VISVESVARAYA TECHNOLOGICAL UNIVERSITY

"JnanaSangama", Belgaum -590014, Karnataka.

LAB REPORT
on

Artificial Intelligence (22CS5PCAIN)

Submitted by

Saurav Chhetri (1BM21CS194)

in partial fulfillment for the award of the degree of
BACHELOR OF ENGINEERING
in
COMPUTER SCIENCE AND ENGINEERING

B.M.S. COLLEGE OF ENGINEERING
(Autonomous Institution under VTU)
BENGALURU-560019
Nov-2023 to Feb-2024

B. M. S. College of Engineering,

Bull Temple Road, Bangalore 560019

(Affiliated To Visvesvaraya Technological University, Belgaum)

Department of Computer Science and Engineering

CERTIFICATE

This is to certify that the Lab work entitled "**Artificial Intelligence**" carried out by **Saurav Chhetri (1BM21CS194),** who is bonafide student of **B.M.S. College of Engineering.** It is in partial fulfillment for the award of **Bachelor of Engineering in Computer Science and Engineering** of the Visvesvaraya Technological University, Belgaum during the academic semester Nov2023 to Feb-2024. The Lab report has been approved as it satisfies the academic requirements in respect of a **Artificial Intelligence (22CS5PCAIN)** work prescribed for the said degree.

Pallavi Gb
Assistant Professor
Department of CSE
BMSCE, Bengaluru

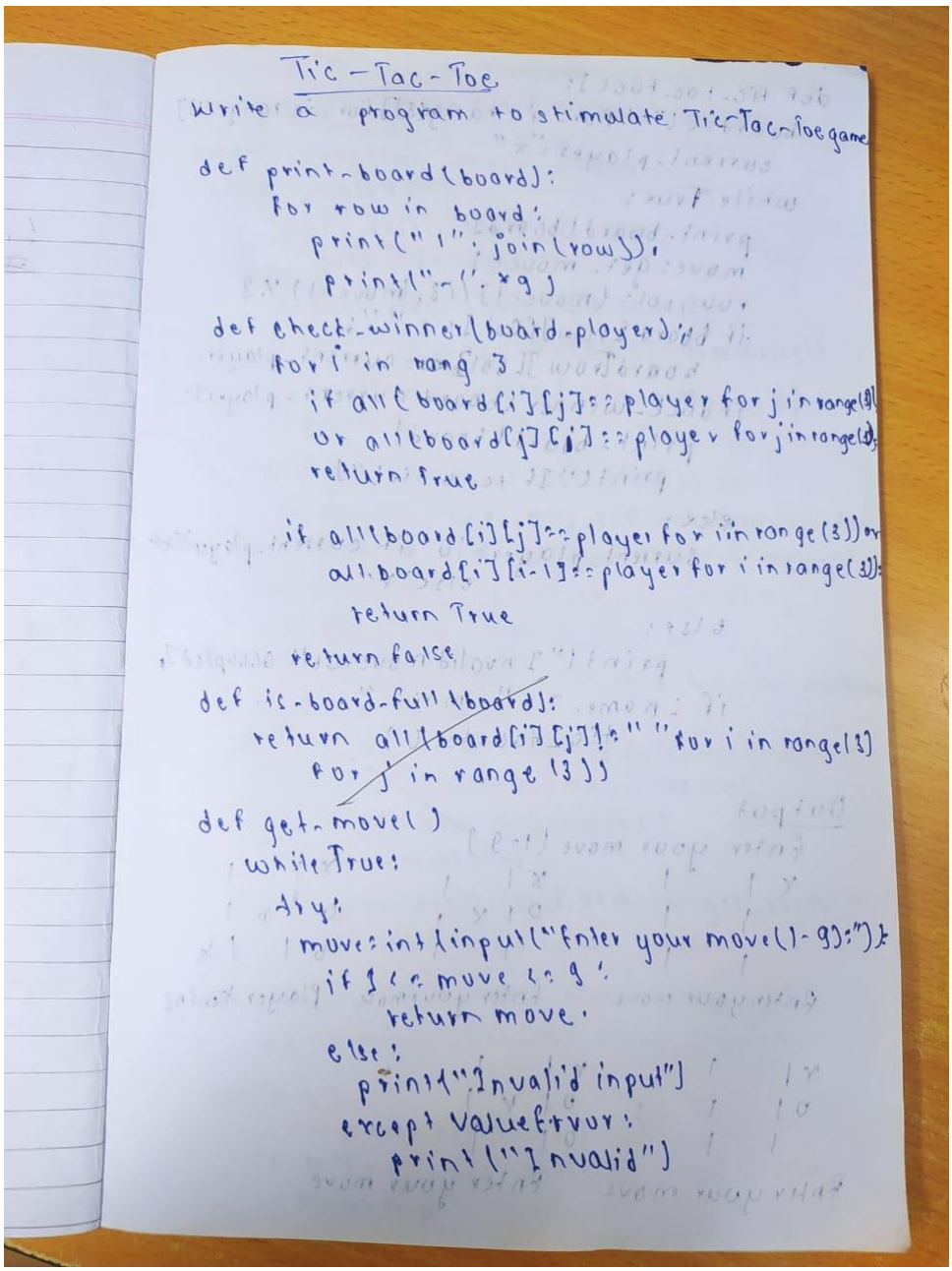
Dr. Jyothi S Nayak
Professor and Head
Department of CSE
BMSCE, Bengaluru

Index Sheet

Course Outcome

CO1	Apply knowledge of agent architecture, searching and reasoning techniques for different applications.
CO2	Analyse Searching and Inferencing Techniques.
CO3	Design a reasoning system for a given requirement.
CO4	Conduct practical experiments for demonstrating agents, searching and inferencing.

Lab Observation Notes:



Tic-Tac-Toe

Write a program to stimulate Tic-Tac-Toe game

```
def print_board(board):
    for row in board:
        print("|".join(row))
        print("-"*9)
def check_winner(board,player):
    for i in rang 3
        if all(board[i][j]==player for j in range(3)
        or all(board[j][i]==player for j in range(3)
        return True

    if all(board[i][j]==player for i in range(3)) or
        all.board[i][i-1]==player for i in range(3):
            return True
    return false
def is_board_full(board):
    return all(board[i][j]!=" " for i in range(3)
        for j in range(3))
def get_move()
    while True:
        try:
            move=int(input("Enter your move(1-9):"))
            if 1<= move <=9:
                return move.
            else:
                print("Invalid input")
            except valueErrvor:
                print("Invalid")
```

```
def tic_tac_toe():
    board = [[" " for _ in range(3)] for _ in range(3)]
    current_player = "X"
    while True:
        print_board(board)
        move = get_move()
        row, col = (move-1)//3, (move-1)%3
        if board[row][col] == " ":
            board[row][col] = current_player
        if check_winner(board, current_player):
            print_board(board)
            print("It is a tie!")
        else:
            current_player = "O" if current_player == "X"
                             else "X"
    else:
        print("Invalid move, cell occupied")
if __name__ == "__main__":
    tic_tac_toe()
```

Output

Enter your move (1-9)

```
X |   |       X |   |       X |   |
  |   |       O | X |       O | X |
  |   |       |   |         O |   | X
```

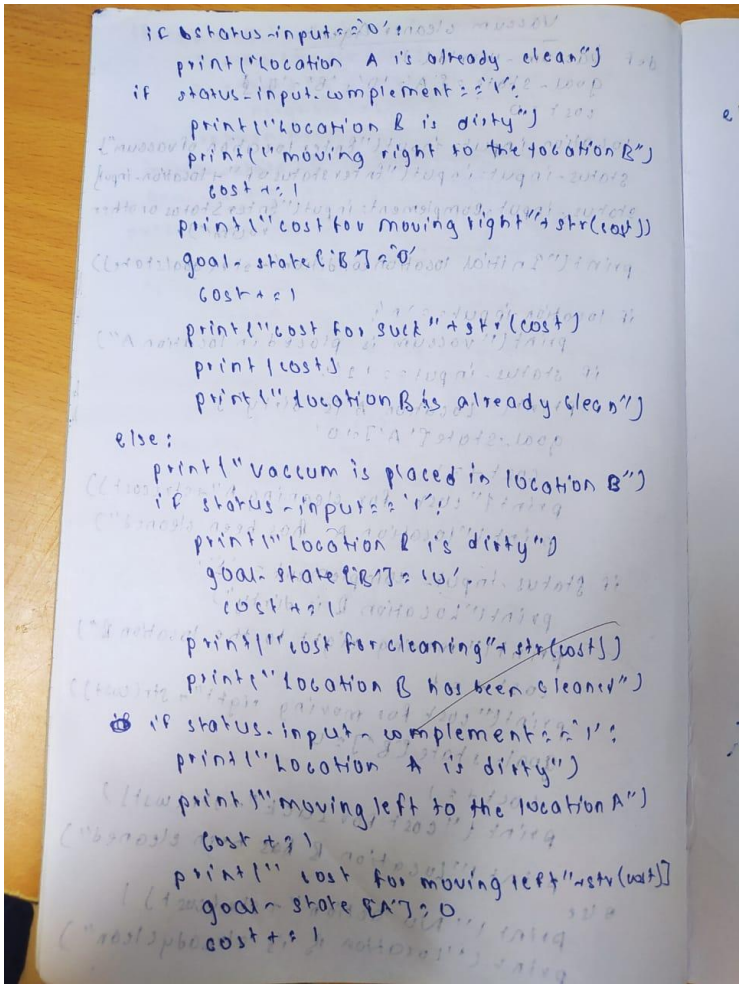
Enter your move Enter your move Player X wins

```
X |   |       X |   |
O |   |       O | X |
  |   |       O |   |
```

