```
In [1]:
from keras.utils import np utils
from keras.datasets import mnist
import seaborn as sns
from keras.initializers import RandomNormal
Using TensorFlow backend.
In [0]:
%matplotlib inline
import matplotlib.pyplot as plt
import numpy as np
import time
def plt_dynamic(x, vy, ty, ax, colors=['b']):
    ax.plot(x, vy, 'b', label="Validation Loss")
    ax.plot(x, ty, 'r', label="Train Loss")
   plt.legend()
    plt.grid()
    fig.canvas.draw()
In [3]:
#splitting the data into train and test
(X train, y train), (X test, y test) = mnist.load data()
Downloading data from https://s3.amazonaws.com/img-datasets/mnist.npz
In [4]:
#train and test data shape and image shpae
print("Number of training examples :", X_{train.shape[0]}, "and each image is of shape (%d, %d)"%(X_{train.shape[0]})
train.shape[1], X_train.shape[2]))
print("Number of training examples :", X test.shape[0], "and each image is of shape (%d,
%d) "%(X test.shape[1], X test.shape[2]))
Number of training examples : 60000 and each image is of shape (28, 28)
Number of training examples: 10000 and each image is of shape (28, 28)
In [0]:
# if you observe the input shape its 2 dimensional vector
# for each image we have a (28*28) vector
# we will convert the (28*28) vector into single dimensional vector of 1 * 784
X train = X train.reshape(X train.shape[0], X train.shape[1]*X train.shape[2])
X test = X test.reshape(X test.shape[0], X test.shape[1]*X test.shape[2])
In [6]:
# after converting the input images from 3d to 2d vectors
print("Number of training examples :", X_train.shape[0], "and each image is of shape
(%d)"%(X train.shape[1]))
print("Number of training examples :", X_test.shape[0], "and each image is of shape (%d)"%(X_test.
shape[1]))
Number of training examples : 60000 and each image is of shape (784)
Number of training examples: 10000 and each image is of shape (784)
In [7]:
# An example data point
```

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print(X train[0])
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In [0]:

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# if we observe the above matrix each cell is having a value between 0-255 # before we move to apply machine learning algorithms lets try to normalize the data # X \Rightarrow (X - Xmin)/(Xmax - Xmin) = X/255

X_train = X_train/255
X_test = X_test/255
```

In [9]:

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# example data point after normlizing
print(X_train[0])
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```

In [10]:

```
# here we are having a class number for each image
print("Class label of first image :", y_train[0])

# lets convert this into a 10 dimensional vector
# ex: consider an image is 5 convert it into 5 => [0, 0, 0, 0, 0, 1, 0, 0, 0, 0]
# this conversion needed for MLPs

Y_train = np_utils.to_categorical(y_train, 10)
Y_test = np_utils.to_categorical(y_test, 10)

print("After converting the output into a vector : ",Y_train[0])
Class label of first image : 5
```

After converting the output into a vector: [0. 0. 0. 0. 0. 1. 0. 0. 0. 0.]

In [0]:

```
from keras.models import Sequential
from keras.layers import Dense, Activation
from keras.layers.normalization import BatchNormalization
from keras.layers import Dropout

# https://gist.github.com/greydanus/f6eee59eaf1d90fcb3b534a25362cea4
# https://stackoverflow.com/a/14434334
# this function is used to update the plots for each epoch and error
def plt_dynamic(x, vy, ty, ax, colors=['b']):
    ax.plot(x, vy, 'b', label="Validation Loss")
    ax.plot(x, ty, 'r', label="Train Loss")
```

```
plt.legend()
  plt.grid()
  fig.canvas.draw()

In [0]:

# some model parameters
#output size
  output_dim = 10
#input size
  input_dim = X_train.shape[1]
#batch input size
batch_size = 128
#No of epochs
nb epoch = 20
```

```
In [13]:
```

```
print('Columsn :',X_train.shape[1],'Rows :',X_train.shape[0])
```

Columsn : 784 Rows : 60000

Applied various types of architecture with different drop rates with different optimizers and different normalization and drop out at different layers

2 Layer architecture With Batch Normalization and Dropout

```
In [14]:
```

```
model relu = Sequential()
#layer-1
model_relu.add(Dense(500, activation='relu', input_shape=(input_dim,), kernel_initializer=RandomNor
mal(mean=0.0, stddev=0.039, seed=None)))
#adding batch normalization
model relu.add(BatchNormalization())
#addding dropout rate
model relu.add(Dropout(0.5))
#layer-2
model relu.add(Dense(200, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.039
, seed=None)))
#adding batch noramalization
model relu.add(BatchNormalization())
#adding drop out rate
model relu.add(Dropout(0.5))
model relu.add(Dense(output dim, activation='softmax'))
#print(model relu.summary())
#using optimizer adam
model relu.compile(optimizer='adam', loss='categorical crossentropy', metrics=['accuracy'])
history = model relu.fit(X train, Y train, batch size=batch size, epochs=nb epoch, verbose=1, valid
ation data=(X_test, Y_test))
WARNING: Logging before flag parsing goes to stderr.
W0829 13:26:52.092908 140021963048832 deprecation_wrapper.py:119] From
/usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow backend.py:74: The name
tf.get default graph is deprecated. Please use tf.compat.v1.get default graph instead.
W0829 13:26:52.129713 140021963048832 deprecation wrapper.py:119] From
/usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow backend.py:517: The name
tf.placeholder is deprecated. Please use tf.compat.v1.placeholder instead.
W0829 13:26:52.140062 140021963048832 deprecation wrapper.py:119] From
/usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow backend.py:4115: The name
tf.random_normal is deprecated. Please use tf.random.normal instead.
W0829 13:26:52.245176 140021963048832 deprecation wrapper.py:119] From
/usr/local/lih/nython3 6/dist-nackages/keras/hackend/tensorflow hackend ny.133. The name
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tf.placeholder_with_default is deprecated. Please use tf.compat.v1.placeholder_with_default instea
d.
W0829 13:26:52.271583 140021963048832 deprecation.py:506] From /usr/local/lib/python3.6/dist-
packages/keras/backend/tensorflow_backend.py:3445: calling dropout (from
tensorflow.python.ops.nn_ops) with keep_prob is deprecated and will be removed in a future
version.
Instructions for updating:
Please use `rate` instead of `keep prob`. Rate should be set to `rate = 1 - keep prob`.
W0829 13:26:52.411946 140021963048832 deprecation wrapper.py:119] From
/usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow backend.py:4138: The name
tf.random uniform is deprecated. Please use tf.random.uniform instead.
W0829 13:26:52.428584 140021963048832 deprecation wrapper.py:119] From
/usr/local/lib/python3.6/dist-packages/keras/optimizers.py:790: The name tf.train.Optimizer is dep
recated. Please use tf.compat.vl.train.Optimizer instead.
\verb|W0829 13:26:52.576616 140021963048832 deprecation.py:323| From / usr/local/lib/python3.6/dist-property for the statement of the statement 
packages/tensorflow/python/ops/math grad.py:1250: add dispatch support.<locals>.wrapper (from
tensorflow.python.ops.array_ops) is deprecated and will be removed in a future version.
Instructions for updating:
Use tf.where in 2.0, which has the same broadcast rule as np.where
Train on 60000 samples, validate on 10000 samples
60000/60000 [============= ] - 10s 161us/step - loss: 0.3707 - acc: 0.8881 - val 1
oss: 0.1326 - val acc: 0.9559
Epoch 2/20
60000/60000 [=========== ] - 5s 83us/step - loss: 0.1860 - acc: 0.9433 -
val loss: 0.0953 - val acc: 0.9687
Epoch 3/20
```

```
val loss: 0.0845 - val acc: 0.9733
Epoch 4/20
60000/60000 [============= - 5s 88us/step - loss: 0.1225 - acc: 0.9614 -
val loss: 0.0813 - val acc: 0.9743
Epoch 5/20
60000/60000 [===========] - 5s 86us/step - loss: 0.1119 - acc: 0.9662 -
val loss: 0.0758 - val acc: 0.9763
Epoch 6/20
60000/60000 [============= ] - 5s 84us/step - loss: 0.1022 - acc: 0.9678 -
val_loss: 0.0715 - val_acc: 0.9784
Epoch 7/20
60000/60000 [============= ] - 5s 83us/step - loss: 0.0985 - acc: 0.9691 -
val_loss: 0.0688 - val_acc: 0.9788
Epoch 8/20
60000/60000 [============] - 5s 82us/step - loss: 0.0864 - acc: 0.9733 -
val loss: 0.0681 - val acc: 0.9793
Epoch 9/20
60000/60000 [============] - 5s 83us/step - loss: 0.0794 - acc: 0.9751 -
val loss: 0.0626 - val acc: 0.9798
Epoch 10/20
60000/60000 [============] - 5s 83us/step - loss: 0.0744 - acc: 0.9760 -
val loss: 0.0655 - val acc: 0.9796
Epoch 11/20
60000/60000 [===========] - 5s 86us/step - loss: 0.0748 - acc: 0.9761 -
val loss: 0.0568 - val acc: 0.9829
Epoch 12/20
60000/60000 [============] - 5s 85us/step - loss: 0.0740 - acc: 0.9764 -
val loss: 0.0597 - val acc: 0.9822
Epoch 13/20
60000/60000 [===========] - 5s 84us/step - loss: 0.0662 - acc: 0.9786 -
val loss: 0.0552 - val acc: 0.9833
Epoch 14/20
60000/60000 [============] - 5s 84us/step - loss: 0.0647 - acc: 0.9799 -
val loss: 0.0595 - val acc: 0.9819
Epoch 15/20
60000/60000 [=============] - 5s 82us/step - loss: 0.0627 - acc: 0.9805 -
val loss: 0.0600 - val acc: 0.9824
Epoch 16/20
60000/60000 [===========] - 5s 84us/step - loss: 0.0592 - acc: 0.9810 -
val loss: 0.0556 - val acc: 0.9835
Epoch 17/20
60000/60000 [============] - 5s 85us/step - loss: 0.0568 - acc: 0.9817 -
val loss: 0.0533 - val acc: 0.9846
Epoch 18/20
```

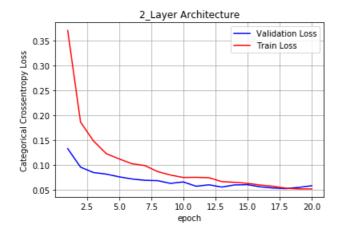
```
val loss: 0.0521 - val acc: 0.9839
Epoch 19/20
60000/60000 [============] - 5s 84us/step - loss: 0.0515 - acc: 0.9829 -
val loss: 0.0545 - val acc: 0.9835
Epoch 20/20
60000/60000 [============] - 5s 83us/step - loss: 0.0514 - acc: 0.9833 -
val loss: 0.0579 - val_acc: 0.9837
```

In [15]:

```
score 1 = model_relu.evaluate(X_test, Y_test, verbose=0)
print('Test score:', score 1[0])
print('Test accuracy:', score_1[1])
fig,ax = plt.subplots(1,1)
ax.set xlabel('epoch')
ax.set ylabel('Categorical Crossentropy Loss')
# list of epoch numbers
x = list(range(1, nb epoch+1))
vy = history.history['val_loss']
ty = history.history['loss']
plt_dynamic(x, vy, ty, ax)
plt.title('2_Layer Architecture')
plt.show()
```

Test score: 0.057854038857636625

Test accuracy: 0.9837

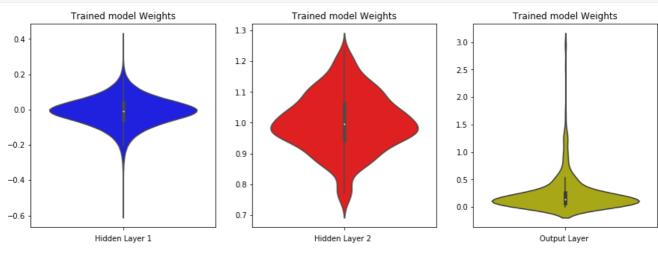


if we observe that above plot after 20 epochs our test loss may grater than our train loss

In [16]:

```
w after = model relu.get weights()
h1 w = w after[0].flatten().reshape(-1,1)
h2 w = w after[2].flatten().reshape(-1,1)
out w = w after[4].flatten().reshape(-1,1)
fig = plt.figure(figsize=(15,5))
plt.title("Weight matrices after model trained")
plt.subplot(1, 3, 1)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h1_w,color='b')
plt.xlabel('Hidden Layer 1')
plt.subplot(1, 3, 2)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h2_w, color='r')
plt.xlabel('Hidden Layer 2 ')
plt.subplot(1, 3, 3)
```

```
plt.title("Trained model Weights")
ax = sns.violinplot(y=out_w,color='y')
plt.xlabel('Output Layer ')
plt.show()
```



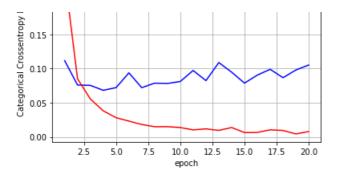
2 Layer architecture With-out Batch Normalization and Dropout

```
In [17]:
model relu = Sequential()
model_relu.add(Dense(500, activation='relu', input_shape=(input_dim,), kernel_initializer=RandomNor
mal(mean=0.0, stddev=0.039, seed=None)))
#adding batch normalization
#model relu.add(BatchNormalization())
#addding dropout rate
#model relu.add(Dropout(0.5))
#laver-2
model relu.add(Dense(200, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.039
, seed=None)))
#adding batch noramalization
#model relu.add(BatchNormalization())
#adding drop out rate
#model relu.add(Dropout(0.5))
model relu.add(Dense(output dim, activation='softmax'))
#print(model relu.summary())
#using optimizer adam
model relu.compile(optimizer='adam', loss='categorical crossentropy', metrics=['accuracy'])
history = model relu.fit(X train, Y train, batch size=batch size, epochs=nb epoch, verbose=1, valid
ation_data=(X_test, Y_test))
```

