

**Cartesian.**  $d\mathbf{l} = dx \hat{\mathbf{x}} + dy \hat{\mathbf{y}} + dz \hat{\mathbf{z}}; \quad d\tau = dx \, dy \, dz$

*Gradient:*  $\nabla t = \frac{\partial t}{\partial x} \hat{\mathbf{x}} + \frac{\partial t}{\partial y} \hat{\mathbf{y}} + \frac{\partial t}{\partial z} \hat{\mathbf{z}}$

*Divergence:*  $\nabla \cdot \mathbf{v} = \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z}$

*Curl:*  $\nabla \times \mathbf{v} = \left( \frac{\partial v_z}{\partial y} - \frac{\partial v_y}{\partial z} \right) \hat{\mathbf{x}} + \left( \frac{\partial v_x}{\partial z} - \frac{\partial v_z}{\partial x} \right) \hat{\mathbf{y}} + \left( \frac{\partial v_y}{\partial x} - \frac{\partial v_x}{\partial y} \right) \hat{\mathbf{z}}$

*Laplacian:*  $\nabla^2 t = \frac{\partial^2 t}{\partial x^2} + \frac{\partial^2 t}{\partial y^2} + \frac{\partial^2 t}{\partial z^2}$

**Spherical.**  $d\mathbf{l} = dr \hat{\mathbf{r}} + r \, d\theta \hat{\boldsymbol{\theta}} + r \sin \theta \, d\phi \hat{\boldsymbol{\phi}}; \quad d\tau = r^2 \sin \theta \, dr \, d\theta \, d\phi$

*Gradient:*  $\nabla t = \frac{\partial t}{\partial r} \hat{\mathbf{r}} + \frac{1}{r} \frac{\partial t}{\partial \theta} \hat{\boldsymbol{\theta}} + \frac{1}{r \sin \theta} \frac{\partial t}{\partial \phi} \hat{\boldsymbol{\phi}}$

*Divergence:*  $\nabla \cdot \mathbf{v} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 v_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta \, v_\theta) + \frac{1}{r \sin \theta} \frac{\partial v_\phi}{\partial \phi}$

*Curl:*  $\nabla \times \mathbf{v} = \frac{1}{r \sin \theta} \left[ \frac{\partial}{\partial \theta} (\sin \theta \, v_\phi) - \frac{\partial v_\theta}{\partial \phi} \right] \hat{\mathbf{r}}$   
 $+ \frac{1}{r} \left[ \frac{1}{\sin \theta} \frac{\partial v_r}{\partial \phi} - \frac{\partial}{\partial r} (r v_\phi) \right] \hat{\boldsymbol{\theta}} + \frac{1}{r} \left[ \frac{\partial}{\partial r} (r v_\theta) - \frac{\partial v_r}{\partial \theta} \right] \hat{\boldsymbol{\phi}}$

*Laplacian:*  $\nabla^2 t = \frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial t}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial t}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 t}{\partial \phi^2}$

**Cylindrical.**  $d\mathbf{l} = ds \hat{\mathbf{s}} + s \, d\phi \hat{\boldsymbol{\phi}} + dz \hat{\mathbf{z}}; \quad d\tau = s \, ds \, d\phi \, dz$

*Gradient:*  $\nabla t = \frac{\partial t}{\partial s} \hat{\mathbf{s}} + \frac{1}{s} \frac{\partial t}{\partial \phi} \hat{\boldsymbol{\phi}} + \frac{\partial t}{\partial z} \hat{\mathbf{z}}$

*Divergence:*  $\nabla \cdot \mathbf{v} = \frac{1}{s} \frac{\partial}{\partial s} (s v_s) + \frac{1}{s} \frac{\partial v_\phi}{\partial \phi} + \frac{\partial v_z}{\partial z}$

*Curl:*  $\nabla \times \mathbf{v} = \left[ \frac{1}{s} \frac{\partial v_z}{\partial \phi} - \frac{\partial v_\phi}{\partial z} \right] \hat{\mathbf{s}} + \left[ \frac{\partial v_s}{\partial z} - \frac{\partial v_z}{\partial s} \right] \hat{\boldsymbol{\phi}} + \frac{1}{s} \left[ \frac{\partial}{\partial s} (s v_\phi) - \frac{\partial v_s}{\partial \phi} \right] \hat{\mathbf{z}}$

*Laplacian:*  $\nabla^2 t = \frac{1}{s} \frac{\partial}{\partial s} \left( s \frac{\partial t}{\partial s} \right) + \frac{1}{s^2} \frac{\partial^2 t}{\partial \phi^2} + \frac{\partial^2 t}{\partial z^2}$

## Triple Products

(1)  $\mathbf{A} \cdot (\mathbf{B} \times \mathbf{C}) = \mathbf{B} \cdot (\mathbf{C} \times \mathbf{A}) = \mathbf{C} \cdot (\mathbf{A} \times \mathbf{B})$

(2)  $\mathbf{A} \times (\mathbf{B} \times \mathbf{C}) = \mathbf{B}(\mathbf{A} \cdot \mathbf{C}) - \mathbf{C}(\mathbf{A} \cdot \mathbf{B})$

