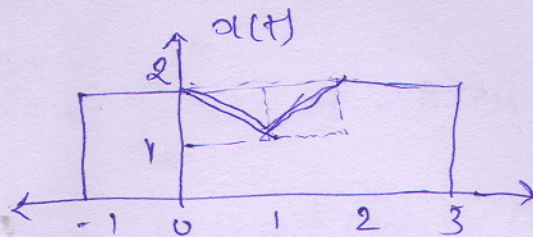


Tutorial - 6 - Que.

① For the signal $x(t)$ shown below, find

a) $X(0)$

b) $\int_{-\infty}^{+\infty} X(\omega) d\omega$

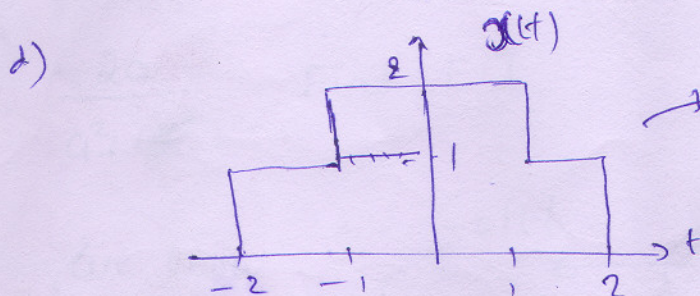


② Find the FT of the following signals.

a) $x_1(t) = \text{A rect}(t/2\tau)$

b) $x_L(t) = \frac{2a}{a^2 + t^2}$

c) $x(t) = \pi \left[\frac{(t-1)}{2} \right]$

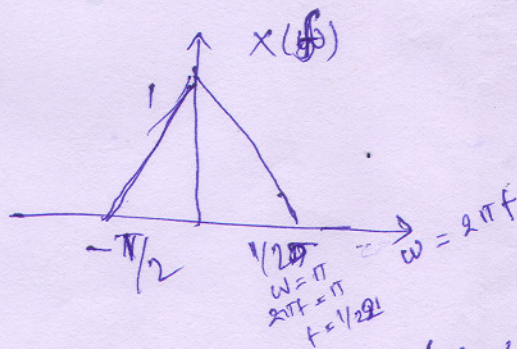
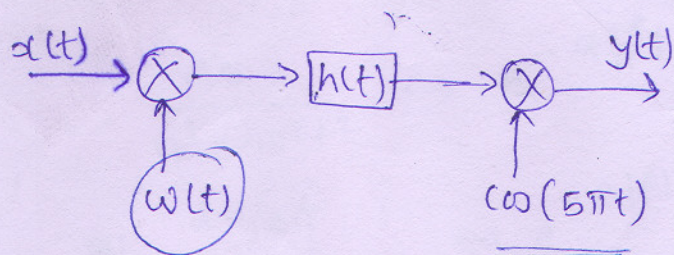


$\rightarrow x(t) + x_1(t-1) + x_1(t+1)$
 $x(t/2) + x(t)$

$\omega = \pi$

$2\pi f = \pi$
 $f = \frac{1}{2}$

③ Consider the system shown in fig. a). The FT of i/p signal is shown in fig. b). Find the FT of $y(t)$ given that $w(t) = \cos(5\pi t)$ and $h(t) = \frac{\sin(6\pi t)}{\pi t}$



④ Given $y(t) = x(t) * h(t)$, $g(t)$ and $g(t) = x(3t) * h(3t)$ such that $g(t) = Ay(Bt)$, so, what is A & B?

⑤ A causal & stable LTI system has the freq. response $H(\omega) = \frac{j\omega + 4}{6 - \omega^2 + 5j\omega}$

a) Find the I.R. b) What is the o/p when the i/p applied is $x(t) = e^{-4t}u(t) - te^{-4t}u(t)$

Tutorial-6 Answers.

Q.1

a) $X(0) = \int_{-\infty}^{+\infty} x(t) \cdot e^{-j2\pi(0)t} \cdot dt = \int_{-\infty}^{+\infty} x(t) \cdot dt = \text{Area under } x(t)$

$$= (1 \times 2) + \left\{ (3 \times 2) - \left(\frac{1}{2} \times 1 \times 2 \right) \right\}$$

$$= 2 + 6 - 1 = \underline{7} \quad \checkmark$$

b) $\int_{-\infty}^{+\infty} X(f) \cdot df = \int_{-\infty}^{+\infty} X(f) \cdot e^{j2\pi f(0)} \cdot df = x(0) = \underline{2}$

Q.2

$\frac{2a}{a^2 + t^2} \xrightarrow{\text{F.T.}} \frac{2a}{a^2 + \omega^2}$

$\frac{2a}{a^2 + 4\pi^2 f^2}$ Find F.T.