```
60000/60000 [============] - 3s 51us/step - loss: 0.0280 - acc: 0.9909 -
val_loss: 0.0721 - val_acc: 0.9782
Epoch 6/20
val_loss: 0.0938 - val_acc: 0.9736
Epoch 7/20
val loss: 0.0721 - val acc: 0.9804
Epoch 8/20
60000/60000 [===========] - 3s 51us/step - loss: 0.0148 - acc: 0.9950 -
val loss: 0.0787 - val acc: 0.9798
Epoch 9/20
60000/60000 [============] - 3s 49us/step - loss: 0.0149 - acc: 0.9950 -
val loss: 0.0782 - val acc: 0.9790
Epoch 10/20
val loss: 0.0811 - val acc: 0.9803
Epoch 11/20
60000/60000 [============] - 3s 49us/step - loss: 0.0102 - acc: 0.9968 -
val loss: 0.0973 - val acc: 0.9763
Epoch 12/20
60000/60000 [=============] - 3s 49us/step - loss: 0.0116 - acc: 0.9962 -
val loss: 0.0824 - val acc: 0.9792
Epoch 13/20
val loss: 0.1089 - val acc: 0.9755
Epoch 14/20
60000/60000 [=============] - 3s 49us/step - loss: 0.0136 - acc: 0.9956 -
val loss: 0.0948 - val acc: 0.9756
Epoch 15/20
60000/60000 [===========] - 3s 52us/step - loss: 0.0062 - acc: 0.9980 -
val loss: 0.0787 - val acc: 0.9816
Epoch 16/20
60000/60000 [=============] - 3s 50us/step - loss: 0.0065 - acc: 0.9979 -
val loss: 0.0905 - val acc: 0.9798
Epoch 17/20
val_loss: 0.0990 - val_acc: 0.9795
Epoch 18/20
val loss: 0.0867 - val acc: 0.9800
Epoch 19/20
60000/60000 [============] - 3s 50us/step - loss: 0.0042 - acc: 0.9987 -
val loss: 0.0980 - val_acc: 0.9801
Epoch 20/20
val loss: 0.1053 - val acc: 0.9792
In [18]:
score 1 = model relu.evaluate(X test, Y test, verbose=0)
print('Test score:', score 1[0])
print('Test accuracy:', score_1[1])
fig,ax = plt.subplots(1,1)
ax.set_xlabel('epoch')
ax.set ylabel('Categorical Crossentropy Loss')
# list of epoch numbers
x = list(range(1, nb epoch+1))
vy = history.history['val loss']
ty = history.history['loss']
plt_dynamic(x, vy, ty, ax)
plt.title('2 Layer Architecture')
plt.show()
```

Test score: 0.10529097638992689 Test accuracy: 0.9792

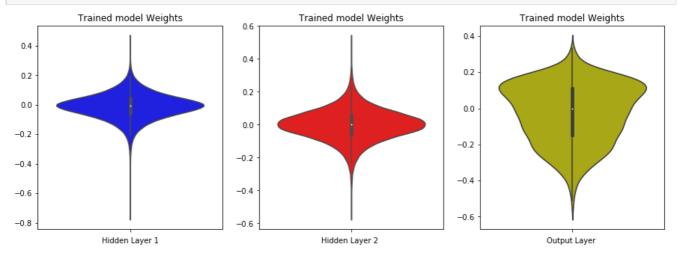




Here we see that in above plot with out apply of batch-normalization and drop out we got test loss > train loss

```
In [19]:
```

```
w after = model relu.get weights()
h1 w = w after[0].flatten().reshape(-1,1)
h2 w = w after[2].flatten().reshape(-1,1)
out_w = w_after[4].flatten().reshape(-1,1)
fig = plt.figure(figsize=(15,5))
plt.title("Weight matrices after model trained")
plt.subplot(1, 3, 1)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h1 w,color='b')
plt.xlabel('Hidden Layer 1')
plt.subplot(1, 3, 2)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h2_w, color='r')
plt.xlabel('Hidden Layer 2 ')
plt.subplot(1, 3, 3)
plt.title("Trained model Weights")
ax = sns.violinplot(y=out_w,color='y')
plt.xlabel('Output Layer ')
plt.show()
```



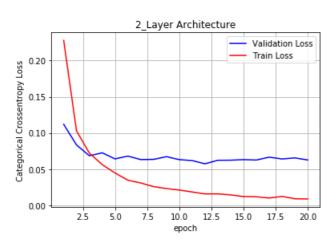
2 layer architecture We also experiment with Different optimizer like Adadelta with different drop-out rate 0.2

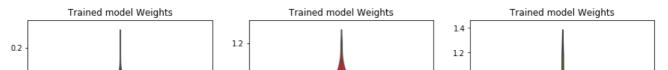
```
In [20]:
```

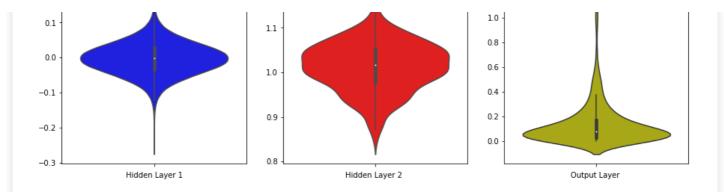
```
model_relu = Sequential()
#layer-1
model_relu.add(Dense(500, activation='relu', input_shape=(input_dim,), kernel_initializer=RandomNor
mal(mean=0.0, stddev=0.039, seed=None)))
#adding batch normalization
```

```
model relu.add(BatchNormalization())
#addding dropout rate
model relu.add(Dropout(0.2))
#layer-2
model relu.add(Dense(200, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.039
, seed=None)))
#adding batch noramalization
model relu.add(BatchNormalization())
#adding drop out rate
model relu.add(Dropout(0.2))
model relu.add(Dense(output dim, activation='softmax'))
#print(model relu.summary())
#using optimizer Adadelta
model relu.compile(optimizer='Adadelta', loss='categorical crossentropy', metrics=['accuracy'])
history = model relu.fit(X train, Y train, batch size=batch size, epochs=nb epoch, verbose=1, valid
ation data=(X test, Y test))
#-----train and test error plots -----
score_1 = model_relu.evaluate(X_test, Y_test, verbose=0)
print('Test score:', score_1[0])
print('Test accuracy:', score 1[1])
fig,ax = plt.subplots(1,1)
ax.set xlabel('epoch')
ax.set ylabel('Categorical Crossentropy Loss')
# list of epoch numbers
x = list(range(1, nb epoch+1))
vy = history.history['val loss']
ty = history.history['loss']
plt_dynamic(x, vy, ty, ax)
plt.title('2_Layer Architecture')
plt.show()
           -----layer wise plots ------
w after = model relu.get weights()
h1 w = w after[0].flatten().reshape(-1,1)
h2 w = w after[2].flatten().reshape(-1,1)
out w = w after[4].flatten().reshape(-1,1)
fig = plt.figure(figsize=(15,5))
plt.title("Weight matrices after model trained")
plt.subplot(1, 3, 1)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h1 w,color='b')
plt.xlabel('Hidden Layer 1')
plt.subplot(1, 3, 2)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h2_w, color='r')
plt.xlabel('Hidden Layer 2 ')
plt.subplot(1, 3, 3)
plt.title("Trained model Weights")
ax = sns.violinplot(y=out w,color='y')
plt.xlabel('Output Layer ')
plt.show()
4
Train on 60000 samples, validate on 10000 samples
Epoch 1/20
60000/60000 [============= ] - 6s 100us/step - loss: 0.2279 - acc: 0.9306 -
val loss: 0.1119 - val acc: 0.9662
Epoch 2/20
60000/60000 [=============] - 5s 89us/step - loss: 0.1027 - acc: 0.9680 -
val loss: 0.0833 - val acc: 0.9751
Epoch 3/20
60000/60000 [============] - 5s 88us/step - loss: 0.0721 - acc: 0.9778 -
val loss: 0.0684 - val acc: 0.9789
Enoch 4/20
```

```
בוטטעם דובט
60000/60000 [============] - 5s 87us/step - loss: 0.0562 - acc: 0.9823 -
val loss: 0.0725 - val acc: 0.9772
Epoch 5/20
val loss: 0.0641 - val acc: 0.9812
Epoch 6/20
60000/60000 [============] - 5s 87us/step - loss: 0.0347 - acc: 0.9889 -
val loss: 0.0680 - val acc: 0.9810
Epoch 7/20
60000/60000 [============= ] - 5s 89us/step - loss: 0.0308 - acc: 0.9898 -
val_loss: 0.0631 - val_acc: 0.9812
Epoch 8/20
val loss: 0.0634 - val acc: 0.9822
Epoch 9/20
60000/60000 [============] - 5s 88us/step - loss: 0.0231 - acc: 0.9921 -
val loss: 0.0672 - val acc: 0.9817
Epoch 10/20
60000/60000 [=========== ] - 5s 88us/step - loss: 0.0210 - acc: 0.9932 -
val loss: 0.0631 - val acc: 0.9840
Epoch 11/20
60000/60000 [============] - 5s 89us/step - loss: 0.0184 - acc: 0.9939 -
val loss: 0.0618 - val acc: 0.9833
Epoch 12/20
val loss: 0.0573 - val acc: 0.9846
Epoch 13/20
val loss: 0.0622 - val acc: 0.9836
Epoch 14/20
60000/60000 [=============] - 5s 87us/step - loss: 0.0144 - acc: 0.9953 -
val_loss: 0.0623 - val_acc: 0.9850
Epoch 15/20
60000/60000 [============] - 5s 88us/step - loss: 0.0120 - acc: 0.9961 -
val loss: 0.0630 - val acc: 0.9833
Epoch 16/20
val loss: 0.0625 - val acc: 0.9852
Epoch 17/20
60000/60000 [============] - 5s 87us/step - loss: 0.0100 - acc: 0.9966 -
val loss: 0.0665 - val acc: 0.9843
Epoch 18/20
60000/60000 [============= ] - 5s 89us/step - loss: 0.0123 - acc: 0.9960 -
val loss: 0.0640 - val acc: 0.9849
Epoch 19/20
60000/60000 [============] - 5s 88us/step - loss: 0.0089 - acc: 0.9972 -
val_loss: 0.0655 - val_acc: 0.9861
Epoch 20/20
60000/60000 [============] - 5s 89us/step - loss: 0.0088 - acc: 0.9972 -
val loss: 0.0626 - val acc: 0.9858
Test score: 0.06257566632076009
Test accuracy: 0.9858
```







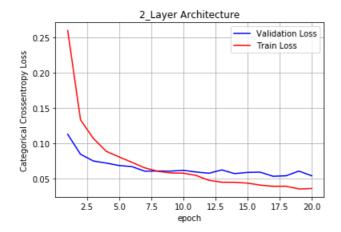
2 layer architecture We also experiment with by Adding only one batch normalization and one drop-out after first layer with adam with drop 5.0

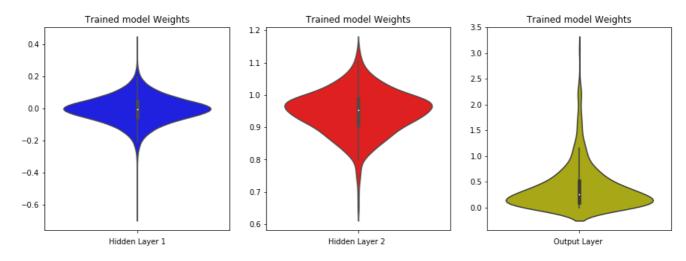
```
In [21]:
```

```
model relu = Sequential()
#layer-1
model relu.add(Dense(500, activation='relu', input shape=(input dim,), kernel initializer=RandomNor
mal(mean=0.0, stddev=0.039, seed=None)))
#adding batch normalization
model_relu.add(BatchNormalization())
#addding dropout rate
model relu.add(Dropout(0.5))
#layer-2
model relu.add(Dense(200, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.039
, seed=None)))
#adding batch noramalization
#model relu.add(BatchNormalization())
#adding drop out rate
#model relu.add(Dropout(0.2))
model relu.add(Dense(output dim, activation='softmax'))
#print(model_relu.summary())
#using optimizer Adadelta
model relu.compile(optimizer='Adam', loss='categorical crossentropy', metrics=['accuracy'])
history = model relu.fit(X train, Y train, batch size=batch size, epochs=nb epoch, verbose=1, valid
ation data=(X test, Y test))
#-----train and test error plots ------
score 1 = model relu.evaluate(X test, Y test, verbose=0)
print('Test score:', score 1[0])
print('Test accuracy:', score 1[1])
fig,ax = plt.subplots(1,1)
ax.set_xlabel('epoch')
ax.set ylabel('Categorical Crossentropy Loss')
# list of epoch numbers
x = list(range(1, nb epoch+1))
vy = history.history['val loss']
ty = history.history['loss']
plt_dynamic(x, vy, ty, ax)
plt.title('2 Layer Architecture')
plt.show()
                                                 -----laver wise plots -----
w_after = model_relu.get_weights()
h1_w = w_after[0].flatten().reshape(-1,1)
h2_w = w_after[2].flatten().reshape(-1,1)
out_w = w_after[4].flatten().reshape(-1,1)
```

```
fig = plt.figure(figsize=(15,5))
plt.title("Weight matrices after model trained")
plt.subplot(1, 3, 1)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h1 w,color='b')
plt.xlabel('Hidden Layer 1')
plt.subplot(1, 3, 2)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h2 w, color='r')
plt.xlabel('Hidden Layer 2 ')
plt.subplot(1, 3, 3)
plt.title("Trained model Weights")
ax = sns.violinplot(y=out w,color='y')
plt.xlabel('Output Layer ')
plt.show()
4
Train on 60000 samples, validate on 10000 samples
Epoch 1/20
60000/60000 [============] - 5s 81us/step - loss: 0.2600 - acc: 0.9211 -
val_loss: 0.1131 - val_acc: 0.9642
Epoch 2/20
60000/60000 [============ ] - 4s 69us/step - loss: 0.1335 - acc: 0.9582 -
val_loss: 0.0849 - val_acc: 0.9737
Epoch 3/20
60000/60000 [============] - 4s 67us/step - loss: 0.1072 - acc: 0.9666 -
val loss: 0.0754 - val acc: 0.9752
Epoch 4/20
60000/60000 [============] - 4s 70us/step - loss: 0.0891 - acc: 0.9716 -
val loss: 0.0724 - val acc: 0.9783
Epoch 5/20
val loss: 0.0690 - val acc: 0.9789
Epoch 6/20
val_loss: 0.0674 - val_acc: 0.9805
Epoch 7/20
60000/60000 [============] - 4s 67us/step - loss: 0.0656 - acc: 0.9784 -
val loss: 0.0610 - val_acc: 0.9827
Epoch 8/20
val_loss: 0.0612 - val acc: 0.9807
Epoch 9/20
60000/60000 [===========] - 4s 68us/step - loss: 0.0585 - acc: 0.9800 -
val loss: 0.0610 - val_acc: 0.9816
Epoch 10/20
val loss: 0.0622 - val acc: 0.9816
Epoch 11/20
60000/60000 [============= ] - 4s 71us/step - loss: 0.0549 - acc: 0.9818 -
val_loss: 0.0598 - val_acc: 0.9830
Epoch 12/20
60000/60000 [============] - 4s 68us/step - loss: 0.0481 - acc: 0.9842 -
val_loss: 0.0581 - val_acc: 0.9833
Epoch 13/20
val loss: 0.0628 - val acc: 0.9834
Epoch 14/20
60000/60000 [============] - 4s 67us/step - loss: 0.0452 - acc: 0.9851 -
val loss: 0.0575 - val acc: 0.9838
Epoch 15/20
60000/60000 [============] - 4s 68us/step - loss: 0.0441 - acc: 0.9853 -
val loss: 0.0593 - val acc: 0.9842
Epoch 16/20
val loss: 0.0595 - val acc: 0.9836
Epoch 17/20
60000/60000 [============] - 4s 68us/step - loss: 0.0396 - acc: 0.9870 -
val_loss: 0.0537 - val_acc: 0.9842
Epoch 18/20
60000/60000 [============= ] - 4s 67us/step - loss: 0.0397 - acc: 0.9873 -
val loss: 0.0545 - val_acc: 0.9852
Epoch 19/20
60000/60000 [===========] - 4s 67us/step - loss: 0.0359 - acc: 0.9881 -
val loss: 0.0611 - val acc: 0.9837
```