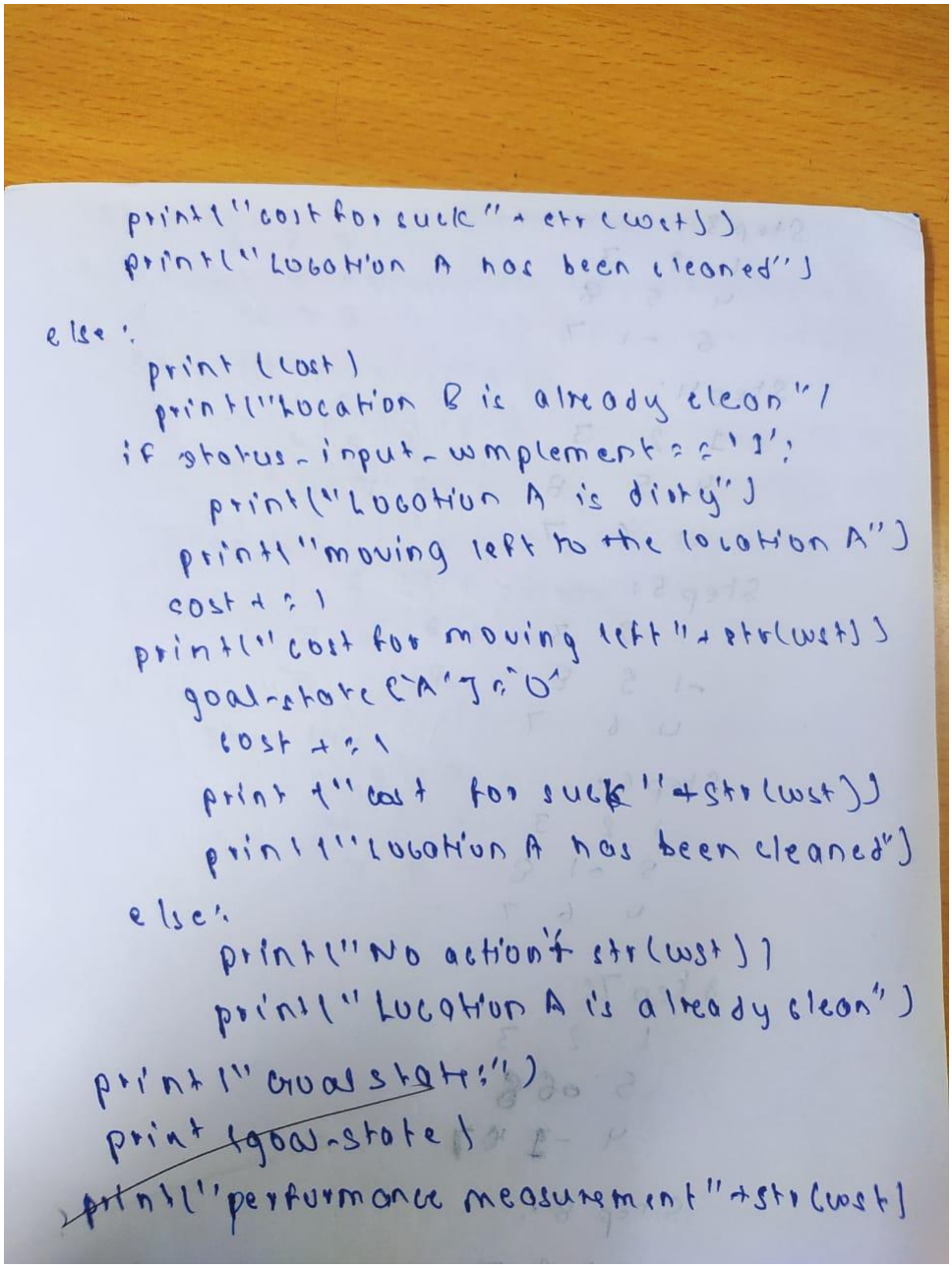
Enter your move Enter your move

Vaccum cleaner Agent

```
def vaccum_world():
    goal_state = {'A': '0', 'B': '0'}
    cost = 0
    location_input = input("Enter location of vaccum")
    status_input = input("Enter status of " + location_input)
    status_input_complement = input("Enter Status of other room")
    print("Initial location condition" + str(goal_state))

    if location_input == 'A':
        print("Vaccum is placed in location A")
        if status_input == '1':
            print("Location A is dirty")
            goal_state['A'] = '0'
            cost += 1
            print("cost for cleaning A" + str(cost))
            print("Location A has been cleaned")
    if status_input_complement == '1':
        print("Location B is dirty")
        print("moving right to the location B")
        cost += 1
        print("cost for moving right" + str(cost))
        goal_state['B'] = '0'
        cost += 1
        print("cost for suck" + str(cost))
        print("Location B has been cleaned")
    else
        print("No action" + str(cost))
        print("Location B is already clean")
```



```
if status_input == '0':
    print("Location A is already clean")
if status_input_complement == '1':
    print("Location B is dirty")
    print("moving right to the location B")
    cost += 1
    print("cost for moving right" + str(cost))
    goal_state['B'] = '0'
    cost += 1
    print("cost for suck" + str(cost))
    print(cost)
    print("location B is already clean")
else:
    print("vaccum is placed in location B")
    if status_input == '1':
        print("Location B is dirty")
        goal_state['B'] = '0'
        cost += 1
        print("cost for cleaning" + str(cost))
        print("location B has been cleaned")
if status_input_complement == '1':
    print("Location A is dirty")
    print("moving left to the location A")
    cost += 1
    print("cost for moving left" + str(cost))
    goal_state['A'] = 0
    cost += 1
```



```
        print("cost for suck" + str(cost))
        print("Location A has been cleaned")

    else:
        print(cost)
        print("Location B is already clean")
    if status_input_wmplement == '1':
        print("Location A is dirty")
        print("moving left to the location A")
        cost += 1
        print("cost for moving left" + str(cost))
        goal_state['A'] = '0'
        cost += 1
        print("cost for suck" + str(cost))
        print("Location A has been cleaned")
    else:
        print("No action" + str(cost))
        print("Location A is already clean")
print("Goal state:")
print(goal_state)
print("performance measurement" + str(cost))
```

Output for program 3

Enter location of vaccum: A
Enter status of A: 1
Enter location of other room: 0
Invalid status: 'A': '0' 'B': '0'
Vaccum is placed in location A
location A is Dirty
Cost for cleaning A: 1
location A has been cleaned
No action
location B is already clean
Goal state: {'A': '0', 'B': '0'.

8 - Puzzle Problem

(3)]

Write a program to solve 8 - puzzle problem.

```
from collection import deque
class puzzle8:
    def __init__(self,size=3):
        self.size=size
    def display_state(self,state):
        for i in range(0,len(state),self.size):
            print(state[i:i+self.size])
        print()
    def get_neighbour(self,state):
        neighbour=[];b,r,c=[],self.get_blank_index(state),
        divmod(self.get_blank_index(state),self.size)
        for m in[(0,1),(1,0),(0,-1),(-1,0)]:
            ns,nc=r[0]+m[0],m[1]+r[1]
            if 0<=ns<self.size and 0<=nc<self.size:
                ns=state[:]
                ns[b],ns[ns*self.size+nc]=ns[ns*
                    self.size+nc],ns[b]
                neighbour.append(ns)
        return neighbour
    def is_goal_state(self,state,target_state):
        return state==target_state
    def bfs(self,initial_state,target_state):
        q,v=deque([(initial_state,[])]),set()
while q:
        cs,p=q.popleft()
    if self.is_goal_state(cs,target_state):
        return p
```

```
if tuple(cs) not in v:
    v.add(tuple(cs))
    q.extend([(n, p+[n]) for n in self.get_
        neighbour(cs)])
    return None
initial_state = [1,2,3,4,-1,5,6,7,8]
goal_state = [1,2,3,4,5,6,7,8,-1]
puzzle_solution = puzzle(), puzzle().bfs(
                initial_state, goal_state)

if solution:
    print("solution found").
    for step,state in enumerate(solution):
        print("step %s\n%s" %(step,
        puzzle.display_state(state))
    else:
        print("No solution found")
```

printf("performance me

Output for program2

Solution found

Step 1:

1 2 3

4 5 -1

6 7 8

step 2:

1 2 3

4 5 8

6 7 -1

Step 3 :

1	2	3
4	5	8
6	-1	7

Step 4 :

1	2	3
4	5	8
	6	7

Step 5 :

1	2	3
-1	5	8
4	6	7

Step 6 :

1	2	3
5	-1	8
4	6	7

Step 7 :

1	2	3
5	6	8
4	-1	7

Step 8 :

1	2	3
4	6	-1
4	7	8

Step 9 :

1	2	3
5	6	-1
4	7	8

Step 10 :

1	2	3
5	-1	
4	7	8

Step 11:

1	2	3
-1	5	6
4	7	8

Step 12:

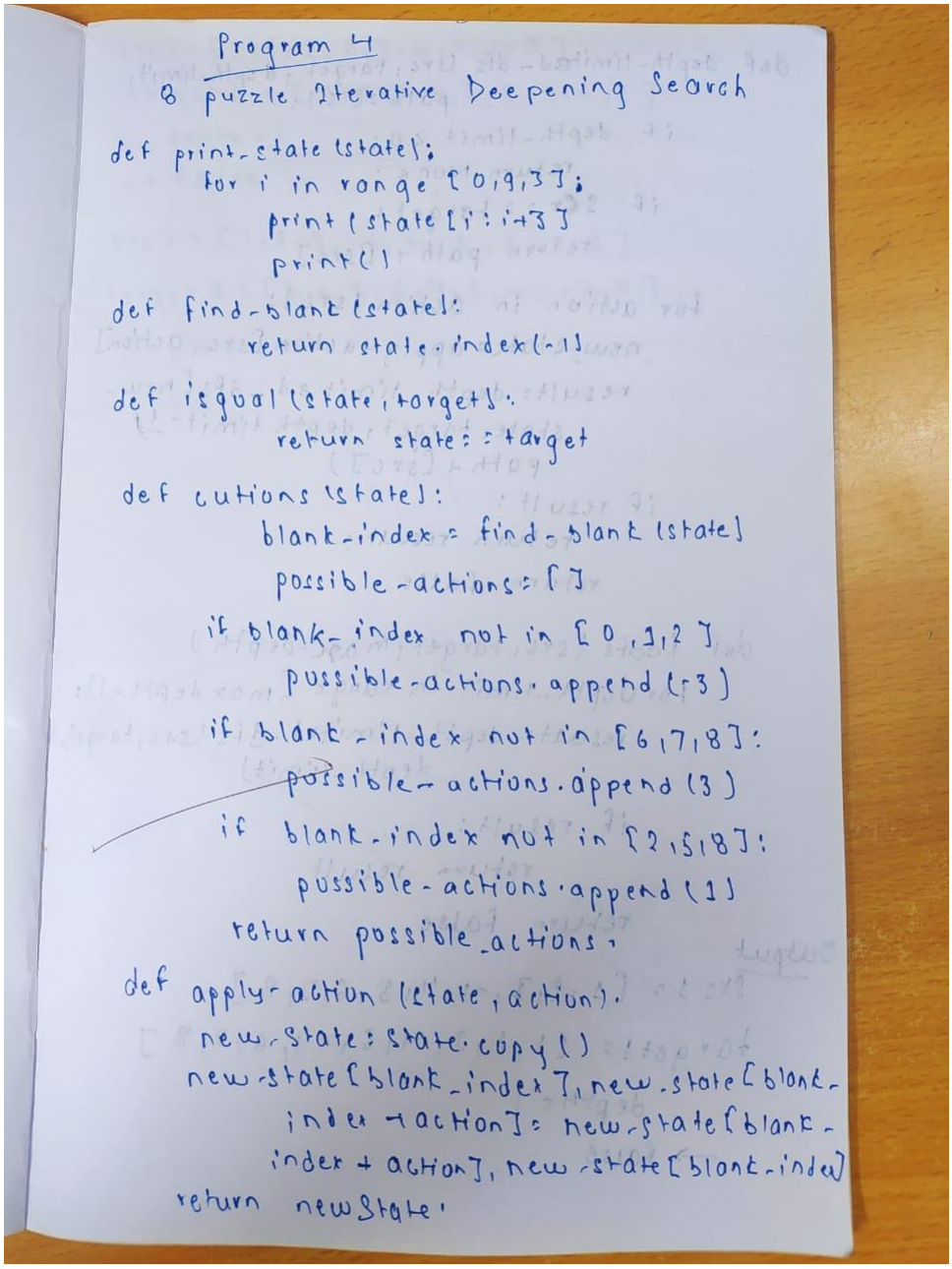
1	2	3
4	5	6
-1	7	8

Step 13:

1	2	3
4	5	6
7	-1	8

Step 14:

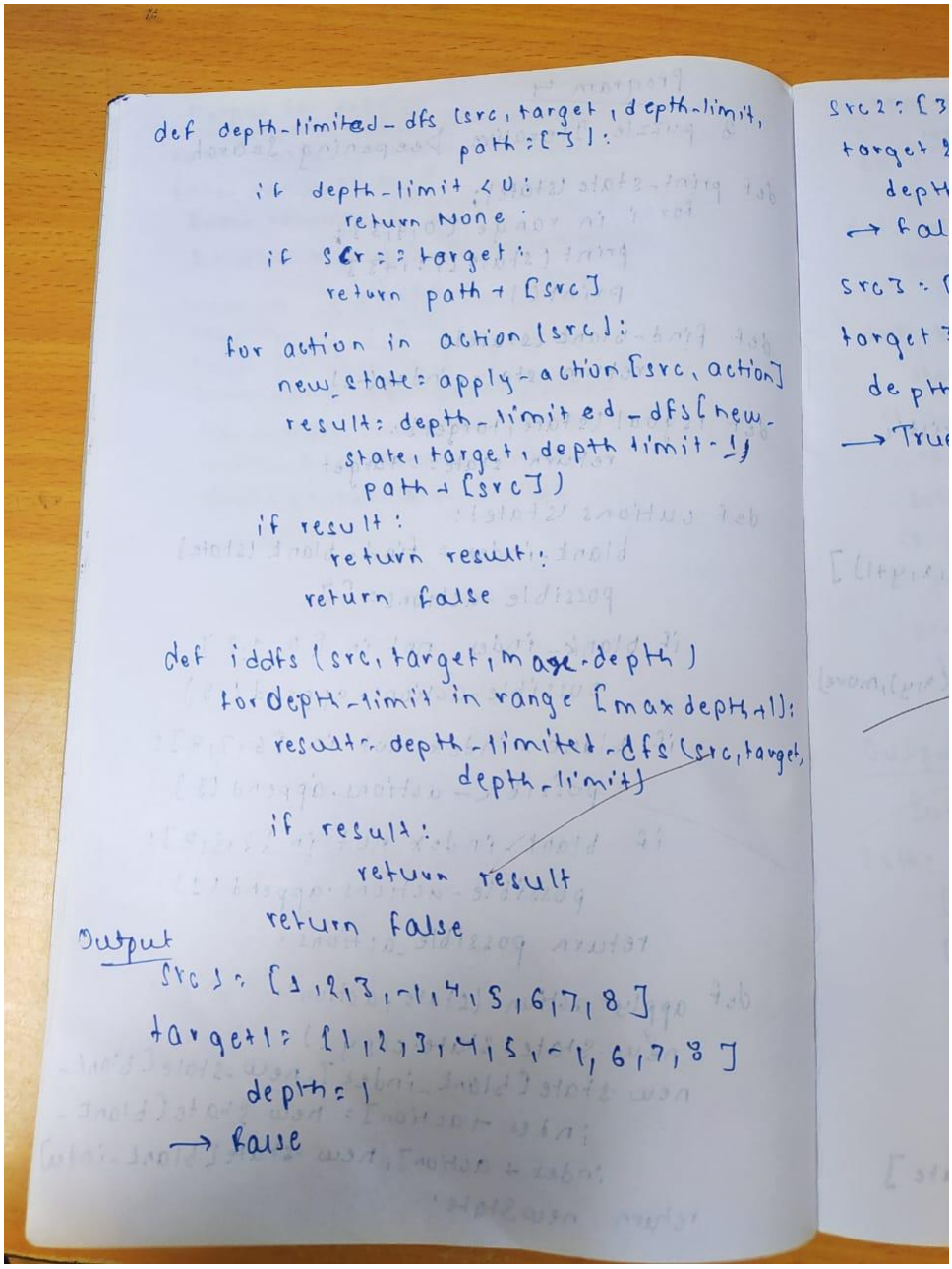
1	2	3
4	5	6
7	8	-1



Program 4

8 puzzle Iterative Deepening Search

```
def print_state(state):
    for i in range(0,9,3):
        print(state[i:i+3])
        print()

def find_blank(state):
    return state.index(-1)

def isgoal(state, target):
    return state == target

def actions(state):
    blank_index = find_blank(state)
    possible_actions = []
    if blank_index not in [0,1,2]:
        possible_actions.append(-3)
    if blank_index not in [6,7,8]:
        possible_actions.append(3)
    if blank_index not in [2,5,8]:
        possible_actions.append(1)
    return possible_actions.

def apply_action(state, action):
    new_state = state.copy()
    new_state[blank_index], new_state[blank_
        index + action] = new_state[blank_
        index + action], new_state[blank_index]
    return newState.
```



```
def depth_limited_dfs(src, target, depth_limit,
                      path=[]):
    if depth_limit < 0:
        return None
    if src == target:
        return path + [src]
    for action in action(src):
        new_state = apply_action[src, action]
        result = depth_limited_dfs[new_
            state, target, depth_limit-1,
            path + [src])
        if result:
            return result
        return false

def iddfs(src, target, max_depth)
    for depth_limit in range[max_depth+1):
        result = depth_limited_dfs(src, target,
                 depth_limit)
        if result:
            return result
        return false
```

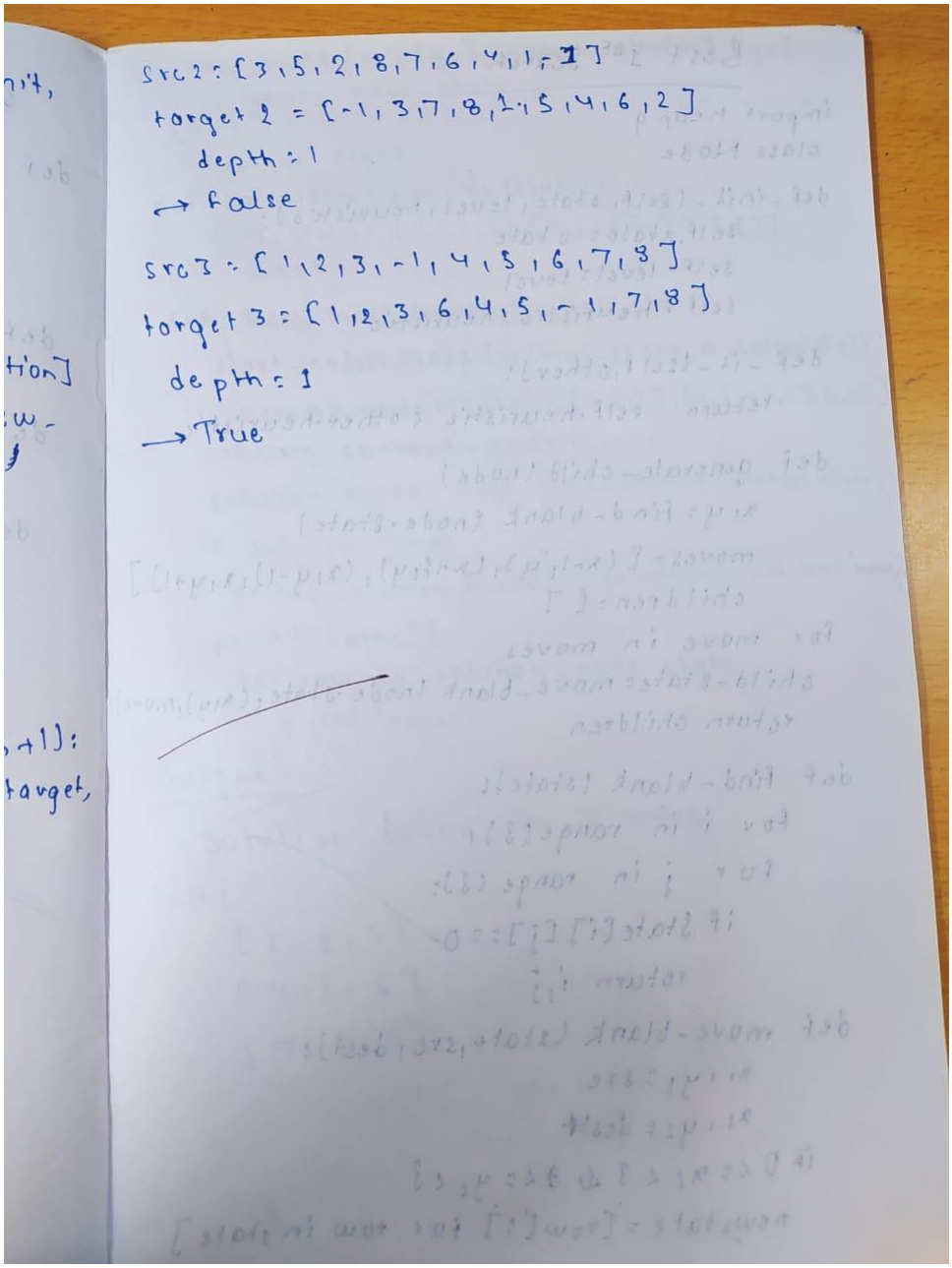
Output

src1 = [1,2,3,-1,4,5,6,7,8]

