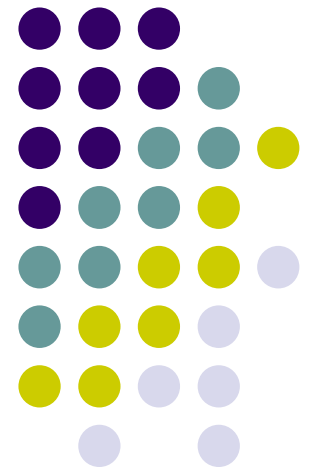


Uncertainty

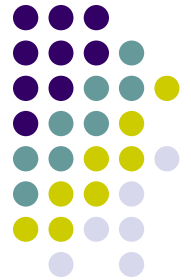


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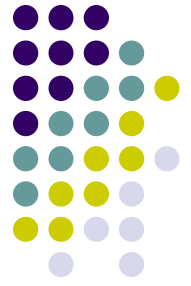
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Uncertainty



- **Logical agents** - Make the epistemological commitment that propositions are true, false or unknown.
- Unfortunately, agents almost never have access to the whole truth about their environment.
- **Qualification problem**
“ A_{g0} will get me there on-time if there is no accident on the bridge, it doesn't rain and my tires remain intact.”



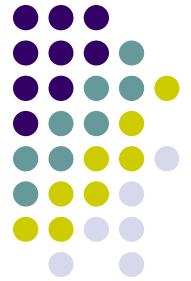
Real World Uncertainty

Let action A_t = leave for airport t minutes before flight

Will A_t get me there on time?

“ A_{90} will get me there on-time if there is no accident on the bridge and it doesn't rain and my tires remain intact.”

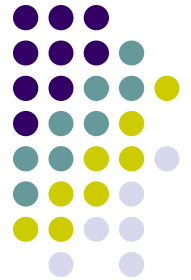
“ A_{120} might reasonably be said to get me there on-time but I'd have to wait ...”



Uncertainty Knowledge

- **Medical Diagnosis** always involves uncertainty –
 - Symptom cannot conclude disease.
 - Disease cannot conclude symptom.
- **First-Order Logic (FOL)** fails for three reasons:
 - Laziness
 - Too much work to list
 - Theoretical ignorance
 - No complete theory for diagnosis
 - Practical ignorance
 - Not all the necessary tests have been run.
- How to solve?
 - Degree of Belief, Probability Theory & Fuzzy Logic

Probability



Probabilistic assertions **summarize** effects of

- **Laziness:** failure to enumerate exceptions, qualifications, etc.
- **Ignorance:** lack of relevant facts, initial conditions, etc.

Subjective probability:

- Probabilities relate propositions to agent's own state of knowledge

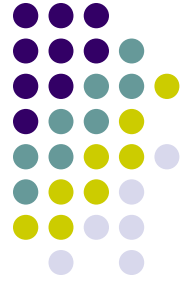
e.g., $P(A_{25} \mid \text{no reported accidents}) = 0.06$

These are **not** assertions about the world.

Probabilities of propositions change with new evidence:

e.g., $P(A_{25} \mid \text{no reported accidents, 5 a.m.}) = 0.15$

Rational Decisions



- Preferences of outcomes
- Utility theory
- Maximum Expected Utility

Decision Theory = Probability Theory + Utility Theory

Making Decisions under Uncertainty



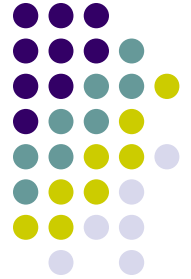
- Suppose I believe the following:
 $P(A_{25} \text{ gets me there on time} \mid \dots) = 0.04$
 $P(A_{90} \text{ gets me there on time} \mid \dots) = 0.70$
 $P(A_{120} \text{ gets me there on time} \mid \dots) = 0.95$
 $P(A_{1440} \text{ gets me there on time} \mid \dots) = 0.9999$
- Which action to choose?
Depends on my **preferences** for missing flight vs. time spent waiting
- **Utility theory** is used to represent and infer preferences.
- **Decision theory = Probability Theory + Utility Theory**



Probability Syntax

- Basic element: **random variable**
- Similar to propositional logic: possible worlds defined by assignment of values to random variables.
- **Boolean random variables**
e.g., *Cavity* (do you have a dental cavity?)
- **Discrete random variables**
e.g., *Weather* is one of $\langle \text{sunny}, \text{rainy}, \text{cloudy}, \text{snow} \rangle$
Domain values must be exhaustive and mutually exclusive
- Elementary proposition constructed by assignment of a value to a random variable: e.g., *Weather* = *sunny*, *Cavity* = *false*
- Complex propositions formed from elementary propositions and standard logical connectives e.g., *Weather* = *sunny* \vee *Cavity* = *false*

