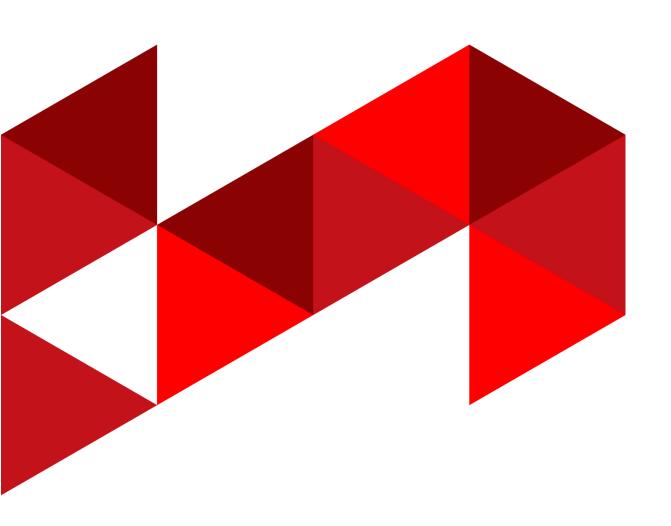




ClaimChart LLM

User Manual



Index

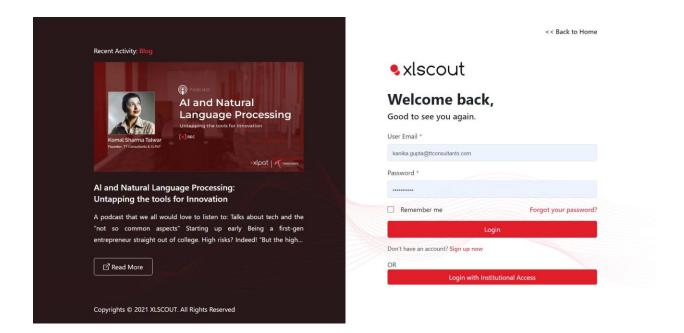
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1. Login

For accessing the tool, click to https://next.xlscout.ai/

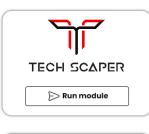


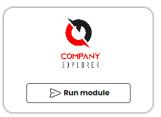
<Insert Email & Password>

2. Home Page

Welcome,

Dhruv Saini







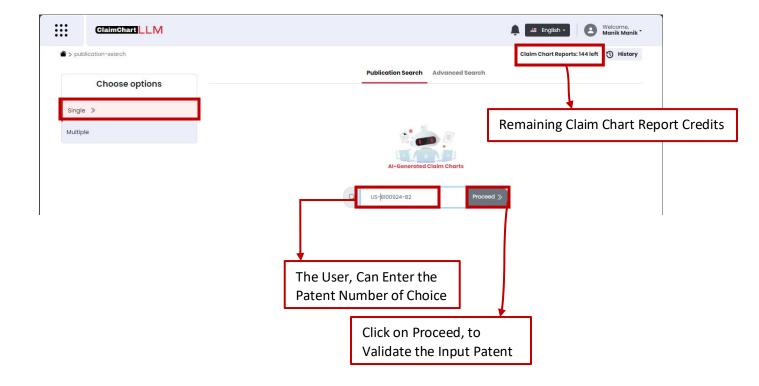








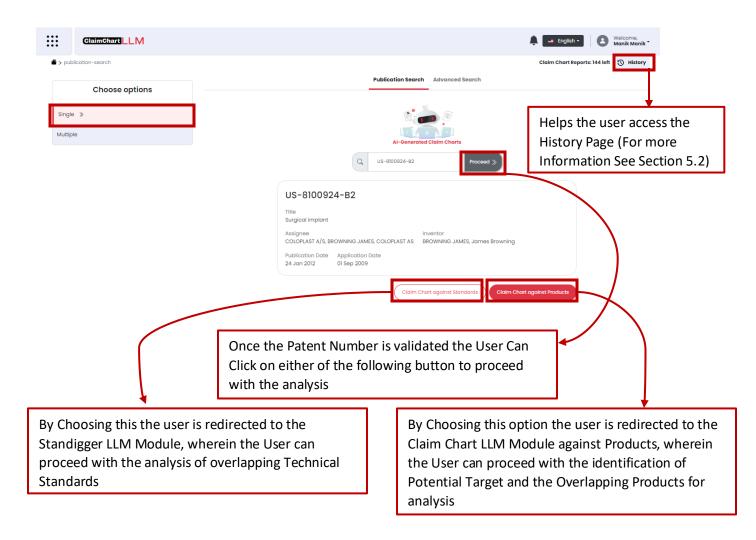
3.1 Publication Search



Note: If the Patents fed to the system are without the kind-code then a window pops up requiring user to select the patent matched with correct kind-code by the system

Note: 1 Claim Chart Report Consumes 1 Credit from the Total Limit out of which the Daily Credit Limit User can run a maximum of 20 cases in a day combining the cases run on Claim Chart LLM + Patdigger LLM + Standigger LLM

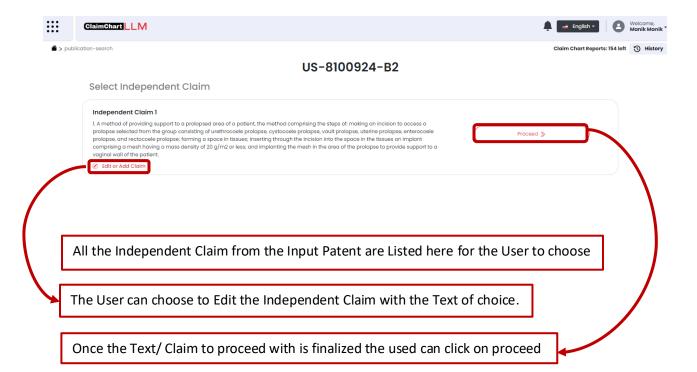
3.1.1 Validating Input Patent



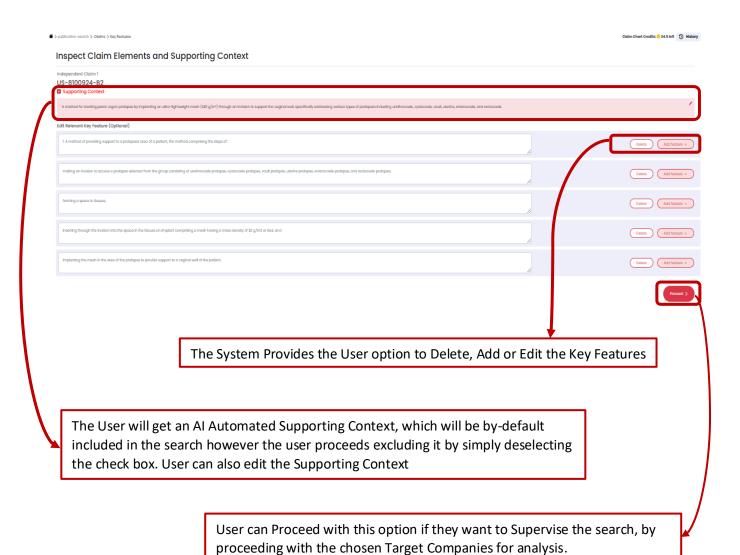
1 Patent Number can be run thrice on any of the Monetization Module (Claim ChartLLM, Standigger LLM, Patdigger LLM) 1 credit will be reduced.

In case of Patdigger LLM user can download 10 free reports for a patent number, however as the user exceeds the count 11-20 reports 1 credit will be deducted

3.1.2 Claim Selection



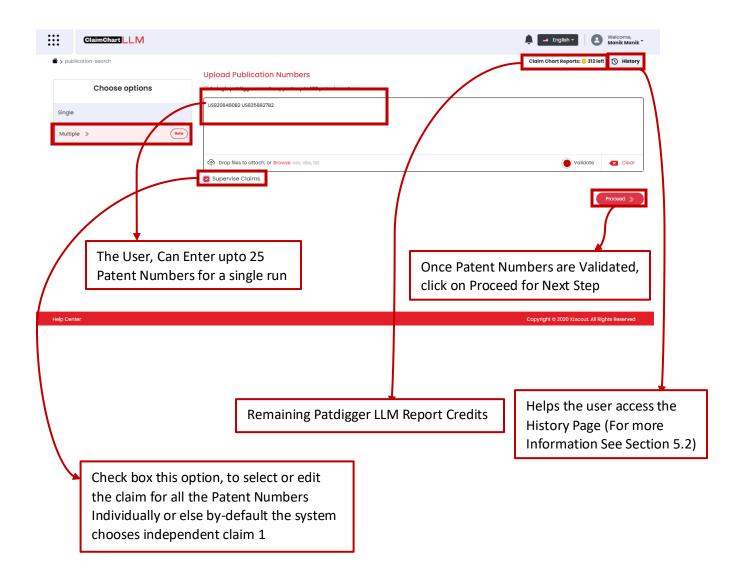
3.1.3 Claim Element Finalization



Note: When the user clicks on "Proceed" button, user will land on "Enter Target page", discussed in detail from Section 5