target1 = [1,2,3,4,5,-1,6,7,8]

depth = 1

→ false



src2 : [3, 5, 2, 8, 7, 6, 4, 1, -1]

target 2 = [-1, 3, 7, 8, 2, 5, 4, 6, 2]

depth : 1

→ false

src3 : [1, 2, 3, -1, 4, 5, 6, 7, 8]

target 3 : [1, 2, 3, 6, 4, 5, -1, 7, 8]

depth : 1

→ True

Best 1st Search

```
import heapq
class Node
def __init__(self, state, level, heuristic):
        self.state = state
        self.level = level
        self.heuristic = heuristic

def __it__(self, other):
    return  self.heuristic < other.heuristic

def  generate_child(node)
     x, y = find_blank (node.state)
     moves = [(x-1, y), (x+1, y), (x, y-1), x, y+1)]
      children = [ ]
for  move in moves
 child_state = move_blank (node.state, (x,y), move)
  return children

def find_blank (state):
    for i in range(3):
     for  j in range (3):
       if state[i][j] == 0
           return i, j
def move_blank (state, src, dest):
      x1, y1 = src
      x2, y2 = dest
  if 0 <= x2 < 3 & 0 <= y2 < 3
   newstate = [row[:] for row in state]
```

```
        new_state[x1][y1], new_state[x2][y2]
        return new_state
    else:
        return None
def calculate_heuristic(state):
    goal_state = [[1,2,3],[4,5,6],[7,8,0]]
    h = 0
def best_first_search(initial_state):
    start_node = Node(initial_state, 0, calculate(state))
if current_node.state == [[1,2,3],[4,5,6],[7,8,0]]
    return current_node
    solution_node = best_first_search(initial state)
    if solution_node:
    print("Solution found in", solution_node.level, "moves");
    print("Path:")
    for row in solution_node.state
        print(row)
```

Output

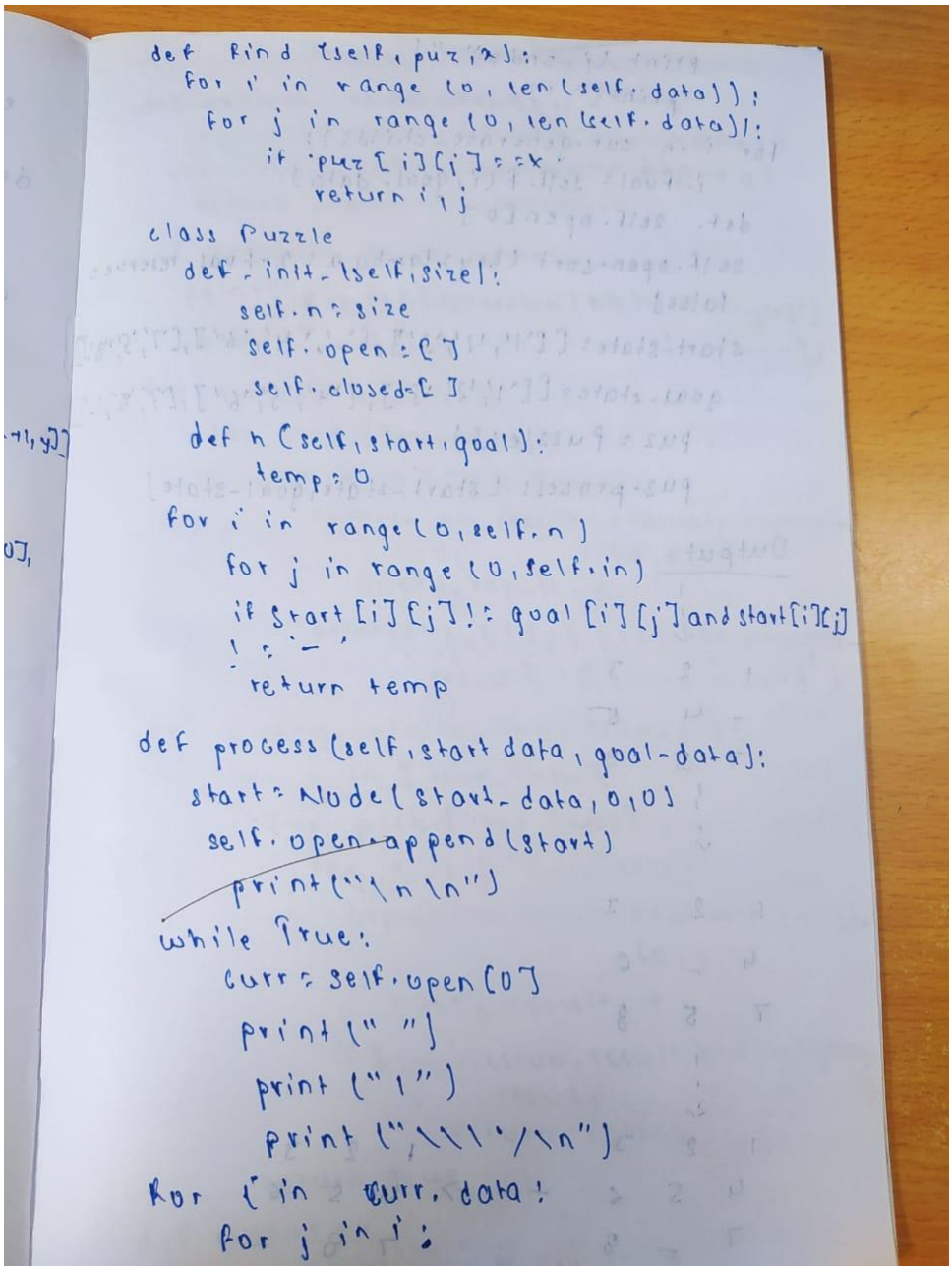
Solution found in 3 moves

Path:

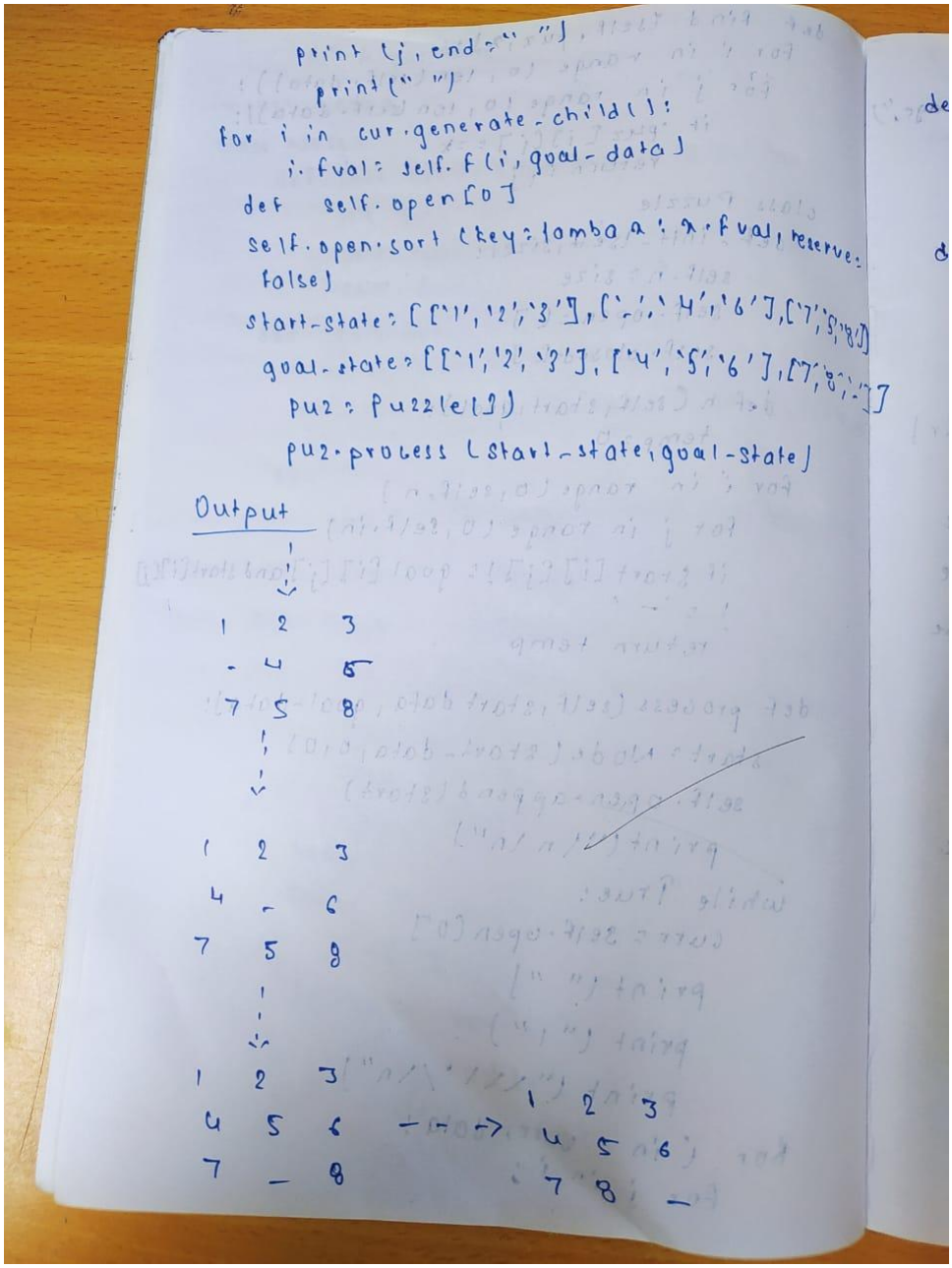
```
[1, 2, 3]
[4, 5, 6]
[7, 8, 0]
```

A* Algorithm

```
import heapq
class Node:
    def __init__(self, data, level, fval):
        self.data = data
        self.level = level
        self.fval = fval
    def generate_child(self):
        x, y = self.find(self.data, '_')
        val_list = [[x, y-1], [x, y+1], [x-1, y], [x+1, y]]
        children = []
        for i in val_list:
            child = self.shuffle(self.data, x, y, i[0],
                                 i[1])
            return children
    def shuffle(self, puz, x1, y1, x2, y2):
        if x2 >= 0 and x2 < len(self.data) and
        y2 >= 0
        y2 < len(self.data):
    def copy(self, root):
        temp = []
        for i in root:
            t = []
        for j in ~~root~~ i:
            t.append(j)
            temp.append(t)
        return temp
```



```
def find (self, puz, x):
    for i in range (0, len (self. data)):
        for j in range (0, len (self. data)):
            if puz [i] [j] == x:
                return i, j
class Puzzle
    def __init__(self, size):
        self. n = size
        self. open = []
        self. closed = []
    def h (self, start, goal):
        temp = 0
    for i in range (0, self. n)
        for j in range (0, self. in)
        if start [i] [j] != goal [i] [j] and start [i] [j]
        != '_':
            return temp
def process (self, start data, goal-data):
    start = Node (start_data, 0, 0)
    self. open. append (start)
    print ("\n \n")
while True:
    curr = self. open [0]
    print (" ")
    print ("|")
    print ("\\|'/\n")
for i in curr. data:
    for j in i:
```



```
        print(j, end=" ")
        print(" ")
for i in cur.generate_child():
    i.fval = self.f(i, goal_data)
def self.open[0]
self.open.sort(key=lamba a: x.fval, reserve=
 false)
start_state=[['1','2','3'],['_','4','6'],['7','5','8']]
goal_state=[['1','2','3'],['4','5','6'],['7','8','_']]
  puz = Puzzle(3)
  puz.process(start_state, goal_state)
```

