48), (21, 233), (90, 380), (195, 330)]
sky_patches = []
for loc in sky_locations:
    sky_patches.append(image[loc[0]:loc[0] + PATCH_SIZE,
                              loc[1]:loc[1] + PATCH_SIZE])

# compute some GLCM properties each patch
xs = []
ys = []
for patch in (grass_patches + sky_patches):
    glcm = greycomatrix(patch, [5], [0], 256, symmetric=True, normed=True)
    xs.append(greycoprops(glcm, 'dissimilarity')[0, 0])
    ys.append(greycoprops(glcm, 'correlation')[0, 0])

# create the figure
fig = plt.figure(figsize=(8, 8))

# display original image with locations of patches
ax = fig.add_subplot(3, 2, 1)
ax.imshow(image, cmap=plt.cm.gray, interpolation='nearest',
          vmin=0, vmax=255)
for (y, x) in grass_locations:
    ax.plot(x + PATCH_SIZE / 2, y + PATCH_SIZE / 2, 'gs')
for (y, x) in sky_locations:
    ax.plot(x + PATCH_SIZE / 2, y + PATCH_SIZE / 2, 'bs')
ax.set_xlabel('Original Image')
ax.set_xticks([])
ax.set_yticks([])
ax.axis('image')

# for each patch, plot (dissimilarity, correlation)
ax = fig.add_subplot(3, 2, 2)
ax.plot(xs[:len(grass_patches)], ys[:len(grass_patches)], 'go',

```

```

        label='Grass')
ax.plot(xs[len(grass_patches):], ys[len(grass_patches):], 'bo',
        label='Sky')
ax.set_xlabel('GLCM Dissimilarity')
ax.set_ylabel('GLCM Correlation')
ax.legend()

# display the image patches
for i, patch in enumerate(grass_patches):
    ax = fig.add_subplot(3, len(grass_patches), len(grass_patches)*1 + i + 1)
    ax.imshow(patch, cmap=plt.cm.gray, interpolation='nearest',
              vmin=0, vmax=255)
    ax.set_xlabel('Grass %d' % (i + 1))

