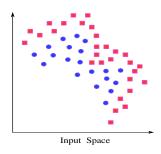
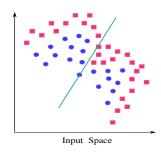
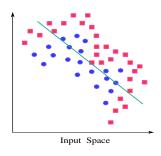
Kernel Function & Methods

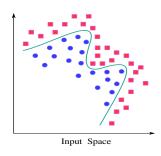
By Van Dinh Tran

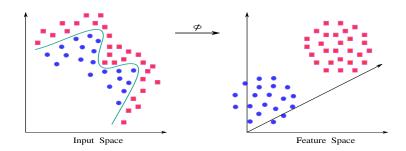
February 16, 2025

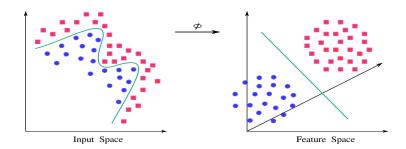


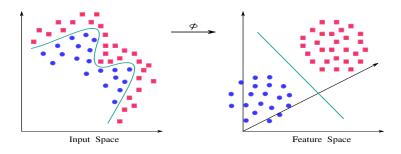












- In feature space, data are more likely to be linearly separable
- To build a model in feature space
 - ▶ Transform data to feature space $(\Phi \colon \mathbb{R}^n \mapsto \mathbb{R}^m \ (n \gg m))$
 - ► Train a model in feature space
- Problem: often leads to high computation

Question: What if the train and prediction of a model in feature space are involved in only pairwise similarities, but not individual representations?

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Idea: Compute $\langle \Phi(x_i), \Phi(x_j) \rangle$ through operations in input space, so **no transformation** is needed.

Solution: Defining a kernel function

$$\begin{aligned} k\colon \mathbb{X}\times\mathbb{X} &\longrightarrow \mathbb{R}\\ \text{such that } k(x_i,x_j) &= \Phi(x_i)^\intercal \Phi(x_j) \end{aligned}$$

Mercer's condition: If the function $k \colon \mathbb{X} \times \mathbb{X} \longrightarrow \mathbb{R}$ is symmetric, positive semi-definite, there exists a space \mathbb{F} and a mapping $\Phi \colon \mathbb{X} \mapsto \mathbb{F}$ such that $k(\mathbf{x}, \mathbf{y}) = \Phi^{\intercal}(\mathbf{x})\Phi(\mathbf{y})$.

- Using kernel to avoid explicit mapping is called *kernel trick*
- The matrix K, $K_{ij} = k(x_i, x_j)$, is called kernel matrix or gram-matrix

Example of an explicit kernel

Problem: Given $\Phi \colon (x_1,x_2) \mapsto (x_1^2,\sqrt{2}x_1x_2,x_2^2)$ and $k(x,y) = (x^\intercal y)^2$. Proof that k is a valid kernel. (Hint: $\forall x,y \in \mathbb{R}^2 : k(x,y) = \Phi^\intercal(x)\Phi(y)$).

Example of an explicit kernel

Problem: Given $\Phi \colon (\mathbf{x}_1, \mathbf{x}_2) \mapsto (\mathbf{x}_1^2, \sqrt{2}\mathbf{x}_1\mathbf{x}_2, \mathbf{x}_2^2)$ and $\mathbf{k}(\mathbf{x}, \mathbf{y}) = (\mathbf{x}^{\mathsf{T}}\mathbf{y})^2$. Proof that \mathbf{k} is a valid kernel. (Hint: $\forall \mathbf{x}, \mathbf{y} \in \mathbb{R}^2 : \mathbf{k}(\mathbf{x}, \mathbf{y}) = \Phi^{\mathsf{T}}(\mathbf{x})\Phi(\mathbf{y})$).