Output

```
1 2 3
_ 4 6
7 5 8
  |
  v
1 2 3
4 _ 6
7 5 8
  |
  v
1 2 3
4 5 6 ---> 1 2 3
7 _ 8      4 5 6
           7 8 _
```

1. Implement Tic –Tac –Toe Game.

```
import math
import copy

X = "X"
O = "O"
EMPTY = None

def initial_state():
    return [[EMPTY, EMPTY, EMPTY],
            [EMPTY, EMPTY, EMPTY],
            [EMPTY, EMPTY, EMPTY]]

def player(board):
    countO = 0
    countX = 0
    for y in [0, 1, 2]:
        for x in board[y]:
            if x == "O":
                countO = countO + 1
            elif x == "X":
                countX = countX + 1
    if countO >= countX:
        return X
    elif countX > countO:
        return O



def actions(board):
```

```
    freeboxes = set()
    for i in [0, 1, 2]:
        for j in [0, 1, 2]:
            if board[i][j] == EMPTY:
                freeboxes.add((i, j))
    return freeboxes


def result(board, action):
    i = action[0]
    j = action[1]
    if type(action) == list:
        action = (i, j)
    if action in actions(board):
        if player(board) == X:
            board[i][j] = X
        elif player(board) == O:
            board[i][j] = O
    return board


def winner(board):
    if (board[0][0] == board[0][1] == board[0][2] == X or board[1][0] == board[1][1] ==
board[1][2] == X or board[2][0] == board[2][1] == board[2][2] == X):
        return X
    if (board[0][0] == board[0][1] == board[0][2] == O or board[1][0] == board[1][1] ==
board[1][2] == O or board[2][0] == board[2][1] == board[2][2] == O):
        return O
    for i in [0, 1, 2]:
        s2 = []
        for j in [0, 1, 2]:
```

```
            s2.append(board[j][i])
        if (s2[0] == s2[1] == s2[2]):
            return s2[0]
    strikeD = []
    for i in [0, 1, 2]:
        strikeD.append(board[i][i])
    if (strikeD[0] == strikeD[1] == strikeD[2]):
        return strikeD[0]
    if (board[0][2] == board[1][1] == board[2][0]):
        return board[0][2]
    return None


def terminal(board):
    Full = True
    for i in [0, 1, 2]:
        for j in board[i]:
            if j is None:
                Full = False
    if Full:
        return True
    if (winner(board) is not None):
        return True
    return False


def utility(board):
    if (winner(board) == X):
        return 1
    elif winner(board) == O:
```

```
        return -1
    else:
        return 0


def minimax_helper(board):
    isMaxTurn = True if player(board) == X else False
    if terminal(board):
        return utility(board)

    scores = []
    for move in actions(board):
        result(board, move)
        scores.append(minimax_helper(board))
        board[move[0]][move[1]] = EMPTY
    return max(scores) if isMaxTurn else min(scores)


def minimax(board):
    isMaxTurn = True if player(board) == X else False
    bestMove = None
    if isMaxTurn:
        bestScore = -math.inf
        for move in actions(board):
            result(board, move)
            score = minimax_helper(board)
            board[move[0]][move[1]] = EMPTY
            if (score > bestScore):
                bestScore = score
                bestMove = move
```

```
            return bestMove
        else:
            bestScore = +math.inf
            for move in actions(board):
                result(board, move)
                score = minimax_helper(board)
                board[move[0]][move[1]] = EMPTY
                if (score < bestScore):
                    bestScore = score
                    bestMove = move
            return bestMove


def print_board(board):
    for row in board:
        print(row)


# Example usage:
game_board = initial_state()
print("Initial Board:")
print_board(game_board)

while not terminal(game_board):
    if player(game_board) == X:
        user_input = input("\nEnter your move (row, column): ")
        row, col = map(int, user_input.split(','))
        result(game_board, (row, col))
    else:
        print("\nAI is making a move...")
```

```
        move = minimax(copy.deepcopy(game_board))
        result(game_board, move)

    print("\nCurrent Board:")
    print_board(game_board)

# Determine the winner
if winner(game_board) is not None:
    print(f"\nThe winner is: {winner(game_board)}")
else:
    print("\nIt's a tie!")
```

```
Initial Board:
[None, None, None]
[None, None, None]
[None, None, None]

Enter your move (row, column): 1,2

Current Board:
[None, None, None]
[None, None, 'X']
[None, None, None]

AI is making a move...

Current Board:
[None, None, None]
[None, 'O', 'X']
[None, None, None]

Enter your move (row, column): 0,0

Current Board:
['X', None, None]
[None, 'O', 'X']
[None, None, None]

AI is making a move...

Current Board:
['X', 'O', None]
[None, 'O', 'X']
[None, None, None]

Enter your move (row, column): 2,1
```

```
Current Board:
['X', 'O', None]
[None, 'O', 'X']
[None, 'X', None]

AI is making a move...

Current Board:
['X', 'O', None]
[None, 'O', 'X']
['O', 'X', None]

Enter your move (row, column): 1,0

Current Board:
['X', 'O', None]
['X', 'O', 'X']
['O', 'X', None]

AI is making a move...

Current Board:
['X', 'O', 'O']
['X', 'O', 'X']
['O', 'X', None]

The winner is: O
```

OUTPUT:

2. Solve 8 puzzle problems.

```
def bfs(src,target):
    queue = []
    queue.append(src)

    exp = []

    while len(queue) > 0:
        source = queue.pop(0)
        exp.append(source)

        print(source)

        if source==target:
            print("Success")
            return

        poss_moves_to_do = []
        poss_moves_to_do = possible_moves(source,exp)

        for move in poss_moves_to_do:

            if move not in exp and move not in queue:
                queue.append(move)
def possible_moves(state,visited_states):
    #index of empty spot
    b = state.index(0)
```

```
    #directions array
    d = []
    #Add all the possible directions

    if b not in [0,1,2]:
        d.append('u')
    if b not in [6,7,8]:
        d.append('d')
    if b not in [0,3,6]:
        d.append('l')
    if b not in [2,5,8]:
        d.append('r')



    # If direction is possible then add state to move
    pos_moves_it_can = []

    # for all possible directions find the state if that move is played
    ### Jump to gen function to generate all possible moves in the given directions

    for i in d:
        pos_moves_it_can.append(gen(state,i,b))

    return [move_it_can for move_it_can in pos_moves_it_can if move_it_can not in
visited_states]
def gen(state, m, b):
    temp = state.copy()

    if m=='d':
        temp[b+3],temp[b] = temp[b],temp[b+3]
```

```
    if m=='u':
        temp[b-3],temp[b] = temp[b],temp[b-3]

    if m=='l':
        temp[b-1],temp[b] = temp[b],temp[b-1]

    if m=='r':
        temp[b+1],temp[b] = temp[b],temp[b+1]



    # return new state with tested move to later check if "src == target"
    return temp

print("Example 1")
src= [2,0,3,1,8,4,7,6,5]
target=[1,2,3,8,0,4,7,6,5]
print("Source: " , src)
print("Goal State: " , target)
bfs(src, target)

print("\nExample 2")
src = [1,2,3,0,4,5,6,7,8]
target = [1,2,3,4,5,0,6,7,8]
print("Source: " , src)
print("Goal State: " , target)
bfs(src, target)
```

OUTPUT:

```
Example 1
Source:  [2, 0, 3, 1, 8, 4, 7, 6, 5]
Goal State:  [1, 2, 3, 8, 0, 4, 7, 6, 5]
[2, 0, 3, 1, 8, 4, 7, 6, 5]
[2, 8, 3, 1, 0, 4, 7, 6, 5]
[0, 2, 3, 1, 8, 4, 7, 6, 5]
[2, 3, 0, 1, 8, 4, 7, 6, 5]
[2, 8, 3, 1, 6, 4, 7, 0, 5]
[2, 8, 3, 0, 1, 4, 7, 6, 5]
[2, 8, 3, 1, 4, 0, 7, 6, 5]
[1, 2, 3, 0, 8, 4, 7, 6, 5]
[2, 3, 4, 1, 8, 0, 7, 6, 5]
[2, 8, 3, 1, 6, 4, 0, 7, 5]
[2, 8, 3, 1, 6, 4, 7, 5, 0]
[0, 8, 3, 2, 1, 4, 7, 6, 5]
[2, 8, 3, 7, 1, 4, 0, 6, 5]
[2, 8, 0, 1, 4, 3, 7, 6, 5]
[2, 8, 3, 1, 4, 5, 7, 6, 0]
[1, 2, 3, 7, 8, 4, 0, 6, 5]
[1, 2, 3, 8, 0, 4, 7, 6, 5]
Success

Example 2
Source:  [1, 2, 3, 0, 4, 5, 6, 7, 8]
Goal State:  [1, 2, 3, 4, 5, 0, 6, 7, 8]
[1, 2, 3, 0, 4, 5, 6, 7, 8]
[0, 2, 3, 1, 4, 5, 6, 7, 8]
[1, 2, 3, 6, 4, 5, 0, 7, 8]
[1, 2, 3, 4, 0, 5, 6, 7, 8]
[2, 0, 3, 1, 4, 5, 6, 7, 8]
[1, 2, 3, 6, 4, 5, 7, 0, 8]
[1, 0, 3, 4, 2, 5, 6, 7, 8]
[1, 2, 3, 4, 7, 5, 6, 0, 8]
[1, 2, 3, 4, 5, 0, 6, 7, 8]
Success
```

