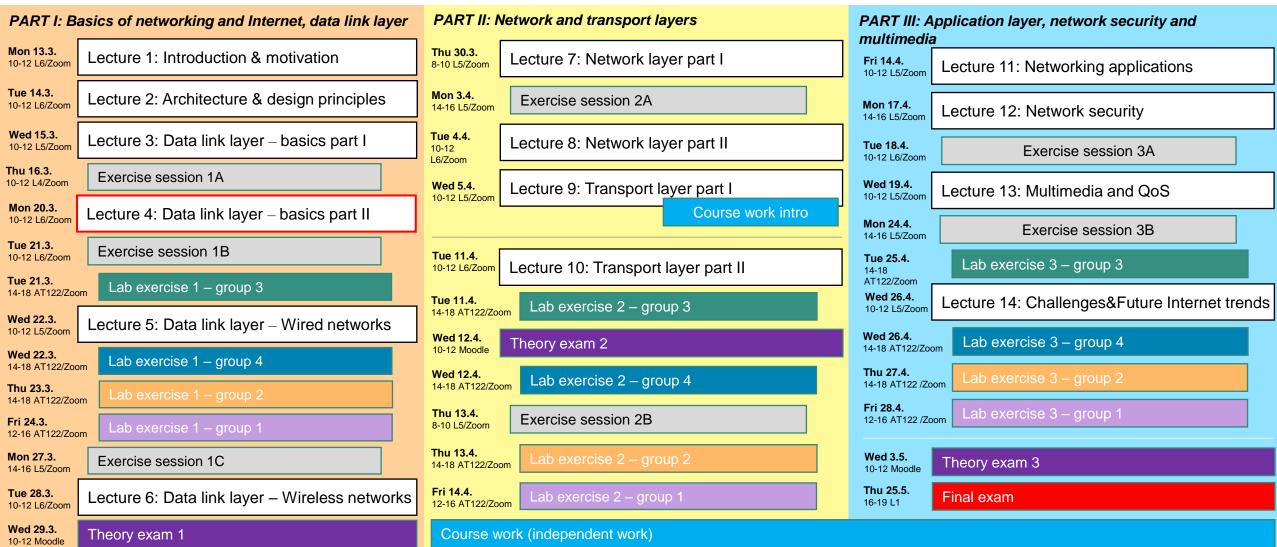


### 521150A Introduction to Internet

**Lecture 4 – Data link layer, part II: Link Control** 



#### Schedule of the course



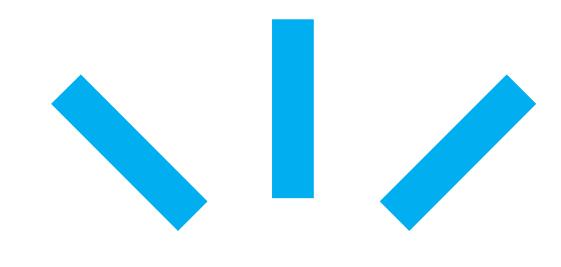
2 521150A Introduction to Internet University of Oulu



# Main learning objectives of this lecture

- 1. Know the main functions of Link Control
- 2. Understand the basic concept of flow control and know its basic types:
  - Stop&wait
  - Pipelining
  - Sliding window
- 3. Understand the concept of error control and know its basic types:
  - Stop&wait ARQ
  - Go-Back-N ARQ
  - Selective repeat

521150A Introduction to Internet
University of Oulu



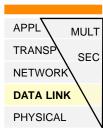
#### **Basics of Link Control**

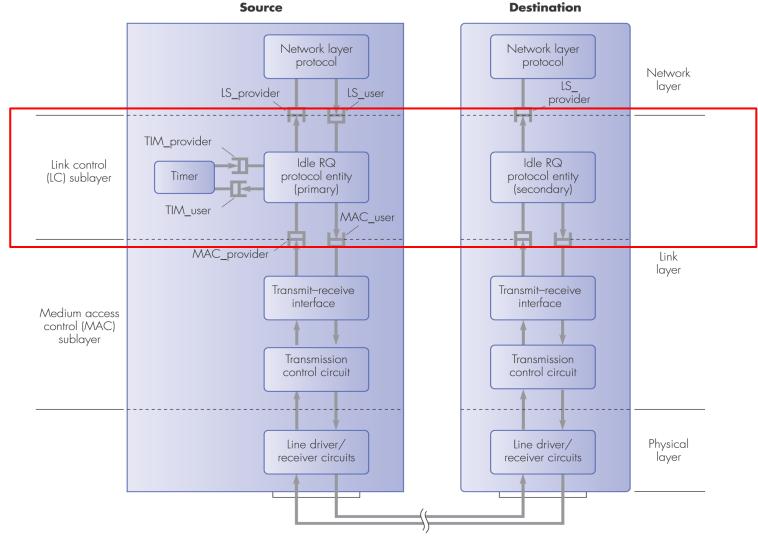
521150A Introduction to Internet
University of Oulu



### Link Control (LC)

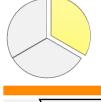








#### Data link layer architecture



**MULT** TRANSP SEC NETWORK **DATA LINK** PHYSICAL

Typically data link layer comprises of two

sublayers: Network layer

- Link control (LC) sublayer
  - Error control
  - Flow control

Link control (LC) sublayer

- **Medium access control** (MAC) sublayer
  - Framing
  - **Transmission** (medium access)

Medium access control (MAC) sublayer

MAC provider Transmit-receive interface Transmission control circuit Line driver/ receiver circuits

protocol

Idle RQ

protocol entity

(primary)

LS user

MAC user

LS provider

TIM provider

Timer

TIM user

Network layer protocol Network layer provide

**Destination** 

Idle RQ

protocol entity

(secondary)

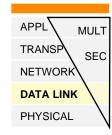
interface

- layer Transmit-receive
  - Transmission
    - control circuit

Line driver/ Physical receiver circuits layer







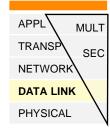
#### Data link control protocols

- Requirements/objectives for effective data communication between two directly-connected transmitting-receiving stations
  - Frame synchronization: data are sent in frames, the beginning and end of each frame must be recognizable;
  - Flow control: sending station must not send frames at a rate faster than the receiving station can absorb them;
  - Error control: bit errors introduced by the transmission system should be corrected, or at least the upper layer should be informed;
  - Addressing: in a shared link (such as LAN), the identity of the two stations involved in transmission must be specified;
  - Control and data on same link: not desirable to have a separate physical communication path for control information, receiver must be able to distinguish control information from the data being transmitted;
  - Link management: procedures for coordination and cooperation among stations for the initiation, maintenance and termination of sustained data exchange;

#### → A data link control protocol is needed







#### Specification of a data link control protocol

#### Building blocks

- Frames (data, acknowledgments)
- Buffers
- Timers
- Sequence numbers (frame ID's)
- Flow control
- Error control (incl. error detection)

