

Tutorial on Laplace Transforms

AV223 - signals and systems

- ① Find the inverse Laplace transform (ILT) of $X(s)$, if $x(t)$ is causal signal.

$$X(s) = \frac{2s^2 + 9s - 47}{(s+1)(s^2 + 6s + 25)}$$

Soln: $X(s) = \frac{2s^2 + 9s - 47}{(s+1)(s^2 + 6s + 25)}$

$$= \frac{\frac{47}{10}s + \frac{41}{2}}{(s^2 + 6s + 25)} + \frac{-27}{10(s+1)}$$

$$= \frac{47/10 s + 41/2}{(s+3)^2 + 16} - \frac{27/10}{s+1}$$

$$= \frac{47/10 (s+3)}{(s+3)^2 + 4^2} + \frac{41/2 - 47/10 \times 3}{(s+3)^2 + 4^2} - \frac{27/10}{s+1}$$

$$= \frac{47/10 (s+3)}{(s+3)^2 + 4^2} + \frac{47/5 (4) \times 1/4}{(s+3)^2 + 4^2} - \frac{27/10}{s+1}$$

$$\text{ILT} \Rightarrow x(t) = \left[\frac{47}{10} e^{-3t} \cos 4t + \frac{47}{20} e^{-3t} \sin 4t - \frac{27}{10} e^{-t} \right] u(t)$$

② Find ILT of $X(s)$: $X(s) = \frac{2}{(s+4)(s-1)}$

if the region of convergences (ROC) are

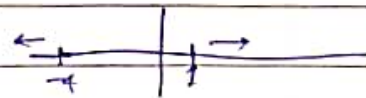
Ⓐ $-4 < \text{Re}\{s\} < 1$

Ⓑ $\text{Re}\{s\} > 1$

Ⓒ $\text{Re}\{s\} < -4$

Soln: $X(s) = \frac{2}{(s+4)(s-1)} = \frac{A}{s+4} + \frac{B}{s-1} \Rightarrow A = \frac{2}{-5} = -2/5$
 $B = 2/5$

$$= \frac{-2/5}{s+4} + \frac{2/5}{s-1}$$



Ⓐ $\text{ILT} \Rightarrow x(t) = \left[-\frac{2}{5} e^{-4t} u(t) - \frac{2}{5} e^t u(-t) \right]$

Ⓑ $\text{ILT} \Rightarrow x(t) = \left[-\frac{2}{5} e^{-4t} + \frac{2}{5} e^t \right] u(t)$

Ⓒ $\text{ILT} \Rightarrow x(t) = - \left[-\frac{2}{5} e^{-4t} + \frac{2}{5} e^t \right] u(-t)$

③ Find the Laplace transform (LT) of $x(t) = e^{-2t} \sin(2t) u(t)$.

Soln:

$$x(t) = e^{-2t} \sin(2t) u(t)$$

$$\sin(2t) u(t) \longleftrightarrow \frac{2}{s^2 + 2^2}$$

$$e^{-2t} \sin(2t) u(t) \longleftrightarrow \frac{2}{(s+2)^2 + 4}$$

$$\therefore X(s) = \frac{2}{(s+2)^2 + 4}$$

$$= \frac{2}{s^2 + 4s + 8}$$

④ Find the transfer function and impulse response of the system given by

$$\frac{d^2 y(t)}{dt^2} + 7 \frac{dy(t)}{dt} + 6y(t) = 7x(t) + 11 \frac{dx(t)}{dt}$$

Soln:

Take LT with initial conditions as zero.

$$\Rightarrow s^2 Y(s) + 7sY(s) + 6Y(s) = 7X(s) + 11sX(s)$$

$$\Rightarrow Y(s) [s^2 + 7s + 6] = X(s) [7 + 11s]$$

$$\Rightarrow \frac{Y(s)}{X(s)} = G(s) = \frac{11s + 7}{s^2 + 7s + 6}$$

↑ Impulse response / transfer function

Now, $G(s) = \frac{11s + 7}{s^2 + 7s + 6}$

$$= \frac{11s + 6}{(s+6)(s+1)} = \frac{A}{s+6} + \frac{B}{s+1} \Rightarrow A = \frac{-66+6}{-5} = 12$$

$$= \frac{12}{s+6} + \frac{B-1}{s+1} \quad B = \frac{-11+6}{5} = -1$$

$$ILT \Rightarrow g(t) = 12e^{-6t} - e^{-t}$$

↑ Impulse response.