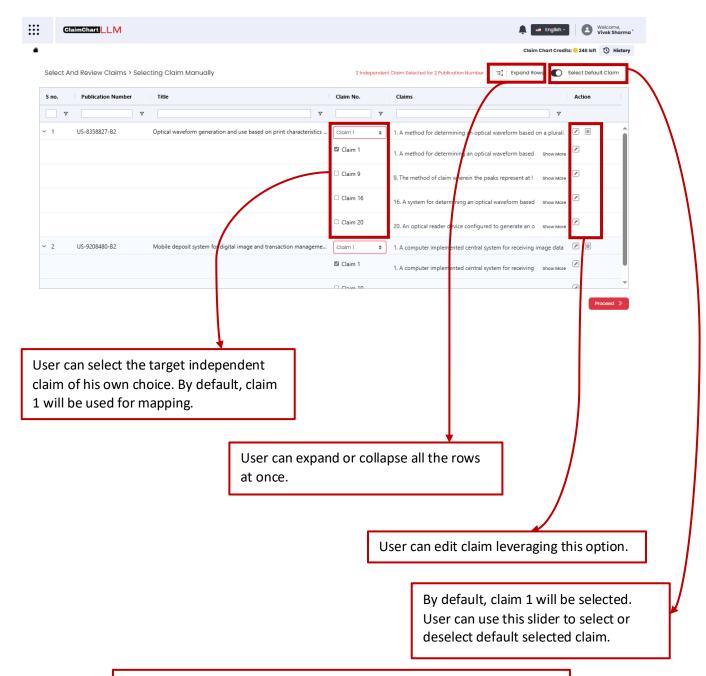
4.1 Publication Search



1 Patent Number can be run thrice on any of the Monetization Module (Claim ChartLLM, Standigger LLM, Patdigger LLM) 1 credit will be reduced.

In case of Patdigger LLM user can download 10 free reports for a patent number, however as the user exceeds the count 11-20 reports 1 credit will be deducted

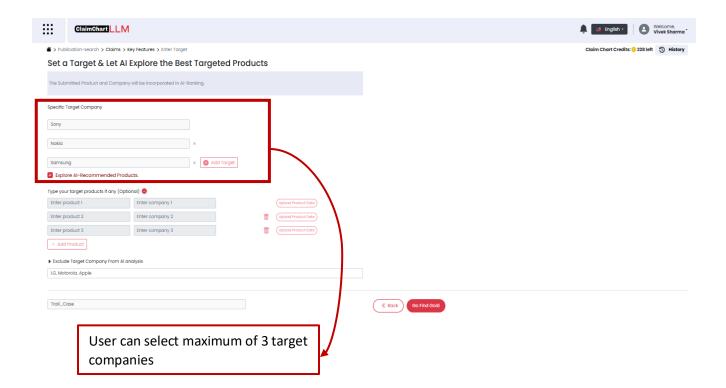
4.2 Supervise Claims



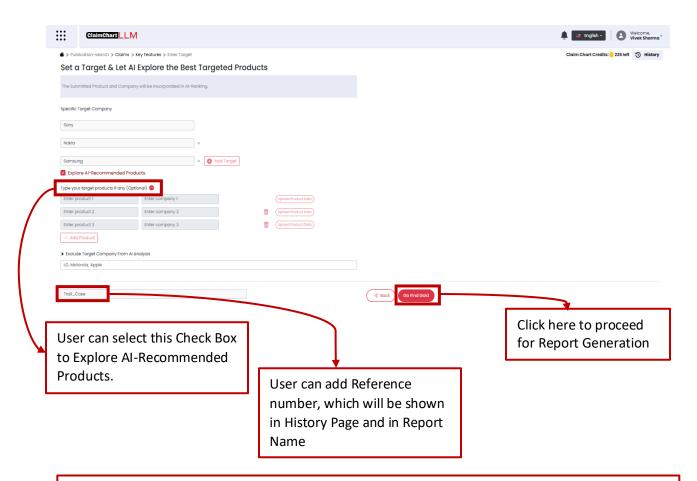
Note: User has to select independent claim for every Patent Number individually to proceed.

Note: When the user clicks on "Proceed" button, user will land on "Enter Target page", discussed in detail from section 5

5. Enter Target

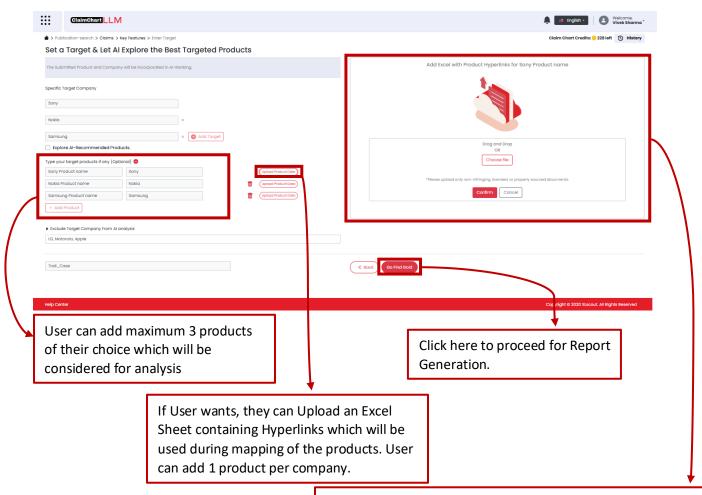


5.1 Manually Entered Companies



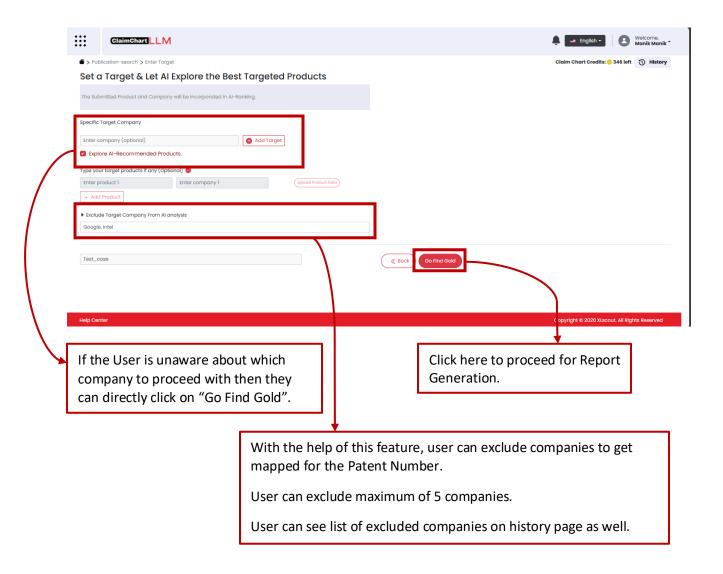
Either for single or for multiple Patent Numbers, in Al-recommended products, Al will recommend 3 products for each manually added company.

5.2 Manually Entered Products



This window will pop up as the User clicks on "Upload" Button. User can upload excel here, and then click on Confirm button to submit.

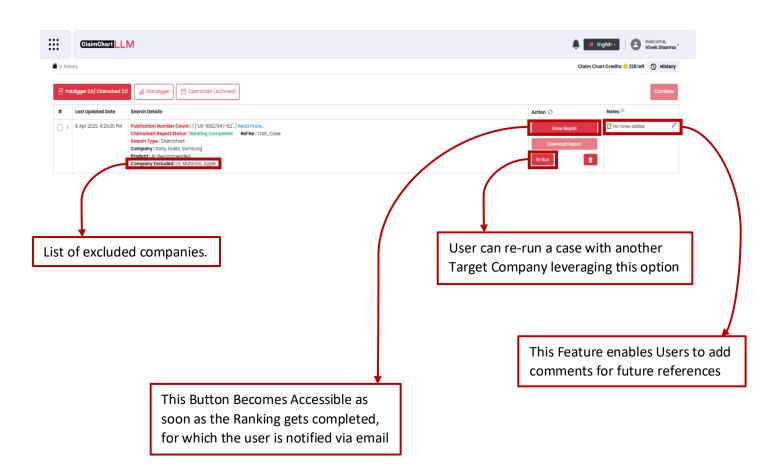
5.3 Al Assisted Search



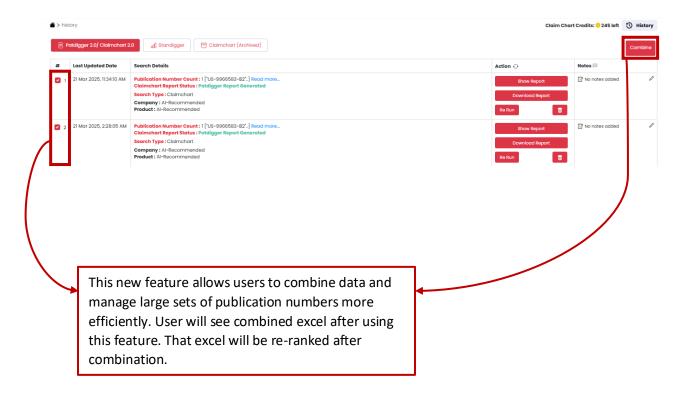
Note: For single patent number, User will see 5 companies and 3 products per company.

For Multiple patent numbers, User will see 3 companies per patent number and 3 products per company.

5.4 History Page



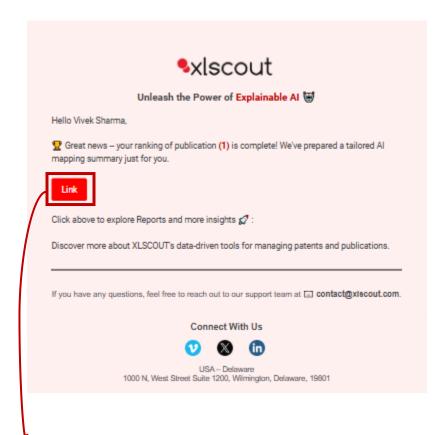
5.4.1 Combine History Feature



Note: User can combine history for only those cases whose status is either "Ranking Completed" or "Patdigger Report Generated".