We know

By duality

$e^{-a|t|} \leftrightarrow \frac{2a}{a^2 + 4\pi^2 f^2}$

$\frac{2a}{a^2 + 4\pi^2 f^2} \leftrightarrow e^{-a|f|}$

for all t
for all f

$\frac{2a}{a^2 + 4\pi^2 f^2} \leftrightarrow e^{-a|f|}$

$\frac{2a/2\pi}{(a/2\pi)^2 + t^2} \leftrightarrow e^{-a|f|}$

taking $\frac{a}{2\pi} = \tilde{a}$

$\frac{2\tilde{a}}{\tilde{a}^2 + t^2} \leftrightarrow 2\pi \cdot e^{-2\pi\tilde{a}|f|}$

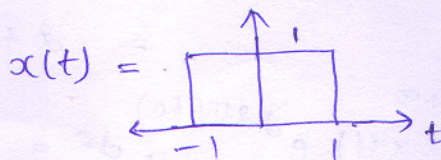
\Rightarrow so, $\frac{2a}{a^2 + t^2} \leftrightarrow 2\pi \cdot e^{-2\pi a|f|}$

b) $x(t) = \Pi\left[\left(\frac{t-1}{2}\right)\right] = \text{rectangular fcn.}$

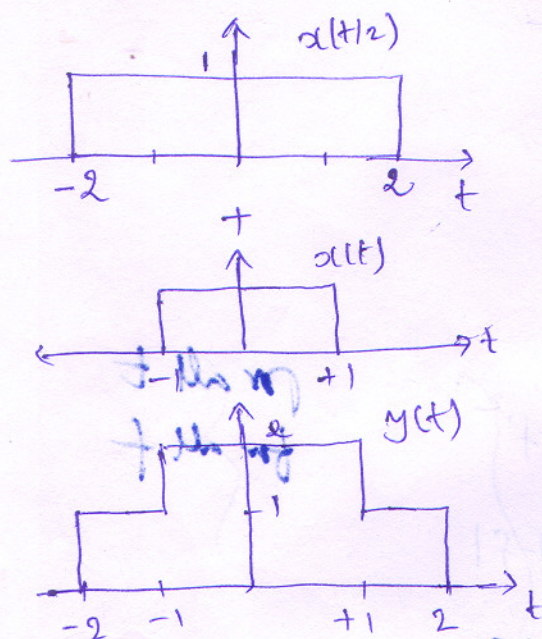
$\frac{t-1}{2} = \tau$

we know $\Pi(t/2) \leftrightarrow 2 \text{sinc}(2f)$, now by time shifting property $\Pi\left[\left(\frac{t-1}{2}\right)\right] \leftrightarrow e^{-j2\pi f(1)} \cdot 2 \text{sinc}(2f)$

c) Here, if we take



then we can represent $y(t)$ as follows.



so, $y(t) = x(t/2) + x(t)$

we know $x(t) = \text{rect}(t/2) \leftrightarrow 2 \text{sinc}(2f)$

so, $y(t) = x(t/2) + x(t)$

$Y(f) = \frac{1}{(1/2)} X\left(\frac{f}{1/2}\right) + X(f)$

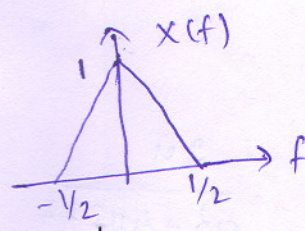
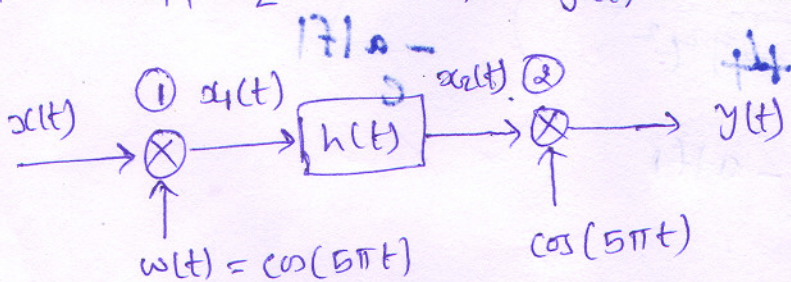
$= 2X(2f) + X(f)$

$= 2 \text{sinc}(4f) + 2 \text{sinc}(2f)$

we can take

$y(t) = x(t) + x(t-1) + x(t+1)$ also.

