

संचारसंविधा २

COMMUNICATION SYSTEM I

AV314: Communication Systems I \Rightarrow Prerequisites:



AV324: Communication Systems II



Communication networks

wireless networks

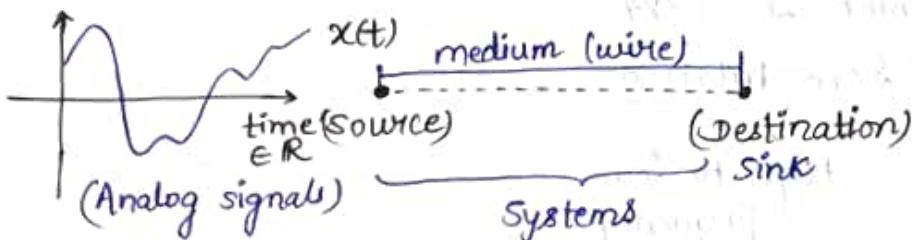
Signals and Systems

↳ Fourier series & Transform

↳ LTI

↳ Convolution

Communication Systems

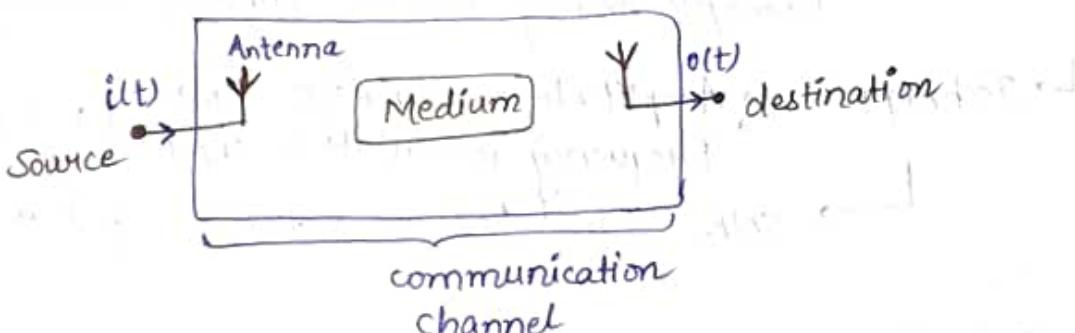


Examples:

voice

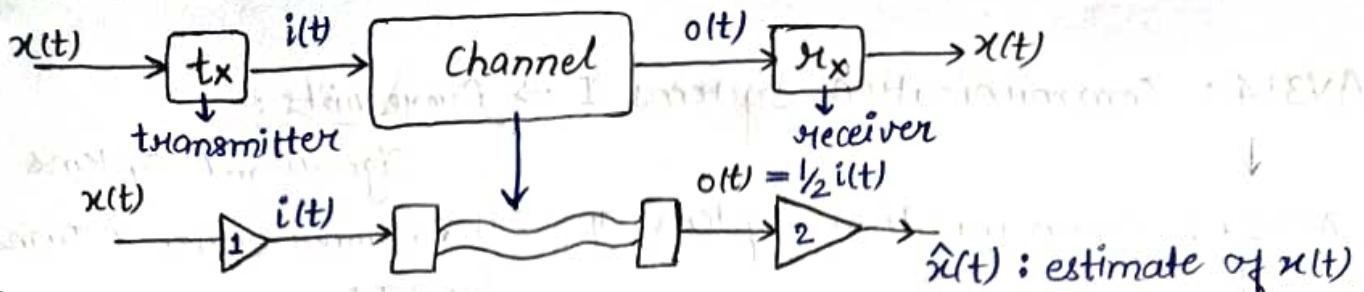
sensor data

Implicit assumption: voltage signals



↳ A system which takes a signal $i(t)$ as i/p and gives $o(t)$ as output, which is some function of $i(t)$ [ideally should be same as $i(t)$].

Communication System Problem: To take the signal $i(t)$ and give $o(t)$ which is somehow related to $i(t)$ so that $i(t)$ can be retrieved.



Problems to Address:

Frequency : f_c

for 1 KHz signal :

$$\lambda = \frac{3 \times 10^8}{1 \times 10^3} = 300 \text{ Km}$$

Antenna size $\sim \lambda/4$

Modulation & Demodulation

↓
Low to high frequency High to low frequency

→ Noise + other distortions

Aim of course : Design wireless communication system to transfer analog signals. [Analog communication system]

↳ Techniques: ↳ Amplitude modulation (AM)
 ↳ Frequency modulation (FM) } For Modem
 ↳ SNR (Signal to Noise Ratio) } For noises

Course Evaluation:

Internals: class tests

Programming/
simulation assignments } MATLAB

Problems, etc.

Resources:

Textbooks:

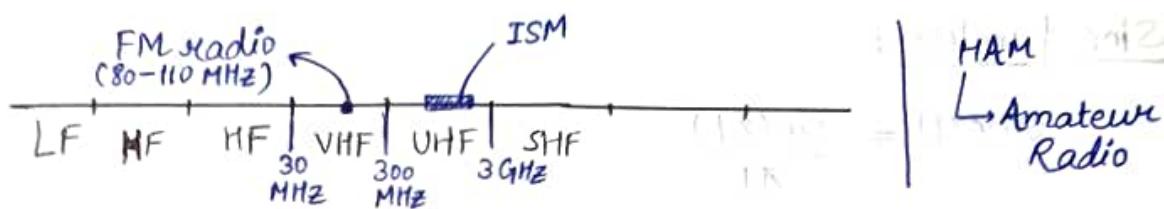
- ① Upamanyu Madhow - Introduction to Comm. Systems, 2014 (Assignments)
- ② Simon Haykin - Communication Systems, 4th ed.



$$\text{error}(x(t), \hat{x}(t)) = 0.01$$

Given the channel, design Rx and Tx such that
 $\text{error}(x(t), \hat{x}(t)) < \epsilon$

Spectrum (Wireless Spectrum)



Band

wifi:

channel: Range of frequencies in which signals can be transmitted
 \hookrightarrow $i(t)$ should fall within this range

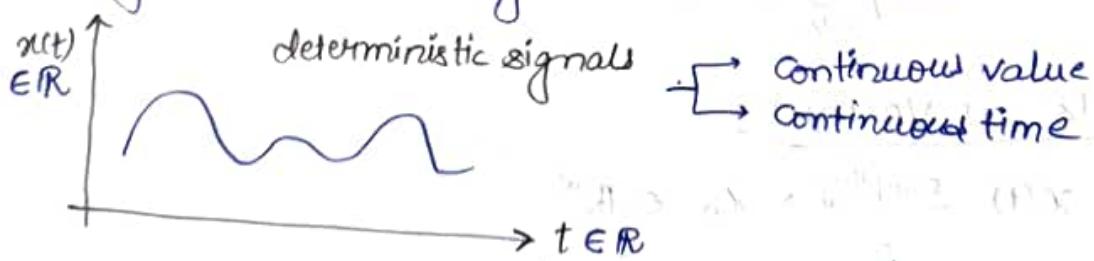
The diagram shows a horizontal double-headed arrow labeled "2.4 GHz (divided into channels)". Above it, a smaller double-headed arrow is labeled "20 MHz (earlier)". Below the main arrow, there are four small boxes representing channels.

SIGNALS & SYSTEMS REVIEW

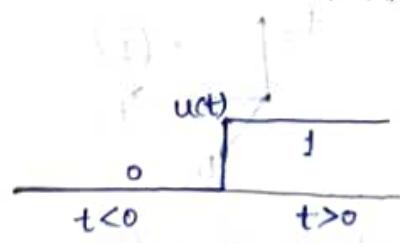
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Signal: Deterministic (one value at a time) function of time.

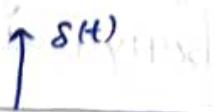
Random signal: Value changes each time we see it.



Step function:



Delta function:



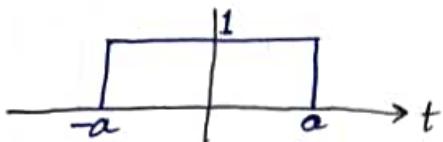
$$\int_{-\infty}^{\infty} \delta(t) dt = 1$$

$$\int_{-\infty}^{+\infty} \delta(t) dt = 0$$

Boxcar function / Indicator function:

$$I_A = \begin{cases} 1, & \text{if } A \text{ is true;} \\ 0, & \text{if } A \text{ is false.} \end{cases}$$

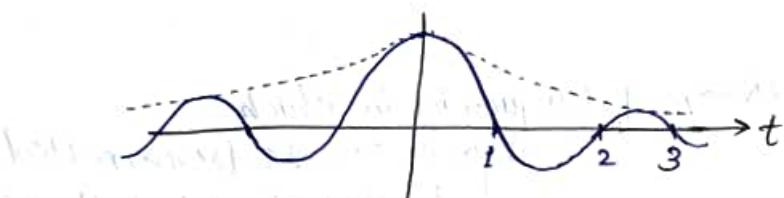
$$I_{\{t \in [a, b]\}}$$



Sinc function:

starting value

$$\text{sinc}(t) = \frac{\sin(\pi t)}{\pi t}$$



Energy of a signal:

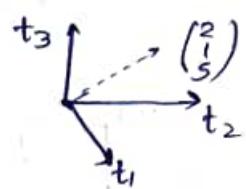
$$E_x = \int_{-\infty}^{\infty} |x(t)|^2 dt$$

Power of a signal:

$$P_x = \frac{1}{T} \int_{-T/2}^{T/2} |x(t)|^2 dt$$

Signals as Vectors:

$$x(t) \xrightarrow{\text{sampling}} x_n \in \mathbb{R}^\alpha$$



Dot product:

$x(t), y(t)$: continuous-time signals

$$\langle x(t), y(t) \rangle = \int_{-\infty}^{\infty} x(t)y(t) dt \rightarrow \text{inner-product}$$

if $= 0$, then $x(t)$ and $y(t)$ are orthogonal.

→ Two signals are similar (one is replica of the other), if both lie along the same line.

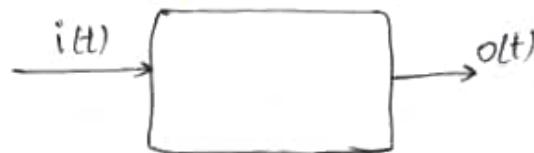
↪ can be checked by using dot-product.

$$\int_{-\infty}^{\infty} x(t) y(t+\tau) dt \rightarrow \text{cross-correlation}$$

(τ: time-lag)

System

↪ Takes a time-signal, processes it, and produces a time-signal.



Linear: $o(t) = 5i(t)$

Non-linear: $o(t) = 5i(t) + 5$
 $= i^2(t)$

Linear System:

Homogeneity: $o(t) \leftarrow i(t)$
 $\alpha o(t) \leftarrow \alpha i(t), \alpha \in \mathbb{R}$

Superposition: $i_1 \rightarrow o_1, i_2 \rightarrow o_2$
 $i_1 + i_2 \rightarrow o_1 + o_2$

Time invariance:

$$i(t) \rightarrow o(t)$$

$$i(t-\tau) \rightarrow o(t-\tau)$$

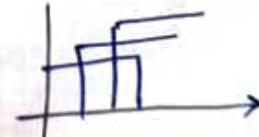
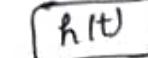
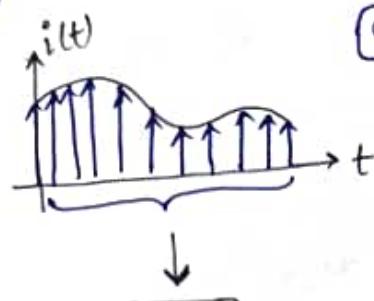
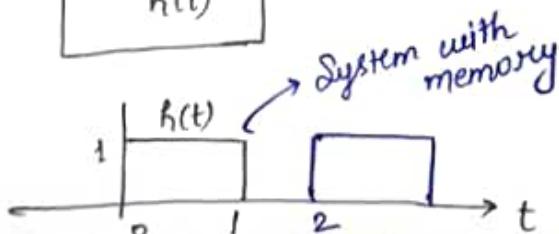
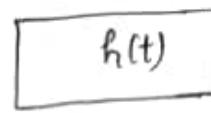
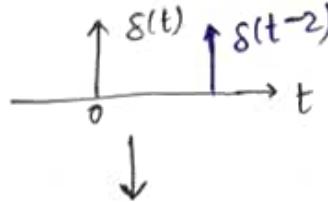
LTI Systems

↪ Characterised by impulse response, $h(t)$.

Eg.

$$\delta(t) \rightarrow \boxed{\text{LTI}} \rightarrow h(t)$$

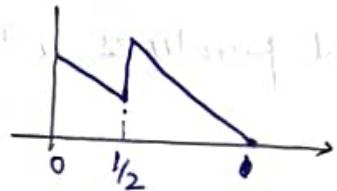
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Convolution:

$$o(t) = \int i(\tau) \cdot h(t-\tau) d\tau = i(t) * h(t)$$

$$= \int i(t-\tau) \cdot h(\tau) d\tau$$



Eg.

$$x(t) \rightarrow \boxed{\quad} \rightarrow y(t)$$

$$y(t) = \int_{-\infty}^t e^{u-t} x(u) du$$

LTI?

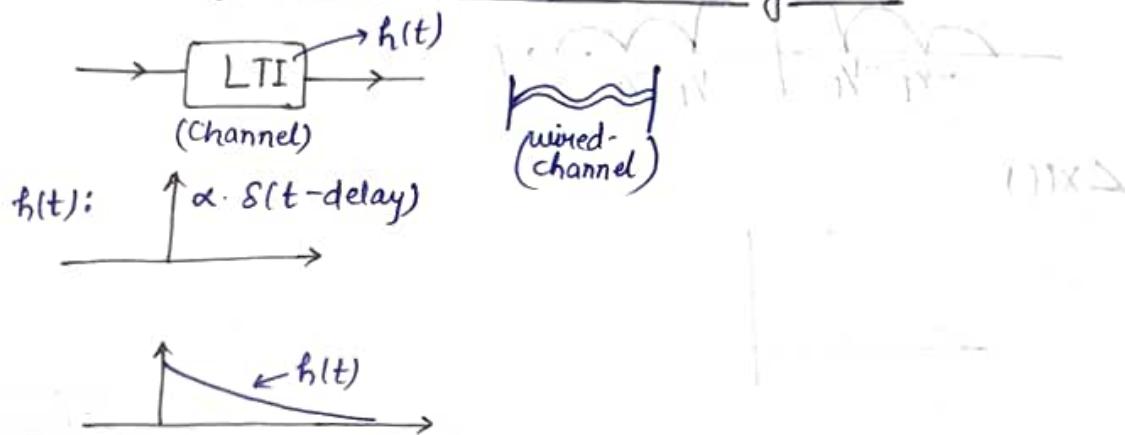
$h(t)$?



Eg.

$$\begin{aligned}
 & \text{Figure showing two rectangular pulses: } I_{[t, t+1]} \text{ and } I_{[t-1, t]} \\
 & I_{[t, t+1]} * I_{[t-1, t]} = [u(t+1) - u(t-1)] * [u(t+1) - u(t-1)] \\
 & = \int_{-\infty}^{\infty} [u(\tau+1) - u(\tau-1)] [u(t-\tau+1) - u(t-\tau-1)] d\tau \\
 & = \int_{-\infty}^{\infty} u(\tau+1) u(t-\tau+1) d\tau - \int_{-\infty}^{\infty} u(\tau+1) u(t-\tau-1) d\tau - \int_{-\infty}^{\infty} u(\tau-1) u(t-\tau+1) d\tau + \int_{-\infty}^{\infty} u(\tau-1) u(t-\tau-1) d\tau \\
 & \quad \left(\int_{-1}^{t+1} d\tau - \int_{-1}^{t-1} d\tau - \int_{t+1}^{t-1} d\tau + \int_{t+1}^{t-1} d\tau, t > 2, t < -2 \right) \\
 & = (u(t+2) - u(t)) (u(t) - u(t-2)) = 0, t > 2, t < -2 \\
 & \quad | \quad 2-t, 0 \leq t \leq 2 \quad | \quad t+2, -2 \leq t < 0.
 \end{aligned}$$

LTI Models for Communication Subsystems



Fourier Transform

$$X(f) = \int_{-\infty}^{\infty} x(t) e^{-j2\pi ft} dt$$

$$x(t) = \int_{-\infty}^{\infty} X(f) e^{j2\pi ft} df$$

$$\begin{aligned}
 e^{j2\pi f_0 t} &\rightarrow h(t) \rightarrow H(f) e^{j2\pi f_0 t} = \int_{-\infty}^{\infty} e^{j2\pi f_0 (t-\tau)} h(\tau) d\tau \\
 h(t) &\leftrightarrow H(f)
 \end{aligned}$$

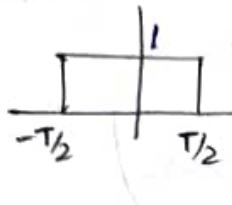
$$\begin{aligned}
 x(t) &\rightarrow h(t) \rightarrow y(t) \\
 x(f) &\downarrow \quad \downarrow H(f) \quad \downarrow \\
 y(f) &= H(f) X(f)
 \end{aligned}$$

FT of Some functions :

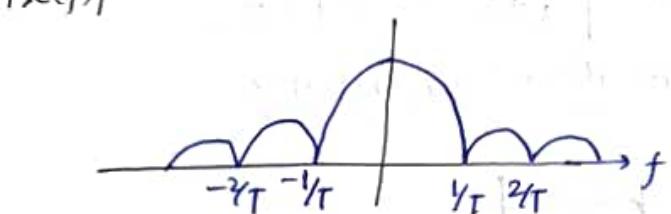
① $x(t) = \delta(t)$

$$X(f) = 1$$

② $x(t) = I_{[-T_2, T_2]}(t)$



$$X(f) = T \operatorname{sinc}(fT) = \frac{T \sin(\pi fT)}{\pi fT} = \int_{-T/2}^{T/2} 1 \cdot e^{j2\pi ft} dt = \frac{1}{2j\pi f} (e^{j\pi fT} - e^{-j\pi fT})$$



$\angle X(f)$



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$v(t) = I_{[0, T]} - I_{[T, 2T]}$

$$\downarrow$$

$$v(f) = e^{-j2\pi f T/2} T \operatorname{sinc}(fT) - e^{-j2\pi f 3T/2} T \operatorname{sinc}(fT).$$

Fourier Transform Properties:

$$x(t) \xleftrightarrow{F} X(f)$$

- $x(t - \tau) \xleftrightarrow{F} e^{-j2\pi f \tau} X(f)$

$$y(t) \xleftrightarrow{F} Y(f)$$

- $\alpha x(t) + \beta y(t) \xleftrightarrow{F} \alpha X(f) + \beta Y(f)$

- $e^{j2\pi f_0 t} x(t) \xleftrightarrow{F} X(f - f_0)$

complex exponential

• Related property:

$$\cos(2\pi f_0 t) x(t) \xleftrightarrow{F} \frac{1}{2} X(f+f_0) + \frac{1}{2} X(f-f_0) \quad [\text{Modulation property}]$$

$$x(t) \xleftrightarrow{F} X^*(f)$$

$$x(t) * y(t) \xleftrightarrow{F} X(f) Y(f) \quad [\text{convolution property}]$$

Proof:

$$\begin{aligned} & \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} x(\tau) y(t-\tau) d\tau \cdot e^{-j2\pi ft} dt \\ &= \int_{-\infty}^{\infty} x(\tau) \left(\int_{-\infty}^{\infty} y(t-\tau) e^{-j2\pi ft} dt \right) d\tau \\ & [t-\tau=u \Rightarrow dt=du] \\ &= \int_{-\infty}^{\infty} x(\tau) \left(\int_{-\infty}^{\infty} y(u) e^{-j\omega u} du \right) e^{-j\omega \tau} d\tau \\ &= \left[(x(\tau) e^{-j\omega \tau} d\tau) (Y(f)) \right] = X(f) Y(f) \end{aligned}$$

e.g.



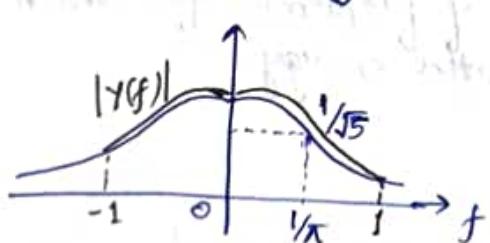
$$h(t) = \int_{-\infty}^t e^{t-u} x(u) du$$

$$y(t) = \int_{-\infty}^t e^{t-u} x(u) du$$

$$h(t) = \int_{-\infty}^t e^{t-u} \delta(u) du$$

$$\begin{aligned} H(f) &= \int_{-\infty}^{\infty} e^{-jt} e^{-j2\pi ft} dt \\ &= \frac{1}{1+j2\pi f} \end{aligned}$$

$$|H(f)| = \frac{1}{\sqrt{1+4\pi^2 f^2}}$$



$$x(t) = 2 \sin(2t)$$

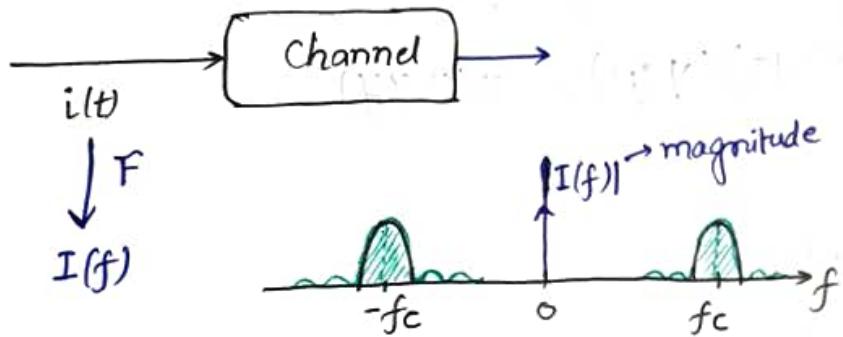
$$\frac{-2}{2} = -T_2 \quad T_2 = \frac{1}{2}$$

$$\int_{-1}^1 \frac{1}{1+j2f} dt \rightarrow \frac{1}{1+j2f} \rightarrow 2 \sin(f \cdot 2)$$

* $x(t) \longleftrightarrow x(-f)$ [Duality property]

* $\int x(t)^2 dt = \int_{-\infty}^{\infty} |x(f)|^2 df$

Bandwidth (BW) → Baseband (BB)
Passband (PB)



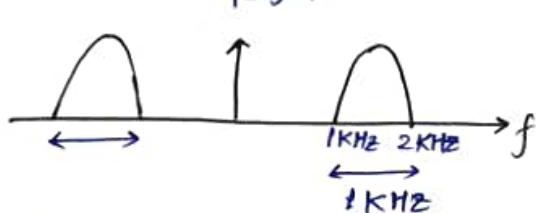
→ double-sided spectrum

→ energy spectral density

$$\int_{-\infty}^{\infty} |I(f)|^2 dt$$

Energy Spectral Density

ESD:



Bandwidth (BW): The range of frequencies for which the signal has non-negative energy.

One-sided BW is 1 kHz.

Two-sided BW is 2 kHz.

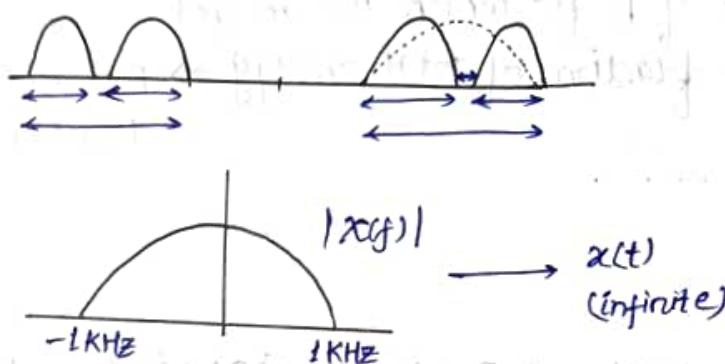
$\rightarrow i(t) \in \mathbb{R}$

$$I(-f) = I^*(f)$$

$$|I(-f)| = |I^*(f)| = |I(f)|$$

$e^{-j2\pi(1k)t} + \frac{1}{2}e^{+j2\pi(0.5k)t}$
 not real signal

Two-sided B/W = Total length of frequency intervals in which $|S(f)| > 0$.



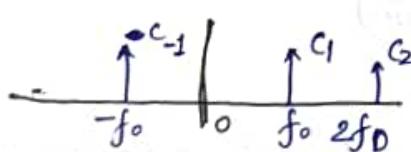
Suppose we had $x(t) \in [-T_2, T_2]$

$$x(t) = \begin{cases} \sin(2\pi f_0 t) & \text{for } t \in [-T_2, T_2] \\ 0, & \text{otherwise.} \end{cases}$$

Digression:

Periodic signal $p(t)$ with period $T_0 = \frac{1}{f_0}$.

$$p(t) = \sum_{-\infty}^{\infty} c_k \cdot e^{j2\pi k f_0 t}$$



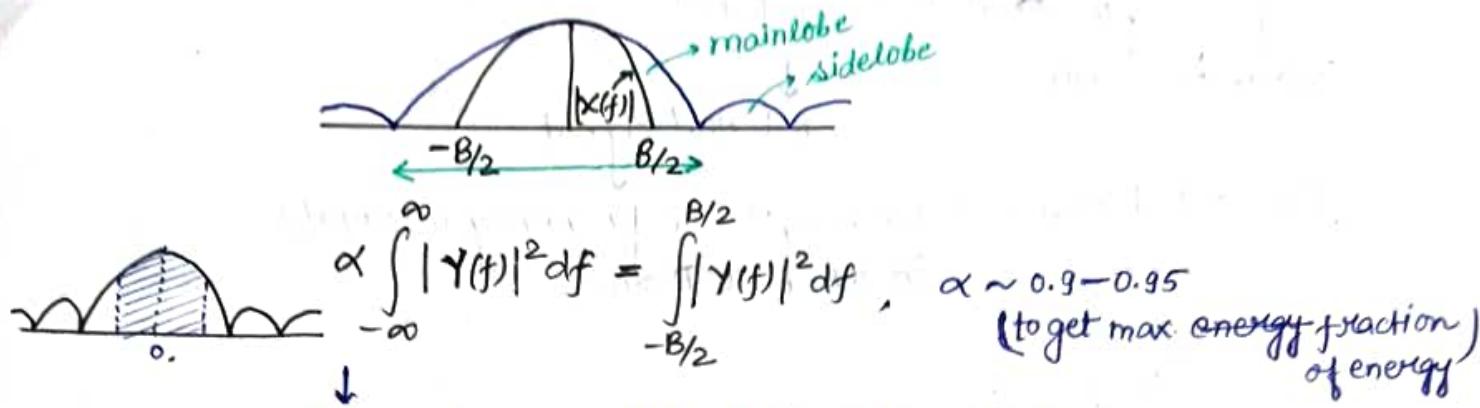
$x(t) = \underbrace{\sin(2\pi f_0 t)}_{T \sin(f_0 t)} \cdot \underbrace{I_{[-T_2, T_2]}}_{\neq t}$



\Rightarrow Infinite Bandwidth $\rightarrow X$

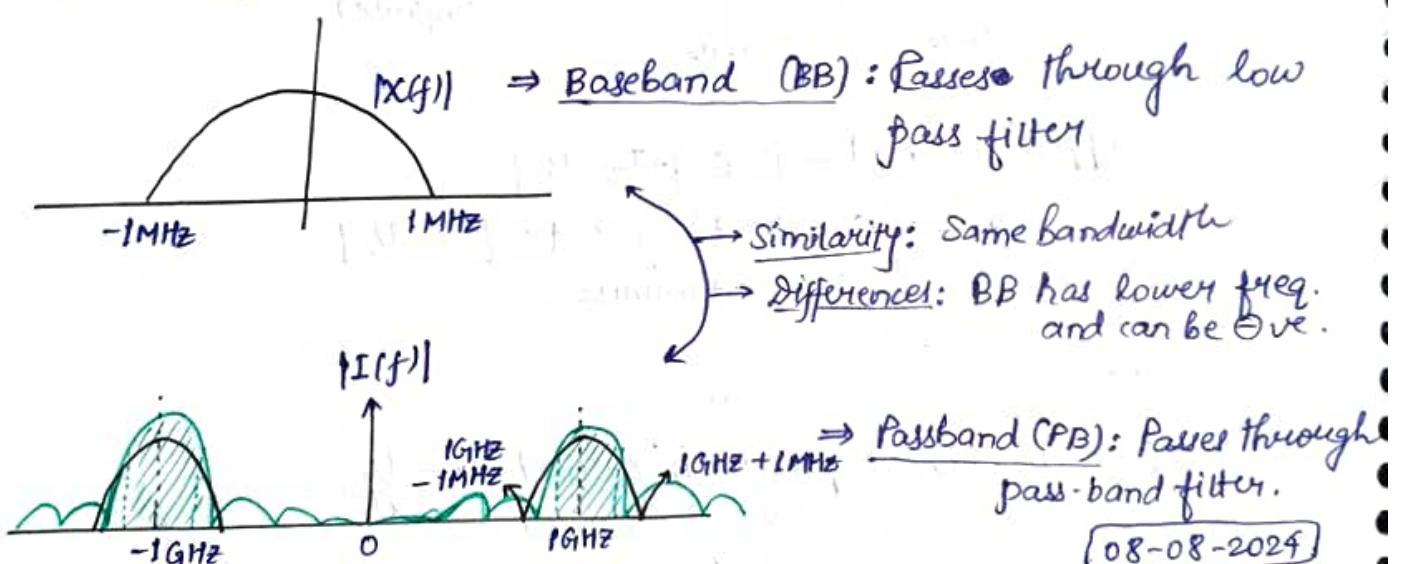
Energy containment

BW:



The value of B for which we can get maximum fraction of total energy \Rightarrow B : energy contained Bandwidth

$$x(t) \rightarrow X(f)$$

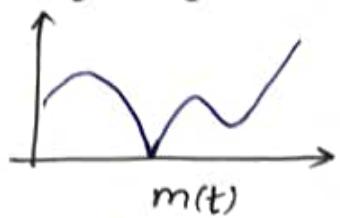


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$x(t)$ is real (\because symmetric)

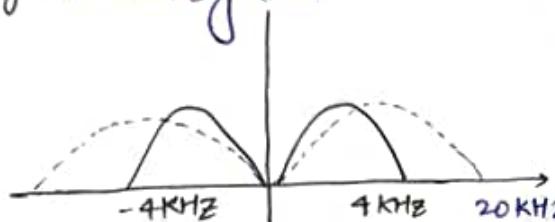
$$\int_{f_1}^{f_2} |X(f)|^2 df = \alpha \int_0^{\infty} |X(f)|^2 df : \text{Range of frequencies in which } \alpha\% \text{ of energy lies.}$$

→ Message signal



↪ BB signal (b/c freq. is low relative to freq. at which it is transmitted)

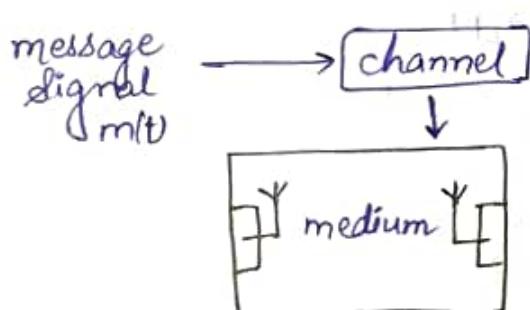
e.g. voice signals



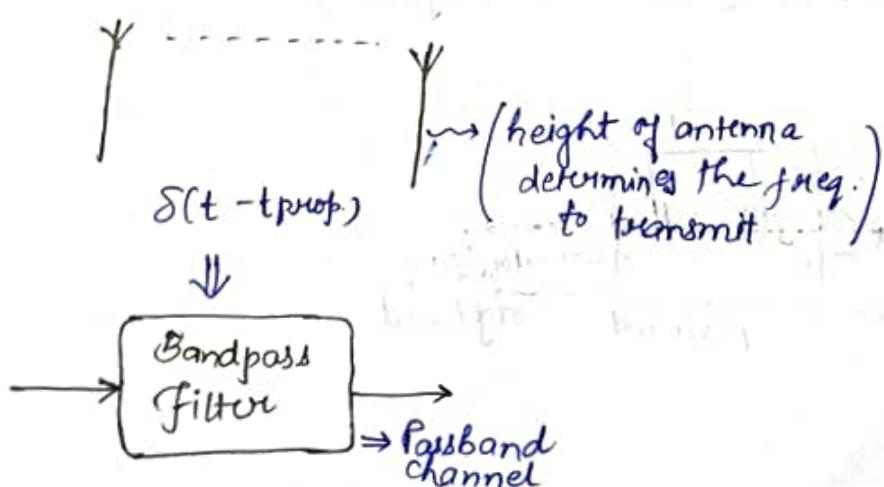
Channel

$$f(\text{ilt}) = o(t)$$

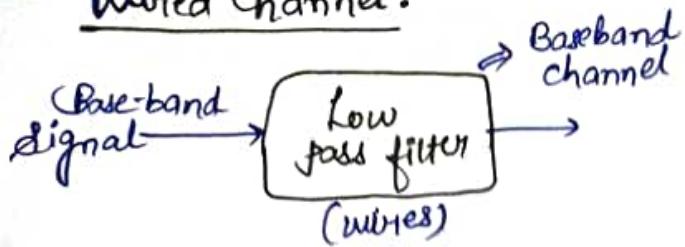
Where do we get $f(\cdot)$ from?
— medium



e.g.

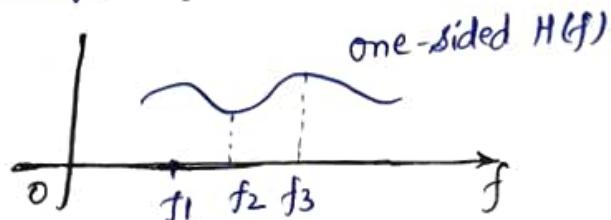


Mixed channel:

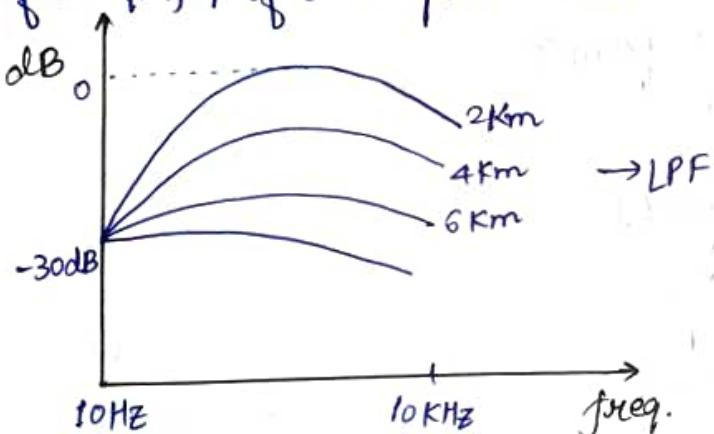


Channel as LTI filters

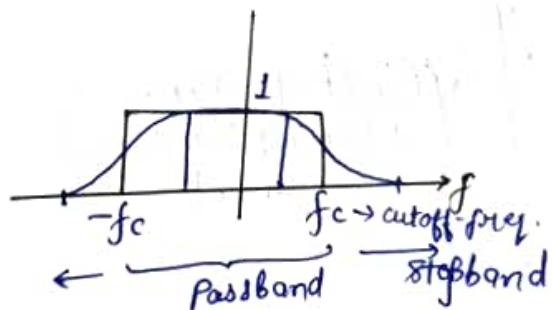
Frequency response, $H(f)$
Impulse response, $h(t)$

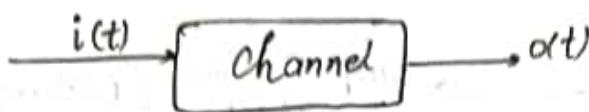


e.g. of $|H(f)|$ of a telephone cable.