## Product Rules

(3)  $\nabla(fg) = f(\nabla g) + g(\nabla f)$

(4)  $\nabla(\mathbf{A} \cdot \mathbf{B}) = \mathbf{A} \times (\nabla \times \mathbf{B}) + \mathbf{B} \times (\nabla \times \mathbf{A}) + (\mathbf{A} \cdot \nabla)\mathbf{B} + (\mathbf{B} \cdot \nabla)\mathbf{A}$

(5)  $\nabla \cdot (f\mathbf{A}) = f(\nabla \cdot \mathbf{A}) + \mathbf{A} \cdot (\nabla f)$

(6)  $\nabla \cdot (\mathbf{A} \times \mathbf{B}) = \mathbf{B} \cdot (\nabla \times \mathbf{A}) - \mathbf{A} \cdot (\nabla \times \mathbf{B})$

(7)  $\nabla \times (f\mathbf{A}) = f(\nabla \times \mathbf{A}) - \mathbf{A} \times (\nabla f)$

(8)  $\nabla \times (\mathbf{A} \times \mathbf{B}) = (\mathbf{B} \cdot \nabla)\mathbf{A} - (\mathbf{A} \cdot \nabla)\mathbf{B} + \mathbf{A}(\nabla \cdot \mathbf{B}) - \mathbf{B}(\nabla \cdot \mathbf{A})$

## Second Derivatives

(9)  $\nabla \cdot (\nabla \times \mathbf{A}) = 0$

(10)  $\nabla \times (\nabla f) = 0$

(11)  $\nabla \times (\nabla \times \mathbf{A}) = \nabla(\nabla \cdot \mathbf{A}) - \nabla^2 \mathbf{A}$

**Gradient Theorem:**  $\int_{\mathbf{a}}^{\mathbf{b}} (\nabla f) \cdot d\mathbf{l} = f(\mathbf{b}) - f(\mathbf{a})$

**Divergence Theorem:**  $\int (\nabla \cdot \mathbf{A}) \, d\tau = \oint \mathbf{A} \cdot d\mathbf{a}$

**Curl Theorem:**  $\int (\nabla \times \mathbf{A}) \cdot d\mathbf{a} = \oint \mathbf{A} \cdot d\mathbf{l}$

## Spherical

$$\begin{cases} x = r \sin \theta \cos \phi \\ y = r \sin \theta \sin \phi \\ z = r \cos \theta \end{cases} \quad \begin{cases} \hat{\mathbf{x}} = \sin \theta \cos \phi \hat{\mathbf{r}} + \cos \theta \cos \phi \hat{\boldsymbol{\theta}} - \sin \phi \hat{\boldsymbol{\phi}} \\ \hat{\mathbf{y}} = \sin \theta \sin \phi \hat{\mathbf{r}} + \cos \theta \sin \phi \hat{\boldsymbol{\theta}} + \cos \phi \hat{\boldsymbol{\phi}} \\ \hat{\mathbf{z}} = \cos \theta \hat{\mathbf{r}} - \sin \theta \hat{\boldsymbol{\theta}} \end{cases}$$

$$\begin{cases} r = \sqrt{x^2 + y^2 + z^2} \\ \theta = \tan^{-1} \left( \sqrt{x^2 + y^2} / z \right) \\ \phi = \tan^{-1} (y/x) \end{cases} \quad \begin{cases} \hat{\mathbf{r}} = \sin \theta \cos \phi \hat{\mathbf{x}} + \sin \theta \sin \phi \hat{\mathbf{y}} + \cos \theta \hat{\mathbf{z}} \\ \hat{\boldsymbol{\theta}} = \cos \theta \cos \phi \hat{\mathbf{x}} + \cos \theta \sin \phi \hat{\mathbf{y}} - \sin \theta \hat{\mathbf{z}} \\ \hat{\boldsymbol{\phi}} = -\sin \phi \hat{\mathbf{x}} + \cos \phi \hat{\mathbf{y}} \end{cases}$$

## Cylindrical

$$\begin{cases} x = s \cos \phi \\ y = s \sin \phi \\ z = z \end{cases} \quad \begin{cases} \hat{\mathbf{x}} = \cos \phi \hat{\mathbf{s}} - \sin \phi \hat{\boldsymbol{\phi}} \\ \hat{\mathbf{y}} = \sin \phi \hat{\mathbf{s}} + \cos \phi \hat{\boldsymbol{\phi}} \\ \hat{\mathbf{z}} = \hat{\mathbf{z}} \end{cases}$$

$$\begin{cases} s = \sqrt{x^2 + y^2} \\ \phi = \tan^{-1} (y/x) \\ z = z \end{cases} \quad \begin{cases} \hat{\mathbf{s}} = \cos \phi \hat{\mathbf{x}} + \sin \phi \hat{\mathbf{y}} \\ \hat{\boldsymbol{\phi}} = -\sin \phi \hat{\mathbf{x}} + \cos \phi \hat{\mathbf{y}} \\ \hat{\mathbf{z}} = \hat{\mathbf{z}} \end{cases}$$