Syntax



- **Atomic event:** A **complete** specification of the state of the world about which the agent is uncertain.

e..g., if the world consists of only two Boolean variables *Cavity* and *Toothache*, then there are 4 distinct atomic events:

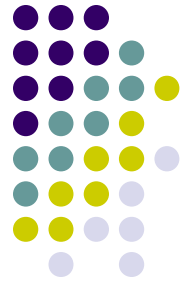
Cavity = *false* \wedge *Toothache* = *false*

Cavity = *false* \wedge *Toothache* = *true*

Cavity = *true* \wedge *Toothache* = *false*

Cavity = *true* \wedge *Toothache* = *true*

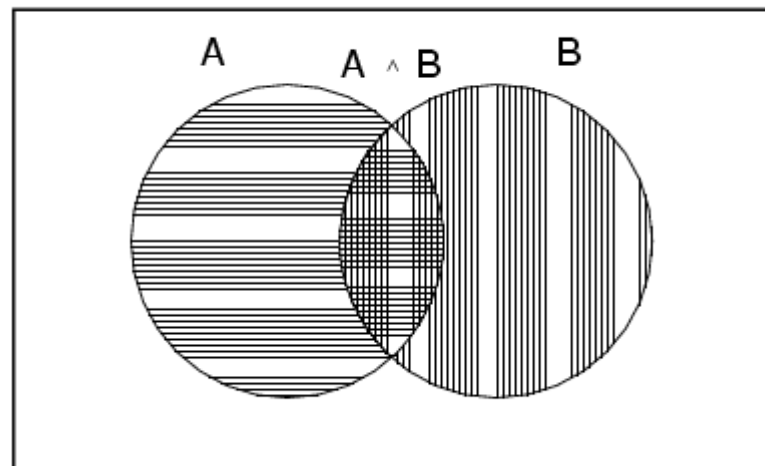
- Atomic events are mutually exclusive and exhaustive.

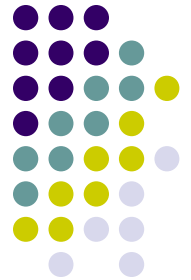


Axioms of Probability

- For any propositions A, B
 - $0 \leq P(A) \leq 1$
 - $P(\text{true}) = 1$ and $P(\text{false}) = 0$
 - $P(A \vee B) = P(A) + P(B) - P(A \wedge B)$

True





Prior Probability

- **Prior or unconditional probabilities of propositions**

e.g., $P(\text{Cavity} = \text{true}) = 0.1$ and $P(\text{Weather} = \text{sunny}) = 0.72$ correspond to belief prior to arrival of any (new) evidence

- **Probability distribution** gives values for all possible assignments:

$P(\text{Weather}) = \langle 0.72, 0.1, 0.08, 0.1 \rangle$ (normalized, i.e., sums to 1)

- **Joint probability distribution** for a set of random variables gives the probability of every atomic event on those random variables

-

$P(\text{Weather}, \text{Cavity})$ = a 4×2 matrix of values:

	sunny	rainy	cloudy	snow
<i>Weather</i> = <i>Cavity</i> = true	0.144	0.02	0.016	0.02
<i>Cavity</i> = false	0.576	0.08	0.064	0.08

- **Every question about a domain can be answered by the joint distribution.**



Conditional Probability

- **Conditional or posterior probabilities**

e.g., $P(\text{cavity} \mid \text{toothache}) = 0.8$

i.e., given that *toothache* is all I know

- (Notation for conditional distributions:

$\mathbf{P}(\text{Cavity} \mid \text{Toothache}) = 2\text{-element vector of } 2\text{-element vectors})$

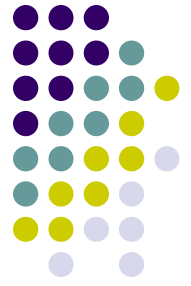
- If we know more, e.g., *cavity* is also given, then we have

$P(\text{cavity} \mid \text{toothache}, \text{cavity}) = 1$

- New evidence may be irrelevant, allowing simplification, e.g.,

$P(\text{cavity} \mid \text{toothache}, \text{sunny}) = P(\text{cavity} \mid \text{toothache}) = 0.8$

- This kind of inference, sanctioned by domain knowledge, is crucial.



