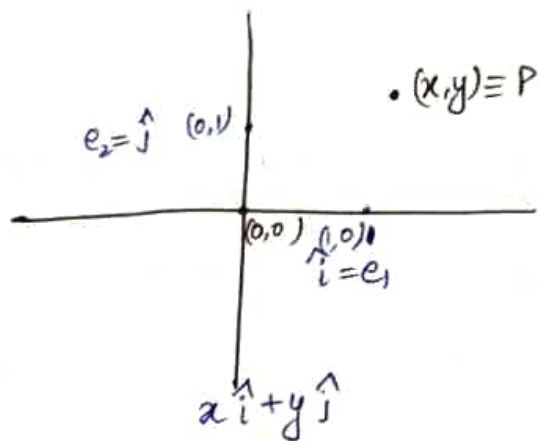


सदिशकलनम्
VECTOR CALCULUS

VECTOR



$$x(1,0) = (x,0)$$

$$y(0,1) = (0,y)$$

$$(x,y) = x e_1 + y e_2$$

$$\|e_1\| = 1 = \|e_2\|$$

Spatial structure

$$d((0,0), (x,y)) = \sqrt{x^2 + y^2}$$

$$= \|(x,y)\| : \text{Euclidean distance / norm}$$

$\|\cdot\|$ is called norm function.

$$\|\cdot\| : \mathbb{R}^2 \rightarrow \mathbb{R}$$

$$\|\vec{v}\| = 0 \Leftrightarrow \vec{v} = \vec{0}$$

$$\|\cdot\|_1 : \mathbb{R}^2 \rightarrow \mathbb{R}$$

$$\|(x,y)\|_1 = |x| + |y|$$

$$\|(x,y)\|_\infty = \sup(|x|, |y|)$$



$$\|\vec{v}\| < 1$$



Inner product:

$$\langle (x_1, y_1), (x_2, y_2) \rangle = x_1 x_2 + y_1 y_2 \rightarrow \text{a fn}$$

$$\langle \cdot, \cdot \rangle : \mathbb{R}^2 \times \mathbb{R}^2 \rightarrow \mathbb{R}$$

$$\langle \vec{v}, \vec{v} \rangle = \|\vec{v}\|^2$$

$$\|\vec{v}\| = \sqrt{\langle \vec{v}, \vec{v} \rangle}$$

Euclidean inner product
gives Euclidean product

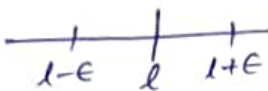
Euclidean Space: Space endowed with Euclidean norm.

Limit

→ $f: A \rightarrow \mathbb{R}, A \subset \mathbb{R}, x \in \mathbb{R},$

$$\lim_{x \rightarrow x_0} f(x) = \bar{l}$$

or $f(x) \rightarrow \bar{l}$ as $x \rightarrow x_0$.



Algebraic defⁿ of zero:
 $\bar{e} + a = a \quad \forall a \in \mathbb{R}$
 $\Rightarrow \bar{e} = 0$.

For any $\epsilon > 0$, there exists $\delta > 0$ such that

$$|f(x) - \bar{l}| < \epsilon \text{ when } |x - x_0| < \delta \equiv x \in (x_0 - \delta, x_0 + \delta) \\ \equiv f(x) \in (\bar{l} - \epsilon, \bar{l} + \epsilon)$$

$$A \subset \mathbb{R}^2$$

$$f: A \rightarrow \mathbb{R}^2$$

$$p_0 \in \mathbb{R}^2$$

$$\lim_{p \rightarrow p_0} f(p) = \bar{l} \text{ vector}$$

$$\|f(p) - \bar{l}\| < \epsilon \text{ whenever} \\ \|p - p_0\| < \delta.$$

$$f(p) \in B(\bar{l}, \epsilon)$$

whenever $p \in B(p_0, \delta)$.

$$\|\bar{x}\| = 1 \rightarrow \text{circle}$$

$$\|\bar{x}\| \leq 1 \rightarrow \text{disc}$$

$$\|\bar{x}\| < 1 \rightarrow \text{open disc} \\ (\text{open ball})$$

Ball \Rightarrow open ball (say)

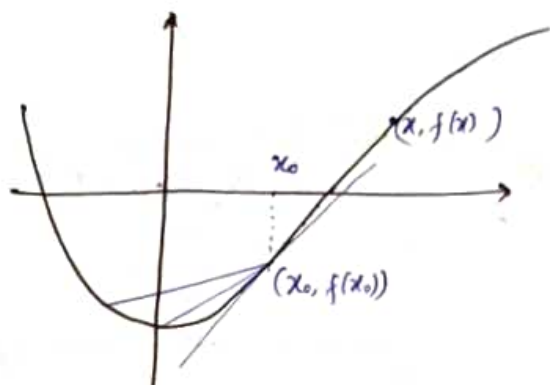
Direction Derivative

$$f: (a, b) \rightarrow \mathbb{R}$$

$$x_0 \in (a, b)$$

$$\lim_{x \rightarrow x_0} \frac{f(x) - f(x_0)}{x - x_0} = l$$

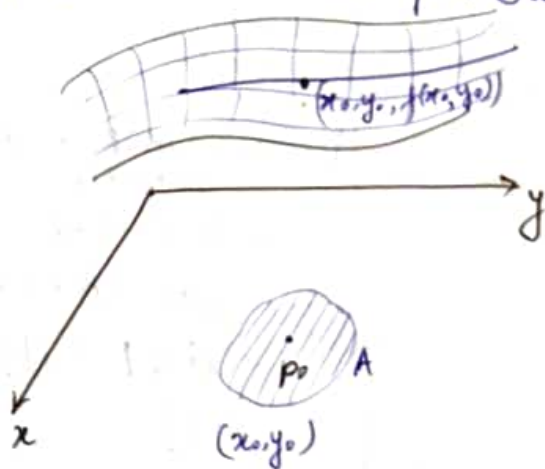
$$f'(x_0) := l$$



$$A \subset \mathbb{R}^2$$

$$f: A \rightarrow \mathbb{R}$$

$p \in A$ s.t. there is an open ball around p in A .



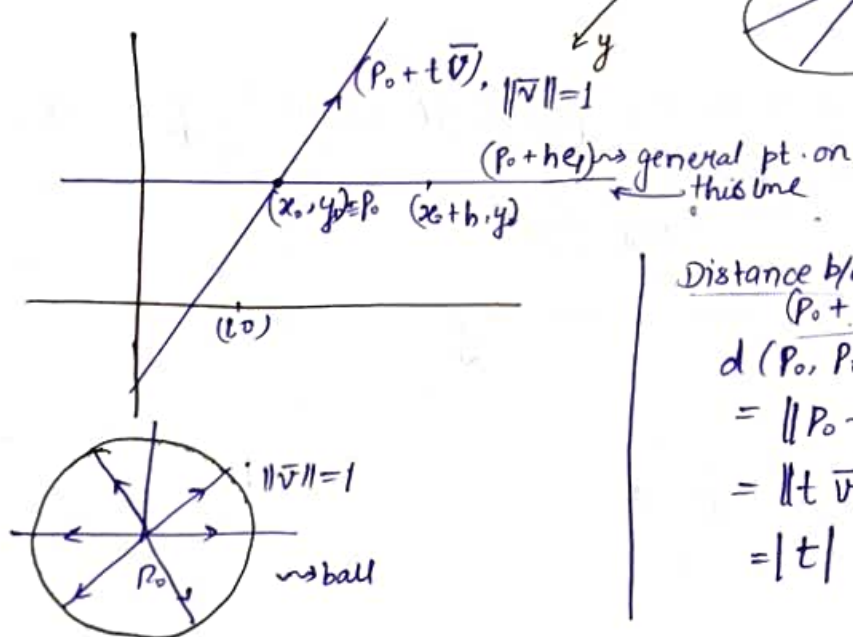
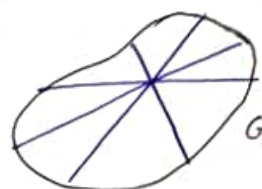
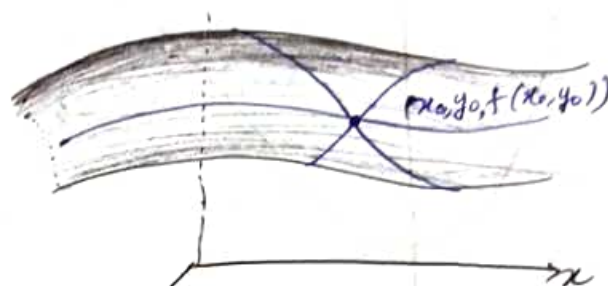
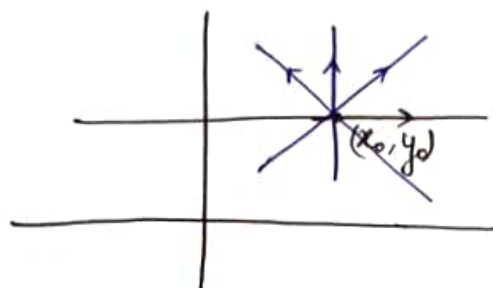
→ $f: G \rightarrow \mathbb{R}$, G open in \mathbb{R}^2