#### Notation of following protocol examples

- P = primary (sender, source)
- S = secondary (receiver, destination)
- I(N) = information (data) with sequence number N
- ACK = positive acknowledgment frame
- NAK = negative acknowledgment frame



#### PPP: Point-to-point data link control

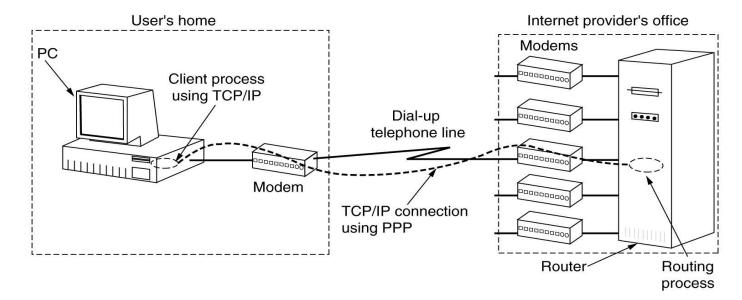


**MULT** TRANSP NETWORK

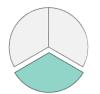
**DATA LINK** 

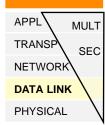
PHYSICAL

- RFC 1661 etc.
- One sender, one receiver, one link
- Easier than shared broadcast link
  - No medium access control
  - No need for explicit MAC addressing
  - E.g., dialup link, ISDN line



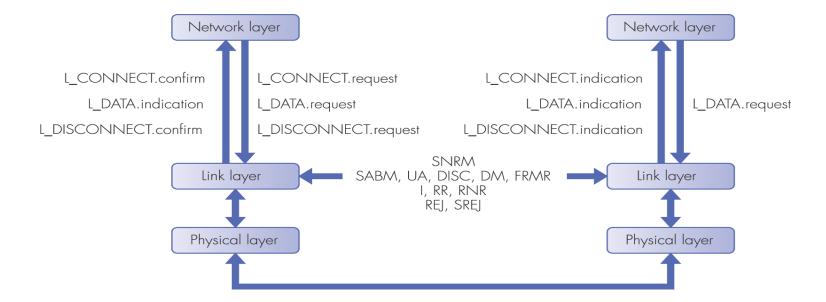






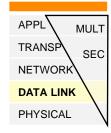
#### **HDLC (High-level Data Link Control)**

- ISO 3009, ISO 4335
- Most important data link control protocol
- Bit-oriented
- Synchronous transmission
  - All transmission in form of frames
- Widely used for point-to-point and point-to-multipoint links
- Also basis for many other important data link protocols









### Link performance characterization (1)

#### Assumptions

- d: length of the physical link (m)
- V: signal propagation speed in the link medium (m/s)
- L: length of a frame (bits)
- Data rate (R, bps) (also called bit rate or bandwidth)
- Amount of data (bits) that can be transmitted per unit of time (s)
- Note inverse relation between data rate and bit duration

#### Delays

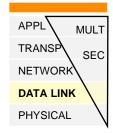
- Transmission delay  $T_x$ : time taken to transmit a frame at the data rate of the link (L/R)
- Propagation delay T<sub>p</sub>: time for the signal to propagate (travel) from one of the link to the other end (medium specific) (d / V)
- One-way delay: time from the transmission of the first bit of a frame to the arrival of the last bit of the frame at receiver
- Round-trip delay: time from the transmission of the first bit of a frame to the arrival of the last bit of the acknowledgment sent by the receiver at sender

521150A Introduction to Internet

University of Oul

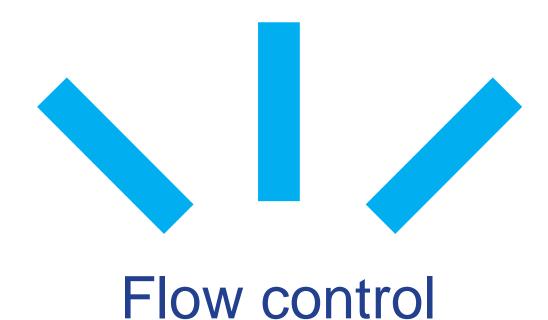






### Link performance characterization (2)

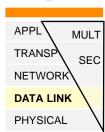
- Bit length of a link: B = R x (d / V)
  - Number of bits fully occupying a link (i.e. bandwidth x delay product, bdp)
- Let's define relationship a = B / L = (d/V) / (L/R) = T<sub>p</sub> / T<sub>x</sub>
  - Number of frames in link of bit length B, when frame length is L
  - Ratio between propagation delay and transmission delay
- Relationship between a and round-trip delay
  - a<1 → round-trip delay determined primarily by transmission delay</li>
  - a=1 → both delays have qual effect
  - a>1 → round-trip delay determined primarily by propagation delay
  - This relationship has great impact on link utilization, as we will soon see
- Bandwidth-delay product (bdp)
  - One-way: number of bits transmitted before first bit arrives at receiver
  - Round-trip: number of bits transmitted before sender receives acknowledgment





#### Flow control





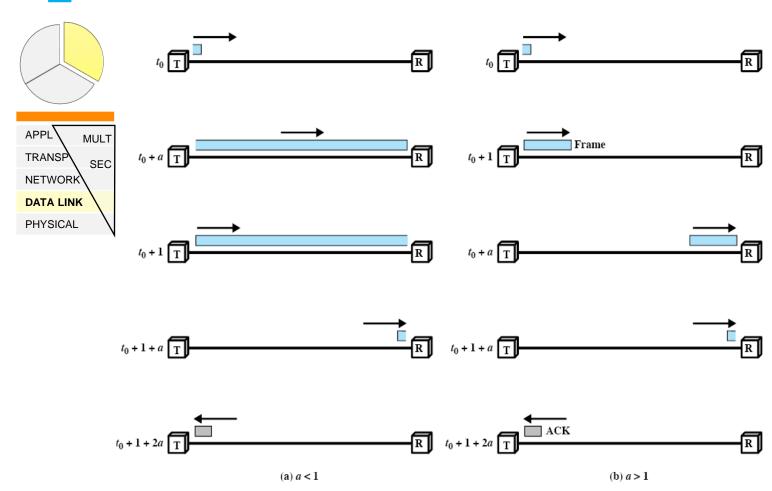
14

- Regulate the flow of data in such manner that fast senders do not swamp slow receivers
  - Receiver typically allocates data buffer of finite length for a connection
- Two basic approaches
  - Feedback-based flow control
    - Based on information provided by receiver to sender
    - Stop-and-wait flow control
    - Flow control with sliding windows
  - Rate-based flow control
    - Built in sender, not based on information provided by receiver
    - Not used in data link layer protocols

### \*\*\*

15

### Stop-and-wait flow control



**a<1:** first bit of frame arrives at receiver before last bit has been transmitted

- Source transmits frame
- Destination receives frame and replies with acknowledgement (ACK)
- Source waits for ACK before sending next frame
- Destination can stop flow by not send ACK
- Only one frame in transit at any time