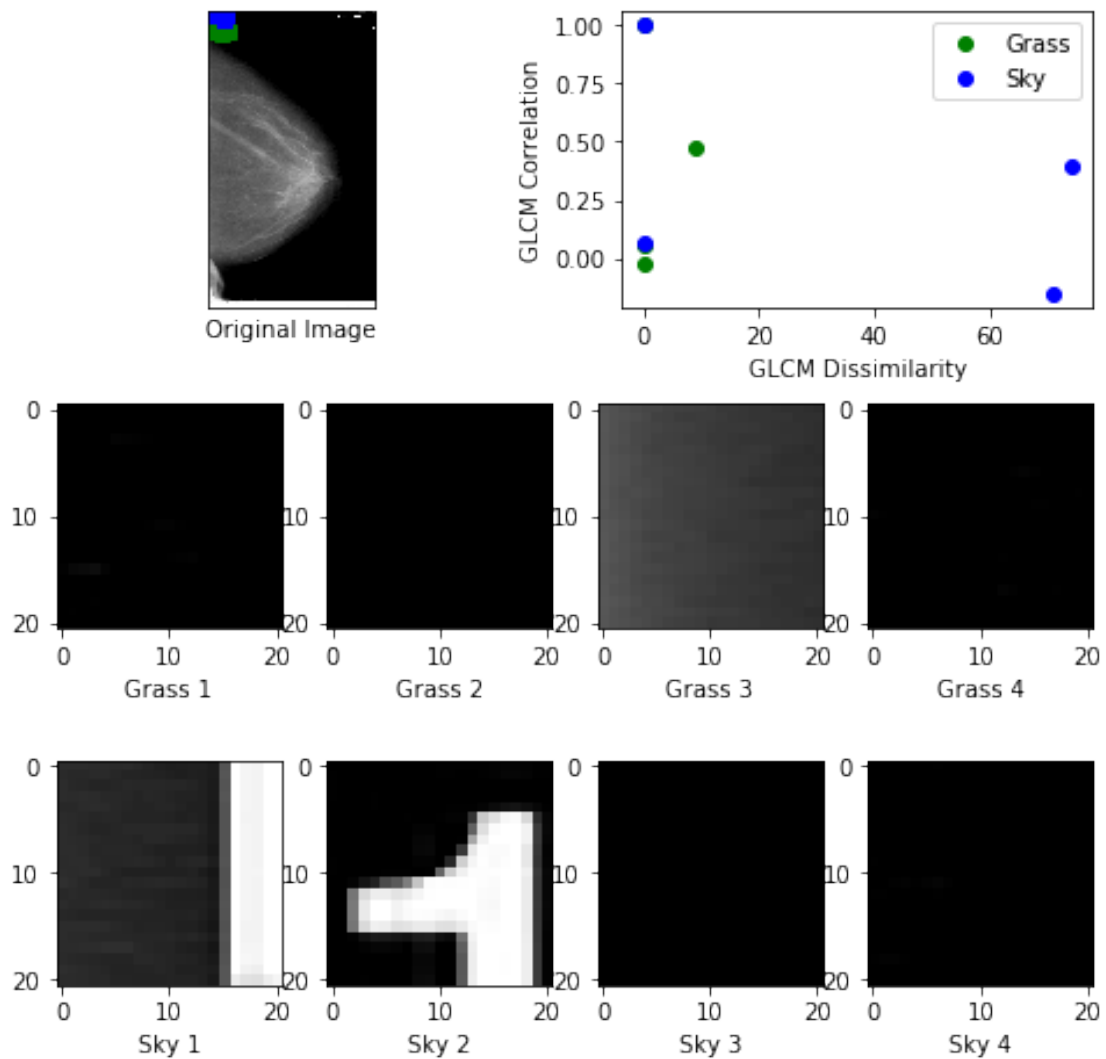
for i, patch in enumerate(sky_patches):
    ax = fig.add_subplot(3, len(sky_patches), len(sky_patches)*2 + i + 1)
    ax.imshow(patch, cmap=plt.cm.gray, interpolation='nearest',
              vmin=0, vmax=255)
    ax.set_xlabel('Sky %d' % (i + 1))

# display the patches and plot
fig.suptitle('Grey level co-occurrence matrix features', fontsize=14)
plt.show()

```

C:\Users\shadowleaf\Anaconda3\lib\site-packages\skimage\feature\texture.py:109: FutureWarning:
if np.issubdtype(image.dtype, np.float):

Grey level co-occurrence matrix features



In [42]: %%file Texture.py

```
import numpy
import threading
import logging
```

```
class CooccurrenceMatrixTextures(object):
    '''The class performs determines the cooccurrence matrix
    for a set window size over and image. It also computes
    and returns a number of statisitcs computed using the
    output cooccurrence matrix'''
```

```

def __init__(self, image, windowRadius = 2):
    self.image = image
    self.windowRadius = windowRadius
    self.xRange = range(-self.windowRadius,self.windowRadius+1)
    self.yRange = range(-self.windowRadius,self.windowRadius+1)
    self.lock = threading.Lock()
    self.__getMatrix()

def acquireLock(self):
    """Hook for multithreaded operation to acquire a lock."""
    self.lock.acquire()

def releaseLock(self):
    """Hook for multithreaded operation to release a lock."""
    self.lock.release()

def getDissimilarity(self):
    '''Getter method to extract the Dissimilarity'''
    return self.__dissimilarity()

def getEntropy(self):
    '''Getter method to extract the Entropy'''
    return self.__entropy()

def getASM(self):
    '''Getter method to extract the Angular Second Momentum'''
    return self.__asm()

def getMean(self):
    '''Getter method to extract the Mean'''
    return self.__mean()

def getVarMean(self):
    '''Getter method to obtain the Mean and Variance'''
    #get texture
    mean = self.__mean()
    var = self.__variance(mean)
    return var, mean

def getCorrVarMean(self):
    '''Getter method to obtain the Mean, Variance and Correlation'''
    #get texture
    mean = self.__mean()

```

