```
In [1]:
```

```
from google.colab import drive
drive.mount('/content/gdrive')
```

Go to this URL in a browser: https://accounts.google.com/o/oauth2/auth?client_id=947318989803-6bn6 qk8qdgf4n4g3pfee6491hc0brc4i.apps.googleusercontent.com&redirect_uri=urn%3Aietf%3Awg%3Aoauth%3A2.0% b&scope=email%20https%3A%2F%2Fwww.googleapis.com%2Fauth%2Fdocs.test%20https%3A%2F%2Fwww.googleapis.2Fauth%2Fdrive%20https%3A%2F%2Fwww.googleapis.com%2Fauth%2Fdrive.photos.readonly%20https%3A%2F%2Fwww.googleapis.com%2Fauth%2Fdrive.photos.readonly%20https%3A%2F%2Fwww.googleapis.com%2Fauth%2Fdrive.photos.readonly%20https%3A%2F%2Fwww.googleapis.com%2Fauth%2Fdrive.photos.readonly%20https%3A%2F%2Fwww.googleapis.com%2Fauth%2Fdrive.photos.readonly%20https%3A%2F%2Fwww.googleapis.com%2Fauth%2Fdrive.photos.readonly%20https%3A%2F%2Fwww.googleapis.com%2Fauth%2Fdrive.photos.readonly%20https%3A%2F%2Fwww.googleapis.com%2Fauth%2Fdrive.photos.readonly%20https%3A%2F%2Fwww.googleapis.com%2Fauth%2Fdrive.photos.readonly%20https%3A%2F%2Fwww.googleapis.com%2Fauth%2Fdrive.photos.readonly%20https%3A%2F%2Fwww.googleapis.com%2Fauth%2Fdrive.photos.readonly%20https%3A%2F%2Fwww.googleapis.com%2Fauth%2Fdrive.photos.readonly%20https%3A%2F%2Fwww.googleapis.com%2Fauth%2Fdrive.photos.readonly%20https%3A%2F%2Fwww.googleapis.com%2Fauth%2Fdrive.photos.readonly%20https%3A%2F%2Fwww.googleapis.com%2Fauth%2Fdrive.photos.readonly%20https%3A%2F%2Fwww.googleapis.com%2Fauth%2Fdrive.photos.readonly%20https%3A%2F%2Fwww.googleapis.com%2Fauth%2Fdrive.photos.readonly%20https%3A%2F%2Fwww.googleapis.com%2Fauth%2Fdrive.photos.readonly%20https%3A%2F%2Fwww.googleapis.com%2Fauth%2Fdrive.photos.readonly%20https%3A%2F%2Fwww.googleapis.com%2Fauth%2Fdrive.photos.readonly%20https%3A%2F%2Fwww.googleapis.com%2Fauth%2Fdrive.photos.readonly%20https%3A%2F%2Fwww.googleapis.com%2Fauth%2Fdrive.photos.readonly%20https%3A%2F%2Fwww.googleapis.com%2Fauth%2Fdrive.photos.readonly%20https%3A%2F%2Fwww.googleapis.com%2Fauth%2Fdrive.photos.readonly%20https%3A%2F%2Fwww.googleapis.com%2Fauth%2Fdrive.photos.photos.photos.photos.photos.photos.photos.photos.photos.photos.photos.photos.photos.photos.p

Enter your authorization code:
......
Mounted at /content/gdrive

.....

In [0]:

```
import pandas as pd
import numpy as np
import itertools
import numpy as np
import matplotlib.pyplot as plt
from sklearn.metrics import confusion_matrix
import matplotlib.pyplot as plt
import seaborn as sns
```

In [0]:

```
# Activities are the class labels
# It is a 6 class classification
ACTIVITIES = {
   0: 'WALKING',
   1: 'WALKING UPSTAIRS',
   2: 'WALKING DOWNSTAIRS',
   3: 'SITTING',
   4: 'STANDING',
   5: 'LAYING',
# Utility function to print the confusion matrix
def confusion matrix(Y true, Y pred):
   Y_true = pd.Series([ACTIVITIES[y] for y in np.argmax(Y_true, axis=1)])
   Y_pred = pd.Series([ACTIVITIES[y] for y in np.argmax(Y_pred, axis=1)])
   return pd.crosstab(Y_true, Y_pred, rownames=['True'], colnames=['Pred'])
def plot confusion matrix(cm, classes,
                          normalize=False.
                          title='Confusion matrix',
                          cmap=plt.cm.Blues):
   if normalize:
       cm = cm.astype('float') / cm.sum(axis=1)[:, np.newaxis]
   plt.imshow(cm, interpolation='nearest', cmap=cmap)
   plt.title(title)
   plt.colorbar()
   tick marks = np.arange(len(classes))
   plt.xticks(tick marks, classes, rotation=90)
   plt.yticks(tick marks, classes)
   fmt = '.2f' if normalize else 'd'
   thresh = cm.max() / 2.
   for i, j in itertools.product(range(cm.shape[0]), range(cm.shape[1])):
       plt.text(j, i, format(cm[i, j], fmt),
                 horizontalalignment="center",
                 color="white" if cm[i, j] > thresh else "black")
   plt.tight_layout()
   plt.ylabel('True label')
   nlt vlahel ('Predicted lahel')
```

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Data

```
In [0]:
```

```
# Data directory
DATADIR = 'gdrive/My Drive/HAR/UCI_HAR_Dataset'
```

In [0]:

```
# Raw data signals
# Signals are from Accelerometer and Gyroscope
# The signals are in x,y,z directions
# Sensor signals are filtered to have only body acceleration
# excluding the acceleration due to gravity
# Triaxial acceleration from the accelerometer is total acceleration
SIGNALS = [
   "body_acc_x",
   "body_acc_y",
   "body_acc_z",
   "body_gyro_x",
    "body_gyro_y",
   "body_gyro_z",
   "total_acc_x",
   "total acc y",
    "total_acc_z"
1
```

In [0]:

```
\# Utility function to read the data from csv file
def read csv(filename):
   return pd.read csv(filename, delim whitespace=True, header=None)
# Utility function to load the load
def load signals(subset):
   signals data = []
   for signal in SIGNALS:
       filename = f'gdrive/My Drive/HAR/UCI HAR Dataset/{subset}/Inertial
Signals/{signal} {subset}.txt'
       signals_data.append(
            _read_csv(filename).as matrix()
       )
    # Transpose is used to change the dimensionality of the output,
    # aggregating the signals by combination of sample/timestep.
   # Resultant shape is (7352 train/2947 test samples, 128 timesteps, 9 signals)
   return np.transpose(signals data, (1, 2, 0))
```

In [0]:

```
def load_y(subset):
    """
    The objective that we are trying to predict is a integer, from 1 to 6,
    that represents a human activity. We return a binary representation of
    every sample objective as a 6 bits vector using One Hot Encoding
    (https://pandas.pydata.org/pandas-docs/stable/generated/pandas.get_dummies.html)
    """
    filename = f'gdrive/My Drive/HAR/UCI_HAR_Dataset/{subset}/y_{subset}.txt'
    y = _read_csv(filename)[0]
    return pd.get_dummies(y).as_matrix()
```

In [0]:

```
def load_data():
    """
    Obtain the dataset from multiple files.
    Returns: X_train, X_test, y_train, y_test
```

```
X train, X test = load signals('train'), load signals('test')
    y_train, y_test = load_y('train'), load_y('test')
    return X train, X test, y train, y test
In [0]:
# Importing tensorflow
np.random.seed (42)
import tensorflow as tf
tf.set random seed(42)
In [0]:
# Configuring a session
session conf = tf.ConfigProto(
  intra op parallelism threads=1,inter op parallelism threads=1)
In [11]:
#Import Keras
from keras import backend as K
sess = tf.Session(graph=tf.get default graph(), config=session conf)
K.set session(sess)
Using TensorFlow backend.
In [0]:
# Importing libraries
from keras.models import Sequential
from keras.layers import LSTM
from keras.layers.core import Dense, Dropout
from keras.layers.normalization import BatchNormalization
In [0]:
# Initializing parameters
base epochs = 30
base batch size = 32
base_n_hidden = 64
In [0]:
# Utility function to count the number of classes
def _count_classes(y):
    return len(set([tuple(category) for category in y]))
In [15]:
# Loading the train and test data
X_train, X_test, Y_train, Y_test = load_data()
/usr/local/lib/python3.6/dist-packages/ipykernel launcher.py:11: FutureWarning: Method .as matrix
will be removed in a future version. Use .values instead.
  # This is added back by InteractiveShellApp.init path()
In [16]:
timesteps = len(X_train[0])
input_dim = len(X_train[0][0])
n_classes = _count_classes(Y_train)
print(timesteps)
print(input dim)
print(len(X_train))
```