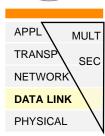
521150A Introduction to Internet

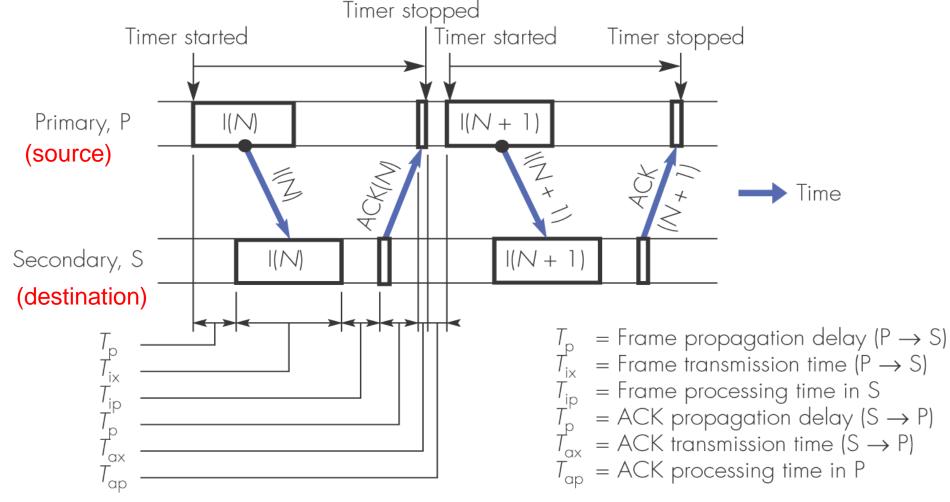
University of Oulu



### Stop-and-wait flow control (2)



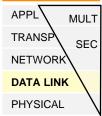




**Link utilization**:  $U=T_{ix}/T_t \sim T_{ix}/(T_{ix}+2T_p) = 1/(1+2T_p/T_{ix}) = 1/(1+2a)$ , where  $a = T_p/T_{ix}$ 







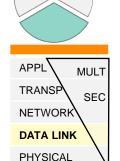
#### Stop-and-wait flow control: Example (1)

- A series of 1000-bit frames is to be transmitted using stop-andwait protocol.
- Determine the link utilization for the following types of data links assuming a transmission bit rate of:
  - I. 1 kbps
  - II. 1 Mbps
  - III. 1 Gbps
  - a) 1 km long twisted-pair cable. Signal propagation speed is 2x10<sup>8</sup> m/s.
  - b) 200 km long leased line. Signal propagation speed is 2x108 m/s.
  - c) 50000 km long satellite link. Signal propagation speed is 3x108 m/s.
  - Bit error rate is negligible (can be ignored).

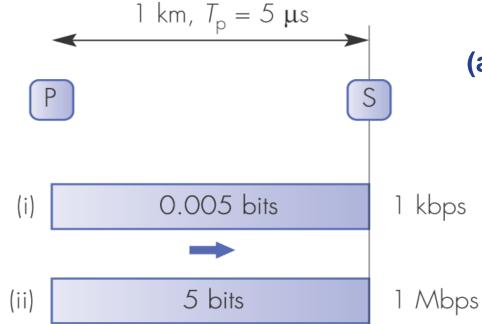


#### Stop-and-wait flow control: Example (2)





#### **Twisted pair**



Frame transmission time  $T_{ix}$  = Number of bits in frame / Bit rate

- (i) 1 kbps:  $T_{ix} = 1000 \text{ b} / 10^3 \text{ b/s} = 1 \text{ s}$
- (ii) 1 Mbps:  $T_{ix} = 1000 \text{ b} / 10^6 \text{ b/s} = 10^{-3} \text{ s} = 1 \text{ ms}$
- (iii) 1 Gbps:  $T_{ix} = 1000 \text{ b} / 10^9 \text{ b/s} = 10^{-6} \text{ s} = 1 \text{ }\mu\text{s}$
- (a) 1 km long twisted-pair cable. Signal propagation speed is 2x10<sup>8</sup> m/s.

Frame propagation delay  $T_p = 10^3 \text{ m} / 2x10^8 \text{ m/s} = 5x10^{-6} \text{ s}$ 

(i) 
$$a = T_p/T_{ix} = 5x10^{-6} \text{ s} / 1 \text{ s} = 5x10^{-6} \rightarrow (1 + 2a) \approx 1, U = 1$$

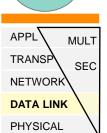
(ii) 
$$a = 5x10^{-6} \text{ s} / 10^{-3} \text{ s} = 5x10^{-3} \rightarrow (1 + 2a) \approx 1, U = 1$$

(iii) 
$$a = 5x10^{-6} \text{ s} / 10^{-6} \text{ s} = 5 \rightarrow (1 + 2a) = 11, U = 0.09$$

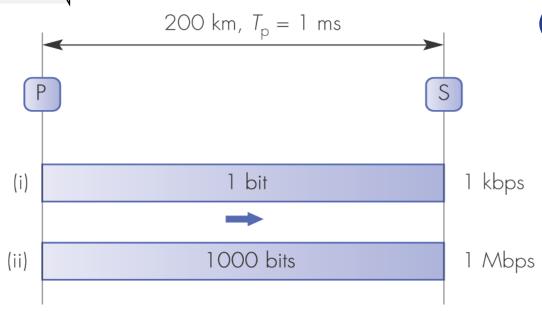


#### Stop-and-wait flow control: Example (3)





#### Leased line



Frame transmission time  $T_{ix}$  = Number of bits in frame / Bit rate

(i) 1 kbps: 
$$T_{ix} = 1000 \text{ b} / 10^3 \text{ b/s} = 1 \text{ s}$$

(ii) 1 Mbps: 
$$T_{ix} = 1000 \text{ b} / 10^6 \text{ b/s} = 10^{-3} \text{ s} = 1 \text{ ms}$$

(iii) 1 Gbps: 
$$T_{ix} = 1000 \text{ b} / 10^9 \text{ b/s} = 10^{-6} \text{ s} = 1 \text{ }\mu\text{s}$$

(b) 200 km long leased line. Signal propagation speed is 2x10<sup>8</sup> m/s.