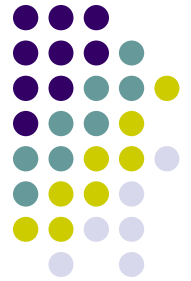
Conditional Probability

- Definition of conditional probability:

$$P(a | b) = \frac{P(a \wedge b)}{P(b)} \quad \text{where} \quad P(b) > 0$$

- **Product rule** gives an alternative formulation:

$$P(a \wedge b) = P(a | b) P(b) = P(b | a) P(a)$$



Axioms of Probability

- Kolmogorov's three axioms

1. All probabilities are between 0 and 1

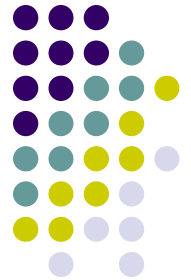
$$0 \leq P(a) \leq 1$$

2. Necessarily true is 1, necessarily false is 0

$$P(\text{true})=1, \quad P(\text{false})=0$$

3. Disjunction

$$P(a \vee b) = P(a) + P(b) - P(a \wedge b)$$



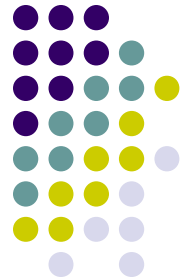
Inference by Enumeration

- Start with the joint probability distribution:



	<i>toothache</i>		\neg <i>toothache</i>	
	<i>catch</i>	\neg <i>catch</i>	<i>catch</i>	\neg <i>catch</i>
<i>cavity</i>	.108	.012	.072	.008
\neg <i>cavity</i>	.016	.064	.144	.576

- $P(\text{toothache}) = 0.108 + 0.012 + 0.016 + 0.064 = 0.2$

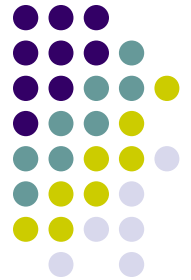


Inference by Enumeration

- Start with the joint probability distribution:

	<i>toothache</i>		\neg <i>toothache</i>	
	<i>catch</i>	\neg <i>catch</i>	<i>catch</i>	\neg <i>catch</i>
<i>cavity</i>	.108	.012	.072	.008
\neg <i>cavity</i>	.016	.064	.144	.576

- $P(\text{cavity} \vee \text{toothache}) = 0.108 + 0.012 + 0.072 + 0.008 + 0.016 + 0.064 = 0.28$



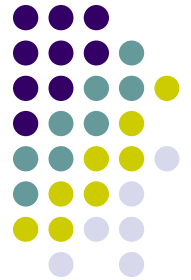
Inference by Enumeration

- Start with the joint probability distribution:

	<i>toothache</i>		\neg <i>toothache</i>	
	<i>catch</i>	\neg <i>catch</i>	<i>catch</i>	\neg <i>catch</i>
<i>cavity</i>	.108	.012	.072	.008
\neg <i>cavity</i>	.016	.064	.144	.576

- Can also compute conditional probabilities:
- $P(\neg \text{cavity} \mid \text{toothache}) = \frac{P(\neg \text{cavity} \wedge \text{toothache})}{P(\text{toothache})}$

$$\begin{aligned} &= \frac{0.016 + 0.064}{0.108 + 0.012 + 0.016 + 0.064} \\ &= 0.4 \end{aligned}$$



Normalization

	<i>toothache</i>		\neg <i>toothache</i>	
	<i>catch</i>	\neg <i>catch</i>	<i>catch</i>	\neg <i>catch</i>
<i>cavity</i>	.108	.012	.072	.008
\neg <i>cavity</i>	.016	.064	.144	.576