Solution:

- Compute $\Phi^{\intercal}(\mathbf{x})\Phi(\mathbf{y})$
 - $\Phi(\mathbf{x}) = (\mathbf{x}_1^2, \sqrt{2}\mathbf{x}_1\mathbf{x}_2, \mathbf{x}_2^2)$
 - $\Phi(\mathbf{y}) = (\mathbf{y}_1^2, \sqrt{2}\mathbf{y}_1\mathbf{y}_2, \mathbf{y}_2^2)$

$$\implies \Phi^{\intercal}(\mathbf{x})\Phi(\mathbf{y}) = \mathbf{x}_1^2\mathbf{y}_1^2 + 2\mathbf{x}_1\mathbf{y}_1\mathbf{x}_2\mathbf{y}_2 + \mathbf{x}_2^2\mathbf{y}_2^2$$

• Compute k(x, y)

$$k(\mathbf{x}, \mathbf{y}) = (\mathbf{x}^{\mathsf{T}} \mathbf{y})^{2}$$

$$= (\mathbf{x}_{1} \mathbf{y}_{1} + \mathbf{x}_{2} \mathbf{y}_{2})^{2}$$

$$= \mathbf{x}_{1}^{2} \mathbf{y}_{1}^{2} + 2\mathbf{x}_{1} \mathbf{y}_{1} \mathbf{x}_{2} \mathbf{y}_{2} + \mathbf{x}_{2}^{2} \mathbf{y}_{2}^{2}$$

$$\Longrightarrow \mathrm{k}(\mathbf{x},\mathbf{y}) = \Phi^\intercal(\mathbf{x})\Phi(\mathbf{y})$$

Some existing kernels

• Euclidean kernels

- \blacktriangleright Gaussian radial basis function (RBF): $k(x,y) = \exp(-\gamma \|x-y\|^2), \ \gamma > 0$
- ▶ Gaussian kernel: $k(x,y) = \exp(-\frac{\|x-y\|^2}{2\delta^2})$

• Graph kernels

- ▶ Diffusion-based kernels
- Decomposition-based kernels

Constructing kernels

We can construct kernels from existing kernels. Given k_i as valid kernels, a valid kernel k can be constructed in the following ways.

- Scalar multiplication: $k(x, x') = \alpha k_1(x, x'), \quad \alpha \ge 0$
- Adding a constant: $k(x, x') = k_1(x, x') + \alpha$, $\alpha \ge 0$
- \bullet Linear combination: $k(x,x') = \sum_{i=1}^n \alpha_i k_i(x,x'), \quad \alpha_i \geq 0$
- **Product:** $k(x, x') = k_1(x, x').k_2(x, x')$
- Polynomial function of a kernel: $k(x, x') = P(k_1(x, x'))$
- Exponential function of a kernel: $k(x, x') = \exp(k_1(x, x'))$

Kernel methods

- Kernel methods are a class of learning algorithms that use kernel functions. Some examples are:
 - ► Kernel perceptron
 - ► Support Vector Machine (SVM)
 - Gaussian processes
- Kernel methods work on pairwise similarities between instances

 The explicit representations of instances are not needed.
- Kernel methods with the use of kernel functions allow to operate in a high dimensional space without ever computing the coordinates of the data in that space, but rather in "low" dimensional space.

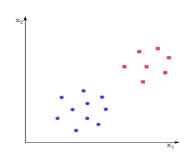
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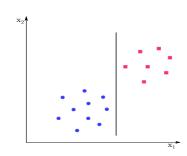
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We focus on SVM [$Vapnik\ et\ al.$, 1997], a linear method and the best known member of kernel methods.

