

Unit - 4

Unit - 4 (Point Estimation)

* Methods of Estimation -→ Method of maximum likelihood estimation :-

↗ 1st time C.F. Gauss
 ↗ Prof. R.A. Fisher

§ Likelihood function:- Let, x_1, x_2, \dots, x_n be a random sample of size n from a population with density function $f(x, \theta)$. Then, the likelihood function of the sample values x_1, x_2, \dots, x_n , usually denoted by $L = L(\theta)$ is their joint density function -

$$L = f(x_1, \theta) f(x_2, \theta) f(x_3, \theta) \cdots f(x_n, \theta)$$

$$\Rightarrow L = \prod_{i=1}^n f(x_i, \theta)$$

$$L(\theta) = \prod_{i=1}^n f(x_i, \theta)$$

To find the maximum value of likelihood function $L(\theta)$, we follow the steps below:-

$$(i) \frac{\partial}{\partial \theta} L(\theta) = 0 \Rightarrow \text{points of extrema.}$$

$$(ii) \frac{\partial^2}{\partial \theta^2} L(\theta). \quad \text{If } \frac{\partial^2}{\partial \theta^2} L(\theta) < 0, \theta \text{ is a point of maxima.}$$

but $\theta = \hat{\theta}$.

Then, the maximum likelihood estimator is -

$$L(\hat{\theta}).$$

Unbiasedness
Consistency
Efficiency

$L(\theta)$.

Properties of Maximum Likelihood Estimators:-

(i) The first & second order derivatives i.e. $\frac{\partial}{\partial \theta} \log L$ and $\frac{\partial^2}{\partial \theta^2} \log L$ exist and are continuous functions of θ in a range R for almost all x .

(ii) The 3rd order derivative $\frac{\partial^3}{\partial \theta^3} \log L$ exists such that

$$\left| \frac{\partial^3}{\partial \theta^3} \log L \right| < M(x), \text{ where } E[M(x)] < k, \text{ a finite quantity.}$$

(iii) For every θ in R ,

$$E\left(-\frac{\partial^2}{\partial \theta^2} \log L\right) = \int_{-\infty}^{\infty} \left(-\frac{\partial^2}{\partial \theta^2} \log L\right) L dx = I(\theta),$$

↑

is finite & non-zero.

(iv) The range of integration is independent of θ . But if the range of integration depends on θ , then $f(x, \theta)$ vanishes at the extremes depending on θ .

$$E(x) = \int_{-\infty}^{\infty} x f(x) dx$$

* Cramer-Rao Theorem — with probability approaching unity as $n \rightarrow \infty$, the likelihood equation $\frac{\partial}{\partial \theta} \log L = 0$, has a solution which converges in probability to the true value θ_0 . In other words, M.L.E's are consistent.

$$\text{As } n \rightarrow \infty, \quad \Pr\{|E(T_n) - \theta| < \epsilon\} \rightarrow 1, \quad \text{as } n \rightarrow \infty$$

$$\Pr\{|E(\hat{\theta}) - \theta| < \epsilon\} \rightarrow 1.$$

Remark:- MLE's are always consistent estimators but need not be unbiased.

For example - in sampling from $N(\mu, \sigma^2)$ population -
 $\text{MLE}(\mu) = \bar{x}$ (sample mean), which is both unbiased and consistent.

but $\text{MLE}(\sigma^2) = s^2$ (sample variance), which is consistent but not unbiased.

$$E(\frac{n}{n-1}s^2) = \sigma^2$$

Theorem (Hazard Bazar's theorem):- Any consistent solution of the likelihood equation provides a maximum of the likelihood with probability tending to unity as the sample size (n) $\rightarrow \infty$.

$$\frac{\partial}{\partial \theta} \log L = 0 \leftarrow \begin{matrix} \text{maximum of} \\ \text{the likelihood} \\ \text{as } n \rightarrow \infty. \end{matrix}$$

Theorem:- If M.L.E. exists, it is the most efficient in the class of such estimators.