Q.3



At first sum at point (1).

we have $x_1(t) = x(t) \cdot \cos(5\pi t)$

$X_1(f) = X(f) * \left[\frac{1}{2} (\delta(f-5/2) + \delta(f+5/2)) \right]$

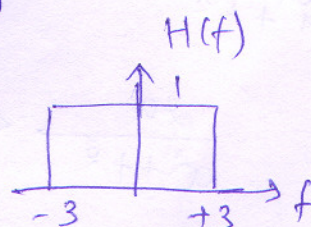
$= \frac{1}{2} [X(f-5/2) + X(f+5/2)]$

then at point (2)

$x_2(t) = x_1(t) * h(t) \Rightarrow X_2(f) = X_1(f) \cdot H(f)$

Now, $h(t) = \frac{\sin(6\pi t)}{\pi t}$

$\leftrightarrow H(f) = \text{rect}(f/6)$



Use $x(t) y(t) \leftrightarrow X(f) * Y(f)$

$x(t) * y(t) \leftrightarrow X(f) Y(f)$

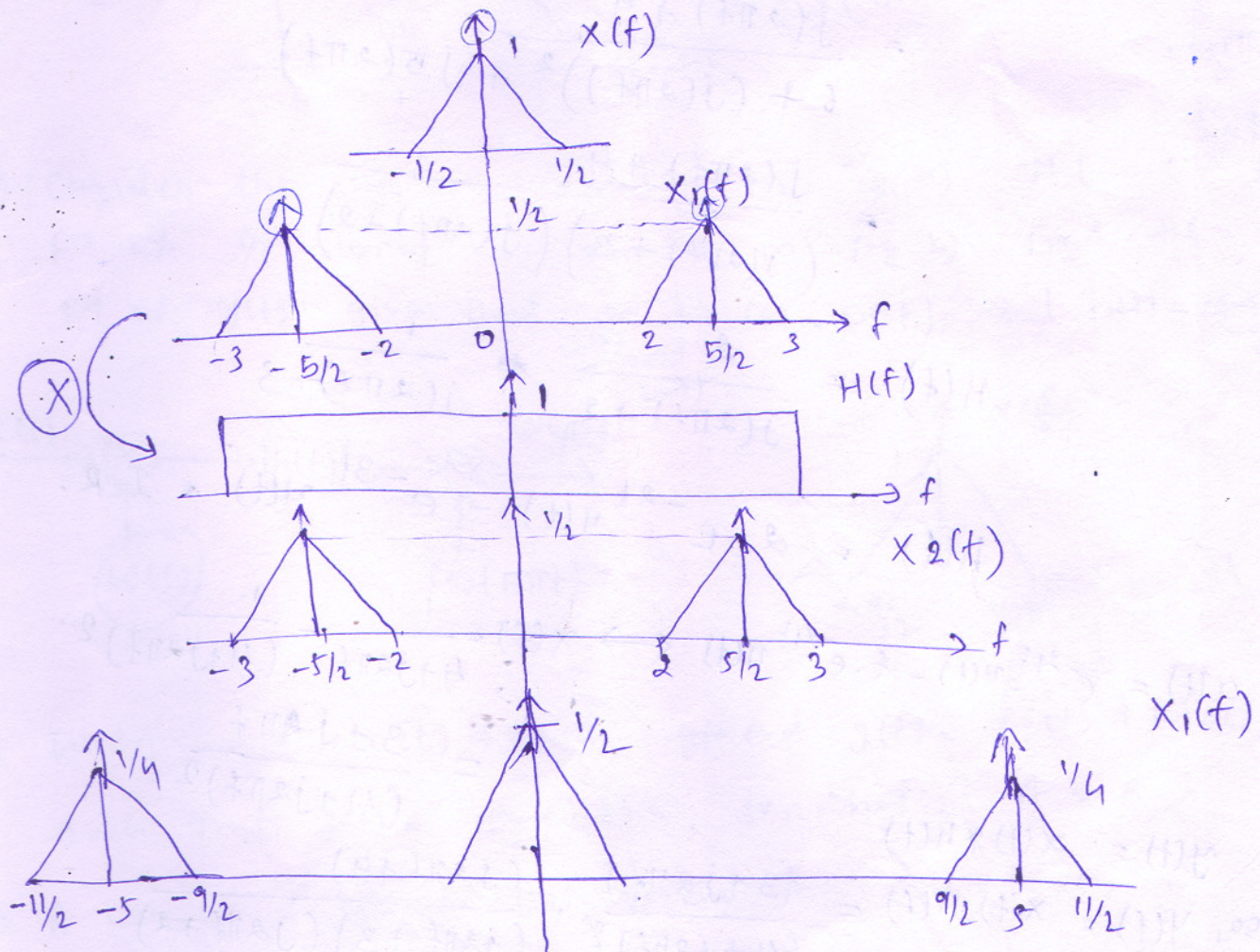
$\leftrightarrow X(f) Y(f)$

Since $X_1(f)$ ^{freq.} range is within the $H(f)$ freq. range, so $X_1(f)$ will be multiplied by 1, and as an output we are getting $X_1(f)$ only.

→ At point $Y(t)$

$$y(t) = x_2(t) \cdot \cos 5\pi t$$

$$\begin{aligned} Y(f) &= X_2(f) * \left[\frac{1}{2} (\delta(f-5/2) + \delta(f+5/2)) \right] \\ &= \frac{1}{2} [X_2(f-5/2) + X_2(f+5/2)] \\ &= \frac{1}{2} [X_1(f-5/2) + X_1(f+5/2)] \\ &= \frac{1}{4} [X(f-5/2-5/2) + X(f-5/2+5/2) + X(f+5/2-5/2) + X(f+5/2+5/2)] \\ &= \frac{1}{4} [X(f-5) + X(f+5)] + \frac{1}{2} X(f) \end{aligned}$$



Q.4

$$g(t) = x(3t) * h(3t)$$