User can combine at max of 5 cases in one go.

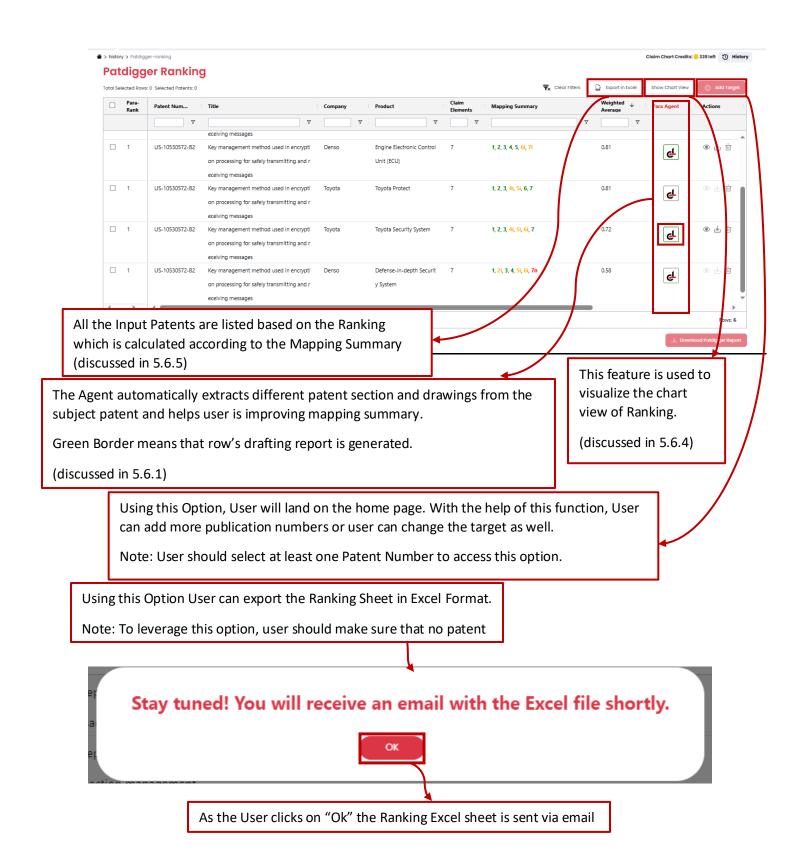
5.5 Ranking Completion



User gets notified about the Ranking completion via mail, by click on the link tab the user is directly redirected to the History Page from where user can access the Report.



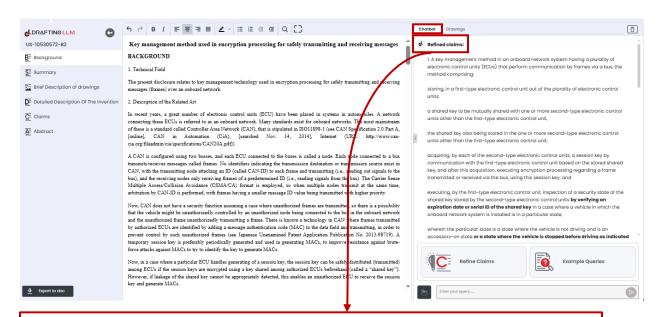
5.6 Patdigger Ranking Page



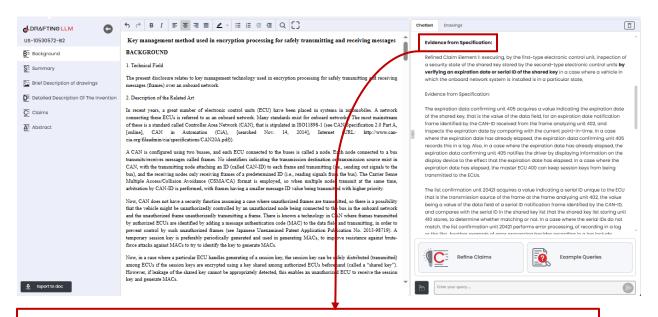
5.5.1 Al Agents

The Agent automatically extracts different patent sections and drawings from the subject patent, making it easy for users to review the application.

5.5.1.1 ChatBot

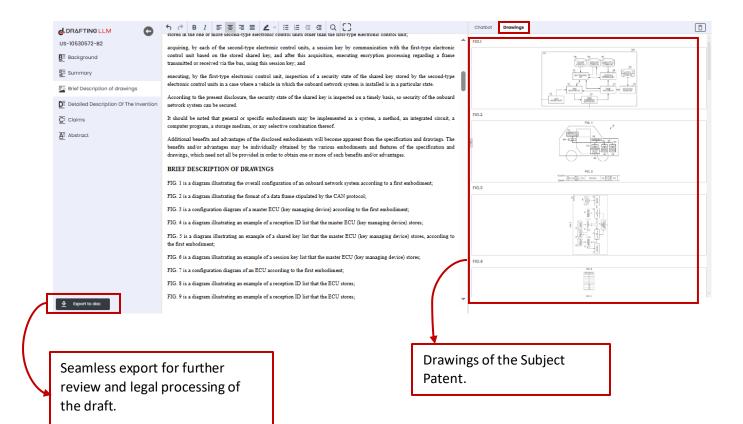


The agent focuses on inferred or non-mapped claim elements identifies by PatdiggerLLM report, then performs claim refinement by incorporating subject matter from subject patent.

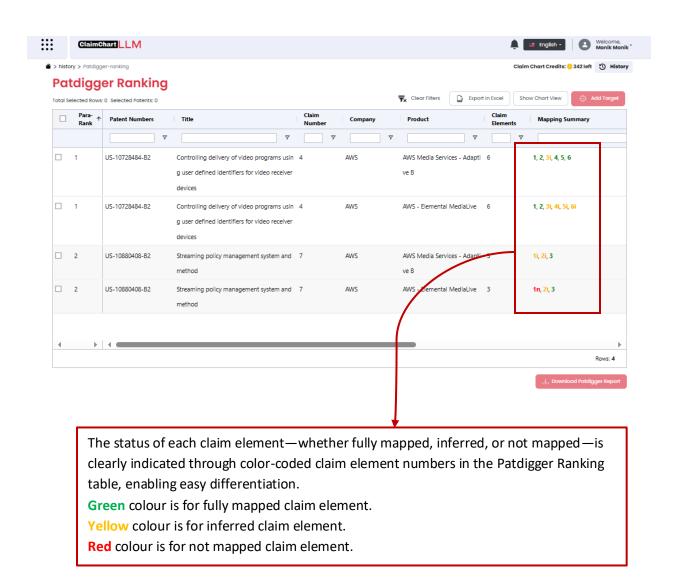


The agent extracts correlative evidence from the detailed description of the Parent patent application for the refined claim elements.

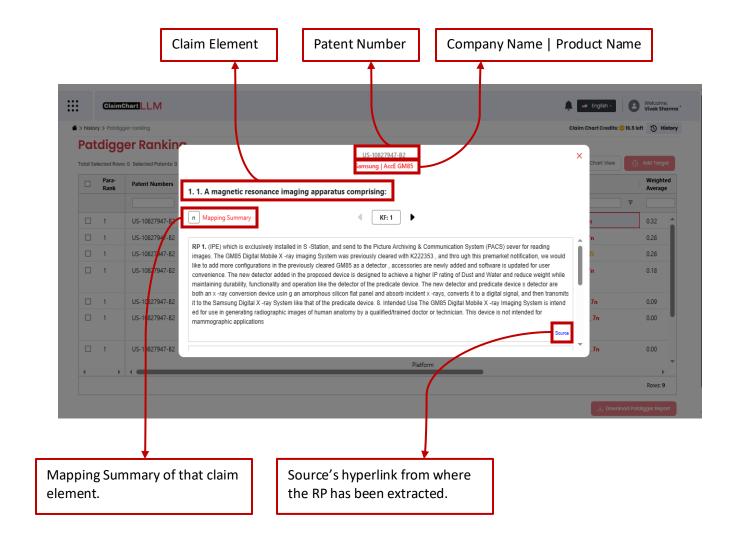
5.6.1.2 Drawings



5.5.2 Mapping Summary Visualization



5.5.3 RP Accessibility



5.5.4 Chart View Ranking

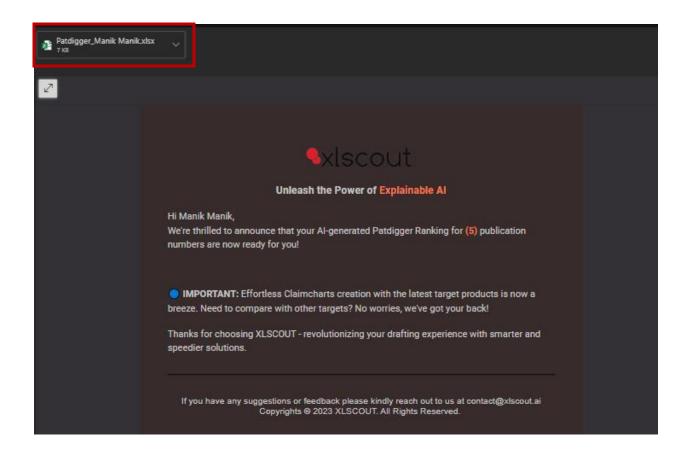


User will get to see two charts as shown below.