Ideal LPF: (Brickwall response)





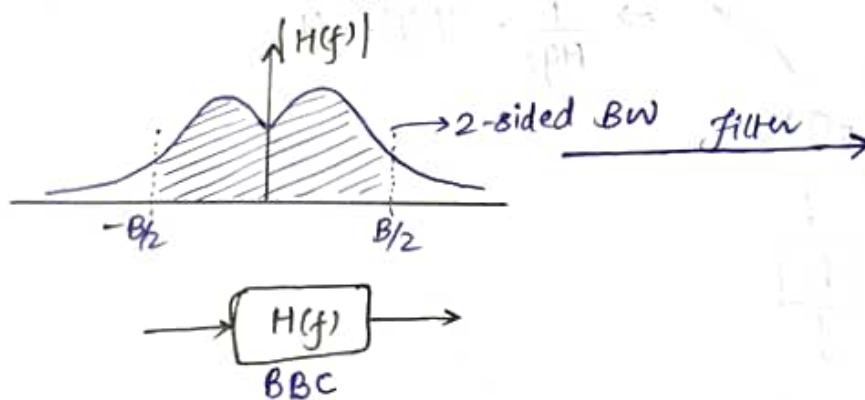
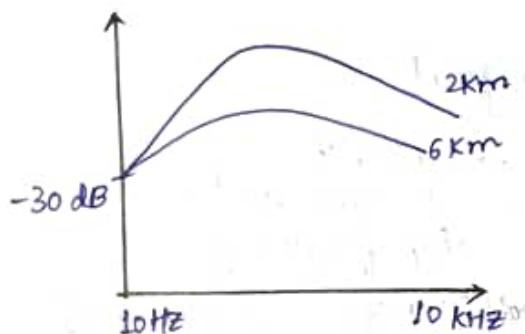
First order models for channels filters (LTI)

Baseband Passband

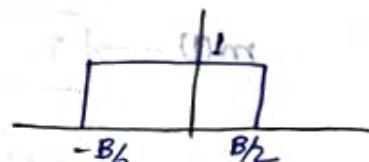
Common problem

- a baseband signal $m(t)$ over BB channel or PB channel

Baseband channels

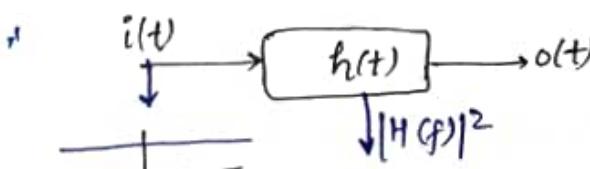


Simpler model:

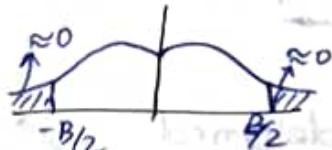


Bandwidth for a channel/System:

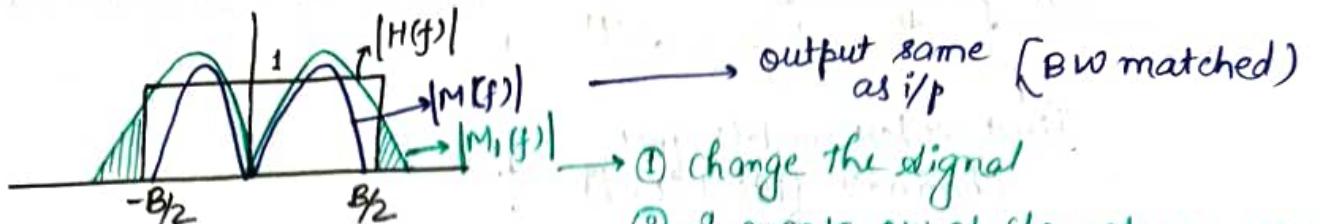
↳ Tells the capability of the channel (ability to transmit particular range of frequencies).



$$\frac{P_A}{-B/2} \quad \frac{P_B}{B/2}$$

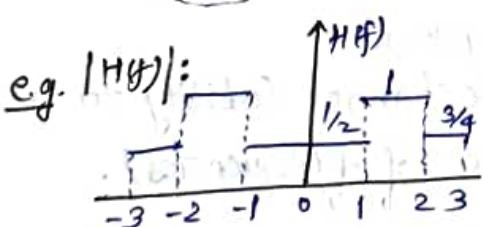
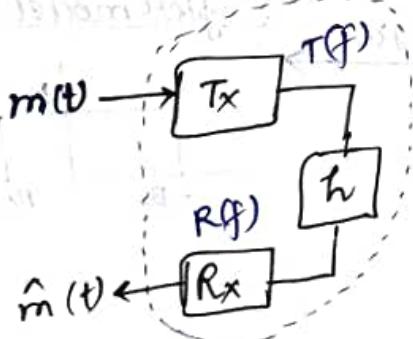
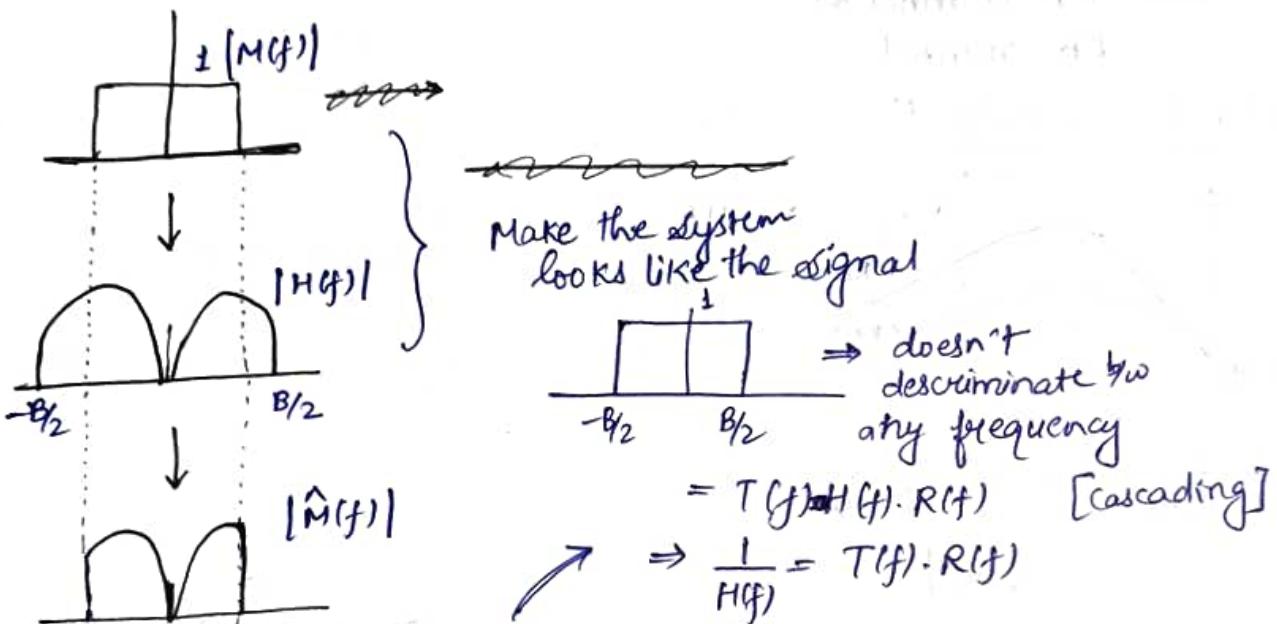


Simpler model for channel:

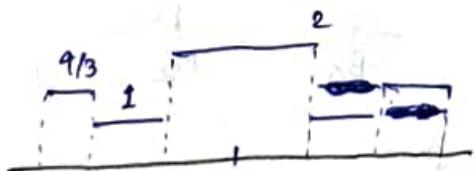


- ① change the signal
- ② Increase BW of channel: expensive
- ③ Expand the signal in time-domain

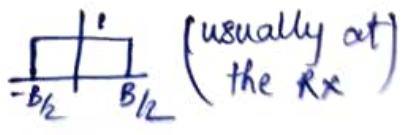
BB → BBC, if the BW of $m(t)$ to compress it in freq.-domain.
 \leq BW of channel

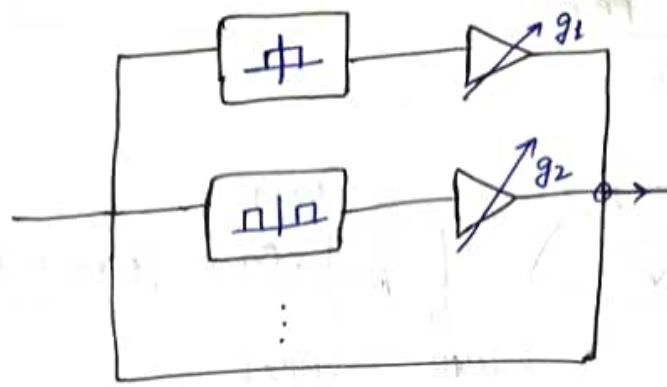


$T(f) \cdot R(f)$:



$T(f) \cdot R(f)$ should be designed so that $T(f) \cdot R(f) \cdot H(f)$

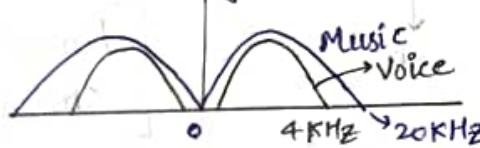




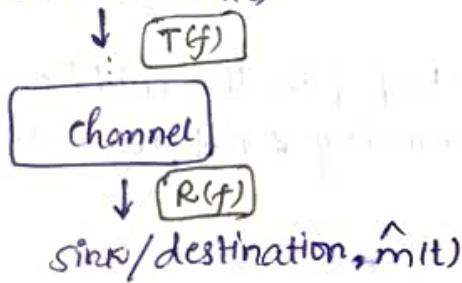
13-08-2024

Review

- Message signal, $m(t)$
 - ↳ a baseband signal (real)



- Source has $m(t)$

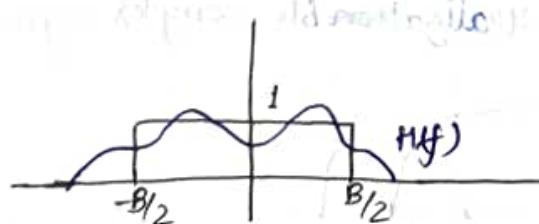


- channels - think using models

Models → LTI ~~need~~ filters

Baseband (LPF) Passband (BPF)

Baseband



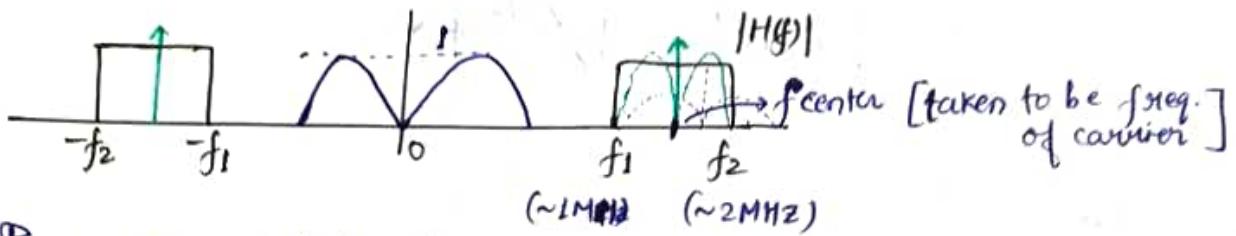
1st check → message P/W $\leq B$

Realistic model → needs equalization

$$T(f) \cdot R(f) = \frac{1}{H(f)} \quad (\text{only in BW})$$

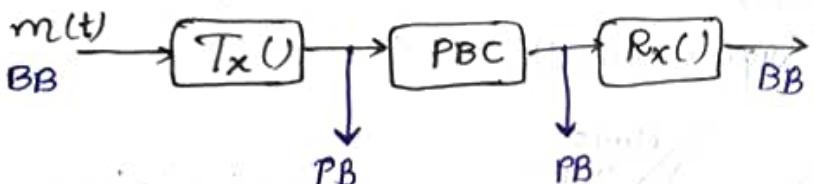
$$A(f)_{\text{min}} = (f_s - \Delta f) - 200 \text{ A (1) dB} \leftarrow \text{min } 200 \text{ dBm power}$$

Baseband Signals over PBC



Constraint: Phase response to be linear [adds delay in time-domain: $|H(f)|e^{j\phi(f)t}$]

Carrier Signal:



[Linear operation doesn't change the frequency.]

Amplitude Modulation:

A signal that can go through the channel:

$$A \cos(2\pi f t)$$

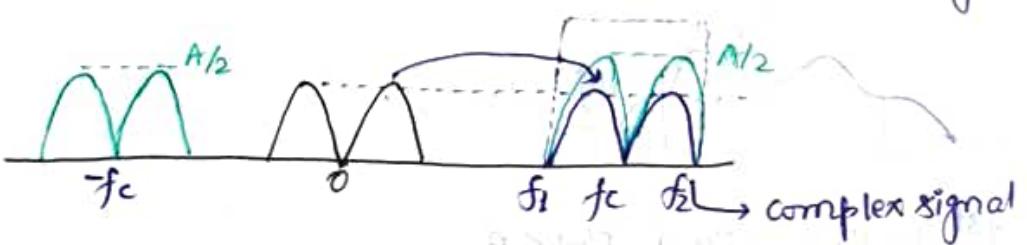
$f \in [f_1, f_2]$ → Try to keep f in the middle to maintain symmetry & not allow signal to fall outside.

$$f_c = \frac{f_1 + f_2}{2}$$

$\begin{cases} \text{carrier amplitude} \\ \text{carrier freq.} \end{cases}$

Frequency translation:

$$m(t) e^{+j2\pi f_c t} \rightarrow \text{unrealizable complex signal}$$

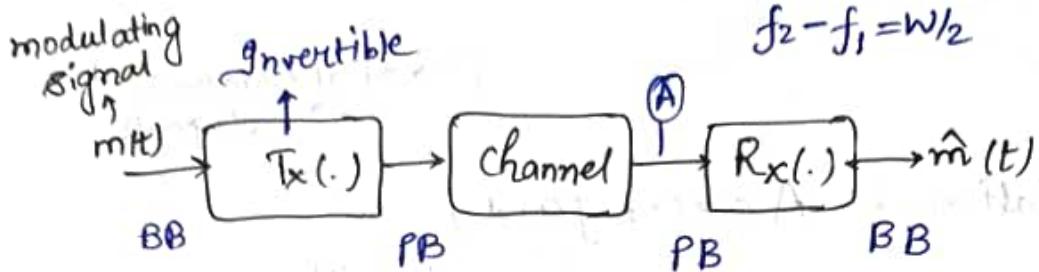
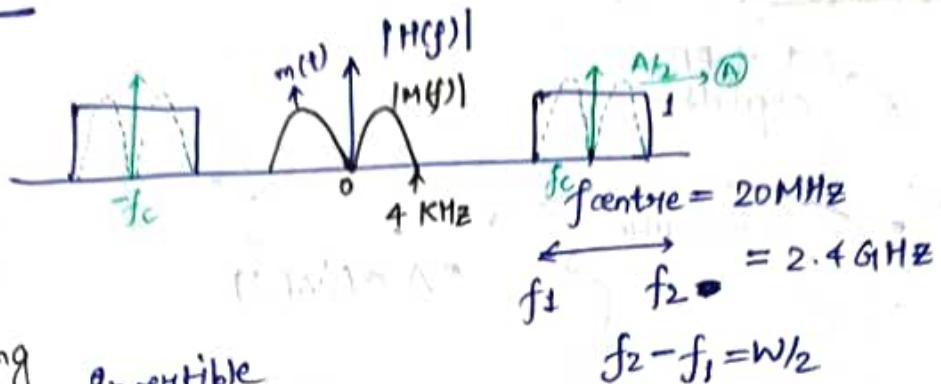


$$m(t) A \cos(2\pi f_c t)$$

$$= m(t) \frac{A}{2} (e^{j2\pi f_c t} + e^{-j2\pi f_c t})$$

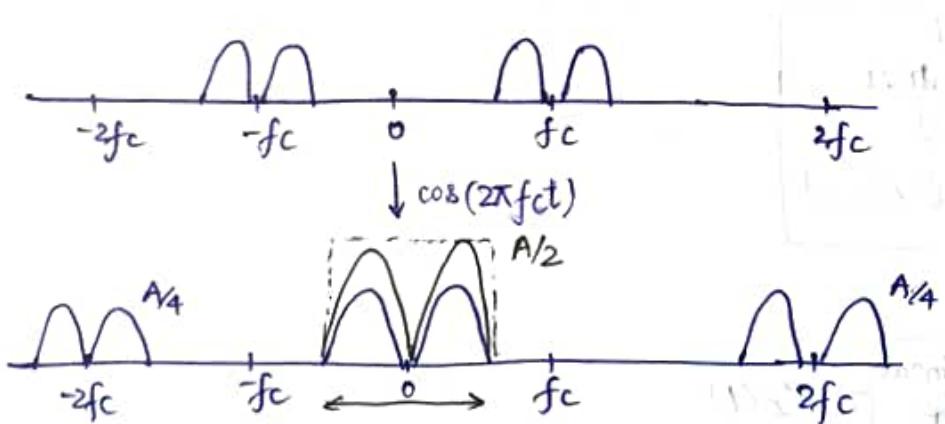
↓ Demodulation

$$\text{multiply with cos/sin} \Rightarrow m(t) A \cos^2(2\pi f_c t) = m(t) A \left[\frac{1 + \cos(4\pi f_c t)}{2} \right]$$

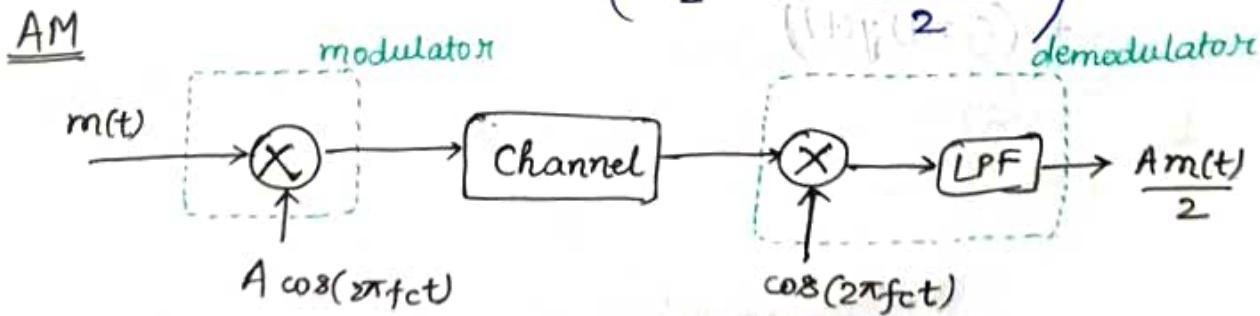
Review

$A \cos(2\pi f_c t) \leftarrow$
 $A m(t) \cdot \cos(2\pi f_c t) \oplus \rightarrow$ Modulated carrier/signal
 ↓
 Amplitude modulation

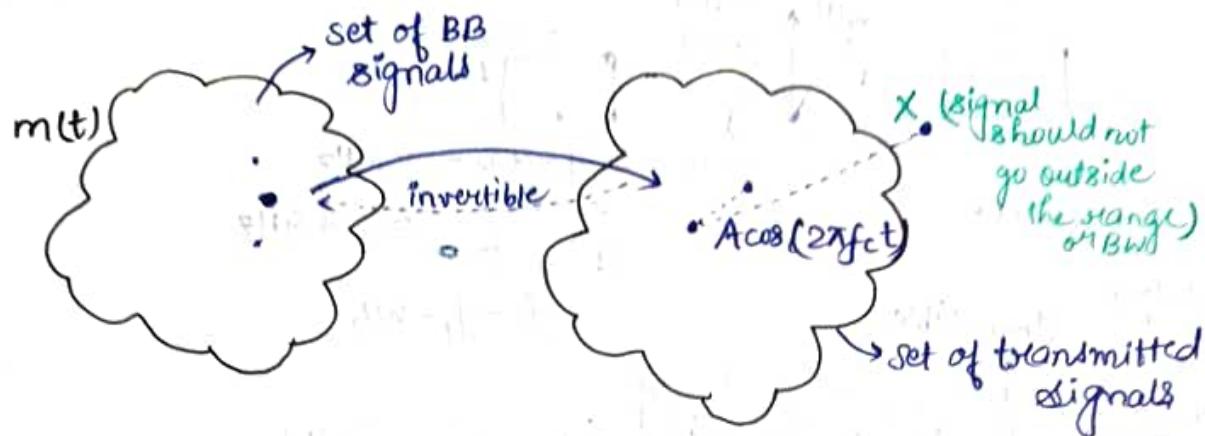
$x(t) \xrightarrow{F} x(t)$
 $x(t) \cos(2\pi f_c t) \longrightarrow \frac{1}{2} x(f-f_c) + \frac{1}{2} x(f+f_c)$



$$A m(t) \cdot \cos^2(2\pi f_c t) = A_m m(t) \left(\frac{1}{2} + \frac{\cos(2\pi(2f_c)t)}{2} \right)$$

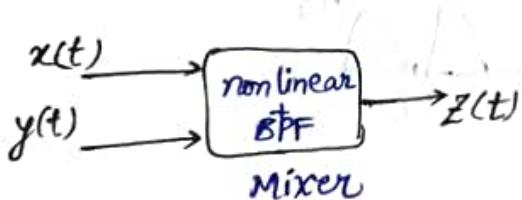
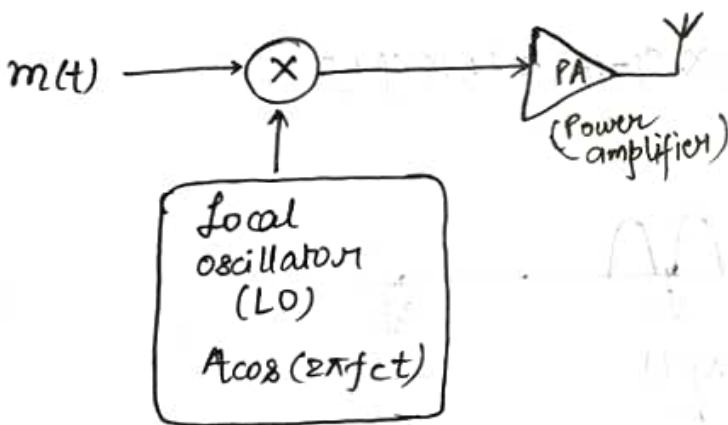


Modulation Schemes

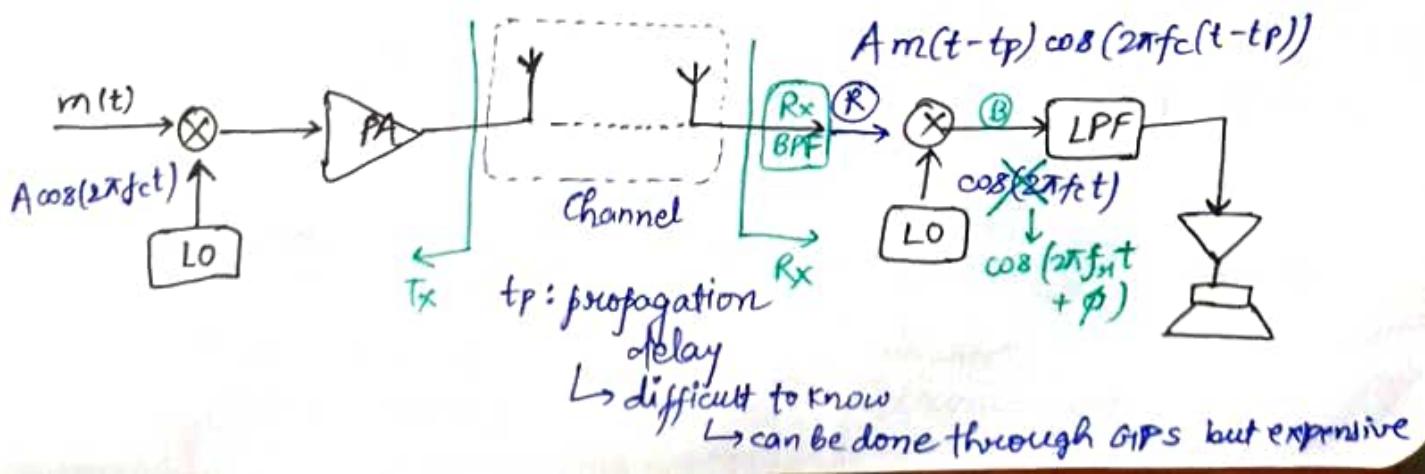
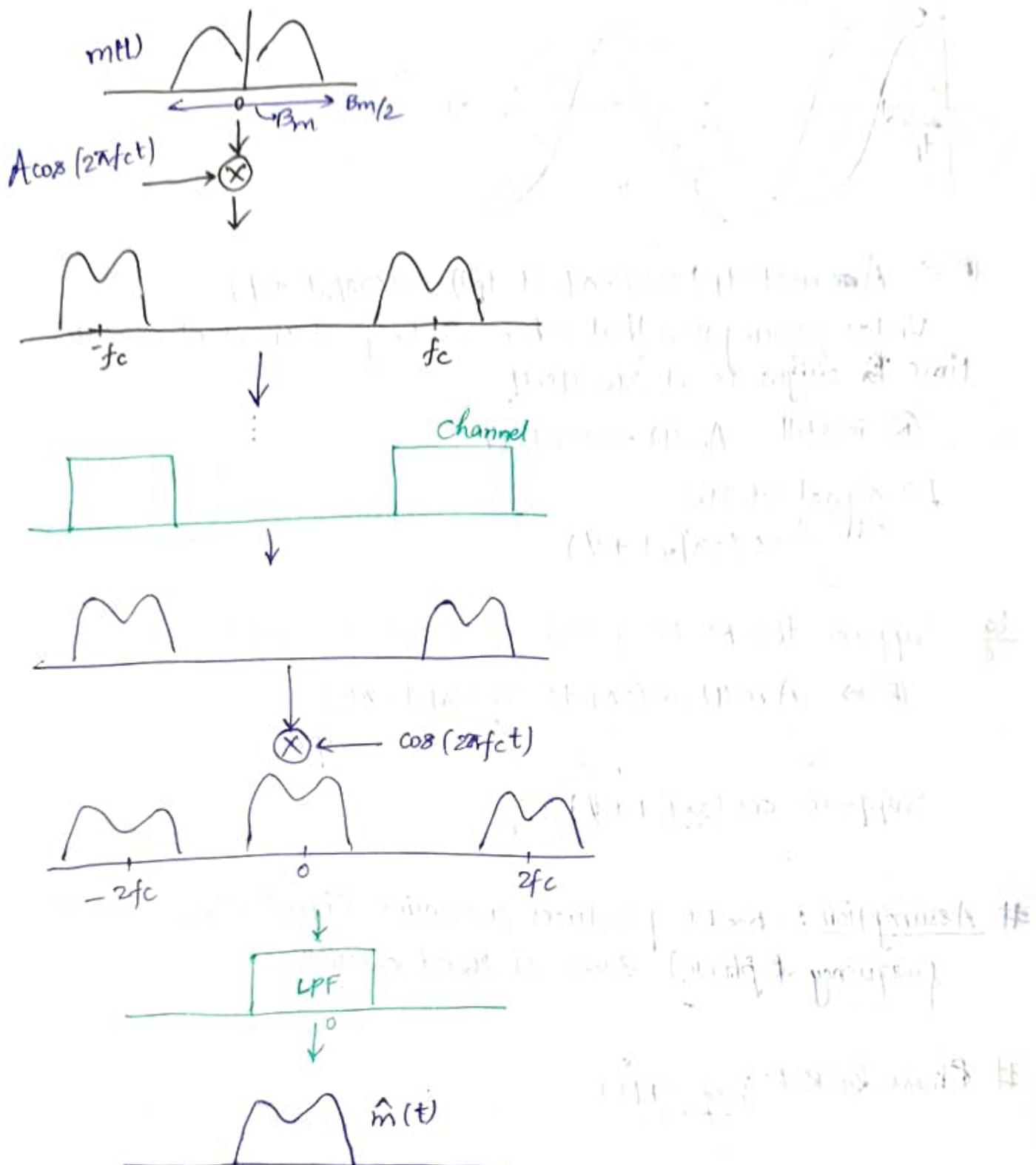


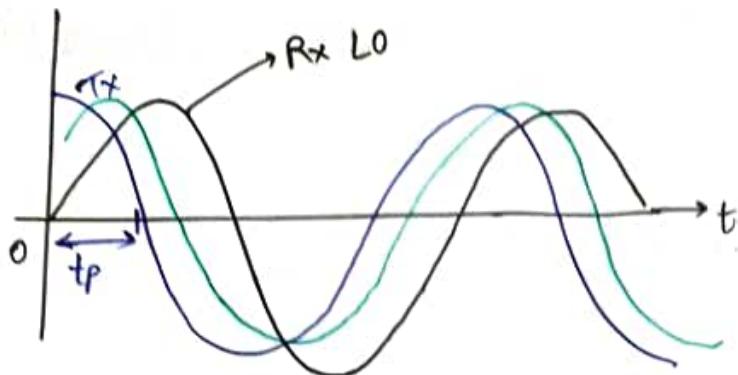
Frequency Modulation : $A \cos(2\pi f(t)t)$
 (FM)
 \downarrow acc. to $m(t)$
 $f(t) = f_c + k_f m(t)$

Phase Modulation : $A \cos(2\pi f_c t + \phi(t))$
 (PM)
 \downarrow acc. to $m(t)$



$$z(t) = c_1 x(t) + \sum c_j y(t) + (c_2 x(t) y(t))$$

Recall



③ $\Rightarrow A m(t - t_p) \cos(2\pi f_c(t - t_p)) \cdot \cos(2\pi f_{rx}t + \phi)$

Under assumption that when looking at received signals time origin is at Rx itself.

R is still $A m(t) \cos(2\pi f_c t)$

LO signal at Rx:

$$\cos(2\pi f_{rx}t + \phi)$$

Eq. Suppose the RX LO produces $\cos(2\pi f_c t + \cancel{\phi})$.

④ $\Rightarrow A m(t) \cos(2\pi f_c t) \cdot \cos(2\pi f_c t + \pi/2)$

\hookrightarrow no output

Suppose $\cos(2\pi f_c t + \phi)$

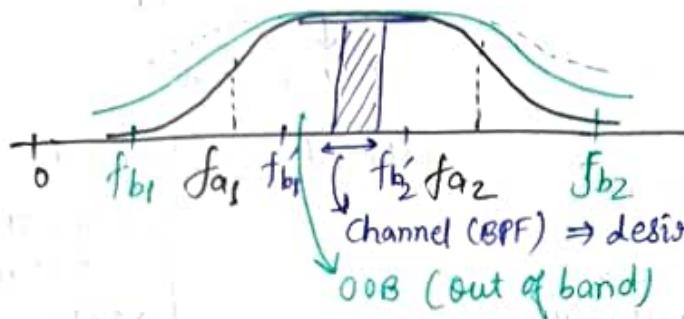
Assumption: Rx LO produces a carrier signal same (same frequency & phase) ~~same~~ as Rxed carrier.

Phase locked loop (PLL)

(W) ~~Phase lock loop~~



BPF model for the channel



$f_{a1} - f_{a2}$: Range of freq. that is tx ed / rx ed

Receiver -

just after the antenna

we need Rx BPF

- channel selection

+
amplification (LNA)

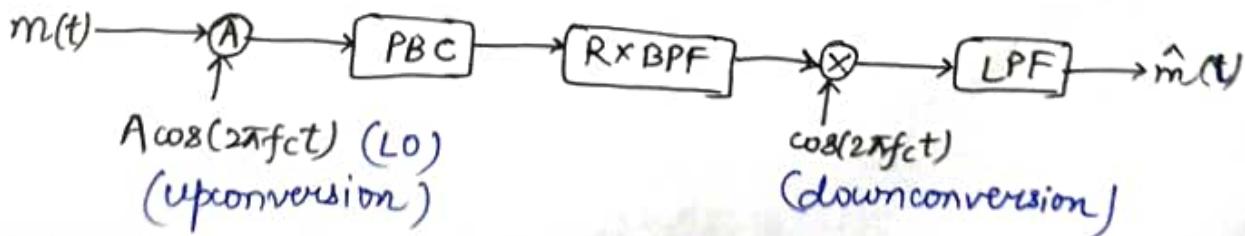
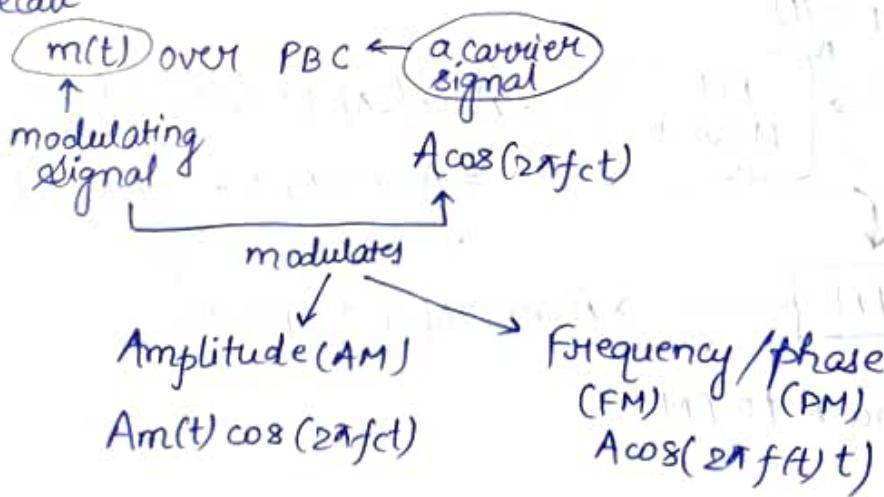
noise cutoff

MIXER

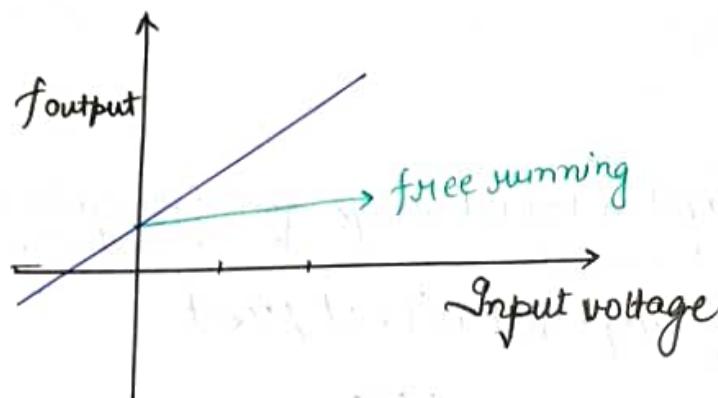
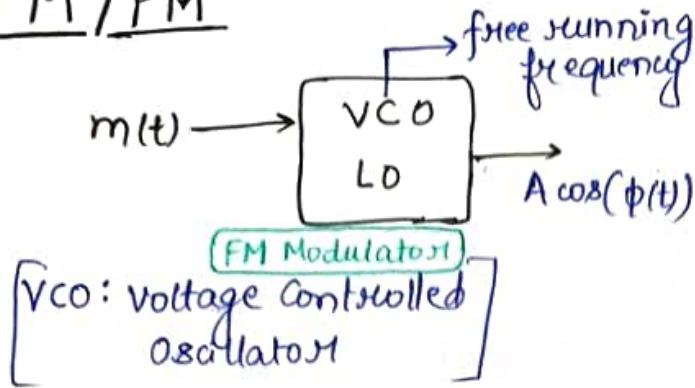
20-08-2024

Passband Communication System

Recall



FM / PM



Ideally $A \cos(2\pi f_c t)$
instantaneous frequency.

In general,

$$A \cos(\phi(t))$$

$$f(t) = \frac{1}{2\pi} \frac{d\phi(t)}{dt}$$

for a VCO

$$f(t) = f_{\text{free}} + K_f [m(t)]$$

\downarrow sensitivity parameter
 \downarrow slope

$$\phi(t) = \int_0^t 2\pi f(u) du, \quad \phi(0) = 0$$

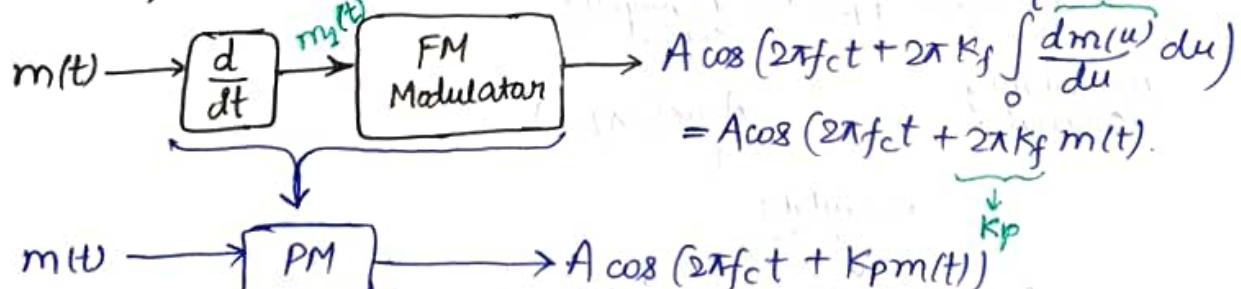
$$\phi(t) = 2\pi f_c t + 2\pi K_f \int_0^t m(u) du$$

So, the FM modulated signal:

$$A \cos(2\pi f_c t + 2\pi K_f \int_0^t m(u) du)$$

Phase Modulation

$$\phi(t) = 2\pi f_c t + K_p m(t)$$



We'll restrict to FM.

Passband Communication

Carrier signal: $A \cos(2\pi f_c t)$

$$\text{AM: } m(t) \xrightarrow{\uparrow A \cos(2\pi f_c t)} \otimes \xrightarrow{} A m(t) \cos(2\pi f_c t)$$

$$\text{FM: } m(t) \xrightarrow{\text{FM modulator}} A \cos\left(2\pi f_c t + 2\pi K_f \int_0^t m(u) du\right)$$

(PM is eq.)