⑤ Find the LT of the following signals and specify ROC

① $x(t) = te^{-2t}u(t)$

② $x(t) = e^{-t}u(t) + e^{-5t}\sin(5t)u(t)$

Soln: ① $x(t) = te^{-2t}u(t)$

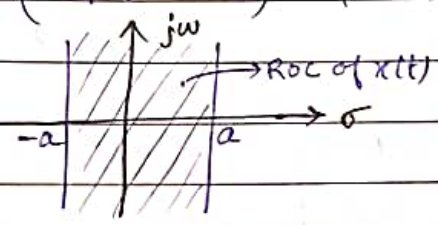
$$\Rightarrow \begin{cases} te^{-2t}, & t > 0 \\ te^{2t}, & t < 0 \end{cases}$$

$$= te^{-2t}u(t) + te^{2t}u(-t)$$

$$\left. \begin{array}{l} te^{-at} \leftrightarrow \frac{1}{(s+a)^2} \\ u(t) \end{array} \right\} \downarrow \text{ROC: } \text{Re}\{s\} > -a$$

$$\mathcal{LT} \Rightarrow X(s) = \frac{1}{(s+2)^2} + \frac{1}{(s-2)^2}$$

$$\hookrightarrow \text{ROC: } (\text{Re}\{s\} > -2) \cap (\text{Re}\{s\} < 2)$$



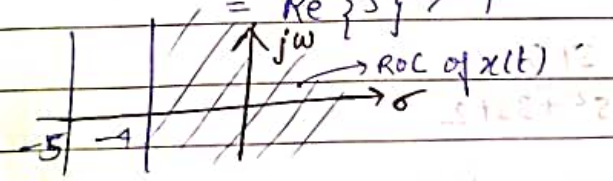
② $x(t) = e^{-4t}u(t) + e^{-5t}\sin(5t)u(t)$

$$\mathcal{LT} \Rightarrow X(s) = \frac{1}{s+4} + \frac{5}{(s+5)^2 + 5^2}$$

$$= \frac{1}{s+4} + \frac{5}{s^2 + 10s + 50}$$

primary of $\hookrightarrow \text{ROC: } (\text{Re}\{s\} > -4) \cap (\text{Re}\{s\} > -5)$

$$\equiv \text{Re}\{s\} > -4$$



⑤ Find the unilateral LT of the signal $x(t) = e^{-2t}u(t+1)$ and find the ROC.

Soln: $x(t) = e^{-2t}u(t+1)$

$$X(s) = \int_{-\infty}^{\infty} e^{-2t}u(t+1)e^{st}dt$$

$$= \int_{-1}^{\infty} e^{-2t}e^{-st}dt = \left[\frac{e^{-(2+s)t}}{-(s+2)} \right]_{-1}^{\infty} = \frac{0 - e^{(2+s)}}{-(s+2)} = \frac{e^{s+2}}{s+2}$$

$$\hookrightarrow \text{ROC: } \text{Re}\{s\} + 2 > 0$$

$$\boxed{\text{Re}\{s\} > -2}$$

⑦ Consider a signal $y(t)$ expressed as $y(t) = x_1(t-2) * x_2(-t+3)$ where $*$ denotes convolution operation, $x_1(t) = e^{-2t} u(t)$ and $x_2(t) = e^{-3t} u(t)$. Determine $Y(s)$.

Soln: $y(t) = 0 \cdot x_1(t-2) * x_2(-t+3)$
 $= [e^{-2(t-2)} u(t-2)] * [e^{-3(-t+3)} u(-t+3)]$

LT $\Rightarrow Y(s) = \text{LT}\{e^{-2(t-2)} u(t-2)\} * \text{LT}\{e^{-3(-t+3)} u(-t+3)\}$
 $= \int_2^\infty e^{-2(t-2)} e^{-st} dt + \int_{-\infty}^3 e^{-3(-t+3)} e^{-st} dt$
 $= e^4 \int_2^\infty e^{-(2+s)t} dt + e^{-9} \int_{-\infty}^3 e^{(3-s)t} dt$
 $= e^4 \left[\frac{e^{-(2+s)t}}{-(2+s)} \right]_2^\infty + e^{-9} \left[\frac{e^{(3-s)t}}{3-s} \right]_{-\infty}^3$
 $= e^4 \frac{e^{-2(2+s)}}{(s+2)} + e^{-9} \frac{e^{-3(s-3)}}{(s-3)}$
 $= \frac{e^{-2s}}{s+2} + \frac{e^{-3s}}{s-3}$

⑧ Find the initial and final values of the following transforms.