128 9 7352

LSTM_ Base_ Model

```
In [0]:
```

```
# Initiliazing the sequential model
model = Sequential()
# Configuring the parameters
model.add(LSTM(base_n_hidden, input_shape=(timesteps, input_dim)))
#adding a batch normalization layer
model.add(BatchNormalization())
 # Adding a dropout layer
model.add(Dropout(0.4))
 # Adding a dense output layer with sigmoid activation
model.add(Dense(n classes, activation='softmax'))
model.summary()
WARNING:tensorflow:From /usr/local/lib/python3.6/dist-
packages/keras/backend/tensorflow backend.py:66: The name tf.get default graph is deprecated. Plea
se use tf.compat.v1.get_default_graph instead.
WARNING:tensorflow:From /usr/local/lib/python3.6/dist-
packages/keras/backend/tensorflow backend.py:541: The name tf.placeholder is deprecated. Please us
e tf.compat.v1.placeholder instead.
WARNING:tensorflow:From /usr/local/lib/python3.6/dist-
packages/keras/backend/tensorflow backend.py:4432: The name tf.random uniform is deprecated. Pleas
e use tf.random.uniform instead.
WARNING:tensorflow:From /usr/local/lib/python3.6/dist-
\verb|packages/keras/backend/tensorflow_backend.py:148: The name tf.placeholder_with_default is a constant of the control of the
deprecated. Please use tf.compat.v1.placeholder with default instead.
WARNING:tensorflow:From /usr/local/lib/python3.6/dist-
packages/keras/backend/tensorflow backend.py:3733: calling dropout (from
tensorflow.python.ops.nn ops) with keep prob is deprecated and will be removed in a future
version.
Instructions for updating:
Please use `rate` instead of `keep_prob`. Rate should be set to `rate = 1 - keep_prob`.
Model: "sequential 1"
                                                           Output Shape
Layer (type)
                                                                                                                 Param #
lstm 1 (LSTM)
                                                           (None, 64)
                                                                                                                18944
batch normalization 1 (Batch (None, 64)
                                                                                                                 256
dropout 1 (Dropout)
                                                            (None, 64)
dense 1 (Dense)
                                                            (None, 6)
______
Total params: 19,590
Trainable params: 19,462
Non-trainable params: 128
```

In [0]:

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/optimizers.py:793: The name t f.train.Optimizer is deprecated. Please use tf.compat.v1.train.Optimizer instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow_backend.py:3576: The name tf.log is deprecated. Please use tf.ma th.log instead.

```
In [0]:
```

```
%%time
# Training the model
model.fit(X train,
     Y train,
     batch_size=32,
     validation data=(X test, Y test),
     epochs=10)
WARNING:tensorflow:From /usr/local/lib/python3.6/dist-
packages/tensorflow/python/ops/math grad.py:1250: add dispatch support.<locals>.wrapper (from
tensorflow.python.ops.array ops) is deprecated and will be removed in a future version.
Instructions for updating:
Use tf.where in 2.0, which has the same broadcast rule as np.where
Train on 7352 samples, validate on 2947 samples
Epoch 1/10
0.7335 - val acc: 0.7021
Epoch 2/10
0.6607 - val acc: 0.8008
Epoch 3/10
0.9312 - val acc: 0.7754
Epoch 4/10
0.4118 - val acc: 0.8850
Epoch 5/10
0.3271 - val acc: 0.8924
Epoch 6/10
0.3125 - val acc: 0.8938
Epoch 7/10
0.3015 - val acc: 0.8843
Epoch 8/10
0.3354 - val acc: 0.8921
Epoch 9/10
0.3122 - val acc: 0.9226
Epoch 10/10
0.2675 - val acc: 0.9104
CPU times: user 11min 1s, sys: 38.8 s, total: 11min 40s
Wall time: 10min 1s
Out[0]:
<keras.callbacks.History at 0x7fe6010ddd68>
In [0]:
score = model.evaluate(X test, Y test, verbose=0)
print('Test loss:', score[0])
print('Test accuracy:', score[1]*100)
Test loss: 0.2675111037987024
Test accuracy: 91.04173736002714
```

In [0]:

```
#train_data
X_train=X_train[:6000]
Y_train=Y_train[:6000]
#cv_data
X_cv=X_train[:1352]
Y_cv=Y_train[:1352]
```

```
In [0]:
print(X train.shape, Y train.shape)
print(X cv.shape, Y cv.shape)
print(X test.shape, Y test.shape)
(6000, 128, 9) (6000, 6)
(1352, 128, 9) (1352, 6)
(2947, 128, 9) (2947, 6)
In [0]:
np.save("gdrive/My Drive/HAR/x train", X train)
np.save("gdrive/My Drive/HAR/y train",Y train)
np.save("gdrive/My Drive/HAR/x_cv", X_cv)
np.save("gdrive/My Drive/HAR/y_cv",Y_cv)
np.save("gdrive/My Drive/HAR/x test", X test)
np.save("gdrive/My Drive/HAR/y_test",Y_test)
In [0]:
X train=np.load('gdrive/My Drive/HAR/x train.npy')
Y train=np.load('gdrive/My Drive/HAR/y train.npy')
X cv=np.load('gdrive/My Drive/HAR/x cv.npy')
Y_cv=np.load('gdrive/My Drive/HAR/y_cv.npy')
X test=np.load('gdrive/My Drive/HAR/x test.npy')
Y test=np.load('gdrive/My Drive/HAR/y test.npy')
In [0]:
lstms = [12, 36, 64]
train_lstms_loss = []
cv lstms loss = []
for i in lstms:
 model = Sequential()
 model.add(LSTM(i, input shape=(timesteps, input dim)))
 model.add(BatchNormalization())
 model.add(Dropout(0.5))
 model.add(Dense(n classes, activation='softmax'))
 model.compile(loss='categorical crossentropy',optimizer='RMSprop',metrics=['accuracy'])
 model.fit(X train,Y train,batch size=32,validation data=(X cv, Y cv),epochs=10,verbose=0)
 train_score = model.evaluate(X_train, Y_train,verbose=0)
 train_lstms_loss.append(train_score)
 test score = model.evaluate(X cv, Y cv,verbose=0)
 cv_lstms_loss.append(test_score)
______")
 print("for lstm
cells",i,"train loss:",train score[0],"train acc:",train score[1],"cv loss:",test score[0],"cv acc:
",test_score[1])
print("-----
4
                                                                               Þ
for 1stm cells 12 train loss: 0.5427719736178793 train acc: 0.7983333333333333 cv loss:
0.5774555450977659 cv acc: 0.7943786982248521
______
_____
for lstm cells 36 train_loss: 0.1419026134143011 train_acc: 0.948 cv_loss: 0.1471664534554336
cv_acc: 0.9312130177514792
______
_____
```

```
_____
for 1stm cells 64 train loss: 0.15687254037896248 train acc: 0.945666666666667 cv loss:
0.1529195671973436 cv acc: 0.9304733727810651
4
In [0]:
train dropout loss = []
cv dropout loss = []
dropouts = [0.2, 0.4, 0.6, 0.9]
for i in dropouts:
 model = Sequential()
 model.add(LSTM(64, input shape=(timesteps, input dim)))
 model.add(BatchNormalization())
 model.add(Dropout(i))
 model.add(Dense(n classes, activation='softmax'))
 model.compile(loss='categorical_crossentropy',optimizer='RMSprop',metrics=['accuracy'])
 model.fit(X train,Y train,batch size=32,validation data=(X cv, Y cv),epochs=10,verbose=0)
 train_score = model.evaluate(X_train, Y_train,verbose=0)
 train dropout loss.append(train score[0])
 test score = model.evaluate(X cv, Y cv,verbose=0)
 cv_dropout_loss.append(test_score[0])
----")
 print("for
dropout",i, "train_loss:",train_score[0], "train_acc:",train_score[1], "cv_loss:",test_score[0], "cv_ac
c:",test_score[1])
_______
_____
for dropout 0.2 train_loss: 0.09121699480417676 train_acc: 0.9618333333333333 cv_loss:
0.08054623748949032 cv_acc: 0.9556213017751479
______
_____
______
for dropout 0.4 train loss: 0.2927109430801174 train acc: 0.9185 cv loss: 0.22138404586332894 cv a
cc: 0.9408284023668639
______
_____
WARNING:tensorflow:Large dropout rate: 0.6 (>0.5). In TensorFlow 2.x, dropout() uses dropout rate
instead of keep prob. Please ensure that this is intended.
______
_____
for dropout 0.6 train loss: 0.2663697602033571 train acc: 0.9165 cv loss: 0.2898362064807076
cv acc: 0.915680473372781
------
_____
WARNING:tensorflow:Large dropout rate: 0.9 (>0.5). In TensorFlow 2.x, dropout() uses dropout rate
instead of keep prob. Please ensure that this is intended.
______
for dropout 0.9 train loss: 0.4850111870571758 train acc: 0.8276666666666667 cv loss:
0.42911438657158224 cv_acc: 0.8461538461538461
_____
In [0]:
train opt loss = []
cv_opt_loss = []
optimizers = ['RMSprop','Adadelta','Adam']
for i in optimizers:
 model = Sequential()
 model.add(LSTM(64, input_shape=(timesteps, input_dim)))
```

model.add(BatchNormalization())

