Hill Climbing Algorithm

In [1]:
```
import francium.algorithms.hill_climbing as hc
import francium.core.eval_functions as eval_functions
from francium.core import State
```

using an environment with z = x^2 + y^2

In [2]:
```
agent = hc.Agent(step_size=1e-1)
env = hc.Environment(x_bounds=(-5.0, 5.0), y_bounds=(-5.0, 5.0), eval_func=eval_functions.convex_x_square)
solver = hc.Solver(agent=agent, environment=env)
```

In [3]:
```
solver.init_solver(
    init_state=State({
        'x': 4.0,
        'y': 2.0,
        'z': env.evaluation_func(4.0, 2.0)
    })
)
```

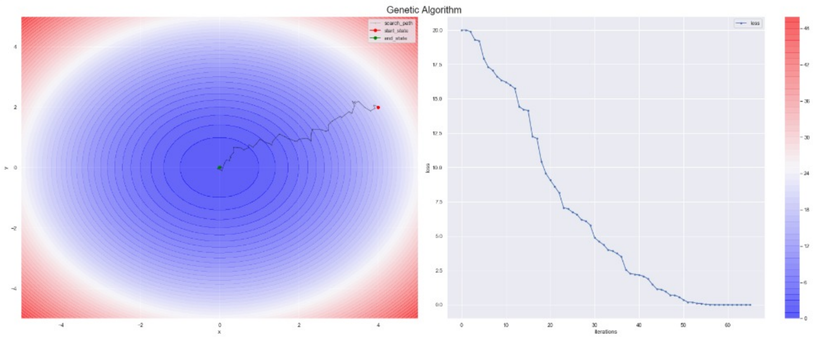
```
[ 2020-12-06 18:05:45,484 - francium.algorithms.hill_climbing.solver ] INFO: => Initialized Solver with State: {'x': 4.0, 'y': 2.0, 'z': 20.0}
```

In [4]:
```
for episode in range(1000):
    trainable = solver.train_step()
    if not trainable:
        break
```

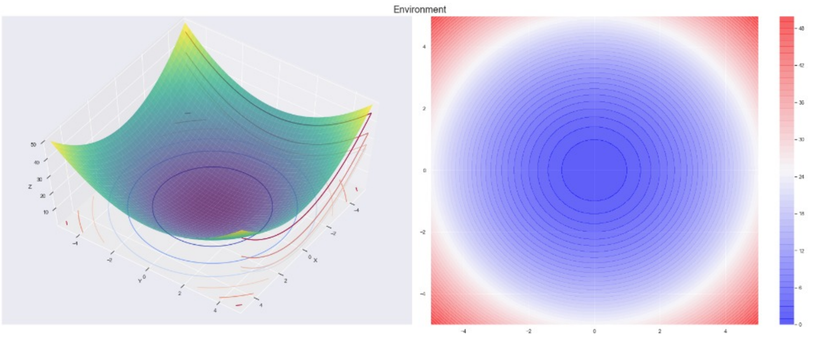
In [5]:
```
solver.memory.best_episode
```

Out[5]:
```
{'x': -0.00032572004545124 85, 'y': 0.006713925485853664, 'z': 4.518288897760412e-05}
```

In [6]:
```
solver.plot_history()
```



In [7]:
```
env.plot_environment()
```



using an environment with z = 5 * sin(x^2 + y^2) + x^2 + y^2

In [8]:
```
agent = hc.Agent(step_size=1e-1)
env = hc.Environment(x_bounds=(-5.0, 5.0), y_bounds=(-5.0, 5.0), eval_func=eval_functions.sinx_plus_x)
solver = hc.Solver(agent=agent, environment=env)
```

In [9]:
```
solver.init_solver(
    init_state=State({
        'x': 4.0,
        'y': 2.0,
        'z': env.evaluation_func(4.0, 2.0)
    })
)
```

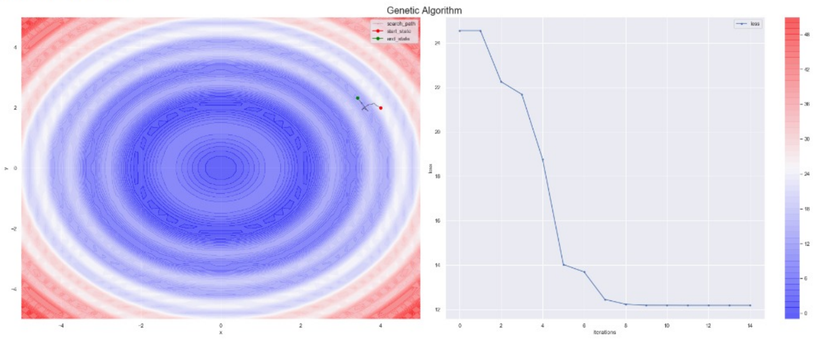
```
[ 2020-12-06 18:05:47,117 - francium.algorithms.hill_climbing.solver ] INFO: => Initialized Solver with State: {'x': 4.0, 'y': 2.0, 'z': 24.56472625363814}
```

In [10]:
```
for episode in range(1000):
    trainable = solver.train_step()
    if not trainable:
        break
```

In [11]:
```
solver.memory.best_episode
```

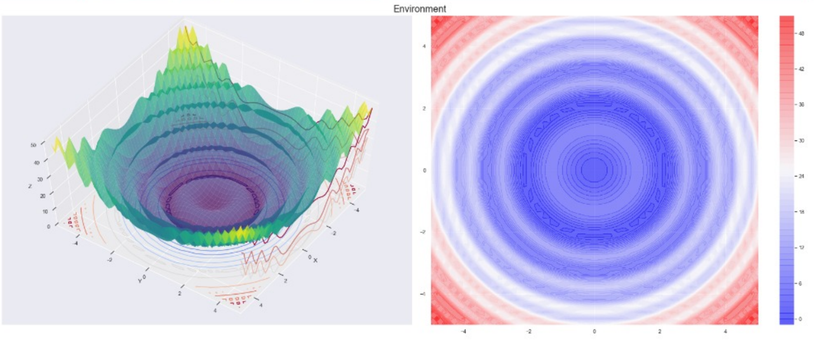
Out[11]:
```
{'x': 3.4188550057829175, 'y': 2.321218803102678, 'z': 12.178423661021002}
```

In [12]:
```
solver.plot_history()
```



In [13]:
```
env.plot_environment()
```

```
C:\Users\shadowleaf\anaconda3\envs\thetensorclan-aws\lib\site-packages\numpy\core\_asarray.py:136: VisibleDeprecationWarning: Creating an ndarray from ragged nested sequences (which is a list-or-tuple of lists-or-tuples-or ndarrays with different lengths or shapes) is deprecated. If you meant to do this, you must specify 'dtype=object' when creating the ndarray
  return array(a, dtype, copy=False, order=order, subok=True)
```



In [13]:
```
```