$$P_0 \in G.$$

$$\lim_{h \rightarrow 0} \frac{f(x_0+h, y_0) - f(x_0, y_0)}{h}$$

$$P_0 = (x_0, y_0)$$

$$P = (x_0+h, y_0)$$



Distance b/w $P_0 = (x_0, y_0)$ & $(P_0 + t\bar{v})$,

$$d(P_0, P_0 + t\bar{v})$$

$$= \|P_0 - (P_0 + t\bar{v})\|$$

$$= \|t\bar{v}\| = |t| \|\bar{v}\|$$

$$= |t|$$

$$\rightarrow \lim_{t \rightarrow 0} \frac{f(P_0 + t\bar{v}) - f(P_0)}{t},$$

if exists, is called the direction derivate of f at P_0 along \bar{v} ($\|\bar{v}\|=1$) and is denoted by $D_{\bar{v}}(f)|_{P_0}$.

Observations:

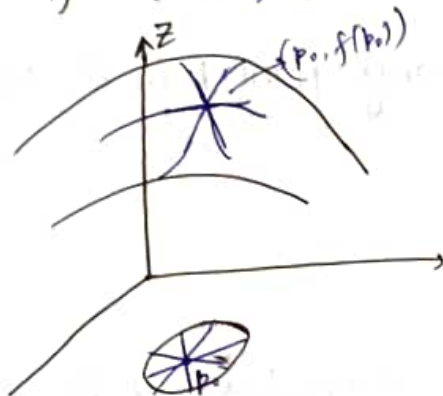
$$\textcircled{1} \frac{\partial}{\partial x}(f)|_{P_0} = D_{e_1}(f)|_{P_0}.$$

$$\textcircled{2} \phi(t) = f(p_0 + t\bar{v})$$

$$\begin{aligned} \frac{d}{dt} \phi(t) \Big|_{t=0} &= \lim_{t \rightarrow 0} \frac{\phi(t) - \phi(0)}{t-0} \\ &= \lim_{t \rightarrow 0} \frac{f(p_0 + t\bar{v}) - f(p_0)}{t} \\ &= D_{\bar{v}}(f) \Big|_{p_0} \end{aligned}$$

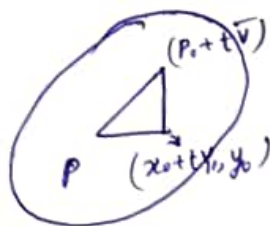
5-06-2023

$$\rightarrow f: G \rightarrow \mathbb{R}, G \subset \mathbb{R}^2$$



$$\lim_{t \rightarrow 0} \frac{f(p_0 + t\bar{v}) - f(p_0)}{t}$$

$$= \lim_{t \rightarrow 0} \frac{f(x_0 + tv_1, y_0 + tv_2) - f(x_0 + tv_1, y_0)}{tv_2} \times v_2 + \frac{f(x_0 + tv_1, y_0) - f(x_0, y_0)}{tv_1} \times v_1$$



$$p_0 = (x_0, y_0)$$

$$p_0 + t\bar{v} = (x_0 + tv_1, y_0 + tv_2)$$

$$\bar{v} = (v_1, v_2)$$

$$\|\bar{v}\| \neq 0 \Rightarrow v_1^2 + v_2^2 = 1$$

$$v_1 \neq 0 \neq v_2$$

$$\frac{f(x_0 + tv_1, y_0 + tv_2) - f(x_0, y_0)}{t}$$

$$= \frac{\partial}{\partial y}(f) \Big|_{(x_0 + tv_1, y_0)} \times v_2 + \frac{\partial}{\partial x}(f) \Big|_{(x_0 + tv_1, y_0)} \times v_1$$

Conclusions

① Partial derivatives exist in a neighbourhood of p_0 .

② One of the partial derivatives is continuous at p_0 .

$$\lim_{t \rightarrow 0} \phi(x_0 + tv_1, y_0) = \phi(x_0, y_0)$$

$$\begin{aligned}\lim_{p \rightarrow p_0} f(p) &= f(p_0) \\ &= \frac{\partial f}{\partial y} \Big|_{(x_0, y_0)} \cdot \frac{1}{\sqrt{2}} + \frac{\partial f}{\partial x} \Big|_{(x_0, y_0)} \cdot \frac{1}{\sqrt{2}} \\ &= \langle \nabla f|_{p_0}, \vec{v} \rangle\end{aligned}$$

Theorem:

$$p_0 \in G \subset \mathbb{R}^3$$

G is open

[A subset G of \mathbb{R}^n is called open if for any point P in it, one can find an open ball around P in G .]

$$f: G \rightarrow \mathbb{R}$$

Suppose that

- ① the partial derivative of f exists in a neighbourhood of p_0 .
- ② Two of the three partial derivatives are continuous at p_0 .

$$\text{Then: } \begin{cases} \text{① } D_{\vec{v}}(f)|_{p_0} \text{ exists } \forall \vec{v}. \\ \text{② } D_{\vec{v}}(f)|_{p_0} = \langle \nabla f|_{p_0}, \vec{v} \rangle. \end{cases}$$

Corollary: $f: G \rightarrow \mathbb{R}$, $G \subset \mathbb{R}^3$, open.

If f is C^1 -type, then

$$\text{① } D_{\vec{v}}(f)|_{p_0} \text{ exists } \forall \vec{v}.$$

$$\text{② } D_{\vec{v}}(f)|_{p_0} = \langle \nabla f|_{p_0}, \vec{v} \rangle.$$

Defn: A function is called C^1 -type if its 1st order partial derivatives exist and they are continuous.

$$\text{① } \text{If } f(x, y, z) = \sin(x^2 + y^2) + e^{xyz}.$$

Prove $D_{\vec{v}}(f)$ exists when $\vec{v} = (\frac{1}{\sqrt{5}}, \frac{1}{\sqrt{5}}, \frac{1}{\sqrt{3}})$ & $p_0 = (0, 1, 0)$.

Soln: $\sin(x^2 + y^2)$ is C^1 -type fn as it is a composition of two C^1 -type functions $(x^2 + y^2)$ which is a polynomial function and $\sin(x)$ which is trigonometric function.

e^{xyz} is also C^1 -type fn, being composition of exp. fn. and xyz fn, both of which are C^1 -type.