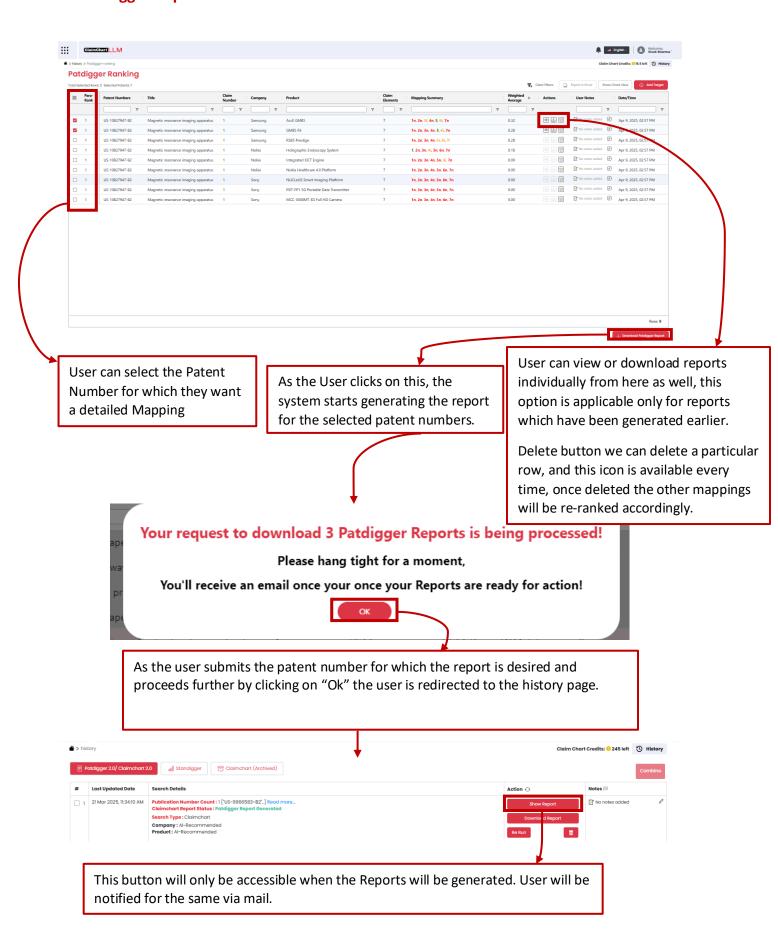
First chart will let user know which product is mapped from which company (how many products from 1 company are mapped).

In second chart, User can see mapped products for a particular Patent.

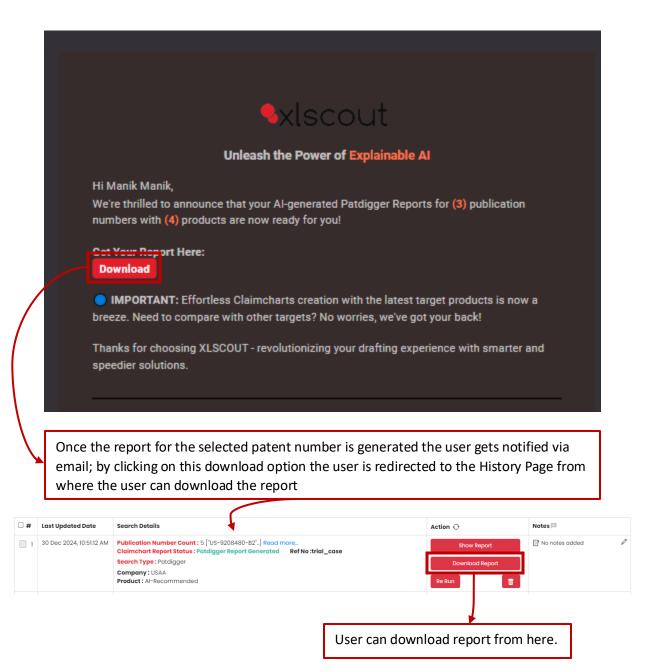
5.5.5 Excel containing Patdigger Ranking



5.6 Patdigger Report Generation

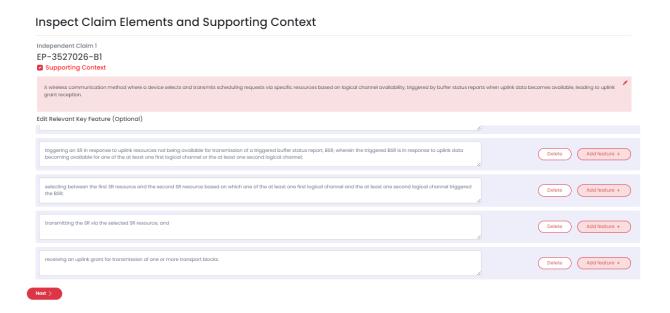


5.7 Patdigger Report Completion



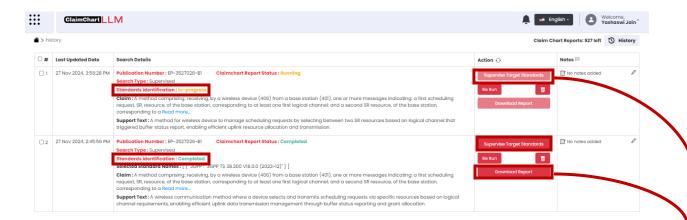
6 Standigger LLM

If the User, Proceeds with the Claim Chart against Standard Option (As Discussed in Section 3.1.1), The User is redirected to the Claim Element Finalization Window (Same, as Discussed in Section 5)



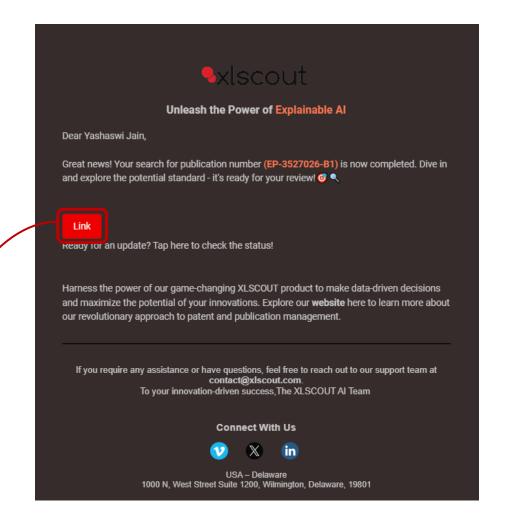
Once the Claim Elements and Supporting Context is finalized, as the User clicks on Next, the user is directed to the History Page (See Next Section 6.1)

6.1 Standigger LLM History Page



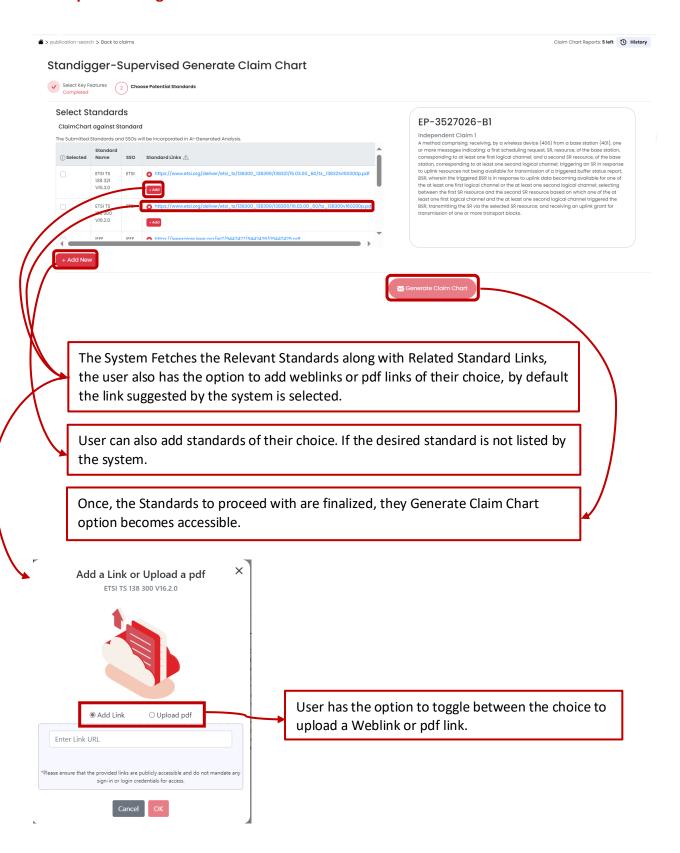
Claim Chart LLM and Standigger LLM Share the Same History Page, the only difference being when the Standard Identification is in-progress, the Supervise Target Standards Options stays in-accessible and as soon as the Identification is Completed, the Option become Accessible. User can also download the report directly from History Page.

6.1.1 Potential Standards List Mail



As soon as the Potential Standards are fetched, the user is informed via mail which has a clickable Link which redirects to the Supervise Target Standard List, Beside receiving the mail the Supervise Target Standard Option in the History Page also becomes accessible.

6.2 Supervise Target Standard



6.2.1 Standigger LLM Report Generation

Generate Claim Chart

Select your preference:

- O Separate Charts: Create separate charts for each selected standard.
- O Combined Chart: Create a single chart using all selected standards.