model.add(Dropout(0.2))

```
model.add(Dense(n classes, activation='softmax'))
 model.compile(loss='categorical crossentropy',optimizer=i,metrics=['accuracy'])
 model.fit(X train,Y train,batch size=32,validation data=(X cv, Y cv),epochs=10,verbose=0)
 train score = model.evaluate(X train, Y train, verbose=0)
 train opt loss.append(train score[0])
 test score = model.evaluate(X cv, Y cv,verbose=0)
 cv opt loss.append(test score[0])
_____")
 print("for optimizer
",i,"train_loss:",train_score[0],"train_acc:",train_score[1],"cv_loss:",test_score[0],"cv_acc:",tes
t_score[1])
______
_____
for optimizer RMSprop train loss: 0.09372042466270614 train acc: 0.9646666666666667 cv loss:
0.08798773764093963 cv_acc: 0.9563609467455622
______
_____
_____
for optimizer Adadelta train loss: 0.10666192313204859 train acc: 0.9461666666666667 cv loss: 0.0
923617873280571 cv acc: 0.9571005917159763
______
_____
______
_____
for optimizer Adam train_loss: 0.09250945657089081 train_acc: 0.964166666666666 cv_loss:
0.08666882475565281 cv acc: 0.9548816568047337
______
_____
4
In [0]:
model = Sequential()
model.add(LSTM(64, input shape=(timesteps, input dim)))
model.add(BatchNormalization())
model.add(Dropout(0.2))
model.add(Dense(n classes, activation='softmax'))
model.compile(loss='categorical_crossentropy',optimizer='RMSprop',metrics=['accuracy'])
model.fit(X train,Y train,batch size=32,validation data=(X test, Y test),epochs=20,verbose=1)
score = model.evaluate(X_test, Y_test,verbose=0)
print('Test loss:', score[0])
print('Test accuracy:', score[1]*100)
Train on 6000 samples, validate on 2947 samples
Epoch 1/20
6000/6000 [============] - 57s 10ms/step - loss: 0.7780 - acc: 0.6847 - val loss
: 0.9274 - val acc: 0.7065
Epoch 2/20
1.0003 - val_acc: 0.6176
Epoch 3/20
0.4645 - val acc: 0.8490
Epoch 4/20
6000/6000 [============= ] - 49s 8ms/step - loss: 0.1943 - acc: 0.9327 - val loss:
1.4064 - val acc: 0.7598
Epoch 5/20
6000/6000 [============= ] - 49s 8ms/step - loss: 0.1708 - acc: 0.9363 - val loss:
0.2106 - val acc: 0.9179
Epoch 6/20
6000/6000 [============= ] - 49s 8ms/step - loss: 0.1470 - acc: 0.9448 - val loss:
0.2387 - val acc: 0.9223
Epoch 7/20
0.3111 - val acc: 0.9026
Epoch 8/20
0.3288 - val acc: 0.9118
Epoch 9/20
```

```
6000/6000 [============== ] - 49s 8ms/step - loss: 0.1201 - acc: 0.9497 - val loss:
0.3280 - val acc: 0.9148
Epoch 10/20
6000/6000 [============= ] - 49s 8ms/step - loss: 0.1259 - acc: 0.9535 - val loss:
0.3860 - val acc: 0.9063
Epoch 11/20
6000/6000 [============= ] - 49s 8ms/step - loss: 0.1137 - acc: 0.9552 - val loss:
0.4017 - val acc: 0.9043
Epoch 12/20
6000/6000 [============= ] - 49s 8ms/step - loss: 0.1108 - acc: 0.9550 - val loss:
0.3834 - val acc: 0.9162
Epoch 13/20
0.3190 - val_acc: 0.9077
Epoch 14/20
0.3842 - val_acc: 0.9135
Epoch 15/20
6000/6000 [============= ] - 49s 8ms/step - loss: 0.1084 - acc: 0.9550 - val loss:
0.4441 - val acc: 0.9080
Epoch 16/20
6000/6000 [============= ] - 49s 8ms/step - loss: 0.1154 - acc: 0.9558 - val loss:
0.4180 - val_acc: 0.9026
Epoch 17/20
0.4901 - val_acc: 0.8996
Epoch 18/20
6000/6000 [============ ] - 50s 8ms/step - loss: 0.1067 - acc: 0.9577 - val loss:
0.4419 - val acc: 0.9077
Epoch 19/20
0.7073 - val acc: 0.8941
Epoch 20/20
6000/6000 [============= ] - 50s 8ms/step - loss: 0.1034 - acc: 0.9562 - val loss:
0.3852 - val acc: 0.9145
Test loss: 0.38519705226556006
Test accuracy: 91.44893111638956
In [0]:
model = Sequential()
model.add(LSTM(64, input shape=(timesteps, input dim),return sequences=True))
model.add(BatchNormalization())
model.add(Dropout(0.2))
model.add(LSTM(128))
model.add(BatchNormalization())
model.add(Dropout(0.4))
model.add(Dense(n_classes, activation='softmax'))
model.compile(loss='categorical crossentropy',optimizer='RMSprop',metrics=['accuracy'])
model.fit(X train,Y train,batch size=32,validation data=(X test, Y test),epochs=20,verbose=1)
score = model.evaluate(X_test, Y_test, verbose=0)
print('Test loss:', score[0])
print('Test accuracy:', score[1]*100)
Train on 6000 samples, validate on 2947 samples
Epoch 1/20
s: 1.9998 - val acc: 0.6179
Epoch 2/20
: 0.5322 - val acc: 0.8768
Epoch 3/20
6000/6000 [============ ] - 98s 16ms/step - loss: 0.1426 - acc: 0.9450 - val loss
: 0.4220 - val_acc: 0.8938
Epoch 4/20
6000/6000 [============ ] - 97s 16ms/step - loss: 0.1465 - acc: 0.9477 - val loss
: 0.2921 - val acc: 0.9189
Epoch 5/20
6000/6000 [============== ] - 97s 16ms/step - loss: 0.1209 - acc: 0.9503 - val loss
: 0.3555 - val acc: 0.9006
Epoch 6/20
6000/6000 [============= ] - 98s 16ms/step - loss: 0.1279 - acc: 0.9492 - val loss
: 0.4008 - val_acc: 0.9006
Epoch 7/20
6000/6000 [============= ] - 98s 16ms/step - loss: 0.1165 - acc: 0.9545 - val loss
```

0 0105

```
: U.4223 - val acc: U.9135
Epoch 8/20
6000/6000 [=============== ] - 97s 16ms/step - loss: 0.1215 - acc: 0.9515 - val loss
: 0.4944 - val acc: 0.9121
Epoch 9/20
6000/6000 [============== ] - 98s 16ms/step - loss: 0.1096 - acc: 0.9523 - val loss
: 0.3731 - val acc: 0.9152
Epoch 10/20
: 0.2140 - val_acc: 0.9325
Epoch 11/20
6000/6000 [============== ] - 96s 16ms/step - loss: 0.1070 - acc: 0.9530 - val loss
: 0.4739 - val acc: 0.9097
Epoch 12/20
: 0.9212 - val acc: 0.8378
Epoch 13/20
6000/6000 [============= ] - 97s 16ms/step - loss: 0.1084 - acc: 0.9577 - val loss
: 0.2648 - val acc: 0.9063
Epoch 14/20
: 0.6211 - val acc: 0.8714
Epoch 15/20
6000/6000 [============ ] - 98s 16ms/step - loss: 0.1054 - acc: 0.9553 - val loss
: 0.3850 - val acc: 0.9002
Epoch 16/20
6000/6000 [============== ] - 96s 16ms/step - loss: 0.1110 - acc: 0.9538 - val loss
: 0.3388 - val acc: 0.9196
Epoch 17/20
6000/6000 [============= ] - 97s 16ms/step - loss: 0.1026 - acc: 0.9537 - val loss
: 0.2729 - val acc: 0.9084
Epoch 18/20
: 0.2615 - val acc: 0.9203
Epoch 19/20
: 0.2883 - val acc: 0.9080
Epoch 20/20
: 0.2172 - val acc: 0.9369
Test loss: 0.21721666411171675
Test accuracy: 93.68849677638276
```

- 1.By using LSTM 2 layer architecture we got 93% model accuracy so by refering this paper we use a divide and conquer apporach to get some more accuracy than LSTM models Refer: https://www.ncbi.nlm.nih.gov/pmc/articles/PMC5949027/
- 2.So we splitting the data into 2 models one model contains 3 class labels and another contains another 3 class labels like 'STANDING,SITTING,LYING' consider as one model called static model and 'WALKING UPSTSAIRS,WALKING DOWNSTAIRS,WALKING' as another model called dynamic model
- 3. First we create a binary model i.e.., we set >3 class labels as 1 and < 3 class labels as 0
- 4.second we create a model for > 3 class labels and predict also called as static model
- 5. Third we create a model for < 3 class labels and predict also called as dynamic model

Refer the above paper for to get some more better understading the way of implementation