(a) $X(s) = \frac{s+5}{s^2+3s+2}$

Soln: $x(0^+) = \lim_{s \rightarrow \infty} s X(s)$
 $= \lim_{s \rightarrow \infty} \frac{s(s+5)}{s^2+3s+2}$
 $= \lim_{s \rightarrow \infty} \frac{1 + 5/s}{1 + 3/s + 2/s^2} = 1$
 $x(\infty) = \lim_{s \rightarrow 0} s X(s) = \lim_{s \rightarrow 0} \frac{s(s+5)}{s^2+3s+2} = 0.$

⑥ $X(s) = \frac{s^2 + 5s + 7}{s^2 + 3s + 2}$

Soln: $x(0^+) = \lim_{s \rightarrow \infty} sX(s)$

$$= \lim_{s \rightarrow \infty} \frac{s(s^2 + 5s + 7)}{s^2 + 3s + 2}$$

$$= \lim_{s \rightarrow \infty} \frac{1 + 5/s + 7/s^2}{1/s + 3/s^2 + 2/s^3} = \infty$$

⑦ ~~Q~~ $x(\infty) = \lim_{s \rightarrow 0} sX(s) = 0.$

⑧ Consider an LTI system with input $x(t) = e^{-t} u(t)$ and impulse response $h(t) = e^{-2t} u(t)$. Determine the output signal $y(t)$.

Soln: $y(t) = x(t) * h(t)$
 $Y(s) = X(s) \cdot H(s)$

$$x(t) = e^{-t} u(t) \longleftrightarrow X(s) = \frac{1}{s+1}$$

$$h(t) = e^{-2t} u(t) \longleftrightarrow H(s) = \frac{1}{s+2}$$

$$\therefore Y(s) = \frac{1}{(s+1)} \cdot \frac{1}{(s+2)} = \frac{A}{(s+1)} + \frac{B}{(s+2)} \Rightarrow A=1, B=-1$$

$$= \frac{1}{s+1} - \frac{1}{s+2}$$

$$\text{ILT} \Rightarrow e^{-t} u(t) - e^{-2t} u(t) = y(t).$$

⑩ An LTI system is defined as:

$$\frac{d^3 y(t)}{dt^3} + 6 \frac{d^2 y(t)}{dt^2} + 11 \frac{dy(t)}{dt} + 6y(t) = x(t),$$

with $x(t) = e^{-t} u(t)$. Find $y(t)$ if $y(0^-) = 1$, $\dot{y}(0^-) = -1$ and $\ddot{y}(0^-) = 1$.

Soln:

$$\frac{d^3 x(t)}{dt^3} \leftrightarrow s^3 X(s) - s^2 x(0^-) - s^1 \dot{x}(0^-) - \ddot{x}(0^-)$$

$$\frac{d^2 x(t)}{dt^2} \leftrightarrow s^2 X(s) - s x(0^-) - \dot{x}(0^-)$$

$$\frac{dx(t)}{dt} \leftrightarrow s X(s) - x(0^-)$$

By LT

$$\Rightarrow [s^3 Y(s) - s^2 y(0^-) - s \dot{y}(0^-) - \ddot{y}(0^-)] + 6 [s^2 Y(s) - s y(0^-) - \dot{y}(0^-)] + 11 [s Y(s) - y(0^-)] + 6 Y(s) = \frac{1}{s+4}$$

$$\Rightarrow Y(s) [s^3 + 6s^2 + 11s + 6] = \frac{1}{s+4} - s^2 + \frac{5s}{s+4} - \frac{6}{s+4}$$

$$\Rightarrow Y(s) [s^3 + 6s^2 + 11s + 6] = \frac{1}{s+4} + s^2 + 5s + 6 = \frac{s^3 + 6s^2 + 11s + 6}{s+4}$$

$$\Rightarrow Y(s) = \frac{s^3 + 9s^2 + 26s + 25}{(s^3 + 6s^2 + 11s + 6)(s+4)}$$

$$= \frac{1}{s+4} + \frac{3s^2 + 15s + 19}{(s^3 + 6s^2 + 11s + 6)(s+4)}$$

$$= \frac{1}{s+4} + \frac{A}{(s+1)} + \frac{B}{s+2} + \frac{C}{s+3} + \frac{D}{s+4}$$

$$= \frac{1}{s+4} + \frac{7/6}{s+1} + \frac{-1/2}{s+2} + \frac{1/2}{s+3} + \frac{-7/6}{s+4}$$

$$= \frac{7/6}{s+1} + \frac{-1/2}{s+2} + \frac{1/2}{s+3} + \frac{-1/6}{s+4}$$

$$\text{ILT} \Rightarrow y(t) = \left[\frac{7}{6} e^{-t} - \frac{1}{2} e^{-2t} + \frac{1}{2} e^{-3t} - \frac{1}{6} e^{-4t} \right] u(t)$$