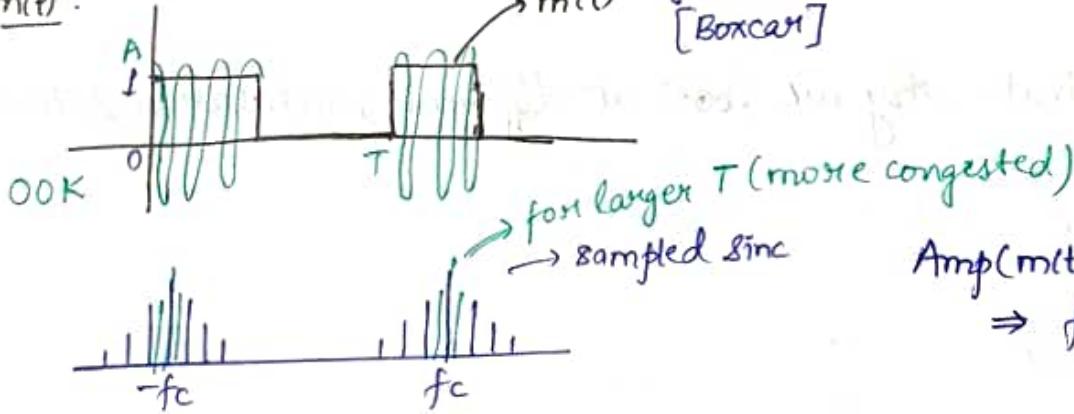
$$m(t) \xrightarrow{F} M(f)$$

PBC:

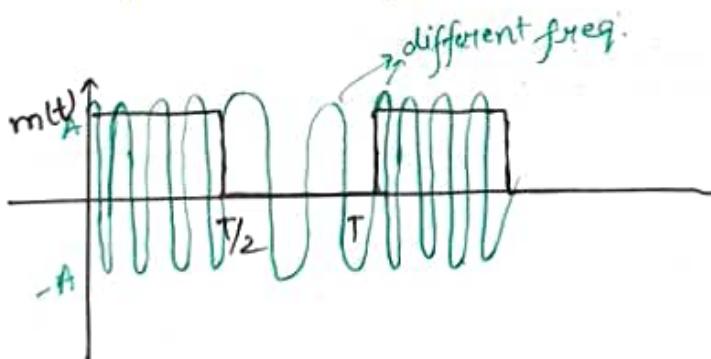
$$\begin{aligned} &A m(t) \cos(2\pi f_c t) \xrightarrow{F} \\ &A \cos\left(2\pi f_c t + 2\pi K_f \int_0^t m(u) du\right) \end{aligned}$$

AM:

m(t):



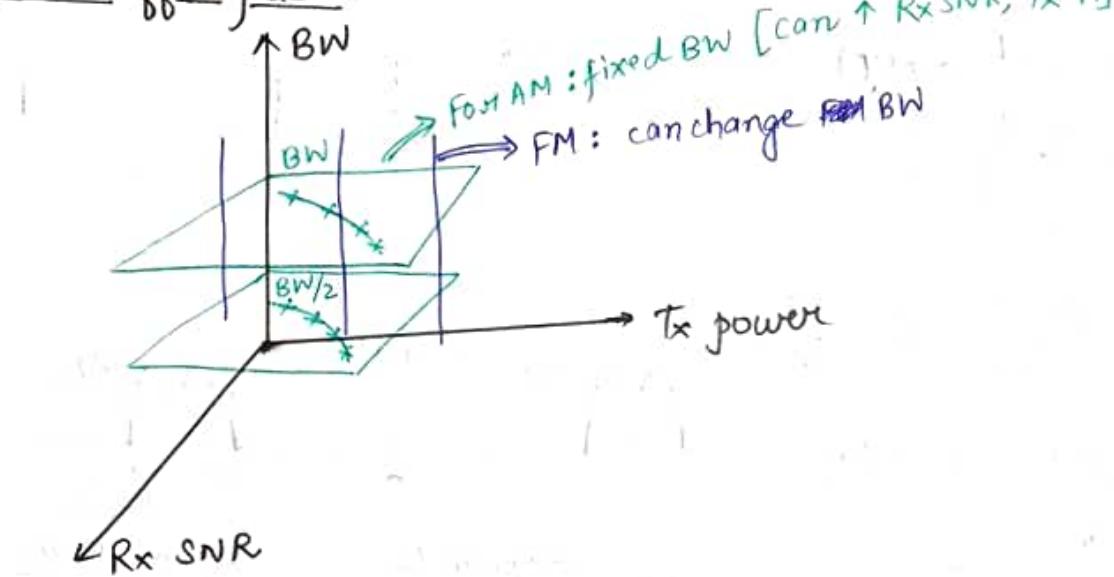
FM:



Performance metrics:

- Bandwidth
- Power (Transmit) $\uparrow \Rightarrow$ Battery drain
- Rx SNR
- complexity

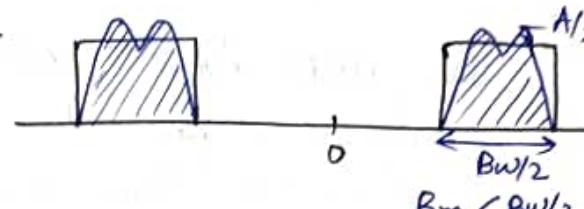
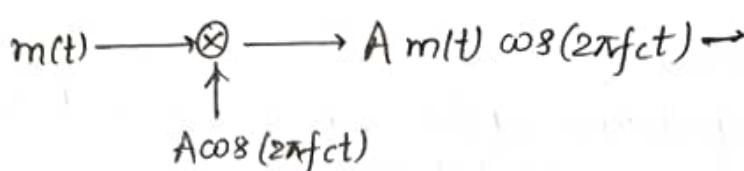
Tradeoff space:



Motivate why we look at different modulation schemes

Amplitude Modulation Schemes

- ↳ Double sideband suppressed carrier (DSB, DSBSC)
- ↳ Plain AM / Large carrier AM (LCAM)
- ↳ Single sideband SSB
- ↳ Vestigial sideband (VSB) } X



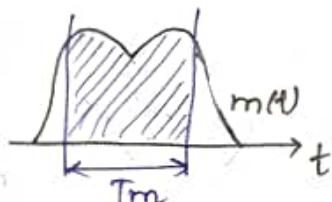
DSB spectrum:

$$\frac{A}{2} M(f-f_c) + \frac{A}{2} M(f+f_c)$$

Transmit power energy: $\frac{A^2}{4} \times 2 \times E_m$

$$= \frac{A^2}{2} E_m$$

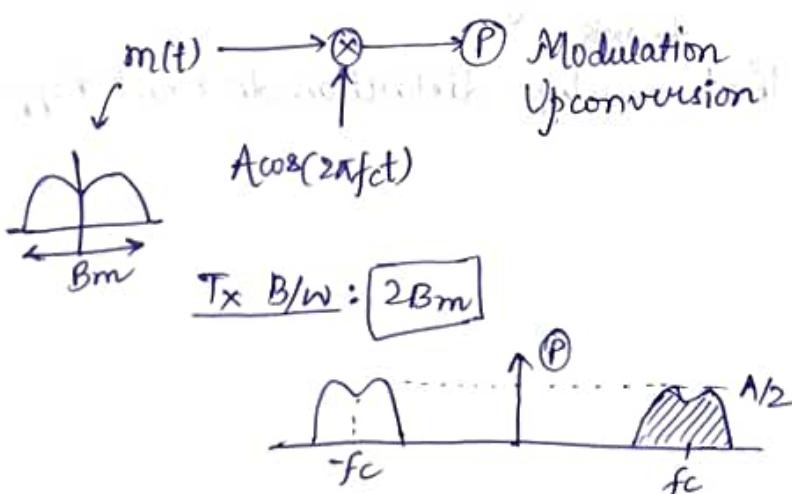
$$P_m = \frac{E_m}{T_m}$$



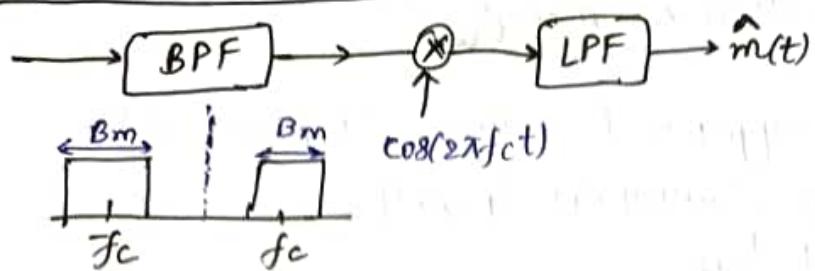
↳ Time duration during which most of the energy is transmitted

$\boxed{\frac{A^2}{2} P_m} \Rightarrow$ Transmitted power

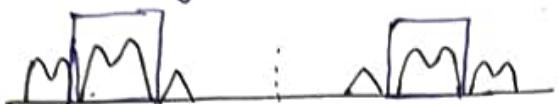
(22-08-2024)



DSB Rx Demodulation:



Eg. with multiple channels



Eg. $m(t) = A_m \sin(2\pi f_m t)$

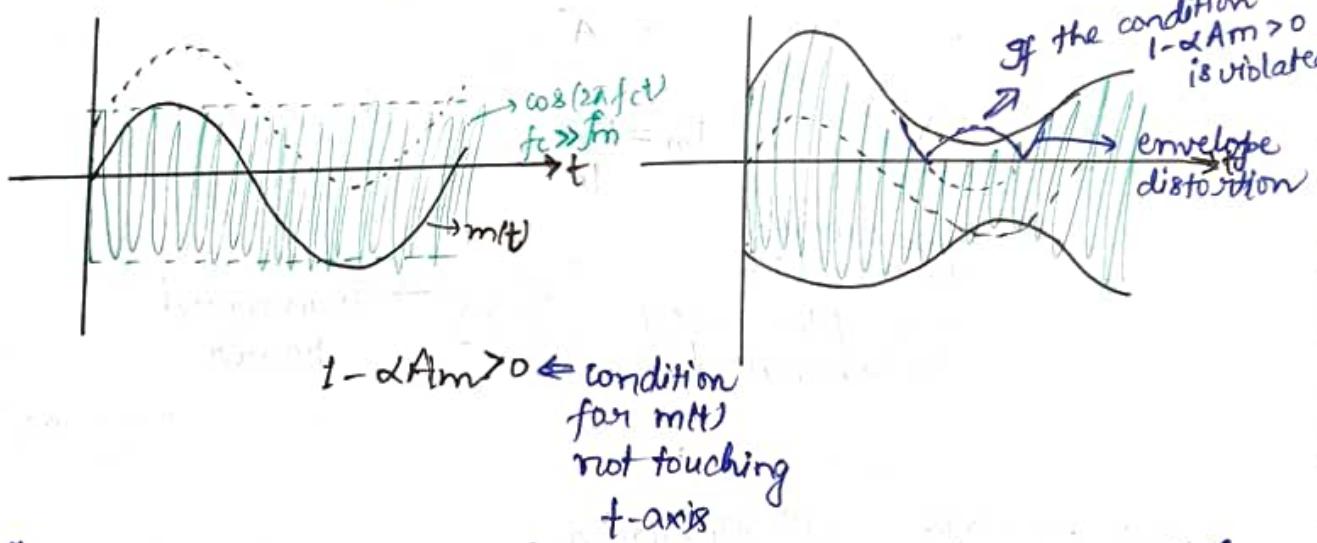
Draw magnitude spectrum of the DSB modulated signal.

Draw the time domain modulated signal.

Soln: $m(t) = A_m \sin(2\pi f_m t)$

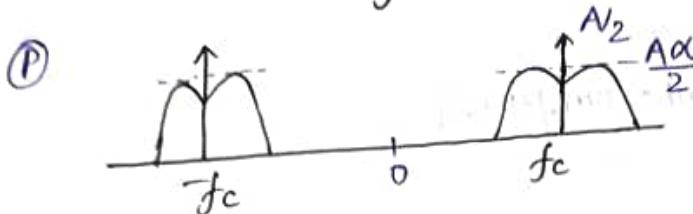
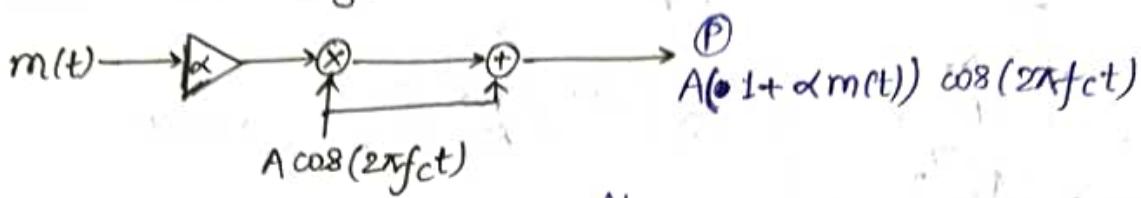
$$A(1 + \alpha A_m \sin(2\pi f_m t)) \cdot \cos(2\pi f_c t)$$

Modulated signal



In LCAW, ~~ensure~~ ensure that envelope distortion does not happen.

Plain AM or Large Carrier AM (LCAM)



$$\text{Tx BW: } [2B_m]$$

$$\text{Tx power: } \int_{T_{\text{eff}}} A^2 (1 + \alpha m(t))^2 \cos^2(2\pi f_c t) dt$$

$$= \int_{T_{\text{eff}}} \frac{A^2}{2} (1 + \alpha^2 m(t)^2 + 2\alpha m(t)) (1 + \cos(\frac{2\pi \cdot 2f_c}{\alpha} t)) dt$$

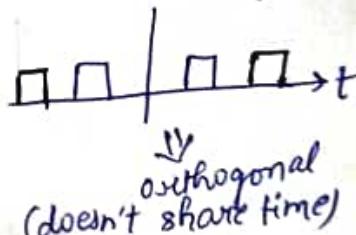
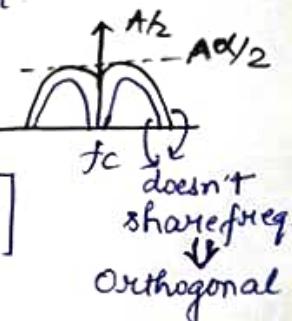
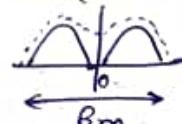
$$\approx \int_{T_{\text{eff}}} \frac{A^2}{2} (1 + \alpha^2 m(t)^2 + 2\alpha m(t)) dt$$

$$\approx \int_{T_{\text{eff}}} \left(\frac{A^2}{2} + \frac{\alpha^2 A^2 m(t)^2}{2} \right) dt \quad \begin{array}{l} \text{For signal with no dc-component} \\ \Rightarrow \int m(t) dt = 0 \text{ (mean=0)} \end{array}$$

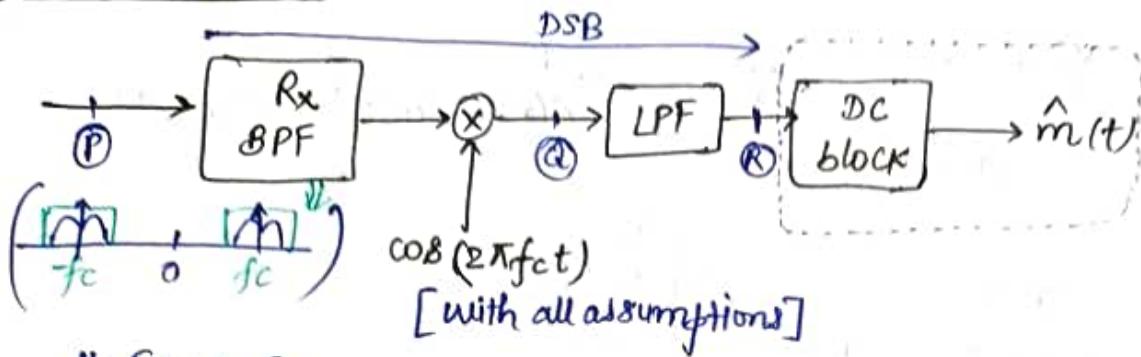
$$= \frac{A^2}{2} T_{\text{eff}} + \frac{\alpha^2 A^2 E_m}{2}$$

Divide by T_{eff} ,

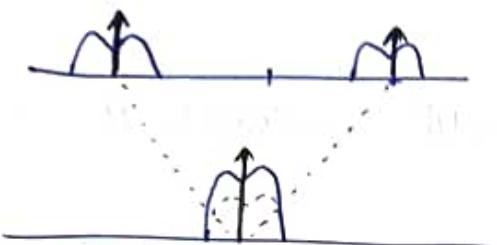
$$\text{Tx Power} = \frac{A^2}{2} + \frac{\alpha^2 A^2 P_m}{2} \quad \begin{array}{l} \text{Carrier power} \\ + \text{scaled DSB power} \end{array}$$



LCAM Receiver



For DSB:

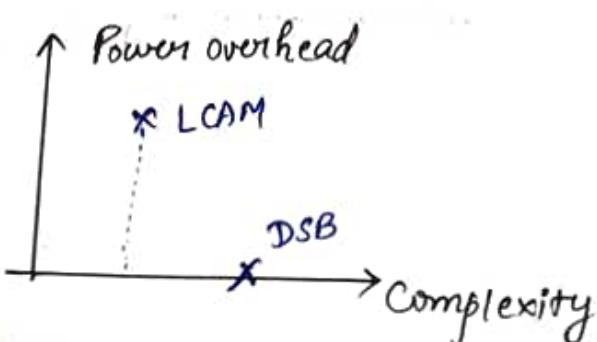
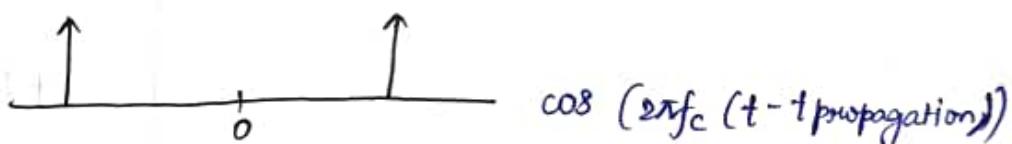
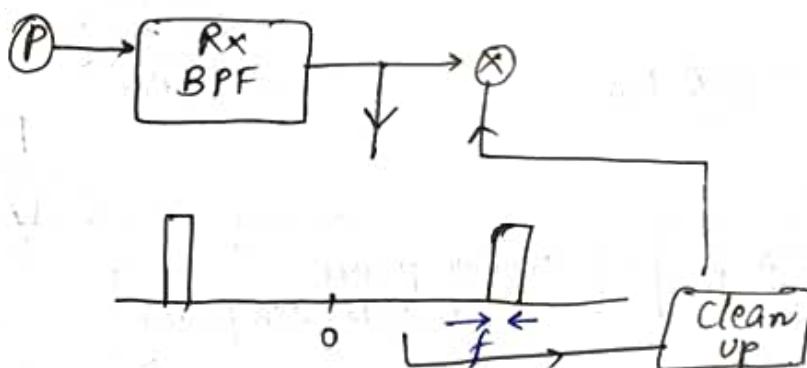


$$\textcircled{P} \Rightarrow A(1 + \alpha m(t)) \cos(2\pi f_{ct})$$

$$\textcircled{Q} \Rightarrow A(1 + \alpha m(t)) \cos^2(2\pi f_{ct})$$

$$\textcircled{R} \Rightarrow \frac{A}{2} + \frac{A\alpha}{2} m(t)$$

$$\hat{m}(t) = \frac{\alpha A}{2} m(t).$$



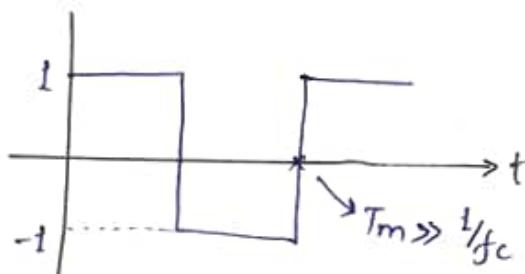
- Pilot signals [in-band] → helps in demodulating using an envelope detector.
- Out of band schemes
 - ↳ Needs more BW

→ go out of band
in the carrier
Then, frequency division

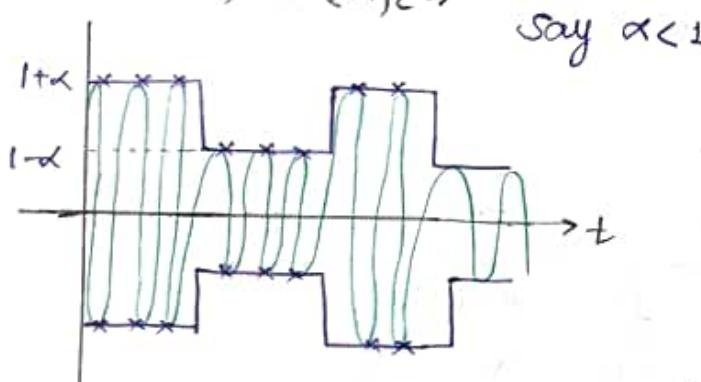
27-08-2024

LCAM signal in time-domain:

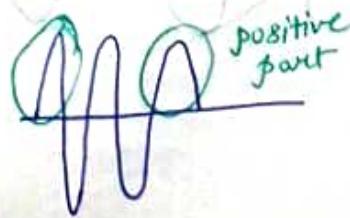
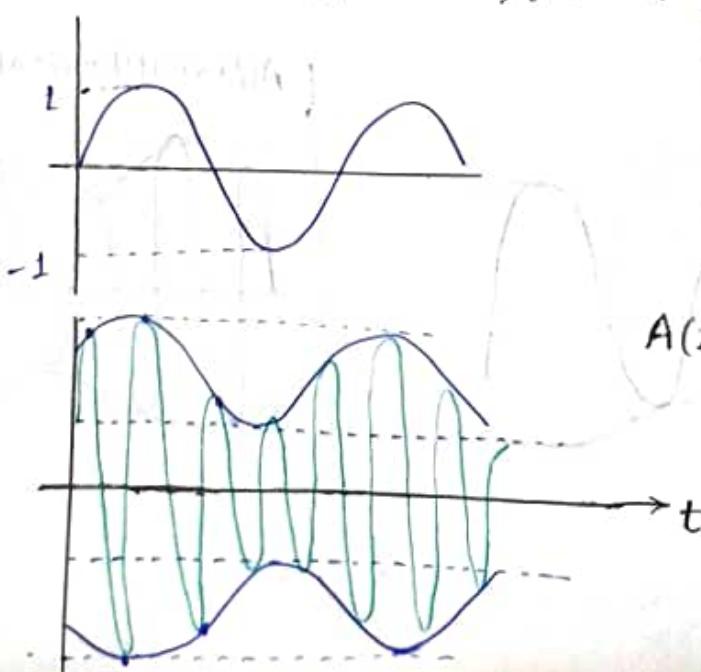
Eg. Consider $m(t)$ to be



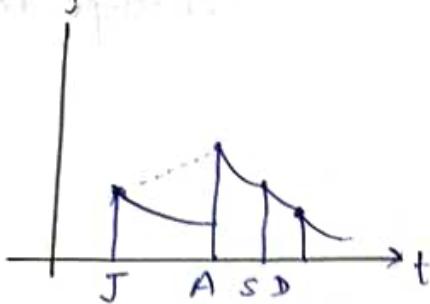
$$A(1 + \alpha m(t)) \cos(2\pi f_c t)$$



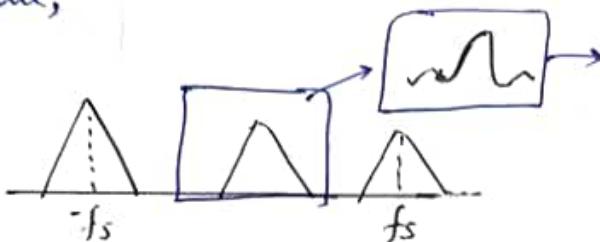
Eg. Consider $m(t)$ to be $A_m \sin(2\pi f_m t)$.



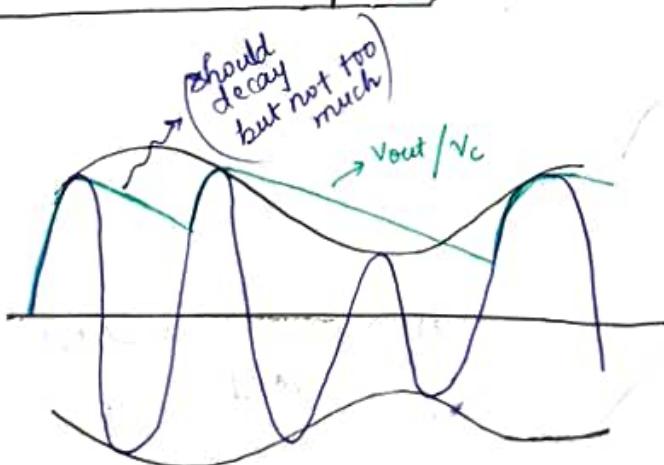
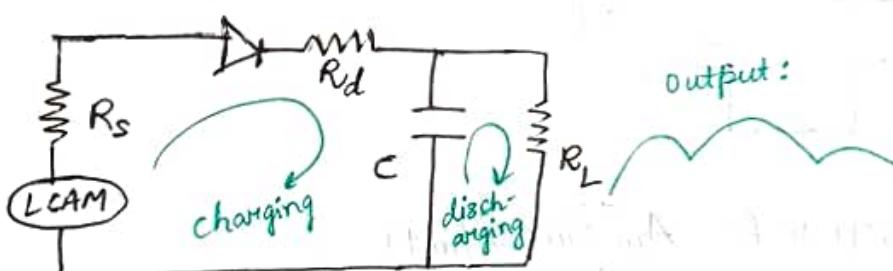
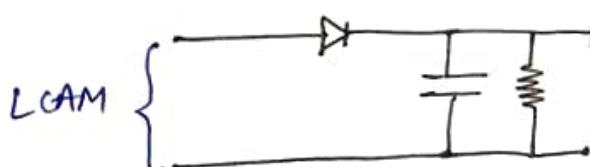
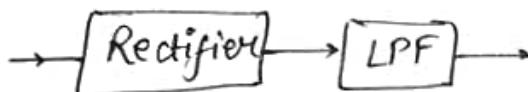
Interpolation:



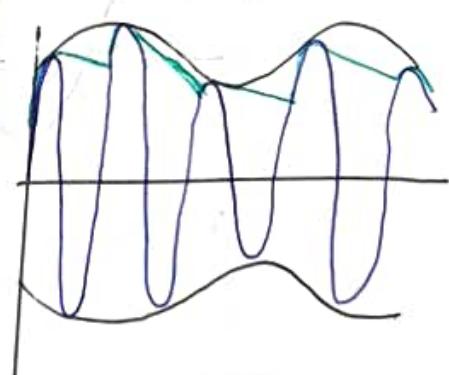
Recall,

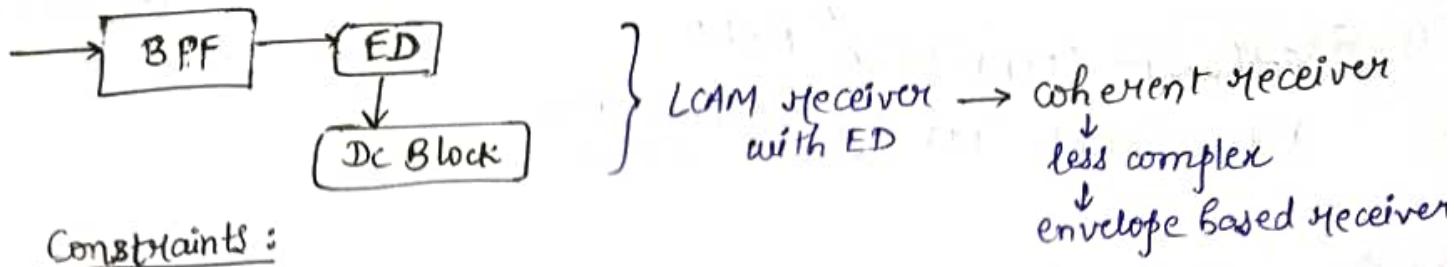


Envelope detector:



$$A(1 + \alpha m(t)) \cos(2\pi f_c t)$$





Constraints:

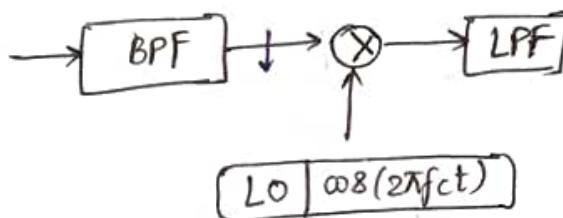
$$C(R_s + R_d) \ll 1/f_c$$

charging time constant

$$\frac{1}{f_c} \ll C R_L \ll \frac{1}{B_m}$$

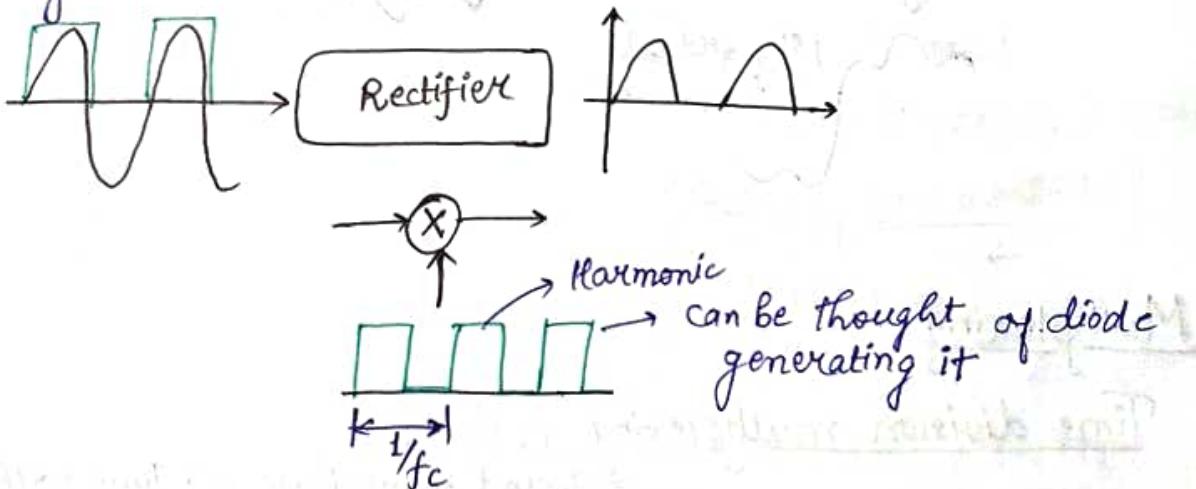
disch. time constant time taken for modulating signal to change
 $B_m \rightarrow$ (B/W of m(t))

Receiver:

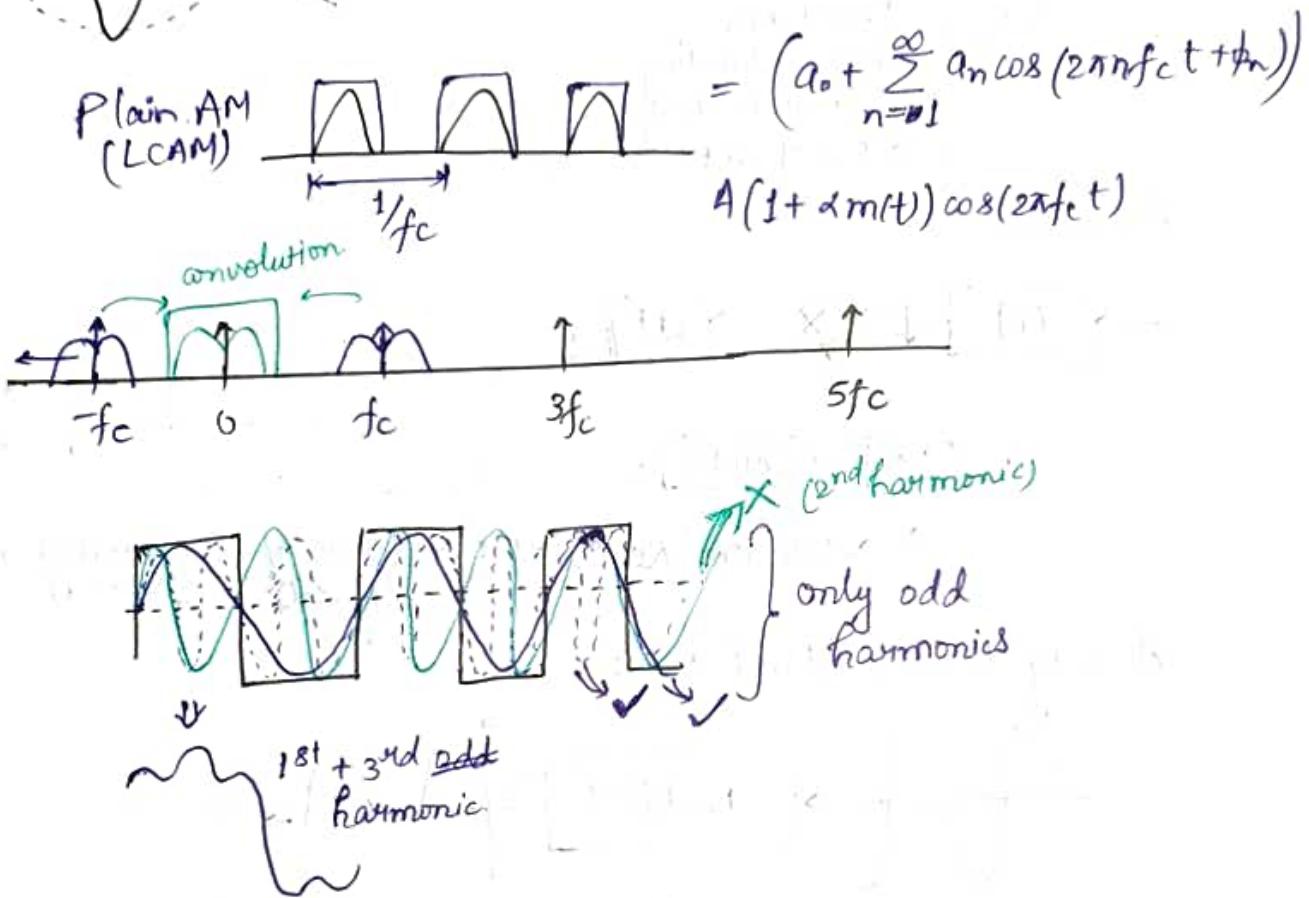
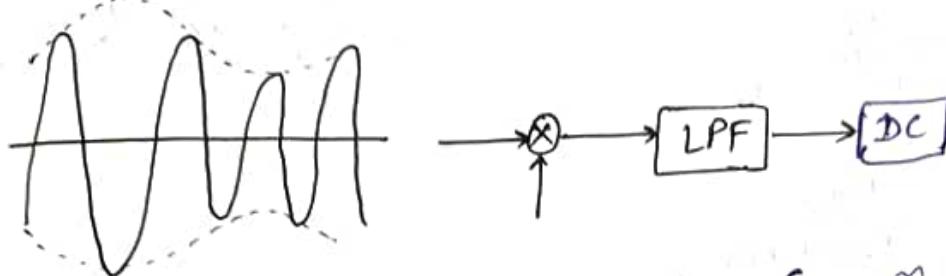


\hookrightarrow coherent Receivers : Generate of frequency matched signals

A way to understand E.D:



Coherent (DSB) }
 Non-coherent (ED) } Demodulation schemes



Multiplexing

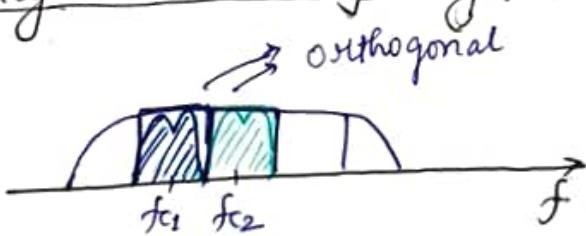
Time division multiplexing (TDM):

doesn't share time \Rightarrow Time orthogonal

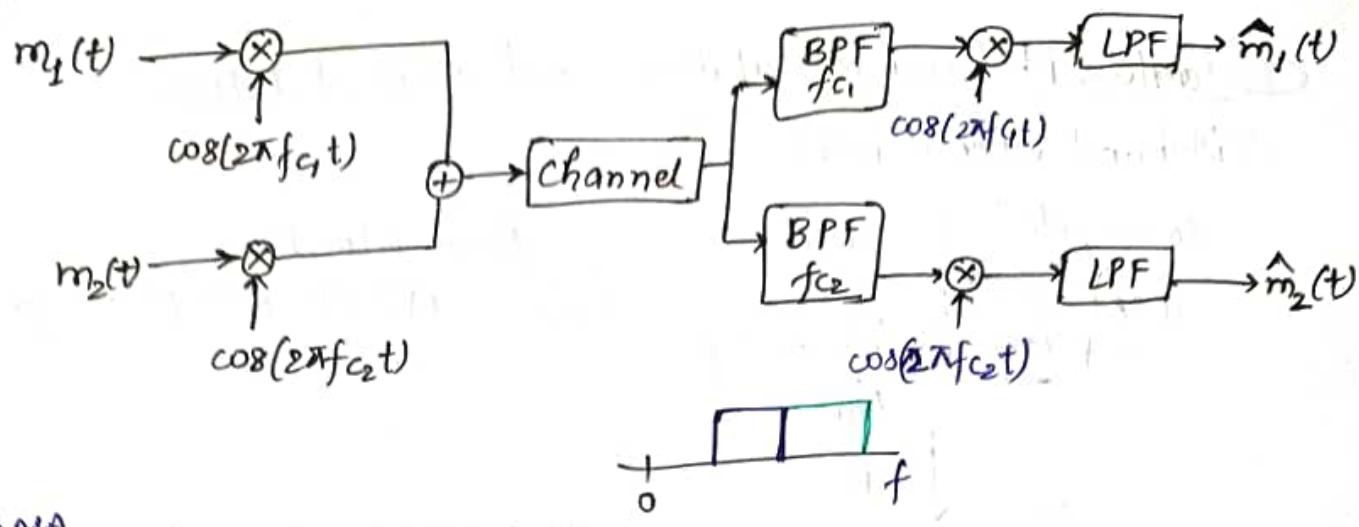
$m_1(t), m_2(t)$

time \Rightarrow one BW, one channel

Frequency division multiplexing (FDM):

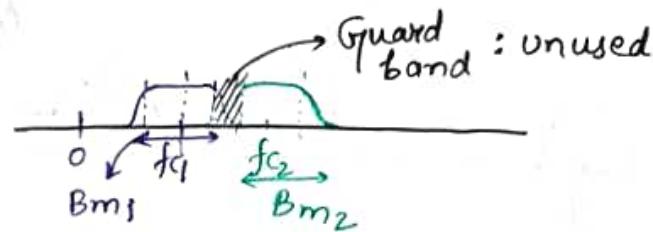


if two signals are orthogonal, they can be multiplexed.