This option empowers users to customize their charting approach. By selecting the **Separate Chart** option, each chosen standard is meticulously mapped to the claim elements individually, providing a focused and detailed analysis.

Alternatively, choosing the **Combined Chart** option consolidates all selected standards into a single comprehensive chart, offering a holistic comparison against the claim elements. This flexibility ensures that users can tailor the output to their specific needs and preferences.

7 Final Report ClaimChart LLM



7.1 Report Summary

Report Summary

Potential Targets of US-20160350581-A1

Most Relevant Companies
Apple
Samsung
Google
Sony
Microsoft
Amazon
LG
Fitbit
Garmin
Ouraring
Toshiba
Facebook
Fossil Group
Xiaomi
Huawei
Most Relevant New Entrants
Motiv
Nimb
Oura
Circular
Ultrahuman

All The Potential Targets are enlisted; these are divided into 2 sections One for Big-Companies and other for Mid-Size Companies

Key Feature Mapping Product Data:

+‡+	Key Feature Mapping Product Data:									
			Epson	Canon	Canon Inc.	EFI				
	CE No.	Claim Element	Epson SureColor P-series printers	Canon imagePROGRAF PRO series	Canon UVgel Roll-to- Roll printers	EFI VUTEK printers with LED curing technology				
	1	An inkjet recording method comprising:	✓	✓	✓	I				
	2	applying an undercoating liquid onto a recording medium, the undercoating liquid containing a surfactant in an amount of at least 0.001 % by mass with respect to total solution,	I		I	I				
	3	the surfactant imparting a surface tension of 25 mN/m or less when the surfactant is dissolved in 1,6- hexanediol diacrylate at the critical micelle concentration,	I	*	I	*				
	4	wherein the surface tension is measured according to the Wilhelmy method at a liquid temperature of 20 °C and 60 % relative humidity using a surface tensiometer and	I	I	~	I				
	5	wherein the critical micelle concentration is that concentration of surfactant where the surface	I	I	1	I				

Key Feature Mapping Product Data Matrix, helps user get a clear view of mapping of claim elements with each product.

7.2 Input Patent Details

Publication No.: US-9188452-B2 | Application No.: US-201414182345-A | Priority No.: US-201161566121-P

Title: System and method for improved routing that combines real-time and likelihood information

Publication Date: 20151117 | Application Date: 20140218 | Priority Date: 20111202

Assignee: CORTLAND CAPITAL MARKET SERVICES LLC AS ADMINISTRATIVE AGENT

Inventor(s): FUCHS GIL

Abstract

A system and method for improved routing that combines real-time and likelihood information. In accordance with an embodiment, the system comprises a digital map/map information; a likelihood routing information; a route processor; wherein, when a request is received from a user/driver, or from another system, to receive a routing information, the system receives real-time information from a traffic-monitoring device or service providing real-time information; wherein the route processor adjusts the received real-time information based on the system's likelihood routing information; and wherein the routing information based on the combination of real-time and likelihood information can then be provided to the user/driver or other system in response to the original request.

Independent Claims/Key Features:

A system for determining a fastest route for a vehicle using historical and real time traffic flow information comprising:

- a digital map and map information
- a historical traffic flow information
- a route processor
- a user interface configured to accept user input comprising:
- a request to calculate the fastest route
- a present vehicle location or a user selected location to be used as a starting location of the route one or more user selected destination locations
- a present time or a user selected time for when the vehicle will start to travel the route wherein upon the route processor receiving the route request from the user interface the route processor further receives real time traffic flow information along potential routes and real time conditions that affect traffic flow along the potential routes

wherein the route processor determines a drive time along the potential routes based on the user input and the received real time traffic flow and conditions information along the potential routes adjusted by the historical traffic flow information for time intervals when the vehicle is anticipated to traverse points along the potential routes wherein the route processor selects from the potential routes a route with the fastest travel time

The Report consists of Input Patent Details describing about Publication, Application, Priority Date and Number along with Title, Assignee, Inventor, Abstract, Independent Claim broken into Key Features.

7.3 Evidence of Use Chart

1. Product Name: Skydio 2 Company Name: Skydio

Sno	Claim Elements	Product Specification	Explanation	Relevant Paragraphs (RPs)
1	A computerized method for controlling an unmanned vehicle, comprising:	Skydio 2 is an intelligent drone controlled via a smartphone app	The claim element describes a computerized method for controlling an unmanned vehicle, which directly corresponds to the Skydio 2's operation as an intelligent drone managed through a smartphone app. This method is substantiated by the context where the Skydio 2 offers three controller options: the smartphone app for autonomous flight, the Skydio Beacon, and a joystick controller, with the smartphone app being the primary control mechanism. This indicates that the Skydio 2 utilizes a computerized method, via the app, to facilitate control over the drone, aligning with the claim element's focus on a computerized control method for unmanned vehicles [RP-1]. The context further elaborates on the Skydio Beacon as a control option, which, through its integrated GPS sensors, enhances the drone's ability to track subjects more reliably. This capability is an extension of the computerized method for controlling the drone, as it leverages GPS and GLONASS satellites for tracking, thereby providing a more sophisticated and reliable control mechanism. This advanced tracking feature, enabled by computerized systems, supports the claim element by showcasing how technology is utilized to improve the control and functionality of the unmanned vehicle [RP-1]. Additionally, the mention of onboard AI in the context highlights the integration of artificial intelligence to predict environmental changes and enhance obstacle avoidance. This aspect of the Skydio 2's technology illustrates a sophisticated computerized method for controlling the drone, where AI is used to process environmental data and make real-time decisions, further supporting the claim element. The onboard AI not only facilitates autonomous flight but also improves the safety and reliability of the drone's operation, demonstrating the practical application of computerized methods in controlling unmanned vehicles [RP-3].	reference: [1] RP-1: critical of the video quality, despite the 4k resolution. realistically, it is good enough for anything short of professional quality cinematography, controllers: there are three controller options for the skydio 2: the smartphone app for autonomous flight, the skydio beacon, and the joystick controller. with the smartphone app being the default control mechanism, skydio recommends downloading the app to verify it works before purchasing the drone. however, it pairs with the drone easier than any other smartphone controllable drone, kudos to skydio there, the skydio beacon is the next remote upgrade in the skydio 2's kits, it is a small handheld tv remote - looking device with a monochrome display and a few buttons, the integrated gps sensors allow for the drone to track you more reliably than with the camera sensors alone, a feature seen first in the now defunct airogd drones, the beacon uses gps and glonass satellites for tracking, giving a reliable signal for the skydio 2 to follow, in ideal settings, it has a range of 1. 5 km for remote control operations, the joystick controller is your basic drone remote; two joysticks and a smartphone reference: [2] RP-2: fly the skydio 27 there are 3 ways to fly the skydio 2 remote controller with smartphone connected skydio beacon you can also launch and land the skydio 2 from the palm of your hand, what is the skydio beacon? the skydio 2 beacon allows you to fly, track subjects and control the quadcopter very easily with one hand, it has a small display so you can view the flight parameters such as gps, battery levels, tracking intelligent modes and much more, is the skydio 2 easy to fly? the skydio 2 is so very easy to fly with no real experience required, when flying, it is always best to be in a clear open space away from other people, cars, buildings, aerials and masts etc. also, make sure there is nothing obstructing the propellers, it is well recommended to read the skydio 2

Relevant Paragraph (RP) Reference Numbering after each paragraph of AI-generated explanation. It includes RP number from the identified references next to the explanation.

For each Product listed in Report Summary, a Similar EOU Chart is presented which has Claim Elements/ Key Features mapped against Product Specification followed by an Explanation.

NOTE: Explanation is generated by the system and the source (see next section) is mentioned for validation.

7.3.1 Sources for Validation

Sources:

- [1] https://www.google.com/maps/d/viewer?mid=1IM8Iv DTPGRlmJoY-wVwW-k9tJs
- [2] https://mapsplatform.google.com/maps-products/routes/
- [3] https://developers.google.com/maps/
- [4] https://maps.google.com/
- [5] https://outscraper.com/google-maps-traffic-extractor/

Along with Each EOU Chart, Source Hyperlinks are presented, enabling the User to Validate the explanation

Order Summary

Report Generated on: Tue, May 7, 2024 Type of Order: ClaimchartLLM

Report Generated by: Sameer Varshney Reference Number: Reference_Check

The Reference Number entered by the User during Product Selection is mentioned at the end of the report

Note: User also has the Option to Enter Boolean Queries and then Fetch the Input Patent Number, this can be done utilizing our **ADVANCED SEARCH** Option

8 Final Report Standigger LLM



9. Report Summary

▲ Report Summary (Beta)

Standard Setting Organization (SSO) Related to Patent:

Standards Name And Number And Its Versions	Standard Setting Organisation (SSO).	Mapped Claim Elements out of 8
ETSI TS 138 321 V15.3.0	ETSI	1, 2, 3, 4, 5, 6, 7, and 8

This Summary showcases all the Standards which were selected by the user for EOU Mapping and shows the Mapped Element Summary

Please Note: The EOU Chart is prepared similar to Claim Chart LLM EOU Charting (As shown in section 7.2-7.3.1) the only difference being in Standigger LLM, the mapping is done taking the Chosen link (as shown in Section 6.2) as reference.