3. Implement Iterative deepening search algorithm.

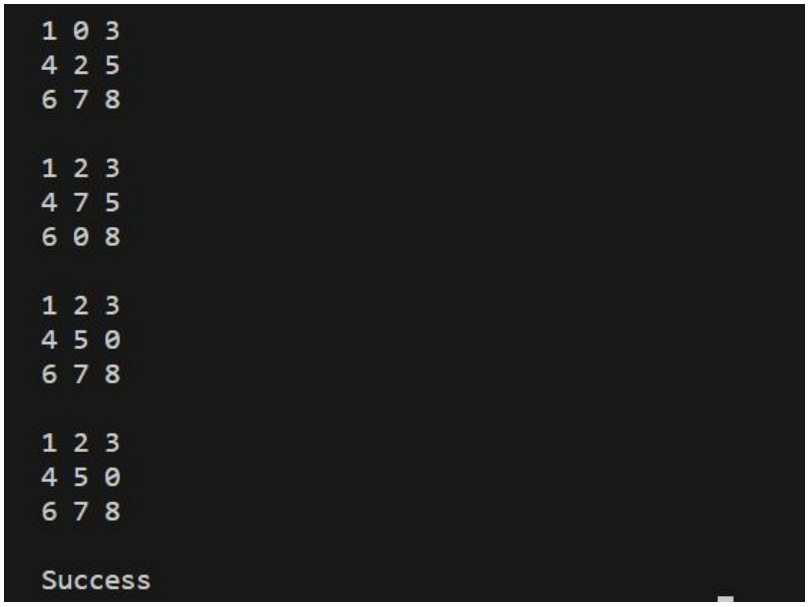
```
def iterative_deepening_search(src, target):
    depth_limit = 0
    while True:
        result = depth_limited_search(src, target, depth_limit, [])
        if result is not None:
            print("Success")
            return
        depth_limit += 1
        if depth_limit > 30:  # Set a reasonable depth limit to avoid an infinite loop
            print("Solution not found within depth limit.")
            return

def depth_limited_search(src, target, depth_limit, visited_states):
    if src == target:
        print_state(src)
        return src

    if depth_limit == 0:
        return None

    visited_states.append(src)
    poss_moves_to_do = possible_moves(src, visited_states)

    for move in poss_moves_to_do:
        if move not in visited_states:
            print_state(move)
            result = depth_limited_search(move, target, depth_limit - 1, visited_states)
```

```
            if result is not None:
                return result

    return None

def possible_moves(state, visited_states):
    b = state.index(0)
    d = []

    if b not in [0, 1, 2]:
        d.append('u')
    if b not in [6, 7, 8]:
        d.append('d')
    if b not in [0, 3, 6]:
        d.append('l')
    if b not in [2, 5, 8]:
        d.append('r')

    pos_moves_it_can = []

    for i in d:
        pos_moves_it_can.append(gen(state, i, b))

    return [move_it_can for move_it_can in pos_moves_it_can if move_it_can not in
visited_states]

def gen(state, m, b):
    temp = state.copy()

    if m == 'd':
        temp[b + 3], temp[b] = temp[b], temp[b + 3]
```

```
    elif m == 'u':
        temp[b - 3], temp[b] = temp[b], temp[b - 3]
    elif m == 'l':
        temp[b - 1], temp[b] = temp[b], temp[b - 1]
    elif m == 'r':
        temp[b + 1], temp[b] = temp[b], temp[b + 1]

    return temp


def print_state(state):
    print(f"{state[0]} {state[1]} {state[2]}\n{state[3]} {state[4]} {state[5]}\n{state[6]}
{state[7]} {state[8]}\n")


print("Example 1")
src = [1,2,3,0,4,5,6,7,8]
target = [1,2,3,4,5,0,6,7,8]
print("Source: " , src)
print("Goal State: " , target)
iterative_deepening_search(src, target)
```

OUTPUT:

```
Example 1
Source:  [1, 2, 3, 0, 4, 5, 6, 7, 8]
Goal State:  [1, 2, 3, 4, 5, 0, 6, 7, 8]
0 2 3
1 4 5
6 7 8

1 2 3
6 4 5
0 7 8

1 2 3
4 0 5
6 7 8

0 2 3
1 4 5
6 7 8

2 0 3
1 4 5
6 7 8

1 2 3
6 4 5
0 7 8

1 2 3
6 4 5
7 0 8

1 2 3
4 0 5
6 7 8
```



4. Implement A* search algorithm.

```
def print_grid(src):
    state = src.copy()
    state[state.index(-1)] = ' '
    print(
        f"""
{state[0]} {state[1]} {state[2]}
{state[3]} {state[4]} {state[5]}
{state[6]} {state[7]} {state[8]}
        """
    )

def h(state, target):
    #Manhattan distance
    dist = 0
    for i in state:
        d1, d2 = state.index(i), target.index(i)
        x1, y1 = d1 % 3, d1 // 3
        x2, y2 = d2 % 3, d2 // 3
```

```
        dist += abs(x1-x2) + abs(y1-y2)
    return dist


def astar(src, target):
    states = [src]
    g = 0
    visited_states = set()
    while len(states):
        moves = []
        for state in states:
            visited_states.add(tuple(state))
            print_grid(state)
            if state == target:
                print("Success")
                return
            moves += [move for move in possible_moves(state, visited_states) if move not in
moves]
        costs = [g + h(move, target) for move in moves]
        states = [moves[i] for i in range(len(moves)) if costs[i] == min(costs)]
        g += 1
    print("Fail")


def possible_moves(state, visited_states):
    b = state.index(-1)
    d = []
    if 9 > b - 3 >= 0:
        d += 'u'
    if 9 > b + 3 >= 0:
        d += 'd'
    if b not in [2,5,8]:
        d += 'r'
```

```
    if b not in [0,3,6]:
        d += 'l'
    pos_moves = []
    for move in d:
        pos_moves.append(gen(state,move,b))
    return [move for move in pos_moves if tuple(move) not in visited_states]

def gen(state, direction, b):
    temp = state.copy()
    if direction == 'u':
        temp[b-3], temp[b] = temp[b], temp[b-3]
    if direction == 'd':
        temp[b+3], temp[b] = temp[b], temp[b+3]
    if direction == 'r':
        temp[b+1], temp[b] = temp[b], temp[b+1]
    if direction == 'l':
        temp[b-1], temp[b] = temp[b], temp[b-1]
    return temp

#Test 1
print("Example 1")
src = [1,2,3,-1,4,5,6,7,8]
target = [1,2,3,4,5,-1,6,7,8]
print("Source: " , src)
print("Goal State: " , target)
astar(src, target)


# Test 2
print("Example 2")
```

```
src = [1,2,3,-1,4,5,6,7,8]
target=[1,2,3,6,4,5,-1,7,8]
print("Source: " , src)
print("Goal State: " , target)
astar(src, target)


# Test 3
print("Example 3")
src = [1,2,3,7,4,5,6,-1,8]
target=[1,2,3,6,4,5,-1,7,8]
print("Source: " , src)
print("Goal State: " , target)
astar(src, target)
```

OUTPUT:

```
Example 1
Source:  [1, 2, 3, -1, 4, 5, 6, 7, 8]
Goal State:  [1, 2, 3, 4, 5, -1, 6, 7, 8]

1 2 3
  4 5
6 7 8


1 2 3
4   5
6 7 8


1 2 3
4 5
6 7 8

Success
Example 2
Source:  [1, 2, 3, -1, 4, 5, 6, 7, 8]
Goal State:  [1, 2, 3, 6, 4, 5, -1, 7, 8]

1 2 3
  4 5
6 7 8


1 2 3
6 4 5
  7 8

Success
```

```
Example 3
Source:  [1, 2, 3, 7, 4, 5, 6, -1, 8]
Goal State:  [1, 2, 3, 6, 4, 5, -1, 7, 8]

1 2 3
7 4 5
6   8


1 2 3
7 4 5
  6 8


1 2 3
  4 5
7 6 8


  2 3
1 4 5
7 6 8


1 2 3
4   5
7 6 8


1 2 3
4 6 5
7   8
```

```
1 2 3
  6 5
4 7 8


1 2 3
6   5
4 7 8


1 2 3
6 7 5
4   8


1 2 3
6 7 5
  4 8


1 2 3
  7 5
6 4 8


  2 3
1 7 5
6 4 8


1 2 3
7   5
6 4 8
```

```
7 1 3
4 6 5
  2 8


7 1 3
4 6 5
2   8


7 1 3
4   5
2 6 8


7 1 3
4 6 5
2 8


7 1 3
  4 5
2 6 8


7 1 3
2 4 5
  6 8

Fail
```

5. Implement vacuum cleaner agent.

```
def clean(floor, row, col):
    i, j, m, n = row, col, len(floor), len(floor[0])
    goRight = goDown = True
    cleaned = [not any(f) for f in floor]
    while not all(cleaned):
        while any(floor[i]):
            print_floor(floor, i, j)
            if floor[i][j]:
                floor[i][j] = 0
                print_floor(floor, i, j)
            if not any(floor[i]):
                cleaned[i] = True
                break
            if j == n - 1:
                j -= 1
                goRight = False
            elif j == 0:
                j += 1
                goRight = True
            else:
                j += 1 if goRight else -1
        if all(cleaned):
            break
        if i == m - 1:
            i -= 1
            goDown = False
        elif i == 0:
            i += 1
```

```
            goDown = True
        else:
            i += 1 if goDown else -1
        if cleaned[i]:
            print_floor(floor, i, j)

def print_floor(floor, row, col): # row, col represent the current vacuum cleaner position
    for r in range(len(floor)):
        for c in range(len(floor[r])):
            if r == row and c == col:
                print(f" >{floor[r][c]}< ", end = '')
            else:
                print(f"  {floor[r][c]}  ", end = '')
        print(end = '\n')
    print(end = '\n')

# Test 1
floor = [[1, 0, 0, 0],
         [0, 1, 0, 1],
         [1, 0, 1, 1]]

print("Room Condition: ")
for row in floor:
    print(row)
print("\n")
clean(floor, 1, 2)
```