```
Epoch 20/20
60000/60000 [============] - 4s 67us/step - loss: 0.0364 - acc: 0.9881 - val_loss: 0.0545 - val_acc: 0.9852
Test score: 0.054469384077978064
Test accuracy: 0.9852
```





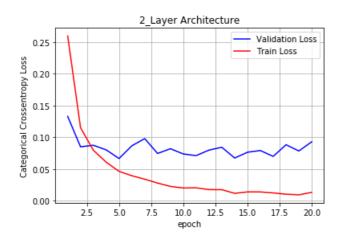
2 layer architecture We also experiment with by Adding only one batch normalization and onedrop-out before last layer with Adam with drop 0.5

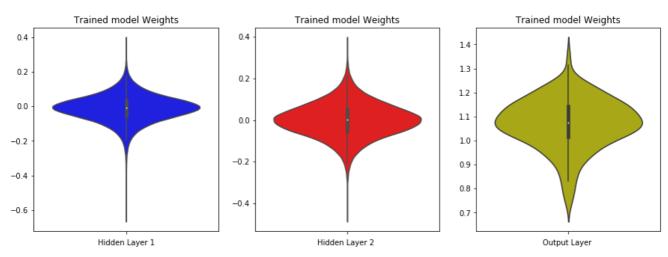
```
In [22]:
```

```
model_relu = Sequential()
#layer-1
model relu.add(Dense(500, activation='relu', input shape=(input dim,), kernel initializer=RandomNor
mal(mean=0.0, stddev=0.039, seed=None)))
#adding batch normalization
#model relu.add(BatchNormalization())
#addding dropout rate
#model relu.add(Dropout(0.2))
#layer-2
model relu.add(Dense(200, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.039
, seed=None)))
#adding batch noramalization
model relu.add(BatchNormalization())
#adding drop out rate
model relu.add(Dropout(0.5))
model relu.add(Dense(output dim, activation='softmax'))
#print(model relu.summary())
#using optimizer Adadelta
model relu.compile(optimizer='Adam', loss='categorical crossentropy', metrics=['accuracy'])
```

```
history = model relu.fit(X train, Y train, batch size=batch size, epochs=nb epoch, verbose=1, valid
ation_data=(X_test, Y_test))
                -----train and test error plots -----
score 1 = model relu.evaluate(X test, Y test, verbose=0)
print('Test score:', score_1[0])
print('Test accuracy:', score_1[1])
fig,ax = plt.subplots(1,1)
ax.set xlabel('epoch')
ax.set ylabel('Categorical Crossentropy Loss')
# list of epoch numbers
x = list(range(1, nb epoch+1))
vy = history.history['val loss']
ty = history.history['loss']
plt dynamic(x, vy, ty, ax)
plt.title('2 Layer Architecture')
plt.show()
                           -----layer wise plots ------
w_after = model_relu.get_weights()
h1_w = w_after[0].flatten().reshape(-1,1)
h2 w = w after[2].flatten().reshape(-1,1)
out_w = w_after[4].flatten().reshape(-1,1)
fig = plt.figure(figsize=(15,5))
plt.title("Weight matrices after model trained")
plt.subplot(1, 3, 1)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h1 w,color='b')
plt.xlabel('Hidden Layer 1')
plt.subplot(1, 3, 2)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h2_w, color='r')
plt.xlabel('Hidden Layer 2 ')
plt.subplot(1, 3, 3)
plt.title("Trained model Weights")
ax = sns.violinplot(y=out_w,color='y')
plt.xlabel('Output Layer ')
plt.show()
4
Train on 60000 samples, validate on 10000 samples
Epoch 1/20
60000/60000 [============] - 5s 79us/step - loss: 0.2597 - acc: 0.9221 -
val loss: 0.1330 - val acc: 0.9586
Epoch 2/20
60000/60000 [=========== ] - 4s 66us/step - loss: 0.1153 - acc: 0.9657 -
val loss: 0.0851 - val acc: 0.9737
Epoch 3/20
60000/60000 [============= ] - 4s 65us/step - loss: 0.0797 - acc: 0.9758 -
val loss: 0.0875 - val acc: 0.9724
Epoch 4/20
60000/60000 [============= ] - 4s 66us/step - loss: 0.0609 - acc: 0.9811 -
val loss: 0.0803 - val acc: 0.9730
Epoch 5/20
60000/60000 [============= ] - 4s 65us/step - loss: 0.0465 - acc: 0.9859 -
val_loss: 0.0667 - val_acc: 0.9782
Epoch 6/20
60000/60000 [============ ] - 4s 66us/step - loss: 0.0396 - acc: 0.9871 -
val loss: 0.0868 - val acc: 0.9744
Epoch 7/20
60000/60000 [============] - 4s 65us/step - loss: 0.0342 - acc: 0.9888 -
val loss: 0.0980 - val acc: 0.9724
Epoch 8/20
60000/60000 [============ ] - 4s 65us/step - loss: 0.0280 - acc: 0.9911 -
val loss: 0.0747 - val acc: 0.9800
Epoch 9/20
60000/60000 [============] - 4s 67us/step - loss: 0.0228 - acc: 0.9925 -
val loss: 0.0821 - val_acc: 0.9772
```

```
FDOCH IU/ZU
60000/60000 [============] - 4s 68us/step - loss: 0.0203 - acc: 0.9935 -
val_loss: 0.0739 - val_acc: 0.9795
Epoch 11/20
60000/60000 [============] - 4s 68us/step - loss: 0.0206 - acc: 0.9931 -
val_loss: 0.0712 - val_acc: 0.9805
Epoch 12/20
60000/60000 [============= ] - 4s 69us/step - loss: 0.0178 - acc: 0.9943 -
val loss: 0.0799 - val_acc: 0.9788
Epoch 13/20
val loss: 0.0844 - val acc: 0.9792
Epoch 14/20
60000/60000 [============ ] - 4s 67us/step - loss: 0.0118 - acc: 0.9959 -
val loss: 0.0674 - val acc: 0.9819
Epoch 15/20
60000/60000 [============] - 4s 65us/step - loss: 0.0141 - acc: 0.9955 -
val loss: 0.0766 - val acc: 0.9823
Epoch 16/20
60000/60000 [============] - 4s 66us/step - loss: 0.0141 - acc: 0.9952 -
val loss: 0.0793 - val acc: 0.9809
Epoch 17/20
60000/60000 [============ ] - 4s 66us/step - loss: 0.0125 - acc: 0.9958 -
val loss: 0.0700 - val acc: 0.9840
Epoch 18/20
60000/60000 [============= - 4s 66us/step - loss: 0.0105 - acc: 0.9963 -
val loss: 0.0884 - val acc: 0.9813
Epoch 19/20
val loss: 0.0785 - val acc: 0.9826
Epoch 20/20
60000/60000 [============= ] - 4s 66us/step - loss: 0.0134 - acc: 0.9956 -
val loss: 0.0930 - val acc: 0.9800
Test score: 0.09304900475722334
Test accuracy: 0.98
```





3-layer Architecture with Batch-Normalization and Dropout

In [23]:

```
model relu2 = Sequential()
#laver-1
model relu2.add(Dense(500, activation='relu', input shape=(input dim,), kernel initializer=RandomNo
rmal(mean=0.0, stddev=0.039, seed=None)))
#adding batch normalization
model_relu2.add(BatchNormalization())
#addding dropout rate
model relu2.add(Dropout(0.5))
#layer-2
model relu2.add(Dense(300, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.03
9, seed=None)))
#adding batch noramalization
model relu2.add(BatchNormalization())
#adding drop out rate
model relu2.add(Dropout(0.5))
#laver-3
model_relu2.add(Dense(200, activation='relu', kernel_initializer=RandomNormal(mean=0.0, stddev=0.03
9, seed=None)))
#adding batch noramalization
model relu2.add(BatchNormalization())
#adding drop out rate
model relu2.add(Dropout(0.5))
model relu2.add(Dense(output dim, activation='softmax'))
#print(model relu2.summary())
#using optimizer adam
model relu2.compile(optimizer='adam', loss='categorical crossentropy', metrics=['accuracy'])
history = model_relu2.fit(X_train, Y_train, batch_size=batch_size, epochs=nb_epoch, verbose=1, vali
dation data=(X test, Y test))
Train on 60000 samples, validate on 10000 samples
Epoch 1/20
60000/60000 [============= ] - 8s 133us/step - loss: 0.4738 - acc: 0.8567 -
val_loss: 0.1498 - val_acc: 0.9544
Epoch 2/20
60000/60000 [============== ] - 7s 111us/step - loss: 0.2196 - acc: 0.9350 -
val_loss: 0.1086 - val acc: 0.9653
Epoch 3/20
60000/60000 [============= ] - 7s 110us/step - loss: 0.1737 - acc: 0.9482 -
val loss: 0.0947 - val acc: 0.9693
val loss: 0.0790 - val acc: 0.9749
Epoch 5/20
60000/60000 [============ ] - 7s 111us/step - loss: 0.1309 - acc: 0.9608 -
val loss: 0.0792 - val acc: 0.9744
Epoch 6/20
60000/60000 [============= ] - 7s 111us/step - loss: 0.1215 - acc: 0.9637 -
val loss: 0.0767 - val acc: 0.9777
Epoch 7/20
val loss: 0.0684 - val acc: 0.9791
Epoch 8/20
val loss: 0.0722 - val acc: 0.9783
Epoch 9/20
60000/60000 [============] - 7s 110us/step - loss: 0.0962 - acc: 0.9699 -
val loss: 0.0766 - val acc: 0.9764
Epoch 10/20
60000/60000 [===========] - 7s 111us/step - loss: 0.0939 - acc: 0.9711 -
val loss: 0.0678 - val acc: 0.9792
Epoch 11/20
60000/60000 [============= ] - 7s 110us/step - loss: 0.0906 - acc: 0.9722 -
val_loss: 0.0668 - val_acc: 0.9801
Epoch 12/20
60000/60000 [==============] - 7s 110us/step - loss: 0.0828 - acc: 0.9747 -
val loss: 0.0606 - val acc: 0.9809
Epoch 13/20
```

```
60000/60000 [============= ] - 7s 111us/step - loss: 0.0775 - acc: 0.9758 -
val_loss: 0.0624 - val_acc: 0.9813
Epoch 14/20
60000/60000 [==========
                             =======] - 7s 111us/step - loss: 0.0755 - acc: 0.9765 -
val_loss: 0.0647 - val_acc: 0.9804
Epoch 15/20
60000/60000 [============] - 7s 110us/step - loss: 0.0717 - acc: 0.9780 -
val loss: 0.0610 - val acc: 0.9822
Epoch 16/20
60000/60000 [============ ] - 7s 109us/step - loss: 0.0692 - acc: 0.9786 -
val loss: 0.0609 - val acc: 0.9814
Epoch 17/20
60000/60000 [============ ] - 7s 111us/step - loss: 0.0683 - acc: 0.9785 -
val loss: 0.0595 - val acc: 0.9834
Epoch 18/20
60000/60000 [============= ] - 7s 112us/step - loss: 0.0673 - acc: 0.9789 -
val loss: 0.0592 - val acc: 0.9824
Epoch 19/20
60000/60000 [============= ] - 7s 113us/step - loss: 0.0634 - acc: 0.9798 -
val loss: 0.0565 - val acc: 0.9837
Epoch 20/20
60000/60000 [============] - 7s 110us/step - loss: 0.0623 - acc: 0.9806 -
val loss: 0.0504 - val acc: 0.9849
```

In [24]:

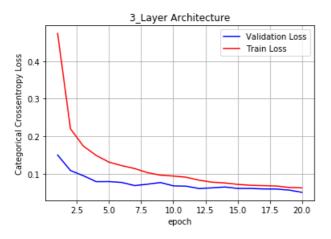
```
score_4 = model_relu2.evaluate(X_test, Y_test, verbose=0)
print('Test score:', score_4[0])
print('Test accuracy:', score_4[1])

fig,ax = plt.subplots(1,1)
ax.set_xlabel('epoch')
ax.set_ylabel('Categorical Crossentropy Loss')

# list of epoch numbers
x = list(range(1,nb_epoch+1))

vy = history.history['val_loss']
ty = history.history['loss']
plt_dynamic(x, vy, ty, ax)
plt.title('3_Layer Architecture')
plt.show()
```

Test score: 0.0504366103822249 Test accuracy: 0.9849



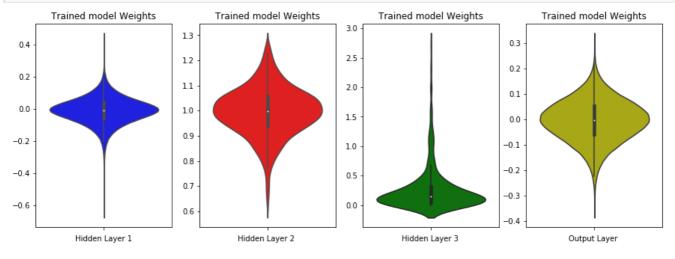
In above plot at epoch 20 our train and test loss becomes same

In [25]:

```
w_after = model_relu2.get_weights()

h1_w = w_after[0].flatten().reshape(-1,1)
h2_w = w_after[2].flatten().reshape(-1,1)
h3_w = w_after[4].flatten().reshape(-1,1)
```

```
out w = w after[6].flatten().reshape(-1,1)
fig = plt.figure(figsize=(15,5))
plt.title("Weight matrices after model trained")
plt.subplot(1, 4, 1)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h1 w,color='b')
plt.xlabel('Hidden Layer 1')
plt.subplot(1, 4, 2)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h2_w, color='r')
plt.xlabel('Hidden Layer 2 ')
plt.subplot(1, 4, 3)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h3 w, color='g')
plt.xlabel('Hidden Layer 3 ')
plt.subplot(1, 4, 4)
plt.title("Trained model Weights")
ax = sns.violinplot(y=out_w,color='y')
plt.xlabel('Output Layer ')
plt.show()
```



3-layer Architecture with-out Batch-Normalization and Dropout

In [26]:

```
model relu2 = Sequential()
#layer-1
model relu2.add(Dense(500, activation='relu', input shape=(input dim,), kernel initializer=RandomNo
rmal(mean=0.0, stddev=0.039, seed=None)))
#adding batch normalization
#model relu2.add(BatchNormalization())
#addding dropout rate
#model relu2.add(Dropout(0.5))
#layer-2
model relu2.add(Dense(300, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.03
9, seed=None)))
#adding batch noramalization
#model relu2.add(BatchNormalization())
#adding drop out rate
#model_relu2.add(Dropout(0.5))
#laver-3
model relu2.add(Dense(200, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.03
9, seed=None)))
#adding batch noramalization
#model relu2.add(BatchNormalization())
#adding drop out rate
#model relu2.add(Dropout(0.5))
```

```
model relu2.add(Dense(output dim, activation='softmax'))
#print(model relu2.summary())
#using optimizer adam
model relu2.compile(optimizer='adam', loss='categorical crossentropy', metrics=['accuracy'])
history = model relu2.fit(X train, Y train, batch size=batch size, epochs=nb epoch, verbose=1, vali
dation data=(X test, Y test))
4
                                                             )
Train on 60000 samples, validate on 10000 samples
Epoch 1/20
60000/60000 [============] - 4s 73us/step - loss: 0.2393 - acc: 0.9295 -
val loss: 0.0985 - val acc: 0.9686
Epoch 2/20
60000/60000 [============] - 4s 59us/step - loss: 0.0852 - acc: 0.9740 -
val loss: 0.0770 - val acc: 0.9754
Epoch 3/20
60000/60000 [============= ] - 4s 59us/step - loss: 0.0549 - acc: 0.9824 -
val loss: 0.0884 - val acc: 0.9741
Epoch 4/20
val loss: 0.0993 - val acc: 0.9702
Epoch 5/20
val loss: 0.0748 - val acc: 0.9799
Epoch 6/20
60000/60000 [============] - 4s 61us/step - loss: 0.0259 - acc: 0.9916 -
val_loss: 0.0709 - val_acc: 0.9806
Epoch 7/20
60000/60000 [============] - 4s 59us/step - loss: 0.0220 - acc: 0.9931 -
val_loss: 0.0775 - val_acc: 0.9802
Epoch 8/20
val_loss: 0.0680 - val_acc: 0.9813
Epoch 9/20
60000/60000 [===========] - 3s 58us/step - loss: 0.0161 - acc: 0.9948 -
val loss: 0.0827 - val acc: 0.9786
Epoch 10/20
60000/60000 [============ ] - 4s 59us/step - loss: 0.0171 - acc: 0.9946 -
val loss: 0.0841 - val acc: 0.9794
Epoch 11/20
60000/60000 [============= ] - 4s 61us/step - loss: 0.0160 - acc: 0.9946 -
val loss: 0.0884 - val acc: 0.9795
Epoch 12/20
60000/60000 [============] - 4s 60us/step - loss: 0.0155 - acc: 0.9950 -
val loss: 0.0817 - val acc: 0.9802
Epoch 13/20
val loss: 0.1019 - val acc: 0.9762
Epoch 14/20
val loss: 0.0805 - val acc: 0.9827
Epoch 15/20
60000/60000 [=============] - 4s 59us/step - loss: 0.0079 - acc: 0.9975 -
val_loss: 0.0916 - val_acc: 0.9817
Epoch 16/20
60000/60000 [============] - 4s 58us/step - loss: 0.0106 - acc: 0.9964 -
val_loss: 0.0830 - val_acc: 0.9827
Epoch 17/20
val_loss: 0.1009 - val acc: 0.9799
Epoch 18/20
val loss: 0.0858 - val acc: 0.9812
Epoch 19/20
val loss: 0.0984 - val acc: 0.9818
Epoch 20/20
60000/60000 [============] - 3s 58us/step - loss: 0.0066 - acc: 0.9980 -
val loss: 0.0914 - val acc: 0.9813
```

In [27]:

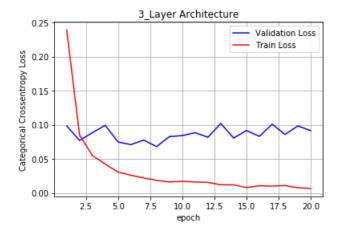
```
score_4 = model_relu2.evaluate(X_test, Y_test, verbose=0)
print('Test score:', score_4[0])
print('Test accuracy:', score_4[1])

fig,ax = plt.subplots(1,1)
ax.set_xlabel('epoch')
ax.set_ylabel('Categorical Crossentropy Loss')

# list of epoch numbers
x = list(range(1,nb_epoch+1))

vy = history.history['val_loss']
ty = history.history['loss']
plt_dynamic(x, vy, ty, ax)
plt.title('3_Layer Architecture')
plt.show()
```

Test score: 0.09140819830668388 Test accuracy: 0.9813

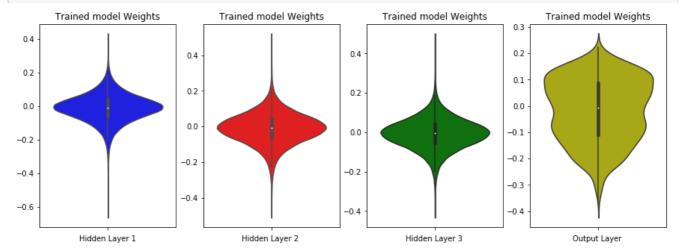


Here we see that in above plot with out apply of batch-normalization and drop out we got test loss > train loss

In [28]:

```
w after = model relu2.get weights()
h1 w = w after[0].flatten().reshape(-1,1)
h2 w = w after[2].flatten().reshape(-1,1)
h3 w = w after[4].flatten().reshape(-1,1)
out w = w after[6].flatten().reshape(-1,1)
fig = plt.figure(figsize=(15,5))
plt.title("Weight matrices after model trained")
plt.subplot(1, 4, 1)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h1 w,color='b')
plt.xlabel('Hidden Layer 1')
plt.subplot(1, 4, 2)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h2 w, color='r')
plt.xlabel('Hidden Layer 2 ')
plt.subplot(1, 4, 3)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h3 w, color='g')
plt.xlabel('Hidden Layer 3 ')
plt.subplot(1, 4, 4)
nlt.title("Trained model Weights")
```

```
ax = sns.violinplot(y=out_w,color='y')
plt.xlabel('Output Layer ')
plt.show()
```

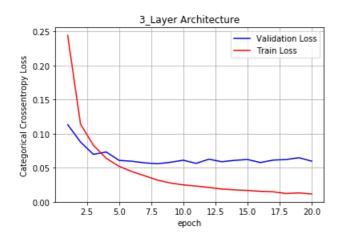


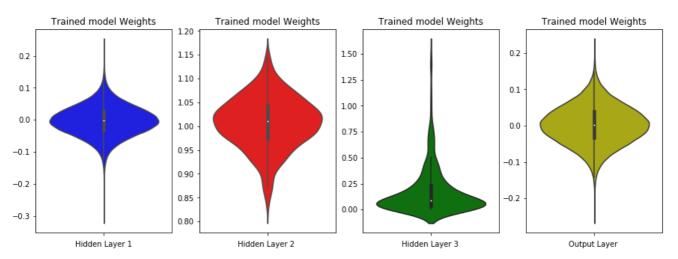
3 layer architecture We also experiment with Different optimizer like Adadelta with different drop-out rate 0.2

```
In [29]:
model relu2 = Sequential()
#laver-1
model relu2.add(Dense(500, activation='relu', input shape=(input dim,), kernel initializer=RandomNo
rmal(mean=0.0, stddev=0.039, seed=None)))
#adding batch normalization
model relu2.add(BatchNormalization())
#addding dropout rate
model relu2.add(Dropout(0.2))
#layer-2
model_relu2.add(Dense(300, activation='relu', kernel_initializer=RandomNormal(mean=0.0, stddev=0.03
9, seed=None)))
#adding batch noramalization
model relu2.add(BatchNormalization())
#adding drop out rate
model relu2.add(Dropout(0.2))
#laver-3
model relu2.add(Dense(200, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.03
9, seed=None)))
#adding batch noramalization
model relu2.add(BatchNormalization())
#adding drop out rate
model relu2.add(Dropout(0.2))
model relu2.add(Dense(output_dim, activation='softmax'))
#print(model relu2.summary())
#using optimizer adam
model relu2.compile(optimizer='Adadelta', loss='categorical crossentropy', metrics=['accuracy'])
history = model relu2.fit(X train, Y train, batch size=batch size, epochs=nb epoch, verbose=1, vali
dation_data=(X_test, Y_test))
#------train and test error ------
score 4 = model relu2.evaluate(X test, Y test, verbose=0)
print('Test score:', score 4[0])
print('Test accuracy:', score 4[1])
fig,ax = plt.subplots(1,1)
ax.set_xlabel('epoch')
ax.set_ylabel('Categorical Crossentropy Loss')
# list of epoch numbers
x = list(range(1, nb epoch+1))
```

```
vy = history.history['val loss']
ty = history.history['loss']
plt dynamic(x, vy, ty, ax)
plt.title('3 Layer Architecture')
plt.show()
                                            ----- performance -----
w after = model relu2.get weights()
h1_w = w_after[0].flatten().reshape(-1,1)
h2 w = w after[2].flatten().reshape(-1,1)
h3_w = w_after[4].flatten().reshape(-1,1)
out w = w after[6].flatten().reshape(-1,1)
fig = plt.figure(figsize=(15,5))
plt.title("Weight matrices after model trained")
plt.subplot(1, 4, 1)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h1 w,color='b')
plt.xlabel('Hidden Layer 1')
plt.subplot(1, 4, 2)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h2 w, color='r')
plt.xlabel('Hidden Layer 2 ')
plt.subplot(1, 4, 3)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h3 w, color='g')
plt.xlabel('Hidden Layer 3 ')
plt.subplot(1, 4, 4)
plt.title("Trained model Weights")
ax = sns.violinplot(y=out_w,color='y')
plt.xlabel('Output Layer ')
plt.show()
4
Train on 60000 samples, validate on 10000 samples
Epoch 1/20
60000/60000 [============] - 9s 145us/step - loss: 0.2440 - acc: 0.9250 -
val loss: 0.1133 - val acc: 0.9648
Epoch 2/20
60000/60000 [============= ] - 7s 116us/step - loss: 0.1140 - acc: 0.9655 -
val_loss: 0.0878 - val_acc: 0.9710
Epoch 3/20
60000/60000 [=============] - 7s 116us/step - loss: 0.0830 - acc: 0.9738 -
val loss: 0.0698 - val_acc: 0.9782
Epoch 4/20
60000/60000 [==============] - 7s 118us/step - loss: 0.0640 - acc: 0.9796 -
val loss: 0.0732 - val acc: 0.9783
Epoch 5/20
60000/60000 [============= ] - 7s 118us/step - loss: 0.0522 - acc: 0.9837 -
val loss: 0.0609 - val_acc: 0.9811
Epoch 6/20
60000/60000 [============] - 7s 119us/step - loss: 0.0445 - acc: 0.9853 -
val loss: 0.0596 - val acc: 0.9819
Epoch 7/20
60000/60000 [============ ] - 7s 116us/step - loss: 0.0383 - acc: 0.9873 -
val loss: 0.0573 - val acc: 0.9835
Epoch 8/20
60000/60000 [============ ] - 7s 117us/step - loss: 0.0320 - acc: 0.9897 -
val loss: 0.0560 - val acc: 0.9834
Epoch 9/20
val loss: 0.0581 - val acc: 0.9834
Epoch 10/20
val loss: 0.0612 - val acc: 0.9826
Epoch 11/20
60000/60000 [==========] - 7s 117us/step - loss: 0.0233 - acc: 0.9924 -
```

```
val loss: 0.0565 - val acc: 0.9844
Epoch 12/20
60000/60000 [============ ] - 7s 115us/step - loss: 0.0213 - acc: 0.9932 -
val loss: 0.0627 - val acc: 0.9838
Epoch 13/20
60000/60000 [============ ] - 7s 115us/step - loss: 0.0189 - acc: 0.9936 -
val loss: 0.0589 - val acc: 0.9842
Epoch 14/20
60000/60000 [============] - 7s 118us/step - loss: 0.0178 - acc: 0.9940 -
val loss: 0.0610 - val acc: 0.9833
Epoch 15/20
60000/60000 [============= ] - 7s 117us/step - loss: 0.0169 - acc: 0.9944 -
val loss: 0.0622 - val acc: 0.9845
Epoch 16/20
60000/60000 [============= ] - 7s 117us/step - loss: 0.0156 - acc: 0.9950 -
val loss: 0.0578 - val_acc: 0.9858
Epoch 17/20
60000/60000 [============] - 7s 116us/step - loss: 0.0149 - acc: 0.9949 -
val loss: 0.0613 - val acc: 0.9852
Epoch 18/20
60000/60000 [============= ] - 7s 117us/step - loss: 0.0124 - acc: 0.9959 -
val_loss: 0.0621 - val_acc: 0.9855
Epoch 19/20
60000/60000 [============== ] - 7s 118us/step - loss: 0.0132 - acc: 0.9956 -
val loss: 0.0648 - val acc: 0.9834
Epoch 20/20
60000/60000 [============ ] - 7s 116us/step - loss: 0.0118 - acc: 0.9960 -
val loss: 0.0598 - val acc: 0.9845
Test score: 0.05980458545034853
Test accuracy: 0.9845
```





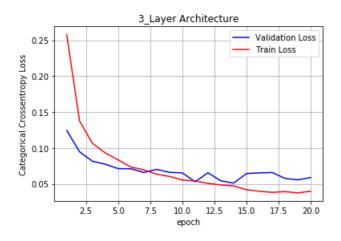
3 layer architecture Here below we experiment with one batch-normalization and 1 drop out layer at begining of the architecture with Adam optimizer and drop 0.5

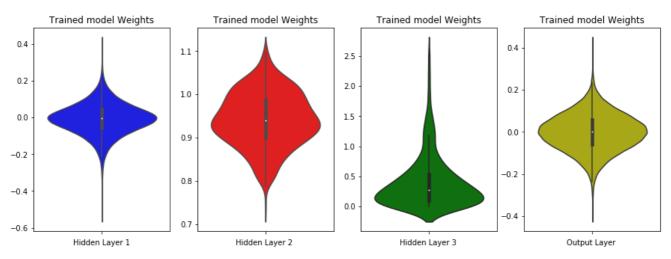
```
In [30]:
```