Binary model

```
In [17]:
```

```
#https://github.com/UdiBhaskar/Human-Activity-Recognition--Using-Deep-
NN/blob/master/Human%20Activity%20Detection-Without%20Verbose%20.ipynb
# Data directory
DATADIR = 'gdrive/My Drive/HAR/UCI_HAR_Dataset'

# Raw data signals
# Signals are from Accelerometer and Gyroscope
# The signals are in x,y,z directions
# Sensor signals are filtered to have only body acceleration
# excluding the acceleration due to gravity
# Triaxial acceleration from the accelerometer is total acceleration
SIGNALS = [
```

```
"body acc x",
    "body_acc_y",
    "body_acc_z",
    "body gyro x",
    "body_gyro_y",
    "body_gyro_z",
    "total acc x",
    "total_acc_y",
    "total acc z"
# Utility function to read the data from csv file
def _read_csv(filename):
   return pd.read csv(filename, delim whitespace=True, header=None)
# Utility function to load the load
def load signals(subset):
   signals_data = []
    for signal in SIGNALS:
        filename = f'gdrive/My Drive/HAR/UCI HAR Dataset/{subset}/Inertial
Signals/{signal} {subset}.txt
       signals data.append(
            read csv(filename).as matrix()
    # Transpose is used to change the dimensionality of the output,
    # aggregating the signals by combination of sample/timestep.
    # Resultant shape is (7352 train/2947 test samples, 128 timesteps, 9 signals)
    return np.transpose(signals_data, (1, 2, 0))
def load_y(subset):
    The objective that we are trying to predict is a integer, from 1 to 6,
    that represents a human activity. We return a binary representation of
    every sample objective as a 6 bits vector using One Hot Encoding
    (https://pandas.pydata.org/pandas-docs/stable/generated/pandas.get dummies.html)
    filename = f'gdrive/My Drive/HAR/UCI HAR Dataset/{subset}/y {subset}.txt'
    y = read csv(filename)[0]
    y[y \le 3] = 0 #here we scaling y_{class} labels 1,2,3 as 0
    y[y>3] = 1 #here we scaling y class labels 4,5,6 as 1
    return pd.get_dummies(y).as_matrix()
def load data():
    Obtain the dataset from multiple files.
    Returns: X_train, X_test, y_train, y_test
    X train, X test = load signals('train'), load signals('test')
    y_train, y_test = load_y('train'), load_y('test')
    return X train, X test, y train, y test
# Loading the train and test data
X train bin, X test bin, Y train bin, Y test bin = load data()
/usr/local/lib/python3.6/dist-packages/ipykernel_launcher.py:32: FutureWarning: Method .as_matrix
will be removed in a future version. Use .values instead.
/usr/local/lib/python3.6/dist-packages/ipykernel launcher.py:52: FutureWarning: Method .as matrix
will be removed in a future version. Use .values instead.
In [0]:
```

```
from keras.layers.convolutional import Conv1D
from keras.layers.convolutional import MaxPooling1D
from keras.layers import Dense
from keras.layers import Flatten
```

In [23]:

```
binary_model = Sequential()
binary_model.add(Conv1D(filters=64, kernel_size=3, activation='relu', kernel_initializer='he_uniform
```

```
',input_shape=(timesteps, input_dim)))
binary_model.add(BatchNormalization())
binary_model.add(Dropout(0.5))
binary_model.add(Conv1D(filters=32, kernel_size=3, activation='relu',kernel_initializer='he_uniform
'))
binary_model.add(BatchNormalization())
binary_model.add(Dropout(0.5))
binary_model.add(MaxPooling1D(pool_size=2))
binary_model.add(Flatten())
binary_model.add(Dense(2, activation='softmax'))
binary_model.summary()
```

Model: "sequential 2"

Layer (type)	Output	Shape	Param #
conv1d_3 (Conv1D)	(None,	126, 64)	1792
batch_normalization_3 (Batch	(None,	126, 64)	256
dropout_3 (Dropout)	(None,	126, 64)	0
conv1d_4 (Conv1D)	(None,	124, 32)	6176
batch_normalization_4 (Batch	(None,	124, 32)	128
dropout_4 (Dropout)	(None,	124, 32)	0
max_pooling1d_2 (MaxPooling1	(None,	62, 32)	0
flatten_2 (Flatten)	(None,	1984)	0
dense 2 (Dense)	(None,	2)	3970

Total params: 12,322 Trainable params: 12,130 Non-trainable params: 192

In [25]:

```
binary_model.compile(loss='categorical_crossentropy', optimizer='Adam', metrics=['accuracy'])
binary_model.fit(X_train_bin,Y_train_bin, epochs=30, batch_size=32,validation_data=(X_test_bin, Y_test_bin), verbose=1)
```

```
Train on 7352 samples, validate on 2947 samples
Epoch 1/30
7352/7352 [===========] - 6s 881us/step - loss: 0.0578 - acc: 0.9808 -
val loss: 0.0087 - val acc: 0.9986
Epoch 2/30
7352/7352 [===========] - 3s 357us/step - loss: 0.0079 - acc: 0.9974 -
val_loss: 0.0073 - val_acc: 0.9983
Epoch 3/30
7352/7352 [==========] - 3s 354us/step - loss: 0.0058 - acc: 0.9984 -
val_loss: 0.0106 - val_acc: 0.9956
Epoch 4/30
7352/7352 [===========] - 3s 364us/step - loss: 0.0036 - acc: 0.9990 -
val loss: 0.0030 - val acc: 0.9990
Epoch 5/30
val loss: 0.0028 - val acc: 0.9993
Epoch 6/30
7352/7352 [==========] - 3s 359us/step - loss: 0.0010 - acc: 0.9996 -
val loss: 0.0041 - val acc: 0.9993
Epoch 7/30
7352/7352 [============] - 3s 346us/step - loss: 9.2203e-04 - acc: 0.9997 - val
loss: 0.0017 - val_acc: 0.9997
Epoch 8/30
7352/7352 [===========] - 3s 356us/step - loss: 0.0042 - acc: 0.9988 -
val loss: 8.5511e-04 - val acc: 0.9997
Epoch 9/30
7352/7352 [===========] - 3s 358us/step - loss: 0.0013 - acc: 0.9997 -
val loss: 6.8389e-04 - val acc: 0.9997
Epoch 10/30
7352/7352 [=========] - 3s 375us/step - loss: 1.3490e-04 - acc: 1.0000 - val
```

```
loss: 9.8621e-04 - val acc: 0.9997
Epoch 11/30
7352/7352 [===========] - 3s 392us/step - loss: 0.0030 - acc: 0.9990 -
val loss: 3.6772e-04 - val acc: 1.0000
Epoch 12/30
7352/7352 [===========] - 3s 374us/step - loss: 0.0019 - acc: 0.9995 -
val loss: 9.7679e-04 - val acc: 0.9997
Epoch 13/30
7352/7352 [==========] - 3s 356us/step - loss: 0.0054 - acc: 0.9993 -
val_loss: 0.0021 - val_acc: 0.9993
Epoch 14/30
loss: 0.0010 - val acc: 0.9997
Epoch 15/30
loss: 0.0020 - val acc: 0.9997
Epoch 16/30
7352/7352 [============] - 3s 388us/step - loss: 9.7779e-04 - acc: 0.9997 - val
loss: 0.0014 - val_acc: 0.9997
Epoch 17/30
loss: 6.5504e-04 - val acc: 0.9997
Epoch 18/30
7352/7352 [===========] - 3s 357us/step - loss: 0.0121 - acc: 0.9978 -
val loss: 0.0086 - val_acc: 0.9986
Epoch 19/30
7352/7352 [==========] - 3s 348us/step - loss: 0.0026 - acc: 0.9993 -
val loss: 0.0115 - val acc: 0.9980
Epoch 20/30
7352/7352 [==========] - 3s 370us/step - loss: 2.2864e-04 - acc: 1.0000 - val
loss: 0.0104 - val acc: 0.9983
Epoch 21/30
loss: 0.0092 - val acc: 0.9983
Epoch 22/30
7352/7352 [==========] - 3s 358us/step - loss: 0.0013 - acc: 0.9995 -
val loss: 0.0095 - val acc: 0.9986
Epoch 23/30
7352/7352 [===========] - 3s 352us/step - loss: 7.6134e-04 - acc: 0.9997 - val
loss: 0.0140 - val acc: 0.9980
Epoch 24/30
7352/7352 [==========] - 3s 369us/step - loss: 6.4754e-04 - acc: 0.9997 - val
loss: 0.0075 - val_acc: 0.9986
Epoch 25/30
loss: 0.0092 - val acc: 0.9980
Epoch 26/30
7352/7352 [==========] - 3s 377us/step - loss: 4.3807e-05 - acc: 1.0000 - val
loss: 0.0075 - val acc: 0.9986
Epoch 27/30
loss: 0.0074 - val_acc: 0.9986
Epoch 28/30
loss: 0.0071 - val acc: 0.9990
Epoch 29/30
7352/7352 [===========] - 3s 353us/step - loss: 0.0018 - acc: 0.9995 -
val loss: 0.0046 - val_acc: 0.9990
Epoch 30/30
7352/7352 [===========] - 3s 350us/step - loss: 0.0026 - acc: 0.9995 -
val loss: 0.0015 - val acc: 0.9997
Out[25]:
```

<keras.callbacks.History at 0x7f7061515588>

In [26]:

```
binary_model_score = binary_model.evaluate(X_test_bin,Y_test_bin,verbose=0)
print('Test loss:', binary_model_score[0])
print('Test accuracy:', binary_model_score[1]*100)
```