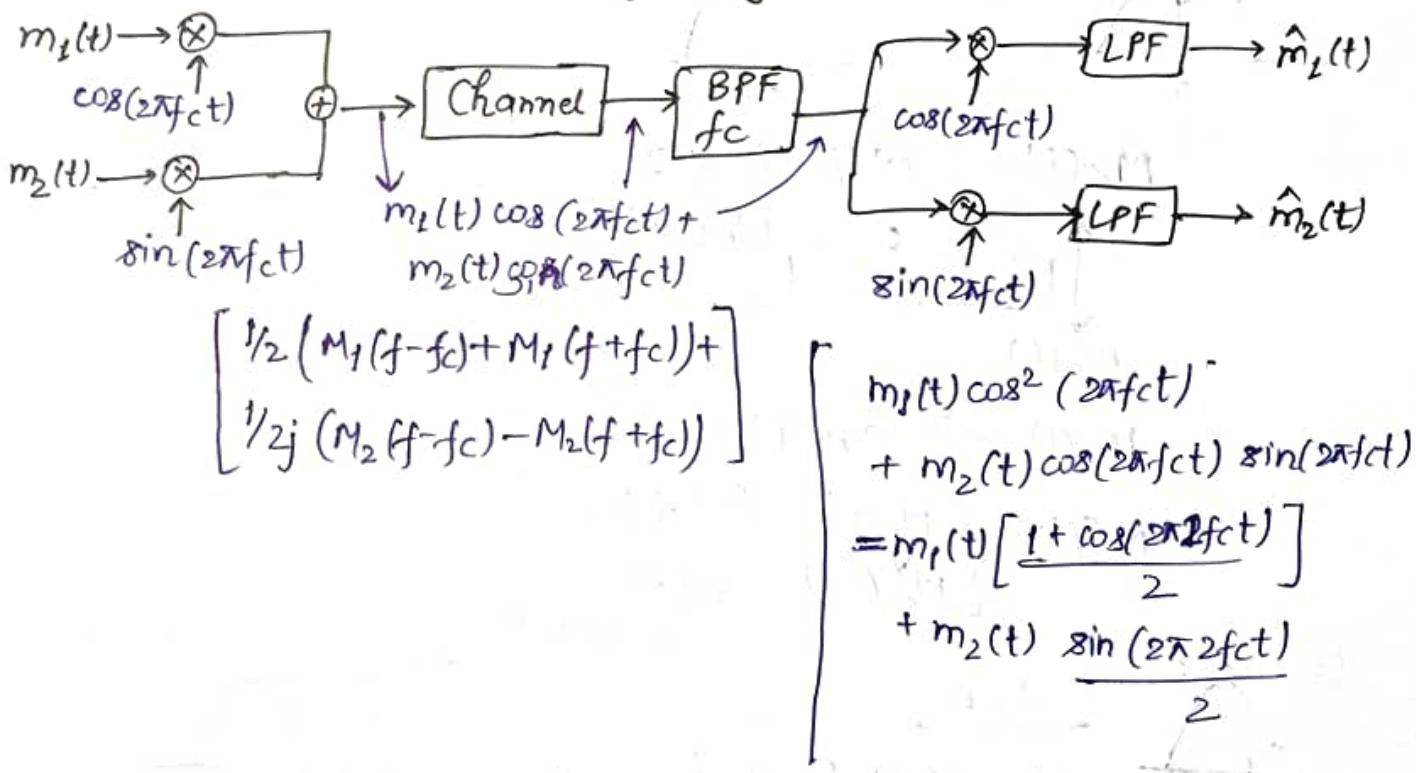


CDMA

OFDMA

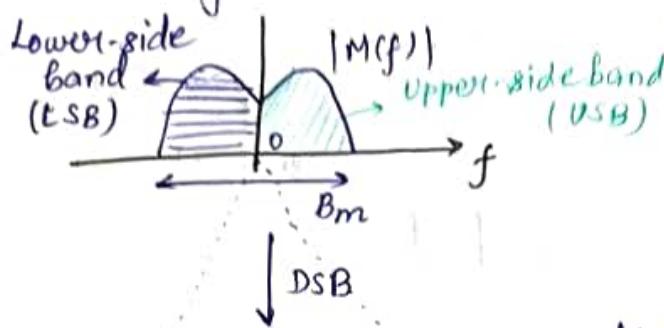


Quadrature Carrier Multiplexing (QCM):



Single Sideband Modulation and Demodulation

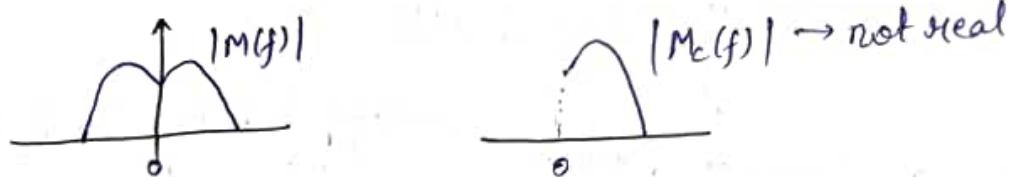
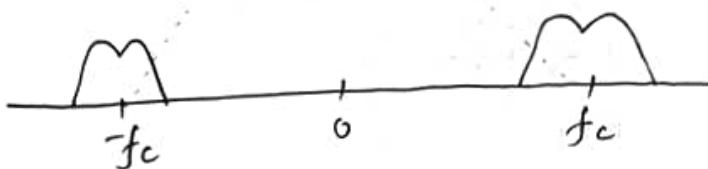
Sideband signal $m(t)$



Real valued:

$$M(-f) = M^*(f) \Rightarrow \text{Symmetric}$$

$$\frac{1}{2} (M(f-f_c) + M(f+f_c))$$

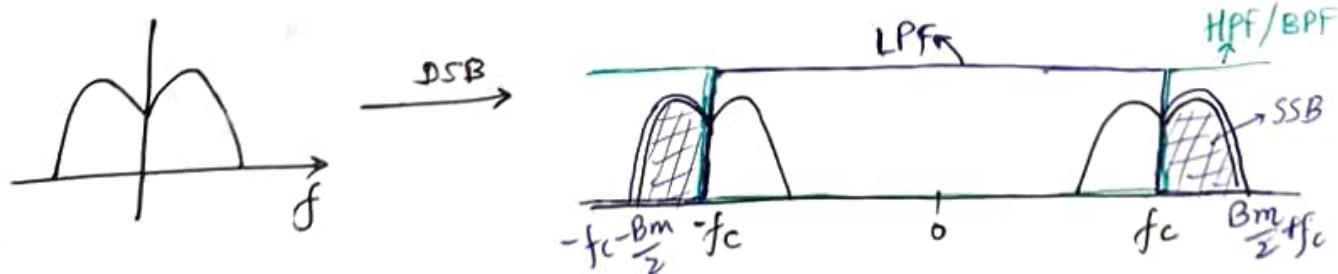
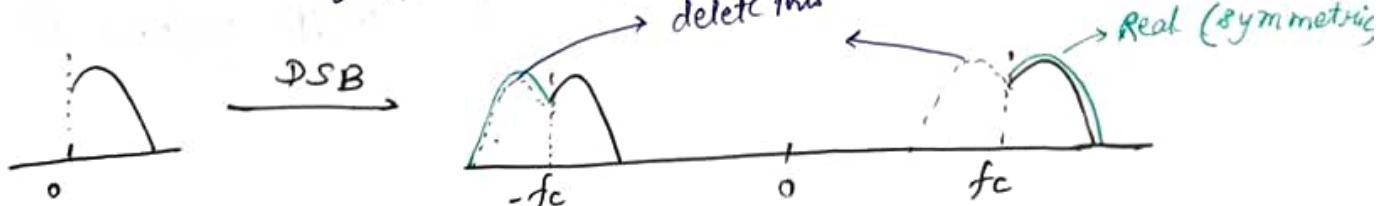


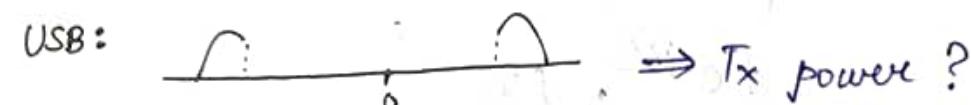
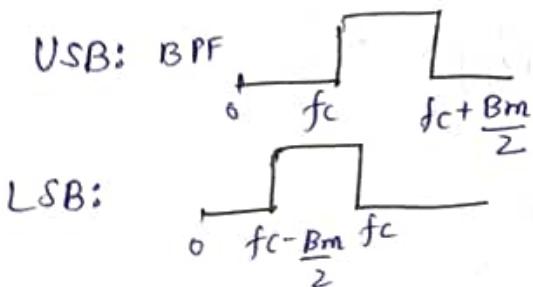
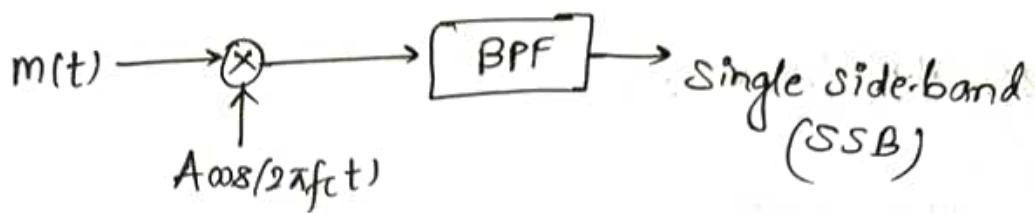
$$M_c(f) = \begin{cases} M(f) & \text{if } f \geq 0 \\ 0 & \text{otherwise} \end{cases}$$

$\uparrow F$
 $\downarrow m_c(t)$

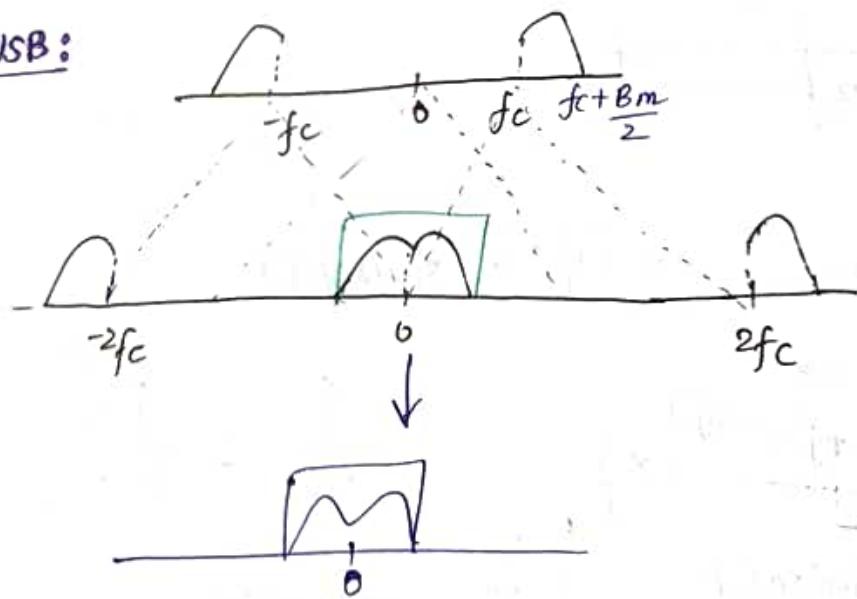
$$m_c(t) \xleftarrow{\equiv} m(t)$$

$$M(f) = \begin{cases} M_c(f) & \text{for } f \geq 0 \\ M_c^*(-f) & , f < 0 \end{cases}$$

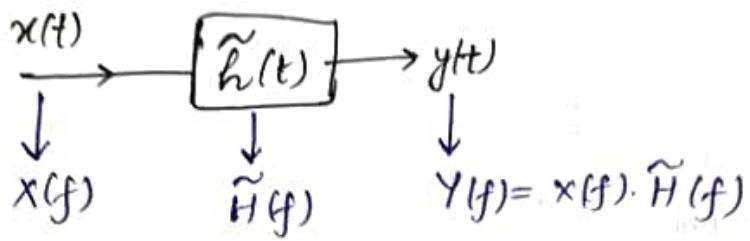




for USB:

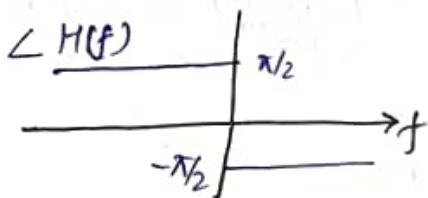
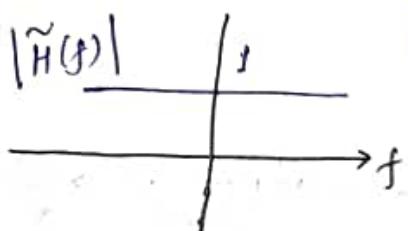


Hilbert Transform Filter



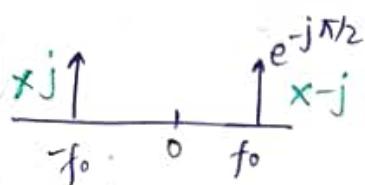
$$\tilde{H}(f) = -j \operatorname{sgn}(f) = \begin{cases} -j, & f \geq 0 \\ +j, & f < 0 \end{cases}$$

$$= \begin{cases} e^{-j\pi/2}, & f \geq 0 \\ e^{j\pi/2}, & f < 0 \end{cases}$$



Eg. $\cos(2\pi f_0 t) \rightarrow \tilde{H}(f) \rightarrow \sin(2\pi f_0 t)$

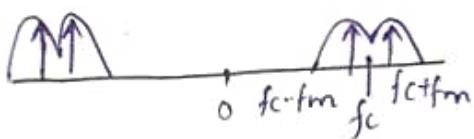
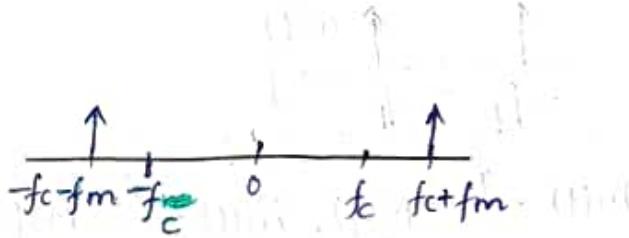
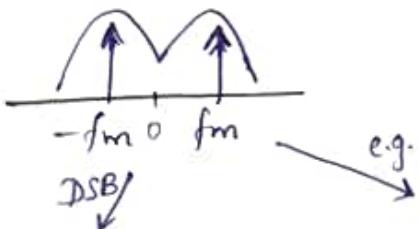
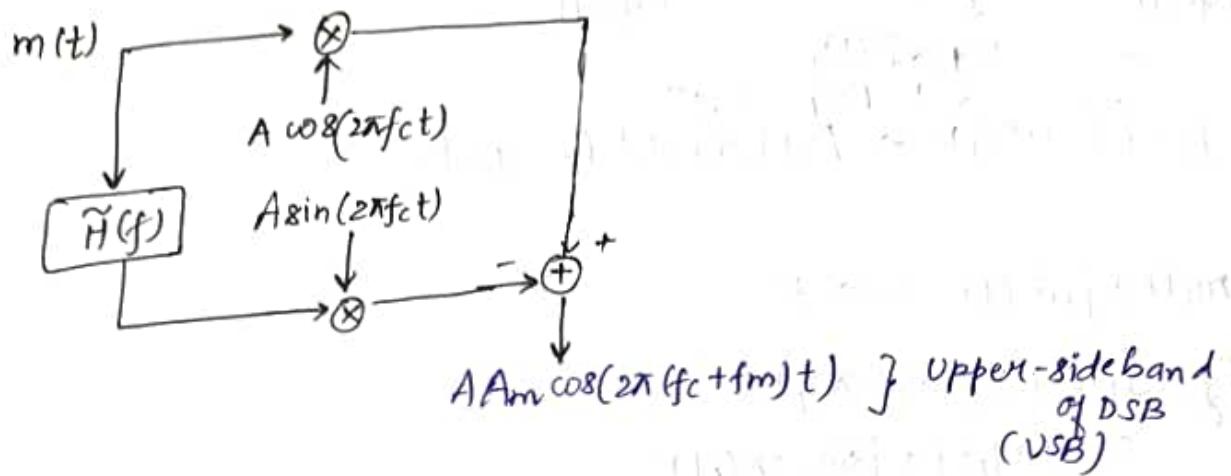
$$\frac{-j e^{j2\pi f_0 t} + j e^{-j2\pi f_0 t}}{2} \times \frac{j}{j} = \sin(2\pi f_0 t)$$



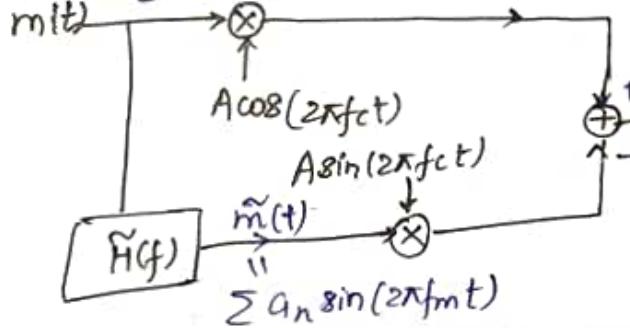
Eg. $\sum a_n \cos(2\pi f_n t) + \sum b_n \sin(2\pi f_n t) \rightarrow \tilde{H}(f) \rightarrow \sum a_n \sin(2\pi f_n t) + \sum b_n \cos(2\pi f_n t)$

wideband phase shifter

$$Eg \quad m(t) = A_m \cos(2\pi f_m t)$$



$$m(t) = \sum a_n \cos(2\pi f_m t)$$



$$USB = \sum a_n \cos(2\pi(f_c + f_m)t)$$

: Phase Discrimination Method

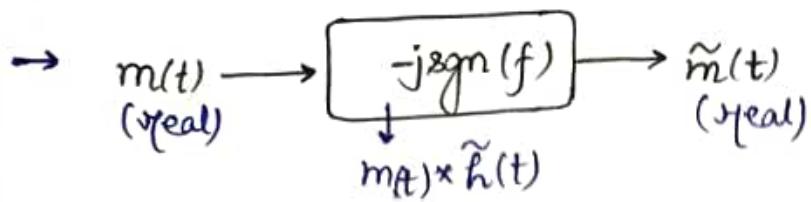
- ① Frequency discrimination method (using BPF)
- ② Phase desc. method
- ③ Weaver's method (Assignment)

$$Eg \quad m(t)$$



$m(t), \tilde{m}(t)$: Real

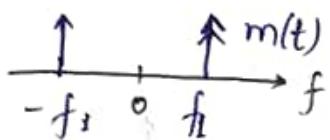
Spectrum of $m(t) \pm j \tilde{m}(t)$



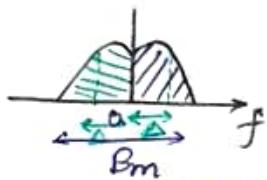
$\tilde{H}(-f) = \tilde{H}^*(f) \Rightarrow h(t)$ should be real.

$$m(t) \pm j\tilde{m}(t) \rightarrow F$$

e.g. If $m(t) = \cos(2\pi f_1 t)$
 $\cos(2\pi f_1 t) + j\sin(2\pi f_1 t)$
 $= e^{j2\pi f_1 t}$



$$m(t) \xleftarrow{F} M(f), \quad \tilde{m}(t) \xrightarrow{F} \tilde{M}(f)$$



$$M(f) = U(f) + L(f)$$



$$\tilde{M}(f) = -jU(f) + jL(f)$$

$$\text{Now, } m(t) \pm j\tilde{m}(t) \xrightarrow{F} M(f) + j\tilde{M}(f) = \begin{array}{c} 2U(f) \\ \hline 0 \quad B_{m/2} \end{array} f$$

$$= U(f) + L(f) + U(f) - L(f)$$

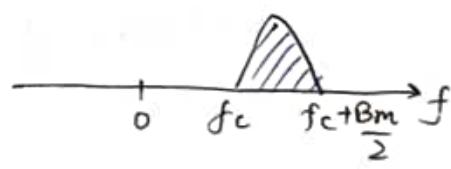
$$= 2U(f)$$

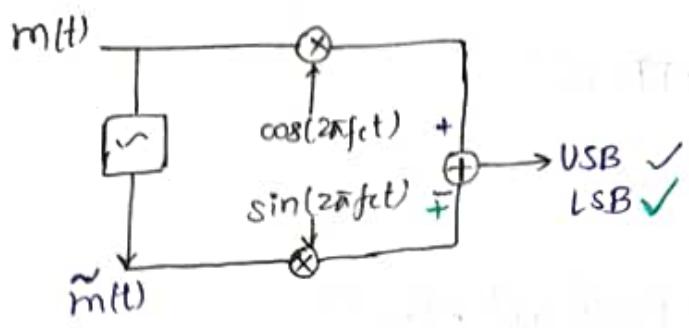
Suppose we take
 $(m(t) + j\tilde{m}(t)) \cdot e^{j2\pi f_c t} \xrightarrow{F}$

Suppose [Take real part of signal]

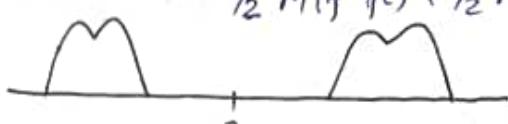
$$\operatorname{Re}\{(m(t) + j\tilde{m}(t)) \cdot e^{j2\pi f_c t}\} \cdot \cos(\dots) + \sin(\dots)$$

$$= m(t) \cos(2\pi f_c t) \pm \tilde{m}(t) \sin(2\pi f_c t)$$





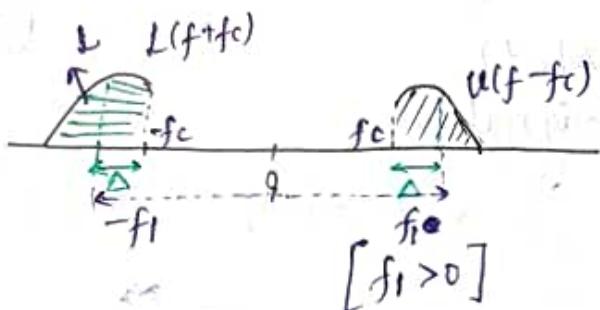
$$\begin{aligned} & F \left\{ m(t) \cos(2\pi f_c t) - \tilde{m}(t) \sin(2\pi f_c t) \right\} \\ &= F \left\{ m(t) \cos(2\pi f_c t) \right\} - F \left\{ \tilde{m}(t) \sin(2\pi f_c t) \right\} \quad u(f-f_c) + L(f+f_c) \\ & \quad \frac{1}{2} M(f-f_c) + \frac{1}{2} M(f+f_c) \end{aligned}$$



$$\frac{1}{2} u(f-f_c) + \frac{1}{2} L(f-f_c) + \frac{1}{2} u(f+f_c) + \frac{1}{2} L(f+f_c)$$

$$\frac{-ju(f-f_c) + jL(f-f_c)}{2j} - \frac{-ju(f+f_c) + jL(f+f_c)}{2j}$$

$$= \frac{-u(f-f_c)}{2} + \frac{L(f-f_c)}{2} + \frac{u(f+f_c)}{2} - \frac{L(f+f_c)}{2}$$



FREQUENCY MODULATION

Review on FM ($PM \equiv FM$)

In FM, how do we get the passband signal?

Instantaneous frequency of the signal,

$$f(t) = \frac{1}{2\pi} \frac{d}{dt} \phi(t) \quad \text{for } A \cos(\phi(t)) \\ \text{or } A \cos(2\pi f_c t + \phi(t))$$

$$f(t) = K_f \cdot m(t)$$

K_f has units Hz/V

$$\phi(0) = 0$$

$$\phi(t) = \cancel{2\pi} \int_0^t K_f m(u) du$$

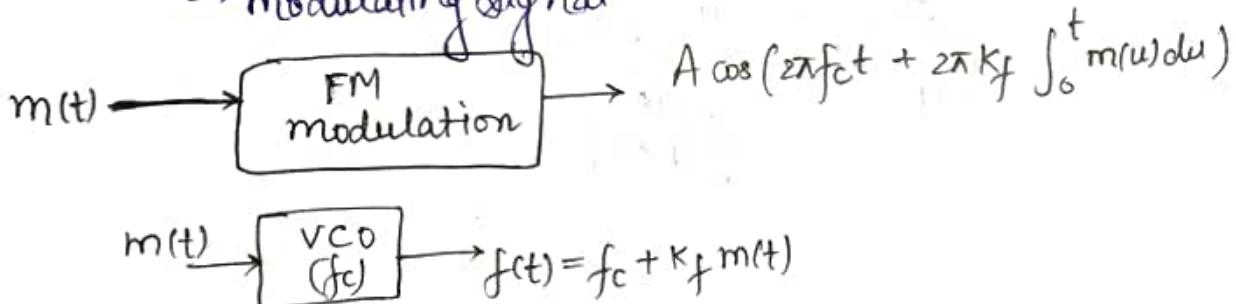
FM signal:

$$A \cos(2\pi f_c t + 2\pi K_f \int_0^t m(u) du)$$

05-09-2024

$$m(t) = A_m \cos(2\pi f_m t)$$

↳ modulating signal



→ FM allows change in BW.

single tone → single frequency

Suppose $m(t) = A_m \cos(2\pi f_m t)$,

$$\text{then FM signal : } A \cos(2\pi f_c t + 2\pi K_f \int_0^t m(u) du)$$

$$= A \cos(2\pi f_c t + 2\pi K_f A_m \frac{\sin(2\pi f_m t)}{2\pi f_m})$$

$$= A \cos(2\pi f_c t + \frac{K_f A_m}{f_m} \sin(2\pi f_m t))$$

$K_f A_m$: equal to max^m frequency deviation.

f_m : equal to BW

$$\beta = \frac{k_f A_m}{f_m}$$

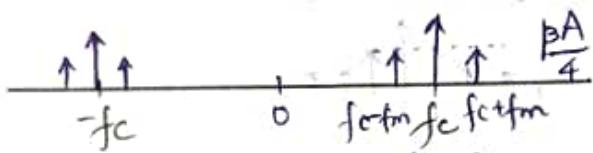
: modulation index

$$\text{FM signal} = A \cos(2\pi f_c t + \beta \sin(2\pi f_m t))$$

$$= A \cos(2\pi f_c t) \cdot \cos(\beta \sin(2\pi f_m t)) - A \sin(2\pi f_c t) \cdot \sin(\beta \sin(2\pi f_m t))$$

$\beta \ll 1$: regime leads to narrow-band FM signals
 $\cos \theta \approx 1, \sin \theta \approx \theta$

$$= A \cos(2\pi f_c t) - A \sin(2\pi f_c t)(\beta \sin(2\pi f_m t))$$



$$\text{Power} = \frac{A^2}{2}$$

(since β is very small, so we can ignore power)
count from $BA/2$

Suppose β is not small,

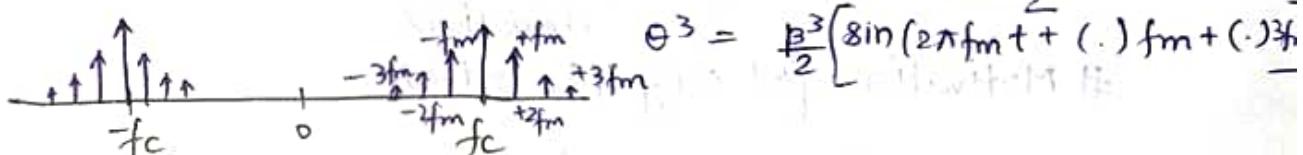
$$\text{then } \cos(\theta) = 1 - \frac{\theta^2}{2!} + \frac{\theta^4}{4!}, \dots$$

$$\sin(\theta) = \theta - \frac{\theta^3}{3!} + \dots$$

$$\text{Here } \theta = \beta \sin(2\pi f_m t)$$

$$\theta^2 = \beta^2 \sin^2(2\pi f_m t)$$

$$= \beta^2 (1 - \cos(4\pi f_m t))$$



Theoretically, FM has infinite BW

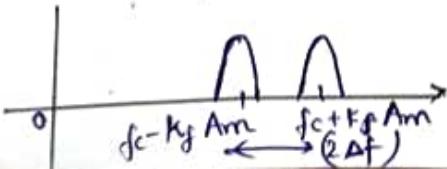
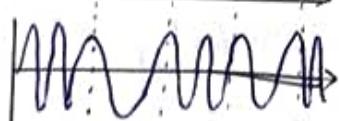
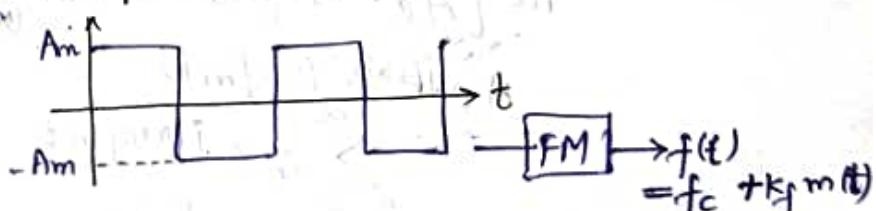
Effective BW: (for any β)

$$\text{One-sided BW} = 2(f_m + \Delta f)$$

↳ Carson's rule for $m(t) = A_m \cos(2\pi f_m t)$

→ For smaller β , $\Delta f = k_f A_m$ will be very small,
so, $\text{BW} = 2f_m$ ($\beta \ll 1$ case)

→ For larger β , $m(t)$:

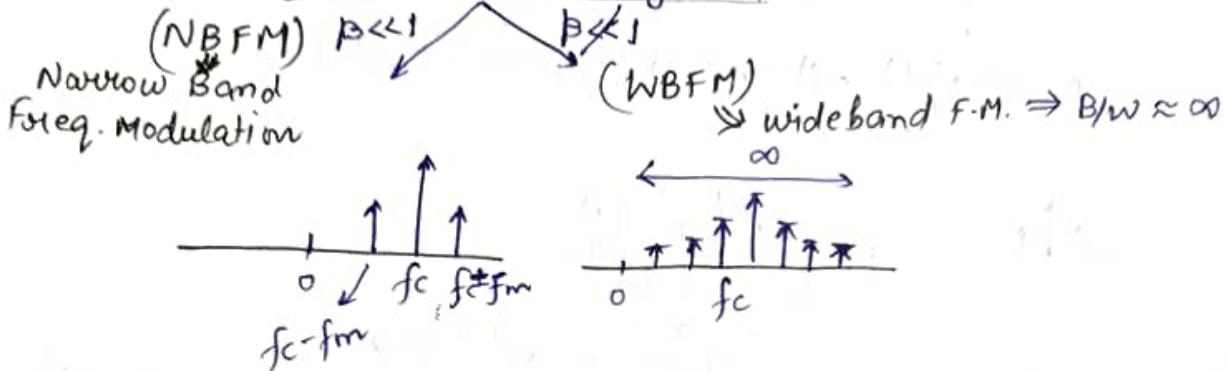


FM Signal Analysis

$$A \cos(2\pi f_c t + 2\pi k_f \int m(u) du)$$

What is the F(.) of this?

$$m(t) = A_m \cos(2\pi f_m t)$$



Curson's Rule:

FM B/W is [one-sided]

$$2\Delta f + 2f_m$$

$k_f A_m$ (max. frequency deviation)

Motivation for why this is true.

F.M. signal for $m(t) = A_m \cos(2\pi f_m t)$

$$A \cos(2\pi f_c t + \beta \sin(2\pi f_m t)) \rightarrow \text{not periodic in general}$$

$f_c \cdot T_p, \} \in \mathbb{Z}_+ \rightarrow \text{Periodic}$
 $f_m \cdot T_p$

$$\operatorname{Re} \left\{ A e^{j2\pi f_c t} e^{j\beta \sin(2\pi f_m t)} \right\}$$

$$A e^{j\beta \sin(2\pi f_m t)}$$

$$= \sum_{n=-\infty}^{\infty} c_n e^{j2\pi n f_m t}$$

$$c_n = A f_m \int_{-\frac{1}{2}f_m}^{\frac{1}{2}f_m} e^{j\beta \sin(2\pi f_m t)} \cdot e^{-j2\pi n f_m t} dt$$

$$\text{Take } u = 2\pi f_m t$$

$$C_n = \frac{1}{2\pi} \int_{-\pi}^{\pi} e^{j(\beta \sin u - nu)} du$$

$$= \frac{1}{2\pi} \int_{-\pi}^{\pi} e^{j(\beta \sin u - nu)} du$$

↓

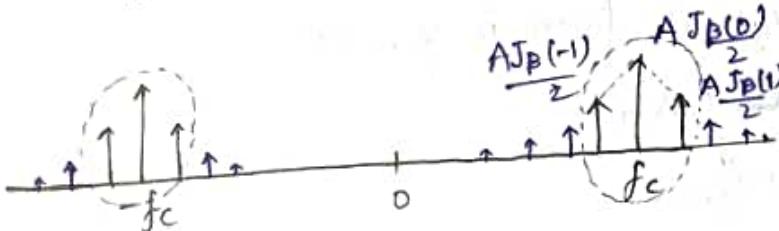
Bessel f^n : $J_\beta(n) \rightarrow n^{\text{th}} \text{ order, 1st kind}$

$$\therefore C_n = A J_\beta(n)$$

$$\sum_{n=-\infty}^{\infty} A J_\beta(n) e^{j2\pi n f_m t}$$

$$(*) = \operatorname{Re} \left\{ \sum_{n=-\infty}^{\infty} A J_\beta(n) \underbrace{e^{j2\pi n f_m t} \cdot e^{j2\pi f_c t}}_{e^{j2\pi(f_c + f_m \cdot n)t}} \right\}$$

$$= \sum_{n=-\infty}^{\infty} A J_\beta(n) \cos(2\pi(f_c + n f_m)t)$$



$\beta \ll 1$:

$$J_\beta(0) = 1$$

$$J_\beta(1) = \beta/2$$

$$J_\beta(n) \approx 0$$

$$\sum_{n=-\infty}^{\infty} J_\beta^2(n) = 1 \Rightarrow \text{Power} = \sum_{n=-\infty}^{\infty} \frac{A^2}{2} J_\beta^2(n)$$

$\therefore \text{FM power} \rightarrow \boxed{A^2/2}$

$$A \cos(2\pi f_c t + 2\pi k_f \int_0^t m(u) du) \rightarrow i(t)$$

$$= A \cos(2\pi f_c t + \beta i(t))$$

$$\cos(2\pi f_c t) - \cos(\beta i(t))$$

$$- \sin(2\pi f_c t) - \sin(\beta i(t))$$

$$i(t) = \boxed{\text{triangle}}$$

$$i^2(t) = \boxed{\text{triangle}}$$

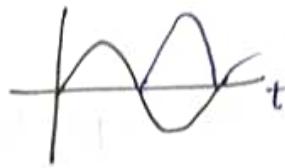
$$i^3(t) = \boxed{\text{bell}}$$

For a general signal $m(t)$,

$$2\Delta f + 2(Bm/2)$$

$$\downarrow$$

$$K_f \frac{\max|m(t)|}{t}$$



10-09-2024

FM - transmitter

(modulation schemes)

Recall

$$\text{FM signal: } A \cos(2\pi f_c t + 2\pi K_f \int_0^t m(u) du)$$

Spectrum

→ no analytical form in general

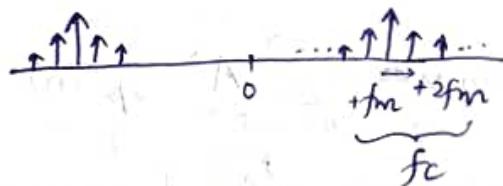
$$m(t) = Am \cos(2\pi f_m t)$$

$$\beta = K_f A_m / f_m$$

$\beta \ll 1$: NBFM - like DSB + carrier

$\beta \gg 1$: WBFM

$$\sum A J_n(\beta) \cos(2\pi(f_c + n f_m)t)$$



Carson's Rule:

$$2\Delta f + 2f_m$$

\downarrow
 $K_f A_m$: max^m freq. deviation

General $m(t) \rightarrow B_m$ (2 sided)

$$\beta = \Delta f / (B_m/2)$$

$$2\Delta f + B_m$$

Power is $\frac{A^2}{2}$.

FM modulators
 f_c, β, A

Direct methods

Indirect methods

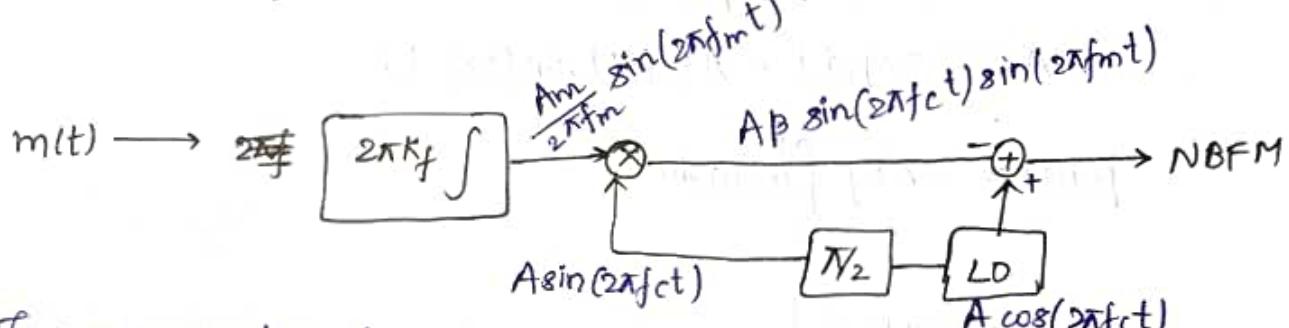
Indirect methods



How can you generate a NBFM signal?