OUTPUT:

```
Room Condition:
[1, 0, 0, 0]
[0, 1, 0, 1]
[1, 0, 1, 1]


 1   0   0   0
 0   1  >0<  1
 1   0   1   1

 1   0   0   0
 0   1   0  >1<
 1   0   1   1

 1   0   0   0
 0   1   0  >0<
 1   0   1   1

 1   0   0   0
 0   1  >0<  0
 1   0   1   1

 1   0   0   0
 0  >1<  0   0
 1   0   1   1

 1   0   0   0
 0  >0<  0   0
 1   0   1   1

 1   0   0   0
 0   0   0   0
 1  >0<  1   1
```

```
 1   0   0   0
 0   0   0   0
>1<  0   1   1

 1   0   0   0
 0   0   0   0
>0<  0   1   1

 1   0   0   0
 0   0   0   0
 0  >0<  1   1

 1   0   0   0
 0   0   0   0
 0   0  >1<  1

 1   0   0   0
 0   0   0   0
 0   0  >0<  1

 1   0   0   0
 0   0   0   0
 0   0   0  >1<

 1   0   0   0
 0   0   0   0
 0   0   0  >0<

 1   0   0   0
 0   0   0  >0<
 0   0   0   0

 1   0   0  >0<
 0   0   0   0
 0   0   0   0
```

```
 1   0  >0<  0
 0   0   0   0
 0   0   0   0

 1  >0<  0   0
 0   0   0   0
 0   0   0   0

>1<  0   0   0
 0   0   0   0
 0   0   0   0

>0<  0   0   0
 0   0   0   0
 0   0   0   0
```

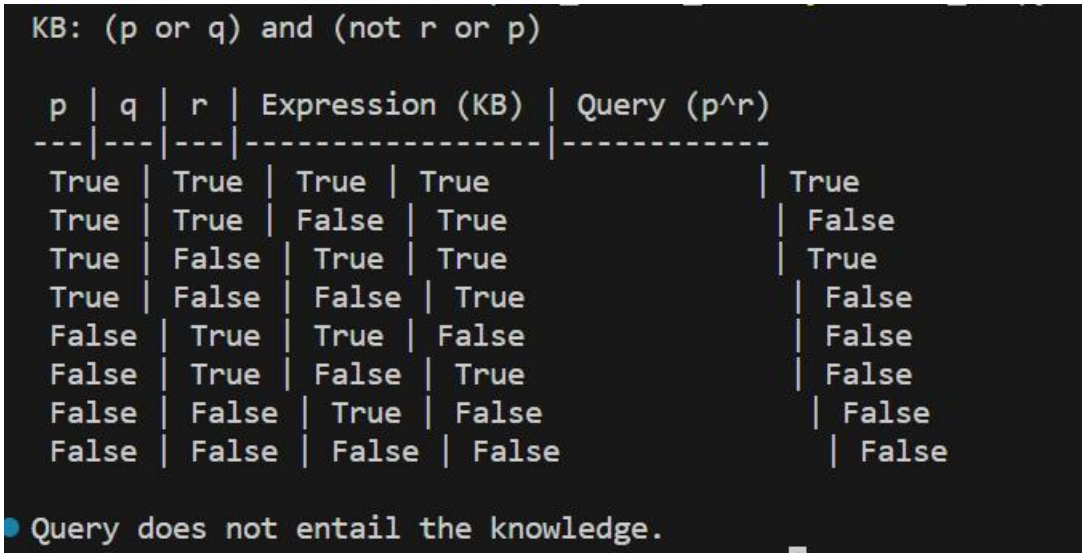
6. **Create a** **knowledge**

base using prepositional logic and show that the given query entails the knowledge base or not.

```
def evaluate_expression(p, q, r):
    expression_result = (p or q) and (not r or p)
    return expression_result

def generate_truth_table():
    print(" p | q | r | Expression (KB) | Query (p^r)")
    print("---|---|---|-----------------|------------")

    for p in [True, False]:
        for q in [True, False]:
            for r in [True, False]:
                expression_result = evaluate_expression(p, q, r)
                query_result = p and r

                print(f" {p} | {q} | {r} | {expression_result}              | {query_result}")

def query_entails_knowledge():
    for p in [True, False]:
        for q in [True, False]:
            for r in [True, False]:
                expression_result = evaluate_expression(p, q, r)
                query_result = p and r

                if expression_result and not query_result:
                    return False

    return True
```

```
def main():
    generate_truth_table()

    if query_entails_knowledge():
        print("\nQuery entails the knowledge.")
    else:
        print("\nQuery does not entail the knowledge.")

if __name__ == "__main__":
    main()
```

OUTPUT:



7. Create a knowledge base using prepositional logic and prove the given query using resolution

```
import re


def main(rules, goal):
    rules = rules.split(' ')
    steps = resolve(rules, goal)
    print('\nStep\t|Clause\t|Derivation\t')
    print('-' * 30)
    i = 1
    for step in steps:
        print(f' {i}.\t| {step}\t| {steps[step]}\t')
        i += 1
def negate(term):
    return f'~{term}' if term[0] != '~' else term[1]


def reverse(clause):
    if len(clause) > 2:
        t = split_terms(clause)
        return f'{t[1]}v{t[0]}'
    return ''
def split_terms(rule):
    exp = '(~*[PQRS])'
    terms = re.findall(exp, rule)
    return terms


split_terms('~PvR')
def contradiction(goal, clause):
    contradictions = [ f'{goal}v{negate(goal)}', f'{negate(goal)}v{goal}']
    return clause in contradictions or reverse(clause) in contradictions
def resolve(rules, goal):
```

```
    temp = rules.copy()
    temp += [negate(goal)]
    steps = dict()
    for rule in temp:
        steps[rule] = 'Given.'
    steps[negate(goal)] = 'Negated conclusion.'
    i = 0
    while i < len(temp):
        n = len(temp)
        j = (i + 1) % n
        clauses = []
        while j != i:
            terms1 = split_terms(temp[i])
            terms2 = split_terms(temp[j])
            for c in terms1:
                if negate(c) in terms2:
                    t1 = [t for t in terms1 if t != c]
                    t2 = [t for t in terms2 if t != negate(c)]
                    gen = t1 + t2
                    if len(gen) == 2:
                        if gen[0] != negate(gen[1]):
                            clauses += [f'{gen[0]}v{gen[1]}']
                        else:
                            if contradiction(goal,f'{gen[0]}v{gen[1]}'):
                                temp.append(f'{gen[0]}v{gen[1]}')
                                steps[''] = f'Resolved {temp[i]} and {temp[j]} to {temp[-1]}, which is in
turn null. \
                                \nA contradiction is found when {negate(goal)} is assumed as true.
Hence, {goal} is true."
                                return steps
                    elif len(gen) == 1:
```

```
                clauses += [f'{gen[0]}']
            else:
                if contradiction(goal,f'{terms1[0]}v{terms2[0]}'):
                    temp.append(f'{terms1[0]}v{terms2[0]}')
                    steps[''] = f"Resolved {temp[i]} and {temp[j]} to {temp[-1]}, which is in turn null. \
                    \nA contradiction is found when {negate(goal)} is assumed as true. Hence, {goal} is true."
                    return steps
        for clause in clauses:
            if clause not in temp and clause != reverse(clause) and reverse(clause) not in temp:
                temp.append(clause)
                steps[clause] = f'Resolved from {temp[i]} and {temp[j]}.'
        j = (j + 1) % n
    i += 1
  return steps
rules = 'Rv~P Rv~Q ~RvP ~RvQ' #(P^Q)<=>R : (Rv~P)v(Rv~Q)^(~RvP)^(~RvQ)
goal = 'R'
print('Rules: ',rules)
print("Goal: ",goal)
main(rules, goal)

rules = 'PvQ ~PvR ~QvR' #P=vQ, P=>Q : ~PvQ, Q=>R, ~QvR
goal = 'R'
print('Rules: ',rules)
print("Goal: ",goal)
main(rules, goal)

rules = 'PvQ PvR ~PvR RvS Rv~Q ~Sv~Q' # (P=>Q)=>Q, (P=>P)=>R, (R=>S)=>~(S=>Q)
goal = 'R'
print('Rules: ',rules)
```

print("Goal: ",goal)

main(rules, goal)

OUTPUT:

```
Example 1
Rules:  Rv~P Rv~Q ~RvP ~RvQ
Goal:  R

Step    |Clause |Derivation
-----------------------------
 1.     | Rv~P  | Given.
 2.     | Rv~Q  | Given.
 3.     | ~RvP  | Given.
 4.     | ~RvQ  | Given.
 5.     | ~R    | Negated conclusion.
 6.     |       | Resolved Rv~P and ~RvP to Rv~R, which is in turn null.
A contradiction is found when ~R is assumed as true. Hence, R is true.

Example 2
Rules:  PvQ ~PvR ~QvR
Goal:  R

Step    |Clause |Derivation
-----------------------------
 1.     | PvQ   | Given.
 2.     | ~PvR  | Given.
 3.     | ~QvR  | Given.
 4.     | ~R    | Negated conclusion.
 5.     | QvR   | Resolved from PvQ and ~PvR.
 6.     | PvR   | Resolved from PvQ and ~QvR.
 7.     | ~P    | Resolved from ~PvR and ~R.
 8.     | ~Q    | Resolved from ~QvR and ~R.
 9.     | Q     | Resolved from ~R and QvR.
 10.    | P     | Resolved from ~R and PvR.
 11.    | R     | Resolved from QvR and ~Q.
 12.    |       | Resolved R and ~R to Rv~R, which is in turn null.
A contradiction is found when ~R is assumed as true. Hence, R is true.
```

```
Example 3
Rules:  PvQ PvR ~PvR RvS Rv~Q ~Sv~Q
Goal:  R

Step    |Clause |Derivation
-----------------------------
 1.     | PvQ   | Given.
 2.     | PvR   | Given.
 3.     | ~PvR  | Given.
 4.     | RvS   | Given.
 5.     | Rv~Q  | Given.
 6.     | ~Sv~Q | Given.
 7.     | ~R    | Negated conclusion.
 8.     | QvR   | Resolved from PvQ and ~PvR.
 9.     | Pv~S  | Resolved from PvQ and ~Sv~Q.
 10.    | P     | Resolved from PvR and ~R.
 11.    | ~P    | Resolved from ~PvR and ~R.
 12.    | Rv~S  | Resolved from ~PvR and Pv~S.
 13.    | R     | Resolved from ~PvR and P.
 14.    | S     | Resolved from RvS and ~R.
 15.    | ~Q    | Resolved from Rv~Q and ~R.
 16.    | Q     | Resolved from ~R and QvR.
 17.    | ~S    | Resolved from ~R and Rv~S.
 18.    |       | Resolved ~R and R to ~RvR, which is in turn null.
A contradiction is found when ~R is assumed as true. Hence, R is true.
```