Test loss: 0.001487480033914023 Test accuracy: 99.9660671869698

```
In [0]:
```

```
binary model.save('gdrive/My Drive/HAR/final binary model.m1')
```

sharpening test data

```
In [0]:
```

```
'''from scipy import ndimage
def sharpen(x test, sigma, alpha):
  r = x test.shape[0]
  c = x test.shape[1]
  d = x test.shape[2]
  container = np.empty((r, c, d))
   i = 0
   for row in x test:
     test = np.array([row])
      blurred = ndimage.gaussian_filter(test, sigma)
      sharpened = test + alpha * (test - blurred)
      container[i] = sharpened
     i = i + 1
   return container'''
Out[0]:
ma) \n sharpened = test + alpha * (test - blurred) \n i = i + 1\n return container'
```

container[i] = sharpened\n

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Static Model

In [87]:

```
# Data directory
DATADIR = 'gdrive/My Drive/HAR/UCI_HAR_Dataset'
# Raw data signals
# Signals are from Accelerometer and Gyroscope
# The signals are in x,y,z directions
# Sensor signals are filtered to have only body acceleration
# excluding the acceleration due to gravity
# Triaxial acceleration from the accelerometer is total acceleration
SIGNALS = [
   "body_acc_x",
   "body_acc_y",
   "body_acc_z",
    "body_gyro_x",
   "body_gyro_y",
   "body_gyro_z",
   "total acc x",
   "total_acc_y",
    "total_acc_z"
]
# Utility function to read the data from csv file
def _read_csv(filename):
   return pd.read csv(filename, delim whitespace=True, header=None)
# Utility function to load the load
def load signals(subset):
    signals data = []
    for signal in SIGNALS:
       filename = f'gdrive/My Drive/HAR/UCI HAR Dataset/{subset}/Inertial
Signals/{signal} {subset}.txt
       signals data.append(
            read csv(filename).as matrix()
```

```
# Transpose is used to change the dimensionality of the output,
    # aggregating the signals by combination of sample/timestep.
    # Resultant shape is (7352 train/2947 test samples, 128 timesteps, 9 signals)
    return np.transpose(signals data, (1, 2, 0))
def load_y(subset):
    11 11 11
    The objective that we are trying to predict is a integer, from 1 to 6,
    that represents a human activity. We return a binary representation of
    every sample objective as a 6 bits vector using One Hot Encoding
    (https://pandas.pydata.org/pandas-docs/stable/generated/pandas.get dummies.html)
    filename = f'gdrive/My Drive/HAR/UCI HAR Dataset/{subset}/y {subset}.txt'
    y = read csv(filename)[0]
    y subset = y > 3 #taking y class labels greater than 3
    y = y[y_subset]
    return pd.get dummies(y).as matrix(),y subset
def load_static_data():
    Obtain the dataset from multiple files.
    Returns: X_train, X_test, y_train, y_test
    X train, X test = load signals('train'), load signals('test')
    y train, y train sub = load y('train')
    y test,y test sub = load y('test')
    X train = X train[y train sub]
    X_test = X_test[y_test_sub]
    return X_train, X_test, y_train, y_test
# Loading the train and test data
X_train_static, X_test_static, Y_train_static, Y_test_static = load_static_data()
/usr/local/lib/python3.6/dist-packages/ipykernel launcher.py:32: FutureWarning: Method .as matrix
will be removed in a future version. Use .values instead.
/usr/local/lib/python3.6/dist-packages/ipykernel launcher.py:51: FutureWarning: Method .as matrix
will be removed in a future version. Use .values instead.
In [88]:
print('X:shape', X train static.shape, 'Y:shape', Y train static.shape)
#print('X:shape',X_cv_static.shape,'Y:shape',Y_cv_static.shape)
print('X:shape', X test static.shape, 'Y:shape', Y test static.shape)
X:shape (4067, 128, 9) Y:shape (4067, 3)
X:shape (1560, 128, 9) Y:shape (1560, 3)
In [0]:
from sklearn.model_selection import RandomizedSearchCV
from sklearn.model selection import GridSearchCV
from keras.models import Sequential
from keras.layers import Dense
from keras.layers import Dropout
import keras
import keras.utils
from keras import utils as np utils
from keras.wrappers.scikit_learn import KerasClassifier
In [0]:
%%time
create model(filters=1, filters2=1, kernel size=1, kernel size=1, dropout rate2=0.0, dropout rate=0.0):
  model = Sequential()
```

model.add(keras.layers.Conv1D(filters=filters,

(timesteps, input_dim)))

kernel size=kernel size, kernel regularizer=keras.regularizers.12(0.55),

activation='relu', kernel initializer='he uniform', input shape=

```
model.add(BatchNormalization())
  model.add(Dropout(dropout rate))
 model.add(keras.layers.Conv1D(filters=filters2,
kernel size=kernel size2, kernel regularizer=keras.regularizers.12(0.28),
                              activation='relu',kernel_initializer='he_uniform'))
 model.add(BatchNormalization())
 model.add(Dropout(dropout rate2))
 model.add(MaxPooling1D(pool_size=2))
  model.add(Flatten())
 model.add(Dense(3, activation='softmax'))
 model.compile(loss='categorical crossentropy', optimizer='Adam', metrics=['accuracy'])
seed = 7
numpy.random.seed(seed)
model = KerasClassifier(build fn=create model, epochs=30, batch size=16, verbose=0)
# define the grid search parameters
filters = [1, 32, 64]
filters2 = [1, 26, 36]
kernel_size = [1,3,5,7]
kernel_size2 = [1, 2, 6, 8]
dropout rate = [0.0, 0.2, 0.4, 0.6, 0.8]
dropout_rate2 = [0.0, 0.1, 0.3, 0.5, 0.9]
param = dict(filters=filters,kernel_size=kernel_size,dropout_rate=dropout_rate,filters2=filters2,
            dropout rate2=dropout rate2, kernel size2=kernel size2)
rand = RandomizedSearchCV(estimator=model,param distributions=param,cv=3)
rand_result = rand.fit(X_train_static, Y_train_static)
# summarize results
print("Best: %f using %s" % (rand result.best score , rand result.best params ))
4
                                                                                          . ▶
Best: 0.889599 using {'kernel_size2': 1, 'kernel_size': 7, 'filters2': 26, 'filters': 32,
'dropout rate2': 0.9, 'dropout rate': 0.2}
CPU times: user 55min, sys: 2min 12s, total: 57min 12s
Wall time: 48min 57s
In [92]:
static model = Sequential()
static model.add(Conv1D(filters=32, kernel size=7, activation='relu',kernel initializer='he uniform
',input shape=(timesteps, input dim)))
static model.add(BatchNormalization())
static model.add(Dropout(0.0))
static model.add(Conv1D(filters=32, kernel size=1, activation='relu',kernel initializer='he uniform
static_model.add(BatchNormalization())
static model.add(Dropout(0.2))
static model.add(Conv1D(filters=32, kernel size=7, activation='relu',kernel initializer='he uniform
'))
static model.add(MaxPooling1D(pool size=2))
static_model.add(Flatten())
static model.add(Dense(32,activation='relu'))
static model.add(Dense(3, activation='softmax'))
static model.compile(loss='categorical crossentropy', optimizer='Adam', metrics=['accuracy'])
static model.fit(X train static, Y train static, epochs=59, batch size=32,
                validation_data=(X_test_static, Y_test_static), verbose=1)
Train on 4067 samples, validate on 1560 samples
Epoch 1/59
0.2683 - val acc: 0.8910
Epoch 2/59
4067/4067 [===========] - 2s 415us/step - loss: 0.2222 - acc: 0.9112 -
val loss: 0.3736 - val acc: 0.8756
Epoch 3/59
4067/4067 [===========] - 2s 404us/step - loss: 0.2306 - acc: 0.9046 -
val loss: 0.3486 - val acc: 0.8545
Epoch 4/59
4067/4067 [===========] - 2s 404us/step - loss: 0.2051 - acc: 0.9115 -
val loss: 0.3071 - val acc: 0.8750
Epoch 5/59
4067/4067 [===========] - 2s 422us/step - loss: 0.2001 - acc: 0.9134 -
val loss: 0.2938 - val acc: 0.8929
Epoch 6/59
4067/4067 [===========] - 2s 396us/step - loss: 0.1903 - acc: 0.9211 -
val loss: 0.2835 - val acc: 0.9038
```

```
Epoch 7/59
4067/4067 [===========] - 2s 401us/step - loss: 0.2079 - acc: 0.9122 -
val loss: 0.3417 - val acc: 0.8776
Epoch 8/59
4067/4067 [===========] - 2s 403us/step - loss: 0.1784 - acc: 0.9230 -
val loss: 0.2629 - val acc: 0.9038
Epoch 9/59
4067/4067 [===========] - 2s 399us/step - loss: 0.1901 - acc: 0.9191 -
val_loss: 0.2487 - val_acc: 0.9122
Epoch 10/59
val loss: 0.2527 - val_acc: 0.9135
Epoch 11/59
4067/4067 [===========] - 2s 422us/step - loss: 0.1767 - acc: 0.9213 -
val loss: 0.2374 - val acc: 0.9006
Epoch 12/59
4067/4067 [============] - 2s 428us/step - loss: 0.1789 - acc: 0.9203 -
val loss: 0.3060 - val acc: 0.8808
Epoch 13/59
4067/4067 [===========] - 2s 442us/step - loss: 0.1597 - acc: 0.9277 -
val loss: 0.2390 - val acc: 0.9147
Epoch 14/59
val loss: 0.3087 - val acc: 0.9103
Epoch 15/59
4067/4067 [============] - 2s 418us/step - loss: 0.1483 - acc: 0.9361 -
val loss: 0.4047 - val acc: 0.8910
Epoch 16/59
4067/4067 [==========] - 2s 429us/step - loss: 0.1495 - acc: 0.9363 -
val loss: 0.2725 - val acc: 0.9179
Epoch 17/59
4067/4067 [==========] - 2s 412us/step - loss: 0.1294 - acc: 0.9439 -
val loss: 0.2909 - val acc: 0.9077
Epoch 18/59
4067/4067 [===========] - 2s 417us/step - loss: 0.1539 - acc: 0.9378 -
val loss: 0.2716 - val acc: 0.9109
Epoch 19/59
4067/4067 [===========] - 2s 424us/step - loss: 0.1431 - acc: 0.9373 -
val loss: 0.3384 - val_acc: 0.9173
Epoch 20/59
4067/4067 [===========] - 2s 447us/step - loss: 0.1407 - acc: 0.9390 -
val_loss: 0.3228 - val_acc: 0.9160
Epoch 21/59
4067/4067 [===========] - 2s 436us/step - loss: 0.1416 - acc: 0.9329 -
val loss: 0.3610 - val_acc: 0.8923
Epoch 22/59
4067/4067 [===========] - 2s 457us/step - loss: 0.1274 - acc: 0.9489 -
val loss: 0.3253 - val acc: 0.9192
Epoch 23/59
4067/4067 [============] - 2s 447us/step - loss: 0.1183 - acc: 0.9501 -
val loss: 0.2975 - val acc: 0.9135
Epoch 24/59
4067/4067 [===========] - 2s 434us/step - loss: 0.1357 - acc: 0.9432 -
val loss: 0.2616 - val acc: 0.9218
Epoch 25/59
val loss: 0.3600 - val acc: 0.9026
Epoch 26/59
4067/4067 [===========] - 2s 427us/step - loss: 0.1318 - acc: 0.9457 -
val loss: 0.3595 - val acc: 0.8955
Epoch 27/59
4067/4067 [==========] - 2s 436us/step - loss: 0.1570 - acc: 0.9368 -
val loss: 0.3598 - val acc: 0.8923
Epoch 28/59
4067/4067 [============] - 2s 422us/step - loss: 0.1253 - acc: 0.9484 -
val loss: 0.3379 - val acc: 0.9006
Epoch 29/59
4067/4067 [===========] - 2s 412us/step - loss: 0.1274 - acc: 0.9457 -
val_loss: 0.3340 - val_acc: 0.9147
Epoch 30/59
4067/4067 [===========] - 2s 420us/step - loss: 0.1058 - acc: 0.9555 -
val loss: 0.3280 - val_acc: 0.9212
Epoch 31/59
4067/4067 [============] - 2s 415us/step - loss: 0.1356 - acc: 0.9479 -
val loss: 0.2701 - val_acc: 0.9263
Epoch 32/59
4067/4067 [===========] - 2s 417us/step - loss: 0.1217 - acc: 0.9511 -
```