Frame propagation delay  $T_p = 200x10^3 \text{ m} / 2x10^8 \text{ m/s} = 10^{-3} \text{ s}$ 

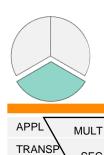
(i) 
$$a = T_p/T_{ix} = 10^{-3} \text{ s} / 1 \text{ s} = 1 \times 10^{-3} \rightarrow (1 + 2a) \approx 1, U = 1$$

(ii) 
$$a = 10^{-3} \text{ s} / 10^{-3} \text{ s} = 1 \rightarrow (1 + 2a) > 1$$
,  $U = 1/(1+2) = 0.33$ 

(iii) 
$$a = 10^{-3} \text{ s} / 10^{-6} \text{ s} = 1000 \rightarrow U = 0.0005$$

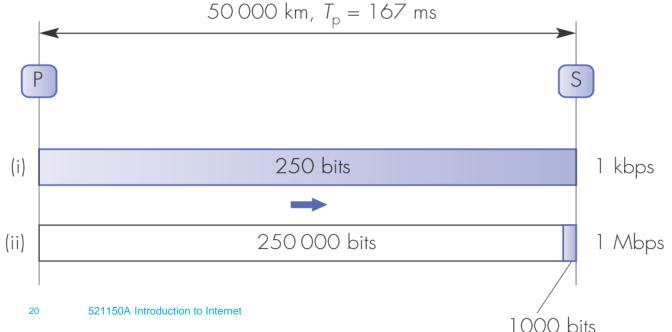


#### Stop-and-wait flow control: Example (4)



DATA LINK
PHYSICAL

#### Satellite link



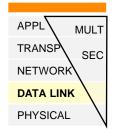
Frame transmission time T<sub>ix</sub> = Number of bits in frame / Bit rate

- (i) 1 kbps:  $T_{ix} = 1000 \text{ b} / 10^3 \text{ b/s} = 1 \text{ s}$
- (ii) 1 Mbps:  $T_{ix} = 1000 \text{ b} / 10^6 \text{ b/s} = 10^{-3} \text{ s} = 1 \text{ ms}$
- (c) A 50000 km long satellite link. Signal propagation speed is 3x108 m/s.

Frame propagation delay  $T_p = 50x10^6 \text{ m} / 3x10^8 \text{ m/s} = 0.167 \text{ s}$ 

- (i)  $a = T_p/T_{ix} = 0.167 \text{ s} / 1 \text{ s} = 0.167 \rightarrow (1 + 2a) > 1$ , U = 1/(1+0.334) = 0.75
- (ii)  $a = 0.167 \text{ s} / 10^{-3} \text{ s} = 167 \rightarrow (1 + 2a) > 1$ , U = 1/(1+334) = 0.003





#### Stop-and-wait flow control: Example (5)

#### Observations

- Relatively short links
  - Link utilization is 100% for lower bit rates
- Longer terrestial links
  - Link utilization is high for low bit rates
  - Link utilization falls off significantly as bit rate increases
- Long satellite links
  - Link utilization is poor (due to high propagation delay)

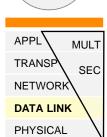
#### →Stop-and-wait flow-control suitable for short and low bit rate links

E.g. links based on modems and analog PSTN

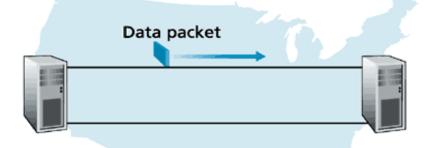


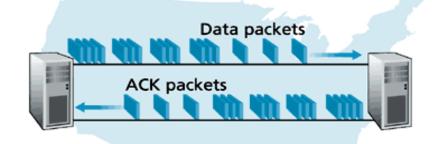
### Pipelining (1)





Primary (sender, source) is allowed to send multiple packets
 without waiting for acknowledgements





a. A stop-and-wait protocol in operation

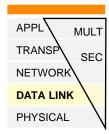
b. A pipelined protocol in operation

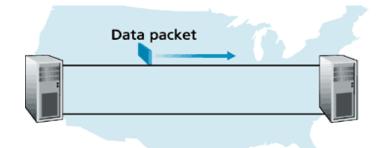
- Much better utilization of link capacity, with increased buffer requirements and larger ranges of sequence numbers
- Bi-directional, requires full-duplex link
- Requires flow control with sliding windows

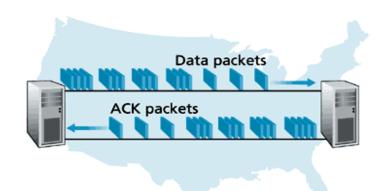


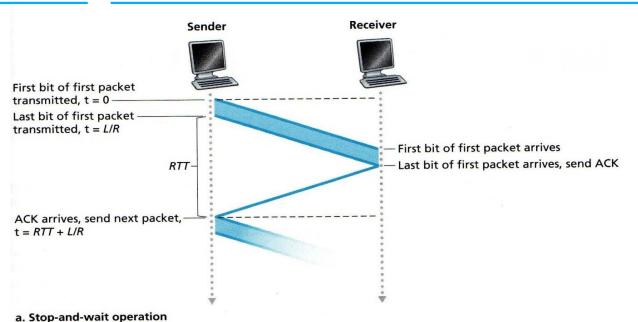
### Pipelining (2)

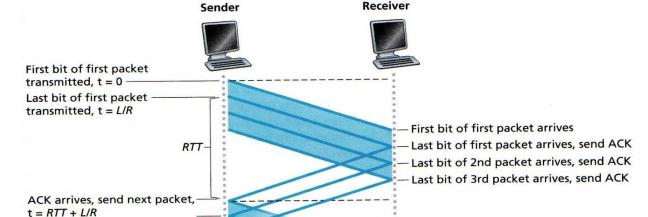








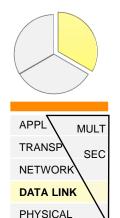


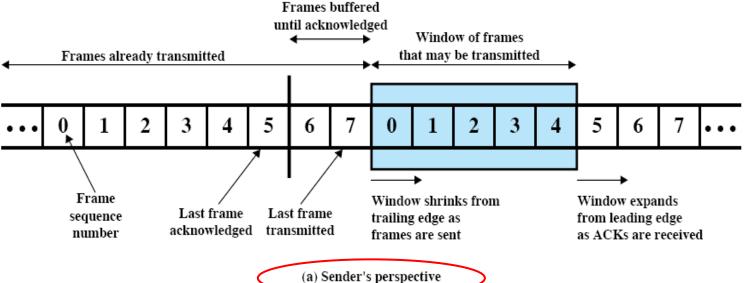


b. Pipelined operation



### -Flow control: Sliding windows (1)





Window of frames that may be accepted

O 1 2 3 4 5 6 7 0 1 2 3 4 5 6 7 ...