```

        var = self.__variance(mean)
        corr = self.__correlation(mean, var)
        return corr, var, mean

def __dissimilarity(self):
    '''This method gets the contrast image derived from the GLCM'''

    #first create the contrast matrix
    topHalf = self.__diagMatrix()
    weights = topHalf + topHalf.T
    print(weights)

    #flatten
    weights = weights.flatten()

    #apply to the image through broadcasting
    weightedGLCM = self.GLCM * weights

    #sum along the third axis
    dissimilarity = numpy.sum(weightedGLCM,2)

    #return the result
    return dissimilarity

def __entropy(self):
    '''This method gets the entropy from the GLCM'''

    #mask off the glcm
    maGLCM = numpy.ma.MaskedArray(self.GLCM, self.GLCM == 0)

    #calculate the logs and sum along the 3rd dimension
    entropy = numpy.sum(numpy.log(maGLCM) * maGLCM * (-1), 2)

    #return the result
    return entropy

def __asm(self):
    '''This method returns the Angular Second Momentum for the GLCM'''

    return numpy.sum(self.GLCM * self.GLCM, 2)

def __mean(self):
    '''This method gets the GLCM mean'''

    #create the output array
    shape = numpy.shape(self.GLCM)
    meanGLCM = numpy.zeros([shape[0],shape[1]])

```



```

#Loop over each quantisation
steps = range(0,256,16)
coeff = 0
for x in steps:

    #sum the contents of the row and multiply by the coocurrence (GLCM Mean)
    summedStep = numpy.sum((self.GLCM[:, :, x:x+16] * coeff), 2)
    coeff += 1

    #sum into the output image
    meanGLCM += summedStep

#return the output image
return meanGLCM

def __variance(self, mean):
    '''This method gets the GLCM variance and mean'''
    #create the output array
    shape = numpy.shape(self.GLCM)
    varGLCM = numpy.zeros([shape[0], shape[1]])

    #Loop over each quantisation
    steps = range(256)
    coeff = numpy.repeat(range(16), 16)
    for x in steps:

        #sum the contents of the row and multiply by the coocurrence (GLCM Var)
        step = self.GLCM[:, :, x] * numpy.power(coeff[x] - mean, 2)

        #sum into the output image
        varGLCM += step

    #return the output image
    return varGLCM

def __correlation(self, mean, var):
    '''This method calculates the GLCM correlation, variance and mean'''
    #create the output array
    shape = numpy.shape(self.GLCM)
    corrGLCM = numpy.zeros([shape[0], shape[1]])

    #Loop over quantisation steps
    steps = range(256)
    coeffA = numpy.repeat(range(16), 16)
    coeffB = numpy.tile(range(16), 16)
    for x in steps:

```

```

        #determine correlation (small additive value to prevent divide by zero)
        step = self.GLCM[:, :, x] * ((coeffA[x] - mean) * (coeffB[x] - mean)) / (varA[x] * varB[x])

        #sum into the output image
        corrGLCM += step

    #return the output image
    return corrGLCM

def __getMatrix(self):
    '''This function computes the cooccurrence matrix'''

    #create output arrays
    shape = numpy.shape(self.image)
    self.GLCM = numpy.zeros([shape[0], shape[1], 256], numpy.int16)

    #set image as masked array
    maImage = numpy.ma.masked_array(self.image, self.image < 0)

    #scale the image to 4bit
    scaledImage = self.__scaleImage(maImage)

    #create the x and y indeices for the lookup
    [self.indexX, self.indexY] = numpy.meshgrid(range(shape[1]), range(shape[0]))

