

Indian Institute of Space Science and Technology

Thiruvananthapuram

MA 211 - Integral Transforms

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Tutorial-3

1. Determine the inverse Laplace transform of the following functions.

(a) $\frac{s}{s^2 - 2s + 2}$ (b) $\frac{e^{-2s}}{s^2 - s}$.

2. Use “Convolution” theorem to determine the inverse Laplace transform of the following functions.

(a) $\frac{1}{s^2(s+2)^2}$, (b) $\frac{1}{\sqrt{s}(s-1)}$, (use $\text{erf}f(t) = \frac{2}{\sqrt{\pi}} \int_0^t e^{-x^2} dx$)

3. Suppose the Laplace transform of a function $f : [0, \infty) \rightarrow \mathbb{R}$ is given by $L_T(f(x)) = \hat{f}(s)$.

(a) Show that $L_T\left(\int_0^x f(t) dt\right) = \frac{\hat{f}(s)}{s}$. [Hint: Let $g(x) = \int_0^x f(t) dt$ such that $\frac{dg}{dx} = f(x)$]

(b) Using this determine the inverse Laplace transform of $\frac{1}{s(s^2 + 1)}$.

4. Let $a > 0$. Consider the function $f : [0, \infty) \rightarrow \mathbb{R}$, defined by $f(x) = \begin{cases} x^2, & \text{for } 0 \leq x < a, \\ 0, & \text{for } x \geq a. \end{cases}$
Express f in terms of the Heaviside unit step functions and obtain the Laplace transform of it.

5. Consider the function $f : \mathbb{R} \rightarrow \mathbb{R}$, defined by $f(x) = \begin{cases} 0, & \text{for } x < 1, \\ -1, & \text{for } 1 \leq x < 3, \\ 1, & \text{for } 3 \leq x < 5, \\ -1, & \text{for } 5 \leq x < 6, \\ 0, & \text{for } x \geq 6. \end{cases}$

Express f in terms of the Heaviside unit step functions and obtain the Laplace transform of it.

6. Let $a > 0$. Determine the Laplace transform of the following functions.

(a) $f(x) = \begin{cases} x/a, & \text{for } 0 \leq x < a, \\ (2a - x)/a, & \text{for } a \leq x \leq 2a, \end{cases}$ such that $f(x + 2a) = f(x)$.

(b) $f(x) = \begin{cases} \frac{1-e^{3x}}{x}, & \text{for } x > 0 \\ 1, & \text{for } x = 0. \end{cases}$

7. Use Laplace transform to solve the following initial-value-problems.

(a) $\frac{d^2y}{dx^2} - 2\frac{dy}{dx} - 3y = xe^x$, $x > 0$ with $y(0) = 2$, $\frac{dy}{dx}(0) = 1$.

(b) $x\frac{d^2y}{dx^2} - \frac{dy}{dx} = -1$, $x > 0$ with $y(0) = 0$ and $\frac{dy}{dx}(0) = B$,
where B is a constant.

8. Use Laplace transform to solve the following initial-value-problems.

(a) $\frac{dy}{dx} - y = f(x)$, $x > 0$ with $y(0) = 0$, where $f(x) = \begin{cases} 0, & \text{for } 0 \leq x < 3, \\ (\sin x)^2, & \text{for } x \geq 3. \end{cases}$

(b) $\frac{d^2y}{dx^2} + y = f(x)$, $x > 0$ with $y(0) = 1$, $\frac{dy}{dx}(0) = 0$, where

i. $f(x) = \begin{cases} \sin x, & \text{for } 0 \leq x < \pi, \\ 0, & \text{for } \pi \leq x < 2\pi, \end{cases}$ such that $f(x + 2\pi) = f(x)$.

ii. $f(x) = (\sqrt{x} + 1)^3$.

9. Use “Laplace Convolution theorem” to solve

(a) $y(x) = x + \int_0^x e^{(x-t)}y(t) dt$, $x \geq 0$.

10. A system consists of two unit masses lying in a straight line on a smooth surface and conducted together to two fixed points by three springs. When a sinusoidal force is applied to the system, the displacements $y_1(x)$ and $y_2(x)$ of the respective masses from their equilibrium positions satisfy the equations

$$\begin{cases} \frac{d^2y_1}{dx^2} = y_2 - 2y_1 + \sin 2x, & \frac{d^2y_2}{dx^2} = -2y_2 + y_1. \end{cases}$$

Given that the system is initially at rest in the equilibrium position ($y_1 = y_2 = 0$). Use Laplace transform to solve the equations for $y_1(x)$ and $y_2(x)$.