Window shrinks from trailing edge as frames are received

Window shrinks from trailing edge as frames are received

Window shrinks from trailing edge as frames are received

- Receiver has buffer W long
- Transmitter can send up to W frames without ACK
- Each frame is numbered
- ACK includes number of next frame expected



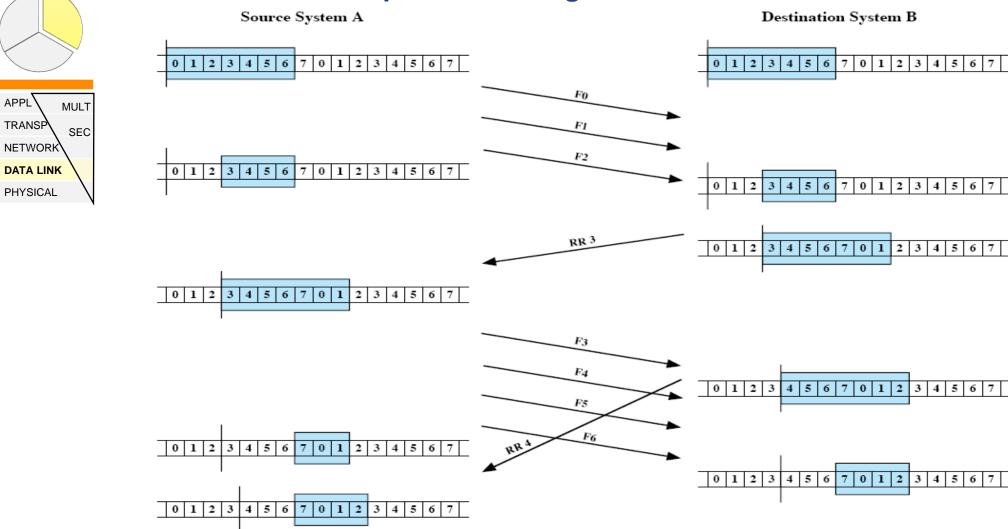
TRANSP

NETWORK

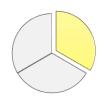
PHYSICAL

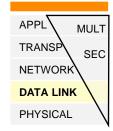
### Flow control: Sliding windows (2)

#### **Example with sliding window of 7 frames**









#### Flow control: Performance enhancements

 Receiver acknowledges multiple I frames with one ACK

#### Piggybacking

 Acknowledgements are attached to I frames (ACK field), instead of being transmitted as separate ACK frames

521150A Introduction to Internet University of Oulu



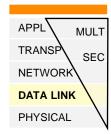
521150A Introduction to Internet

University of Oulu

27







#### **Error control**

- Two types of errors
  - Lost frame
  - Damaged frame
- Mechanisms used for error control
  - Error detection
  - Positive acknowledgments
  - Retransmission after timeout (retransmission timer)
  - Negative acknowledgment and retransmission
- Three types of ARQ (automatic repeat request)
  - Stop-and-wait ARQ
  - Go-back-N ARQ
  - Selective repeat ARQ

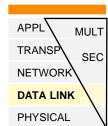
**Continuous RQ** 

(uses sliding window flow control)



### Stop-and-wait ARQ (aka idle RQ)





error free

corrupted
I frame

Primary, P I(N) I(N + 1)

Secondary, S I(N) I(N + 1)

Timer started Timer stopped

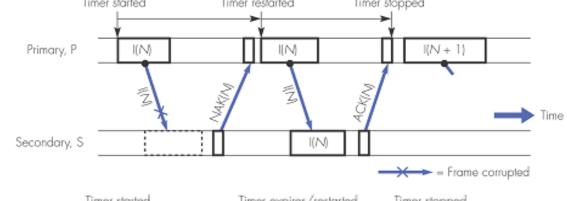
Timer stopped

Timer stopped

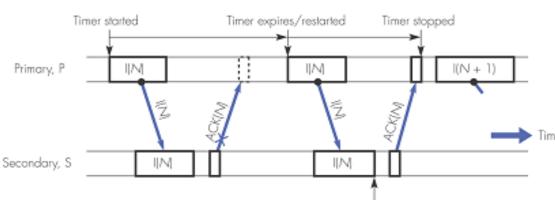
Timer stopped

Timer stopped

Timer stopped



corrupted ACK frame



Duplicate detected

#### **Building blocks**

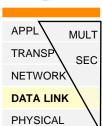
- Retransmission timer
- Error detection
- Receiver feedback(ACK, NAK)
- Retransmission



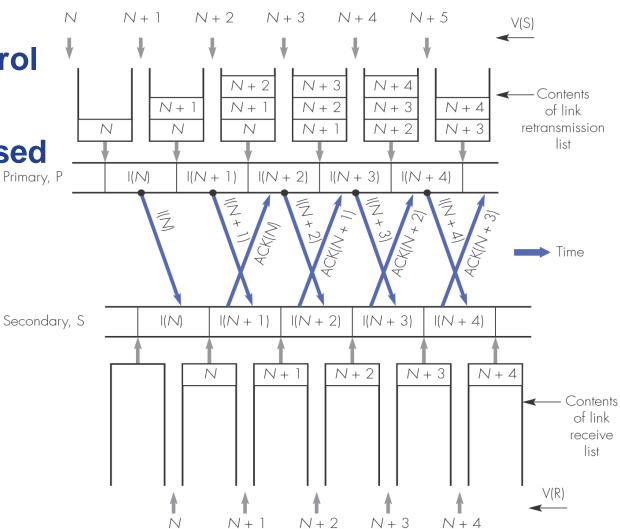
#### **Continuous RQ**

### Continuous RQ frame sequence without transmission errors:





- Incorporate flow control
- Link utilization much improved with increased buffer storage requirements
- Bidirectional
  - Requires duplex link
- Two basic types
  - Go-back-N ARQ
  - Selective repeat ARQ



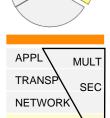
V(S) = send sequence variable

V(R) = receive sequence variable



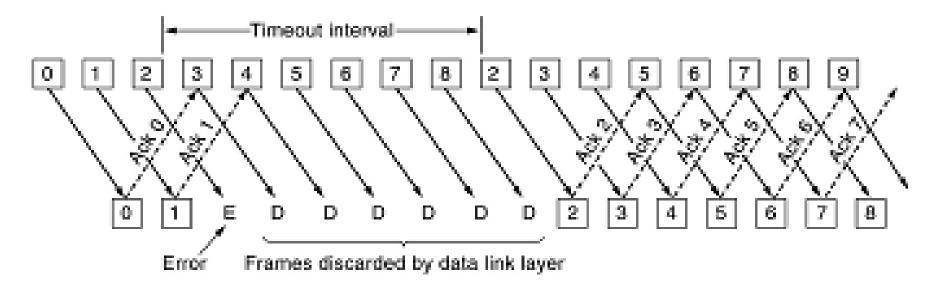
### Go-back-N ARQ (1)





DATA LINK
PHYSICAL

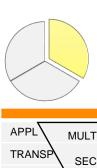
- Receiver discards all frames after an erroneous frame
- Sender resends all discarded frames
  - Sender has to buffer unacknowledged frames