8. Implement unification in first order logic

```
import re

def getAttributes(expression):
    expression = expression.split("(")[1:]
    expression = "(".join(expression)
    expression = expression[:-1]
    expression = re.split("(?<!\(.),(?!.\))", expression)
    return expression

def getInitialPredicate(expression):
    return expression.split("(")[0]

def isConstant(char):
    return char.isupper() and len(char) == 1

def isVariable(char):
    return char.islower() and len(char) == 1

def replaceAttributes(exp, old, new):
    attributes = getAttributes(exp)
    for index, val in enumerate(attributes):
        if val == old:
            attributes[index] = new
    predicate = getInitialPredicate(exp)
    return predicate + "(" + ",".join(attributes) + ")"

def apply(exp, substitutions):
    for substitution in substitutions:
```

```
        new, old = substitution
        exp = replaceAttributes(exp, old, new)
    return exp

def checkOccurs(var, exp):
    if exp.find(var) == -1:
        return False
    return True



def getFirstPart(expression):
    attributes = getAttributes(expression)
    return attributes[0]



def getRemainingPart(expression):
    predicate = getInitialPredicate(expression)
    attributes = getAttributes(expression)
    newExpression = predicate + "(" + ",".join(attributes[1:]) + ")"
    return newExpression

def unify(exp1, exp2):
    if exp1 == exp2:
        return []

    if isConstant(exp1) and isConstant(exp2):
        if exp1 != exp2:
            return False

    if isConstant(exp1):
```

```
    return [(exp1, exp2)]

if isConstant(exp2):
    return [(exp2, exp1)]

if isVariable(exp1):
    if checkOccurs(exp1, exp2):
        return False
    else:
        return [(exp2, exp1)]

if isVariable(exp2):
    if checkOccurs(exp2, exp1):
        return False
    else:
        return [(exp1, exp2)]

if getInitialPredicate(exp1) != getInitialPredicate(exp2):
    print("Predicates do not match. Cannot be unified")
    return False

attributeCount1 = len(getAttributes(exp1))
attributeCount2 = len(getAttributes(exp2))
if attributeCount1 != attributeCount2:
    return False

head1 = getFirstPart(exp1)
head2 = getFirstPart(exp2)
initialSubstitution = unify(head1, head2)
if not initialSubstitution:
```

```
        return False
    if attributeCount1 == 1:
        return initialSubstitution

    tail1 = getRemainingPart(exp1)
    tail2 = getRemainingPart(exp2)

    if initialSubstitution != []:
        tail1 = apply(tail1, initialSubstitution)
        tail2 = apply(tail2, initialSubstitution)

    remainingSubstitution = unify(tail1, tail2)
    if not remainingSubstitution:
        return False

    initialSubstitution.extend(remainingSubstitution)
    return initialSubstitution

print("\nExample 1")
exp1 = "knows(f(x),y)"
exp2 = "knows(J,John)"
print("Expression 1: ",exp1)
print("Expression 2: ",exp2)

substitutions = unify(exp1, exp2)
print("Substitutions:")
print(substitutions)

print("\nExample 2")
exp1 = "knows(John,x)"
```

```
exp2 = "knows(y,mother(y))"
print("Expression 1: ",exp1)
print("Expression 2: ",exp2)

substitutions = unify(exp1, exp2)
print("Substitutions:")
print(substitutions)


print("\nExample 3")
exp1 = "Student(x)"
exp2 = "Teacher(Rose)"
print("Expression 1: ",exp1)
print("Expression 2: ",exp2)

substitutions = unify(exp1, exp2)
print("Substitutions:")
print(substitutions)
```

OUTPUT:

```
Example 1
Expression 1:  knows(f(x),y)
Expression 2:  knows(J,John)
Substitutions:
[('J', 'f(x)'), ('John', 'y')]

Example 2
Expression 1:  knows(John,x)
Expression 2:  knows(y,mother(y))
Substitutions:
[('John', 'y'), ('mother(y)', 'x')]

Example 3
Expression 1:  Student(x)
Expression 2:  Teacher(Rose)
Predicates do not match. Cannot be unified
Substitutions:
False
```

9. Convert a given first order logic statement into Conjunctive Normal Form (CNF).

```
def getAttributes(string):
    expr = '\([^)]+\)'
    matches = re.findall(expr, string)
    return [m for m in str(matches) if m.isalpha()]

def getPredicates(string):
    expr = '[a-z~]+\([A-Za-z,]+\)'
    return re.findall(expr, string)

def Skolemization(statement):
    SKOLEM_CONSTANTS = [f'{chr(c)}' for c in range(ord('A'), ord('Z')+1)]
    matches = re.findall('[∃].', statement)
    for match in matches[::-1]:
        statement = statement.replace(match, '')
        for predicate in getPredicates(statement):
            attributes = getAttributes(predicate)
            if ''.join(attributes).islower():
                statement = statement.replace(match[1],SKOLEM_CONSTANTS.pop(0))
    return statement
import re

def fol_to_cnf(fol):
    statement = fol.replace("=>", "-")
    expr = '\[([^]]+)\]'
    statements = re.findall(expr, statement)
    for i, s in enumerate(statements):
        if '[' in s and ']' not in s:
            statements[i] += ']'
```

```
    for s in statements:
        statement = statement.replace(s, fol_to_cnf(s))
    while '-' in statement:
        i = statement.index('-')
        br = statement.index('[') if '[' in statement else 0
        new_statement = '~' + statement[br:i] + '|' + statement[i+1:]
        statement = statement[:br] + new_statement if br > 0 else new_statement
    return Skolemization(statement)

print(fol_to_cnf("bird(x)=>~fly(x)"))
print(fol_to_cnf("∃x[bird(x)=>~fly(x)]"))

print(Skolemization(fol_to_cnf("animal(y)<=>loves(x,y)")))
print(Skolemization(fol_to_cnf("∀x[∀y[animal(y)=>loves(x,y)]]=>[∃z[loves(z,x)]]")))
print(fol_to_cnf("[american(x)&weapon(y)&sells(x,y,z)&hostile(z)]=>criminal(x)"))
```

OUTPUT:

```
Example 1
FOL: bird(x)=>~fly(x)
CNF:  ~bird(x)|~fly(x)

Example 2
FOL: ∃x[bird(x)=>~fly(x)]
CNF:  [~bird(A)|~fly(A)]

Example 3
FOL: animal(y)<=>loves(x,y)
CNF:  ~animal(y)<|loves(x,y)

Example 4
FOL: ∀x[∀y[animal(y)=>loves(x,y)]]=>[∃z[loves(z,x)]]
CNF:  ∀x~[∀y[~animal(y)|loves(x,y)]]|[[loves(A,x)]]

Example 5
FOL: [american(x)&weapon(y)&sells(x,y,z)&hostile(z)]=>criminal(x)
CNF:  ~[american(x)&weapon(y)&sells(x,y,z)&hostile(z)]|criminal(x)
```

10. Create a knowledge base consisting of first order logic statements and prove the given query using forward reasoning.

```
import re


def isVariable(x):
    return len(x) == 1 and x.islower() and x.isalpha()


def getAttributes(string):
    expr = '\([^)]+\)'
    matches = re.findall(expr, string)
    return matches


def getPredicates(string):
    expr = '([a-z~]+)\([^&|]+\)'
    return re.findall(expr, string)


class Fact:
    def __init__(self, expression):
        self.expression = expression
        predicate, params = self.splitExpression(expression)
        self.predicate = predicate
        self.params = params
        self.result = any(self.getConstants())


    def splitExpression(self, expression):
        predicate = getPredicates(expression)[0]
        params = getAttributes(expression)[0].strip('()').split(',')
        return [predicate, params]


    def getResult(self):
```

```
        return self.result

    def getConstants(self):
        return [None if isVariable(c) else c for c in self.params]

    def getVariables(self):
        return [v if isVariable(v) else None for v in self.params]

    def substitute(self, constants):
        c = constants.copy()
        f = f"{self.predicate}({','.join([constants.pop(0) if isVariable(p) else p for p in self.params])})"
        return Fact(f)

class Implication:
    def __init__(self, expression):
        self.expression = expression
        l = expression.split('=>')
        self.lhs = [Fact(f) for f in l[0].split('&')]
        self.rhs = Fact(l[1])

    def evaluate(self, facts):
        constants = {}
        new_lhs = []
        for fact in facts:
            for val in self.lhs:
                if val.predicate == fact.predicate:
                    for i, v in enumerate(val.getVariables()):
                        if v:
                            constants[v] = fact.getConstants()[i]
                    new_lhs.append(fact)
```

```
        predicate, attributes = getPredicates(self.rhs.expression)[0],
str(getAttributes(self.rhs.expression)[0])
        for key in constants:
            if constants[key]:
                attributes = attributes.replace(key, constants[key])
        expr = f'{predicate}{attributes}'
        return Fact(expr) if len(new_lhs) and all([f.getResult() for f in new_lhs]) else None


class KB:
    def __init__(self):
        self.facts = set()
        self.implications = set()


    def tell(self, e):
        if '=>' in e:
            self.implications.add(Implication(e))
        else:
            self.facts.add(Fact(e))
        for i in self.implications:
            res = i.evaluate(self.facts)
            if res:
                self.facts.add(res)


    def query(self, e):
        facts = set([f.expression for f in self.facts])
        i = 1
        print(f'Querying {e}:')
        for f in facts:
            if Fact(f).predicate == Fact(e).predicate:
                print(f'\t{i}. {f}')
                i += 1
```

```
    def display(self):
        print("All facts: ")
        for i, f in enumerate(set([f.expression for f in self.facts])):
            print(f'\t{i+1}. {f}')

kb = KB()
kb.tell('missile(x)=>weapon(x)')
kb.tell('missile(M1)')
kb.tell('enemy(x,America)=>hostile(x)')
kb.tell('american(West)')
kb.tell('enemy(Nono,America)')
kb.tell('owns(Nono,M1)')
kb.tell('missile(x)&owns(Nono,x)=>sells(West,x,Nono)')
kb.tell('american(x)&weapon(y)&sells(x,y,z)&hostile(z)=>criminal(x)')
kb.query('criminal(x)')
kb.display()

kb_ = KB()
kb_.tell('king(x)&greedy(x)=>evil(x)')
kb_.tell('king(John)')
kb_.tell('greedy(John)')
kb_.tell('king(Richard)')
kb_.query('evil(x)')
```

OUTPUT:

```
Example 1
Querying criminal(x):
        1. criminal(West)
All facts:
        1. american(West)
        2. enemy(Nono,America)
        3. hostile(Nono)
        4. sells(West,M1,Nono)
        5. owns(Nono,M1)
        6. missile(M1)
        7. weapon(M1)
        8. criminal(West)

Example 2
Querying evil(x):
        1. evil(John)
```