Genetic Algorithm

In [1]: import francium.algorithms.genetic_algorithm as ga import francium.core.eval_functions as eval_functions

using an environment with $z = x^2 + y^2$

```
In [4]: agent = ga.Agent()
env = ga.Environment(x_bounds=(-5.0, 5.0), y_bounds=(-5.0, 5.0), eval_func=eval_functions.convex_x_square)
solver = ga.Solver(agent=agent, environment=env, pop_size=100)
```

In [5]: solver.init_solver()

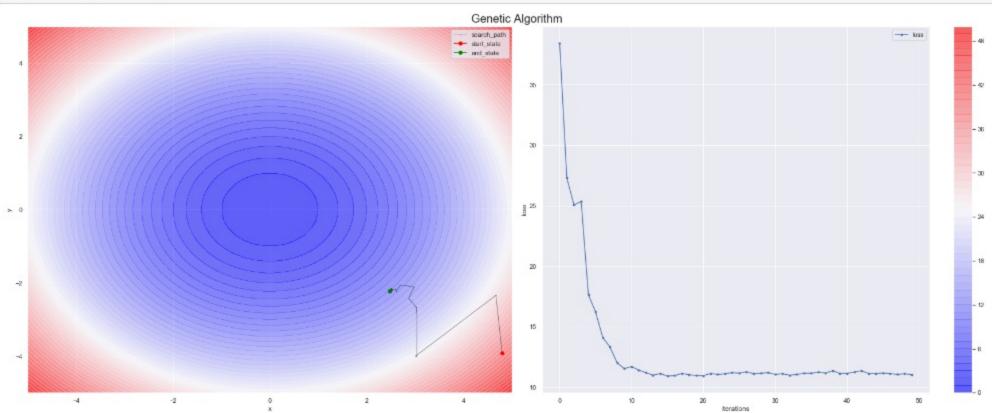
[2020-12-03 16:03:30,189 - francium.algorithms.genetic_algorithm.solver] INFO: => Initialized Agent !

In [6]: for episode in range(50): trainable = solver.train_step() if not trainable: break

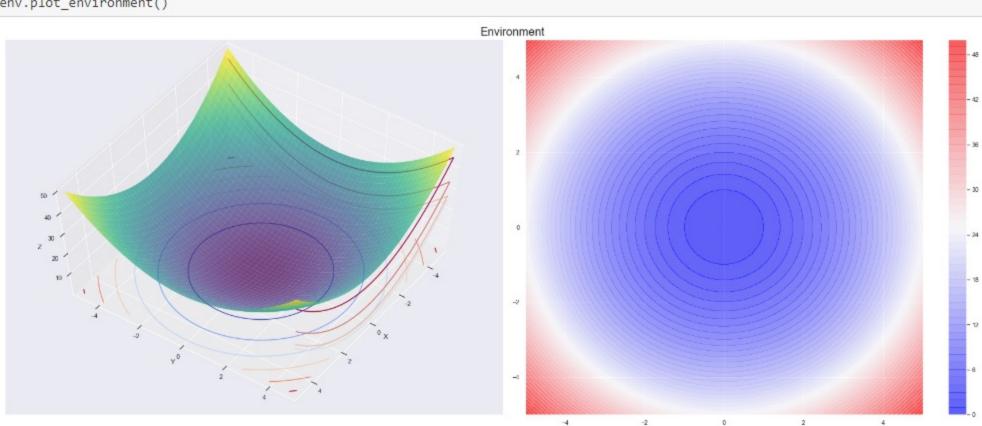
In [7]: solver.memory.best_episode

Out[7]: {'x': 2.5146588957311944, 'y': -2.1445624334917754, 'z': 10.922657393024195}

In [8]: solver.plot_history()



In [9]: env.plot_environment()



using an environment with $z = 5 * sin(x^2 + y^2) + x^2 + y^2$

```
In [11]: agent = ga.Agent()
 env = ga.Environment(x_bounds=(-5.0, 5.0), y_bounds=(-5.0, 5.0), eval_func=eval_functions.sinx_plus_x)
 solver = ga.Solver(agent=agent, environment=env, pop_size=100)
```

In [12]: solver.init_solver()

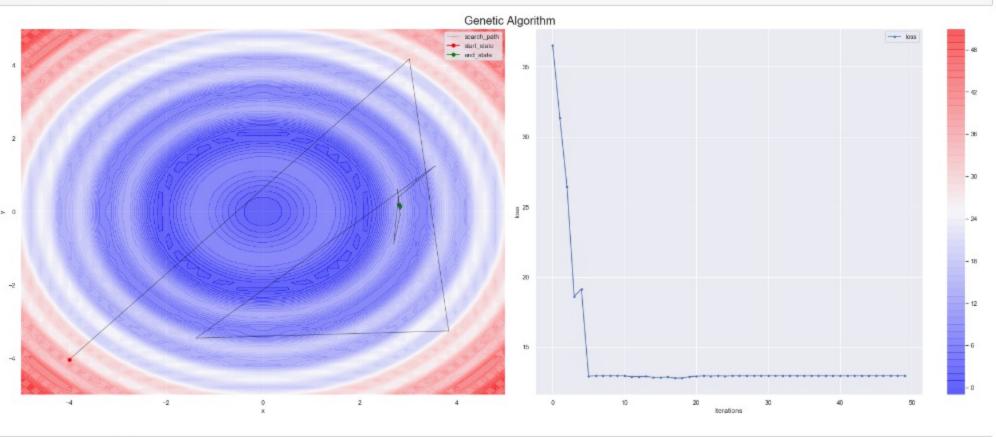
[2020-12-03 16:06:02,604 - francium.algorithms.genetic_algorithm.solver] INFO: => Initialized Agent !

In [13]: for episode in range(50): trainable = solver.train_step() if not trainable: break

In [14]: solver.memory.best_episode

Out[14]: {'x': 2.7889714146335893, 'y': 0.15665519229271258, 'z': 12.796381098863423}

In [15]: solver.plot_history()



In [16]: env.plot_environment()

C:\Users\shadowleaf\anaconda3\envs\thetensorclan-aws\lib\site-packages\numpy\core_asarray.py:136: VisibleDeprecationWarning: C reating an ndarray from ragged nested sequences (which is a list-or-tuple of lists-or-tuples-or ndarrays with different lengths or shapes) is deprecated. If you meant to do this, you must specify 'dtype=object' when creating the ndarray return array(a, dtype, copy=False, order=order, subok=True)