Since f is C^1 -type, by the theorem, $D_{\vec{v}}(f)|_{p_0}$ exists \forall dir. \vec{v} and for any pt. p_0 .

and hence being specific,

$D\bar{v}(f)|_{p_0}$ exists when $\bar{v} = (\frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}})$.

$$\begin{aligned} \text{and, } D\bar{v}(f)|_{p_0} &= \langle \nabla f|_{p_0}, \bar{v} \rangle \\ &= \frac{1}{\sqrt{3}} [\cos(x^2+y^2) \cdot 2x + yz e^{xyz}]|_{(0,1,0)} + \frac{1}{\sqrt{3}} [\cos(x^2+y^2) \cdot 2y + xz e^{xyz}]|_{(0,1,0)} \\ &\quad + \frac{1}{\sqrt{3}} [xy e^{xyz}]|_{(0,1,0)} \\ &= 0 + 0 + 0 = 0 \\ \Rightarrow D\bar{v}(f)|_{p_0} &= 0 \end{aligned}$$

Q) Find directions \bar{v} for which $D\bar{v}(f)|_{(0,0)}$ exists.

$$f(x,y) = \begin{cases} \frac{2xy}{x^2+y^2}, & (x,y) \neq (0,0) \\ 0, & \text{otherwise.} \end{cases}$$

Soln:

$$\lim_{t \rightarrow 0} \frac{f(p_0 + t\bar{v}) - f(p_0)}{t}$$

$$\left[\begin{array}{l} p_0 \equiv (0,0) \\ \bar{v} = (v_1, v_2), \|\bar{v}\| = 1 \Leftrightarrow v_1^2 + v_2^2 = 1 \end{array} \right]$$

$$= \lim_{t \rightarrow 0} \frac{f(tv_1, tv_2) - f(0,0)}{t}$$

$\left. \begin{array}{l} v_1=0, v_2=1 \\ v_1=1, v_2=0 \\ v_1 \neq 0, v_2 \neq 0 \end{array} \right\} \text{ never zero together}$

$$= \lim_{t \rightarrow 0} \frac{t^2 v_1 v_2}{t^2 (v_1^2 + v_2^2)} - 0$$

$$= \lim_{t \rightarrow 0} \frac{v_1 v_2}{t} \xrightarrow{v_1 v_2 = 0} \text{ exists value is 0}$$

$\xrightarrow{v_1 v_2 \neq 0} \text{ does not exist.}$

$$\underline{v_1 v_2 = 0}$$

$$\begin{aligned} \bullet v_1=0, v_2=1 &\rightarrow \bar{v} = \hat{e}_2 \rightarrow \frac{\partial}{\partial y} \\ \bullet v_1=1, v_2=0 &\rightarrow \bar{v} = \hat{e}_1 \rightarrow \frac{\partial}{\partial x} \end{aligned}$$

→ ~~$P \in G \subset \mathbb{R}^2$ open~~ $P_0 \in G \subset \mathbb{R}^2$ open.

$$f: G \rightarrow \mathbb{R}$$

Is f diff. at P_0 ?



$$\lim_{(h,k) \rightarrow (0,0)} \frac{f(x_0+h, y_0+k) - f(x_0, y_0) - \alpha h - \beta k}{\sqrt{h^2+k^2}} = 0$$

Costr.: / can see that

→ Existence of tangent plane at P_0 .

In general No! \Uparrow ? \Downarrow ? → yes

Existence of tangent lines at P_0

III

Differentiability of the fn f at P_0 .

No, in general \Uparrow \Downarrow → yes

Existence of dir. der. of f at P_0 for all dir.



$$f(x) = f(a) + (x-a)f_1(x)$$

$$\lim_{x \rightarrow a} f(x) = f(a)$$

$$\Leftrightarrow \lim_{x \rightarrow a} (f(x) - f(a)) = 0$$

⇒ When $x \approx a$, then $f(x) \approx f(a)$.

$$f(x) = f(a) + (x-a)f_1(x)$$

When $x \approx a$,

$$f(x) \approx f(a) + (x-a)f_1(a)$$

$$= f(a) + (x-a)\alpha$$

As if $f(x) = f(a) + (x-a)\alpha$.

$$f'(a) = \alpha = f_1(a)$$

$$Q \quad f(x, y) = \begin{cases} \frac{x^2 y}{x^2 + y^2}, & (x, y) \neq (0, 0) \\ 0, & \text{otherwise} \end{cases}$$

Show that f is not differentiable at $(0, 0)$.

Soln: $\lim_{t \rightarrow 0} \frac{f(p_0 + t\bar{v}) - f(p_0)}{t}, \quad p_0 = (0, 0), \bar{v} = (v_1, v_2)$

$$= \lim_{t \rightarrow 0} \frac{f(t\bar{v}_1, t\bar{v}_2) - f(0, 0)}{t}, \quad |\bar{v}| = 1, v_1^2 + v_2^2 = 1.$$

$$= \lim_{t \rightarrow 0} \frac{t^3 v_1^2 v_2}{t^2(t^2 v_1^2 + v_2^2)} = 0$$

$$= \lim_{t \rightarrow 0} \frac{v_1^2 v_2}{t^2 v_1^2 + v_2^2}$$

$$= \begin{cases} 0, & \bar{v} = (1, 0) \rightarrow G_1 \rightsquigarrow \frac{\partial f}{\partial x} \\ 0, & \bar{v} = (0, 1) \rightarrow G_2 \rightsquigarrow \frac{\partial f}{\partial y} \\ \frac{v_1^2}{v_2}, & \bar{v} = (v_1, v_2), v_1 \neq 0, v_2 \neq 0 \rightarrow \text{arbitrary dirn} \end{cases}$$

$D_{\bar{v}} f|_{(0,0)}$ exists for all direction \bar{v} .

$$\langle \nabla f|_{(0,0)}, \bar{v} \rangle = 0 \neq \frac{v_1^2}{v_2} = D_{\bar{v}}(f)|_{p_0} \text{ when } v_1 \neq 0, v_2 \neq 0$$

$$\langle \frac{\partial f}{\partial x}|_{(0,0)}, \frac{\partial f}{\partial y}|_{(0,0)}, \bar{v} \rangle$$

$$= \langle (0, 0), \bar{v} \rangle$$

$\Rightarrow f$ is not differentiable.

Q $f(x, y, z) = z^2 + \sin(e^{x^2+y^2})$. Is it diff at $(0, 0, 0)$?

Soln:

If f is G_1 -type, then f is differentiable.

z^2, x^2+y^2 , exponent, \sin are G_1 -type.

\therefore Composition is G_1 type $\Rightarrow f$ is G_1 type.
 $\Rightarrow f$ is diff.

Remark:

A: $\begin{cases} A_1: \text{all the partial derivatives of } f \text{ exist in open ball around } p. \\ A_2: \text{two of 3 partial derivatives of } f \text{ are continuous at } p. \end{cases}$

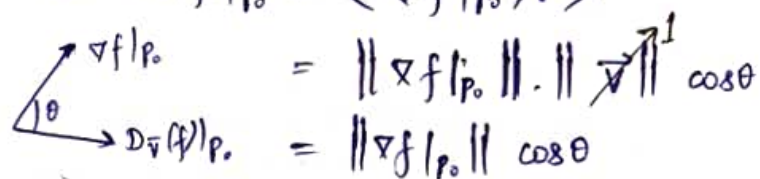
\downarrow
B: $\{f \text{ is differentiable at } p.\}$

\downarrow
C: $\begin{cases} C_1: D_v(f)|_{p_0} \text{ exist for all dir}^n \\ C_2: D_v(f)|_{p_0} = \langle \nabla f|_{p_0}, \bar{v} \rangle \end{cases}$

→ Suppose f is diff / C_1 -type.

(i) $D_v(f)|_{p_0}$ exists $\forall \bar{v}$.