$$G(f) = \frac{1}{3} X\left(\frac{f}{3}\right) \cdot \frac{1}{3} H\left(\frac{f}{3}\right) = \frac{1}{9} X\left(\frac{f}{3}\right) \cdot H\left(\frac{f}{3}\right) = \frac{1}{9} Y\left(\frac{f}{3}\right) \quad \dots (1)$$

$$g(t) = \frac{1}{9} \cdot x(3t) \cdot A \cdot y(Bt)$$

$$G(f) = \frac{A}{B} Y\left(\frac{f}{B}\right) \quad \dots (2)$$

Comparing (1) & (2) we get A = 1/3, B = 3

Q.5

$$H(f) = H(f) = \frac{j(2\pi f) + 4}{6 - (4\pi^2 f^2) + \cancel{55(2\pi f)} + 10j\pi f}$$

$$= \frac{j(2\pi f) + 4}{6 - (j(2\pi f))^2 + j(10\pi f)}$$

$$= \frac{j(2\pi f) + 4}{6 + (j(2\pi f))^2 + j5(2\pi f)}$$

$$= \frac{j(2\pi f) + 4}{(j(2\pi f) + 3)(j(2\pi f) + 2)}$$

$$H(f) = \frac{2}{j(2\pi f) + 2} + \frac{1}{j(2\pi f) + 3}$$

$$h(t) = 2 \cdot e^{-2t} u(t) - e^{-3t} u(t) = I.R.$$

$$\text{Here } x(t) = e^{-4t} u(t) - t \cdot e^{-4t} u(t) \leftrightarrow X(f) = \frac{1}{4 + j2\pi f} - \frac{1}{(4 + j2\pi f)^2}$$

$$= \frac{3 + j4\pi f}{(4 + j2\pi f)^2}$$

$$\text{Now, } y(t) = x(t) * h(t)$$

$$\text{So, } Y(f) = X(f) \cdot H(f) = \frac{(3 + j4\pi f)}{(4 + j2\pi f)^2} \cdot \frac{(j2\pi f + 4)}{(j2\pi f + 3)(j2\pi f + 2)}$$

$$Y(f) = \frac{1}{(j2\pi f + 2)(j2\pi f + 4)} = \frac{1/2}{j2\pi f + 2} - \frac{1/2}{j2\pi f + 4}$$

$$\text{So, } \boxed{y(t) = \frac{1}{2} e^{-2t} u(t) - \frac{1}{2} e^{-4t} u(t)}$$