Maximum likelihood estimator -

$$\hat{\theta} = \hat{\theta} \rightarrow \text{most efficient}$$

$$\theta = \hat{\theta} \rightarrow \text{most efficient}$$

$\epsilon = 1$

Invariance property of M.L.E:-

If T is the M.L.E of θ , and $\psi(\theta)$ is one-to-one function of θ , then $\psi(T)$ is the M.L.E of $\psi(\theta)$.

Ex- In random sampling from normal population $N(\mu, \sigma^2)$, find the maximum likelihood estimator for μ when σ^2 is known.

Solution: Here, $X \sim N(\mu, \sigma^2)$, then -

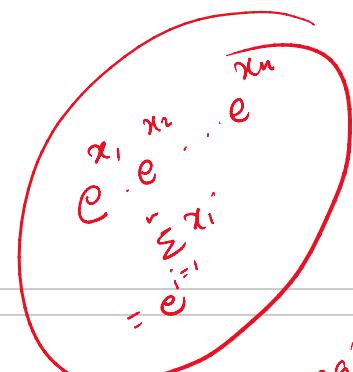
$$f(x, \theta) = \frac{1}{\sigma \sqrt{2\pi}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

$$\text{So, } f(x_i, \theta) = \frac{1}{\sigma \sqrt{2\pi}} e^{-\frac{(x_i-\mu)^2}{2\sigma^2}}$$

$$\frac{1}{\sigma \sqrt{2\pi}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

Now, likelihood function is -

$$\begin{aligned} L(\theta) &= \prod_{i=1}^n f(x_i, \theta) = \prod_{i=1}^n \frac{1}{\sigma \sqrt{2\pi}} e^{-\frac{(x_i-\mu)^2}{2\sigma^2}} \\ &= \frac{1}{\sigma^n \sqrt{(2\pi)^n}} e^{-\frac{(x_1-\mu)^2}{2\sigma^2}} \cdot \frac{1}{\sigma^n \sqrt{(2\pi)^n}} e^{-\frac{(x_2-\mu)^2}{2\sigma^2}} \cdots \frac{1}{\sigma^n \sqrt{(2\pi)^n}} e^{-\frac{(x_n-\mu)^2}{2\sigma^2}} \\ &= \left(\frac{1}{\sigma \sqrt{2\pi}} \right)^n e^{-\frac{(x_1-\mu)^2}{2\sigma^2}} \cdots e^{-\frac{(x_n-\mu)^2}{2\sigma^2}} \end{aligned}$$



$$\frac{\partial}{\partial \theta} \log L = 0$$

$$2 \log n = \log 2^n$$

~~$$\frac{\partial}{\partial \theta} \log L = 0$$~~

$$1 - \sum_{i=1}^n \frac{(x_i-\mu)^2}{2\sigma^2} \quad \checkmark$$

$$\frac{\partial}{\partial \theta} \log L$$

$$2^{10^4}$$

$$L(\theta) = \frac{1}{(2\pi)^n} e^{-\sum_{i=1}^n \frac{(x_i - \mu)^2}{2\sigma^2}}$$

$$\Rightarrow \log L = -\frac{n}{2} \log(2\pi) - \frac{n}{2} \log \sigma^2 - \frac{1}{2\sigma^2} \sum_{i=1}^n (x_i - \mu)^2$$

Now, when σ^2 is known, the likelihood equation is -

$$\frac{\partial}{\partial \mu} \log L = 0$$

$$\Rightarrow -\frac{1}{2\sigma^2} \sum_{i=1}^n 2(x_i - \mu) (-1) = 0 \quad [\text{from } ①]$$

$$\Rightarrow \sum_{i=1}^n (x_i - \mu) = 0$$

$$\Rightarrow (x_1 - \mu) + (x_2 - \mu) + \dots + (x_n - \mu) = 0$$

$$\Rightarrow x_1 + x_2 + \dots + x_n = n\mu$$

$$\Rightarrow \mu = \frac{x_1 + x_2 + \dots + x_n}{n}$$

$$\Rightarrow \mu = \bar{x} \text{ (sample mean).}$$

\therefore M.L.E for μ is the sample mean \bar{x} . ✓

(b) M.L.E for σ^2 , when μ is known.