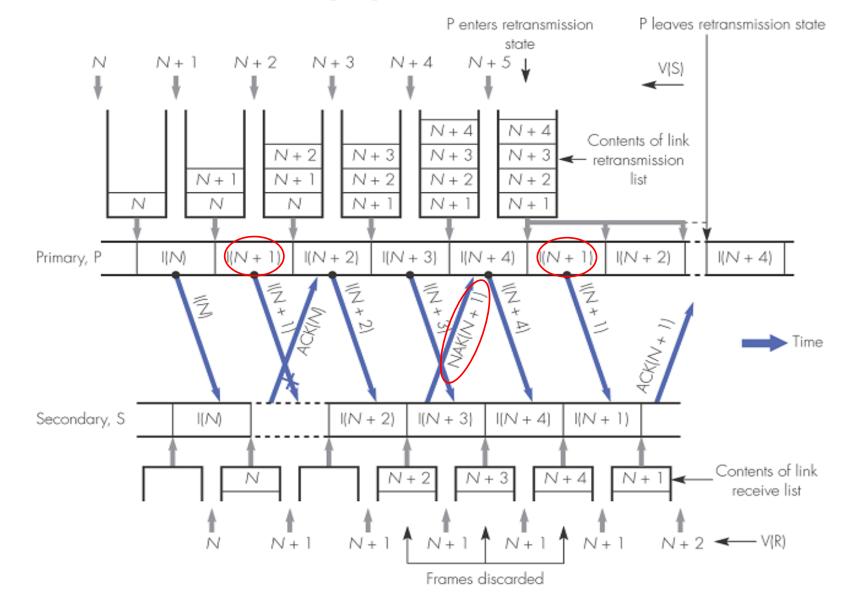
### Go-back-N ARQ (2)

#### Corrupted I frame:



NETWORK

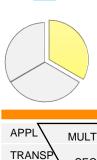
DATA LINK
PHYSICAL



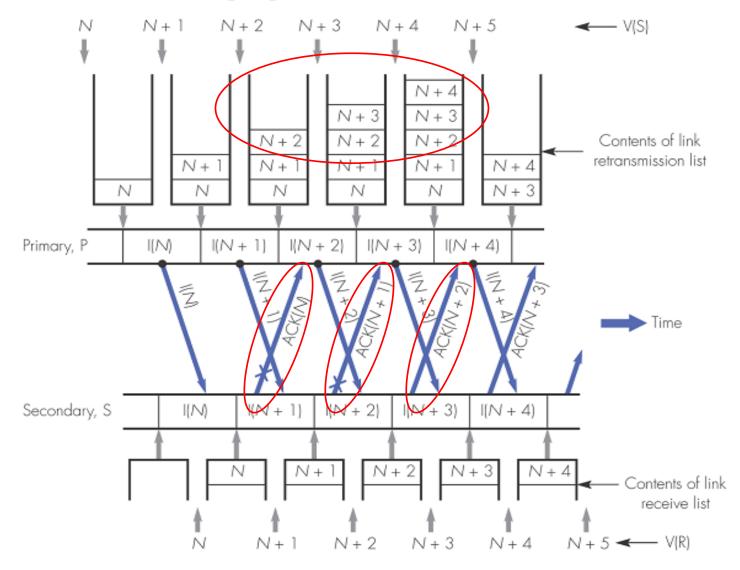


### Go-back-N ARQ (3)

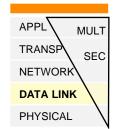
#### Corrupted ACK frame:



DATA LINK
PHYSICAL

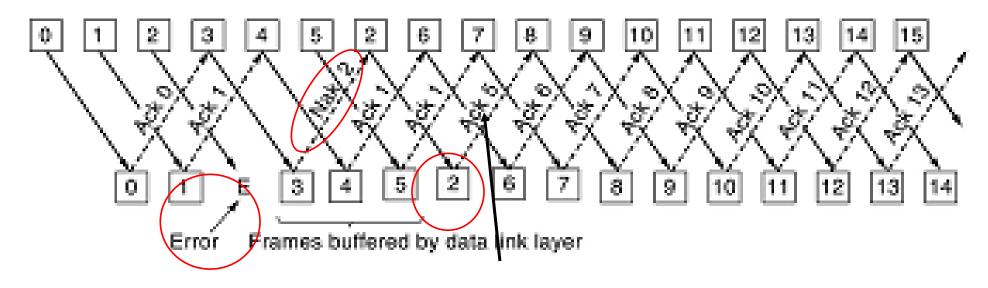






### Selective repeat ARQ (1)

- Receiver buffers frames received after an erroneous frame
- Sender retransmits only the erroneous frame
  - Sender has to buffer unacknowledged frames