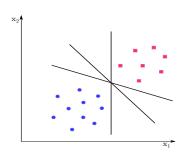
${\bf Hard\text{-}margin~SVM}$



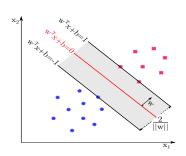
${\bf Hard\text{-}margin~SVM}$



Hard-margin SVM



$\operatorname{Hard-margin}$ SVM



Hard-margin SVM

We define:

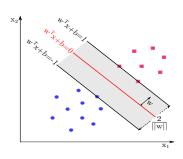
- h: $\mathbf{w}^{\intercal}\mathbf{x} + \mathbf{b} = 0$ (decision boundary) If $(\mathbf{w}^{\intercal}\mathbf{x} + \mathbf{b} > 0)$, Label "+1" If $(\mathbf{w}^{\intercal}\mathbf{x} + \mathbf{b} < 0)$, Label "-1"
- h_{\oplus} : $\mathbf{w}^{\intercal}\mathbf{x}_{\oplus} + \mathbf{b} = 1$ (positive hyperplane)
- $h_{\ominus} : \mathbf{w}^{\intercal} \mathbf{x}_{\ominus} + \mathbf{b} = -1$ (negative hyperplane)

It can be seen that

•
$$\mathbf{w}^{\mathsf{T}}\mathbf{x}_{+} + \mathbf{b} \ge 1 \Rightarrow \mathbf{y}_{+}(\mathbf{w}^{\mathsf{T}}\mathbf{x}_{+} + \mathbf{b} \ge 1)$$

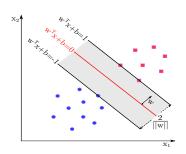
•
$$\mathbf{w}^{\mathsf{T}}\mathbf{x}_{-} + \mathbf{b} \le -1 \Rightarrow \mathbf{y}_{-}(\mathbf{w}^{\mathsf{T}}\mathbf{x}_{-} + \mathbf{b} \ge 1)$$

$$\Rightarrow y_i(\boldsymbol{w}^\intercal \boldsymbol{x}_i + b) \geq 1$$



Margin

$$\begin{split} \mathbf{Margin} &= d(h_{\oplus}, h_{\ominus}) \\ &= d(\mathbf{x}_0 \in h_{\oplus}, h_{\ominus}) \\ &= \frac{|\mathbf{w}\mathbf{x}_0 + b + 1|}{\|\mathbf{w}\|} \\ &= \frac{\left|(\mathbf{w}\mathbf{x}_0 + b - 1) + 2\right|}{\|\mathbf{w}\|} \\ &= \frac{2}{\|\mathbf{w}\|} \end{split}$$



Maximize margin

$$\begin{split} & \underset{\mathbf{w}}{\operatorname{Max}} \frac{2}{\|\mathbf{w}\|} \\ & \operatorname{Subject\ to}\ y_i(\mathbf{w}^\intercal \mathbf{x}_i + b) \geq 1,\ i = 1, \dots, N \\ & \underset{\mathbf{w}}{\operatorname{Min}} \frac{1}{2} \mathbf{w}^\intercal \mathbf{w} \\ & \operatorname{Subject\ to}\ - (y_i(\mathbf{w}^\intercal \mathbf{x}_i + b) - 1) \leq 0,\ i = 1, \dots, N \end{split}$$

Note that optimization with constraints:

- \bullet Equalities \rightarrow Lagrange multipliers
 - Inequalities \rightarrow KKT (Karush–Kuhn–Tucker)

Optimization

Lagrangian function:

$$\begin{split} \mathcal{L}(\boldsymbol{w},b,\boldsymbol{\alpha}) &= \frac{1}{2} \boldsymbol{w}^\intercal \boldsymbol{w} - \sum_{i=1}^N \alpha_i (y_i (\boldsymbol{w}^\intercal \boldsymbol{x}_i + b) - 1) \\ &\text{Subject to } \alpha_i \geq 0 \end{split}$$

Dual form:

$$\begin{aligned} & \underset{\boldsymbol{\alpha}}{\operatorname{Max}} \underset{\boldsymbol{w}, b}{\operatorname{Min}} \, \mathcal{L}(\boldsymbol{w}, b, \boldsymbol{\alpha}) \\ & \text{Subject to } \alpha_i \geq 0 \end{aligned}$$