Diffr ① partially w.r.t σ^2 , we have -

$$\begin{aligned} \frac{\partial}{\partial \sigma^2} \log L &= 0 \\ \Rightarrow \left(-\frac{n}{2} \times \frac{1}{\sigma^2} + \frac{1}{2\sigma^2} \sum_{i=1}^n (x_i - \mu)^2 \right) &= 0 \times (-2\sigma^2) \\ \Rightarrow n - \frac{1}{\sigma^2} \sum_{i=1}^n (x_i - \mu)^2 &= 0 \end{aligned}$$

$$\frac{\partial}{\partial x} \left(\frac{1}{x} \right)$$

$$\frac{1}{x^2}$$

$$\frac{\partial}{\partial \sigma^2} \left(-\frac{1}{\sigma^2} \right)$$

$$\frac{1}{\sigma^4}$$

$$\begin{aligned} \Rightarrow n - \frac{1}{\sigma^2} \sum_{i=1}^n (x_i - \mu)^2 &= 0 \\ \Rightarrow \sigma^2 &= \frac{1}{n} \sum_{i=1}^n (x_i - \mu)^2 \quad \checkmark \quad x_i \\ &\quad - \sim \text{ (i.e. variance)} \end{aligned}$$

$$\Rightarrow \hat{\sigma}^- = \sqrt{\frac{1}{n} \sum_{i=1}^n \dots}$$

$$\Rightarrow \hat{\sigma}^2 = s^2 \text{ (sample variance)}$$

\therefore M.L.E for σ^2 is the sample variance s^2 .

(c) Find the M.L.E for the simultaneous estimation of $\mu + \sigma^2$:

→ The likelihood equations for the simultaneous estimation of $\mu + \sigma^2$ are -

$$\checkmark \quad \frac{\partial}{\partial \mu} \log L = 0$$

$$\Rightarrow \underline{\hat{\mu} = \bar{x}}$$

$$\& \quad \frac{\partial}{\partial \sigma^2} \log L = 0$$

$$\Rightarrow \underline{\hat{\sigma}^2 = s^2} //$$



Unit-4 (Point Estimation)

Some Problems on Maximum likelihood Estimators

Pb :- Find the maximum likelihood estimate for the parameter λ of a Poisson distribution.

Sol: The probability function of the Poisson distribution with parameter λ is -

$$P(X=x) = f(x, \lambda) = \frac{e^{-\lambda} \lambda^x}{x!}, x=0,1,2,\dots$$

Likelihood function is -

$$\begin{aligned} L &= \prod_{i=1}^n f(x_i, \lambda) = \prod_{i=1}^n \frac{e^{-\lambda} \lambda^{x_i}}{x_i!} \\ &= \frac{e^{-\lambda n} \lambda^{x_1} \lambda^{x_2} \dots \lambda^{x_n}}{x_1! x_2! \dots x_n!} \\ \Rightarrow L &= \frac{e^{-n\lambda} \lambda^{\sum_{i=1}^n x_i}}{x_1! x_2! \dots x_n!} \end{aligned}$$

Taking log on both sides -

$$\begin{aligned} \log L &= \log e^{-n\lambda} + \log \lambda^{\sum_{i=1}^n x_i} - \log(x_1! x_2! \dots x_n!) \\ &= -n\lambda + \sum_{i=1}^n x_i \log \lambda - \sum_{i=1}^n \log(x_i)! \end{aligned}$$

$$\Rightarrow \log L = -n\lambda + \underline{n\bar{x}} \log \lambda - \sum_{i=1}^n \log(x_i)!$$

Likelihood equⁿ is -

$$\frac{\partial}{\partial \lambda} \log L = 0$$

$$\begin{aligned} \bar{x} &= \frac{1}{n} \sum_{i=1}^n x_i \\ \Rightarrow \sum_{i=1}^n x_i &= nx \end{aligned}$$

$$\begin{aligned}\frac{\partial}{\partial \lambda} \log L &= 0 \\ \Rightarrow -n + n\bar{x} \cdot \frac{1}{\lambda} - 0 &= 0 \\ \Rightarrow \frac{\bar{x}}{\lambda} &= 1 \\ \Rightarrow \hat{\lambda} &= \bar{x}.\end{aligned}$$

Thus, the M.L.E. for λ is sample mean (\bar{x}).