Eg. For $A_m \cos(2\pi f_m t)$ as $\propto m(t)$

$$A \cos(2\pi f_c t) - A\beta \sin(2\pi f_c t) \sin(2\pi f_m t)$$



For a general $m(t)$,

$$A \cos \left(2\pi f_c t + 2\pi f_f \int_0^t m(u) du \right)$$

$\underbrace{\qquad\qquad\qquad}_{\frac{A_{\max}}{\pi B_m}}$

$$A \cos \left(2\pi f_c t + \frac{\beta}{B_m} \overrightarrow{A_{\max} i(t)} \right)$$

$$A (\cos(2\pi f_c t) \cdot \cos(\beta i(t)) - \sin(2\pi f_c t) \cdot \sin(\beta i(t)))$$

FM signals have constant envelope.

if $\beta \ll 1$



FM Transmitter / Signal Generation

FM signal: Tx power, BW, Band channel
 (A) (B) (C)

$\beta \ll 1$: Narrowband FM

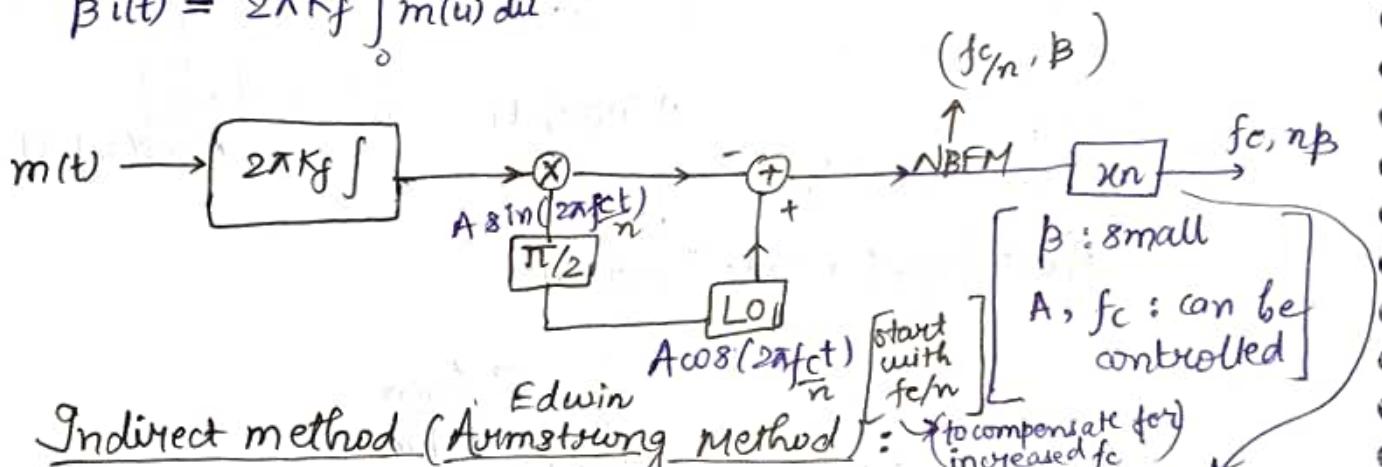
$\beta \not\ll 1$: Wideband FM

NBFM: $m(t)$

$$\begin{aligned} & A \cos(2\pi f_c t + 2\pi K_f \int_0^t m(u) du) \\ &= A \cos(2\pi f_c t + \beta i(t)) \\ &= A \cos(2\pi f_c t) - A \beta i(t) \sin(2\pi f_c t) \end{aligned}$$

$$\beta i(t) = 2\pi K_f \int_0^t m(u) du$$

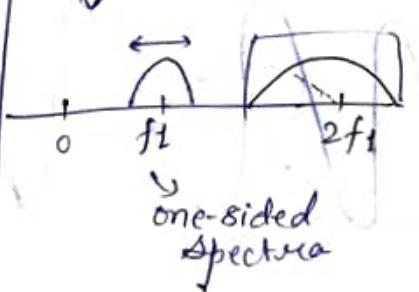
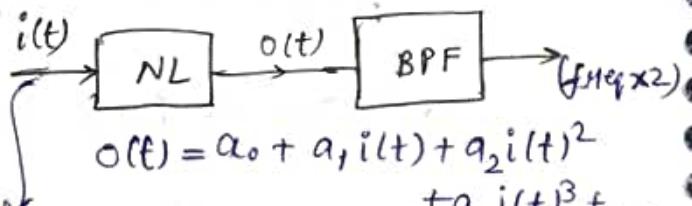
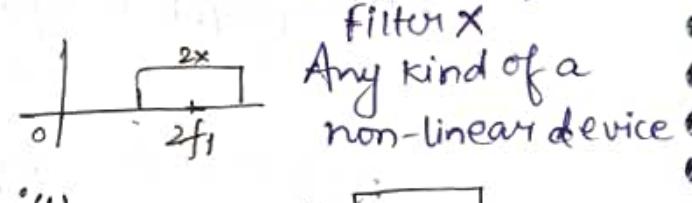
$$|i(t)| < p$$



Indirect method (Armstrong Method): Edwin

$$A \cos(2\pi f_c t + \frac{\Delta f}{B_m/2} i(t))^2$$

$\phi(t)$

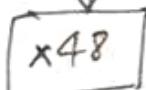
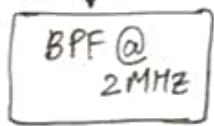
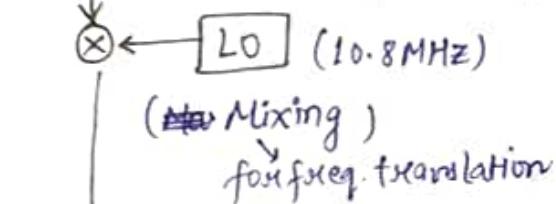
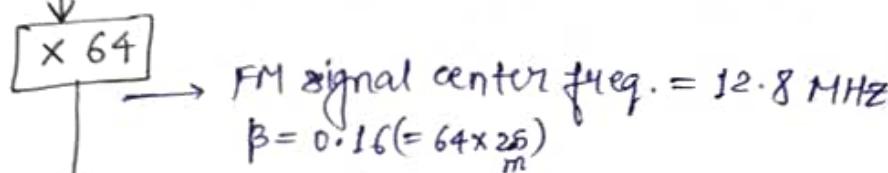
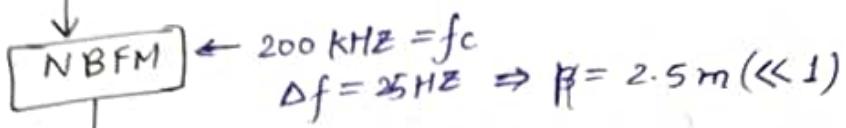


$$\xrightarrow{x_2} \dots \xrightarrow{x_2} \xrightarrow{\text{sum}} x^{2^n}$$

$$\xrightarrow{x_3} \dots \xrightarrow{x_3} \xrightarrow{\text{sum}} x^{3^n}$$

Example of an indirect FM generation:

$$m(t) = \frac{B_m}{2} = 10 \text{ kHz}$$



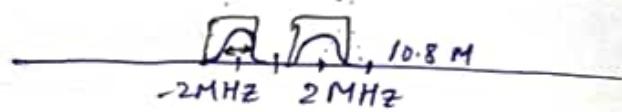
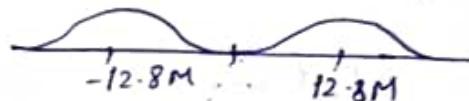
$$\text{FM signal } f_c = 2 \text{ MHz} \times 48 = 96 \text{ MHz}$$

β is now 7.6 ($= 0.16 \times 48$)

$$\Delta f = \beta \times \frac{B_m}{2} \approx 80 \text{ kHz}$$

NBFM:

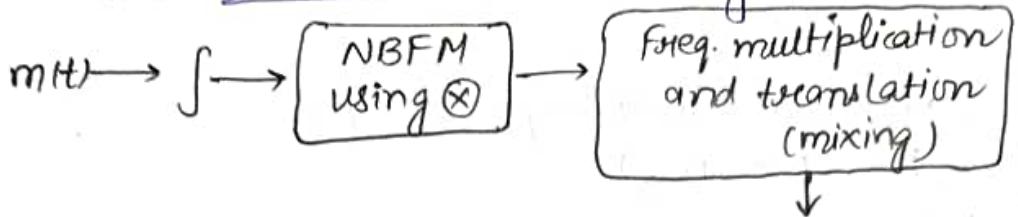
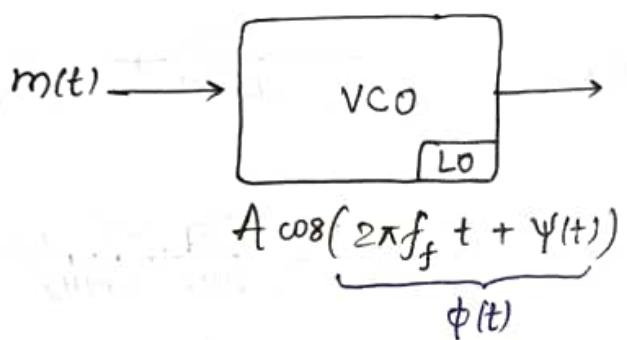
$$BN \approx \frac{2}{\pi} \times \Delta f + \sqrt{\frac{B_m}{2}} = 3200 + 20 \text{ K}$$



FM generation

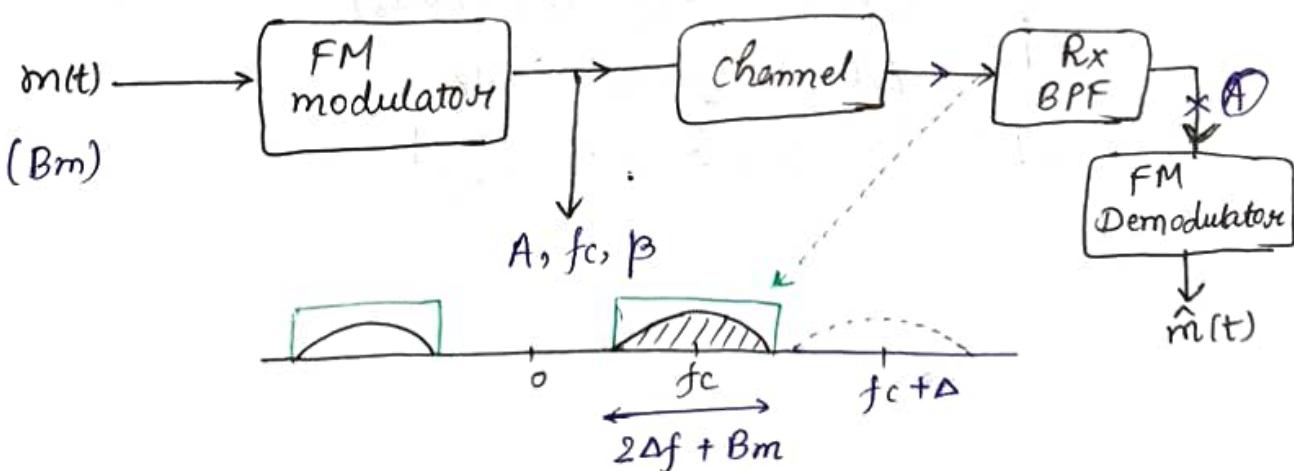
need Tx power - A
BW - B

Band/channel - f_c

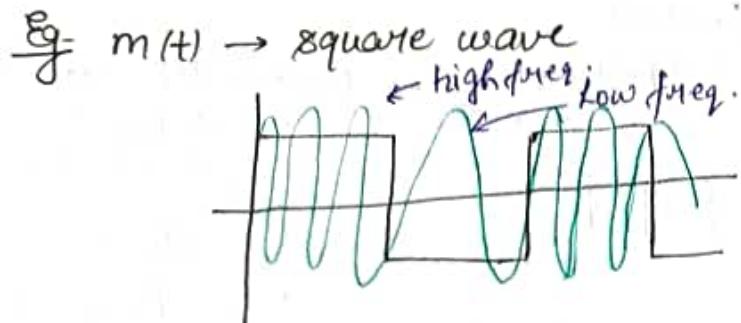
Indirect - method (Armstrong '8):Direct method:

f_f : free running frequency of the VCO ($m(t)=0$)

$$\frac{1}{2\pi} \frac{d\phi(t)}{dt} = f_f + \underbrace{\frac{1}{2\pi} \frac{d}{dt} \psi(t)}_{K_f m(t)}$$

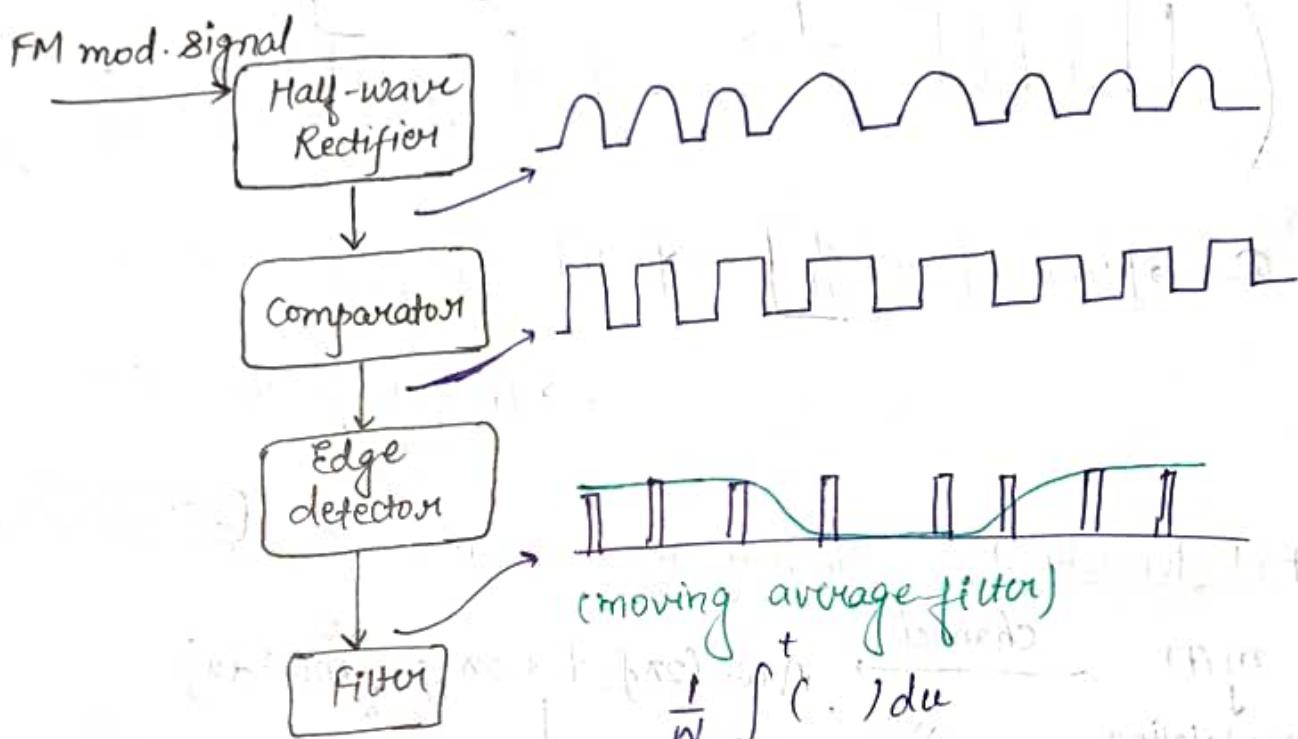
FM-demodulation:

$$A \cos(2\pi f_c t + 2\pi K_f \int_0^t m(u) du)$$

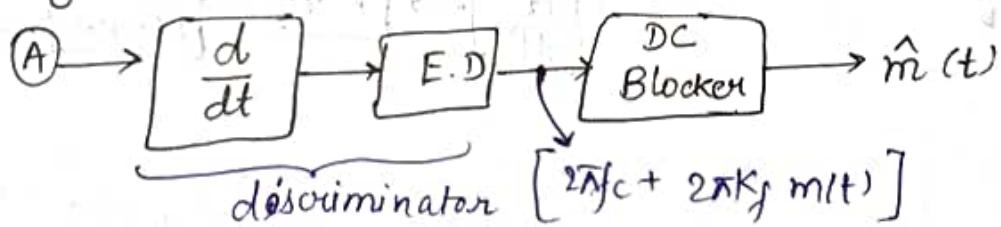


Get the square wave from sinusoids.

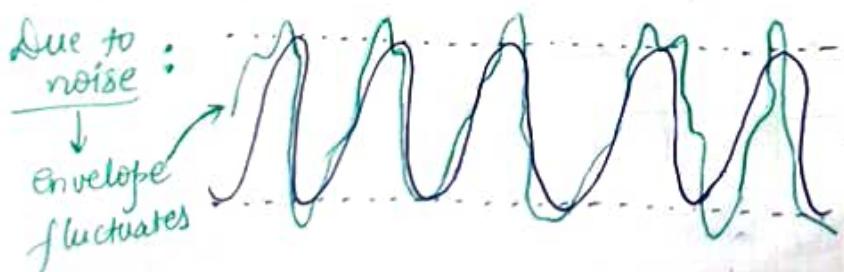
(Pulse/Peak) counting method for FM demodulation:



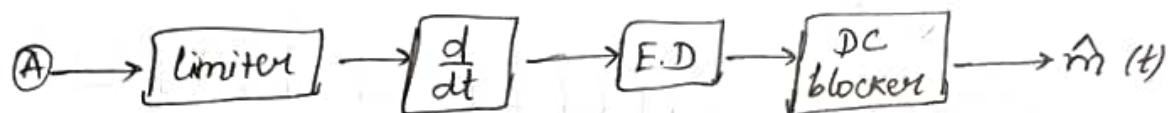
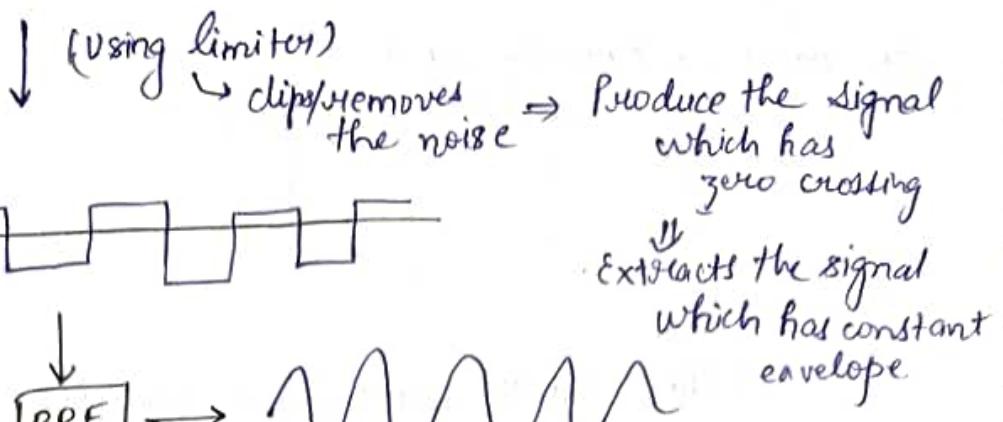
Using differentiator:



$$\begin{aligned} \frac{d}{dt} \left[A \cos(2\pi f_c t + 2\pi K_f \int_0^t m(u) du) \right] \\ \text{constant envelope} = A \sin(2\pi f_c t + 2\pi K_f \int_0^t m(u) du) \times ([2\pi f_c + 2\pi K_f m(t)]) \end{aligned}$$



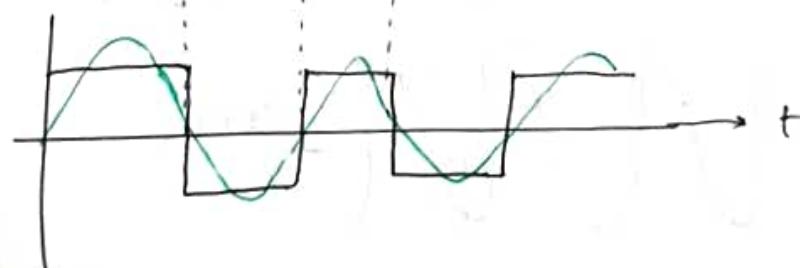
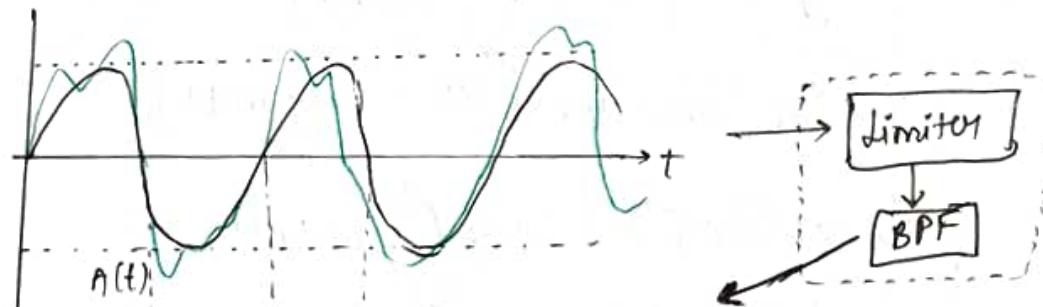
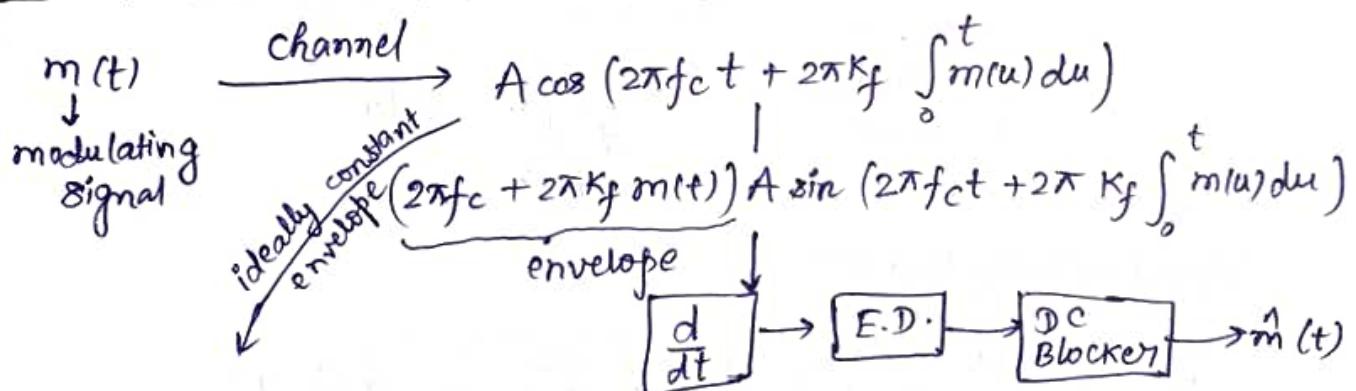
Using limiter



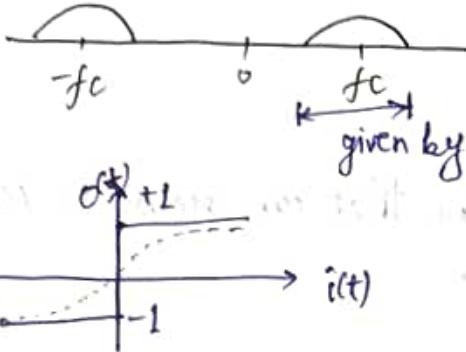
↳ Limiter-discriminator method

(20-09-2024)

FM demodulation : Limiter-discriminator method:



$$i(t) = A \cos(2\pi f_c t + 2\pi K_f \int m(u) du) \rightarrow \boxed{\text{sgn } (\cdot)} \downarrow 0$$

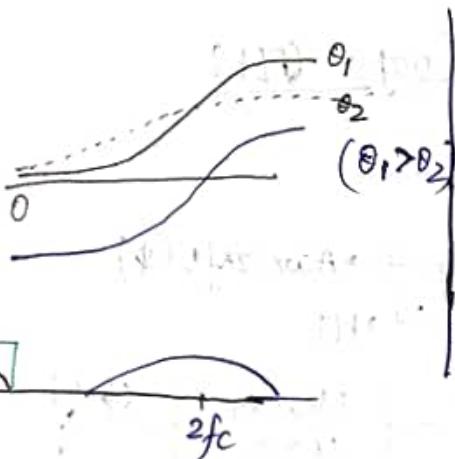


Non-linear: (Mapping)

$$o(t) = a_0 + a_1 i(t) + a_2 i(t)^2 + a_3 i(t)^3$$

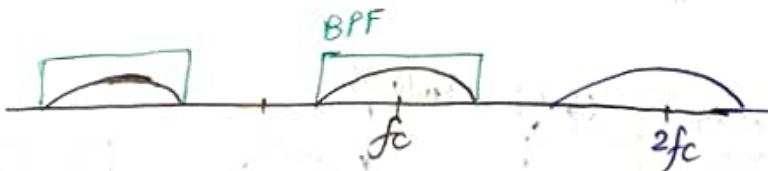
Approximation:

$$\left(\frac{1}{1+e^{-\theta_1}} - \frac{1}{2} \right)^2$$



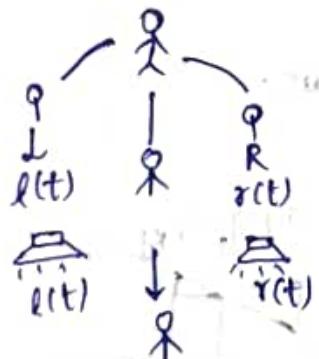
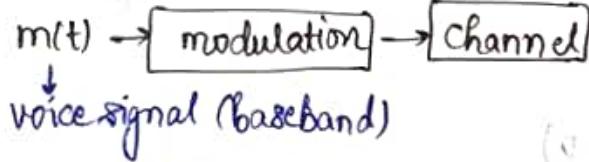
$$\begin{cases} \frac{1}{1+e^{-\theta_1}} \\ \frac{1}{1+e^{-\theta_2}} \end{cases}$$

Sigmoid function
(Activation fn)



01-09-2024

FM : Phase Locked Loop Demodulation



Stereo Signals:

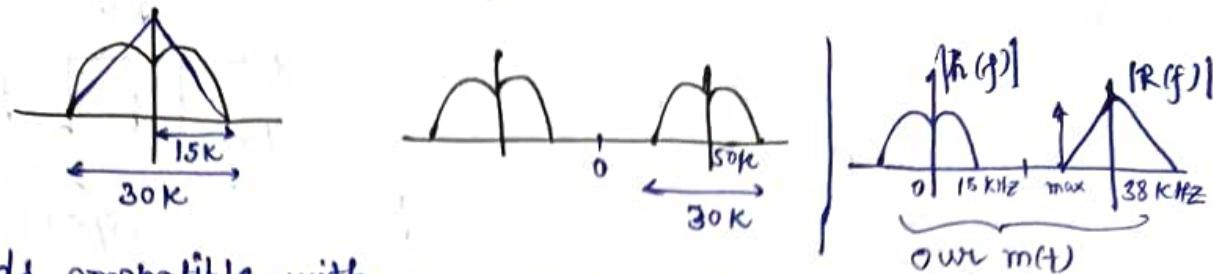
$l(t), r(t)$: two baseband signals

15 kHz
(1-sided BW)

Reading Assignment:
Broadcast FM → Upamony Madhan book

→ Modulator needs a baseband signal.

An idea:



→ Backwards compatible with a mono receiver.

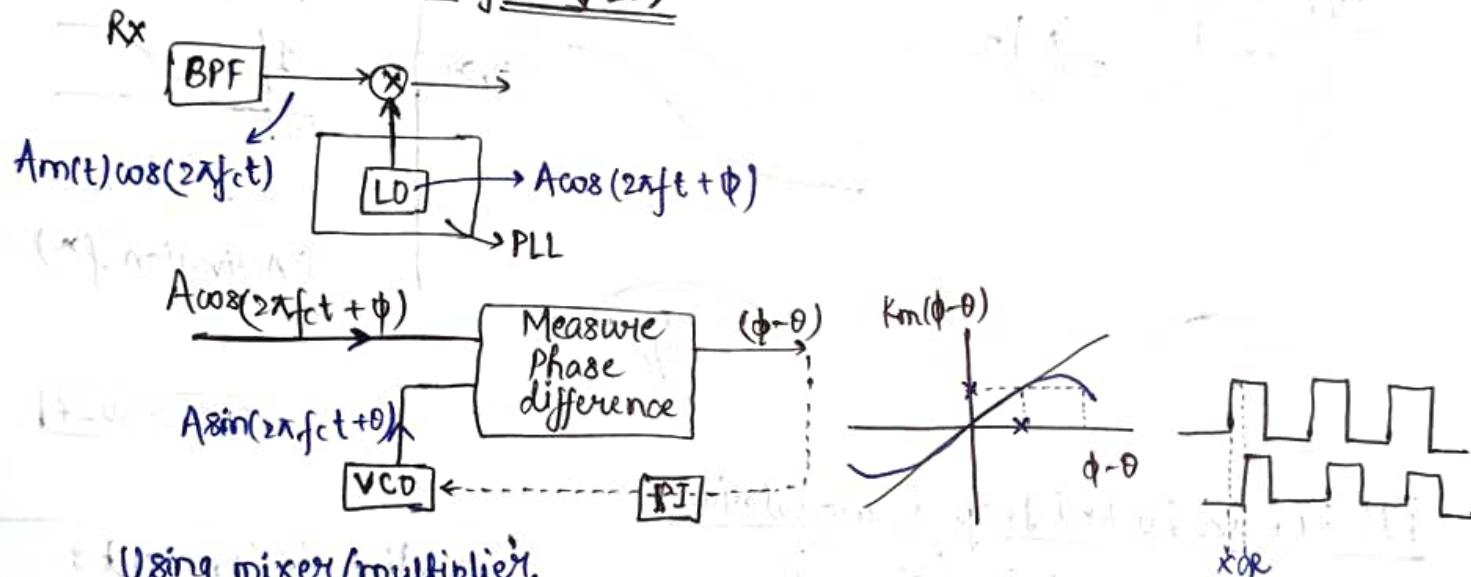
In the actual stereo-FM system

$$l(t) + m(t) = u(t)$$

$$l(t) - m(t) = v(t)$$

Eg. Draw and discuss a block diagram that can recover $l(t)$ and $m(t)$ from the received FM signals.

Phase Locked Loops (PLL)



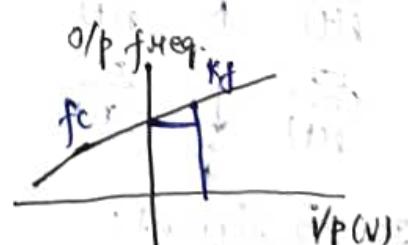
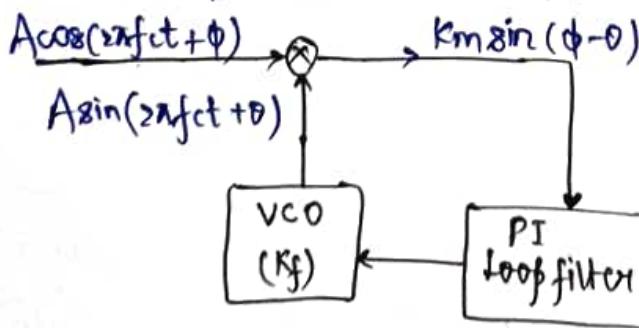
Using mixer/multiplier,

$$A \cos(2\pi f_c t + \phi) A \sin(2\pi f_c t + \theta)$$

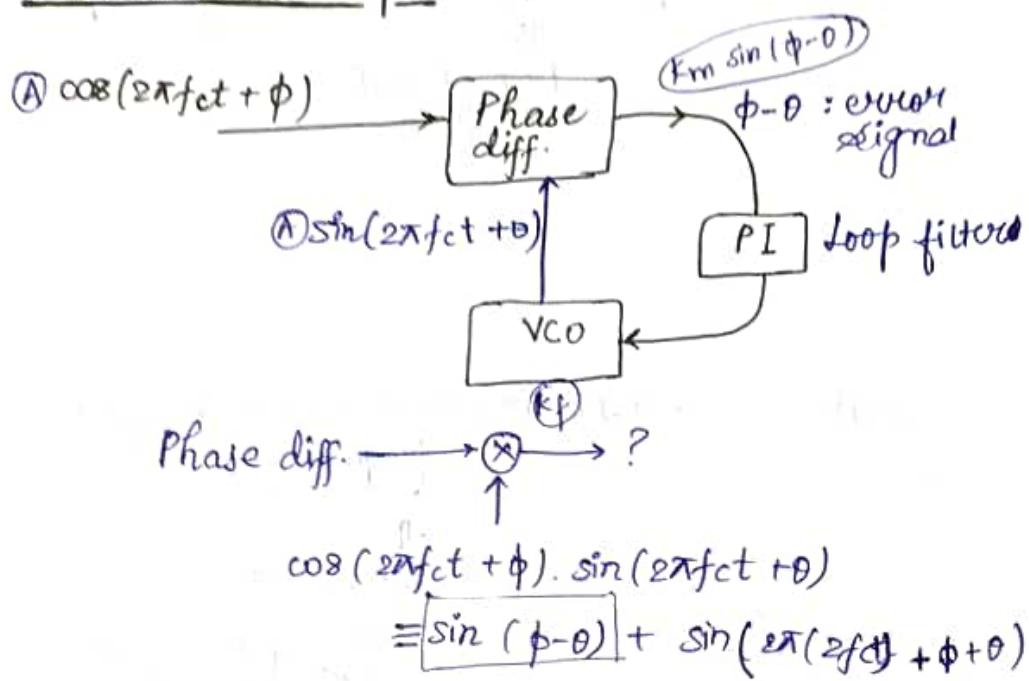
$$A^2 \sin(\phi - \theta) + A^2 \sin(4\pi f_c t + \phi + \theta)$$

↪ Not linear function of $(\phi - \theta)$

for $2\phi - \theta$ values, we get some value.