Standard Setting Organisation (SSO): ETSI

SNo	Claim Elements	Standard Specification	Explanation	Relevant Exercepts
1	A method comprising: receiving, by a	V17.1.0 defines the NR MAC protocol	Structured Text Perspective:	reference:[1]
wireless device (406) from a base station (401	device (406) from a base station (401),	wireless device (UE) The receiving messages from	[RP-1] The method involves a wireless device receiving messages from a base station, which is directly supported by the context where it describes downlink assignments received on the	RP 1. 5.3 DL-SCH data transfer5.3.1 DL Assignment reception
	one or more messages indicating:	from a base station (gNB).	Mere it describes downlink assignments received in the PDCCH indicating a transmission on a DL-SCH for a particular MAC entity and providing the relevant HARQ information. This process is essential for the wireless device to understand there is data intended for it, which it needs to decode and act upon. The mention of different RNTI types and the specific conditions under which the MAC entity should consider the NDI to have been toggled aligns with the process of receiving and interpreting messages from a base station, showcasing a direct application of the NR MAC protocol procedures as outlined in the standard document	Downlink assignments received on the PDCCH both indicate that there is a transmission on a DL-SCH for a particular MAC entity and provide the relevant HARQ information. When the MAC entity has a C-RNTI, Temporary C-RNTI, or CS-RNTI, the MAC entity shall for each PDCCH occasion during which it monitors PDCCH and for each Serving Cell: 1> if a downlink assignment for this PDCCH occasion and this Serving Cell has been

In case of RPs, as discussed in Section 7.3, For Standigger LLM, the System not only cites the text but also the section of the Standard from which the reference has been taken

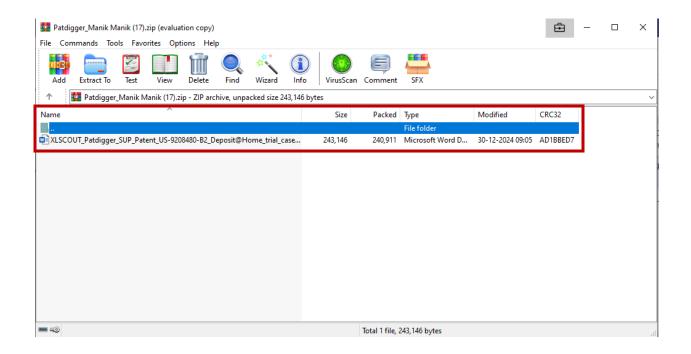
10. Patdigger Reports

10.1 Patdigger Ranking Report (Excel)

4	A	В	C	D	E	F	G	Н	1
	Case Details				XIscout An	alγsis			
	Rank ▼	Patent Numbers	Title	Claim Numbe	Company	Product	Claim Element	Mapped Summar 🔻	Weighted Averag ▼
	1	US-9208480-B2	Mobile deposit system for digital image and transaction management	1	USAA	Deposit@Home	9	1, 2, 3, 4, 5, 6, 7, 8 and 9	1
	1	US-9208480-B2	Mobile deposit system for digital image and transaction management	1	USAA	USAA Mobile App	9	1, 2, 3, 4, 5, 6, 7, 8 and 9	0.931372549
	1	US-9208480-B2	Mobile deposit system for digital image and transaction management	1	USAA	Deposit@Mobile	9	, '2i', 3, 4, 5, 6, 7, 8 and 9	0.901960784
	2	US-8358827-B2	aveform generation and use based on print characteristics for MICR data of paper de	1	USAA	USAA Deposit@Mobile	4	'1i', 2, '3i' and 4i	0.575
	2	US-8358827-B2	aveform generation and use based on print characteristics for MICR data of paper de	1	USAA	USAA Document Scanner	4	'1i', 2 and 4i	0.4
	2	US-8358827-B2	aveform generation and use based on print characteristics for MICR data of paper de	1	USAA	USAA Mobile Check Deposit	4	'1i', 2, '3i' and 4i	0.575
	3	US-8180137-B2	parison of optical and magnetic character data for identification of character defect	1	USAA	USAA Deposit@Mobile	8	1i', '2i', '4i', '5i', '6i' and 7	0.386363636
)	3	US-8180137-B2	parison of optical and magnetic character data for identification of character defect	1	USAA	USAA Digital Check Scanner	8	', 2, 3, 4, '5i', '6i', '7i' and	0.647727273
ι	3	US-8180137-B2	parison of optical and magnetic character data for identification of character defect	1	USAA	JSAA Remote Deposit Capture	8	1, '2i', '3i', '4i', '5i' and 6i	0.375
2	4	US-8010454-B2	System and method for preventing fraud in check orders	1	USAA	HOVER	11	, '41', '51', '61', '71', '81', '91'	0.491803279
3	4	US-8010454-B2	System and method for preventing fraud in check orders	1	USAA	SafePilot	11	'5i', '8i' and 11i	0.172131148
1	4	US-8010454-B2	System and method for preventing fraud in check orders	1	USAA	TEAC Crash Detection	11	4i', '5i', '6i', '7i', '8i', '9i', '1	0.524590164
;	5	US-8328080-B2	Document production using image transfer to mated substrate	1	USAA	HOVER	6	1, 2 and 5i	0.279411765
;	5	US-8328080-B2	Document production using image transfer to mated substrate	1	USAA	Deposit@Mobile	6	1 and 5i	0.191176471
,	5	US-8328080-B2	Document production using image transfer to mated substrate	1	USAA	SafePilot	6	None	0
2			_				•		

Α	В	С	D
Patent Numbers	Weighted Average	Rank	Claim Number
US-9208480-B2	0.94444444	1	1
US-8358827-B2	0.516666667	2	1
US-8180137-B2	0.46969697	3	1
US-8010454-B2	0.396174863	4	1
US-8328080-B2	0.156862745	5	1

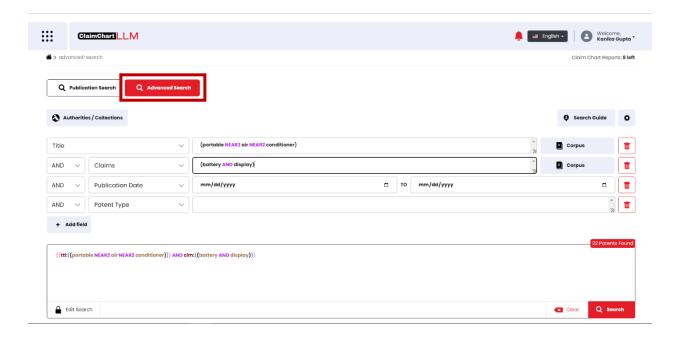
10.2 Patdigger Claim Chart Reports (ZIP file)



The user will receive two comprehensive reports to streamline their analysis:

- 1. **Email Report**: An Excel sheet delivered via email, providing an overview analysis of the claim charts. This includes a ranked arrangement of the patent list, ensuring quick access to prioritized insights.
- 2. **Downloadable Report**: A zip folder accessible from the **History Page** under the "Download Report" option. This folder contains detailed Claim Chart document reports for an in-depth review.

11. Advanced Search

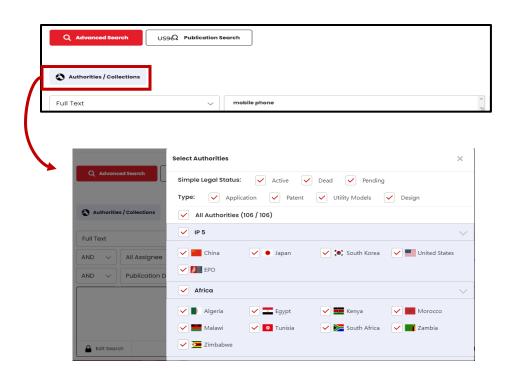


The Advanced Search section has input search fields, search assistance features and search settings options defined below.

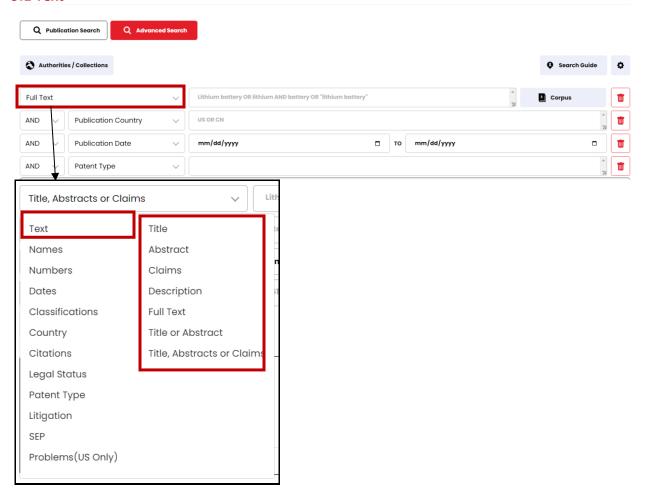
9.1 Authorities/Collections

User can filter results by following options:

- 1. Simple Legal Status for selecting Active, Dead or Pending Patent.
- 2. Type of Patent
 - Application
 - Patent
 - Utility
 - Design
- 3. All Authorities displaying different regions