(ii) $D_v(f)|_{p_0} = \langle \nabla f|_{p_0}, \bar{v} \rangle$


$$\begin{aligned} \nabla f|_{p_0} &= \|\nabla f|_{p_0}\| \cdot \|\bar{v}\| \cos \theta \\ D_{\bar{v}}(f)|_{p_0} &= \|\nabla f|_{p_0}\| \cos \theta \end{aligned}$$

$$\min [D_{\bar{v}}(f)|_{p_0}] = 0, \theta = \pi/2$$

$$\max [D_{\bar{v}}(f)|_{p_0}] = \|\nabla f|_{p_0}\|, \theta = 0, \pi; \bar{v} = \pm \nabla f|_{p_0}$$

→ Corollary:

If (A) $\begin{cases} (A_1) D_{\bar{v}}(f)|_{p_0} \text{ exists } \forall \bar{v} \\ (A_2) D_{\bar{v}}(f)|_{p_0} = \langle \nabla f|_{p_0}, \bar{v} \rangle \end{cases}$

does not hold, then

f is not differentiable at p_0 .

$$B \Rightarrow A (= A_1 \& A_2)$$

$$\sim B \Leftarrow \sim A (= \sim A_1 \& \sim A_2)$$

$$(= \sim A_1 \vee \sim A_2)$$

$$(= \sim A_1 \text{ or } \sim A_2)$$

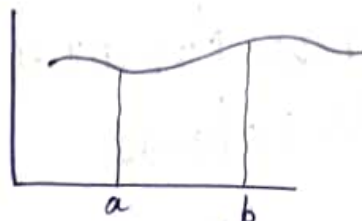
ARC LENGTH FUNCTION 12-06-2023

→ perpendicular is the shortest

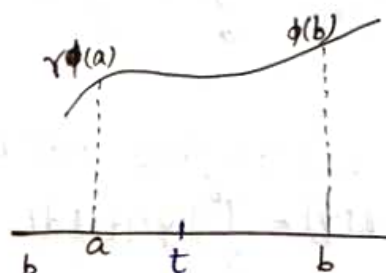
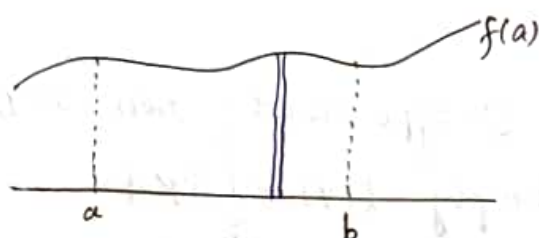
$\nabla f|_{P_0} \rightarrow$ gives perpendicular dirⁿ

→ $\int_a^b f(x) dx$

weighted length of the f^n of interval $[a, b]$



→ Parametric equations give directed/oriented curve.



Weighted length of interval $[a, b] = \int_a^b f(x) dx$

$\gamma \phi [a, b] \xrightarrow{\text{continuous}} \mathbb{R}^2 \text{ (or } \mathbb{R}^3)$

We shall call γ to be parametric curve.

eg. $\gamma_1(t) = \cos t, \sin t$, $t \in (0, 2\pi]$

$\gamma_2(t) = (\cos 2\pi t, \sin 2\pi t)$, $t \in (0, 1)$

$\gamma_3(t) = (t, 0)$, $t \in (a, b)$



oriented/directed curve

$$L_n = \sum_{i=1}^n \|\gamma(t_i) - \gamma(t_{i-1})\|$$

If $\lim_{n \rightarrow \infty} L_n = l$ exists, $l \rightarrow$ length of γ

$$\lim_{\substack{\Delta t \rightarrow 0 \\ n \rightarrow \infty}} \int_{t=1}^{\infty} \gamma(t) \Delta t$$

Q) (i) $\gamma(t) = \cos t, \sin t, t \in [0, 2\pi]$.

(ii) $\phi(t) = (x, 0), x \in [a, b]$.

Soln: γ is C^1 -fn of \sin & \cos

ϕ is C^1 -fn.

$\Rightarrow l(\gamma)$ exists & $l(\phi) = \int_0^{2\pi} \|\gamma'(t)\| dt$

$\gamma'(t) = (-\sin t, \cos t), t \in [0, 2\pi]$.

$\|\gamma'(t)\| = 1$

$l(\gamma) = \int_a^b \|\gamma'(t)\| dt = \int_a^b 1 dt$

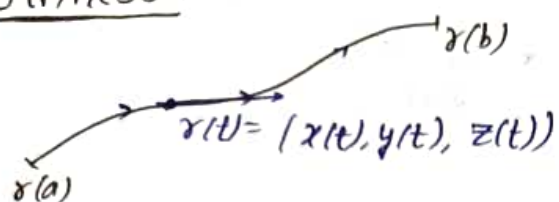
$\int_a^b f(x) dx = \int_a^b 1 dx = \int_a^b dx$

Theorem: Let $\gamma: [a, b] \rightarrow \mathbb{R}^3$ be a C^1 -type curve. Then, $l(\gamma)$ exists, and $l(\gamma) = \int_a^b \|\gamma'(t)\| dt$ or simply $l(\gamma) = \int_a^b \|\gamma'\|$.



$$\frac{d}{dx} s(x) = \|r'(x)\| \leftarrow \text{continuous.}$$

Smoothness:



r is C^1 -type. (say)

$$r'(t) = (x'(t), y'(t), z'(t))$$

Tangent vector at 't',

$$T(t) = r'(t)$$

If $r'(t) \neq 0 \forall t$, then we call r

Smoothness $\Leftrightarrow C^1$ -type + non-zero tangent

$$\Pi(t) = \frac{T(t)}{\|T(t)\|} \text{ is called unit tangent at the point 't'.$$

C^1 -type \Rightarrow Tangent is continuous.

Smoothness \Rightarrow non-zero continuous tangent at any pt.

$$s(x) = \int_a^x \|r'(t)\| dt$$

r is smooth \Rightarrow ① $s \uparrow$ strictly
② s is smooth.

$$\begin{aligned} \rightarrow l(r) &= \int_a^b \|r'(t)\| dt \\ s(x) &= \int_a^x \|r'(t)\| dt \end{aligned}$$

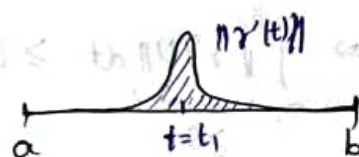
$$\boxed{\frac{d}{dx} s(x) = \|r'(x)\|}$$

and if $ds = \|r'(t)\| dt$

$$l(r) = \int_0^{l(r)} 1 ds$$

$$s(a) = 0$$

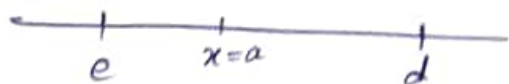
$$s(b) = l(r).$$



\rightarrow If a continuous fn takes non-zero value at a point, then it takes non-zero values ~~at~~ in an interval around that point.

#

$$\cdot f(a) \neq 0$$



If there is no interval

then $f \equiv 0$ on $[e, d] \setminus \{a\}$
 $\xrightarrow{\text{reads 'minus'}}$

$$\lim_{x \rightarrow a} f(x) = f(a)$$

$$\lim_{\substack{x \rightarrow a \\ x \neq a}} f(x) = \lim_{x \rightarrow a} 0 = 0 \neq f(a)$$

This contradicts the assumption of $f(x)$ is continuous.

Theorem: Let $s: [a, b] \rightarrow \mathbb{R}$ be the arc length function of C^1 -type curve $\gamma: [a, b] \rightarrow \mathbb{R}^3$. Then, the following holds

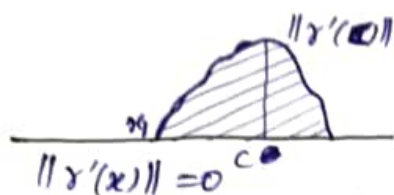
- (i) $s(x) \geq 0 \quad \forall x \in [a, b]$, $s(a) = 0$, and $s(b) = l(\gamma)$.
- (ii) s is non-decreasing
- (iii) $s \equiv 0$ iff $\gamma'(t) \equiv \vec{0}$ for some $t \in [a, b]$, i.e., $s \equiv 0$ iff $\gamma' = \vec{0}$ on $[a, b]$.
- (iv) If $\gamma'(t) \neq \vec{0} \quad \forall t \in [a, b]$ (i.e., γ is smooth), then $s(x) = 0$ iff $x = a$.
- (v) If $\gamma'(t) \neq \vec{0} \quad \forall t \in [a, b]$ (i.e., γ is smooth), then s is strictly increasing on $[a, b]$.
- (vi) s is continuous on $[a, b]$.
- (vii) s is differentiable on $[a, b]$.
- (viii) s is C^1 -type on $[a, b]$, and $\frac{d}{dx} s(x) = \|\gamma'(x)\| \quad \forall x \in [a, b]$.
- (ix) s is smooth if γ is smooth.