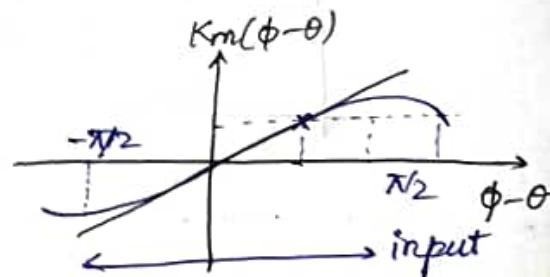
Phaselocked Loops



Ideal phase differentiator: memoryless

$$\cos(2\pi f_{ct} t + \phi) \xrightarrow{\otimes} \phi - \theta$$

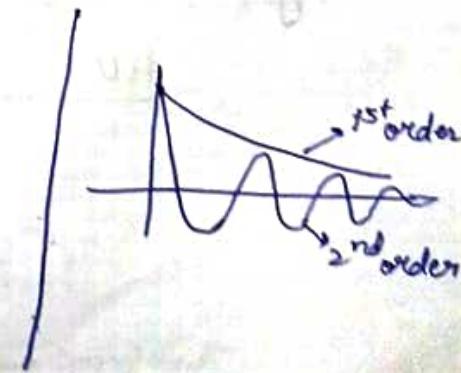
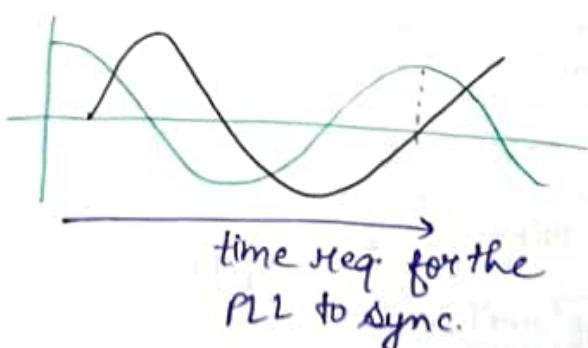
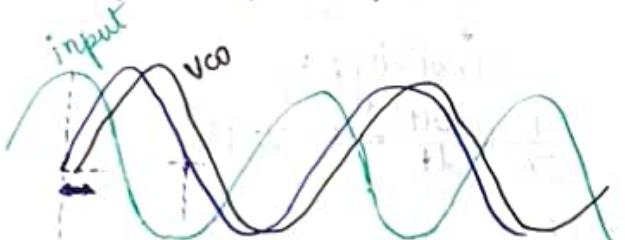
$\sin(2\pi f_{ct} t + \theta)$

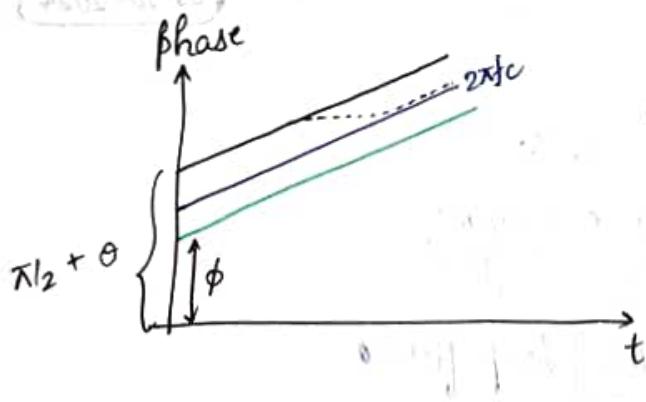


VCO

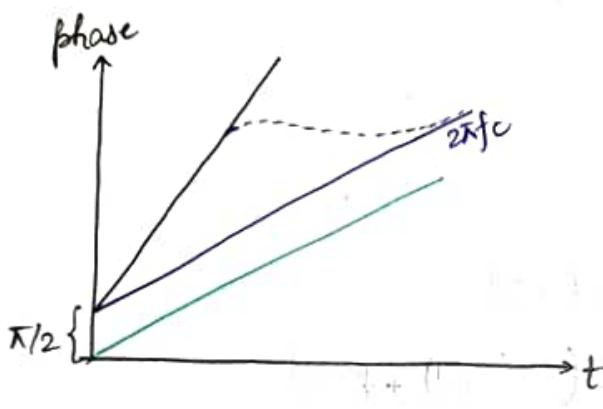
$$v_i(t) \xrightarrow{\text{VCO}} \sin(2\pi f(t) \cdot t)$$

$$f(t) = f_f + K_v \cdot v_i(t)$$

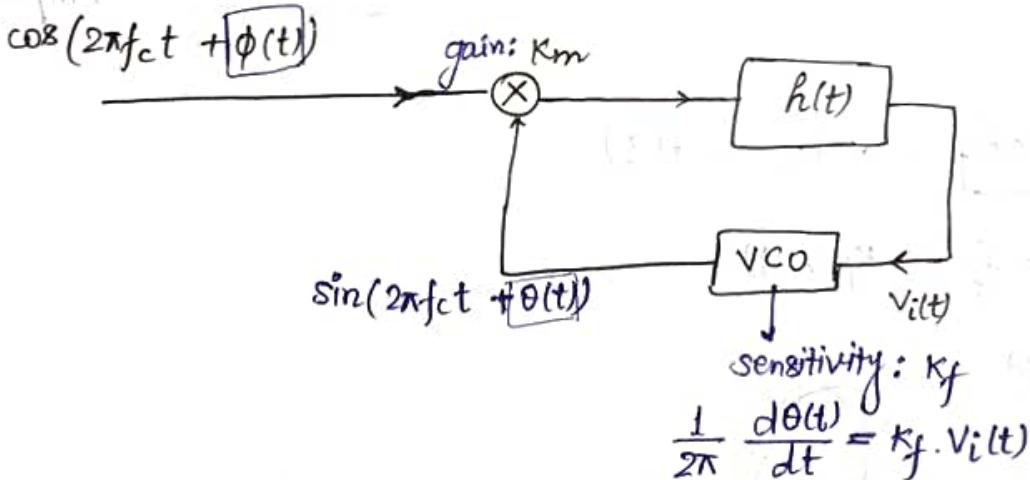
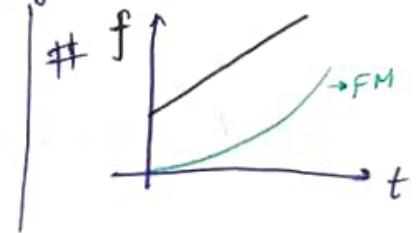
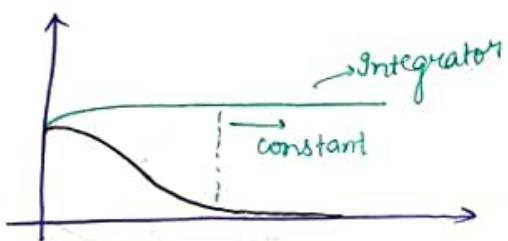




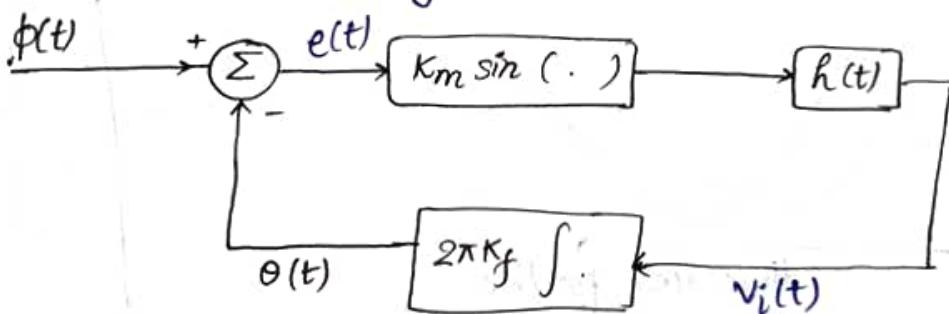
→ PLL is able to track change in phase
 ↓
 Proportional filter



→ PLL is able to track change in frequency
 ↓
 Integrator



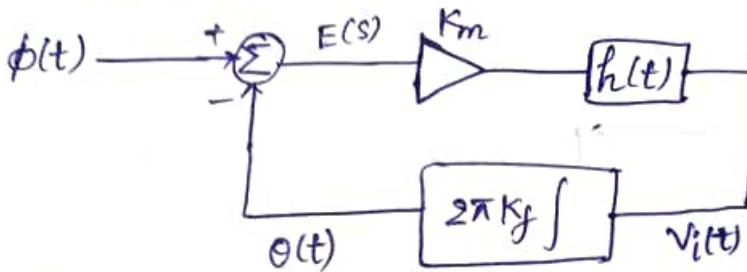
Signals which are interesting:



$$\begin{aligned}
 e(t) &= \phi(t) - \theta(t) \\
 &= \phi(t) - 2\pi K_f \int v_i(t) dt \\
 &= \phi(t) - 2\pi K_f \int_0^t \left(\int_0^u h(\tau) \cdot K_m \sin(e(u-\tau)) \cdot d\tau \right) du \\
 \Rightarrow \frac{de(t)}{dt} &= \frac{d\phi(t)}{dt} - 2\pi K_f \int_0^t (h(\tau) \cdot K_m \sin(e(t-\tau))) d\tau
 \end{aligned}$$

Small error analysis:

$$e(t) \approx 0.$$



Laplace domain: $\phi(s)$, $\theta(s)$, $H(s)$.

$$\begin{aligned}
 E(s) &= \phi(s) - \theta(s) \\
 &= \phi(s) - \frac{2\pi K_f K_m \cdot H(s) E(s)}{s}
 \end{aligned}$$

$$\begin{aligned}
 \Rightarrow E(s) &= \frac{s\phi(s)}{s + 2\pi K_f K_m H(s)} \\
 &= \frac{s\phi(s)}{s + K H(s)}
 \end{aligned}$$

Case: $H(s) = 1$.

$$E(s) = \frac{s\phi(s)}{s + K}$$

i) $\phi(t)$:

$$\frac{\Delta}{s} \xrightarrow[0]{\Delta} t$$

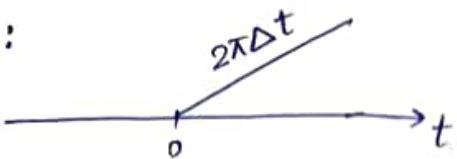
$$\phi(s) = \Delta/s$$

$$\therefore E(s) = \frac{\Delta}{s + K}$$

$$e(t) : \Delta e^{-Kt}$$

$$v_i(t) : \frac{K_m \Delta e^{-Kt}}{Km} \xrightarrow{\text{integrate}} \text{constant}$$

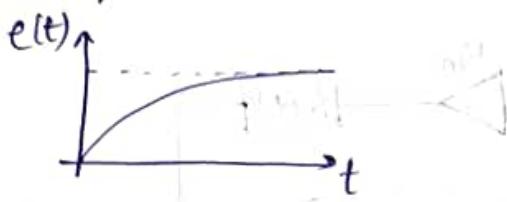
⑩ $\phi(t)$:



$$E(s) = \frac{s(2\pi\Delta/s^2)}{s+k}$$

$$= \frac{2\pi\Delta}{s(s+k)}$$

$$\Rightarrow e(t) = \frac{2\pi\Delta}{k} (1 - e^{-kt})$$



Case: $H(s) = 1 + a/s$

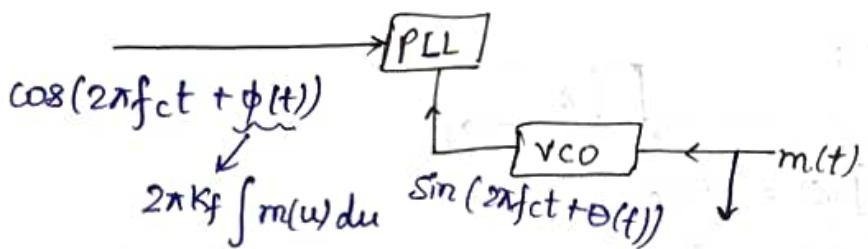
$$E(s) = \frac{s^2 \cdot 2\pi\Delta/s^2}{s^2 + ks + ka}$$

$$= \frac{2\pi\Delta}{s^2 + ks + ka}$$

$e(t)$: Diminishing sinusoid



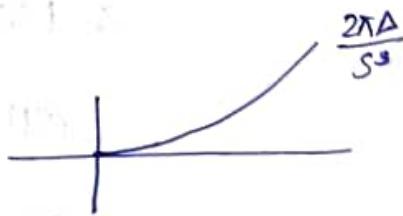
FM demodulation



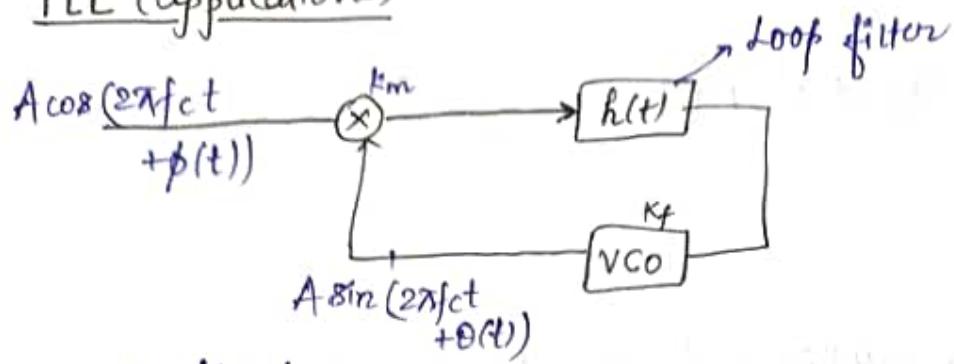
$$\phi(t) - \theta(t) = e$$

$$\text{Suppose } \phi(s) = \frac{2\pi\Delta}{s^3}$$

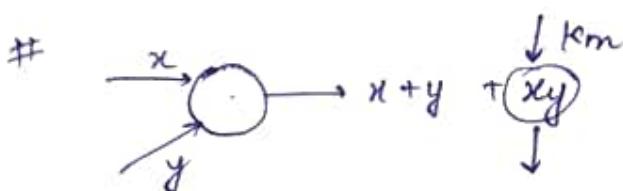
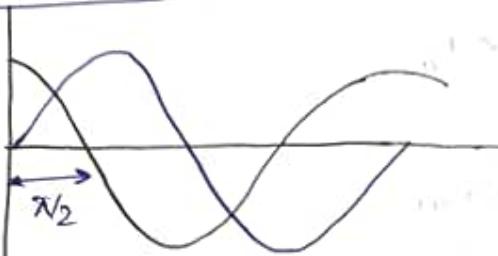
$$E(s) = \frac{2\pi\Delta/s}{s^2 + ks + ka}$$



PLL (applications)



Under 'lock'



DSB demodulation

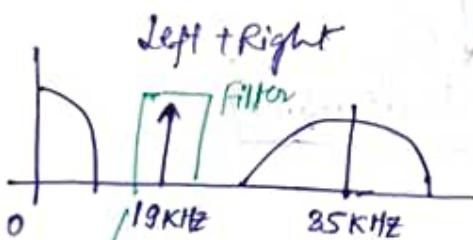
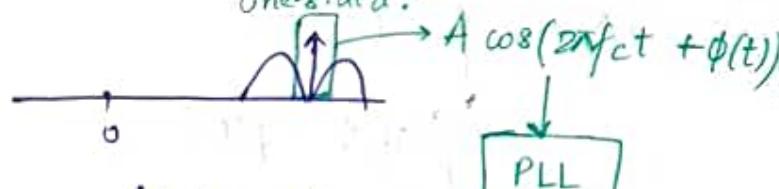
$$A m(t) \cdot \cos(2\pi f_c t + \phi(t))$$

Error signal:

$$A m(t) \sin(\phi(t) - \theta(t))$$

$$\# A (1 + \alpha_m(t)) \cdot \cos(\omega_0 t + \phi(t))$$

one-sided:



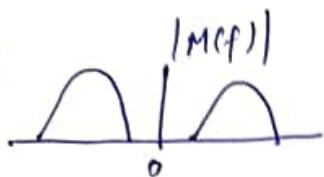
Can use PLLs if we have a pilot signal easily!

$$A^2 m(t)^2 \cos^2(2\pi f_c t + \phi(t))$$

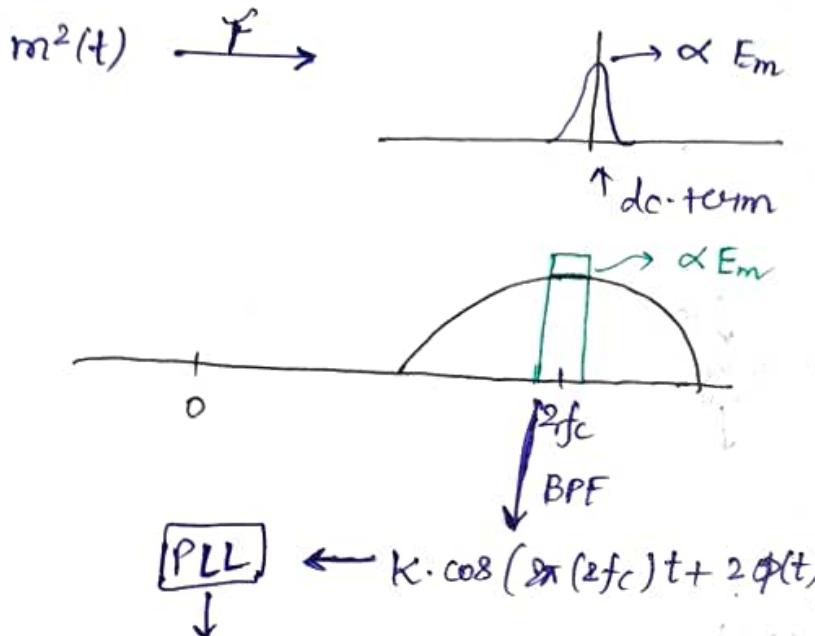
@ $2f_c$

$$A^2 m(t)^2 \cos(2\pi(2f_c)t + 2\phi(t)).$$

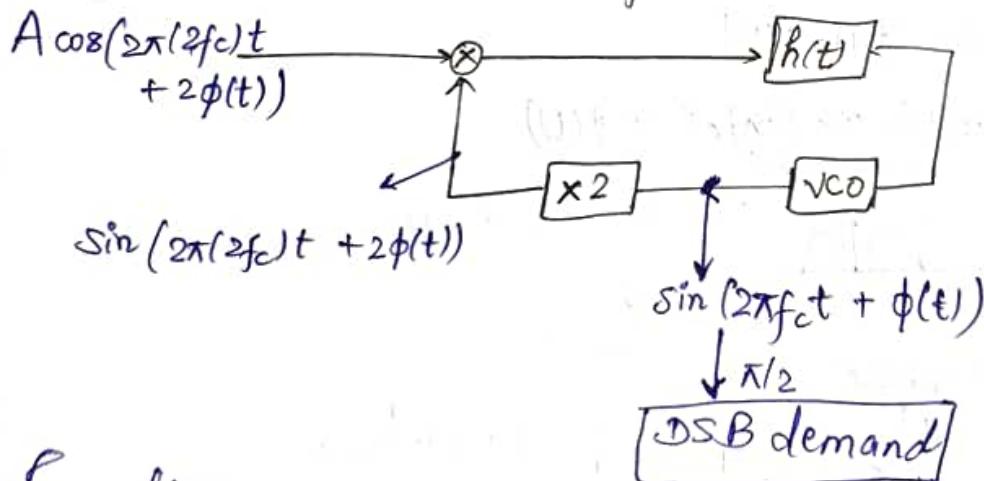
$m(t)$:



↳ no dc-term $m(t)$ is a baseband voice-signal.

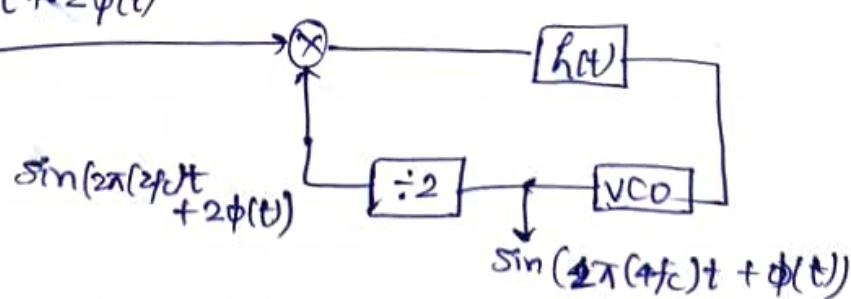


Frequency division and multiplication:



freq. division:

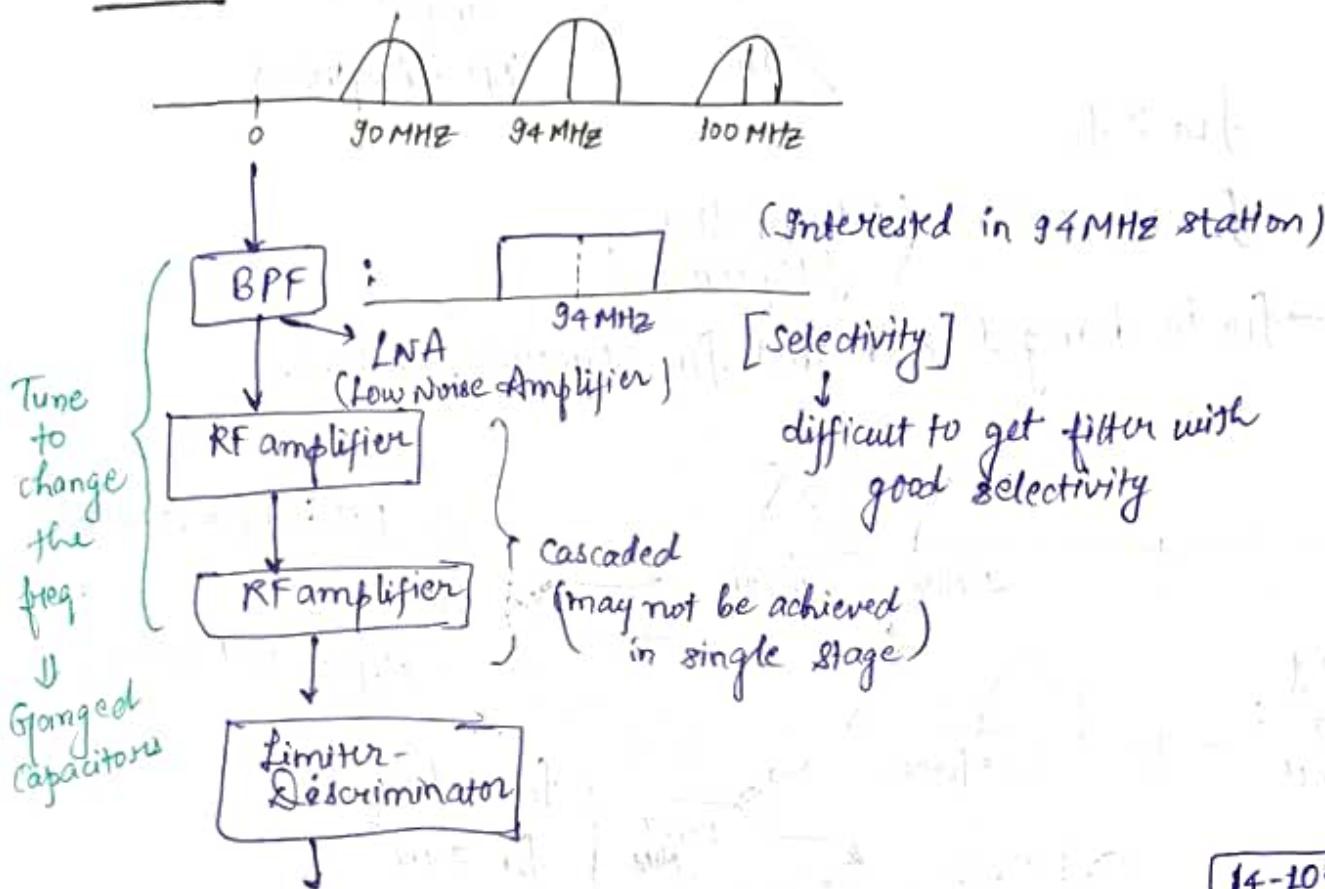
$$A \cos(2\pi(2f_c)t + 2\phi(t))$$



Receiver Architectures

- Tuned RF (TRF) (old)
- Superheterodyne (old)
- Zero IF architecture

TRF

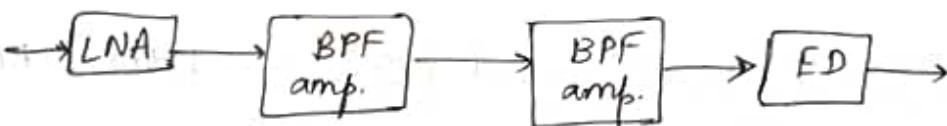


TRF

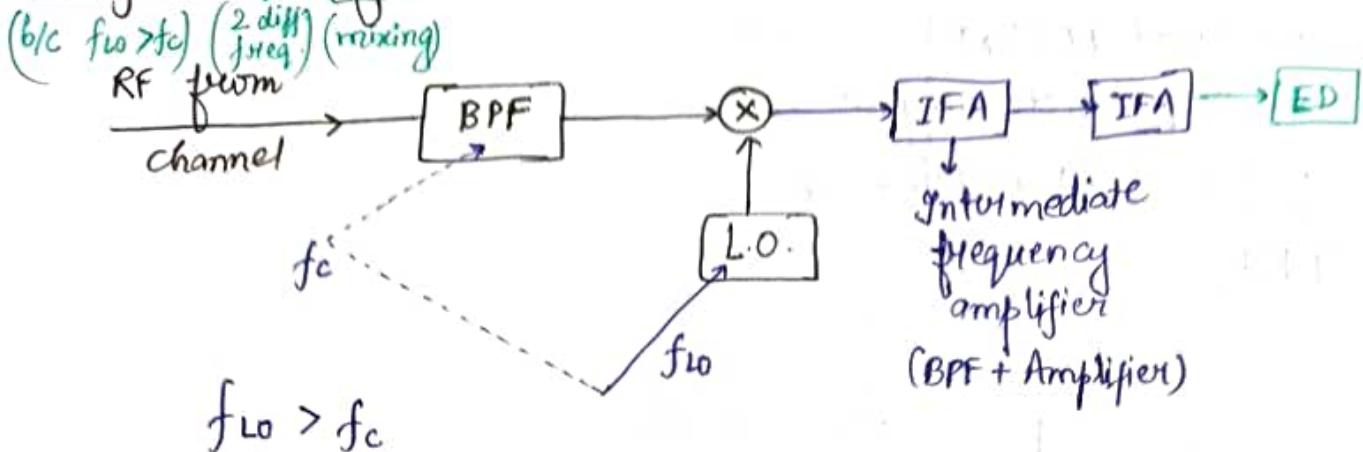
↳ for fixed channel

↳ if tuning, joint/ganged tuning of all stages together.

↳ Rx selectivity

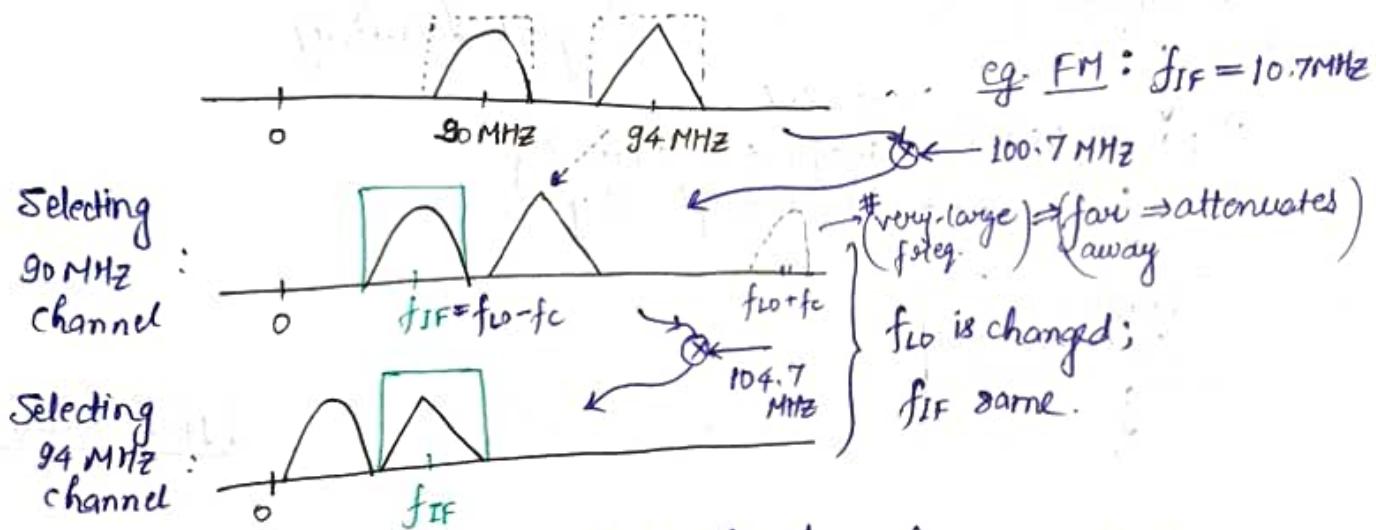


Superheterodyne Architectures



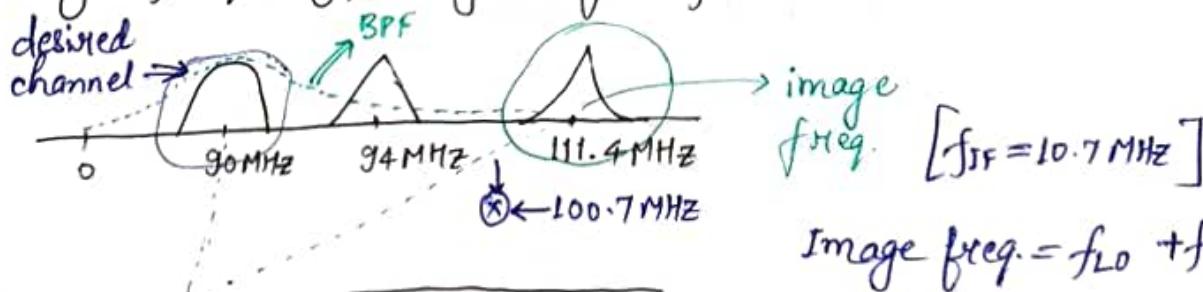
$$f_{LO} - f_c = f_{IF} \text{ (intermediate frequency)}$$

$\rightarrow f_{L0}$ is changed such that f_{IF} remains constant.



- IFA or filter to select the channel.
 - Working at a lower ~~center~~ fixed ^{intermediate} center frequency (f_{IF}).
 - Compared to IRF, it is easier to make selective filters.
 - Works even without BPF; required to cutoff noise.

Image frequency / Image signal problem: Without BPF



$$\text{Image freq.} = f_{LO} + f_{IF}$$

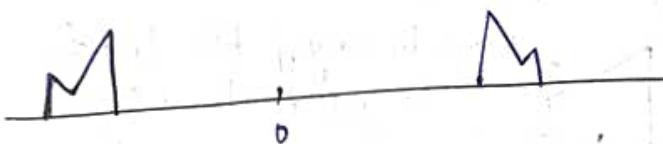
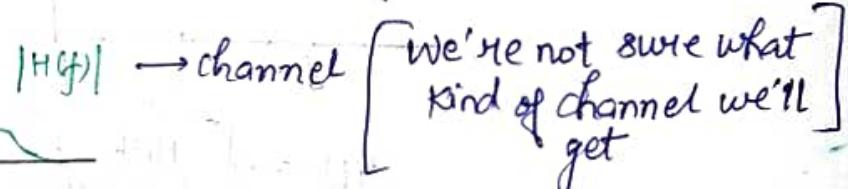
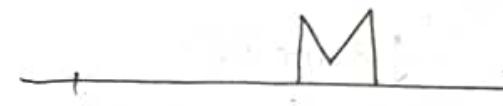
o 10.7 MHz \leftarrow Both desired & image freq.
shifted to immediate intermediate freq.

BPF (frontend) : Removes the image signal

- ↳ Need not be very selective.
- ↳ easier to design than TRF, where BPF is very selective.

Zero IF : Homodyne (tuning of same frequency)

- ↳ $f_{IF} = 0 \Rightarrow f_{LO} = f_c \Rightarrow$ DSB Receiver (But tunable)



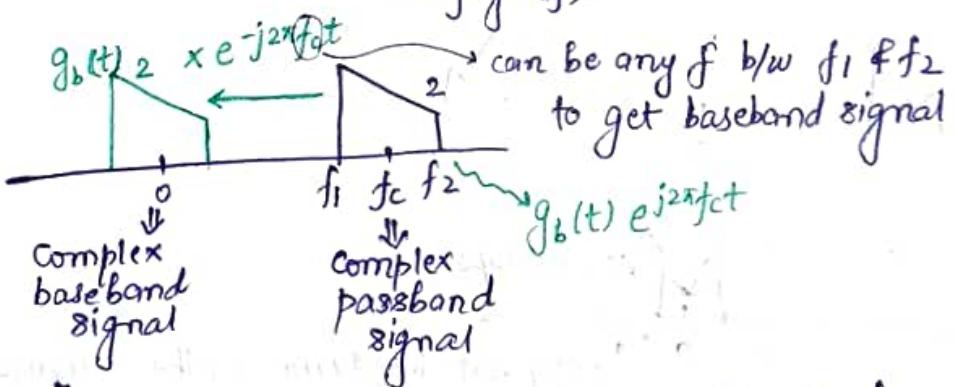
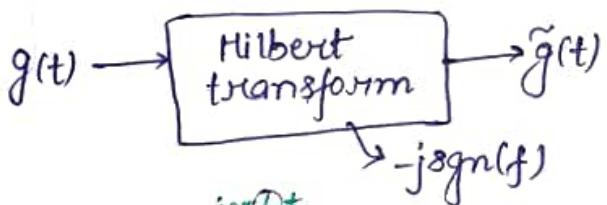
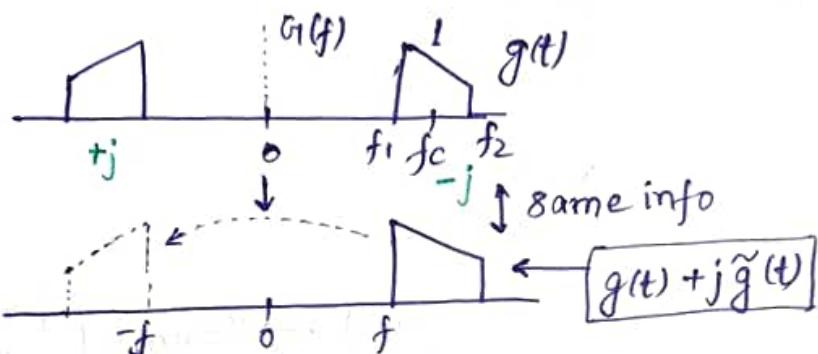
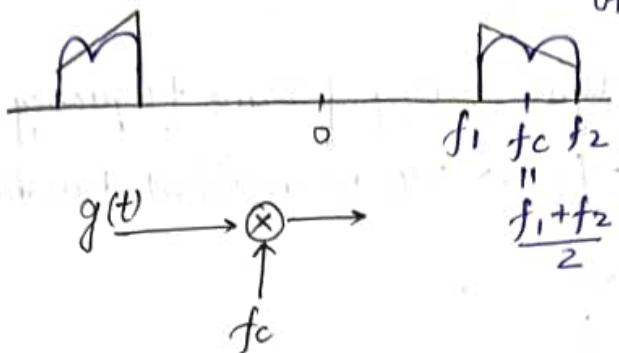
$M \rightarrow$ overlaps

\rightarrow may not be same as the original signal (M).

Zero IF: Complex Baseband Representation

A general passband signal (Real!):

$$g(t) = G(f)$$



Complex baseband representation of a passband signal.

$$g_b(t) e^{j2\pi fct}$$

$$\operatorname{Re}\{g_b(t) e^{j2\pi fct}\} = g(t)$$

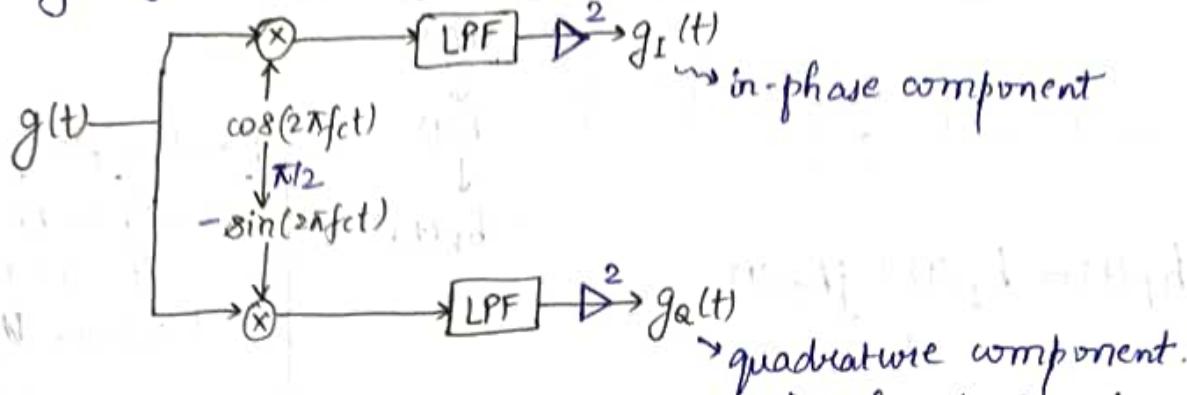
$$g_I(t) + jg_Q(t)$$

baseband signals

$$= g_I(t) \cos(2\pi fct) - g_Q(t) \sin(2\pi fct) = g(t).$$

of passband signal.
I → In-phase-quadrature (IQ) representation ^

To get $g_I(t)$, $g_Q(t)$ from $g(t)$, we multiplexing.



→ Converting a passband signal to a baseband signal, makes it easy to do signal processing with it by converting it to digital signal and making use of software.

$$\{g_I(t)\cos(2\pi f_c t) - g_Q(t)\sin(2\pi f_c t)\} \times \frac{e(t)}{e(t)}$$

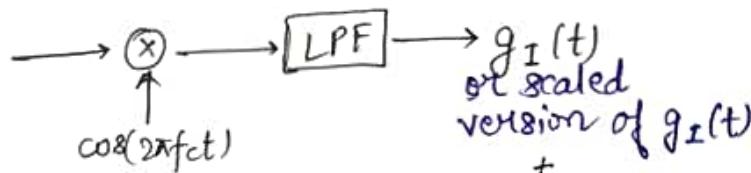
$$| e(t) = \sqrt{g_I^2(t) + g_Q^2(t)} |$$

$$| \alpha(t) = \tan^{-1}\left(\frac{g_Q(t)}{g_I(t)}\right) |$$

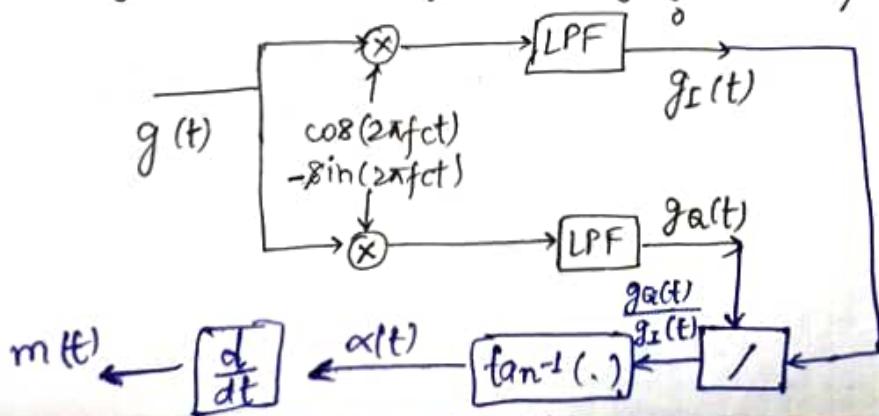
$$= \underbrace{e(t)\cos(2\pi f_c t + \alpha(t))}_{\text{envelope}} = g(t) : \begin{array}{l} \text{Envelope-phase} \\ \text{representation} \\ \text{of a passband signal.} \end{array}$$

Zero IF Receivers

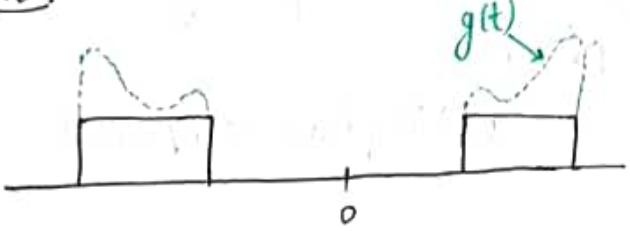
$$\textcircled{1} \quad g(t) = A_m(t) \cos(2\pi f_c t)$$



$$\textcircled{2} \quad g(t) = A \cos(2\pi f_c t + 2\pi K_f \int_0^t m(u) du)$$

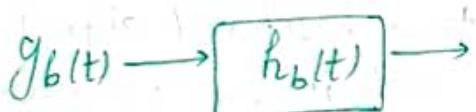


System:



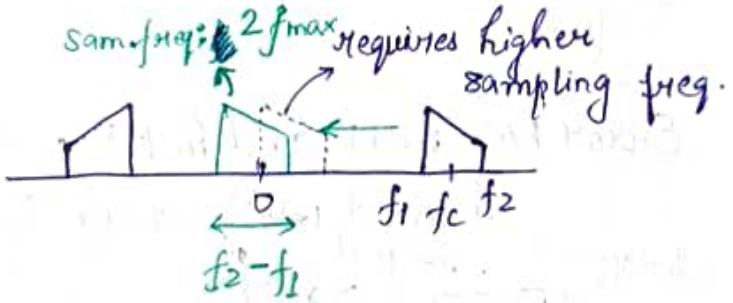
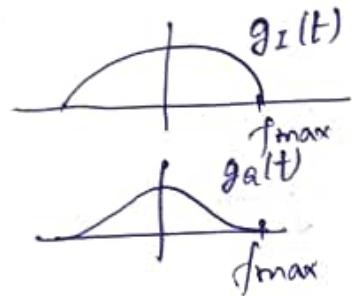
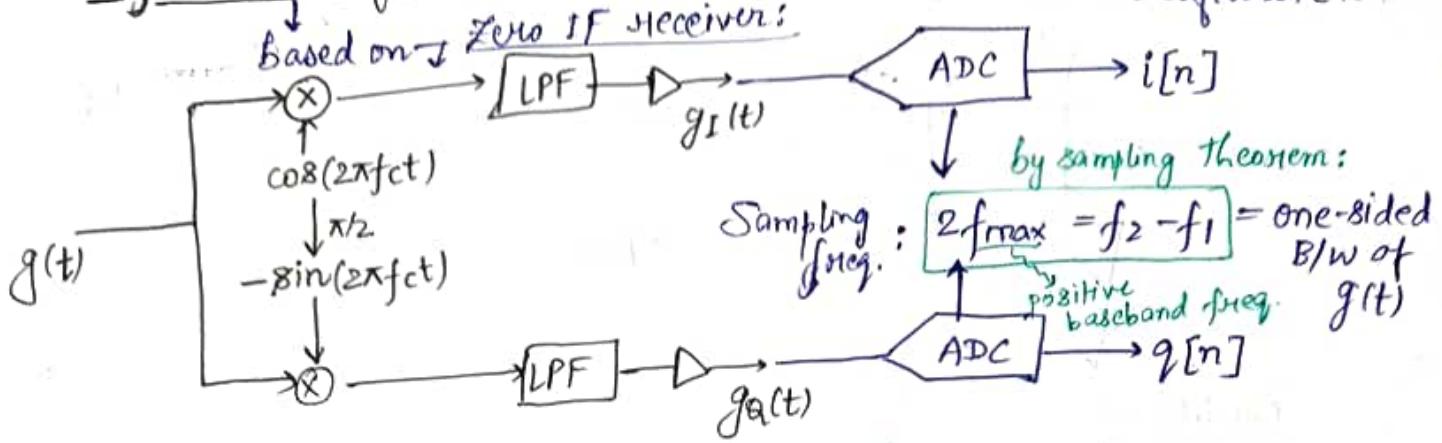
$$\begin{array}{c} H(f) \\ \downarrow \\ h(t) \\ \downarrow \\ h_b(t) \end{array}$$

$$h_b(t) = h_I(t) + j h_Q(t)$$

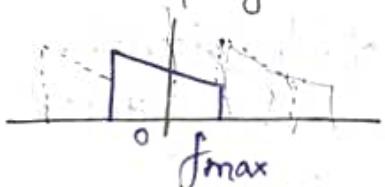


Reading Assignment:
complex BB rep.
of system
↳ source: M. Modha
Simon Haykin
books

Software defined Radio (Receiver): Implemented in microprocessor or software.