Pb :- Obtain maximum likelihood estimate of θ in $f(x, \theta) = (1+\theta)x^\theta$, $0 < x < 1$, based on an independent sample of size n .

$$\begin{aligned}\text{Sol: } L(\theta) &= \prod_{i=1}^n f(x_i, \theta) = \prod_{i=1}^n (1+\theta)x_i^\theta \\ &= (1+\theta)^n x_1^\theta (1+\theta)x_2^\theta \cdots (1+\theta)x_n^\theta \\ &= (1+\theta)^n (x_1 x_2 \cdots x_n)^\theta \\ &= (1+\theta)^n \left(\prod_{i=1}^n x_i \right)^\theta \\ \Rightarrow \log L &= \log(1+\theta)^n + \log \left(\prod_{i=1}^n x_i \right)^\theta \\ &= n \log(1+\theta) + \theta \log \prod_{i=1}^n x_i \\ \Rightarrow \log L &= \underline{n \log(1+\theta)} + \underline{\theta \sum_{i=1}^n \log x_i}\end{aligned}$$

Now, the likelihood equation is —

$$\begin{aligned}\frac{\partial}{\partial \theta} \log L &= 0 \\ \Rightarrow n \cdot \frac{1}{1+\theta} + \sum_{i=1}^n \log x_i &= 0 \\ \Rightarrow \frac{n}{1+\theta} &= -\sum_{i=1}^n \log x_i\end{aligned}$$

$$\Rightarrow \frac{n}{1+\theta} = - \sum_{i=1}^n \log x_i \quad \checkmark$$

$$\Rightarrow \frac{1+\theta}{n} = -\frac{1}{\sum_{i=1}^n \log x_i}$$

$$\Rightarrow 1 + \theta = - \frac{n}{\sum_{i=1}^n \log x_i}$$

$$\Rightarrow \hat{\theta} = -1 - \frac{n}{\sum_{i=1}^n \log x_i} \quad \checkmark$$

$$\Rightarrow \hat{\theta} = -1 - \frac{n}{\log(\prod_{i=1}^n x_i)} // \text{ is the M.L.E for } \theta.$$

$$\frac{\partial}{\partial \theta} \log L = 0$$

$$\Rightarrow \theta = \bar{\theta}$$

\downarrow
 $M \in \Sigma$
 for θ

Pb :- Let T be the M.L.E for parameter θ of a population. Then -

~~(*)~~ $\underline{\varepsilon}(\tau) < \varepsilon(\tau_i)$, τ_i - any other estimator of θ .

~~(b)~~ $\varepsilon(\tau) = \frac{1}{2}$.

$$\varepsilon(\tau) = 1$$

(x) T is an unbiased estimator of θ . ✓

(d) \hat{T} is a consistent estimator of Θ .

Pb :- If T is the most efficient estimator and T' is any other estimator of parameter θ , then which is true?

* (i) $\varepsilon(\tau) < \varepsilon(\tau')$ ✗

$$\varepsilon \in (0, 1]$$

$$\text{f(ii)} \quad \varepsilon(\tau) + \varepsilon(\tau') < 1 \times$$

$$0 < \varepsilon \leq 1.$$

$$\checkmark \quad \varepsilon(\tau) > 0 \quad = 1$$

$$\varepsilon(\tau) = \frac{v(\tau)}{v(\tau')}$$

$$\cancel{\varepsilon(\tau)} < 0$$

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(i) $\varepsilon(\tau) > 0$ (\Rightarrow)
 (ii) $\varepsilon(\tau) < 0$

$$\varepsilon(\tau) = \frac{\text{bias}}{\sqrt{V(\tau)}} > 0$$

$$\begin{array}{l} \varepsilon(\tau) = 1 \\ \varepsilon(\tau) > 0 \end{array} \quad \varepsilon(\tau) + \varepsilon(\tau') > 1$$

Pb If τ is an unbiased estimator of parameter θ , then -

- (i) $\varepsilon(\tau) > \theta$ ~~+ve~~
- (ii) $\varepsilon(\tau) < \theta$ ~~-ve~~
- (iii) $\varepsilon(\tau) - \theta = 0$
- (iv) None of these

$$\underline{\underline{\varepsilon(\tau) = \theta}}$$

$$\begin{aligned} \varepsilon(\tau) - \theta &= 0 \\ \Rightarrow \varepsilon(\tau) &= \theta \end{aligned}$$



Unit-4 (Point Estimation)

1) Sufficiency (sufficient estimators): -

An estimator is said to be sufficient for a parameter, if it contains all the information in the sample regarding the parameter.