    #shift over all directions to create rotational invariance
    x = [0, 1, 1, 1]
    y = [1, 1, 0, -1]
    for i in range(4):

        #roll the image
        shiftedImage = self.__roll2d(scaledImage, x[i], y[i])

        #compute the indices based upon the pixel values
        self.index = self.__findIndex(scaledImage, shiftedImage)
        self.indexInverse = self.__findIndex(shiftedImage, scaledImage)

    #do processing
    self.processElements()

    #get denominator
    den = (self.windowRadius * 2 + 1) ** 2 * 8.0

    #convert to probabilities
    self.GLCM = self.GLCM / den

def __scaleImage(self, image, scaledMin = 0., scaledMax = 15.):

```

```

'''This private method scales the image to 4bit range'''

#gets min and max
imageMax = numpy.max(image)
imageMin = numpy.min(image)

#scale and replace the image
scaledIm = (((image - imageMin) * (scaledMax-scaledMin)) / (imageMax - imageMin))
scaledIm = numpy.round(scaledIm).astype(numpy.int32)
#imgplot = plt.imshow(scaledIm) #@UnusedVariable
#imgplot.set_cmap('Greys')
#plt.show()
return scaledIm

def appendGLCM(self,i,j):

    #roll the indexes
    rolledIndex = self.__roll2d(self.index, i, j)
    rolledIndexInverse = self.__roll2d(self.indexInverse, i, j)

    #use the indices to fill the GLCM
    self.acquireLock()
    self.GLCM[self.indexY,self.indexX,rolledIndex] += 1
    self.GLCM[self.indexY,self.indexX,rolledIndexInverse] += 1
    self.releaseLock()

def processYElements(self, i):
    for j in self.yRange:
        self.appendGLCM(i,j)

def processElements(self):
    threadList = []
    for i in self.xRange:
        t = threading.Thread(name = str(i), target = self.processYElements, args = (i,))
        threadList.append(t)
        logging.info('Starting thread %d', i)
        t.start()
    logging.debug('Waiting to join threads')
    for t in threadList:
        logging.debug('About to join thread %s', t.getName())
        t.join()

def __roll2d(self, image, xdir, ydir):
    '''This private method rolls the image in the given directions'''
    tmp = numpy.roll(image, ydir, 0)
    return numpy.roll(tmp, xdir, 1)

def __findIndex(self, referenceImage, neighbourImage):

```

```

        '''Finds the index into which a count must be inserted'''
        index = referenceImage * 16 + neighbourImage
        return index

def __diagMatrix(self):
    '''Method to create a diagonal matrix'''

    xRange = range(16)
    yRange = range(16)
    dMatrix = numpy.zeros([16,16], numpy.int16)

    #Loop over the array and fill it in
    xInc = 0
    for y in yRange:
        val = 0
        for x in xRange:

            xPos = x + xInc

            if xPos >= 16:
                continue
            else:
                #place the value into the matrix
                dMatrix[y,xPos] = val

            val+=1
            xInc+=1
        return dMatrix

def getGLCM(self):
    '''This returns the GLCM'''
    return self.GLCM

```

Overwriting Texture.py

```

In [43]: from Texture import *
         CooccurrenceMatrixTextures(lum_img)

```

MemoryError

Traceback (most recent call last)

```

<ipython-input-43-be2d1f47fa3b> in <module>()
    1 from Texture import *

```

```
----> 2 CooccurrenceMatrixTextures(lum_img)
```

```
D:\MachineLearningProjects\BreastCancerDetection\Texture.py in __init__(self, image, w
15         self.xRange = range(-self.windowRadius,self.windowRadius+1)
16         self.yRange = range(-self.windowRadius,self.windowRadius+1)
--> 17         self.lock = threading.Lock()
18         self.__getMatrix()
19
```

```
D:\MachineLearningProjects\BreastCancerDetection\Texture.py in __getMatrix(self)
167
168         #create output arrays
--> 169         shape = numpy.shape(self.image)
170         self.GLCM = numpy.zeros([shape[0],shape[1],256], numpy.int16)
171
```

MemoryError:

```
In [78]: import matplotlib.pyplot as plt
import gdal, gdalconst
import numpy as np
from skimage.feature import greycomatrix, greycoprops

#Read SAR image into Numpy Array
filename = "greyscale.png"
sarfile = gdal.Open(filename, gdalconst.GA_ReadOnly)
sarraster = sarfile.ReadAsArray()
print(sarraster.ndim)

#Create rasters to receive texture and define filenames
contrastraster = np.copy(sarraster)
contrastraster[:] = 0

dissimilarityraster = np.copy(sarraster)
dissimilarityraster[:] = 0

homogeneityraster = np.copy(sarraster)
homogeneityraster[:] = 0

energyraster = np.copy(sarraster)
energyraster[:] = 0

correlationraster = np.copy(sarraster)
correlationraster[:] = 0
```

```

ASMraster = np.copy(sarraster)
ASMraster[:] = 0

# Create figure to receive results
fig = plt.figure()
fig.suptitle('GLCM Textures')

# In first subplot add original SAR image
ax = plt.subplot(241)
plt.axis('off')
ax.set_title('Original Image')
plt.imshow(sarraster, cmap = 'gray')

for i in range(sarraster.shape[0]):
    print(i),
    for j in range(sarraster.shape[1]):

        # windows needs to fit completely in image
        if i > (contrastraster.shape[0] - 4) or j > (contrastraster.shape[0] - 4):
            continue

        # Define size of moving window
        glcm_window = sarraster[i-3: i+4, j-3 : j+4]
        # Calculate GLCM and textures
        glcm = greycomatrix(glcm_window, [1], [0], symmetric = True, normed = True )

        # Calculate texture and write into raster where moving window is centered
        contrastraster[i,j] = greycoprops(glcm, 'contrast')
        dissimilarityraster[i,j] = greycoprops(glcm, 'dissimilarity')
        homogeneityraster[i,j] = greycoprops(glcm, 'homogeneity')
        energyraster[i,j] = greycoprops(glcm, 'energy')
        correlationraster[i,j] = greycoprops(glcm, 'correlation')
        ASMraster[i,j] = greycoprops(glcm, 'ASM')
        glcm = None
        glcm_window = None

texturelist = {1: 'contrast', 2: 'dissimilarity', 3: 'homogeneity', 4: 'energy', 5: 'ASM'}
for key in texturelist:
    ax = plt.subplot(2,3,key)
    plt.axis('off')
    ax.set_title(texturelist[key])
    plt.imshow(eval(texturelist[key] + "raster"), cmap = 'gray')
    print(eval(texturelist[key]+"raster"))
plt.show()

```

```

-----

TypeError                                Traceback (most recent call last)

<ipython-input-78-119e100a18aa> in <module>()
    37 plt.axis('off')
    38 ax.set_title('Original Image')
--> 39 plt.imshow(sarraster, cmap = 'gray')
    40
    41

~\Anaconda3\lib\site-packages\matplotlib\pyplot.py in imshow(X, cmap, norm, aspect, in
3203             filternorm=filternorm, filterrad=filterrad,
3204             imlim=imlim, resample=resample, url=url, data=data,
-> 3205             **kwargs)
3206     finally:
3207         ax._hold = washold

~\Anaconda3\lib\site-packages\matplotlib\__init__.py in inner(ax, *args, **kwargs)
1853         "the Matplotlib list!" % (label_namer, func.__name__),
1854         RuntimeWarning, stacklevel=2)
-> 1855     return func(ax, *args, **kwargs)
1856
1857     inner.__doc__ = _add_data_doc(inner.__doc__,

~\Anaconda3\lib\site-packages\matplotlib\axes\_axes.py in imshow(self, X, cmap, norm, a
5485         resample=resample, **kwargs)
5486
-> 5487     im.set_data(X)
5488     im.set_alpha(alpha)
5489     if im.get_clip_path() is None:

~\Anaconda3\lib\site-packages\matplotlib\image.py in set_data(self, A)
651     if not (self._A.ndim == 2
652             or self._A.ndim == 3 and self._A.shape[-1] in [3, 4]):
--> 653         raise TypeError("Invalid dimensions for image data")
654
655     if self._A.ndim == 3:

TypeError: Invalid dimensions for image data

```

GLCM Textures

Original Image

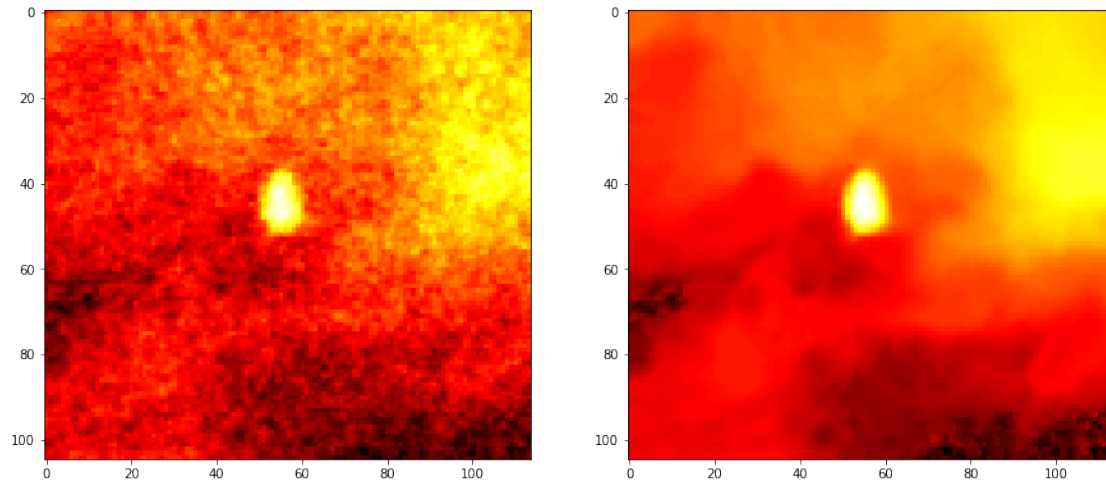
```
In [73]: from PIL import Image
         img = Image.open("IMG-0001-00001.jpg").convert('LA')
         img.save('greyscale.png')

In [89]: #plt.imshow(sarraster)
         print(sarraster)