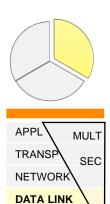


521150A Introduction to Internet University of Oult

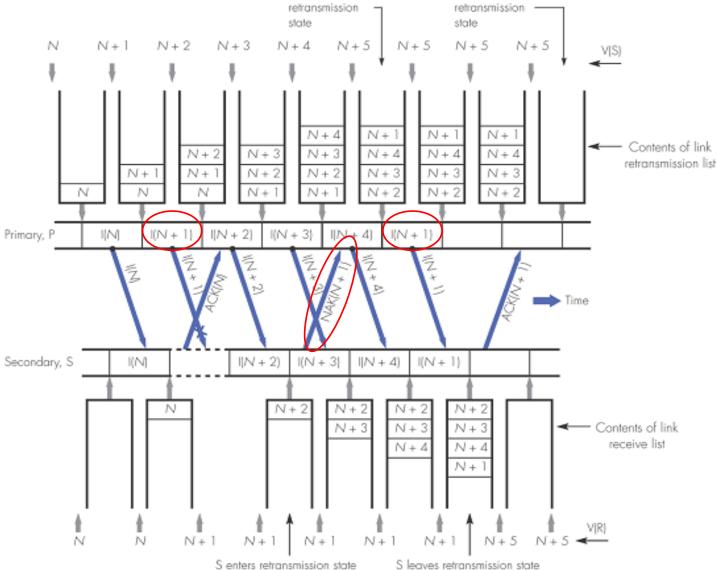


### Selective repeat ARQ (2)





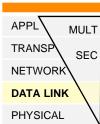
PHYSICAL

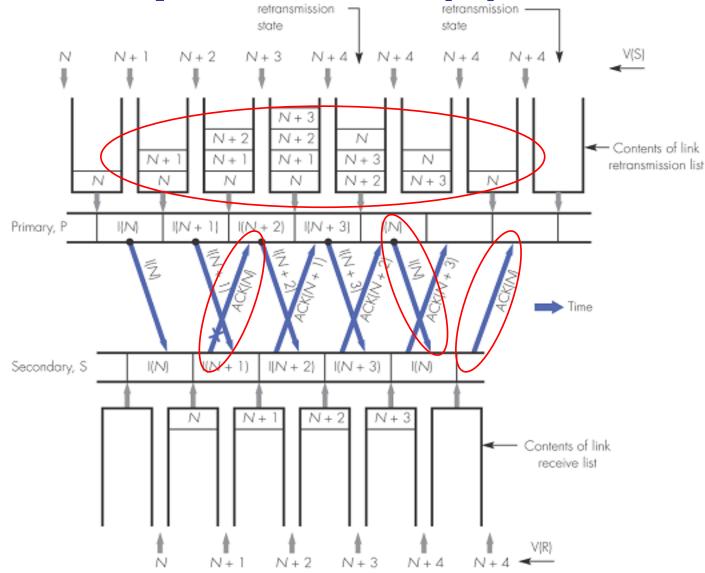


P enters

## Selective repeat ARQ (3) Corrupted ACK frame:







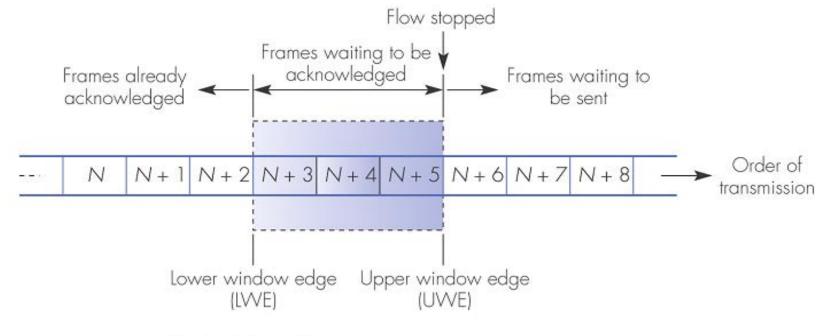


### ARQ: Send/receive window sizes





37



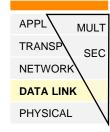
Send window, K = 3

Protocol	Send window	Receive window
Idle RQ	1	1
Selective repeat	K	<i>K</i>
Go-back-N	K	1

521150A Introduction to Internet

University of Oulu



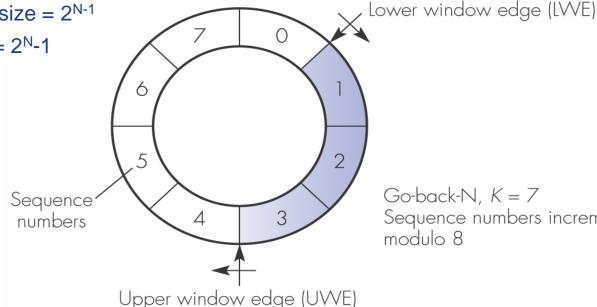


# ARQ: Sequence numbers (frame ID's)

Number of sequence numbers required for window size K

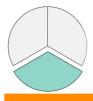
Protocol	Maximum number of frame identifiers
Idle RQ	2
Selective repeat	2K
Go-back-N	K + 1

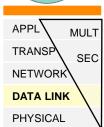
- In practice, *N bits* reserved for sequence numbers
  - Selective repeat: max window size =  $2^{N-1}$
  - Go-back-N: max window size =  $2^{N-1}$
  - Example: Go-back-N with window size K=7 (need 8 sequence numbers, i.e. 3-bit field,  $2^3=8$ )



Go-back-N, K = 7Sequence numbers incremented modulo 8







# Performance: Error-free stop-and-wait flow control

Link utilization: U = 1/(1+2a)

$$a = T_{prop} / T_{trans}$$

- a ~ Number of frames in link of bit length B, when frame length is L
- a ~ Ratio between propagation delay and transmission delay

$$a = (d/V)/(L/R) = [Rd/V)] / L$$

Rd/V = length of medium in bits (bit length)

L = length of frame in bits



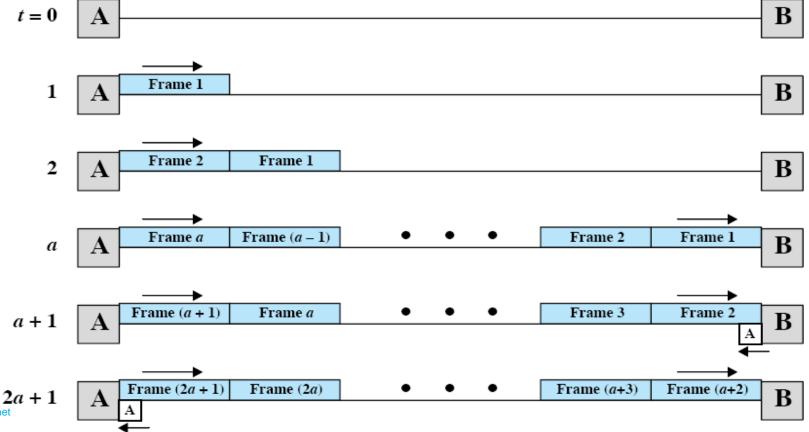


# Performance: Error-free sliding window flow control (1)

Case 1: W (window size)  $\geq$  2a+1

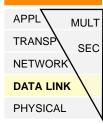
### ACK reaches A at t = 2a+1

→ A can transmit without pause → utilization = 1







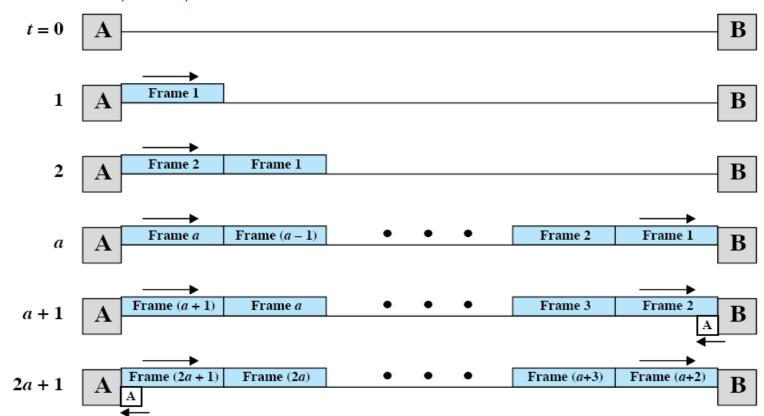


# Performance: Error-free sliding window flow control (2)

Case 2: W (window size) < 2a+1

A exhausts its send window at t = W frames

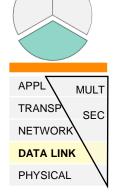
- $\rightarrow$  A cannot send additional frames until t = 2a+1
- $\rightarrow$  utilization = W/(2a + 1)