→ Let x_1, x_2, \dots, x_n be a random sample of size n drawn from a population with p.m.f or p.d.f $f(x, \theta)$.

If the conditional distribution of sample values x_1, x_2, \dots, x_n given T i.e., $f(x_1, x_2, \dots, x_n | T)$ is independent of θ , then T is sufficient estimator for θ .

- If the conditional distribution of sample values x_1, x_2, \dots, x_n given (T_1, T_2) i.e., $f(x_1, x_2, \dots, x_n | (T_1, T_2))$ is independent of θ , then (T_1, T_2) is called joint sufficient estimator of θ .

§ A single sufficient statistic (estimator) may or may not exist but a joint sufficient estimator will always exist for a parameter θ .

$$\begin{aligned} & f(x_1, x_2, \dots, x_n | T) \\ & \neq g(\theta) \end{aligned}$$

Def: If $T = t(x_1, x_2, \dots, x_n)$ is an estimator of a parameter θ , based on a sample x_1, x_2, \dots, x_n of size n from a population with density function $f(x, \theta)$ such that the conditional distribution of x_1, x_2, \dots, x_n given T , is independent of θ , then T is sufficient estimator of θ .

i.e., $f(x_1, x_2, \dots, x_n | T = k)$ is independent of θ .

§ Illustration: Let x_1, x_2, \dots, x_n be a random sample from Bernoulli population with parameter ' p ', $0 < p < 1$ i.e.,

$$x_i = \begin{cases} 1, & \text{with probability } p \\ 0, & \text{with prob. } q = 1-p \end{cases}$$

Then $T = t(x_1, x_2, \dots, x_n) = x_1 + x_2 + \dots + x_n = \sum_{i=1}^n x_i \sim B(n, p)$ ✓
 $\therefore P(T=k) = \binom{n}{k} p^k (1-p)^{n-k}; k=0, 1, 2, \dots, n.$

So, the conditional distribution of sample values given $T=k$ is —

$$\checkmark P(x_1, x_2, \dots, x_n | T=k) = \frac{P(x_1, x_2, \dots, x_n | T=k)}{P(T=k)}$$

$$= \begin{cases} \frac{p^k (1-p)^{n-k}}{\binom{n}{k} p^k (1-p)^{n-k}}, & \sum_{i=1}^n x_i = k \\ 0, & \sum_{i=1}^n x_i \neq k \end{cases}$$

$$= \begin{cases} \frac{1}{\binom{n}{k}}, & \sum_{i=1}^n x_i = k \\ 0, & \sum_{i=1}^n x_i \neq k \end{cases}$$

p

Since this conditional distribution does not depend on p ,

$T = \sum_{i=1}^n x_i$ is sufficient to estimate ' p '.

Next Class § Neymann Factorization Theorem:- $T = t(x)$ is sufficient for θ if and only if the joint density function L of sample values

and only if the joint density function L of sample values can be expressed in the form -

$$L = \underbrace{g_{\theta}[t(x)]}_{g(x, \theta)} \cdot h(x), \text{ where } g_{\theta}[t(x)] \text{ depends on } \theta \text{ & } x \text{ only through the value of } t(x) \text{ and } h(x) \text{ is independent of } \theta.$$

\downarrow

\downarrow

\downarrow

$g_{\theta}[t(x)]$ x^{θ} x

$g(x, \theta) h(x)$

Remarks: (i) $h(x)$ is a function independent of θ . That is, it should not include θ and its domain also do not contain θ .

i.e., the func $h(x) = \frac{1}{2a}, a-\theta < x < a+\theta, -\infty < \theta < \infty$, is not independent of θ .