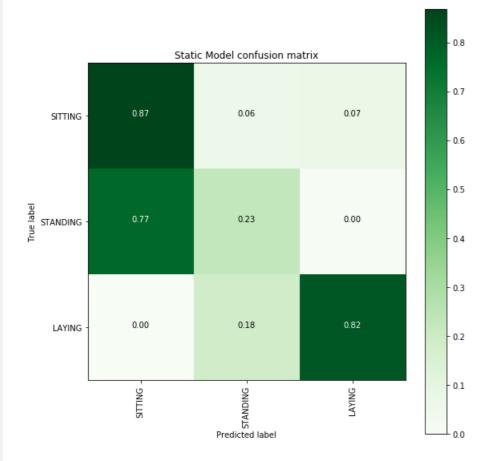
```
val loss: 0.4524 - val acc: 0.8897
Epoch 33/59
4067/4067 [===========] - 2s 440us/step - loss: 0.1173 - acc: 0.9501 -
val loss: 0.3675 - val acc: 0.8904
Epoch 34/59
4067/4067 [============ ] - 2s 420us/step - loss: 0.1057 - acc: 0.9575 -
val loss: 0.4708 - val_acc: 0.8718
Epoch 35/59
4067/4067 [===========] - 2s 411us/step - loss: 0.1195 - acc: 0.9464 -
val_loss: 0.4662 - val_acc: 0.8853
Epoch 36/59
4067/4067 [============== ] - 2s 431us/step - loss: 0.1507 - acc: 0.9361 -
val_loss: 0.5384 - val_acc: 0.8923
Epoch 37/59
4067/4067 [============] - 2s 403us/step - loss: 0.1281 - acc: 0.9484 -
val loss: 0.5009 - val acc: 0.8981
Epoch 38/59
4067/4067 [============] - 2s 402us/step - loss: 0.1100 - acc: 0.9552 -
val loss: 0.5386 - val acc: 0.9019
Epoch 39/59
4067/4067 [============] - 2s 392us/step - loss: 0.1115 - acc: 0.9523 -
val loss: 0.4056 - val acc: 0.9128
Epoch 40/59
4067/4067 [============] - 2s 402us/step - loss: 0.0984 - acc: 0.9589 -
val loss: 0.5095 - val acc: 0.9026
Epoch 41/59
4067/4067 [===========] - 2s 415us/step - loss: 0.1013 - acc: 0.9567 -
val loss: 0.2972 - val acc: 0.9006
Epoch 42/59
4067/4067 [===========] - 2s 412us/step - loss: 0.1159 - acc: 0.9498 -
val loss: 0.5124 - val acc: 0.9026
Epoch 43/59
4067/4067 [===========] - 2s 416us/step - loss: 0.1022 - acc: 0.9557 -
val loss: 0.5227 - val acc: 0.9026
Epoch 44/59
4067/4067 [===========] - 2s 399us/step - loss: 0.0983 - acc: 0.9597 -
val loss: 0.4954 - val acc: 0.8987
Epoch 45/59
4067/4067 [============] - 2s 426us/step - loss: 0.1254 - acc: 0.9479 -
val loss: 0.2917 - val_acc: 0.9199
Epoch 46/59
4067/4067 [============] - 2s 407us/step - loss: 0.1186 - acc: 0.9525 -
val_loss: 0.2711 - val_acc: 0.9199
Epoch 47/59
4067/4067 [===========] - 2s 394us/step - loss: 0.0978 - acc: 0.9604 -
val loss: 0.3164 - val acc: 0.9269
Epoch 48/59
4067/4067 [============] - 2s 396us/step - loss: 0.0956 - acc: 0.9594 -
val loss: 0.3670 - val acc: 0.9186
Epoch 49/59
4067/4067 [============] - 2s 428us/step - loss: 0.0930 - acc: 0.9614 -
val loss: 0.3123 - val acc: 0.9224
Epoch 50/59
4067/4067 [============] - 2s 410us/step - loss: 0.1012 - acc: 0.9582 -
val loss: 0.2761 - val acc: 0.9179
Epoch 51/59
4067/4067 [===========] - 2s 406us/step - loss: 0.1213 - acc: 0.9496 -
val loss: 0.4582 - val acc: 0.8821
Epoch 52/59
4067/4067 [============] - 2s 425us/step - loss: 0.0881 - acc: 0.9658 -
val loss: 0.3291 - val acc: 0.9141
Epoch 53/59
4067/4067 [===========] - 2s 415us/step - loss: 0.1036 - acc: 0.9533 -
val loss: 0.3199 - val acc: 0.9167
Epoch 54/59
4067/4067 [===========] - 2s 419us/step - loss: 0.0873 - acc: 0.9639 -
val loss: 0.2934 - val acc: 0.9154
Epoch 55/59
4067/4067 [===========] - 2s 410us/step - loss: 0.0863 - acc: 0.9636 -
val_loss: 0.3316 - val_acc: 0.9154
Epoch 56/59
val loss: 0.4001 - val_acc: 0.9179
Epoch 57/59
4067/4067 [============= ] - 2s 411us/step - loss: 0.0892 - acc: 0.9648 -
val loss: 0.3249 - val acc: 0.9231
Epoch 58/59
```

In [93]:

```
static_model_score = static_model.evaluate(X_test_static,Y_test_static,verbose=0)
print('Test loss:', static_model_score[0])
print('Test accuracy:', static_model_score[1]*100)
```

Test loss: 0.25014383807258894 Test accuracy: 92.6923076923077

In [94]:



Based on above confusion matrix results the class sitting and standing labels more confuse to predict

In [0]:

```
static_model.save('gdrive/My Drive/HAR/final_static_model.m2')
```

_ . ..