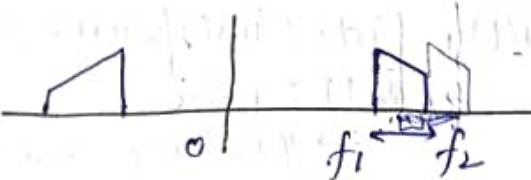


Baseband Sampling theorem:



$$\text{Sampling freq.} = 2f_{\text{max}}$$

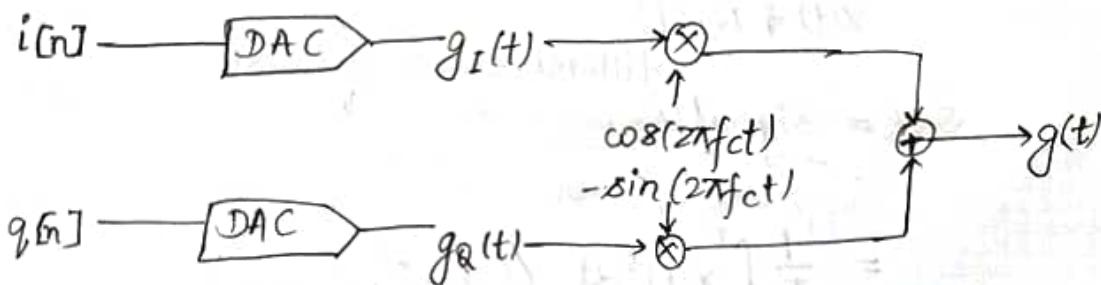
Passband Sampling theorem:



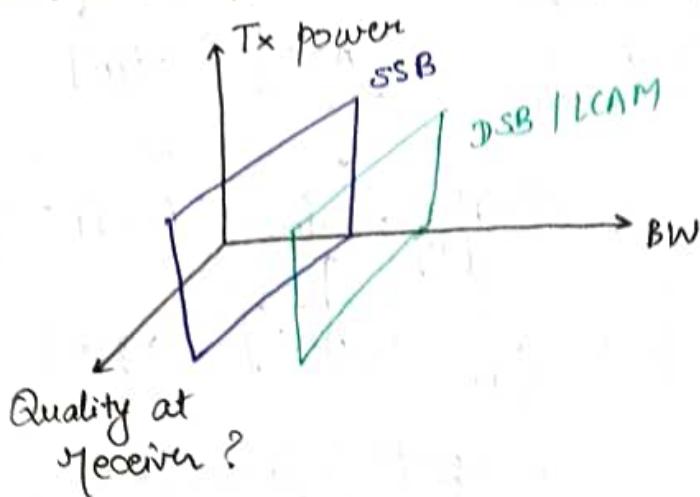
$$\text{Sampling freq.} = f_2 - f_1$$

Software defined Radio (Transmitter):

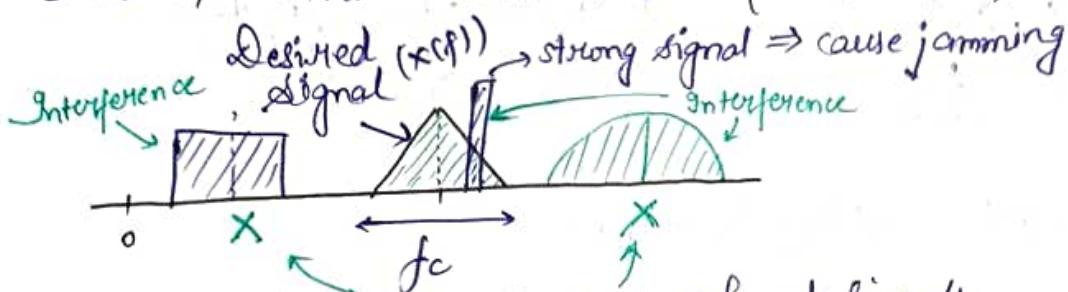
↪ Reverse the receiver



Recall Tradeoffs:



Error b/w $m(t)$ and $\hat{m}(t)$: $e(m(t), \hat{m}(t))$



→ Selectivity: Removing out of band signals.

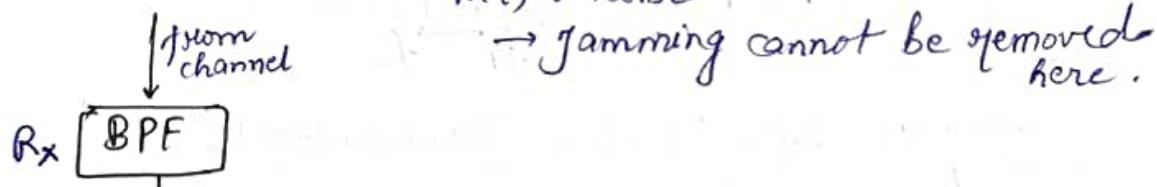
→ In-band interference cannot be filtered.

Noise: Unpredictable random signal

Signal-to-Noise Ratio (SNR): At receiver [Mechanics of SNR calc.]

$x(t) + i(t) + N(t)$, $i(t)$: interference signals

$N(t)$: noise

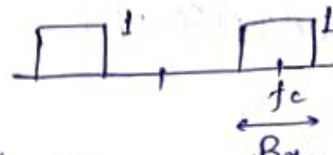
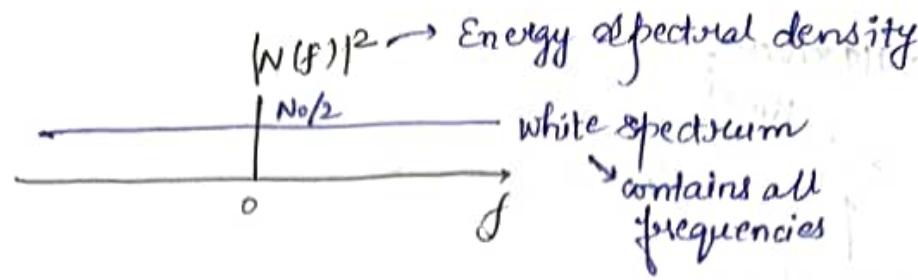


$$\text{SNR} = \frac{\text{Signal power}}{\text{Noise power}}$$

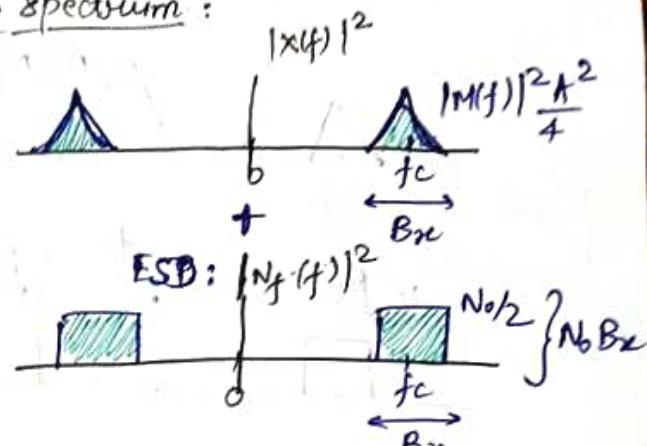
$$= \frac{\frac{1}{T} \int_0^T x(t)^2 dt}{\left(\frac{1}{T} \int_0^T N_f^2(t) dt \right)}$$

avg. unpredictable

Believe

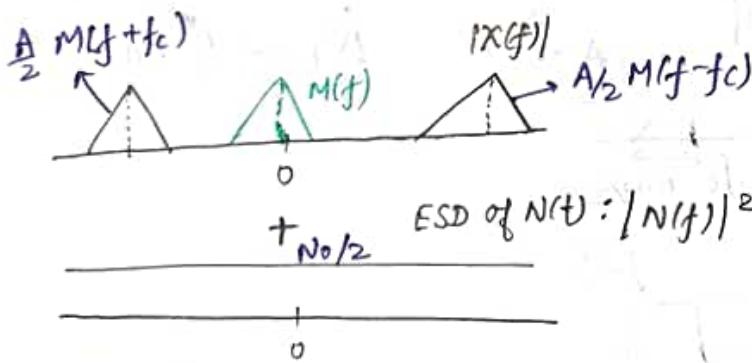
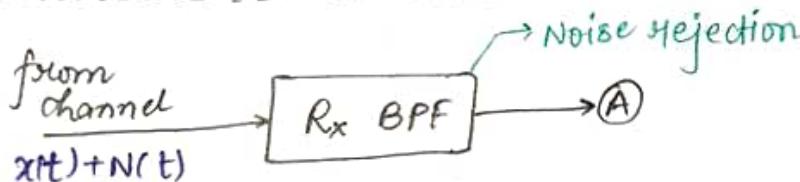


e.g. $x(t) = A_m(t) \cos(2\pi f_c t)$



SNR just after BPF: $\left(\frac{A^2 P_m}{2} \right) / N_0 B_x$

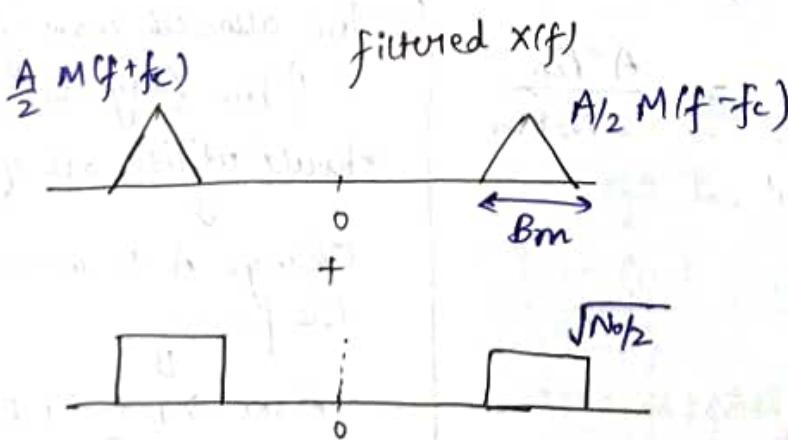
16-10-2024



ESD of $N(t) : |N(f)|^2$

$|N(f)| \sqrt{N_0/2}$

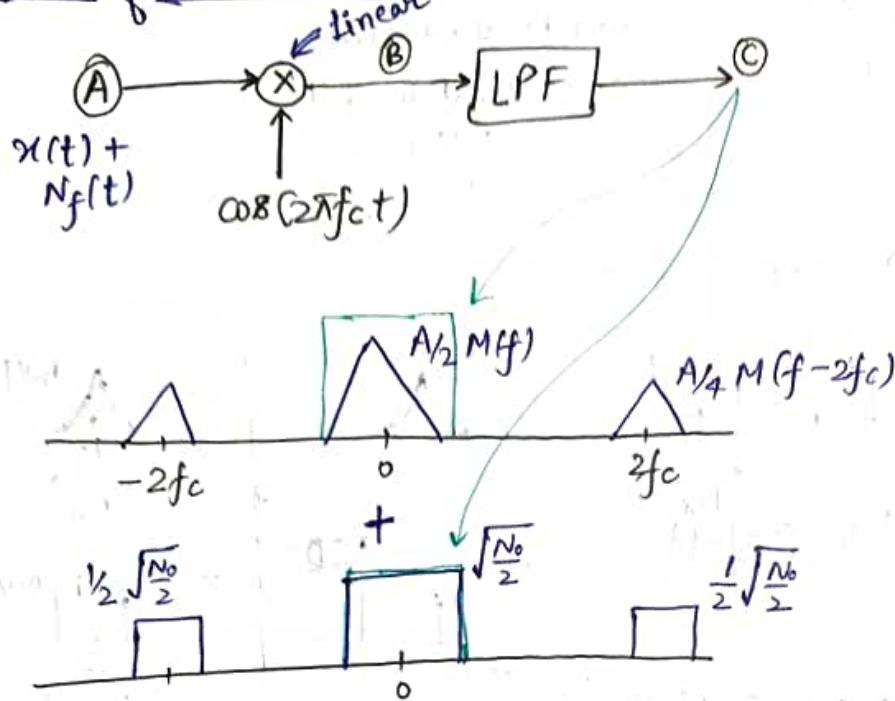
At A:



SNR after BPF: $\frac{A^2 P_m}{2 N_0 B_m}$

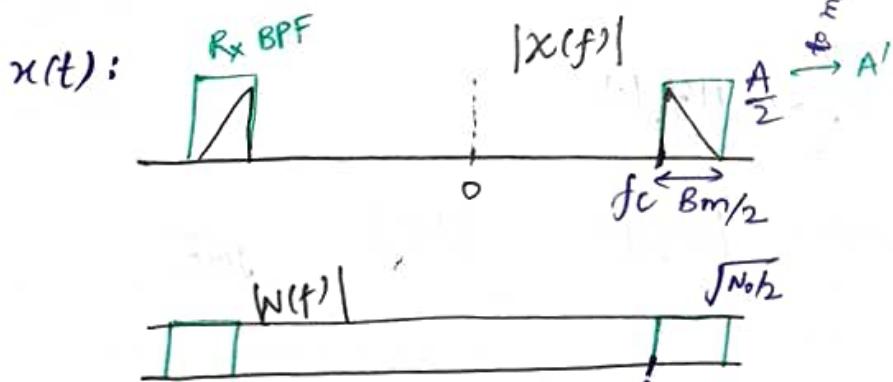
SNR before BPF ≈ 0 [Huge improvement in SNR]

Rest of the Receiver:



$$\text{Final SNR} = \frac{\frac{A^2}{4} P_m}{\frac{N_0}{2} B_m}$$

For SSB



$$\frac{A^2}{4} P_m = \frac{A^2}{2} P_m$$

At ④, after the Rx BPF:

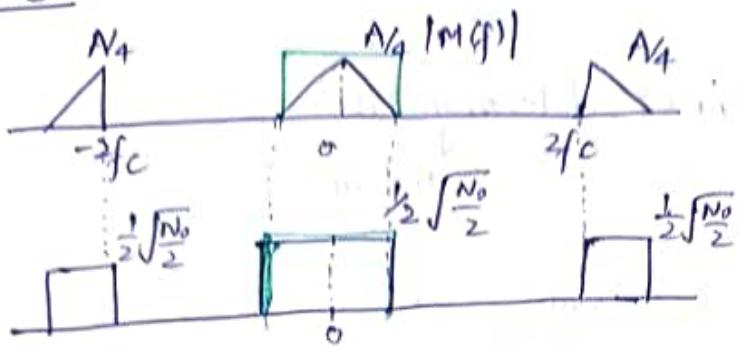
$$\text{SNR} = \frac{\frac{A^2}{4} P_m}{\frac{N_0}{2} \cdot \frac{2B_m}{2}} = \frac{A^2 P_m}{2 N_0 B_m}$$

If the allowed maximum power is $\frac{A^2}{2} P_m$ (say $1W$), we should utilize all of it

↓
Change A to increase the power

↓
Make DSB & SSB power same.

At B:



$$SNR = \frac{\frac{A^2}{16} P_m}{\frac{N_0}{8} B_m} = \frac{A^2 P_m}{2 N_0 B_m}$$

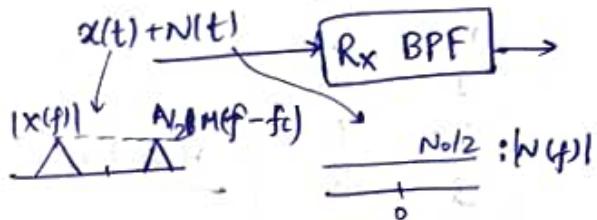
SAURABH KUMAR
SC22B196

Exercise : ① Compare SSB, DSB SNR if Tx powers are same.

② SNR for LCAM, assuming Tx power is same as DSB.

[Submit by 23rd Oct.]

Sol: ① DSB Tx power = $\frac{A^2}{2} P_m$



SSB Tx power = $\frac{A'^2}{4} P_m$

$$\therefore \frac{A^2}{2} P_m = \frac{A'^2}{4} P_m \Rightarrow A'^2 = 2A^2 \Rightarrow A' = \sqrt{2}A$$

SNR of DSB = $\frac{\frac{A^2}{2} P_m}{\frac{N_0(Bm \times 2)}{2}} = \frac{A^2 P_m}{2 N_0 B_m} \quad [BW = Bm \times 2]$

SNR of SSB = $\frac{\frac{A'^2}{4} P_m}{\frac{N_0(Bm)}{2}} = \frac{2A^2 P_m}{2 Bm N_0} = \frac{A^2 P_m}{N_0 B_m} \quad [BW = Bm]$

$\therefore \boxed{SNR(SSB) = 2 SNR(DSB)}$

② DSB Tx power = $\frac{A^2 P_m}{2}$

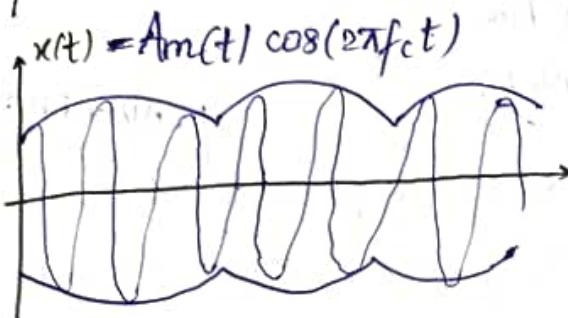
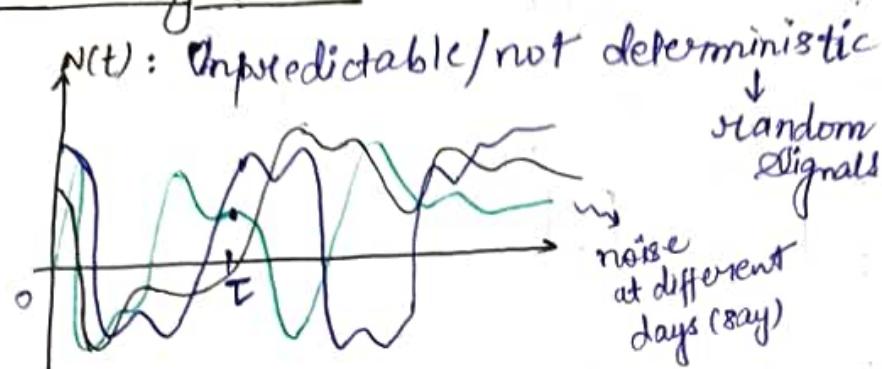
LCAM Tx power = $\frac{A'^2}{2} + \alpha \frac{A'^2 P_m}{2} = \frac{A'^2}{2} (1 + \alpha P_m)$

SNR of LCAM = $\frac{\frac{A'^2}{2} (1 + \alpha P_m)}{\frac{N_0 \times (2Bm)}{2}} = \frac{A^2 P_m}{2 N_0 B_m} = \boxed{SNR(DSB)}$

Also, $T_x P(DSB) = T_x P(LCAM) \Rightarrow \frac{A^2 P_m}{2} = \frac{A'^2}{2} (1 + \alpha P_m)$

$\therefore \boxed{SNR(LCAM) = SNR(DSB)}$

Modelling Noise

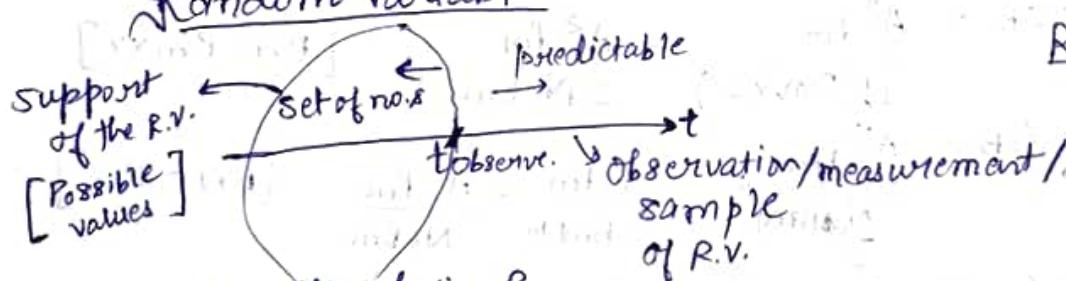


Observation of values at 1 min (τ):

n	x_n
1	0.1
2	1.0
3	0.5
:	:

Random → how do we model such phenomena?

Random Variable:



R.V.: support with distribution

and a distribution?

→ tells how many times a particular no. would appear on observing multiple times at t_{obs} .

Distribution of a R.V.

$P_x(x) = \text{fraction of observations with value } x$

$$X$$

(dist.)

e.g. 0 1 0 0 1 0 0 0

$$P_x(1) = 1/4$$

$$P_x(0) = 1 - P_x(1)$$

$$\sum P_x(x) = 1$$

$x \in S \rightarrow \text{support}$

e.g. Rolling a dice

1	2	4	6	1	2	3	4
5	1	1	2	1	2	1	4

$$S = \{1, 2, \dots, 6\}$$

$$P_x(6) = \frac{1}{6}$$

$$P_x(5) = \frac{1}{6}$$

$$P_x(4) = \frac{2}{6}$$

:

fitting a R.V. model

e.g. 10 persons roll a 10 die and their sum is calculated.

$$\{10, \dots, 60\}$$

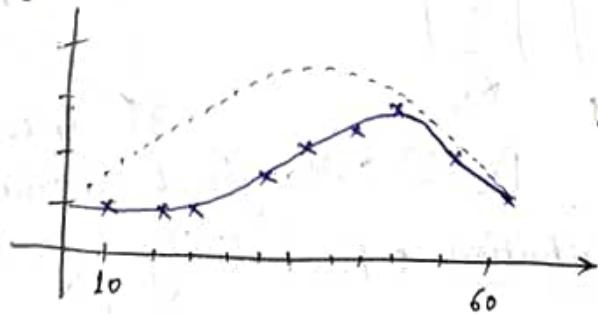
Fit a "reasonable" R.V. here.

Suppose Binomial, then n is max value.

$$p = \text{average}/n$$

Tradeoff: we may not get accurate value fit.

Histogram:



→ we may not get a good fit.

→ Advantage:

we would require

less parameters

No need to calculate for all the values.

S is discrete.

RV: discrete R.V.

$$P_x(x) = \text{PMF}.$$

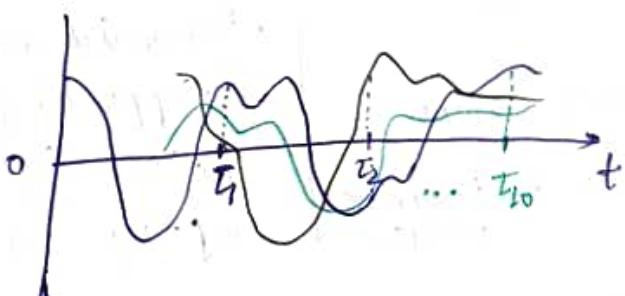
Values at T :

<u>n</u>	-
1	0.1
2	1.0
3	0.5
:	:

Here, values are continuous.

$$S \subseteq \mathbb{R} \quad [\text{continuous R.V.}]$$

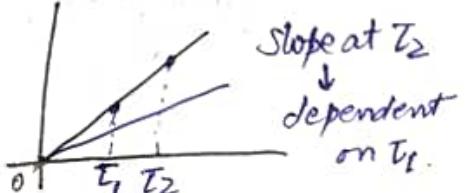
$f_x(x)$: PDF
= fraction of time samples
 $\in [x, x + dx]$



Observe values at 2 times T_1 and T_2 .

<u>n</u>	x_1	x_2
1	0.1	0.5
2	1	3
3	3	2

e.g. Signals: random slopes

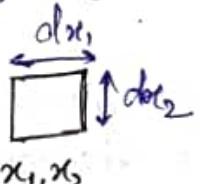


Marginalization $\rightarrow P_{x_1}(x_1) \quad P_{x_2}(x_2)$: Marginal distributions

Joint distribution : Probability of seeing a pair of values.

$$\hookrightarrow P_{x_1, x_2}(x_1, x_2)$$

$$f_{x_1, x_2}(x_1, x_2)$$
: PDF



$$P_{x_1}(x_1) = \sum_{x_2} f_{x_1, x_2}(x_1, x_2)$$

fraction of seeing x_1

sum of probabilities of observing x_1 & some x_2 overall x_2

Suppose 10 times

$$P_{x_1, x_2, \dots, x_{10}}(x_1, \dots, x_{10})$$

$\frac{n}{1}$	0.1	0.01	0.2	...	1.2
2					
:					

Standard models \uparrow

17-10-2024

Random variables \rightarrow vectors - Process

DRV x : $P_x(x)$

CRV x : $f_{x,x}(x)$

Multiple R.V.s: $x_1, x_2 \rightarrow \begin{bmatrix} P_{x_1, x_2}(x_1, x_2) \\ f_{x_1, x_2}(x_1, x_2) \end{bmatrix}$

Standard distributions:

fit data \rightarrow R.V. models

for 10 times

1 : 0.1, 0.2, 0.9, ..., 9

2 : 1, 0.1, 1, 9, ..., 10



Model :

$x_1, x_2, \dots, x_{10} \rightarrow 10^{10}$ parameters
 $\underbrace{P_{x_1, x_2, \dots, x_{10}}}_{10(M)} \quad \underbrace{(x_1, x_2, \dots, x_{10})}_{10(M)} \rightarrow \underbrace{(M^{10})}_{10 \times 10 \text{ (10M)}}$

Standard model : 10 length

Random variables are independent.

$$P_{x_1, \dots, x_{10}}(x_1, \dots, x_{10}) = P_{x_1}(x_1) \dots P_{x_{10}}(x_{10})$$

$\uparrow \quad \uparrow$
 $10(M) + \dots + 10(M) \rightarrow 10 \times 10 \text{ (10M)}$
parameters.

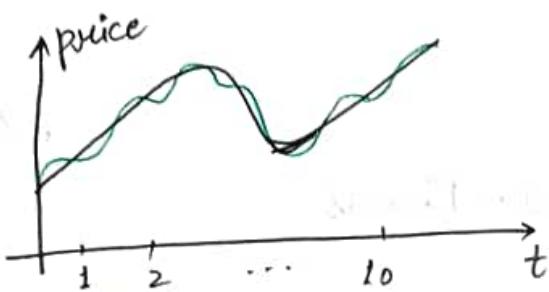
Independent and identically distributed models (IID)

↳ Independent R.V.s

↳ Each of the distribution is same.

$$P_{X_1, X_2, \dots, X_{10}}(x_1, \dots, x_{10}) = P_X(x_1) \cdots P_X(x_{10}) \rightarrow \text{only } M \text{ parameters}$$

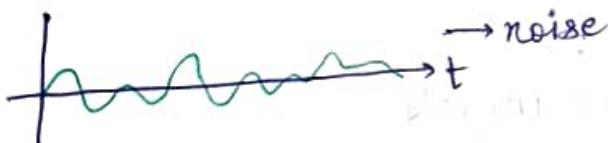
E.g.



Deterministic \rightarrow ~~'Trend'~~ + noise

P_1, P_2, \dots, P_{10}

detrended (Removing deterministic part)



↓
model using indep. & identically distributed.

Random Process

↳ An ordered collection of random variables with index

$t = \text{time}$.

$t \in \mathbb{R}$ \rightarrow cont. time R.P.s

or $t \in \mathbb{Z}$ $\} \text{ also be finite.} \rightarrow$ D.T.R.P

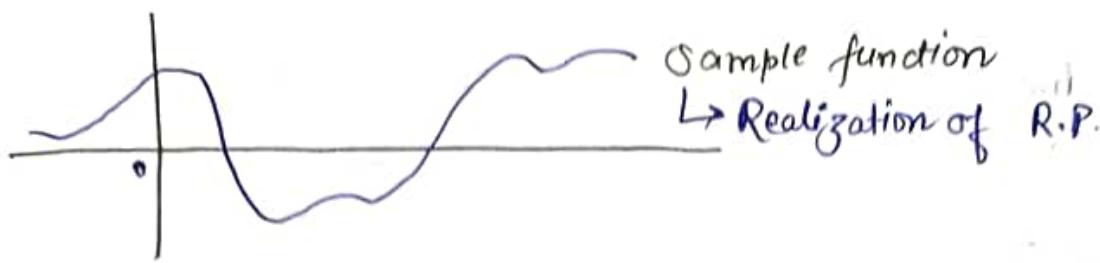
\downarrow disc. time R.P.s

Model for Noise Signal

$(N(t), \forall t \in \mathbb{R}) \rightarrow$ uncountable collection of R.V.s

\downarrow noise \rightarrow R.V.

↳ one R.V. at each time.



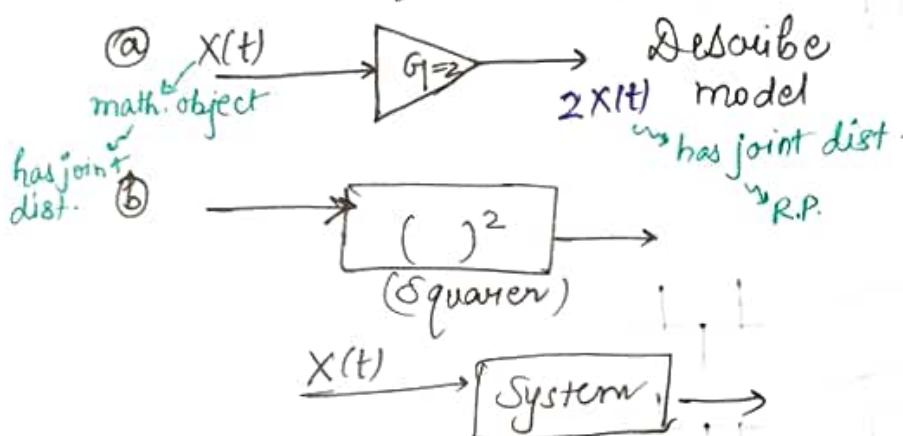
Problem:

D.T.R.P.

$(X(t), t \in \mathbb{Z})$

$X(t)$ is IID. \rightarrow PDF in $[-1, 1]$

$f_X(x) = \text{Unif. } [-1, 1]$

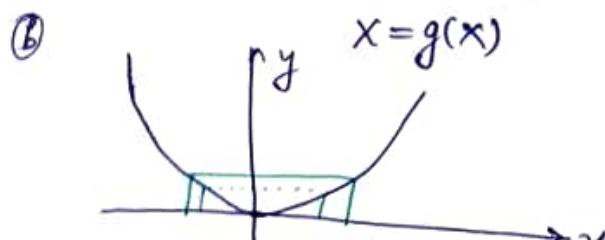


⑤ ④ Joint dist. of $2X(t) = Y(t)$,

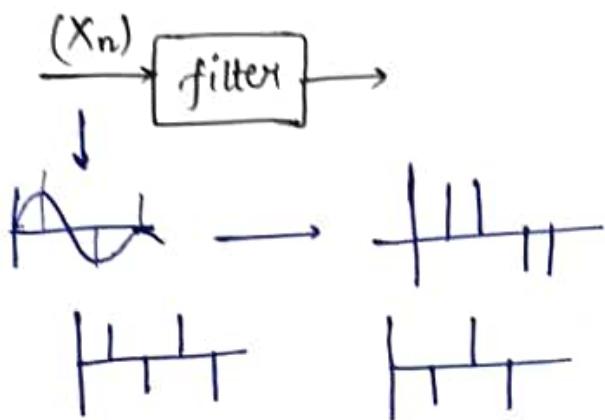
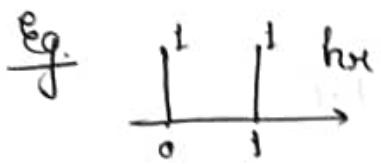
$$f_{Y(1)Y(2)}(y_1, y_2) = f_{X_1X_2}(y_1, y_2)$$

$$f_{Y(1)}(y) : \begin{array}{c} y_1 \\ \hline -2 & 2 \end{array}$$

$$\begin{aligned} f_Y(y) \cdot dy &= \Pr \{ Y \in [y, y+dy] \} = f_{X_1X_2}(y) \cdot dy \\ &= \Pr \{ X \in [y_1, y_1+dy] \} = f_X(y_1) \cdot dy \\ &= f_X(y_1) \cdot dy/2 \end{aligned}$$

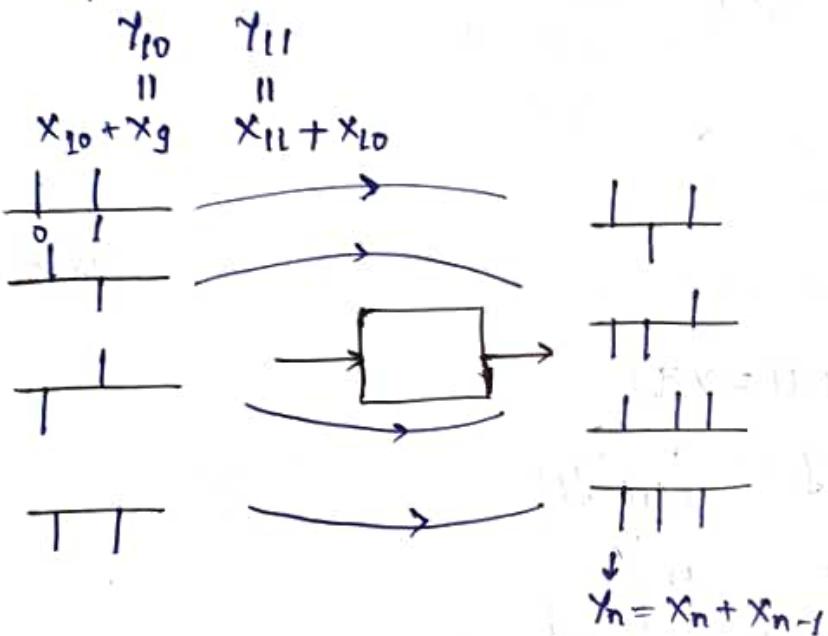


AVG : $Y + X$ \leftarrow



$$y_n = x_n + x_{n-1}$$

Suppose input is IID.



$\rightarrow X+Y$: DRVs

$X \perp Y$ $P_X(x), P_Y(y)$

$$P_Z\{X+Y=z\} = \sum P_X(x) P_Y\{Y=z-x | X=x\}$$

$x(t)$ or (x_n) : Joint distribution

Eg. $P_{x_1, x_2, x_3}(x_1, x_2, x_3)$

Structured models

- Independent
- IID

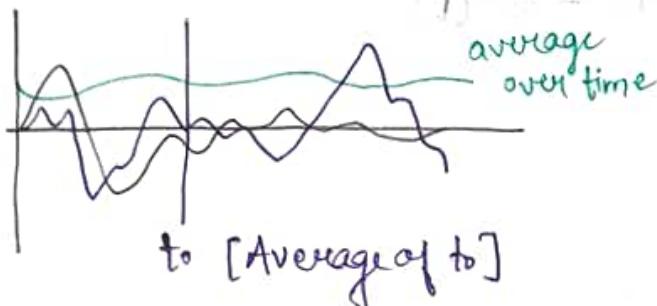
For our applications,



$y(t)$ also has a joint distribution.