Solving optimization

$$\begin{split} \mathcal{L}(\mathbf{w},b,\mathbf{\alpha}) &= \frac{1}{2} \mathbf{w}^\intercal \mathbf{w} - \sum_{i=1}^N \alpha_i (y_i (\mathbf{w}^\intercal \mathbf{x}_i + b) - 1) \\ \frac{\partial \mathcal{L}}{\partial \mathbf{w}} &= \mathbf{w} - \sum_{i=1}^N \alpha_i y_i \mathbf{x}_i = 0 \Longrightarrow \boxed{\mathbf{w} = \sum_{i=1}^N \alpha_i y_i \mathbf{x}_i} \\ \frac{\partial \mathcal{L}}{\partial b} &= \boxed{\sum_{i=1}^N \alpha_i y_i } = 0 \end{split}$$

Substituting into Lagrangian function

$$\begin{split} \mathcal{L}(\boldsymbol{\alpha}) &= \frac{1}{2} \sum_{i=1}^{N} \alpha_i y_i \boldsymbol{x}_i \sum_{j=1}^{N} \alpha_j y_j \boldsymbol{x}_j - \sum_{i=1}^{N} \alpha_i y_i \boldsymbol{x}_i \sum_{j=1}^{N} \alpha_j y_j \boldsymbol{x}_j - b \sum_{i=1}^{N} \alpha_i y_i + \sum_{i=1}^{N} \alpha_i \\ &= \sum_{i=1}^{N} \alpha_i - \frac{1}{2} \sum_{i=1}^{N} \sum_{j=1}^{N} \alpha_i \alpha_j y_i y_j \boldsymbol{x}_i^\mathsf{T} \boldsymbol{x}_j \end{split}$$

Solving optimization

$$\begin{array}{ll} \underset{\boldsymbol{\alpha}}{\operatorname{Max}}\,\mathcal{L}(\boldsymbol{\alpha}) & \underset{\boldsymbol{\alpha}}{\operatorname{Max}}\left(\sum_{i=1}^{N}\alpha_{i} - \frac{1}{2}\sum_{i=1}^{N}\sum_{j=1}^{N}\alpha_{i}\alpha_{j}y_{i}y_{j}\boldsymbol{x_{i}^{\mathsf{T}}\boldsymbol{x_{j}}}\right) \\ \operatorname{Subject\ to}\ \alpha_{i} \geq 0 & & \operatorname{Subject\ to}\ \alpha_{i} \geq 0 \end{array}$$

Solving this optimization by using quadratic programming tools, we get

$$\begin{cases} \alpha_i > 0 & \text{if } \mathbf{x}_i \in h_{\oplus} \text{ or } \mathbf{x}_i \in h_{\ominus} \\ \alpha_i = 0 & \text{otherwise} \end{cases}$$

$$\boldsymbol{w} = \sum_{\boldsymbol{x}_i \text{ is SV}} \alpha_i \boldsymbol{y}_i \boldsymbol{x}_i$$

- Find b: $y_j(\mathbf{w}^\intercal \mathbf{x}_j + b) = 1 \longrightarrow b = y_j \sum_{\mathbf{x}: is \ SV} \alpha_i y_i \mathbf{x}_i^\intercal \mathbf{x}_j$, where \mathbf{x}_j is any SV.
- Decision boundary: $\mathbf{w}^\intercal \mathbf{x} + \mathbf{b} = 0 \Longleftrightarrow \sum_{\mathbf{x}_i \text{ is SV}} \alpha_i y_i \mathbf{x}_i^\intercal \mathbf{x} + \mathbf{b} = 0$
- Decision Rule:

$$y = Sign(\sum_{\boldsymbol{x}_i \text{ is SV}} \alpha_i y_i \boldsymbol{x}_i^{\intercal} \boldsymbol{x} + b)$$

