

Marks: 15

Time: 45 Mins

Each question carries 1 mark. For each wrong answer 0.25 mark will be deducted. Put a \checkmark for the correct answer. All your rough work should be in the provided sheet.

1. If $X(s) = L[x(t)] = \frac{k}{(s+1)(s^2+4)}$ then the final value $x(\infty)$

- -0.25
- A. $k/4$.
 - ☒ B. zero.
 - C. infinite.
 - D. undefined.

2. The inverse Laplace transform of the function $\frac{s+5}{(s+1)(s+3)}$

- \checkmark
- ☒ A. $2e^{-t} - e^{-3t}$
 - B. $2e^{-t} + e^{-3t}$
 - C. $e^{-t} - 2e^{-3t}$
 - D. $e^{-t} + 2e^{-3t}$

3. A LTI system has a impulse response $h(t) = e^{2t}$, for $t > 0$. If initial conditions are zero and the input $x(t) = e^{-3t}$, the output for $t > 0$ is

- \checkmark
- ☒ A. None of these
 - B. $e^{3t} - e^{2t}$
 - C. e^{5t}
 - D. $e^{3t} + e^{2t}$

4. The impulse response of a system is $h(t) = tu(t)$. For an input $u(t-1)$, the out output is

- \checkmark
- A. $\frac{t^2}{2}u(t)$
 - B. $\frac{t(t-1)}{2}u(t-1)$
 - ☒ C. $\frac{(t-1)^2}{2}u(t-1)$
 - D. $\frac{t^2-1}{2}u(t-1)$

5. The input $x(t)$ and output $y(t)$ of an LTI system are related by the differential equation $\frac{d^2y(t)}{dt^2} - \frac{dy(t)}{dt} - 6y(t) = x(t)$. If the system is neither causal nor stable, the impulse response $h(t)$ of the system is

- \checkmark
- A. $\frac{1}{5}e^{3t}u(-t) + \frac{1}{5}e^{-2t}u(-t)$
 - ☒ B. $-\frac{1}{5}e^{3t}u(-t) + \frac{1}{5}e^{-2t}u(-t)$
 - C. $\frac{1}{5}e^{3t}u(-t) - \frac{1}{5}e^{-3t}u(-t)$
 - D. $-\frac{1}{5}e^{3t}u(-t) - \frac{1}{5}e^{-2t}u(-t)$

6. The Laplace transform of a function $x(t) = \begin{cases} 1 & \text{if } a \leq t \leq b \\ 0 & \text{otherwise} \end{cases}$
where $a, b > 0$

~~A~~ $X(s) = \frac{e^{-as} - e^{-bs}}{s}$

B. $X(s) = \frac{e^{(a-b)}}{s}$

☒ C. $X(s) = \frac{e^{-as} - e^{-bs}}{s}$

D. $X(s) = \frac{a-b}{s^2}$

7. If $X(s) = \frac{2(s+1)}{s^2+4s+7}$ then the initial and final values of $x(t)$ are respectively

A. 0, 2

☒ B. 2, 0

C. 0, 2/7

D. 2/7, 0

8. A sequence $x(n)$ with z- transform $X(z) = z^4 + z^2 - 2z + 2 - 3z^{-4}$ is applied as an input to a linear time invariant system with impulse response $h(n) = 2\delta(n-3)$. The output at $n = 4$ is

A. -6

B. 2

☒ C. zero

D. -4

9. Consider a signal $x(t) = e^{-7t}u(t) + e^{-\beta t}u(t)$ and its Laplace transform is denoted by $X(s)$. The ROC of $X(s)$ is $\text{Re}\{s\} > -5$. Find the value of β ?