- Denominator can be viewed as a **normalization constant** α

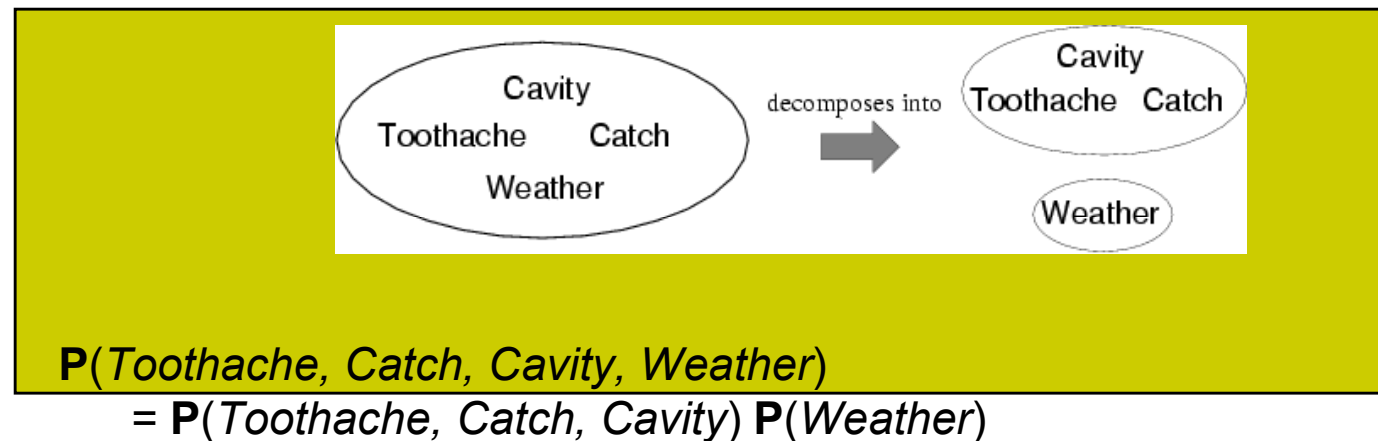
$$\begin{aligned} \mathbf{P}(\text{Cavity} \mid \text{toothache}) &= \alpha, \mathbf{P}(\text{Cavity}, \text{toothache}) \\ &= \alpha, [\mathbf{P}(\text{Cavity}, \text{toothache}, \text{catch}) + \mathbf{P}(\text{Cavity}, \text{toothache}, \neg \text{catch})] \\ &= \alpha, [<0.108, 0.016> + <0.012, 0.064>] \\ &= \alpha, <0.12, 0.08> = <0.6, 0.4> \end{aligned}$$

General idea: compute distribution on query variable by fixing **evidence variables** and summing over **hidden variables**

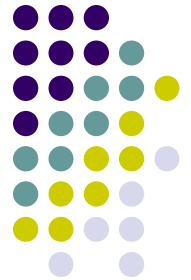


Independence

- A and B are independent iff
 $P(A|B) = P(A)$ or $P(B|A) = P(B)$ or $P(A, B) = P(A) P(B)$

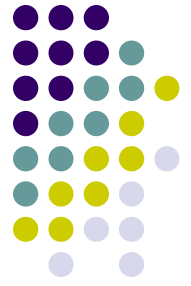


- 32 entries reduced to 12; for n independent biased coins, $O(2^n) \rightarrow O(n)$
- Absolute independence powerful but rare
- Dentistry is a large field with hundreds of variables, none of which are independent. What to do?



Conditional Independence

- $\mathbf{P}(\textit{Toothache}, \textit{Cavity}, \textit{Catch})$ has $2^3 - 1 = 7$ independent entries
- If I have a cavity, the probability that the probe catches in it doesn't depend on whether I have a toothache:
 - (1) $\mathbf{P}(\textit{catch} \mid \textit{toothache}, \textit{cavity}) = \mathbf{P}(\textit{catch} \mid \textit{cavity})$
- The same independence holds if I haven't got a cavity:
 - (2) $\mathbf{P}(\textit{catch} \mid \textit{toothache}, \neg \textit{cavity}) = \mathbf{P}(\textit{catch} \mid \neg \textit{cavity})$
- *Catch* is **conditionally independent** of *Toothache* given *Cavity*:
- $\mathbf{P}(\textit{Catch} \mid \textit{Toothache}, \textit{Cavity}) = \mathbf{P}(\textit{Catch} \mid \textit{Cavity})$
- Equivalent statements:
 - $\mathbf{P}(\textit{Toothache} \mid \textit{Catch}, \textit{Cavity}) = \mathbf{P}(\textit{Toothache} \mid \textit{Cavity})$
 - $\mathbf{P}(\textit{Toothache}, \textit{Catch} \mid \textit{Cavity}) = \mathbf{P}(\textit{Toothache} \mid \textit{Cavity}) \mathbf{P}(\textit{Catch} \mid \textit{Cavity})$



Conditional Independence

- Write out full joint distribution using chain rule:

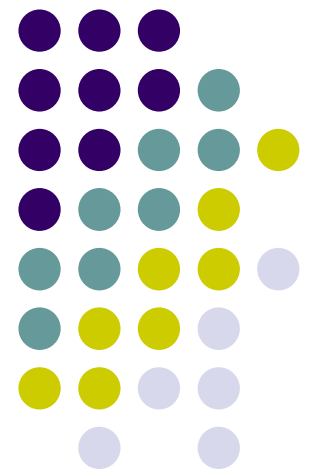
$$\begin{aligned} & \mathbf{P}(\textit{Toothache}, \textit{Catch}, \textit{Cavity}) \\ &= \mathbf{P}(\textit{Toothache} \mid \textit{Catch}, \textit{Cavity}) \mathbf{P}(\textit{Catch}, \textit{Cavity}) \\ &= \mathbf{P}(\textit{Toothache} \mid \textit{Catch}, \textit{Cavity}) \mathbf{P}(\textit{Catch} \mid \textit{Cavity}) \mathbf{P}(\textit{Cavity}) \\ &= \mathbf{P}(\textit{Toothache} \mid \textit{Cavity}) \mathbf{P}(\textit{Catch} \mid \textit{Cavity}) \mathbf{P}(\textit{Cavity}) \end{aligned}$$

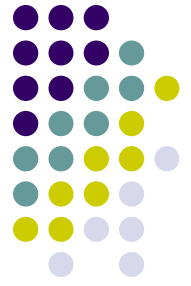
i.e., $2 + 2 + 1 = 5$ independent numbers

- **In most cases, the use of conditional independence reduces the size of the representation of the joint distribution from exponential in n to linear in n .**
- **Conditional independence is our most basic and robust form of knowledge about uncertain environments.**

Bayes' Rule

$$P(a | b) = \frac{P(b | a) P(a)}{P(b)}$$





Bayes' Rule

- Product rule $P(a \wedge b) = P(a | b) P(b) = P(b | a) P(a)$

\Rightarrow **Bayes' rule:**
$$P(a | b) = \frac{P(b | a) P(a)}{P(b)}$$

- or in distribution form

$$P(Y|X) = P(X|Y) P(Y) / P(X) = \alpha P(X|Y) P(Y)$$

- Useful for assessing diagnostic probability from causal probability:
- **$P(\text{Cause}|\text{Effect}) = P(\text{Effect}|\text{Cause}) P(\text{Cause}) / P(\text{Effect})$**
 - E.g., let M be meningitis, S be stiff neck:
 - $P(m|s) = P(s|m) P(m) / P(s) = 0.5 \times 0.00002 / 0.05 = 0.0002$



Combining Evidence

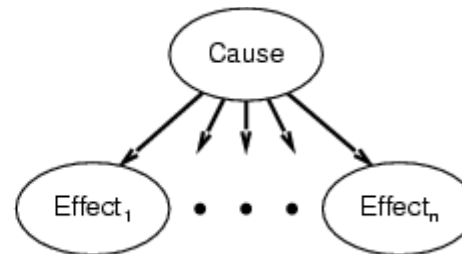
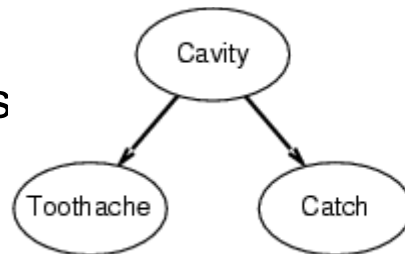
Assume independence
of catch and toothache

$$\begin{aligned} P(\text{Cavity} \mid \text{toothache} \wedge \text{catch}) \\ &= \alpha P(\text{toothache} \wedge \text{catch} \mid \text{Cavity}) P(\text{Cavity}) \\ &= \alpha P(\text{toothache} \mid \text{Cavity}) P(\text{catch} \mid \text{Cavity}) P(\text{Cavity}) \end{aligned}$$

- This is an example of a **naïve Bayes** model:

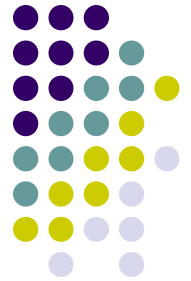


$P(\text{Caus}$



$P(\text{Cause})$

- Total number of parameters is **linear** in n



Summary

- Probability is a rigorous formalism for uncertain knowledge
- **Joint probability distribution** specifies probability of every **atomic event**
- Queries can be answered by summing over atomic events
- For nontrivial domains, we must find a way to reduce the joint size
- **Independence** and **conditional independence** provide the tools