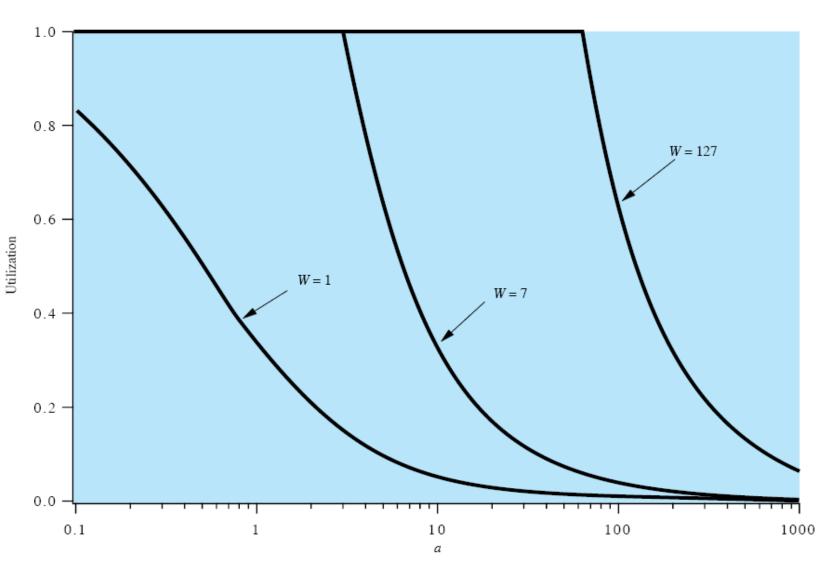
Performance: Error-free sliding window flow

control (3)



### **Utilization:**

$$U = \begin{cases} 1 & W \ge 2a+1 \\ \frac{W}{2a+1} & W < 2a+1 \end{cases}$$

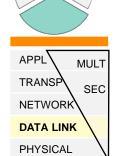


42



## Performance: Stop-and-wait ARQ (1)





Utilization of error-free transmission:

$$U = \frac{T_f}{T_t} \approx \frac{T_f}{T_f + 2T_p} = \frac{1}{1 + 2a}$$

where  $T_f$  = time for emitting single frame

T<sub>t</sub> = total time of line being engaged in transmission of single frame

 $T_p$  = propagation time

- If errors occur, then utilization

$$U = \frac{T_f}{N_r T_t} = \frac{1}{N_r (1 + 2a)}$$

where N<sub>r</sub> is the expected number of transmissions of a frame



**NETWORK** 

**DATA LINK** PHYSICAL

## Performance: Stop-and-wait ARQ (2)

- N<sub>r</sub> derived assuming
  - A single data frame is in error with probability P
  - ACK and NAK are never in error
- Propability it takes exactly k attempts to transmit a frame successfully is  $P^{k-1}(1-P)$
- Then expected number of transmissions of a frame

$$N_{r} = E[transmission] = \sum_{i=1}^{\infty} (i \times \Pr[i \ transmissions]) = \sum_{i=1}^{\infty} (iP^{i-1}(1-P)) = \frac{1}{1-P}$$

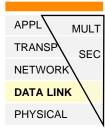
Derivation uses equality

$$\sum_{i=1}^{\infty} (iX^{i-1}) = \frac{1}{(1-X)^2} \text{ for } (-1 < X < 1)$$

Hence utilization

$$U = \left\{ \frac{1 - P}{1 + 2a} \right\}$$





### Performance: Selective repeat ARQ

**Utilization without errors was** 

$$U = \begin{cases} 1 & W \ge 2a+1\\ \frac{W}{2a+1} & W < 2a+1 \end{cases}$$

Again utilization is divided by

$$N_r = \frac{1}{1 - P}$$

Thus utilization for selective repeat ARQ

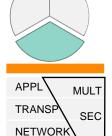
$$U = \begin{cases} 1 - P & W \ge 2a + 1 \\ \frac{W(1 - P)}{2a + 1} & W < 2a + 1 \end{cases}$$

Note:  $W=1 \rightarrow reduces$  to stop-and-wait ARQ utilization



# Performance: Go-back-N ARQ (1)





**DATA LINK** PHYSICAL

Error in single frame generates requirement to retransmit K frames

 $N_r = \text{E[number of transmitt ed frames to successful ly transmit tone frame]} = \sum_{i=1}^{\infty} f(i)P^{i-1}(1-P)$ 

where f(i) is the total number of frames transmitted if the original frame must be transmitted i times:

$$f(i) = 1 + (i-1)K = (1-K) + Ki$$

**Substituting yields** 

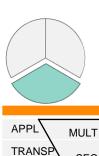
$$N_r = (1 - K) \sum_{i=1}^{\infty} P^{i-1} (1 - P) + K \sum_{i=1}^{\infty} i P^{i-1} (1 - P)$$
$$= 1 - K + \frac{K}{1 - P} = \frac{1 - P + KP}{1 - P}$$

derivation uses equality

$$\sum_{i=1}^{\infty} X^{i-1} = \frac{1}{1-X} \text{ for } (-1 < X < 1)$$



# Performance: Go-back-N ARQ (2)



DATA LINK
PHYSICAL

It can be approximated that

$$K = (2a+1)$$
 for  $W \ge (2a+1)$   
 $K = W$  for  $W < (2a+1)$ 

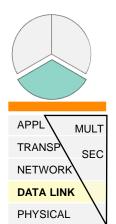
Thus utilization for Go-back-N ARQ

$$U = \begin{cases} \frac{1-P}{1+2aP} & W \ge 2a+1\\ \frac{W(1-P)}{(2a+1)(1-P+WP)} & W < 2a+1 \end{cases}$$

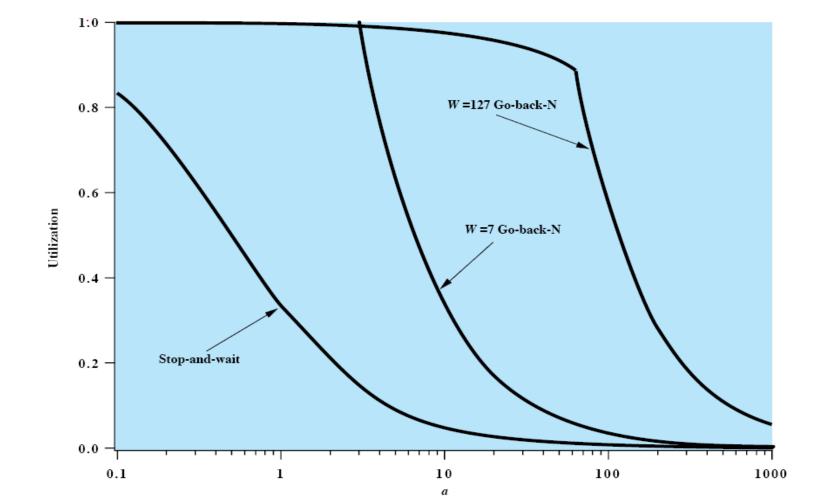
Note: W=1 → reduces to stop-and-wait ARQ utilization



# Performance: ARQ comparison



ARQ utilization as of a function of a (P=10<sup>-3</sup>)
Selective repeat ARQ is effectively equal to Go-back-N ARQ





# Key points to remember

### 1. Main functions of Link Control

### 2. Flow control and its basic types:

- Stop&wait
- Pipelining
- Sliding window

### 3. Error control and its basic types:

- Stop&wait ARQ
- Go-Back-N ARQ
- Selective repeat

521150A Introduction to Internet University of Oulu