```
model relu2 = Sequential()
#laver-1
model relu2.add(Dense(500, activation='relu', input shape=(input dim,), kernel initializer=RandomNo
rmal(mean=0.0, stddev=0.039, seed=None)))
#adding batch normalization
model relu2.add(BatchNormalization())
#addding dropout rate
model relu2.add(Dropout(0.5))
#laver-2
model relu2.add(Dense(300, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.03
9, seed=None)))
#adding batch noramalization
#model_relu2.add(BatchNormalization())
#adding drop out rate
#model relu2.add(Dropout(0.2))
#layer-3
model relu2.add(Dense(200, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.03
9, seed=None)))
#adding batch noramalization
#model relu2.add(BatchNormalization())
#adding drop out rate
#model relu2.add(Dropout(0.2))
model_relu2.add(Dense(output_dim, activation='softmax'))
#print(model relu2.summary())
#using optimizer adam
model relu2.compile(optimizer='Adam', loss='categorical crossentropy', metrics=['accuracy'])
history = model relu2.fit(X train, Y train, batch size=batch size, epochs=nb epoch, verbose=1, vali
dation_data=(X_test, Y_test))
#------train and test error -------
_____
score_4 = model_relu2.evaluate(X_test, Y_test, verbose=0)
print('Test score:', score 4[0])
print('Test accuracy:', score 4[1])
fig,ax = plt.subplots(1,1)
ax.set xlabel('epoch')
ax.set ylabel('Categorical Crossentropy Loss')
# list of epoch numbers
x = list(range(1, nb epoch+1))
vy = history.history['val loss']
ty = history.history['loss']
plt dynamic(x, vy, ty, ax)
plt.title('3 Layer Architecture')
plt.show()
#------layers performance ------
w after = model relu2.get weights()
h1 w = w after[0].flatten().reshape(-1,1)
h2 w = w after[2].flatten().reshape(-1,1)
h3_w = w_after[4].flatten().reshape(-1,1)
out_w = w_after[6].flatten().reshape(-1,1)
fig = plt.figure(figsize=(15,5))
plt.title("Weight matrices after model trained")
plt.subplot(1, 4, 1)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h1 w,color='b')
plt.xlabel('Hidden Layer 1')
plt.subplot(1, 4, 2)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h2_w, color='r')
```

```
|plt.xlabel('Hidden Layer 2 ')
plt.subplot(1, 4, 3)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h3_w, color='g')
plt.xlabel('Hidden Layer 3 ')
plt.subplot(1, 4, 4)
plt.title("Trained model Weights")
ax = sns.violinplot(y=out w,color='y')
plt.xlabel('Output Layer ')
plt.show()
4
Train on 60000 samples, validate on 10000 samples
Epoch 1/20
60000/60000 [============== ] - 6s 100us/step - loss: 0.2582 - acc: 0.9199 -
val loss: 0.1245 - val acc: 0.9590
Epoch 2/20
60000/60000 [============] - 5s 78us/step - loss: 0.1377 - acc: 0.9567 -
val loss: 0.0946 - val acc: 0.9697
Epoch 3/20
60000/60000 [============] - 5s 77us/step - loss: 0.1065 - acc: 0.9656 -
val loss: 0.0814 - val acc: 0.9732
Epoch 4/20
val loss: 0.0773 - val acc: 0.9764
Epoch 5/20
60000/60000 [============] - 5s 78us/step - loss: 0.0834 - acc: 0.9729 -
val_loss: 0.0712 - val_acc: 0.9787
Epoch 6/20
60000/60000 [============= ] - 5s 77us/step - loss: 0.0733 - acc: 0.9764 -
val loss: 0.0709 - val acc: 0.9786
Epoch 7/20
60000/60000 [============= ] - 5s 77us/step - loss: 0.0695 - acc: 0.9779 -
val loss: 0.0658 - val acc: 0.9802
Epoch 8/20
60000/60000 [===========] - 5s 76us/step - loss: 0.0634 - acc: 0.9799 -
val loss: 0.0700 - val acc: 0.9786
Epoch 9/20
val loss: 0.0660 - val acc: 0.9803
Epoch 10/20
60000/60000 [=============] - 5s 79us/step - loss: 0.0552 - acc: 0.9818 -
val loss: 0.0653 - val acc: 0.9819
Epoch 11/20
val loss: 0.0529 - val acc: 0.9839
Epoch 12/20
val loss: 0.0654 - val acc: 0.9802
Epoch 13/20
60000/60000 [============] - 5s 76us/step - loss: 0.0485 - acc: 0.9844 -
val loss: 0.0541 - val acc: 0.9853
Epoch 14/20
60000/60000 [============] - 5s 76us/step - loss: 0.0470 - acc: 0.9844 -
val loss: 0.0509 - val acc: 0.9848
Epoch 15/20
60000/60000 [============] - 5s 77us/step - loss: 0.0417 - acc: 0.9866 -
val_loss: 0.0643 - val_acc: 0.9828
Epoch 16/20
60000/60000 [=============] - 5s 79us/step - loss: 0.0396 - acc: 0.9868 -
val_loss: 0.0652 - val_acc: 0.9820
Epoch 17/20
60000/60000 [=============] - 5s 77us/step - loss: 0.0380 - acc: 0.9875 -
val loss: 0.0658 - val acc: 0.9827
Epoch 18/20
60000/60000 [============] - 5s 78us/step - loss: 0.0391 - acc: 0.9868 -
val loss: 0.0575 - val acc: 0.9838
Epoch 19/20
60000/60000 [============] - 5s 78us/step - loss: 0.0373 - acc: 0.9880 -
val loss: 0.0555 - val acc: 0.9851
Epoch 20/20
60000/60000 [============] - 5s 76us/step - loss: 0.0396 - acc: 0.9871 -
val loss: 0.0587 - val acc: 0.9839
Test score: 0.058732410513349896
Test accuracy: 0.9839
```

•





Above We got our test-loss > train-loss which is not a good performance

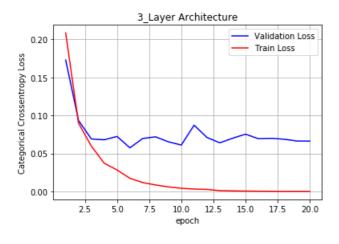
3 layer architecture Here below we experiment with one batch-normalization and 1 drop out layer at before last layer in the architecturer with Adam optimizer and drop 0.5

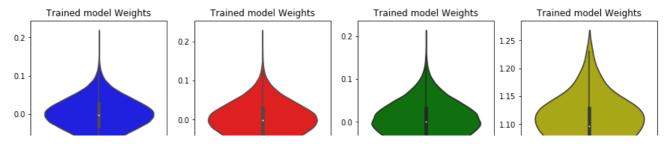
```
In [31]:
```

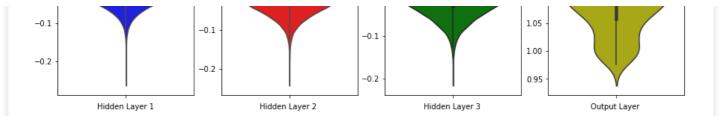
```
model relu2 = Sequential()
#laver-1
model relu2.add(Dense(500, activation='relu', input shape=(input dim,), kernel initializer=RandomNo
rmal(mean=0.0, stddev=0.039, seed=None)))
#adding batch normalization
#model relu2.add(BatchNormalization())
#addding dropout rate
#model relu2.add(Dropout(0.2))
#layer-2
model_relu2.add(Dense(300, activation='relu', kernel_initializer=RandomNormal(mean=0.0, stddev=0.03
9, seed=None)))
#adding batch noramalization
#model relu2.add(BatchNormalization())
#adding drop out rate
#model relu2.add(Dropout(0.2))
#layer-3
model relu2.add(Dense(200, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.03
9, seed=None)))
#adding batch noramalization
model relu2.add(BatchNormalization())
#adding drop out rate
model relu2.add(Dropout(0.2))
model_relu2.add(Dense(output_dim, activation='softmax'))
#print(model relu2.summary())
#using optimizer adam
```

```
model relu2.compile(optimizer='Adadelta', loss='categorical crossentropy', metrics=['accuracy'])
history = model relu2.fit(X train, Y train, batch size=batch size, epochs=nb epoch, verbose=1, vali
dation data=(X test, Y test))
#------train and test error ------
score 4 = model relu2.evaluate(X test, Y test, verbose=0)
print('Test score:', score_4[0])
print('Test accuracy:', score 4[1])
fig,ax = plt.subplots(1,1)
ax.set xlabel('epoch')
ax.set_ylabel('Categorical Crossentropy Loss')
# list of epoch numbers
x = list(range(1,nb_epoch+1))
vy = history.history['val loss']
ty = history.history['loss']
plt dynamic(x, vy, ty, ax)
plt.title('3 Layer Architecture')
plt.show()
                                              -----person entry ------
w_after = model_relu2.get_weights()
h1_w = w_after[0].flatten().reshape(-1,1)
h2_w = w_after[2].flatten().reshape(-1,1)
h3_w = w_after[4].flatten().reshape(-1,1)
out_w = w_after[6].flatten().reshape(-1,1)
fig = plt.figure(figsize=(15,5))
plt.title("Weight matrices after model trained")
plt.subplot(1, 4, 1)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h1_w,color='b')
plt.xlabel('Hidden Layer 1')
plt.subplot(1, 4, 2)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h2_w, color='r')
plt.xlabel('Hidden Layer 2 ')
plt.subplot(1, 4, 3)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h3 w, color='g')
plt.xlabel('Hidden Layer 3 ')
plt.subplot(1, 4, 4)
plt.title("Trained model Weights")
ax = sns.violinplot(y=out w,color='y')
plt.xlabel('Output Layer ')
plt.show()
Train on 60000 samples, validate on 10000 samples
Epoch 1/20
60000/60000 [============= ] - 6s 107us/step - loss: 0.2086 - acc: 0.9362 -
val_loss: 0.1729 - val_acc: 0.9471
Epoch 2/20
60000/60000 [============] - 5s 82us/step - loss: 0.0899 - acc: 0.9725 -
val_loss: 0.0934 - val_acc: 0.9713
Epoch 3/20
val_loss: 0.0691 - val_acc: 0.9786
Epoch 4/20
val loss: 0.0680 - val acc: 0.9793
60000/60000 [============] - 5s 81us/step - loss: 0.0282 - acc: 0.9910 -
```

```
val loss: 0.0724 - val acc: 0.9781
Epoch 6/20
60000/60000 [============] - 5s 78us/step - loss: 0.0173 - acc: 0.9945 -
val loss: 0.0574 - val acc: 0.9839
Epoch 7/20
60000/60000 [===========] - 5s 78us/step - loss: 0.0117 - acc: 0.9962 -
val loss: 0.0697 - val acc: 0.9813
60000/60000 [============] - 5s 79us/step - loss: 0.0085 - acc: 0.9974 -
val loss: 0.0719 - val acc: 0.9811
Epoch 9/20
60000/60000 [============] - 5s 78us/step - loss: 0.0060 - acc: 0.9981 -
val loss: 0.0653 - val acc: 0.9834
Epoch 10/20
val loss: 0.0610 - val acc: 0.9857
Epoch 11/20
60000/60000 [============] - 5s 78us/step - loss: 0.0031 - acc: 0.9991 -
val loss: 0.0872 - val acc: 0.9811
Epoch 12/20
60000/60000 [============] - 5s 79us/step - loss: 0.0027 - acc: 0.9992 -
val_loss: 0.0710 - val_acc: 0.9838
Epoch 13/20
60000/60000 [============] - 5s 77us/step - loss: 0.0011 - acc: 0.9998 -
val loss: 0.0640 - val acc: 0.9856
Epoch 14/20
60000/60000 [=============] - 5s 78us/step - loss: 7.5832e-04 - acc: 0.9998 - val
 loss: 0.0700 - val acc: 0.9856
Epoch 15/20
60000/60000 [==============] - 5s 79us/step - loss: 5.3548e-04 - acc: 0.9998 - val
loss: 0.0754 - val acc: 0.9850
Epoch 16/20
60000/60000 [============= ] - 5s 78us/step - loss: 3.6343e-04 - acc: 0.9999 - val
loss: 0.0694 - val acc: 0.9865
Epoch 17/20
60000/60000 [=============] - 5s 78us/step - loss: 2.0863e-04 - acc: 1.0000 - val
loss: 0.0699 - val acc: 0.9860
Epoch 18/20
60000/60000 [=============] - 5s 78us/step - loss: 7.5309e-05 - acc: 1.0000 - val
loss: 0.0688 - val acc: 0.9867
Epoch 19/20
60000/60000 [==============] - 5s 79us/step - loss: 1.6480e-04 - acc: 1.0000 - val
loss: 0.0664 - val acc: 0.9866
Epoch 20/20
60000/60000 [============= ] - 5s 77us/step - loss: 3.2577e-05 - acc: 1.0000 - val
 loss: 0.0662 - val acc: 0.9866
Test score: 0.06620450230908602
Test accuracy: 0.9866
```







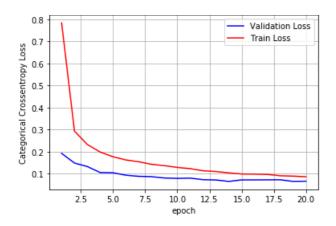
5-layer Architecture with Batch-Normalization and Dropout