Solving optimization

$$\begin{array}{ll} \underset{\boldsymbol{\alpha}}{\operatorname{Max}}\,\mathcal{L}(\boldsymbol{\alpha}) & \qquad & \underset{\boldsymbol{\alpha}}{\operatorname{Max}}(\sum\limits_{i=1}^{N}\alpha_{i} - \frac{1}{2}\sum\limits_{i=1}^{N}\sum\limits_{j=1}^{N}\alpha_{i}\alpha_{j}y_{i}y_{j}\textbf{k}(\boldsymbol{x}_{i},\boldsymbol{x}_{j})) \\ \operatorname{Subject\ to}\ \alpha_{i} \geq 0 & \qquad & \\ \end{array}$$

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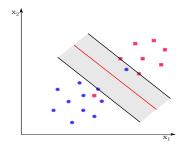
$$w = \sum\limits_{x_i \mathrm{\ is\ SV}} \alpha_i y_i x_i$$

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- Decision boundary: $\mathbf{w}^{\intercal}\mathbf{x} + \mathbf{b} = 0 \iff \sum_{\mathbf{x_i} \text{ is SV}} \alpha_i y_i \mathbf{k}(\mathbf{x_i}, \mathbf{x}) + \mathbf{b} = 0$
- Decision Rule:

$$y = Sign(\sum_{\boldsymbol{x}_i \text{ is SV}} \alpha_i y_i \boldsymbol{k(\boldsymbol{x}_i, \boldsymbol{x})} + b)$$

Soft-margin SVM

- Margin violation: $y_i(\mathbf{w}^\intercal \mathbf{x}_i + \mathbf{b}) \not \geq 1$
- $$\begin{split} \bullet \ \, \forall x_i, \, \text{allowing error} \, \xi_i, \, \, \xi_i \geq 0 \\ y_i(\textbf{w}^\intercal x_i + b) \geq 1 \xi_i \end{split}$$
- \bullet Total error: $E = \sum\limits_{i=1}^{N} \xi_i$



$$\underset{\mathbf{w}}{\operatorname{Min}}\ \frac{1}{2}\mathbf{w}^{\intercal}\mathbf{w} + C \sum_{i=1}^{N} \xi_{i}$$

Subject to $y_i(\mathbf{w}^\intercal \mathbf{x}_i + b) \ge 1 - \xi_i; \ \xi_i \ge 0$

(C controls the cost of misclassification on the training data)

Soft-margin SVM

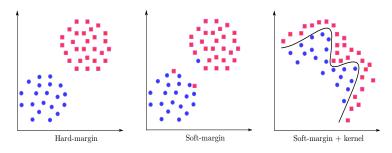
Lagrangian function:

$$\begin{split} \mathcal{L}(\mathbf{w},b,\pmb{\xi},\pmb{\alpha},\pmb{\beta}) &= \frac{1}{2} \mathbf{w}^\intercal \mathbf{w} + C \sum_{i=1}^N \pmb{\xi}_i - \sum_{i=1}^N \alpha_i (y_i(\mathbf{w} \mathbf{x}_i + b) - 1 + \pmb{\xi}_i) - \sum_{i=1}^N \beta_i \pmb{\xi}_i \\ &\text{Subject to } \alpha_i \geq 0; \ \beta_i \geq 0 \end{split}$$

Dual form:

$$\begin{aligned} & \underset{\boldsymbol{\alpha},\boldsymbol{\beta}}{\operatorname{Max}} & \underset{\boldsymbol{w},b,\boldsymbol{\xi}}{\operatorname{Min}} & \mathcal{L}(\boldsymbol{w},b,\boldsymbol{\xi},\boldsymbol{\alpha},\boldsymbol{\beta}) \\ & \text{Subject to } \alpha_{i} > 0; \ \beta_{i} > 0 \end{aligned}$$

SVM in practice



In most cases, soft-margin SVM with kernel is used in practice.

SVM: advantages and disadvantages

• Advantages:

- Scaling relatively well to high dimensional data
- Working well with unstructured and semi-structured data
- Generalizing well; the risk of over-fitting is less in SVM
- Kernel trick is the real strength of SVM
- Efficient in prediction

Disadvantages:

- Not easy to choose an appropriate kernel function
- High time computation for large datasets
- Difficult to understand and interpret