Intermediate Value Theorem

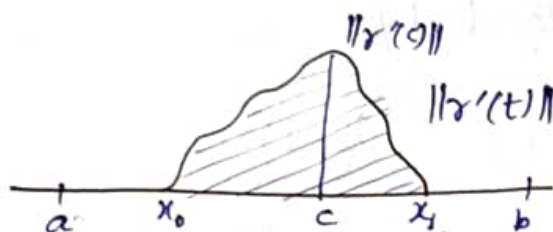
$$f: [a, b] \xrightarrow{\text{cont}} \mathbb{R}$$

$$x_1 < x_2 \in [a, b]$$

Then f attains all the values between $f(x_1)$ and $f(x_2)$ in $[x_1, x_2]$.

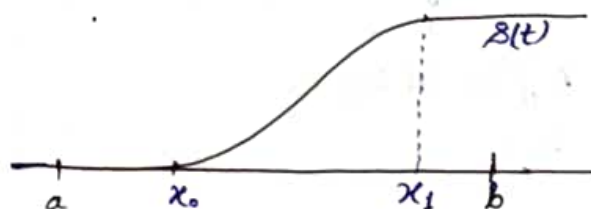


- $s \neq 0$, if $\exists t \in [a, b]$ such that $r'(t) \neq \vec{0}$.
 (i.e. $\exists c \in [a, b]$ s.t. $s(c) \neq 0$)



$$s(c) = \int_a^c ||r'(t)|| dt = \int_a^{x_0} ||r'(t)|| dt + \int_{x_0}^c ||r'(t)|| dt$$

> 0



Q] $c: x^2 = y^3, 9z^2 = 4y$. Initial point is $(0, 0, 0)$ & final pt. is $(8, 9, \frac{4}{3})$.

Parametrize the curve.

Check if $l(c)$ exists. Find arc-length f^n of c , if exists, and hence find $l(c)$, if possible.

Soln:

$$r(t) = (x(t), y(t), z(t))$$

$$z^2 = \frac{4}{9}y \quad \& \quad x^2 = y^3$$

$$t \in (0, \frac{4}{3})$$

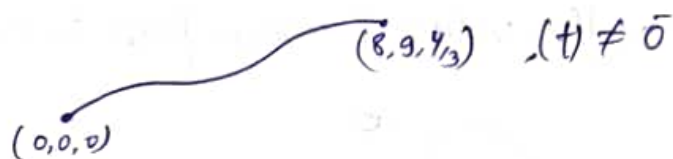
$$z = t, y = \frac{9}{4}t^2, x = \sqrt{\left(\frac{9}{4}\right)^3 t^6} = \pm \frac{27}{8}t^3$$

Initial point is $(0, 0, 0)$ & final pt. is $(8, 9, \frac{4}{3})$.

$$\gamma(t) = \left(\frac{27}{8} t^3, \frac{9}{4} t^2, t \right), \quad t \in [0, 1/3]$$

$$t=0 \rightarrow \gamma(0) = (0, 0, 0)$$

$$t=1/3 \rightarrow \gamma(1/3) = (8, 9, 1/3)$$



$$(0, 0, 0) \quad (8, 9, 1/3) \quad (t) \neq 0$$

$l(c)$ exists if c is C^1 -type.

Since c is given by $\gamma(t)$ and the ^{component} ~~comp~~ n of γ are C^1 -type, γ is C^1 -type and hence $l(\gamma)$ exists and

$$l(\gamma) = \int_0^{1/3} \|\gamma'(t)\| dt$$

$$\gamma'(t) = \left(\frac{3 \times 27}{8} t^2, \frac{9 \times 2}{4} t, 1 \right)$$

$$\|\gamma'(t)\| = \sqrt{\left(\frac{3 \times 27}{8} t^2 \right)^2 + \left(\frac{9 \times 2}{4} t \right)^2 + 1}$$

Since γ is C^1 -type, the arc length s^n

$s: [0, 1/3] \rightarrow \mathbb{R}$ exists and is given by

$$s(x) = \int_0^x \|\gamma'(t)\| dt, \quad x \in [0, 1/3] = \dots$$

$$l(\gamma) = s(1/3)$$

$$l(c)$$

Opposite Orientation

$$\rightarrow \gamma: [a, b] \xrightarrow{\text{cont}} \mathbb{R}^2$$



$$\gamma(a) \rightarrow \gamma(b) \rightarrow \gamma(c)$$

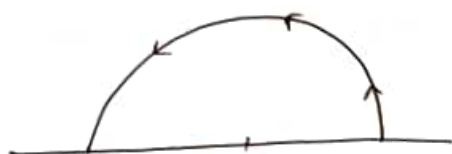
$$\delta(t) = \gamma(a+b-t), \quad t \in [a, b]$$

↳ will be opposite oriented.

$$\phi(t) = (a+b-t), \quad t \in [a, b]$$

$(-\gamma)$ or $\gamma^{-1} = \gamma(a+b-t), \quad t \in [a, b]$
is called inverse of γ .

Q) $\gamma(t) = (\cos t, \sin t), \quad t \in [0, \pi]$



Find γ^{-1} .

Soln: $\gamma^{-1}(t) = \gamma(0+\pi-t)$
 $= (\cos(\pi-t), \sin(\pi-t)), \quad t \in [0, \pi].$
 $= (-\cos t, \sin t).$

- If γ is C^1 -type, γ^{-1} is C^1 -type
 $\Rightarrow l(\gamma^{-1})$ exists.

$$l(\gamma) = \int_a^b \|\gamma'(t)\| dt$$

Aim: To show $l(\gamma) = l(\gamma^{-1})$.

$$\delta(t) = \gamma^{-1}(t) \quad \forall t \in [a, b]$$

$$= \gamma(a+b-t) \quad \forall t \in [a, b]$$

$$l(\gamma^{-1}) = l(\delta) = \int_a^b \|\delta'(t)\| dt$$

$$\delta'(t)$$

$$\frac{d}{dt} \delta(t) = \frac{d}{dt} (\gamma(a+b-t))$$

$$= \frac{d}{ds} \gamma(s) \cdot \frac{ds}{dt} = \gamma'(s) \cdot (-1)$$

$$, \quad s = a+b-t$$

$$l(s) = \int_a^b \| \gamma'(s) \| ds = \int_a^b \| \gamma'(t) \| dt$$

$$= l(\gamma)$$

$$\gamma(t) = (\cos t, \sin t)$$

$$\int_a^b \| \gamma'(s) \| dt$$

$$s = a + b - t$$

$$\| \text{ as if } ds = -dt$$

$$a \xrightarrow{s} b$$

$$b \xrightarrow{s} a$$

as if

$$\int_a^b \| \gamma'(s) \| \times -ds$$

$$= \int_a^b \| \gamma'(s) \| ds.$$

$$\rightarrow f: G \xrightarrow{\text{cont.}} \mathbb{R}$$

LINE INTEGRATION

$$\gamma: [a, b] \xrightarrow{C^1\text{-type}} \mathbb{R}^3$$

$$\{\gamma\} \subset G \quad (\text{to talk about } f(\gamma(t)))$$

\{Points of \gamma in G\}

$$L(\gamma) = \int_a^b \|\gamma'(t)\| dt = \int_a^b 1 \cdot dx$$

We can talk about line integration of f along the length of γ (i.e. weighted length of γ & the weight is by the $f \circ \gamma$)

denoted by $\int_{\gamma} f$ and,

given by

$$\begin{aligned} \int_{\gamma} f &= \int_a^b f(\gamma(t)) ds \\ &= \int_a^b f(\gamma(t)) \underbrace{\|\gamma'(t)\|}_{\text{cont.}} dt \end{aligned}$$

as if $ds = \|\gamma'(t)\| dt$

$$\frac{d}{dx} s(x) = \|\gamma'(x)\|$$

$$\rightarrow \text{Field} \rightarrow \vec{F}: G \rightarrow \mathbb{R}^2 (\text{or } \mathbb{R}^3)$$