```
In [32]:
model relu3 = Sequential()
#layer-1
model relu3.add(Dense(500, activation='relu', input shape=(input dim,), kernel initializer=RandomNo
rmal(mean=0.0, stddev=0.039, seed=None)))
#adding batch normalization
model relu3.add(BatchNormalization())
#addding dropout rate
model relu3.add(Dropout(0.5))
model relu3.add(Dense(400, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.03
9, seed=None)))
#adding batch noramalization
model relu3.add(BatchNormalization())
#adding drop out rate
model relu3.add(Dropout(0.5))
#laver-3
model relu3.add(Dense(300, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.03
9, seed=None)))
#adding batch noramalization
model_relu3.add(BatchNormalization())
#adding drop out rate
model relu3.add(Dropout(0.5))
#layer-4
model relu3.add(Dense(200, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.03
9, seed=None)))
#adding batch noramalization
model relu3.add(BatchNormalization())
#adding drop out rate
model_relu3.add(Dropout(0.5))
#layer-5
model relu3.add(Dense(100, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.03
9, seed=None)))
#adding batch noramalization
model relu3.add(BatchNormalization())
#adding drop out rate
model relu3.add(Dropout(0.5))
model relu3.add(Dense(output dim, activation='softmax'))
#print(model relu3.summary())
#using optimizer adam
model relu3.compile(optimizer='adam', loss='categorical crossentropy', metrics=['accuracy'])
history = model relu3.fit(X train, Y train, batch size=batch size, epochs=nb epoch, verbose=1, vali
dation_data=(X_test, Y_test))
Train on 60000 samples, validate on 10000 samples
Epoch 1/20
60000/60000 [============= ] - 12s 204us/step - loss: 0.7834 - acc: 0.7620 - val 1
oss: 0.1921 - val acc: 0.9478
Epoch 2/20
60000/60000 [============= ] - 10s 159us/step - loss: 0.2929 - acc: 0.9170 - val 1
oss: 0.1483 - val acc: 0.9584
Epoch 3/20
60000/60000 [============= ] - 9s 157us/step - loss: 0.2324 - acc: 0.9356 -
```

val loss: 0.1326 - val acc: 0.9636

```
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60000/60000 [============= ] - 10s 159us/step - loss: 0.1981 - acc: 0.9460 - val 1
oss: 0.1052 - val_acc: 0.9697
Epoch 5/20
60000/60000 [============= ] - 10s 160us/step - loss: 0.1768 - acc: 0.9519 - val 1
oss: 0.1044 - val_acc: 0.9709
Epoch 6/20
60000/60000 [============== ] - 10s 160us/step - loss: 0.1624 - acc: 0.9551 - val 1
oss: 0.0932 - val_acc: 0.9753
Epoch 7/20
60000/60000 [============== ] - 10s 160us/step - loss: 0.1541 - acc: 0.9577 - val 1
oss: 0.0882 - val acc: 0.9746
Epoch 8/20
60000/60000 [============= ] - 10s 159us/step - loss: 0.1425 - acc: 0.9607 - val 1
oss: 0.0866 - val acc: 0.9761
Epoch 9/20
60000/60000 [============= ] - 9s 158us/step - loss: 0.1364 - acc: 0.9633 -
val loss: 0.0806 - val acc: 0.9770
Epoch 10/20
60000/60000 [============= ] - 9s 158us/step - loss: 0.1285 - acc: 0.9648 -
val loss: 0.0789 - val acc: 0.9783
Epoch 11/20
60000/60000 [============= ] - 10s 159us/step - loss: 0.1230 - acc: 0.9665 - val 1
oss: 0.0801 - val acc: 0.9792
Epoch 12/20
val_loss: 0.0730 - val_acc: 0.9806
Epoch 13/20
val loss: 0.0716 - val acc: 0.9796
Epoch 14/20
60000/60000 [============== ] - 9s 157us/step - loss: 0.1039 - acc: 0.9717 -
val loss: 0.0650 - val acc: 0.9823
Epoch 15/20
60000/60000 [============= ] - 9s 158us/step - loss: 0.0987 - acc: 0.9736 -
val loss: 0.0720 - val acc: 0.9812
Epoch 16/20
60000/60000 [=============] - 9s 157us/step - loss: 0.0980 - acc: 0.9731 -
val_loss: 0.0722 - val_acc: 0.9804
Epoch 17/20
60000/60000 [============== ] - 10s 160us/step - loss: 0.0968 - acc: 0.9738 - val 1
oss: 0.0723 - val_acc: 0.9813
Epoch 18/20
60000/60000 [============ ] - 10s 159us/step - loss: 0.0908 - acc: 0.9747 - val 1
oss: 0.0726 - val acc: 0.9811
Epoch 19/20
60000/60000 [============= ] - 10s 159us/step - loss: 0.0891 - acc: 0.9759 - val 1
oss: 0.0651 - val_acc: 0.9824
Epoch 20/20
60000/60000 [============] - 9s 158us/step - loss: 0.0861 - acc: 0.9767 -
val loss: 0.0660 - val acc: 0.9824
In [33]:
score 6 = model relu3.evaluate(X test, Y test, verbose=0)
print('Test score:', score 6[0])
print('Test accuracy:', score_6[1])
fig,ax = plt.subplots(1,1)
ax.set xlabel('epoch')
ax.set ylabel('Categorical Crossentropy Loss')
# list of epoch numbers
x = list(range(1,nb_epoch+1))
vy = history.history['val loss']
ty = history.history['loss']
plt_dynamic(x, vy, ty, ax)
plt.title('5 Layer Architecture')
plt.show()
```

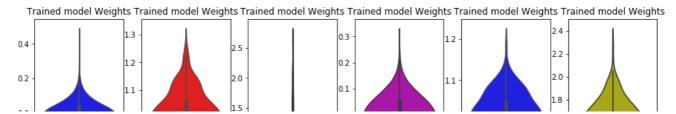
Test score: 0.066039138047304 Test accuracy: 0.9824

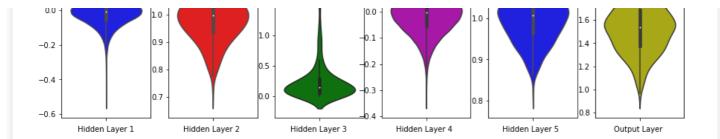


In above plot it maintains smaller error distance from train to test

In [34]:

```
w after = model relu3.get weights()
h1_w = w_after[0].flatten().reshape(-1,1)
h2 w = w after[2].flatten().reshape(-1,1)
h3_w = w_after[4].flatten().reshape(-1,1)
h4 w = w after[6].flatten().reshape(-1,1)
h5_w = w_after[8].flatten().reshape(-1,1)
out w = w after[10].flatten().reshape(-1,1)
fig = plt.figure(figsize=(15,5))
plt.title("Weight matrices after model trained")
plt.subplot(1, 6, 1,)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h1 w,color='b')
plt.xlabel('Hidden Layer 1')
plt.subplot(1, 6, 2)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h2_w, color='r')
plt.xlabel('Hidden Layer 2 ')
plt.subplot(1, 6, 3)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h3_w, color='g')
plt.xlabel('Hidden Layer 3 ')
plt.subplot(1, 6, 4)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h4_w,color='m')
plt.xlabel('Hidden Layer 4 ')
plt.subplot(1, 6, 5)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h5_w,color='b')
plt.xlabel('Hidden Layer 5 ')
plt.subplot(1, 6, 6)
plt.title("Trained model Weights")
ax = sns.violinplot(y=out w,color='y')
plt.xlabel('Output Layer ')
plt.show()
```





5-layer Architecture with-out Batch-Normalization and Dropout

```
In [35]:
```

```
model relu3 = Sequential()
#layer-1
model relu3.add(Dense(500, activation='relu', input shape=(input dim,), kernel initializer=RandomNo
rmal(mean=0.0, stddev=0.039, seed=None)))
#adding batch normalization
#model_relu3.add(BatchNormalization())
#addding dropout rate
#model_relu3.add(Dropout(0.5))
#layer-2
model relu3.add(Dense(400, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.03
9, seed=None)))
#adding batch noramalization
#model relu3.add(BatchNormalization())
#adding drop out rate
#model relu3.add(Dropout(0.5))
#layer-3
model relu3.add(Dense(300, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.03
9, seed=None)))
#adding batch noramalization
#model relu3.add(BatchNormalization())
#adding drop out rate
#model_relu3.add(Dropout(0.5))
#layer-4
model relu3.add(Dense(200, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.03
9, seed=None)))
#adding batch noramalization
#model relu3.add(BatchNormalization())
#adding drop out rate
#model relu3.add(Dropout(0.5))
#layer-5
model relu3.add(Dense(100, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.03
9, seed=None)))
#adding batch noramalization
#model relu3.add(BatchNormalization())
#adding drop out rate
#model relu3.add(Dropout(0.5))
model_relu3.add(Dense(output_dim, activation='softmax'))
#print(model_relu3.summary())
#using optimizer adam
model relu3.compile(optimizer='adam', loss='categorical crossentropy', metrics=['accuracy'])
history = model relu3.fit(X train, Y train, batch size=batch size, epochs=nb epoch, verbose=1, vali
dation data=(X test, Y test))
Train on 60000 samples, validate on 10000 samples
Epoch 1/20
val loss: 0.1198 - val acc: 0.9652
Epoch 2/20
val loss: 0.0879 - val acc: 0.9747
Epoch 3/20
val loss: 0.0929 - val acc: 0.9732
Epoch 4/20
```

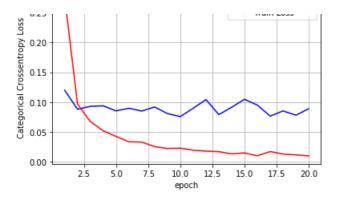
```
Epoch 5/20
val loss: 0.0852 - val acc: 0.9759
Epoch 6/20
60000/60000 [============ ] - 4s 75us/step - loss: 0.0334 - acc: 0.9897 -
val loss: 0.0896 - val acc: 0.9745
Epoch 7/20
val_loss: 0.0849 - val_acc: 0.9805
Epoch 8/20
60000/60000 [============] - 4s 72us/step - loss: 0.0253 - acc: 0.9918 -
val loss: 0.0918 - val acc: 0.9776
Epoch 9/20
60000/60000 [===========] - 4s 72us/step - loss: 0.0222 - acc: 0.9934 -
val loss: 0.0807 - val_acc: 0.9802
Epoch 10/20
val loss: 0.0757 - val_acc: 0.9822
Epoch 11/20
60000/60000 [============] - 4s 72us/step - loss: 0.0193 - acc: 0.9941 -
val_loss: 0.0896 - val_acc: 0.9791
Epoch 12/20
val loss: 0.1042 - val acc: 0.9775
Epoch 13/20
60000/60000 [============] - 4s 71us/step - loss: 0.0169 - acc: 0.9952 -
val loss: 0.0790 - val acc: 0.9827
Epoch 14/20
60000/60000 [============] - 4s 72us/step - loss: 0.0132 - acc: 0.9958 -
val loss: 0.0913 - val acc: 0.9803
Epoch 15/20
60000/60000 [============ ] - 4s 73us/step - loss: 0.0148 - acc: 0.9958 -
val loss: 0.1047 - val acc: 0.9772
Epoch 16/20
60000/60000 [============ ] - 4s 72us/step - loss: 0.0100 - acc: 0.9970 -
val loss: 0.0950 - val acc: 0.9831
Epoch 17/20
val loss: 0.0764 - val acc: 0.9817
Epoch 18/20
val loss: 0.0852 - val acc: 0.9828
Epoch 19/20
60000/60000 [============ ] - 4s 71us/step - loss: 0.0114 - acc: 0.9968 -
val loss: 0.0780 - val acc: 0.9827
Epoch 20/20
60000/60000 [============] - 4s 72us/step - loss: 0.0097 - acc: 0.9973 -
val loss: 0.0888 - val acc: 0.9830
In [36]:
score_6 = model_relu3.evaluate(X_test, Y_test, verbose=0)
print('Test score:', score 6[0])
print('Test accuracy:', score_6[1])
fig,ax = plt.subplots(1,1)
ax.set xlabel('epoch')
ax.set ylabel('Categorical Crossentropy Loss')
# list of epoch numbers
x = list(range(1,nb_epoch+1))
vy = history.history['val_loss']
ty = history.history['loss']
plt_dynamic(x, vy, ty, ax)
plt.title('5_Layer Architecture')
plt.show()
```

Test score: 0.08883313840526234 Test accuracy: 0.983

val loss: 0.0936 - val acc: 0.9757

5_Layer Architecture

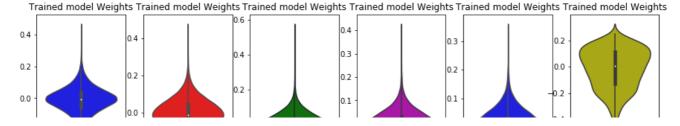
Validation Loss
Train Loss

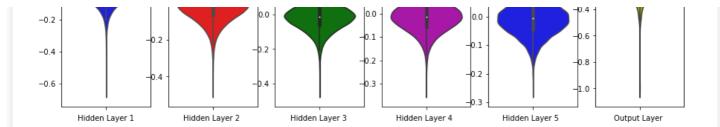


Here we see that in above plot with out apply of batch-normalization and drop out we got test loss > train loss

In [37]:

```
w after = model relu3.get weights()
h1_w = w_after[0].flatten().reshape(-1,1)
h2 w = w after[2].flatten().reshape(-1,1)
h3 w = w after[4].flatten().reshape(-1,1)
h4_w = w_after[6].flatten().reshape(-1,1)
h5_w = w_after[8].flatten().reshape(-1,1)
out_w = w_after[10].flatten().reshape(-1,1)
fig = plt.figure(figsize=(15,5))
plt.title("Weight matrices after model trained")
plt.subplot(1, 6, 1,)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h1_w,color='b')
plt.xlabel('Hidden Layer 1')
plt.subplot(1, 6, 2)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h2_w, color='r')
plt.xlabel('Hidden Layer 2 ')
plt.subplot(1, 6, 3)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h3_w, color='g')
plt.xlabel('Hidden Layer 3 ')
plt.subplot(1, 6, 4)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h4_w,color='m')
plt.xlabel('Hidden Layer 4 ')
plt.subplot(1, 6, 5)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h5 w,color='b')
plt.xlabel('Hidden Layer 5 ')
plt.subplot(1, 6, 6)
plt.title("Trained model Weights")
ax = sns.violinplot(y=out w,color='y')
plt.xlabel('Output Layer ')
plt.show()
```





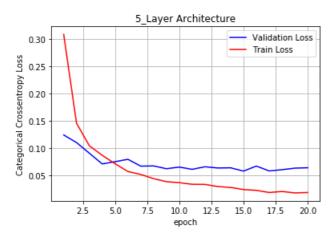
5 layer architecture We also experiment with Different optimizer like Adadelta with different drop-out rate 0.2

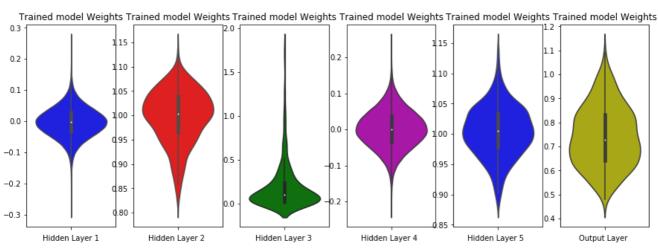
```
In [38]:
```