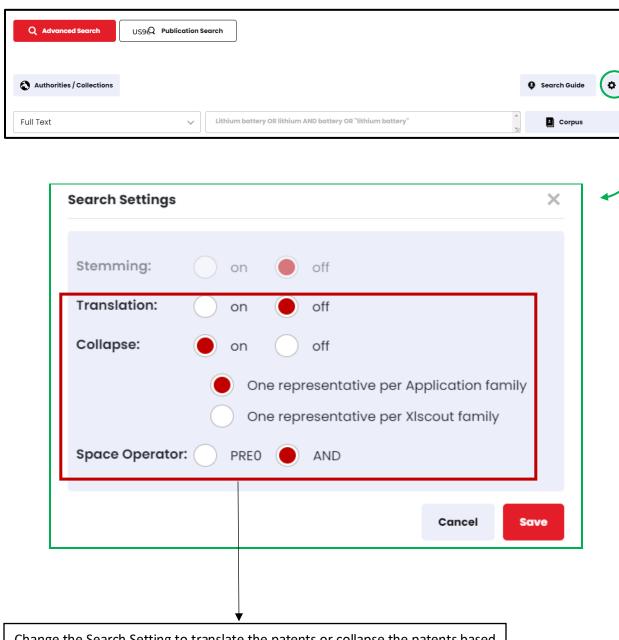


9.1 Text



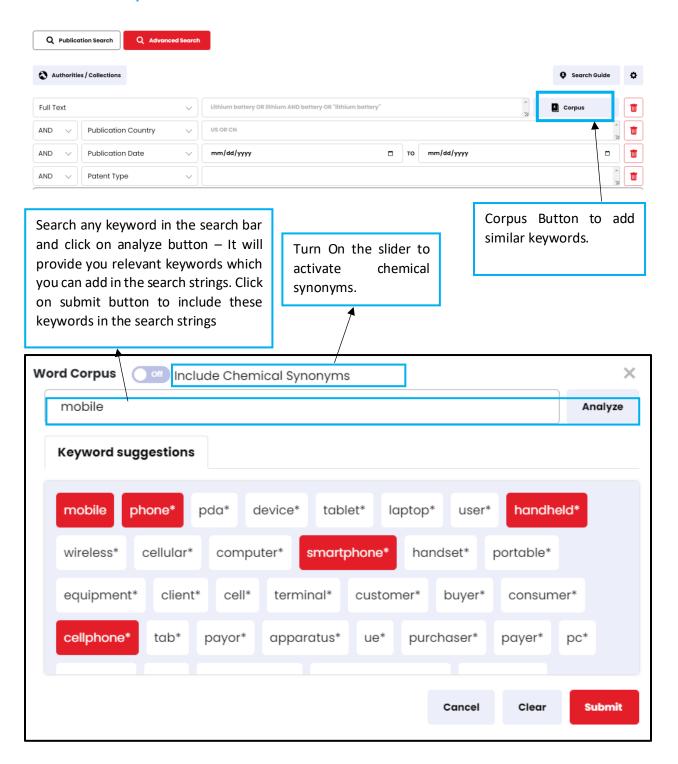
	Text			
S.No.	Search Fields	Definitions		
1.	Title	Searches within the title of the patent publication.		
2.	Abstract	Searches within the abstract of the patent publication		
3.	Claim	Searches within the claims (i.e Independent Claim) of the patent publication		
4.	Description	Searches within the description of the patent publication.		
5.	Full Text	Searches in the full text of the patent publication.		
6.	Title or Abstract	Searches either within the Title or within the Abstract of the patent publication.		
7.	Title, Abstract or Claim	Searches either within the Title or Abstract or Claim of the patent publication		

9.1.1 Search Setting

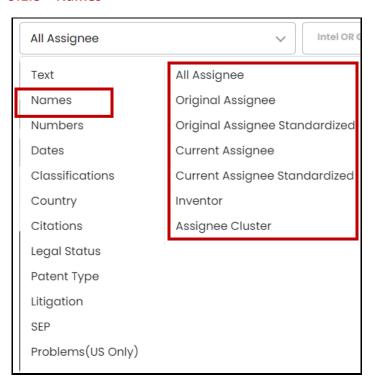


Change the Search Setting to translate the patents or collapse the patents based on Application Family or XIscout Family. Also, Change the behavior of space between two keywords by selecting the default functioning of space from AND (Logical Operator) to PREO (Proximity Operator).

9.1.2 Word Corpus

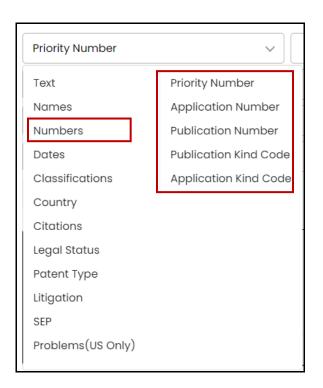


9.1.3 Names



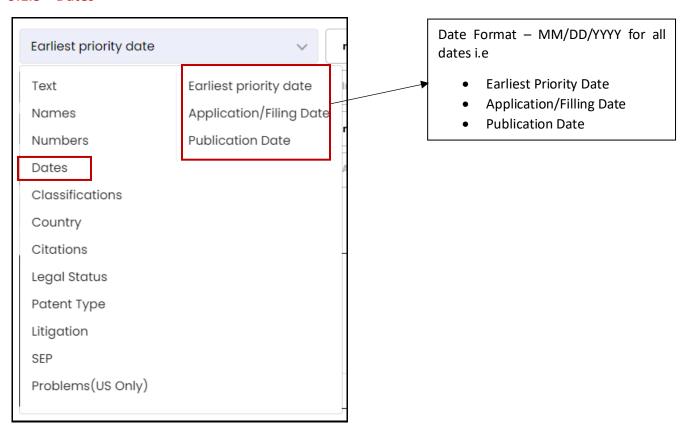
	Names				
S.No.	Search Fields	Definitions			
1.	All Assignee	Searches all the assignee of the patent publication (i.e. original, intermediate or current assignee)			
2.	Original Assignee	Searches in the original assignee of the patent publications.			
3.	Original Assignee Standardized	Searches in the standardized original assignee names of the patent publications. Note: This field contains standardized names of original assignees			
4.	Current Assignee	Searches in the current assignee of the patent publications.			
5.	Current Assignee Standardized	Searches in the standardized current assignee names of the patent publications. Note: This field contains standardized names of current assignees			
6.	Inventor	Searches in the inventor names of the patent publications.			

9.1.4 Numbers



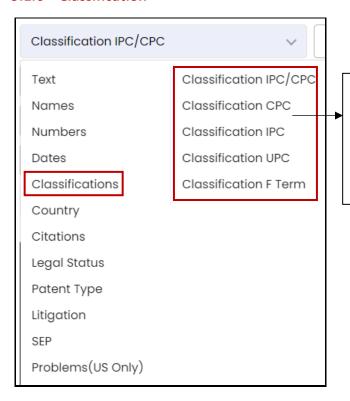
	Number				
S.No.	Search Fields	Definitions			
1.	Priority Number	Search in all the priority numbers of the patent publications For Example – JP2012056895 Note - Do not enter special characters such as a space, comma or forward slash. The country code is required.			
2.	Application Number	Search in the application numbers of the patent publications For Example - CN201380013230 or US12004657A Note - Do not enter special characters such as a space, comma or forward slash. The country code is required.			
3.	Publication Number	Search by entering patent publication numbers Example: US20190272373A1, US20190272373			
4.	Publication Kind Code	Search by kind code of the patent publication numbers Eg. B, B1, B2			
5.	Application Kind Code	Search by kind code of the application numbers Eg. A, A1, A2			

9.1.5 Dates



	Dates				
S.No.	Search Fields	Definitions			
1.	Earliest Priority Date	The earliest filing date in a series of patent applications is referred to as the priority date. If the first patent application for a given invention was a provisional application, the Provisional's filing date is your priority date.			
2.	Application/Filing Date	The date when you filed the patent application is referred as Application/Filing Date.			
3.	Publication Date	The date on which the patent application is published (i.e. the information is available to public.			

9.1.6 Classification

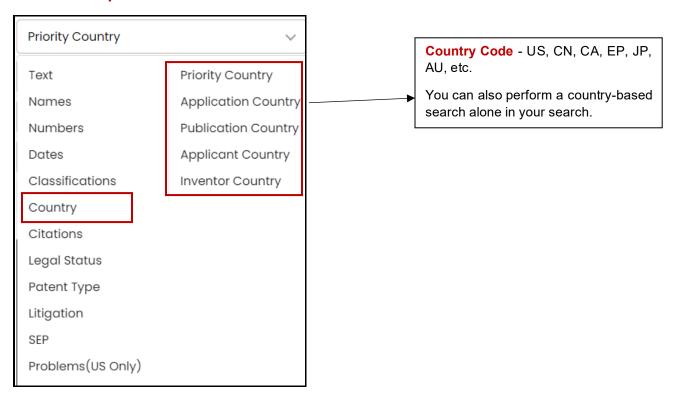


The given examples are the Class format for different classification-based search.