A. 7

☒ B. 5

C. -5

D. none of the above

10. The z- transform of a signal is given by $X(z) = \frac{1}{(1-2z^{-1})^2}$ then ROC $|z| > 2$, then $x[2]$ is

A. 0

☒ B. 1

C. 12

D. 4

11. A causal LTI system is given by the transfer function $H(z) = \frac{2z^2+3}{(z+\frac{1}{3})(z-\frac{1}{3})}$ which of the following statement is/are true

A. The system is stable

B. Final value of the impulse response is 0

☒ C. The initial value of the impulse response is 2

☒ D. all the above

12. A causal LTI system is described by the difference equation $2y[n] = \alpha y[n-2] - 2x[n] + \beta x[n-1]$. The system is stable only if

A. $|\alpha| = 2, |\beta| < 2$

B. $|\alpha| > 2, |\beta| > 2$

☒ C. $|\alpha| < 2$, any value of β

D. $|\beta| < 2$, any value of α

13. The ROC of the Z-transform of a sequence $(5/6)^n u[n] - (6/5)^n u[-n-1]$

A. $|z| < 5/6$

B. $|z| > 5/6$

☒ C. $5/6 < |z| < 6/5$

D. $6/5 < |z| < \infty$

14. A discrete time signal $x[n] = \delta[n-3] + 2\delta[n-5]$ has z transform $X(z)$.

If $Y(z) = X(-z)$ is the z transform of another signal $y[n]$, then

A. $y[n] = x[n]$

☒ B. $y[n] = x[-n]$

☒ C. $y[n] = -x[n]$

D. $y[n] = -x[-n]$

15. The ROC of the given DT signal $x[n] = (2)^{|n|}$, $-\infty < n < \infty$ is $1/2 < |z| < 2$

Rough Work

$\lim_{n \rightarrow \infty} h(n) = \lim_{z \rightarrow \infty} H(z)$

$\frac{2s(s+1)}{s^2+4s+7}$

$\frac{2(1+\frac{1}{2})}{1+\frac{1}{2}+\frac{1}{2}}$

$\lim_{x \rightarrow \infty} x(t) = \lim_{s \rightarrow 0} sX(s)$

$\frac{A}{s+1} + \frac{B}{s+3} = \frac{s+5}{(s+1)(s+3)}$

$A = \frac{4}{2} = 2$

$B = \frac{2}{-2} = -1$

$x(t) = \begin{cases} 1, & [a, b] \\ 0, & \text{elsewhere} \end{cases}$

$= u(t-a) - u(t-b)$

$\frac{e^{-as} - e^{-bs}}{s}$

$X(z) = z^{-3} + 2z^{-5}$

$Y(z) = X(-z) = -z^{-3} - 2z^{-5}$

$y(n) = -\delta(n-3) - 2\delta(n-5)$

$y(n) = -x(n)$

$2Y(z) = \alpha z^{-2} Y(z) - 2X(z) + \beta z^{-1} X(z)$

$Y(z) \{2 - \alpha z^{-2}\} = X(z) \{\beta z^{-1} - 2\}$

$H(z) = \frac{\beta z^{-1} - 2}{2 - \alpha z^{-2}}$

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$2 - \frac{\alpha}{z^2} = 0 \Rightarrow z^2 = \frac{\alpha}{2} \Rightarrow z = \pm \sqrt{\frac{\alpha}{2}}$

$\lim_{n \rightarrow \infty} \frac{1}{z^n} = \lim_{z \rightarrow \infty} \frac{1}{z^n} = 0$

$\frac{2}{(s+1)} + \frac{-1}{(s+3)}$

$2e^{-t}u(t) - e^{-3t}u(t)$

$g = x * h$

$Y = XWH(s) = \left(\frac{1}{s-2}\right)\left(\frac{1}{s+3}\right) = \frac{1}{(s-2)(s+3)}$

$\frac{e^{-2t}}{s-2} - \frac{e^{-3t}}{s+3}$

$\frac{1}{s-2} - \frac{1}{s+3}$

$\frac{1}{s-2} - \frac{1}{s+3}$

$\frac{1}{s-2} - \frac{1}{s+3}$

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$\frac{1}{s-2} - \frac{1}{s+3}$