$$\int_a^b \frac{d}{dt} (g(t)) dt = g(b) - g(a)$$

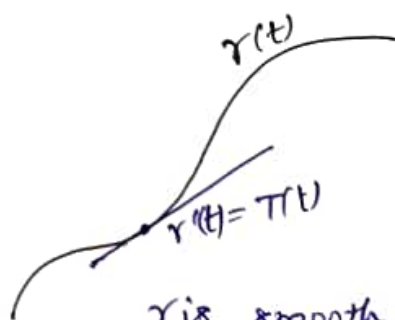
$$\int_{\gamma} \langle \vec{F}, \vec{v} \rangle ; \quad \vec{F} = \nabla f$$

$$\downarrow$$

$$\int_{\gamma} \langle \vec{F}, \vec{T}_\gamma(t) \rangle$$

$$= \int_a^b \left\langle \vec{F}(\gamma(t)), \frac{\gamma'(t)}{\|\gamma'(t)\|} \right\rangle \|\gamma'(t)\| dt$$

$$= \int_a^b \langle \vec{F}(\gamma(t)), \gamma'(t) \rangle dt$$



γ is smooth

$$T(t) = \frac{\gamma'(t)}{\|\gamma'(t)\|}$$

$$\begin{aligned}
& \langle \nabla f(r(t)), r'(t) \rangle \\
&= \left\langle \left(\frac{\partial}{\partial x} (f(r(t))), \frac{\partial}{\partial y} (f(r(t))), (x'(t), y'(t)) \right) \right\rangle \\
&= \frac{\partial}{\partial t} f(r(t)) \cdot x'(t) + \frac{d}{dy} f(r(t)) \cdot y'(t) \\
&= \frac{d}{dt} f(r(t))
\end{aligned}$$

$$\rightarrow G \subset \mathbb{R}^3$$

$$\bar{F}: G \xrightarrow{\text{cont.}} \mathbb{R}^3 \text{ (or } \mathbb{R}^3)$$

$$\gamma: [a, b] \xrightarrow{\text{smooth}} \mathbb{R}^3 \text{ s.t. } \{\gamma\} \subset G$$

Then, the line integration of \bar{F} along γ is denoted by

$$\int_{\gamma} \bar{F} \quad (\text{or } \int_{\gamma} \bar{F} \cdot d\mathbf{s}) \text{ and is given by}$$

$$\int_{\gamma} \bar{F} = \int_a^b \langle \bar{F}(\gamma(t)), \gamma'(t) \rangle dt$$

$$= \int_a^b \left\langle \bar{F}(\gamma(t)), \frac{\gamma'(t)}{\|\gamma'(t)\|} \right\rangle \|\gamma'(t)\| dt$$

$$= \int_a^b \langle \bar{F}(\gamma(t)), \gamma'(t) \rangle dt$$

Theorem (Fundamental Theorem of Line Integral)

$$G \subset \mathbb{R}^3$$

$$\vec{F}: G \xrightarrow{\text{continuous}} \mathbb{R}^2 \text{ (or } \mathbb{R}^3)$$

$$\gamma: [a, b] \xrightarrow{\text{smooth}} \mathbb{R}^3$$

If $\vec{F} = \nabla f$ on G , then

$$\int_{\gamma} \vec{F} = f(\gamma(b)) - f(\gamma(a))$$

Defn: A vector field \vec{F} is called a conservative vector field (CVF) if $\vec{F} = \nabla f$ on $\text{dom}(\vec{F})$.

Suppose $\text{dom}(\vec{F}) = G$, then $f: G \rightarrow \mathbb{R}$
s.t. $\nabla f(p) = \vec{F}(p)$, $p \in G$.

Corollary: If \vec{F} is a C.V.F., then

① $\int_{\gamma_1} \vec{F} = \int_{\gamma_2} \vec{F}$ if γ_1 & γ_2 are two paths with same initial & final pts.

② $\int_{\gamma} \vec{F} = 0$ \forall loop γ .

(Assumption: When talking about line int. of V.F., the path/curve is always smooth or piece-wise smooth.)

Q1 Show that:

$$\textcircled{1} \int_{\gamma} \vec{F} = - \int_{\gamma^{-1}} \vec{F}$$

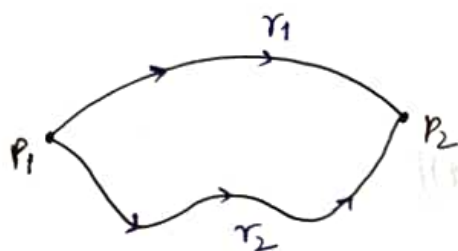
$$\textcircled{2} \int_{\gamma} f = \int_{\gamma^{-1}} f$$

Joining Two Curves

γ_1, γ_2 are parametric curves s.t. end pt. of γ_1 = beginning pt. of γ_2
then we can make a new curve by joining γ_1 & γ_2 s.t. the orientation is respected; the new curve is denoted by γ_1 and γ_2 .

Defⁿ: $\int_{\gamma_1 * \gamma_2} f = \int_{\gamma_1} f + \int_{\gamma_2} f$

$$\int_{\gamma_1 * \gamma_2} \bar{F} = \int_{\gamma_1} \bar{F} + \int_{\gamma_2} \bar{F}$$



$$\gamma_1 * \gamma_2 \quad \times$$

$$\gamma_1 * \gamma_2^{-1} \quad \checkmark$$

$$\int_{\gamma_1 * \gamma_2^{-1}} \bar{F} = 0$$

$$\Rightarrow \int_{\gamma_1} \bar{F} + \int_{\gamma_2^{-1}} \bar{F} = 0$$

$$\Rightarrow \int_{\gamma_1} \bar{F} - \int_{\gamma_2} \bar{F} = 0 \quad (\text{By property})$$

$$\Rightarrow \int_{\gamma_1} \bar{F} = \int_{\gamma_2} \bar{F}$$

Corollary:

If \vec{F} is C.V.F., then

(A) $\int_{\gamma_1} \vec{F} = \int_{\gamma_2} \vec{F}$ for any two paths γ_1 and γ_2 with same initial and final points.

(B) $\int_{\gamma} \vec{F} = 0$ \forall loops γ .

Theorem:

If \vec{F} is a continuous v.f., then the following are equivalent:

(A) $\int_{\gamma_1} \vec{F} = \int_{\gamma_2} \vec{F}$ for path γ_1 & γ_2 of same initial & final pts.

(B) $\int_{\gamma} \vec{F} = 0$ \forall loops γ .

Proof: B \Leftrightarrow (A)

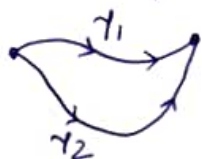
$\nwarrow \nearrow$
C \rightsquigarrow \vec{F} is conservative vector field

Assume (B) holds.

Aim: To show (A) holds,

ie, to show $\int_{\gamma_1} \vec{F} = \int_{\gamma_2} \vec{F}$ where ...

Let γ_1 & γ_2 be two paths. ~~then γ is a loop~~



Define $\gamma = \gamma_1 * \gamma_2$,

then γ is a loop.

$\int_{\gamma} \vec{F} = 0$ by hypothesis (B)

$$\begin{aligned} \int_{\gamma_1 * \gamma_2} \vec{F} &= \int_{\gamma_1} \vec{F} + \int_{\gamma_2} \vec{F} = \int_{\gamma_1} \vec{F} - \int_{\gamma_2} \vec{F} \\ &\Rightarrow \int_{\gamma_1} \vec{F} = \int_{\gamma_2} \vec{F} \end{aligned}$$

Now, aim: To prove $(A) \Rightarrow (B)$.