Dynamic model

```
In [35]:
```

```
# Data directory
DATADIR = 'gdrive/My Drive/HAR/UCI_HAR_Dataset'
# Raw data signals
# Signals are from Accelerometer and Gyroscope
# The signals are in x,y,z directions
# Sensor signals are filtered to have only body acceleration
# excluding the acceleration due to gravity
# Triaxial acceleration from the accelerometer is total acceleration
SIGNALS = [
    "body_acc_x",
    "body_acc_y",
    "body_acc_z",
   "body gyro x",
   "body gyro y",
    "body gyro z",
    "total_acc_x",
   "total_acc_y",
    "total_acc_z"
1
# Utility function to read the data from csv file
def read csv(filename):
    return pd.read csv(filename, delim whitespace=True, header=None)
# Utility function to load the load
def load signals(subset):
    signals data = []
    for signal in SIGNALS:
       filename = f'gdrive/My Drive/HAR/UCI HAR Dataset/{subset}/Inertial
Signals/{signal} {subset}.txt'
       signals_data.append(
            _read_csv(filename).as matrix()
    # Transpose is used to change the dimensionality of the output,
    # aggregating the signals by combination of sample/timestep.
    # Resultant shape is (7352 train/2947 test samples, 128 timesteps, 9 signals)
    return np.transpose(signals data, (1, 2, 0))
def load y(subset):
    The objective that we are trying to predict is a integer, from 1 to 6,
    that represents a human activity. We return a binary representation of
    every sample objective as a 6 bits vector using One Hot Encoding
    (https://pandas.pydata.org/pandas-docs/stable/generated/pandas.get dummies.html)
    filename = f'gdrive/My Drive/HAR/UCI HAR Dataset/{subset}/y {subset}.txt'
    y = read csv(filename)[0]
    y_subset = y <= 3 #taking y_class labels less than 3</pre>
    y = y[y \text{ subset}]
   return pd.get dummies(y).as matrix(),y subset
def load_dynamic_data():
    Obtain the dataset from multiple files.
    Returns: X train, X test, y train, y test
   X_train, X_test = load_signals('train'), load_signals('test')
    y_train, y_train_sub = load y('train')
    y test,y test sub = load y('test')
    X train = X train[y_train_sub]
    X test = X test[y test sub]
    return X_train, X_test, y_train, y_test
# Loading the train and test data
X_train_dynamic, X_test_dynamic, Y_train_dynamic, Y_test_dynamic = load_dynamic_data()
/usr/local/lib/python3.6/dist-packages/ipykernel_launcher.py:32: FutureWarning: Method .as_matrix
will be removed in a future version. Use .values instead.
```

```
/usi/iocai/iib/pychoho.u/uist-packayes/ipykethei_tauhchei.py.oi. rucutewaihing. Mechou .as_mactik
will be removed in a future version. Use .values instead.
In [36]:
print(X train dynamic.shape, Y train dynamic.shape)
print(X test dynamic.shape, Y test dynamic.shape)
(3285, 128, 9) (3285, 3)
(1387, 128, 9) (1387, 3)
In [0]:
import numpy
from sklearn.model selection import RandomizedSearchCV
from sklearn.model selection import GridSearchCV
from keras.models import Sequential
from keras.layers import Dense
from keras.layers import Dropout
import keras
import keras.utils
from keras import utils as np_utils
from keras.wrappers.scikit learn import KerasClassifier
def create_model(filters=1,filters2=1,kernel_size=1,kernel_size=1,dropout_rate=0.0,dropout_rate=0
. ():
  model = Sequential()
  model.add(keras.layers.Conv1D(filters=filters, kernel size=kernel size, activation='relu', kernel
initializer='he uniform',input shape=(timesteps, input dim)))
  model.add(BatchNormalization())
  model.add(Dropout(dropout rate))
  model.add(keras.layers.Conv1D(filters=filters2, kernel size=kernel size2, activation='relu', kerne
l initializer='he uniform'))
  model.add(BatchNormalization())
  model.add(Dropout(dropout rate2))
  model.add(MaxPooling1D(pool size=2))
  model.add(Flatten())
  model.add(Dense(3, activation='softmax'))
  model.compile(loss='categorical crossentropy', optimizer='Adam', metrics=['accuracy'])
  return model
# fix random seed for reproducibility
seed = 7
numpy.random.seed(seed)
model = KerasClassifier(build_fn=create_model, epochs=30, batch_size=16, verbose=0)
# define the grid search parameters
filters = [1,32,64]
filters2 = [1,32,64]
kernel size = [1,3,5,7]
kernel size2 = [1,3,5,7]
dropout rate = [0.0, 0.2, 0.4, 0.6, 0.8]
dropout_rate2 = [0.0,0.2,0.4,0.6,0.8]
param =
dict(filters=filters,kernel_size=kernel_size,dropout_rate=dropout_rate,filters2=filters2,dropout_ra
te2=dropout_rate2, kernel_size2=kernel_size2)
random = RandomizedSearchCV(estimator=model,param distributions=param,cv=3)
rand result = random.fit(X train dynamic, Y train dynamic)
# summarize results
print("Best: %f using %s" % (rand result.best score , rand result.best params ))
4
Best: 0.954642 using {'kernel_size2': 7, 'kernel_size': 1, 'filters2': 32, 'filters': 32,
'dropout_rate2': 0.2, 'dropout_rate': 0.0}
In [37]:
dynamic model = Sequential()
dynamic model.add(Conv1D(filters=32, kernel size=1, activation='relu',kernel initializer='he unifor
m', input shape=(timesteps, input dim)))
dynamic model.add(BatchNormalization())
dynamic model.add(Dropout(0.0))
dynamic model.add(Conv1D(filters=32, kernel size=7, activation='relu',kernel initializer='he unifor
m'))
dynamic model.add(BatchNormalization())
dynamic_model.add(Dropout(0.2))
        model add/MarDeeling1D/moel circ-2)
```

```
dynamic_model.add(MaxroollinglD(pool_Size=2))

dynamic_model.add(Flatten())

dynamic_model.add(Dense(3, activation='softmax'))

dynamic_model.summary()
```

Model: "sequential 4"

Layer (type)	Output	Shape	Param #
convld_8 (Conv1D)	(None,	128, 32)	320
batch_normalization_7 (Batch	(None,	128, 32)	128
dropout_7 (Dropout)	(None,	128, 32)	0
conv1d_9 (Conv1D)	(None,	122, 32)	7200
batch_normalization_8 (Batch	(None,	122, 32)	128
dropout_8 (Dropout)	(None,	122, 32)	0
max_pooling1d_4 (MaxPooling1	(None,	61, 32)	0
flatten_4 (Flatten)	(None,	1952)	0
dense_5 (Dense)	(None,	3)	5859

Total params: 13,635 Trainable params: 13,507 Non-trainable params: 128

In [38]:

```
dynamic_model.compile(loss='categorical_crossentropy', optimizer='Adam', metrics=['accuracy'])
dynamic_model.fit(X_train_dynamic,Y_train_dynamic, epochs=30, batch_size=32,validation_data=(X_test_dynamic, Y_test_dynamic),verbose=1)
```

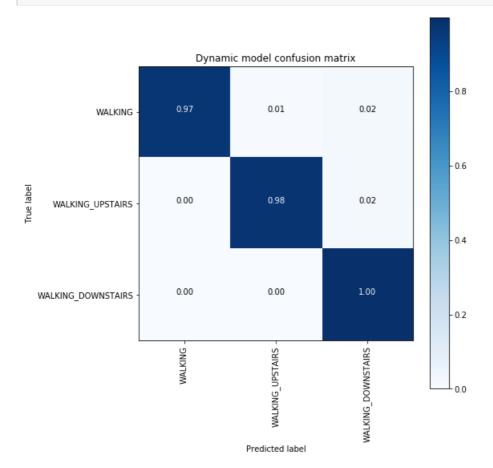
```
Train on 3285 samples, validate on 1387 samples
Epoch 1/30
val loss: 0.4249 - val acc: 0.8717
Epoch 2/30
3285/3285 [============] - 1s 342us/step - loss: 0.1024 - acc: 0.9650 -
val loss: 0.2290 - val acc: 0.9229
Epoch 3/30
3285/3285 [===========] - 1s 347us/step - loss: 0.0371 - acc: 0.9924 -
val loss: 0.1777 - val acc: 0.9430
Epoch 4/30
3285/3285 [=========== ] - 1s 353us/step - loss: 0.0223 - acc: 0.9948 -
val loss: 0.1433 - val acc: 0.9560
Epoch 5/30
3285/3285 [===========] - 1s 344us/step - loss: 0.0124 - acc: 0.9973 -
val_loss: 0.1282 - val_acc: 0.9589
Epoch 6/30
3285/3285 [===========] - 1s 347us/step - loss: 0.0138 - acc: 0.9973 -
val loss: 0.1320 - val acc: 0.9553
Epoch 7/30
3285/3285 [===========] - 1s 342us/step - loss: 0.0061 - acc: 0.9991 -
val loss: 0.1366 - val acc: 0.9618
Epoch 8/30
3285/3285 [============] - 1s 360us/step - loss: 0.0046 - acc: 1.0000 -
val_loss: 0.1017 - val_acc: 0.9632
Epoch 9/30
3285/3285 [============] - 1s 365us/step - loss: 0.0044 - acc: 0.9997 -
val_loss: 0.0724 - val_acc: 0.9726
Epoch 10/30
3285/3285 [============== ] - 1s 352us/step - loss: 0.0031 - acc: 0.9994 -
val_loss: 0.0766 - val_acc: 0.9740
Epoch 11/30
3285/3285 [============ ] - 1s 341us/step - loss: 0.0071 - acc: 0.9979 -
val loss: 0.1750 - val acc: 0.9394
Epoch 12/30
3285/3285 [===========] - 1s 353us/step - loss: 0.0091 - acc: 0.9967 -
val loss: 0.1148 - val acc: 0.9589
```

```
3285/3285 [===========] - 1s 346us/step - loss: 0.0023 - acc: 1.0000 -
val loss: 0.0986 - val acc: 0.9683
Epoch 14/30
val_loss: 0.0990 - val_acc: 0.9640
Epoch 15/30
3285/3285 [============] - 1s 366us/step - loss: 0.0011 - acc: 1.0000 -
val loss: 0.1133 - val acc: 0.9618
Epoch 16/30
3285/3285 [===========] - 1s 346us/step - loss: 0.0023 - acc: 0.9997 -
val loss: 0.0685 - val acc: 0.9784
Epoch 17/30
3285/3285 [===========] - 1s 351us/step - loss: 0.0019 - acc: 0.9997 -
val loss: 0.0845 - val acc: 0.9704
Epoch 18/30
loss: 0.0715 - val acc: 0.9755
Epoch 19/30
loss: 0.0593 - val acc: 0.9784
Epoch 20/30
loss: 0.0672 - val acc: 0.9748
Epoch 21/30
loss: 0.0700 - val_acc: 0.9719
Epoch 22/30
loss: 0.0651 - val acc: 0.9740
Epoch 23/30
3285/3285 [============= ] - 1s 342us/step - loss: 0.0032 - acc: 0.9994 -
val loss: 0.1153 - val_acc: 0.9704
Epoch 24/30
3285/3285 [===========] - 1s 391us/step - loss: 0.0052 - acc: 0.9982 -
val loss: 0.0806 - val acc: 0.9697
Epoch 25/30
3285/3285 [===========] - 1s 367us/step - loss: 0.0045 - acc: 0.9985 -
val_loss: 0.1324 - val_acc: 0.9654
Epoch 26/30
3285/3285 [============] - 1s 363us/step - loss: 0.0099 - acc: 0.9967 -
val loss: 0.1710 - val acc: 0.9632
Epoch 27/30
3285/3285 [===========] - 1s 353us/step - loss: 0.0060 - acc: 0.9976 -
val loss: 0.0965 - val acc: 0.9712
Epoch 28/30
3285/3285 [===========] - 1s 353us/step - loss: 0.0011 - acc: 0.9997 -
val loss: 0.0491 - val acc: 0.9827
Epoch 29/30
loss: 0.0625 - val acc: 0.9798
Epoch 30/30
loss: 0.0615 - val acc: 0.9820
Out[38]:
<keras.callbacks.History at 0x7f7061785a90>
In [39]:
dynamic model score = dynamic model.evaluate(X test dynamic,Y test dynamic,verbose=0)
print('Test loss:', dynamic model score[0])
print('Test accuracy:', dynamic model score[1]*100)
Test loss: 0.06151885367722327
Test accuracy: 98.19754866618601
```

```
In [60]:
```

