Saurabh Palande

304, Shiv Sankalp, Plot No.74 Sector-50, Seawoods(W), Navi Mumbai-400706 India

EDUCATION

Visvesvaraya National Institute of Technology (VNIT) Bachelor of Technology in Mechanical Engineering

Nagpur, India July 2015 - May 2019

Ph.+91-959-432-8719

Email: saurabhpalande60@gmail.com

- Graduated with CGPA of 9.16/10.
- Awarded with Late Mr. Anil Dharashivkar Prize for securing the third-highest CGPA in the 2019 Batch of Mechanical Engineering.

TECHNICAL SKILLS

- Operating Systems: Linux, Windows
- **Programming Languages**: C/C++, Python, MATLAB
- Miscellaneous: Rviz, Gazebo, ROS, V-REP, OpenCV, TensorFlow, Solidworks, ANSYS

WORK EXPERIENCE

Shyena Tech Yarns, Pune, India

Computer Vision Intern

March 2021-Present

Working on 3D Lidar point cloud data, classification, segmentation and 3D object detection algorithms.

Space Renaissance-Indian Chapter, India

Robotics Research Intern

October2020- Jan 2021

 Conducting research focused on robotics design & mechanism, dynamics & control of robotics, sensors, actuator-based applications for robotics.

SIEMENS Ltd, Goa, India

Graduate Trainee Engineer

July 2019 – Feb 2020

Studied the working, production and assembly of SIEMENS Switchgears and Ring Main Units (RMU).

SIEMENS Ltd, Kalwa, India

Mechatronics Certification Program

December 2017

• Successfully completed one-month Siemens India Training (SITRAIN) in certified course "Mechatronics and Process Automation".

SIEMENS Ltd, Kalwa, India

Mechanical Engineering Intern

June 2017 – July 2017

- Studied the production and manufacturing process of Electric Motors.
- Gained Key insights on the Industrial Robots used in the manufacturing of Electric motors.

ACADEMIC PROJECTS

Autonomous driving and path planning using SLAM (Simultaneous Localization and Mapping) algorithm for a differential robot in ROS using Gazebo and Rviz.

- Created a custom robot model using URDF.
- Implemented Path planning with Custom Robot in Robot Operating System using Gazebo and Rviz.

Computer Vision Project: Implementation of Ball Tracking algorithm in ROS using OpenCV.

 Developed a ball tracking program that read video frames from a video file, a ROS Image topic and a USB camera through ROS.

Participated in the event Robo Cup in AXIS'15, annual technical festival of VNIT, Nagpur. (Team of 4)

• Designed and fabricated a manually controlled robot with ball kicking mechanism to kick and push a ball into an opponent's goal post.

Design and Analysis of the use of stiffeners on the front loader of Earth moving machine. (B. Tech Thesis)

• Performed the Finite Element analysis of the loader bucket to find an accurate location and pattern of welding of stiffener to the loader bucket sidewall.

RELATED COURSEWORK

- **Theory of Machine** Basic concept of mechanisms, links, kinematic pairs, kinematic chain, Static and Dynamic force analysis, Vibration in mechanical systems.
- **Design of Machine Elements** Design Principles, Theories of failure and factor of safety, Material Selection
- **Industrial Robotics** Construction of manipulators, Forward kinematics, Inverse kinematics and Jacobian for serial and parallel robots, Manipulator dynamics and force control.
- Manufacturing Process Automation-Automated production lines, programming of CNC machines.
- Machine Vision Application Basics of computer vision, Image processing algorithms, Modeling and registration.
- **Artificial Intelligence in Manufacturing** Overview of artificial intelligence, Fuzzy logic, Genetic algorithms, Artificial Neural Networks.

ONLINE COURSES & CERTIFICATIONS

- Aerial Robotics University of Pennsylvania
- Robotics: Estimation and Learning University of Pennsylvania
- ROS for Beginners: Basics, Motion, and OpenCV.
- ROS Simulating SLAM and Autonomous Driving Custom Robot
- Deep Learning: Advanced CNNs In Python

ACHIEVEMENTS & HONORS

- Awarded with Late Mr. Anil Dharashivkar Prize for securing the third-highest CGPA in the 2019 Batch of Mechanical Engineering in VNIT, Nagpur.
- Awarded Consolation Prize in Maharashtra Talent Search Examination (MTSE) in April, 2012.
- Successfully passed HOMI BHABHA BAL VAIDNYANIK COMPETITION in 2011 and 2008.

EXTRA-CURRICULAR

- Member of "Halla Bol", Dramatics club of VNIT, Nagpur.
- Event Manager of ROBOWARS, for AXIS'18, the annual technical festival of VNIT, Nagpur.
- Event Organizer of ROBOWARS, for AXIS'16, the annual technical festival of VNIT, Nagpur.
- Completed ALL INDIA TREKING EXPEDITION in BELGAUM held by NCC.