```
model relu3 = Sequential()
#laver-1
model relu3.add(Dense(500, activation='relu', input shape=(input dim,), kernel initializer=RandomNo
rmal(mean=0.0, stddev=0.039, seed=None)))
#adding batch normalization
model relu3.add(BatchNormalization())
#addding dropout rate
model relu3.add(Dropout(0.2))
#layer-2
model relu3.add(Dense(400, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.03
9, seed=None)))
#adding batch noramalization
model relu3.add(BatchNormalization())
#adding drop out rate
model relu3.add(Dropout(0.2))
#layer-3
model relu3.add(Dense(300, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.03
9, seed=None)))
#adding batch noramalization
model_relu3.add(BatchNormalization())
#adding drop out rate
model_relu3.add(Dropout(0.2))
#laver-4
model relu3.add(Dense(200, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.03
9, seed=None)))
#adding batch noramalization
model_relu3.add(BatchNormalization())
#adding drop out rate
model relu3.add(Dropout(0.2))
#layer-5
model relu3.add(Dense(100, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.03
9, seed=None)))
#adding batch noramalization
model relu3.add(BatchNormalization())
#adding drop out rate
model relu3.add(Dropout(0.2))
model relu3.add(Dense(output dim, activation='softmax'))
#print(model relu3.summary())
#using optimizer adam
model relu3.compile(optimizer='Adadelta', loss='categorical crossentropy', metrics=['accuracy'])
history = model_relu3.fit(X_train, Y_train, batch_size=batch_size, epochs=nb_epoch, verbose=1, vali
dation data=(X test, Y test))
score 6 = model relu3.evaluate(X test, Y test, verbose=0)
print('Test score:', score_6[0])
print('Test accuracy:', score 6[1])
fig,ax = plt.subplots(1,1)
ax.set xlabel('epoch')
ax.set_ylabel('Categorical Crossentropy Loss')
# list of epoch numbers
x = list(range(1,nb_epoch+1))
vy = history.history['val loss']
```

```
ty = history.history['loss']
plt_dynamic(x, vy, ty, ax)
plt.title('5 Layer Architecture')
plt.show()
w after = model relu3.get weights()
h1 w = w after[0].flatten().reshape(-1,1)
h2 w = w after[2].flatten().reshape(-1,1)
h3_w = w_after[4].flatten().reshape(-1,1)
h4_w = w_after[6].flatten().reshape(-1,1)
h5 w = w after[8].flatten().reshape(-1,1)
out_w = w_after[10].flatten().reshape(-1,1)
fig = plt.figure(figsize=(15,5))
plt.title("Weight matrices after model trained")
plt.subplot(1, 6, 1,)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h1 w,color='b')
plt.xlabel('Hidden Layer 1')
plt.subplot(1, 6, 2)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h2_w, color='r')
plt.xlabel('Hidden Layer 2 ')
plt.subplot(1, 6, 3)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h3_w, color='g')
plt.xlabel('Hidden Layer 3 ')
plt.subplot(1, 6, 4)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h4 w,color='m')
plt.xlabel('Hidden Layer 4 ')
plt.subplot(1, 6, 5)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h5 w,color='b')
plt.xlabel('Hidden Layer 5 ')
plt.subplot(1, 6, 6)
plt.title("Trained model Weights")
ax = sns.violinplot(y=out w,color='y')
plt.xlabel('Output Layer ')
plt.show()
4
Train on 60000 samples, validate on 10000 samples
Epoch 1/20
60000/60000 [============== ] - 13s 219us/step - loss: 0.3082 - acc: 0.9069 - val 1
oss: 0.1241 - val_acc: 0.9633
Epoch 2/20
60000/60000 [============= ] - 10s 166us/step - loss: 0.1455 - acc: 0.9573 - val 1
oss: 0.1102 - val acc: 0.9685
Epoch 3/20
60000/60000 [============= ] - 10s 167us/step - loss: 0.1043 - acc: 0.9689 - val 1
oss: 0.0906 - val acc: 0.9729
Epoch 4/20
60000/60000 [=============] - 10s 167us/step - loss: 0.0869 - acc: 0.9738 - val 1
oss: 0.0711 - val_acc: 0.9789
Epoch 5/20
60000/60000 [============= ] - 10s 167us/step - loss: 0.0715 - acc: 0.9776 - val 1
oss: 0.0752 - val acc: 0.9792
Epoch 6/20
60000/60000 [=============] - 10s 165us/step - loss: 0.0572 - acc: 0.9829 - val 1
oss: 0.0795 - val acc: 0.9771
Epoch 7/20
60000/60000 [============= ] - 10s 168us/step - loss: 0.0518 - acc: 0.9847 - val 1
oss: 0.0670 - val acc: 0.9812
Epoch 8/20
```

```
oss: 0.0675 - val acc: 0.9810
Epoch 9/20
60000/60000 [============== ] - 10s 166us/step - loss: 0.0386 - acc: 0.9882 - val 1
oss: 0.0622 - val acc: 0.9833
Epoch 10/20
60000/60000 [==============] - 10s 167us/step - loss: 0.0368 - acc: 0.9886 - val 1
oss: 0.0653 - val acc: 0.9815
Epoch 11/20
60000/60000 [============== ] - 10s 167us/step - loss: 0.0338 - acc: 0.9895 - val 1
oss: 0.0612 - val acc: 0.9839
Epoch 12/20
60000/60000 [============== ] - 10s 165us/step - loss: 0.0336 - acc: 0.9896 - val 1
oss: 0.0659 - val acc: 0.9818
Epoch 13/20
60000/60000 [============= ] - 10s 168us/step - loss: 0.0297 - acc: 0.9908 - val 1
oss: 0.0636 - val_acc: 0.9848
Epoch 14/20
60000/60000 [============= ] - 10s 167us/step - loss: 0.0281 - acc: 0.9915 - val 1
oss: 0.0639 - val_acc: 0.9827
Epoch 15/20
60000/60000 [=============] - 10s 166us/step - loss: 0.0242 - acc: 0.9924 - val 1
oss: 0.0579 - val_acc: 0.9846
Epoch 16/20
60000/60000 [============== ] - 10s 167us/step - loss: 0.0228 - acc: 0.9929 - val 1
oss: 0.0672 - val acc: 0.9835
Epoch 17/20
60000/60000 [=============] - 10s 167us/step - loss: 0.0187 - acc: 0.9940 - val 1
oss: 0.0582 - val acc: 0.9860
Epoch 18/20
60000/60000 [=============] - 10s 167us/step - loss: 0.0206 - acc: 0.9937 - val 1
oss: 0.0606 - val acc: 0.9859
Epoch 19/20
60000/60000 [============== ] - 10s 166us/step - loss: 0.0180 - acc: 0.9941 - val 1
oss: 0.0633 - val acc: 0.9851
Epoch 20/20
60000/60000 [=============] - 10s 169us/step - loss: 0.0188 - acc: 0.9940 - val 1
oss: 0.0641 - val_acc: 0.9845
Test score: 0.06405649431259226
Test accuracy: 0.9845
```





5 layer architecture Here below we experiment with one batch-normalization and 1 drop out layer in the begining of the architecture it means after first layer with Adam optimizer

```
In [39]:
```

```
model relu3 = Sequential()
#laver-1
model relu3.add(Dense(500, activation='relu', input shape=(input dim,), kernel initializer=RandomNo
rmal(mean=0.0, stddev=0.039, seed=None)))
#adding batch normalization
model relu3.add(BatchNormalization())
#addding dropout rate
model relu3.add(Dropout(0.2))
#laver-2
model relu3.add(Dense(400, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.03
9, seed=None)))
#adding batch noramalization
#model relu3.add(BatchNormalization())
#adding drop out rate
#model relu3.add(Dropout(0.2))
#layer-3
model relu3.add(Dense(300, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.03
9, seed=None)))
#adding batch noramalization
#model relu3.add(BatchNormalization())
#adding drop out rate
#model_relu3.add(Dropout(0.2))
#laver-4
model relu3.add(Dense(200, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.03
9, seed=None)))
#adding batch noramalization
#model relu3.add(BatchNormalization())
#adding drop out rate
#model relu3.add(Dropout(0.2))
#layer-5
model relu3.add(Dense(100, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.03
9, seed=None)))
#adding batch noramalization
#model relu3.add(BatchNormalization())
#adding drop out rate
#model relu3.add(Dropout(0.2))
model relu3.add(Dense(output dim, activation='softmax'))
#print(model relu3.summary())
#using optimizer adam
model relu3.compile(optimizer='adam', loss='categorical crossentropy', metrics=['accuracy'])
history = model relu3.fit(X train, Y train, batch size=batch size, epochs=nb epoch, verbose=1, vali
dation data=(X test, Y test))
score 6 = model relu3.evaluate(X test, Y test, verbose=0)
print('Test score:', score 6[0])
print('Test accuracy:', score 6[1])
fig,ax = plt.subplots(1,1)
ax.set xlabel('epoch')
ax.set_ylabel('Categorical Crossentropy Loss')
# list of epoch numbers
x = list(range(1,nb_epoch+1))
vy = history.history['val loss']
ty = history.history['loss']
plt dynamic(x, vy, ty, ax)
plt.title('5 Layer Architecture')
plt.show()
```

```
w after = model relu3.get weights()
h1 w = w after[0].flatten().reshape(-1,1)
h2 w = w after[2].flatten().reshape(-1,1)
h3_w = w_after[4].flatten().reshape(-1,1)
h4_w = w_after[6].flatten().reshape(-1,1)
h5 w = w after[8].flatten().reshape(-1,1)
out w = w after[10].flatten().reshape(-1,1)
fig = plt.figure(figsize=(15,5))
plt.title("Weight matrices after model trained")
plt.subplot(1, 6, 1,)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h1 w,color='b')
plt.xlabel('Hidden Layer 1')
plt.subplot(1, 6, 2)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h2_w, color='r')
plt.xlabel('Hidden Layer 2 ')
plt.subplot(1, 6, 3)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h3 w, color='g')
plt.xlabel('Hidden Layer 3 ')
plt.subplot(1, 6, 4)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h4_w,color='m')
plt.xlabel('Hidden Layer 4 ')
plt.subplot(1, 6, 5)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h5 w,color='b')
plt.xlabel('Hidden Layer 5 ')
plt.subplot(1, 6, 6)
plt.title("Trained model Weights")
ax = sns.violinplot(y=out w,color='y')
plt.xlabel('Output Layer ')
plt.show()
4
Train on 60000 samples, validate on 10000 samples
Epoch 1/20
60000/60000 [============= ] - 8s 136us/step - loss: 0.2350 - acc: 0.9285 -
val loss: 0.1170 - val acc: 0.9640
Epoch 2/20
60000/60000 [============] - 6s 94us/step - loss: 0.1027 - acc: 0.9687 -
val loss: 0.0900 - val acc: 0.9729
Epoch 3/20
60000/60000 [============] - 6s 98us/step - loss: 0.0822 - acc: 0.9754 -
val loss: 0.0808 - val acc: 0.9775
Epoch 4/20
60000/60000 [============= ] - 6s 101us/step - loss: 0.0644 - acc: 0.9800 -
val loss: 0.0775 - val acc: 0.9770
Epoch 5/20
60000/60000 [============ ] - 6s 98us/step - loss: 0.0578 - acc: 0.9825 -
val loss: 0.0830 - val acc: 0.9767
Epoch 6/20
val loss: 0.0746 - val acc: 0.9776
Epoch 7/20
val loss: 0.0795 - val acc: 0.9793
Epoch 8/20
60000/60000 [============= ] - 6s 94us/step - loss: 0.0390 - acc: 0.9881 -
val loss: 0.0697 - val acc: 0.9809
```

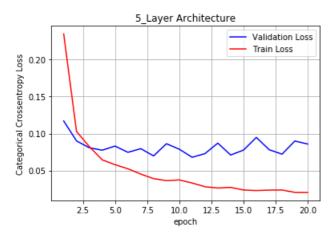
60000/60000 [=============] - 6s 96us/step - loss: 0.0363 - acc: 0.9886 -

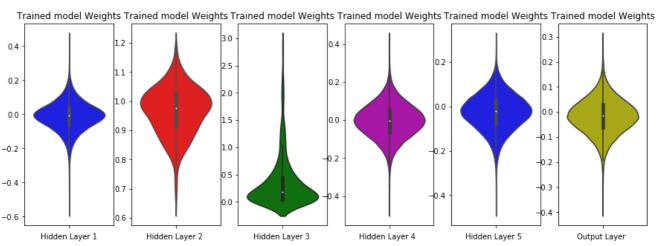
Epoch 9/20

Epoch 10/20

val_loss: 0.0862 - val_acc: 0.9757