- usually difficult to characterise.

$$E Y(t) = \mu(t)$$



Law of large numbers:

X is R.V. (P_x : prob)

$$x_1, x_2, \dots, x_n$$

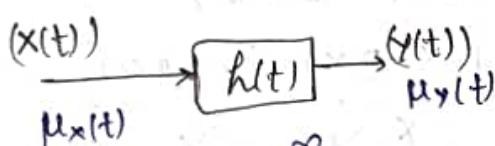
$$\bar{x} = \frac{x_1 + x_2 + \dots + x_n}{n}$$

$$\bar{x} \approx E X$$

$$V = \sum P_x(x)$$

$E(Y^2(t))$: Expected power from of time t

Variance, $\sigma_y^2(t) = E(Y^2(t)) - (E Y(t))^2$



$$Y(t) = \int_0^\infty h(\tau) x(t-\tau) d\tau$$

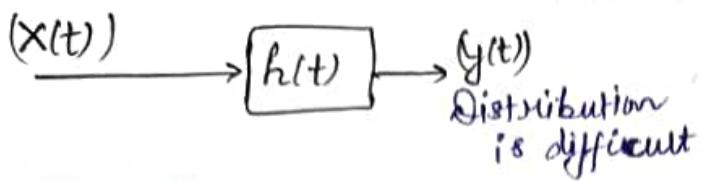
$$E Y(t) = \int_0^\infty \left(\int_0^\infty h(\tau) x(t-\tau) d\tau \right) f_x(y) dy$$

$$= \int_0^\infty \left(\int h(\tau) x(t-\tau) f_x(y) dy \right) d\tau$$

$$= \int_0^\infty h(\tau) \mu_x(t-\tau) d\tau$$

$$\mu_x(t) = \mu_x \text{ (constant)}$$

$$M_y = \underbrace{\mu_x \int_0^\infty h(\tau) d\tau}_{H(0)}$$



$$My(t) = \int h(\tau) \cdot \mu_x(t-\tau) d\tau$$

$$\mu_y = h(0) \mu_x$$

Other such functions: Summary Statistics

↳ gives the information about the complete distribution using a single value.

$$\mathbb{E}x, \mathbb{E}x^2, \text{Var}(x)$$

$$\mathbb{E}x = \mu_x(t), \text{Var}(x(t)) = \sigma_x^2(t)$$

To find $\mathbb{E}(y(t))^2$

$$\mathbb{E}[y(t_1) \cdot y(t_2)] \leftarrow$$

regression

x and y are R.V.s.

$$\mathbb{E}xy = \iint f_{xy}(x,y) \cdot xy \, dx \, dy : \text{correlation of R.Vs}$$

Covariance: $\text{cov}(x,y) = \mathbb{E}xy - \mathbb{E}x \cdot \mathbb{E}y$

$$= \mathbb{E}[(\underbrace{x - \mathbb{E}x}_{\text{mean}=0}) \cdot (\underbrace{y - \mathbb{E}y}_{\text{center R.V.}})]$$

$$Y(t_1) = \int h(u) \cdot x(t_1 - u) \, du$$

$$Y(t_2) = \int h(u) \cdot x(t_2 - v) \, dv$$

$$\begin{aligned} \mathbb{E}[Y(t_1) \cdot Y(t_2)] &= \mathbb{E}\left[\int h(u) \cdot x(t_1 - u) \, du \int h(v) \cdot x(t_2 - v) \, dv\right] \\ &= \mathbb{E}\left[\iint h(u) \cdot h(v) \cdot x(t_1 - u) \cdot x(t_2 - v) \, du \, dv\right] \\ &= \iint h(u) \cdot h(v) \cdot \mathbb{E}[x(t_1 - u) \cdot x(t_2 - v)] \, du \, dv \end{aligned}$$

Wide Sense Stationary (WSS) : weakly stationary

↳ $(x(t))$

↳ weak form of strictly stationary

conditions: • $\mu_x(t) = \mu_x$

• $E[x(t_1), x(t_2)] = R_{xx}(t_1, t_2)$

Autocorrelation

f'n of t_1, t_2

Strictly Stationary R.P.

↳ $(x(t))$

$$f_{x(t_1), x(t_2), \dots, x(t_m)}(x_1, x_2, \dots, x_m) = f_{x(t_1+\tau), x(t_2+\tau), \dots, x(t_m+\tau)}$$

$\forall m, (t_1, \dots, t_m), \tau$

$$f_{x(t)} = f_{x+\tau}(x)$$

$$\Rightarrow \int f_{x(t)} x dx = \int f_{x+\tau}(x) x dx$$

Example of same mean but different dist: Suppose we get diff. gaussian dist. at every time \rightarrow Mean \rightarrow same Variance \rightarrow different.

$$(w-v-t+1)^2$$

$$(v-u-t+1)^2$$

$$(u-t+1)^2$$
 with $w = v + u$, $v = w - u$ \Rightarrow $E[w] = E[v] = E[u]$

$$(d-t)^2$$

new value $E[(w)] \Leftarrow$

$$E[w] = E[v+u] = E[v] + E[u] \text{ (additivity)}$$

$$[w+v = u \Leftarrow w = v+u \text{ select}]$$

$$E[w] = E[v+u] = E[v] + E[u] \text{ (additivity)}$$

$$= E[v] + E[u] = E[(v-u) + (u-t+1) + (t-d)]$$

$$= E[(v-u) + (u-t+1) + (t-d)]$$

$$= E[(v-u) + (u-t+1) + (t-d)]$$

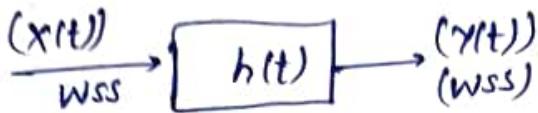
$$= (v-u) + (u-t+1) + (t-d)$$

WSS Random Process

$(x(t))$

$$\textcircled{1} \quad \mathbb{E}[x(t)] = \mu_x \left[\begin{array}{l} \text{summary} \\ \text{statistics} \end{array} \right] = \text{constant.}$$

$$\textcircled{2} \quad \mathbb{E}[x(t_1) \cdot x(t_2)] = R_x(t_1 - t_2)$$



$$\mu_y(t) = \int \underbrace{\mu_x(\tau)}_{\mu_x \text{ for WSS}} \cdot h(t-\tau) d\tau$$

$$[\mu_y = \mu_x \cdot H(0)] \leftarrow \int h(\tau) e^{j2\pi f_0 \tau} d\tau = \hat{h}(f_0)$$

$$\mathbb{E}[y(t_1) y(t_2)]$$

$$Y(t_1) = \int h(u) \cdot x(t_1 - u) du$$

$$Y(t_2) = \int h(v) \cdot x(t_2 - v) dv$$

$$\mathbb{E}[Y(t_1) \cdot Y(t_2)] = \iint h(u) \cdot h(v) \cdot \underbrace{\mathbb{E}[x(t_1 - u) \cdot x(t_2 - v)]}_{\begin{array}{l} R_x(t_1 - u - t_2 + v) \\ R_x(t_1 - t_2 - (u - v)) \end{array}} du dv$$

If $(x(t))$ is WSS \rightarrow function of $(t_1 - t_2)$

$$R_y(t_1 - t_2)$$

$\Rightarrow (y(t))$ is also WSS.

$$\mathbb{E}[Y(t_1) \cdot Y(t_2)] = \iint h(u) \cdot h(v) \cdot R_x(t_1 - t_2 - (u - v)) du dv$$

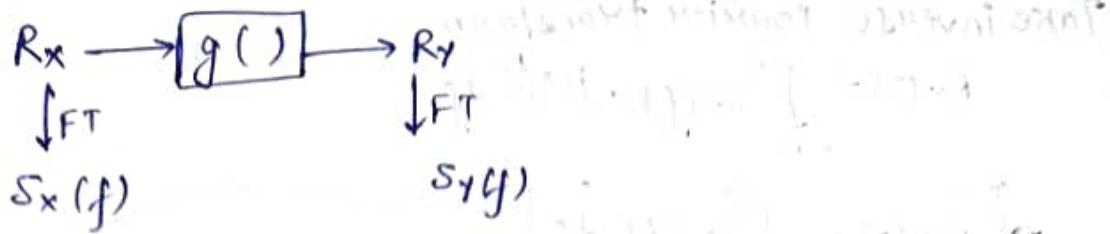
$$\left[\text{Take } u - v = w \Rightarrow u = v + w \right]$$

$$= \iint h(v + w) \cdot h(v) \cdot R_x(t_1 - t_2 - w) du dv$$

$$= \int R_x(t_1 - t_2 - w) \underbrace{\left(\int h(v + w) h(v) dv \right)}_{g(w)} dw$$

$$= \int R_x(t_1 - t_2 - w) g(w) dw$$

$$= R_x * g(t_1 - t_2)$$



$$S_y(f) = S_x(f) \cdot G(f)$$

$$G(f) = \int h(u) h(u+f) du$$

$$G(f)$$

$h(t) * h(-t)$

$$\downarrow FT$$

$$H(f) H^*(f) = |H(f)|^2$$

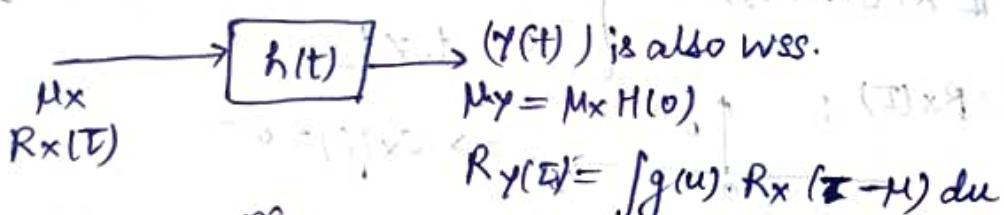
$S_y(f) = S_x(f) \cdot |H(f)|^2$

→ PSD: Power Spectral Density

WSS Random Process: $(x(t))$

- $\mathbb{E} X(t) = \mu_X(t) = M_x$
- $\mathbb{E} X(t_1)X(t_2) = R_X(t_1 - t_2)$
 $= R_X(\tau)$

$(x(t))$ is wss.



$$S_x(f) = \int_{-\infty}^{\infty} R_X(\tau) e^{-j2\pi f\tau} d\tau$$

$$S_y(f) = \int_{-\infty}^{\infty} R_y(\tau) e^{-j2\pi f\tau} d\tau$$

$S_y(f) = G(f) \cdot S_x(f)$
 $\downarrow PSD$
 $= |H(f)|^2 \cdot S_x(f)$

#

$\boxed{\mathbb{E}(x^2(t)) = R_X(0)}$

power

01-11-2024

$(x(t))$

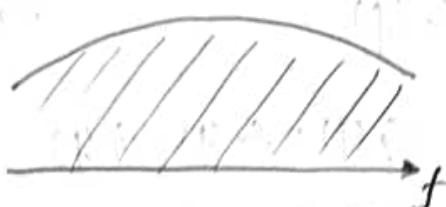
(for $t_1 = t_2$)

Take inverse Fourier transform,

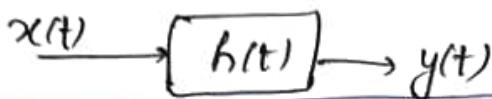
$$R_x(\tau) = \int_{-\infty}^{\infty} S_x(f) e^{j2\pi f \tau} df$$

$$\Rightarrow R_x(0) = \int_{-\infty}^{\infty} S_x(f) df$$

↳ Power spectral density



[Reading Assignment: PSD of bandpass]



$$|X(f)|^2 |H(f)|^2 = |Y(f)|^2$$

Eg. WSS with mean=0 \rightarrow IID

$$\xrightarrow{(x(t))} x(t) \sim N(0, \sigma^2)$$

$$\text{or } \sim \begin{bmatrix} -1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} \sim \mathcal{N}(0, \sigma^2 I_2)$$

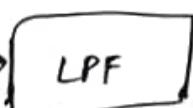
$$\mu_x = 0$$

$$\mathbb{E} X(t_1) \cdot X(t_2) = \begin{cases} \sigma^2, & t_1 = t_2 \\ 0, & t_1 \neq t_2 \end{cases}$$

$$R_x(\tau) : \quad \xrightarrow{\sigma^2 (2\pi \Delta f)^{-1}} \Rightarrow S_x(f) = \sigma^2$$

$$S_x(f) : \quad \sigma^2 \quad \text{white spectrum}$$

Process



$$\frac{1}{f_c} \quad |H(f)|$$

f_c
f_{cutoff}

Output PSD:

$$\frac{1}{f_c} \quad \sigma^2$$

$-f_c$ f_c

Gaussian Processes

$(X(t))$:

$$\begin{array}{c} \text{take values} \\ \rightarrow x_1 \\ \downarrow \text{etc.} \\ \rightarrow x_m \end{array} \quad \begin{array}{c} N(x_1, \mu, \sigma^2) \\ \dots \\ N(x_m, \mu, \sigma^2) \end{array}$$

Sequence of RVs: $(x(t_1), x(t_2), \dots, x(t_m))$

$$x \sim N(\mu, \sigma^2) \quad (\text{gaussian dist.})$$

$$f_x(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

05-11-2011

Gaussian Random Process : Noise Model

$(X(t))$: Random process model joint distribution.

Gaussian:

$$X(t) \sim N(\mu, \sigma^2)$$

$$M_X(t) = M_X$$

$$\mathbb{E}[X(t_1) X(t_2)] = R_X(t_1, t_2)$$

e.g. IID, $X(t) \sim N(\mu, \sigma^2)$

Joint distribution of any collection of RVs from this process is multidimensional Gaussian distribution.

Collection of RVs: (m times) t_1, t_2, \dots, t_m .

Multidim. Gaussian dist.: $f_{X(t_1) X(t_2) \dots X(t_m)}$

e.g. $f_{X(t_1) X(t_2)}(x_1, x_2)$

$$\begin{aligned} \text{if } m=1, MN(x) &= N(x, \mu, \sigma^2) \\ &= \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}} \end{aligned}$$

$$\text{if } m=2, MN(x) = \left(\begin{array}{c} x_1 \\ x_2 \end{array} \right)$$

Eg. If indep. $N(x_1, (\mu_1, \sigma^2))$
 $x_1 \perp x_2 N(x_2, \mu_2, \sigma^2)$

$$f_{x_1 x_2}(x_1, x_2) = \frac{1}{\sqrt{2\pi |\Sigma|}} e^{-(\frac{1}{2}(\vec{x} - \vec{\mu})^T (\Sigma^{-1}(\vec{x} - \vec{\mu})))}$$

$$\Sigma : \text{cov. matrix} = \begin{pmatrix} \sigma_1^2 & \text{cov}(x_1, x_2) \\ \text{cov}(x_1, x_2) & \sigma_2^2 \end{pmatrix}$$

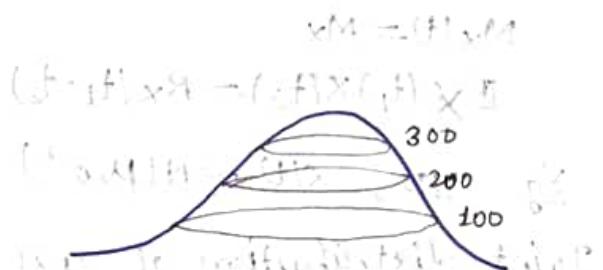
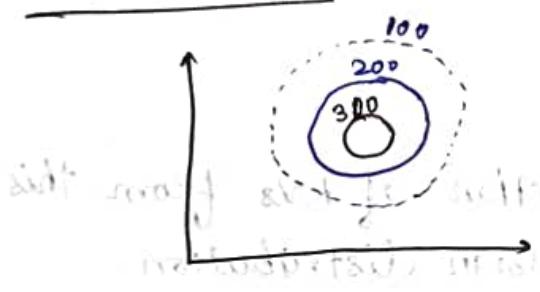
$$\text{cov}(x, y) = E(XY) - E(X)E(Y)$$

(Hoc-Ho) $x \perp y \Rightarrow \text{cov}(x, y) = 0$

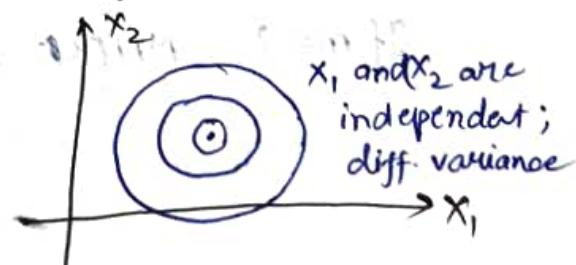
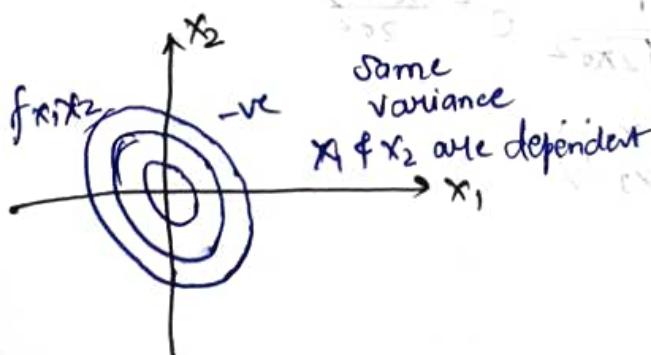
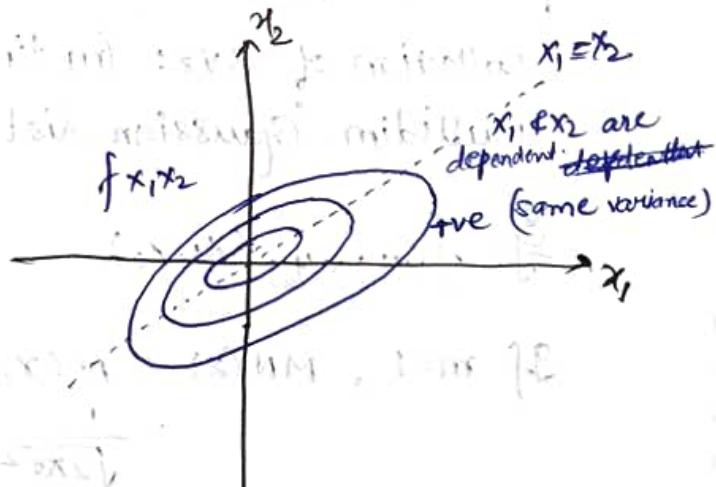
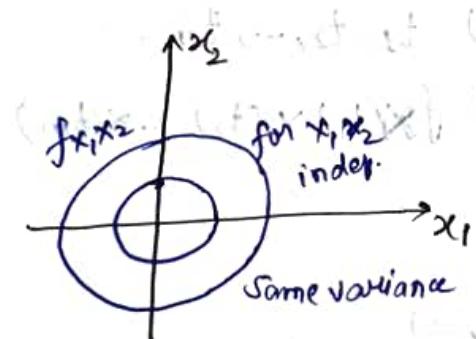
$$\left(\left(\frac{x_1}{\sigma_1} - \frac{\mu_1}{\mu_2} \right) \right)^T \begin{pmatrix} \frac{1}{\sigma_1^2} & 0 \\ 0 & \frac{1}{\sigma_2^2} \end{pmatrix} \left(\left(\frac{x_1}{\sigma_1} - \frac{\mu_1}{\mu_2} \right) \right)$$

Hw: $MN() \rightarrow N.N$

Contour Plane



Eg.



gf m>1 ,

$$f_{X(t_1)X(t_2)\dots X(t_m)}(x_1, x_2, \dots, x_m) = \frac{1}{\sqrt{2\pi|\Sigma|}} e^{-\frac{1}{2} [(\vec{x}-\vec{\mu})^T \Sigma^{-1} (\vec{x}-\vec{\mu})]}$$

$$\vec{\mu} = \begin{pmatrix} \mu_1 \\ \vdots \\ \mu_m \end{pmatrix}, \quad \Sigma = \begin{pmatrix} \sigma_1^2 & & \\ \text{cov}(x_i, x_j) & \ddots & \\ & & \sigma_m^2 \end{pmatrix}$$

\uparrow
mean vector $\overbrace{\hspace{10em}}$ $m \times m$ covar. matrix

Another definition for GP:

Any linear combination of $(X(t_1), \dots, X(t_m))$ is gaussian.

Linear combination: $\sum_{i=1}^m a_i x(t_i)$

$$\text{E.g. } x(t) = N \overset{N(0, \sigma^2)}{\sim} \cos(2\pi f t)$$

$$\text{Gaussian } N(0, \cos^2(2\pi fct)\sigma^2)$$

$(x(t))$

$$a_1 x(t_1) + \dots + a_m x(t_m)$$

$$N(\sum a_i \cos(2\pi f_c t_i)) \sim N(0, ?) \Rightarrow G.R.P.$$

Eg. Find $f_{X_1(t_1), X_2(t_2)}$ distribution

$$f_{X(t_1), X(t_2)}(x_1, x_2) = \frac{1}{\sqrt{2\pi|\Sigma|}} e^{-(\vec{x} - \vec{\mu})^T \Sigma^{-1} (\vec{x} - \vec{\mu})}$$

$$\mu = \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \quad \Sigma = \begin{pmatrix} \sigma^2 \cos^2(2\pi f_c t_1) & \sigma^2 \cos(2\pi f_c t_1) \cos(2\pi f_c t_2) \\ \sigma^2 \cos(2\pi f_c t_1) \cos(2\pi f_c t_2) & \sigma^2 \cos^2(2\pi f_c t_2) \end{pmatrix}$$

$$\text{conv}(x(t_1), x(t_2))$$

$$= E x(t_1) x(t_2)$$

$$= \mathbb{E} N \cos(2\pi f c t_1) \cdot N \cos(2\pi f c t_2)$$

Correction

$$\int x(t_1) \dots x(t_m) (x_1, \dots, x_m) = \frac{1}{\sqrt{(2\pi)^m |\Sigma|}} e^{-\frac{1}{2} (\vec{x} - \vec{\mu})^T \Sigma^{-1} (\vec{x} - \vec{\mu})}$$

Recall:

- Gaussian RP $\sim N(\cdot)$

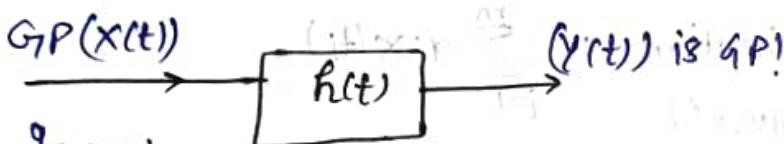
→ any collection of RVs

$$(x(t_1), x(t_2), \dots, x(t_m))$$

$$\forall m \quad \forall (t_1, \dots, t_m) \sim \mathcal{N}(\vec{\mu}, \Sigma)$$

→ any linear combination

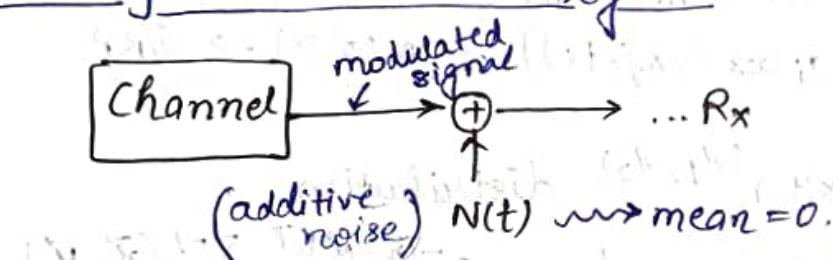
$$\forall \alpha_i \quad \sum \alpha_i x(t_i) \sim N(\cdot)$$



Invariance property

→ Noise models are GP models.

In a passband comm. system



IID
GP { Gaussian RP
white RP }
Constant
($R_N(\tau) = S(\tau)$)

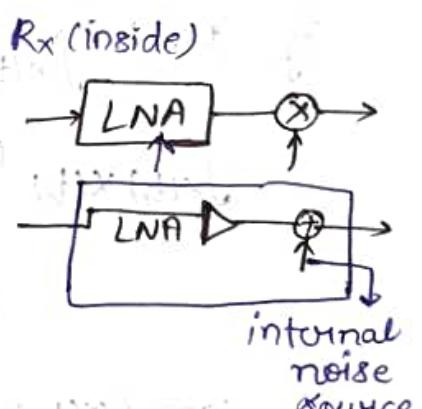
Spectral density \Rightarrow delta in time domain.

What is the covariance?

$$\text{cov}(x(t_1), x(t_2))$$

$$= E[x(t_1)x(t_2)]$$

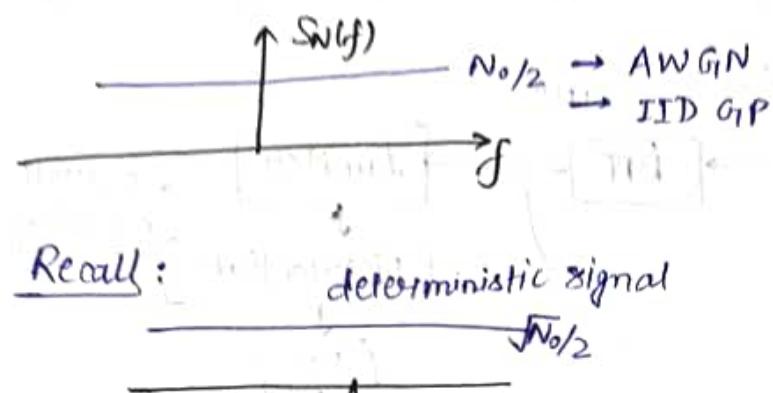
$$= 0 \text{ if } t_1 \neq t_2$$



$\text{cov} = 0 \Rightarrow$ independence
independence $\nRightarrow \text{cov} = 0$

\downarrow
 $\text{cov} = 0$ for Gaussian RP

→ Noise is an additive white G.P.



Recall: deterministic signal

$$\int N(t) e^{-j2\pi ft} dt$$

More correct

$N(t)$ is a R.P.

— AWGN

— PSD.

H/W assignment:

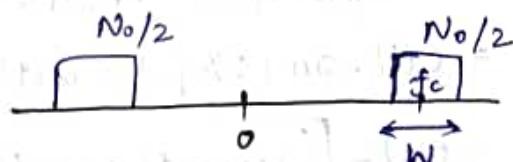
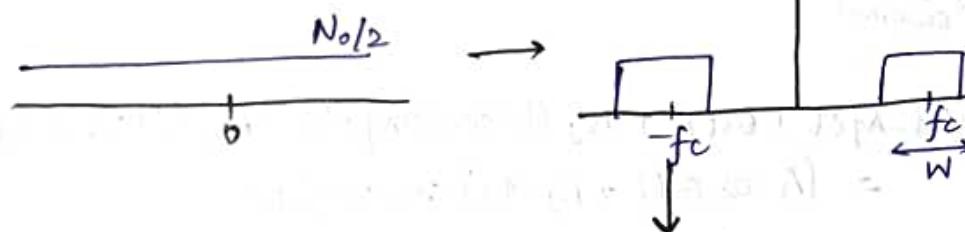
Revisit the SNR analysis.



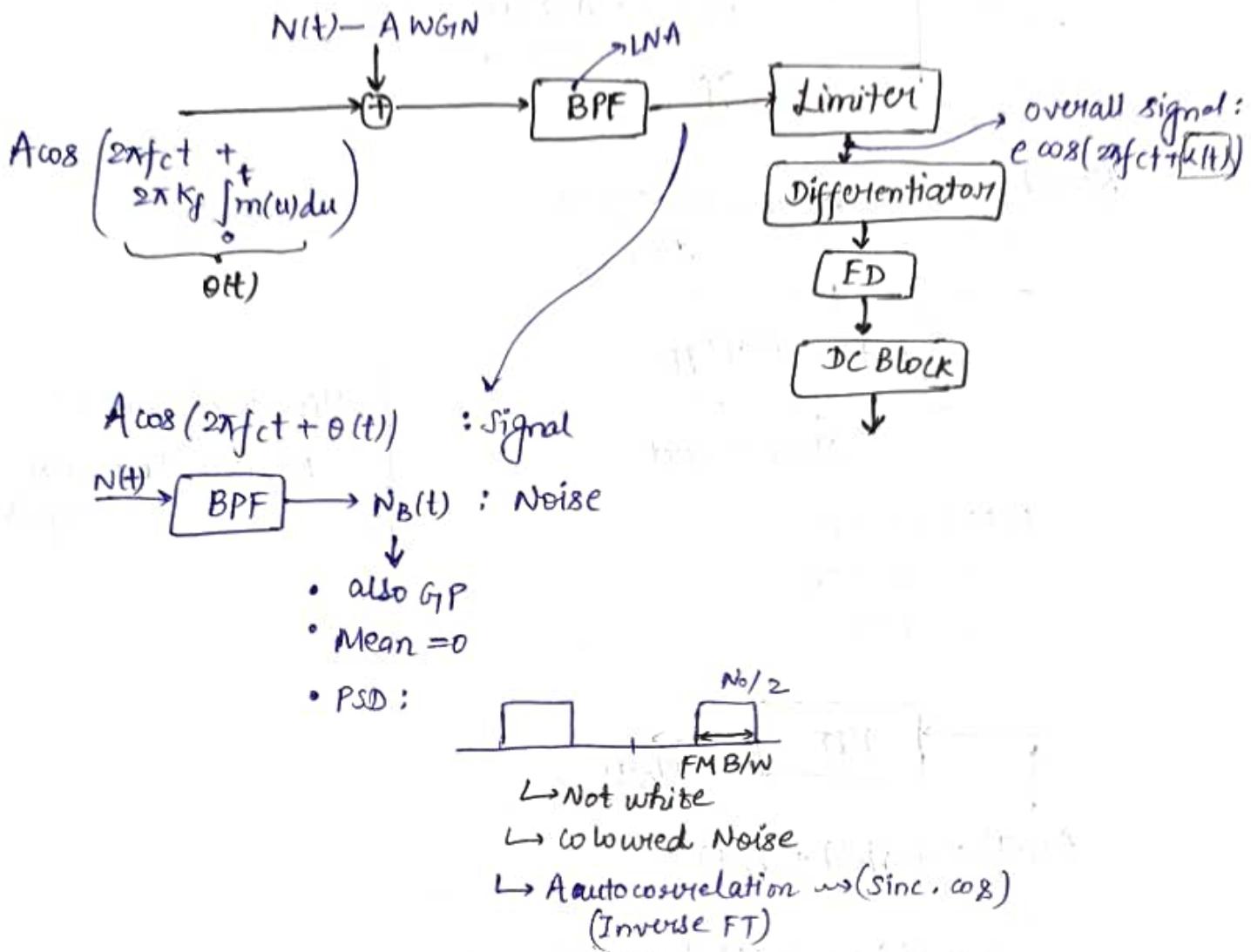
$$A_m(t) \cos(2\pi f_c t) + [N(t)]$$

$$S_{NB}(f) = S_N(f) \cdot |H(f)|^2$$

E.g.



Back to SNR Analysis - SNR-FM



$$N_B(t) = N_I(t) \cos(2\pi f_c t) - N_Q(t) \sin(2\pi f_c t)$$

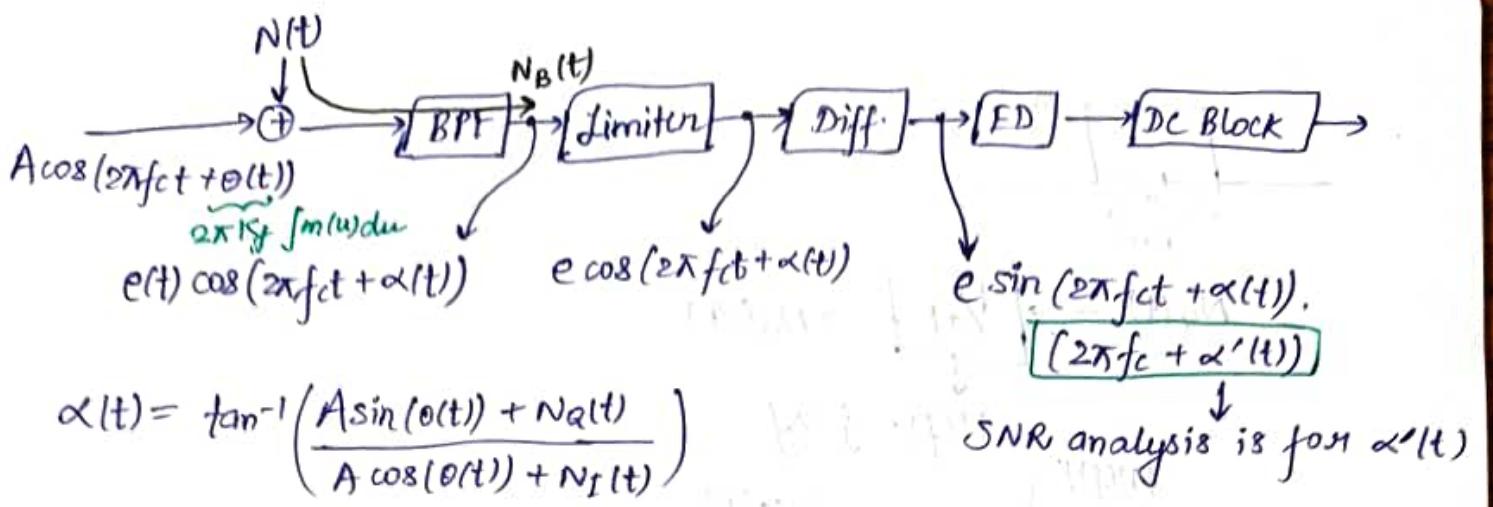
↓
like passband
channel

$$\begin{aligned} & A \cos(2\pi f_c t + \theta(t)) + N_I(t) \cos(2\pi f_c t) - N_Q(t) \sin(2\pi f_c t) \\ &= (A \cos \theta(t) + N_I(t)) \cos(2\pi f_c t) \\ &\quad - (A \sin \theta(t) + N_Q(t)) \sin(2\pi f_c t) \\ &= e(t) \cdot \sin(2\pi f_c t + \alpha(t)) \end{aligned}$$

$$e(t) = \sqrt{(A \cos \theta(t) + N_I(t))^2 + (A \sin \theta(t) + N_Q(t))^2}$$

\rightsquigarrow Limiter removes the variation in $e(t)$ but doesn't do anything to $\alpha(t)$.

$$\alpha(t) = \tan^{-1} \left(\frac{A \sin \theta(t) + N_Q(t)}{A \cos \theta(t) + N_I(t)} \right)$$



$$N_B(t) = N_I(t) \cos(2\pi fct) - N_Q(t) \sin(2\pi fct)$$

For Narrow-band FM
 $\nabla A \gg N_I(t) \quad \forall t$ } Assumptions

$$\alpha(t) = \tan^{-1} \left(\theta(t) + \frac{N_Q(t)}{A} \right) \quad \left[\begin{array}{l} \sin \theta(t) \approx \theta(t) \\ \cos \theta(t) \approx 1 \\ A + N_I(t) \approx A \end{array} \right]$$

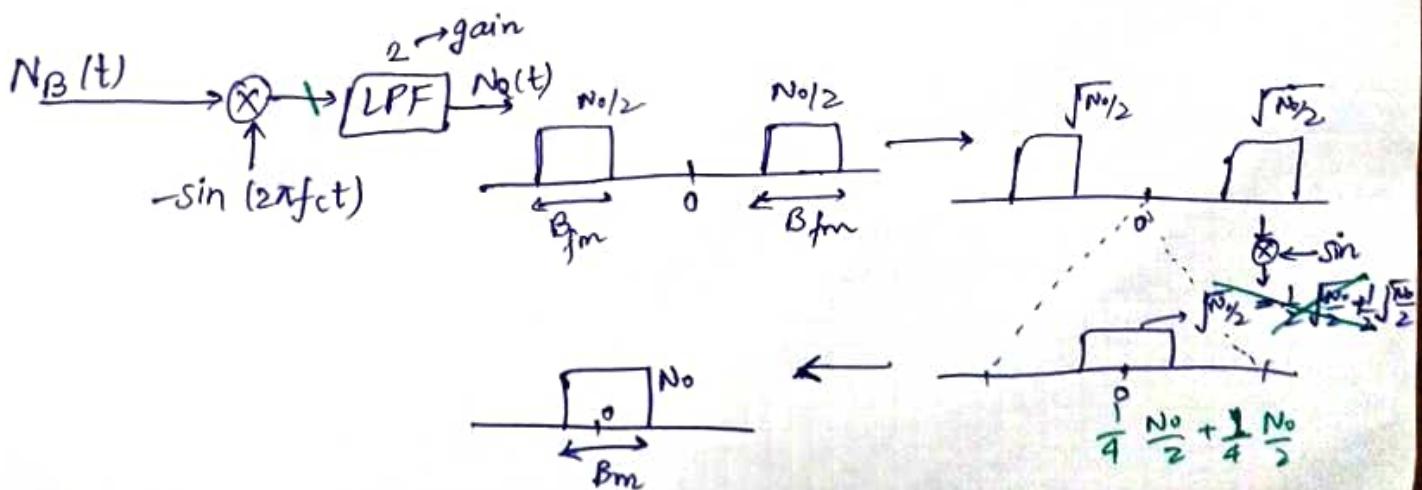
$$= \theta(t) + \frac{N_Q(t)}{A}$$

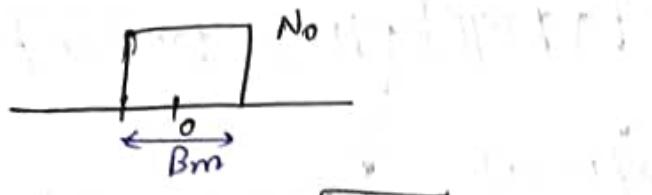
$$\alpha'(t) = \theta'(t) + \frac{N'_Q(t)}{A}$$

\downarrow

$2\pi k_f m(t)$ $\frac{1}{A}$ Noise
 (desired)

$$(4\pi^2 k_f^2 P_m)$$





$$N_Q(t) \xrightarrow{d/dt} N_Q'(t)$$

$$H(f) = j 2\pi f$$

$$|H(f)|^2$$

$$4\pi^2 f^2$$

$$N_0 \cdot 4\pi^2 f^2$$

$$B_m$$

$$B_{fm}$$

actual signal

$$\text{Noise power} = \frac{2}{A^2} \int_{-B_m/2}^{B_m/2} 4\pi^2 N_0 f^2 df$$

$$= \frac{4\pi^2 N_0 B_m^3}{12 A^2}$$

$$SNR = \left(4\pi^2 K_f^2 P_m \right) \left(\frac{12 A^2}{4\pi^2 N_0 B_m^3} \right)$$

$$= \frac{f^2 A^2 P_m}{N_0} \left(\frac{K_f}{B_m} \right)^2 \left(\frac{1}{B_m} \right)$$