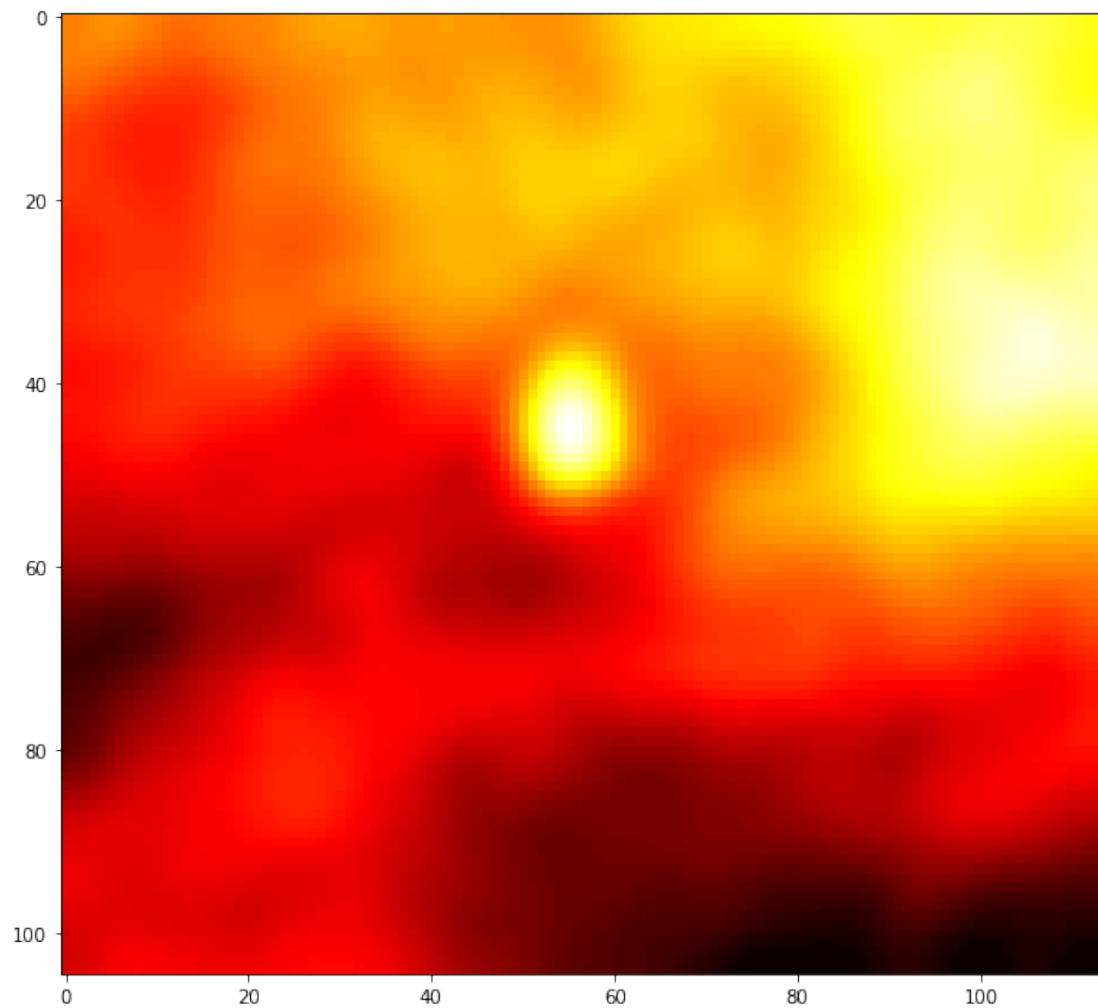
[[[255 255 255 ... 0 0 0]
  [255 255 255 ... 0 0 0]
  [255 255 255 ... 0 0 0]
  ...
  [255 255 255 ... 255 255 255]
  [255 255 255 ... 255 255 255]
  [255 255 255 ... 255 255 255]]

[[[255 255 255 ... 255 255 255]
  [255 255 255 ... 255 255 255]
  [255 255 255 ... 255 255 255]
  ...
  [255 255 255 ... 255 255 255]
  [255 255 255 ... 255 255 255]
  [255 255 255 ... 255 255 255]]]

In [98]: import cv2
         crp_img = mpimg.imread('IMG-0003-00001.jpg')
         lum_crp_img = crp_img[:, :, 0]
         crp_dst = cv2.fastNlMeansDenoisingColored(crp_img, None, 10, 10, 7, 21)
         plt.figure(figsize=(15, 15))
         plt.subplot(121), plt.imshow(lum_crp_img, cmap='hot')
         plt.subplot(122), plt.imshow(crp_dst[:, :, 0], cmap='hot')
         plt.show()
```

```
In [139]: from scipy import ndimage
          lowpass = ndimage.gaussian_filter(crp_img, 3)
          plt.figure(figsize=(10, 10))
          plt.imshow(lowpass[:, :, 0], cmap='hot')
          plt.show()
```



```
In [143]: gauss_highpass = crp_img - lowpass  
          lowpass = ndimage.gaussian_filter(gauss_highpass, 3)  
          plt.figure(figsize=(10, 10))  
          plt.imshow(gauss_highpass[:, :, 0], cmap='hot')  
          plt.show()
```