Assume (A) holds to show (B) holds

Let γ be a loop.

$$\int_{\gamma} \bar{F}$$



$$\text{let } \gamma_1 = P_1 \xrightarrow{\gamma} P_2$$

$$\gamma_2 = P_1 \xrightarrow{\gamma^{-1}} P_2$$

Note that $\gamma = \gamma_1 \star \gamma_2^{-1}$

$$\text{By hyp., } \int_{\gamma} \bar{F} = \int_{\gamma} F$$

$$\Rightarrow \int_{\gamma_1} \bar{F} - \int_{\gamma_2} F = 0$$

$$\Rightarrow \int_{\gamma_1} \bar{F} + \int_{\gamma_2} \bar{F} = 0$$

$$\Rightarrow \int_{\gamma_1 \star \gamma_2^{-1}} \bar{F} = 0 \Rightarrow \int_{\gamma} F = 0$$

$$\therefore (A) \Leftrightarrow (B)$$

$$\nwarrow (C) \nearrow$$



First Structural Theorem of CVF:

Let $G \subset \mathbb{R}^3$ (or \mathbb{R}^2) open & $\vec{F}: G \rightarrow \mathbb{R}^3$ (or \mathbb{R}^2) a continuous V.F.
 Suppose that G is path connected, then the following are equivalent:

(A) ...

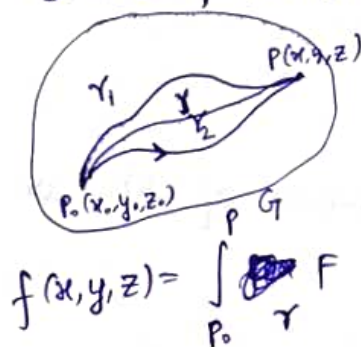
(B) ...

(C) \vec{F} is a c.v.f., i.e., $\exists f: G \rightarrow \mathbb{R}$ such that $\nabla f = \vec{F}$ on G .

Proof: (A) \Leftrightarrow (B) already proved.
 no need of condition that G is path connected.

(C) \Rightarrow (B)
 \Rightarrow (A) already done.

For (A) \Rightarrow (C), assume (A) holds.



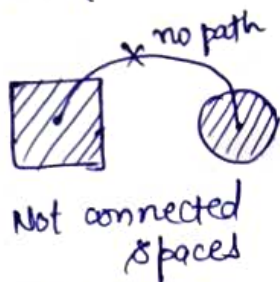
\rightarrow for a given $g: [a, b] \xrightarrow{\text{cont.}} \mathbb{R}$ } Fundamental theorem of calculus

$$h(x) = \int_a^x g(t) dt$$

Since G is path connected, there exists a path from P_0 to P and take one of them (say γ).

fact: $\nabla f = \vec{F}$ on G .

$G \subset \mathbb{R}^3$ (or \mathbb{R}^2) is called path connected if for any two points P_1 and P_2 in G , there exists a path / curve joining P_1 & P_2 and lying on G .



$$A \Leftrightarrow B \Leftrightarrow C$$

$$\sim A \Leftrightarrow \sim B \Leftrightarrow \sim C$$

Q] Let $F(x,y) = \left(\frac{-y}{x^2+y^2}, \frac{x}{x^2+y^2} \right) \forall (x,y) \in \mathbb{R}^2 - \{0,0\}$.

check conservativeness.

Soln: \bar{F} is rational function \Rightarrow continuous $\forall (x,y) \in \mathbb{R}^2 - \{0,0\}$.

$$\gamma(t) = (\gamma \cos t, \gamma \sin t), t \in [0, 2\pi]$$

$$(\text{claim: } \int \bar{F} = 2\pi \neq 0)$$

$$\gamma'(t) = (-\gamma \sin t, \gamma \cos t) \forall t \in [0, 2\pi) \neq (0,0)$$

$\Rightarrow \gamma'$ is continuous fn.

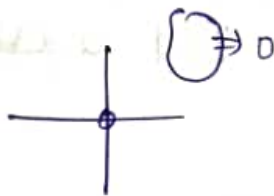
Hence, $\int \bar{F}$ makes sense.

$$\int_0^{2\pi} \bar{F}(\gamma(t)) \cdot \gamma'(t) dt \quad (\bar{F} \text{ is cont. \& } \gamma \text{ is smooth})$$

$$= \int_0^{2\pi} \left\langle \left(-\frac{\gamma \sin t}{\gamma^2}, \frac{\gamma \cos t}{\gamma^2} \right), (-\gamma \sin t, \gamma \cos t) \right\rangle dt$$

$$= \int_0^{2\pi} 1 \cdot dt = 2\pi \neq 0.$$

Hence from the 1st structural theorem of CVF, we see that F is not CVF in G .

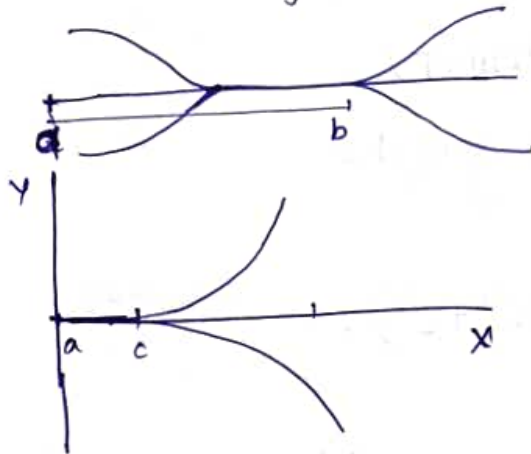
→
#

$$\gamma(t) = (x(t), y(t))$$

$$\gamma'(t) = (x'(t), y'(t))$$

$$\|\gamma'(t)\|$$

$$\int \|\gamma'(t)\|$$



→ Check if $\vec{F} = \nabla f$ on $\text{dom}(\vec{F})$.

Assume $\exists f$ such that $\vec{F} = \nabla f$ on $\text{dom}(\vec{F})$ be defined by

$$\vec{F}(x, y, z) = \nabla f(x, y, z) \quad \text{Find } f.$$

Suppose $\vec{F}: G \rightarrow \mathbb{R}^3$

$$\vec{F}: (F_1, F_2, F_3) = \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z} \right)$$

$$\frac{\partial f}{\partial x} = F_1 \Rightarrow f = \int F_1 dx + c_1(y, z)$$

$$F_2 = \frac{\partial f}{\partial y} = \frac{\partial}{\partial y} \left(\int F_1 dx \right) + \frac{\partial}{\partial y} c_1$$

$$\Rightarrow \frac{\partial}{\partial y} c_1 = F_2 - \frac{\partial}{\partial y} \left(\int F_1 dx \right)$$

$$\Rightarrow c_1 = \int \left(F_2 - \frac{\partial}{\partial y} \left(\int F_1 dx \right) \right) dy + c_2(z)$$

Q1) $\bar{F}(x, y, z) = \left(\frac{x}{x^2+y^2}, \frac{y}{x^2+y^2}, e^z \right)$. Is \bar{F} a CVF?

Soln: Assume that \bar{F} is CVF.

We shall try to find f such that

$$\nabla f = \bar{F} \text{ on } \text{dom}(\bar{F}) = \mathbb{R}^3 \setminus \text{z-axis}$$

$$f = \frac{1}{2} \ln(x^2+y^2) + e^z \quad (\mathbb{R}^3 - \{\text{z-axis}\})$$

diff. w.r.t. x

$$\text{dom}(f) = \mathbb{R}^3 \setminus \text{z-axis} = \text{dom}(\bar{F})$$

We see that $\nabla f = \bar{F}$ on $\text{dom}(\bar{F})$.

$\Rightarrow \bar{F}$ is CVF.

Q1) $\bar{F}(x, y, z) = (\sin(z)e^x, y^2, \cos(z)e^x + z^3)$.

Check if CVF.

Soln: Assume that $\exists f$, $\nabla f = \bar{F}$ on $\text{dom}(\bar{F})$.