Epoch 13/30

```
from sklearn.metrics import confusion_matrix
predict_dynamic = dynamic_model.predict(X_test_dynamic)
f_predict_dynamic = np.argmax(predict_dynamic,axis=1)
cm = confusion_matrix(np.argmax(Y_test_dynamic,axis=1), f_predict_dynamic)
plt.figure(figsize=(8.8))
```



In above confusion matrix results states that 98% of class labels are correctly predicted

```
In [0]:
```

```
dynamic_model.save('gdrive/My Drive/HAR/final_dynamic_model.m3')
```

Normal model

In [41]:

```
# Data directory
DATADIR = 'gdrive/My Drive/HAR/UCI_HAR_Dataset'
# Raw data signals
# Signals are from Accelerometer and Gyroscope
# The signals are in x,y,z directions
\# Sensor signals are filtered to have only body acceleration
# excluding the acceleration due to gravity
# Triaxial acceleration from the accelerometer is total acceleration
SIGNALS = [
   "body_acc_x",
   "body_acc_y",
    "body_acc_z",
    "body_gyro_x",
    "body_gyro_y",
    "body_gyro_z",
    "total_acc_x",
    "total_acc_y",
    "total_acc_z"
# Utility function to read the data from csv file
def _read_csv(filename):
return pd.read_csv(filename, delim_whitespace=True, header=None)
```

```
# Utility function to load the load
def load signals(subset):
    signals data = []
    for signal in SIGNALS:
        filename = f'qdrive/My Drive/HAR/UCI HAR Dataset/{subset}/Inertial
Signals/{signal} {subset}.txt'
        signals data.append(
            _read_csv(filename).as matrix()
    # Transpose is used to change the dimensionality of the output,
    # aggregating the signals by combination of sample/timestep.
    # Resultant shape is (7352 train/2947 test samples, 128 timesteps, 9 signals)
    return np.transpose(signals data, (1, 2, 0))
def load y(subset):
    The objective that we are trying to predict is a integer, from 1 to 6,
    that represents a human activity. We return a binary representation of
    every sample objective as a 6 bits vector using One Hot Encoding
    (https://pandas.pydata.org/pandas-docs/stable/generated/pandas.get dummies.html)
    filename = f'gdrive/My Drive/HAR/UCI_HAR_Dataset/{subset}/y_{subset}.txt'
    y = read csv(filename)[0]
    return pd.get_dummies(y).as_matrix()
def load data():
    Obtain the dataset from multiple files.
    Returns: X train, X test, y train, y test
    X_train, X_test = load_signals('train'), load_signals('test')
    y train,y test = load y('train'), load y('test')
   return X train, X test, y train, y test
# Loading the train and test data
Q_X_train, Q_X_test, Q_Y_train, Q_Y_test = load_data()
/usr/local/lib/python3.6/dist-packages/ipykernel_launcher.py:32: FutureWarning: Method .as_matrix
will be removed in a future version. Use .values instead.
/usr/local/lib/python3.6/dist-packages/ipykernel launcher.py:49: FutureWarning: Method .as matrix
will be removed in a future version. Use .values instead.
```

In [0]:

```
from keras.models import load_model
b_model = load_model('gdrive/My Drive/HAR/final_binary_model.m1')
s_model = load_model('gdrive/My Drive/HAR/final_static_model.m2')
d_model = load_model('gdrive/My Drive/HAR/final_dynamic_model.m3')
```

In [0]:

```
#predicting output activity
def predict(X):
   ##predicting whether dynamic or static
   predict_binary = binary_model.predict(X)
   f predict binary = np.argmax(predict binary, axis=1)
   #static data filter
   X_static = X[f_predict_binary==1]
    #dynamic data filter
   X_dynamic = X[f_predict_binary==0]
   #predicting static activities
   predict static = static model.predict(X static)
   f_predict_static = np.argmax(predict_static,axis=1)
   #adding 3 because need to get inal prediction lable as output
   f_predict_static = f_predict_static + 3
   #predicting dynamic activites
   predict dynamic = dynamic model.predict(X dynamic)
    f predict dynamic = np.argmax(predict dynamic,axis=1)
    #adding 1 because need to get inal prediction lable as output
    f predict dynamic = f predict dynamic
```

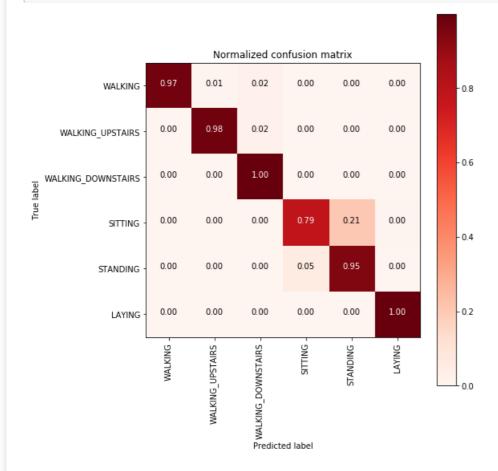
```
##appending final output to one list in the same sequence of input data
i,j = 0,0
final_predict = []
for q_p in f_predict_binary:
    if q_p == 1:
        final_predict.append(f_predict_static[i])
        i = i + 1
    else:
        final_predict.append(f_predict_dynamic[j])
        j = j + 1
return final_predict
```

In [44]:

```
from sklearn.metrics import accuracy_score
train_pred = predict(Q_X_train)
test_pred = predict(Q_X_test)
print('Accuracy of train data',accuracy_score(np.argmax(Q_Y_train,axis=1),train_pred))
print('Accuracy of validation data',accuracy_score(np.argmax(Q_Y_test,axis=1),test_pred))
```

Accuracy of train data 0.9802774755168662 Accuracy of validation data 0.9460468272819816

In [47]:



In [96]:

```
from prettytable import PrettyTable
x = PrettyTable()
x.field_names = ["Model", "Accuracy"]
x.add_row(["LSTM BASE MODEL ", '91%'])
x.add_row(["LSTM 2 Layer ", '93%'])
```

```
x.add_row(["Static model ", '92%'])
x.add_row(["Dynamic model ", '98%'])
x.add_row(["Binary + static + dynamic ", '94%'])
print(x)
```

Model	Accuracy
LSTM BASE MODEL LSTM 2 Layer Static model Dynamic model Binary + static + dynamic	91% 93% 93% 92% 98%

Observations

- 1. In this dataset about Human activity Recognition using smart phones data, Various LSTM and CNN deep learning techniques are applied
- 2. We got the results by using LSTM we got 93% accuracy
- 3. By applying the new concept called Divide and conquer we dividede te data into two parts
- 4. Applied first 3 class labels as one model and remaining 3 class labels as another model and predicted individually
- 5. first 3 class label models called dynamic models and last 3 class labels called as static models
- 6. Applied as 2 models and we got Static model as 92% accuracy and dynamic model as 98% accuracy
- 7. In static model there is a lot of confusion between standing and sitting class labels because of that confusion it gives lower accuracy
- 8. But in dynamic models it gives excellent classification it gaves 98% accuracy
- 9. Overall by combing all these 6 labels we got 94% as final accuracy by using concept called divde and conquer