```
60000/60000 [============] - 6s 95us/step - loss: 0.0372 - acc: 0.9885 -
val loss: 0.0788 - val acc: 0.9805
Epoch 11/20
60000/60000 [============] - 6s 93us/step - loss: 0.0330 - acc: 0.9898 -
val loss: 0.0679 - val acc: 0.9829
Epoch 12/20
60000/60000 [============ ] - 6s 94us/step - loss: 0.0280 - acc: 0.9910 -
val_loss: 0.0728 - val_acc: 0.9834
Epoch 13/20
60000/60000 [============] - 6s 95us/step - loss: 0.0262 - acc: 0.9918 -
val loss: 0.0870 - val acc: 0.9826
Epoch 14/20
60000/60000 [============= ] - 6s 95us/step - loss: 0.0271 - acc: 0.9917 -
val_loss: 0.0709 - val_acc: 0.9821
Epoch 15/20
60000/60000 [============] - 6s 95us/step - loss: 0.0236 - acc: 0.9927 -
val_loss: 0.0776 - val_acc: 0.9829
Epoch 16/20
60000/60000 [============= ] - 6s 94us/step - loss: 0.0228 - acc: 0.9929 -
val loss: 0.0948 - val acc: 0.9818
Epoch 17/20
60000/60000 [============] - 6s 94us/step - loss: 0.0234 - acc: 0.9929 -
val loss: 0.0781 - val acc: 0.9824
Epoch 18/20
val loss: 0.0721 - val acc: 0.9818
Epoch 19/20
60000/60000 [============] - 6s 96us/step - loss: 0.0204 - acc: 0.9939 -
val loss: 0.0899 - val acc: 0.9791
Epoch 20/20
val loss: 0.0857 - val acc: 0.9807
Test score: 0.08574480261191275
Test accuracy: 0.9807
```





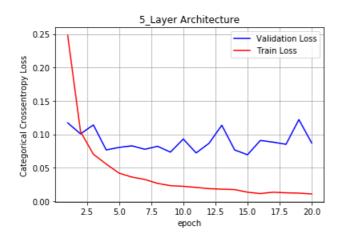
5 layer architecture Here below we experiment with one batch-normalization and 1 drop out layer in the before last layer of the architecture with Adam optimizer and drop 0.5

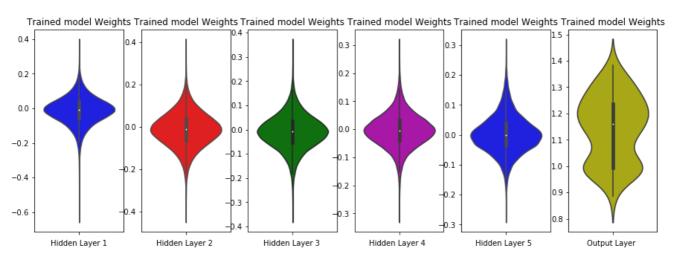
In [40]:

```
model relu3 = Sequential()
#layer-1
model relu3.add(Dense(500, activation='relu', input shape=(input dim,), kernel initializer=RandomNo
rmal(mean=0.0, stddev=0.039, seed=None)))
#adding batch normalization
#model_relu3.add(BatchNormalization())
#addding dropout rate
#model relu3.add(Dropout(0.2))
#layer-2
model relu3.add(Dense(400, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.03
9, seed=None)))
#adding batch noramalization
#model relu3.add(BatchNormalization())
#adding drop out rate
#model relu3.add(Dropout(0.2))
#laver-3
model relu3.add(Dense(300, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.03
9, seed=None)))
#adding batch noramalization
#model relu3.add(BatchNormalization())
#adding drop out rate
#model_relu3.add(Dropout(0.2))
#layer-4
model relu3.add(Dense(200, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.03
9. seed=None)))
#adding batch noramalization
#model relu3.add(BatchNormalization())
#adding drop out rate
#model relu3.add(Dropout(0.2))
#layer-5
model relu3.add(Dense(100, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.03
9, seed=None)))
#adding batch noramalization
model relu3.add(BatchNormalization())
#adding drop out rate
model relu3.add(Dropout(0.5))
model relu3.add(Dense(output dim, activation='softmax'))
#print(model relu3.summary())
#using optimizer adam
model relu3.compile(optimizer='adam', loss='categorical crossentropy', metrics=['accuracy'])
history = model relu3.fit(X train, Y train, batch size=batch size, epochs=nb epoch, verbose=1, vali
dation data=(X test, Y test))
score_6 = model_relu3.evaluate(X_test, Y_test, verbose=0)
print('Test score:', score 6[0])
print('Test accuracy:', score 6[1])
fig,ax = plt.subplots(1,1)
ax.set_xlabel('epoch')
ax.set_ylabel('Categorical Crossentropy Loss')
# list of epoch numbers
x = list(range(1, nb epoch+1))
vy = history.history['val loss']
ty = history.history['loss']
plt dynamic(x, vy, ty, ax)
plt.title('5 Layer Architecture')
plt.show()
w after = model relu3.get weights()
h1 w = w after[0].flatten().reshape(-1,1)
```

```
h2 w = w after[2].flatten().reshape(-1,1)
h3 w = w after[4].flatten().reshape(-1,1)
h4_w = w_after[6].flatten().reshape(-1,1)
h5_w = w_after[8].flatten().reshape(-1,1)
out w = w after[10].flatten().reshape(-1,1)
fig = plt.figure(figsize=(15,5))
plt.title("Weight matrices after model trained")
plt.subplot(1, 6, 1,)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h1_w,color='b')
plt.xlabel('Hidden Layer 1')
plt.subplot(1, 6, 2)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h2 w, color='r')
plt.xlabel('Hidden Layer 2 ')
plt.subplot(1, 6, 3)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h3 w, color='g')
plt.xlabel('Hidden Layer 3 ')
plt.subplot(1, 6, 4)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h4 w,color='m')
plt.xlabel('Hidden Layer 4 ')
plt.subplot(1, 6, 5)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h5 w,color='b')
plt.xlabel('Hidden Layer 5 ')
plt.subplot(1, 6, 6)
plt.title("Trained model Weights")
ax = sns.violinplot(y=out_w,color='y')
plt.xlabel('Output Layer ')
plt.show()
4
Train on 60000 samples, validate on 10000 samples
Epoch 1/20
60000/60000 [============] - 8s 133us/step - loss: 0.2481 - acc: 0.9283 -
val loss: 0.1171 - val acc: 0.9651
Epoch 2/20
60000/60000 [============= ] - 5s 89us/step - loss: 0.1040 - acc: 0.9715 -
val loss: 0.1006 - val acc: 0.9705
Epoch 3/20
60000/60000 [============] - 5s 88us/step - loss: 0.0701 - acc: 0.9800 -
val loss: 0.1140 - val acc: 0.9672
Epoch 4/20
60000/60000 [============] - 5s 90us/step - loss: 0.0554 - acc: 0.9841 -
val loss: 0.0765 - val acc: 0.9790
Epoch 5/20
val loss: 0.0803 - val acc: 0.9797
Epoch 6/20
val loss: 0.0827 - val acc: 0.9787
Epoch 7/20
60000/60000 [============ ] - 5s 89us/step - loss: 0.0324 - acc: 0.9901 -
val loss: 0.0775 - val_acc: 0.9795
Epoch 8/20
60000/60000 [============ ] - 5s 89us/step - loss: 0.0265 - acc: 0.9923 -
val loss: 0.0820 - val acc: 0.9793
Epoch 9/20
60000/60000 [=========== ] - 5s 90us/step - loss: 0.0231 - acc: 0.9935 -
val loss: 0.0733 - val acc: 0.9820
Epoch 10/20
val loss: 0.0929 - val acc: 0.9799
Epoch 11/20
60000/60000 [===========] - 5s 91us/step - loss: 0.0205 - acc: 0.9944 -
```

```
val loss: 0.0721 - val acc: 0.9828
Epoch 12/20
60000/60000 [============] - 5s 89us/step - loss: 0.0186 - acc: 0.9946 -
val loss: 0.0864 - val acc: 0.9794
Epoch 13/20
60000/60000 [============] - 5s 89us/step - loss: 0.0178 - acc: 0.9948 -
val loss: 0.1135 - val acc: 0.9725
Epoch 14/20
val loss: 0.0766 - val acc: 0.9804
Epoch 15/20
60000/60000 [============] - 5s 90us/step - loss: 0.0133 - acc: 0.9964 -
val loss: 0.0693 - val acc: 0.9838
Epoch 16/20
60000/60000 [============] - 5s 90us/step - loss: 0.0112 - acc: 0.9968 -
val loss: 0.0907 - val acc: 0.9799
Epoch 17/20
60000/60000 [============] - 5s 89us/step - loss: 0.0133 - acc: 0.9962 -
val loss: 0.0882 - val acc: 0.9805
Epoch 18/20
60000/60000 [============] - 5s 89us/step - loss: 0.0123 - acc: 0.9968 -
val_loss: 0.0850 - val_acc: 0.9818
Epoch 19/20
val_loss: 0.1220 - val_acc: 0.9759
Epoch 20/20
60000/60000 [============] - 5s 89us/step - loss: 0.0107 - acc: 0.9969 -
val loss: 0.0869 - val acc: 0.9829
Test score: 0.08687413363270534
Test accuracy: 0.9829
```





In [44]:

```
from prettytable import PrettyTable
x = PrettyTable()
```

```
x.field names = ["Layer ", "Test Score", "Test Accuracy", "Epoch", "Drop Outrate", "Optimizer", "ACtiv
ation", "Drop out + Normalization Layers", "Test performance"]
                                         "ReLu","Every","good"])
"ReLu","None","Not-good"])
x.add row(["2", 0.057, 0.98,20, 0.5,"ADAM",
x.add_row(["2", 0.10, 0.98,20, 0.5,"ADAM", "ReLu","None","Not-good"])
x.add_row(["2", 0.062, 0.98,20, 0.2,"Ada_delta","ReLu","Every","Not-good"])
print(x)
x2 = PrettyTable()
x2.field names = ["Layer ","Test Score", "Test Accuracy", "Epoch", "Drop Outrate", "Optimizer", "ACti
vation","Drop out + Normalization Layers","Test performance"]
                                            "ReLu", "Every", "good"])
"ReLu", "None", "Not-good"])
x2.add_row(["3", 0.050, 0.98,20, 0.5,"ADAM",
x2.add_row(["3", 0.091, 0.98,20, 0.5,"ADAM", "ReLu","None","Not-good"])
x2.add_row(["3", 0.059, 0.98,20, 0.2,"Ada_delta","ReLu","Every","Not-good"])
x2.add_row(["3", 0.058, 0.98,20, 0.5,"ADAM", "ReLu","First","Not-good"])
x2.add_row(["3", 0.066, 0.98,20, 0.5,"ADAM", "ReLu","Last","Not-good"])
x2.add_row(["3", 0.066, 0.98,20, 0.5,"ADAM",
print(x2)
x3 = PrettvTable()
x3.field names = ["Layer ","Test Score", "Test Accuracy", "Epoch", "Drop Outrate", "Optimizer", "ACti
vation","Drop out + Normalization Layers","Test performance"]
x3.add_row(["5", 0.066, 0.98,20, 0.5,"ADAM", "ReLu","Every","good"])
x3.add_row(["5", 0.088, 0.98,20, 0.5,"ADAM", "ReLu","None","Not-good"])
x3.add row(["5", 0.064, 0.98,20, 0.2,"Ada delta","ReLu","Every","Not-good"])
x3.add_row(["5", 0.085, 0.98,20, 0.5,"ADAM", "ReLu","First","Not-good"])
x3.add_row(["5", 0.086, 0.98,20, 0.5,"ADAM", "ReLu","Last","Not-good"])
print(x3)
                                       | Layer | Test Score | Test Accuracy | Epoch | Drop Outrate | Optimizer | ACtivation | Drop out +
Normalization Layers | Test performance |
| 2 | 0.057 | 0.98
                                  | 20 |
                                               0.5
                                                       | ADAM | ReLu
            | good
0.1 | 0.98
| Not-good
                                  Everv
           0.1
                                      20 |
                                                0.5 | ADAM |
                                                                         ReLu
| 2
                                   Not-good
None
        | 0.062 | 0.98
| 2
                                  | 20 |
                                               0.2
                                                        | Ada delta | ReLu
                     Not-good
       | 0.054 | 0.98
                                  | 20 |
                                               0.5
                                                        | ADAM |
                                                                         ReTu
                                                                                 1
1 2
                                  İ
First
                 Not-good
            ....|
|---
                       0.98
       0.093
                                                        20 |
                                                           ADAM |
                                               0.5
1 2
                                   ReLu
                                                                                 Not-good
| Layer | Test_Score | Test_Accuracy | Epoch | Drop_Outrate | Optimizer | ACtivation | Drop_out +
Normalization Layers | Test performance |
+----
                                         __+____
3 | 0.05 | 0.98
                                      20 |
                                               0.5
                                  - 1
                                                        | ADAM |
                                                                         ReLu
       | good
| 0.091 | 0.98
Every
                                   20 |
                                                        | ADAM | ReLu
1 3
                                               0.5
None
            Not-good
1 3
        | 0.059 | 0.98
                                     20 I
                                                0.2
                                                        | Ada_delta | ReLu
                                   1
Every
                       Not-good
                                   - [
           0.058
                       0.98
                                      20 |
                                                0.5
                                                             ADAM
1 3
                                   ReLu
                       Not-good
First
                                   | 0.066 | 0.98
| 3
                                  20 |
                                               0.5
                                                        | ADAM | ReLu
                                                                                 1
           | Not-good
Last
                                 -----+
```

		+		+						
5	1	0.066	0.9	В	20	0.5		ADAM	ReLu	I
very		1	good	1						
5		0.088	0.9	В	20	0.5	- 1	ADAM	ReLu	I
one		1	Not-good							
5		0.064	0.9	В	20	0.2	1	Ada delta	ReLu	I
very		1	Not-goo	d l						
5		0.085	0.9	В	20	0.5	- 1	ADAM	ReLu	I
irst		1	Not-goo	d l						
5		0.086	0.9	В	20	0.5	1	ADAM	ReLu	1
ast		1	Not-good							

Observations

- 1. Applied Various Level Architectures (2,3,5) for observing the model performance using MNIST data
- 2. Applied models with and with out Batch Normalization and Drop_out rate
- 3. Models with batch normalization and dropuout rate gives better results compare to without apply
- 4. For all models we get same kind of accuracy but difference occur at test_loss i.e, with-out batch models we got test-loss > train loss leads to bad model performance
- 5. We use Constant drop out rate, we may get good results with opitmal drop-out rate and optimal layers by doing some hyper parameter tuning for drop-out and no of layers and no of neurons per layers
- 6. We get similar performance for 2,3,5 architectures with batch normalization and drop-out rate 3 layer architecture gives smoother curve at test loss compare to 2,5 architectures
- 7. If we observe above tables model with batch-normalization and drop-out 0.5 at every layers model gives good performance
- 8. If we took low drop-rate and high drop rate with out batch normalization model performance is not good observe the above error plots for every model observe the difference
- 9. Models with batch-normalization and drop-out rate 0.5 at every layers gives similar performance which is good 3 layer architecture gives good performance because it converges with train loss means training and validation performs well