For Example:

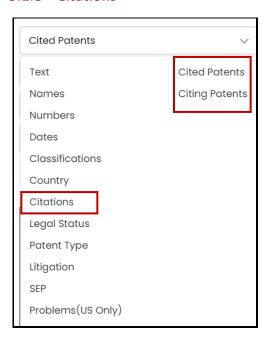
- A61B or A61B2/01 (IPC/CPC)
- 532 or 532/201 or 530/388.2 (US class)
- 2C088AA06 or 2C088 (F-Term)

9.1.7 Country



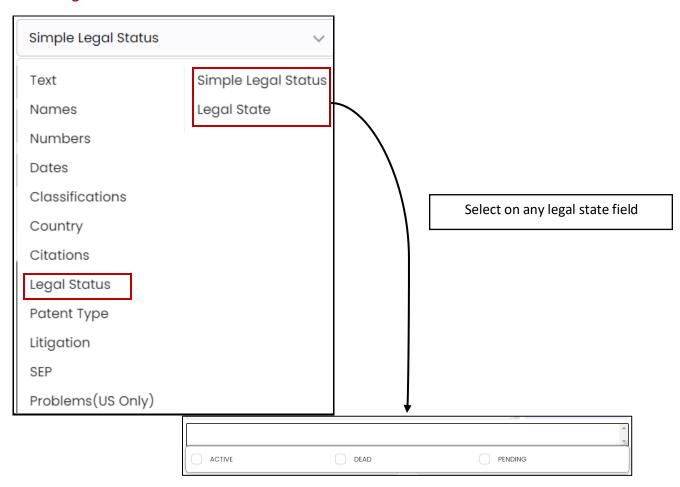
	Country				
S.No.	Search Fields	Definitions			
1.	Priority Country	Search by country code of priority country of the patent publications			
2.	Application Country	Search by country code of application country of the patent publications			
3.	Publication Country	Search by country code of the patent publications			
4.	Applicant Country	Search by country code of applicant country of the patent publications			
5.	Inventor Country	Search by country code of inventor country of the patent publications			

9.1.8 Citations



Citation				
S.No.	Search Fields	Definitions		
1.	Cited Patents	Searches backward citations of the input patent		
2.	Citing Patents	Searches forward citations of the input patent		

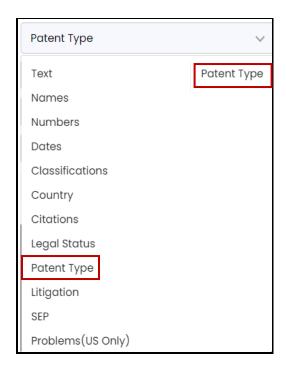
9.1.9 Legal Status



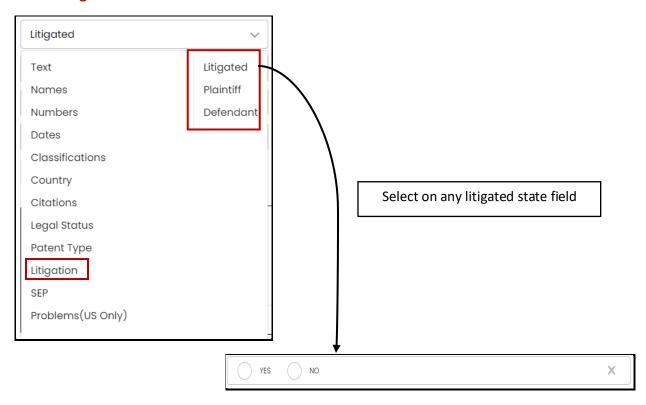
	Legal Status				
S.No.	Search Fields	Definitions			
1.	Simple Legal Status	Search can be restricted to a specific legal state of the patent publication. Values include: I Alive II Dead III Pending			
2.	Legal State	Search can be restricted by the current legal status of patent publications resulting in the legal state of the publication. Values include: I Examination II Published			

III Granted
IV Restoration
V P-Revoked
VI Expired
VII Withdrawn
VIII Rejected
IX Non-Payment
X Revoked
XI Double
XII Ceased
XIII Lapsed
XIV Abandoned
XV Discontinuation

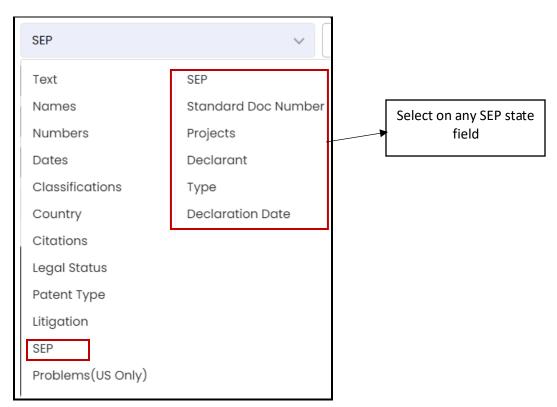
9.1.10 Patent Type



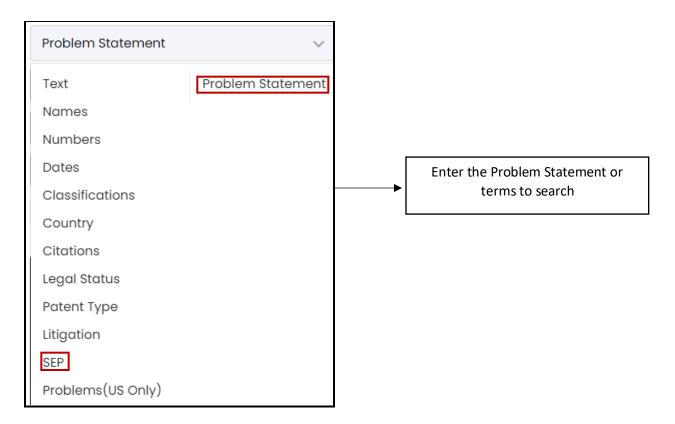
9.1.11 Litigation



9.1.12 SEP



9.1.13 Problems (US only)



9.3 Search Guide

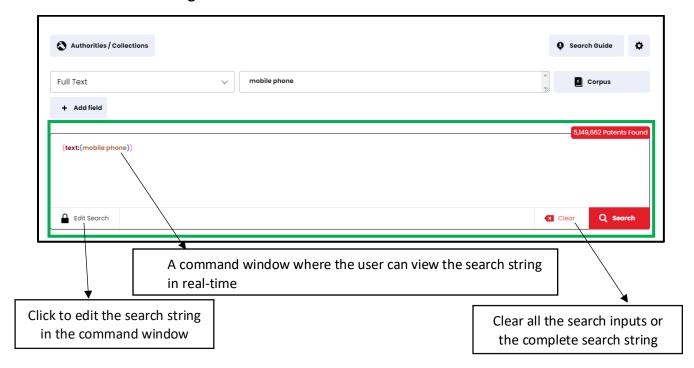


Search guide - Definition and syntax of Operators

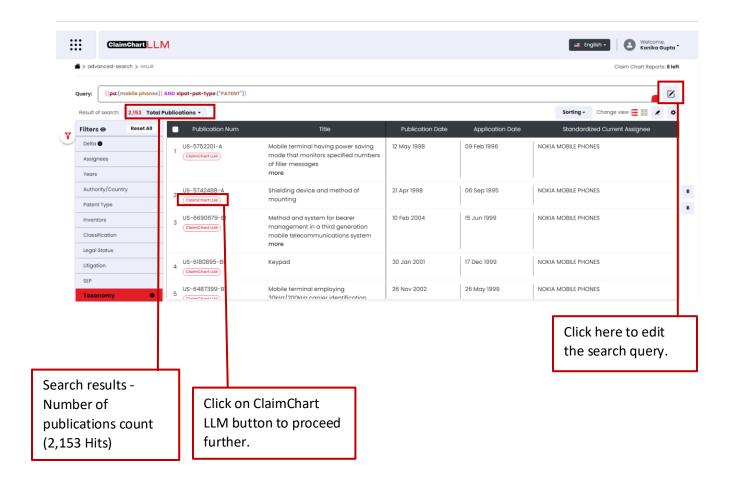
Logical Operators						
S.No.	Operators	Function	Example			
1.	AND	Finds documents that contain/match all the search terms entered.	Touch AND Screen			
2.	OR	Finds documents that contain any one of the search terms entered.	Vehicle OR Car			
3.	NOT	Finds documents which contain the first search term but do not contain the second/following search term.	Vehicle NOT Car			
Proximity Operators						
S.No.	Operators	Function	Example			
1.	PREn	For searching words in proximity in the ordered manner. Finds documents that contain the search terms within a proximity of `n` words to each other in the order specified.	Title:(Agriculture PRE1 machine) - will find results in which the word agriculture is always preceding the word machine.			
2.	NEARn	For searching words in proximity in unordered manner. Finds documents that contain the search terms within a proximity of `n` words to each other in any order (right or left)	Title: (Agriculture NEAR3 machine)			
3.	NEARs	For finding documents containing search terms in the same sentence.	Clm: (collision NEARs detection)			
4.	NEARp	For finding documents containing search terms in the same paragraph.	Text: (composition NEARp ethanol)			
	Wildcard Operators					
S.No.	Operators	Function	Example			
1.	?	Replaces only one character and can be used in the middle and at the end of a word.	Title: car? - Add title: car or car? Title: twist?? - Add twist or twist??			

2.	()	For defining the order in which the search terms should be logically combined in the search.	((autonomous or self-driving or driverless) NEAR4 (car or vehicle)) AND sensor		
1.	11 11	For searching the terms in the exact form/manner as specified.	"3d-printing"		
S.No.	Operators	Function	Example		
Other operators					
		Does not support use with quotations.			
2.	*	NOTE: It cannot be used at the beginning or in the middle of a search term.	Title: formula*		
		entered.	Title: fermente*		
		Replaces unlimited characters in the search term			
		Does not support use with quotations.			
		NOTE : It cannot be used at the beginning of a search term.			
		search term too.			
		with wildcard replacements, please add the original			
		cover both, the original search term and the terms			
		search term has a wildcard replacement. In order to			
		It will find only those results in which the original			

9.3.1 View search string



9.4 Advanced Search Results



Note: On Clicking on "Claim Chart LLM", the further steps are exactly same as the Publication Search, Refer Section 4 for more information