(ii) The original sample $x = (x_1, x_2, \dots, x_n)$ is always statistic.

(iii) Invariance property of sufficient estimators:

If T is a sufficient estimator for the parameter θ and if $\psi(T)$ is a one-to-one function of T , then $\psi(T)$ is sufficient estimator of $\psi(\theta)$.

* Fisher-Neymann Criterion: A statistic $t_1 = t(x_1, x_2, \dots, x_n)$ is sufficient estimator of parameter θ if and only if the likelihood function (joint p.d.f of sample values) can be expressed as:-

$$\underline{L = \prod^n f(x_i, \theta) = g_1(t_1, \theta) h(x_1, x_2, \dots, x_n)},$$

$$\checkmark L = \prod_{i=1}^n f(x_i, \theta) = \underline{g_1(t_1, \theta)} \underline{h(x_1, x_2, \dots, x_n)} ,$$

where $g_1(t_1, \theta)$ is the p.d.f. of statistic t_1 and $\underline{h(x_1, x_2, \dots, x_n)}$ is a function of sample observations only, independent of θ .

Ex- Let x_1, x_2, \dots, x_n be a random sample from a population

with b.d.f., $f(x, \theta) = \theta x^{\theta-1}$; $0 < x < 1, \theta > 0$.

Check whether $t_1 = \underline{\prod_{i=1}^n x_i}$, is sufficient for θ or not.

Sol: Here, likelihood function is given by —

$$\begin{aligned}\checkmark L(x, \theta) &= \prod_{i=1}^n f(x_i, \theta) \checkmark \\ &= \prod_{i=1}^n \theta x_i^{\theta-1} \\ &= (\theta x_1^{\theta-1}) \cdot (\theta x_2^{\theta-1}) \dots (\theta x_n^{\theta-1}) \\ &= \theta^n x_1^{\theta-1} \cdot x_2^{\theta-1} \dots x_n^{\theta-1} = \theta^n (x_1 x_2 \dots x_n)^\theta (x_1 \dots x_n)^{-1} \\ &= \underbrace{\theta^n \prod_{i=1}^n x_i^{\theta-1}}_{\theta^n \prod_{i=1}^n x_i^{\theta-1} \cdot \prod_{i=1}^n x_i^{-1}} \\ &= (\underbrace{\theta^n \prod_{i=1}^n x_i^{\theta}}_{\theta^n \prod_{i=1}^n x_i^{\theta}}) \cdot \frac{1}{\prod_{i=1}^n x_i}\end{aligned}$$

$$\therefore L(x, \theta) = \underline{g(t_1, \theta)} \cdot \underline{h(x_1, x_2, \dots, x_n)}$$

Hence, by Factorization Theorem, $t_1 = \underline{\prod_{i=1}^n x_i}$ is sufficient estimator for θ .

Pb: let x_1, x_2, \dots, x_n be a random sample from Cauchy population

$$f(x, \theta) = \frac{1}{\pi} \cdot \frac{1}{1+(x-\theta)^2}; -\infty < x < \infty, -\infty < \theta < \infty.$$

Examine if there exists a sufficient statistic for θ . ✓

YES

NO

Sol:

$$\begin{aligned} L(x, \theta) &= \prod_{i=1}^n f(x_i, \theta) = \prod_{i=1}^n \frac{1}{\pi} \cdot \frac{1}{1+(x_i-\theta)^2} \\ &= \frac{1}{\pi^n} \prod_{i=1}^n \frac{1}{1+(x_i-\theta)^2} \\ &= \frac{1}{\pi^n} \left\{ \frac{1}{1+(x_1-\theta)^2} \cdot \frac{1}{1+(x_2-\theta)^2} \cdots \right. \\ &\quad \left. \frac{1}{1+(x_n-\theta)^2} \right\} \end{aligned}$$

$$\Rightarrow L(x, \theta) \neq \underline{g(t, \theta) \cdot h(x_1, x_2, \dots, x_n)}$$

thus, there does not exist a single sufficient estimator
for θ . =