Shall

$$f = \sin(z)e^x + \frac{y^3}{3} + \frac{z^4}{9} + C$$

$$\frac{\partial}{\partial y} C_1 = y^2, \quad C_1 = y^2 dy + C_2(z)$$

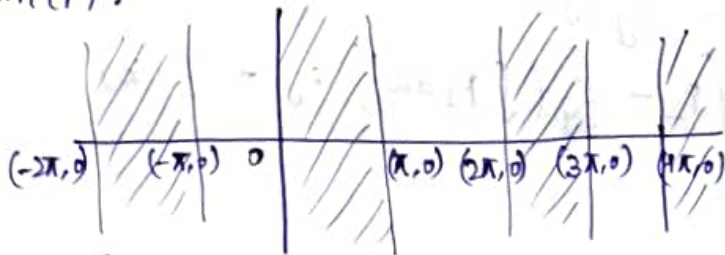
$$\frac{\partial}{\partial z} C_2(x) = F_3 - \frac{\partial}{\partial x} f$$

$$= z^3$$

\therefore CVF

Q1) $\bar{F}(x, y) = (\sqrt{\sin x}, y)$. Check if CVF.

Soln: $\text{dom}(\bar{F})$:



$$\int \sqrt{\sin x} dx$$

$$[0, \pi] \times \mathbb{R}$$

$$f = \int_0^x \sqrt{\sin t} dt + \frac{y^2}{2} \quad \text{in } [0, \pi] \times \mathbb{R}$$

$$\nabla f|_{\pi} = \bar{F} \text{ in } [0, \pi]$$

$$\nabla f|_{2\pi} = \bar{F} \text{ in } [0, 2\pi]$$

$$\textcircled{1} F(x, y) = \left(\frac{-y}{x^2+y^2}, \frac{x}{x^2+y^2} \right), \text{ ~~dom(F)~~ }^G \subset \mathbb{R}^2 \setminus \{0, 0\}.$$

$$\text{Soln: } \text{dom}(F) = \mathbb{R}^2 \setminus \{0, 0\}$$

Try finding f s.t.

$$\nabla f = \bar{F} \text{ in } \text{dom}(\bar{F})$$

$$f_1(x, y) = -\tan^{-1}\left(\frac{x}{y}\right)$$

$$f_2(x, y) = \tan^{-1}\left(\frac{y}{x}\right)$$

$$\nabla f_1 = \bar{F} \text{ on } \mathbb{R} \setminus x\text{-axis} \neq \text{dom}(F)$$

$$\nabla f_2 = \bar{F} \text{ on } \mathbb{R} \setminus y\text{-axis} \neq \text{dom}(F)$$

$$\textcircled{1} F(x, y) = \left(\frac{x}{x^2+y^2}, \frac{y}{x^2+y^2}, e^z \right).$$

$$\text{Soln: } C_1: x^2+y^2=1, \text{ oriented } \oplus \text{vely.}$$

$$C_2: (x-5)^2 + (y-5)^2 = 25, \text{ oriented } \oplus \text{vely.}$$

$$C_3: \overline{(2, 5, 3) \quad (1, 3, 0)}$$

$$\int_{C_1} F \neq \int_{C_2} F = \int_{C_3} F = f(1, 3, 5) - f(2, 5, 3)$$

→ Suppose F is C.V.F.

$$(F_1, F_2) = \nabla f = \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y} \right)$$

$$F_1 = \frac{\partial f}{\partial x}, \quad \frac{\partial f}{\partial y} = F_2$$

$$\frac{\partial F_1}{\partial y} = \frac{\partial}{\partial y} \left(\frac{\partial f}{\partial x} \right) ; \quad \frac{\partial F_2}{\partial x} = \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial y} \right)$$

if F is C^1 -type.

curl of F is zero,

for F is conservative.

Q1 $F(x, y) = (xy, y^2)$. Is F a C.V.F?

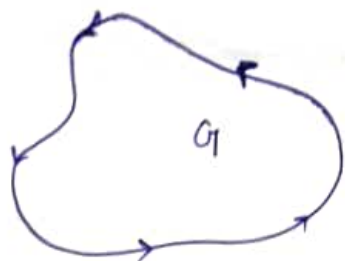
Soln: $F_1 = \frac{\partial f}{\partial x}, \quad F_2 = \frac{\partial f}{\partial y}$

$$F_1 = y$$

$$F_2 = 2y$$

$$\frac{\partial F_1}{\partial y} \neq \frac{\partial F_2}{\partial x} \quad \& \quad F \text{ is } C^1\text{-type}$$

$\therefore F$ is not C.V.F.



G is simply x-y connected.

$$\bar{F}: G \rightarrow \mathbb{R}^2$$

$$\bar{F} = (F_1, F_2)$$

$F = C^1$ -type

G has boundary ∂G oriented (anti-clockwise).

$$\iint_G \left(\frac{\partial}{\partial x} F_2 - \frac{\partial}{\partial y} F_1 \right) = \int_{\partial G} F$$

$$\int_{\partial G} F = \int_{\partial G} \langle (F_1(r(t)), F_2(r(t))), (x'(t), y'(t)) \rangle dt$$

$$= \int_{\partial G} (F_1 dx + F_2 dy)$$

Q1 $\int_C (2x^3 - y^3) dx + (x^3 + y^3) dy$

Soln:



$C: x^2 + y^2 = 1$ (Integrate using Green's theorem)

$$\partial G = \gamma(t) = (\cos t, \sin t), t \in [0, 2\pi]$$

$$\int_{\partial G} (2x^3 - y^3) dx + (x^3 + y^3) dy$$

$$= \int_0^{2\pi} \langle F(r(t)), r'(t) \rangle dt$$

$$\bar{F}(x, y) = (2x^3 - y^3, x^3 - y^3)$$

G is simply connected, \bar{F} is C^1 -type, hence we can apply

Green's theorem:

$$\iint_G \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right)$$

$$\text{RHS} = \iint_{x^2+y^2=1} (3x^2+3y^2) dx dy$$

$$J\left(\frac{x}{r}, \frac{y}{r}\right) = J_{(x,y)}(r, \theta)$$

$$\begin{vmatrix} \frac{\partial}{\partial x} r & \frac{\partial}{\partial x} \theta \\ \frac{\partial}{\partial y} r & \frac{\partial}{\partial y} \theta \end{vmatrix}$$

GREEN'S THEOREM

$$\iint_G \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) = \int_{\partial G} \bar{F}$$

$$J\left(\frac{r}{x}, \frac{\theta}{y}\right) = J_{(x,y)}(r, \theta)$$

$$\begin{vmatrix} \frac{\partial}{\partial x} r & \frac{\partial}{\partial x} \theta \\ \frac{\partial}{\partial y} r & \frac{\partial}{\partial y} \theta \end{vmatrix}$$

$G \subset \mathbb{R}^2$ is open and simply connected, ~~is a~~

$$\bar{F}: G \xrightarrow{G\text{-type}} \mathbb{R}^2$$

$$\text{Suppose } \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} = 0 \Rightarrow F \text{ is CVF}$$

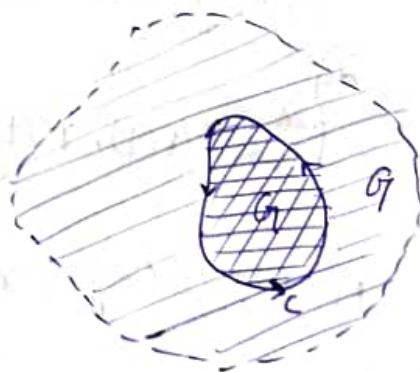
$$\bar{F} \text{ is CVF} \Leftrightarrow \int \bar{F} = 0$$

$$\underbrace{\iint_G \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) dx dy}_0 = \int_C \bar{F}$$

$\therefore F \text{ is CVF.}$

$$\iint_G \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) dx dy = \int_{\partial G} \bar{F} - \int_{\partial G} \bar{F} - \int_{\partial G} \bar{F}$$

$$\underbrace{\int \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) dx dy}_0 = \int_{\partial G} \bar{F} - \int_{\partial G} \bar{F}$$



$$\therefore \int F_{\gamma_1} = \int F_{\gamma_2}$$

Parametric eqn is

$$(1-t)P_1 + tP_2$$

$(-1, 2)$ $\xrightarrow{(2, 3)}$

$$= \int_0^1 \langle F(L(t)), L'(t) \rangle dt$$

