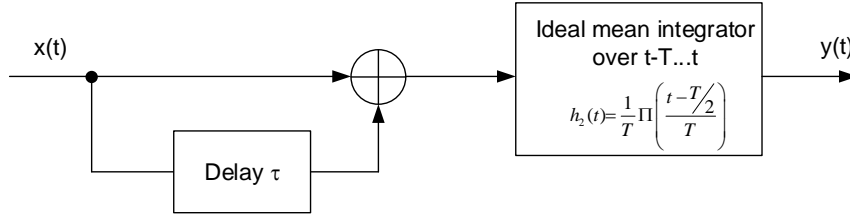


COMMUNICATION THEORY, Class Exercise 2, Fall 2023

- Derive the impulse response $h(t)$ and the frequency response or transfer function $H(f)$ of the following LTI system, and investigate how the results vary depending on the values of the delay τ and the integrating window T .



- An LTI transmission channel has the following frequency response for $f_{MHz} \geq 0$, where $K = 3$ and $t_d = 0.04 \mu s$. Note that here the frequency domain is expressed in MHz.

$$H(f_{MHz}) = \begin{cases} K e^{-j20\pi t_d} & f_{MHz} < 10 \text{ MHz} \\ K \left| \cos \left[\frac{6\pi}{70} (f_{MHz} - 10) \right] \right| e^{-j2\pi f_{MHz} t_d} & 10 \text{ MHz} \leq f_{MHz} < 30 \text{ MHz} \\ K \left| \cos \left(\frac{6\pi}{7} \right) \right| e^{-j2\pi f_{MHz} t_d} & f_{MHz} \geq 30 \text{ MHz} \end{cases}$$

- Assuming the channel impulse is real-valued, find the frequency response at $f_{MHz} < 0$
 - Determine at which frequencies the channel causes either amplitude or phase linear distortion, and whether it causes any non-linear distortion
- A sinusoidal signal $a \cdot \cos(2\pi f_0 t)$ with frequency $f_0 = 1 \text{ kHz}$ and amplitude a either 0.5 V or 1.0 V is used as the input $x(t)$ of a non-linear device, which is described by the following input-output response:

$$y(t) = 12x(t) - 3x^2(t) + x^3(t)$$

The output signal $y(t)$ is then filtered by an RC-lowpass filter described by its frequency response $H_{RC}(f) = \frac{1}{1 + j2\pi fRC}$, with parameters $R = 1 \text{ k}\Omega$, $C = 0.500 \text{ mF}$.

- Find which harmonics of the original frequency f_0 appear in the output signal $y(t)$
- Calculate the distortion coefficients associated to the harmonics and the total harmonic distortion factor (THD) of the filtered output signal, as per the following definitions:
 - distortion coefficients $d_2 = |A_{2f_0}|/|A_{f_0}|$, $d_3 = |A_{3f_0}|/|A_{f_0}|$, ...
with A_f denoting the amplitude of a frequency component f
 - total harmonic distortion factor $THD = \sqrt{d_2^2 + d_3^2 + \dots}$