# Fundamentals of Algorithms for Non-linear Constrained Optimisation

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### Non-linear Constrained Problem

Consider the general constrained optimization problem:

$$\min_{x \in \mathbb{R}^n} f(x) \quad \text{subject to} \quad \begin{cases} c_i(x) &= 0, \quad i \in \mathscr{E} \\ c_i(x) &\geq 0, \quad i \in \mathscr{I} \end{cases} \tag{1}$$

- *f* is the objective function.
- $c_i: G \subset \mathbb{R}^n \to \mathbb{R}$  smooth,
- If and E are the finite index sets of inequality and equality constraints.
- We focus on fundamental concepts and building blocks that are common to more than one algorithm.

# Special cases (for which specialized algorithms exist):

- Linear programming (LP): f, all c<sub>i</sub> linear; solved by simplex & interior-point methods.
- Quadratic programming (QP): f quadratic, all c<sub>i</sub> linear.
- Linearly constrained optimization: all c<sub>i</sub> linear.
- Bound-constrained optimization: constraints are only of the form  $x_i \ge l_i$  or  $x_i \le u_i$ .
- Convex programming: f convex, equality c<sub>i</sub> linear, inequality c<sub>i</sub> concave.

## Categorization of algorithms

### **Quadratic programming:**

- for solving quadratic programming problems.
- its particular characteristics can be exploited by efficient algorithms,
- quadratic programming sub-problems need to be solved by sequential quadratic programming methods and certain interior-point methods for non-linear programming.
- Consist of active set, interior-point, and gradient projection methods.

## Categorisation of algorithms

#### penalty and augmented Lagrangian methods

- Combining the objective function and constraints into a penalty function  $\phi(x; \mu)$ , attack problem (1) by solving a sequence of unconstrained problems.
- $\mu$  is called the penalty parameter  $\mu > 0$ .
- e.g. if only equality constraints exist:

$$\phi(x;\mu) = f(x) + \frac{\mu}{2} \sum_{i \in \mathscr{E}} c_i(x)^2$$

• Minimise this unconstrained function, for a series of increasing values of  $\mu$ , until the solution of the constrained optimisation problem is identified to sufficient accuracy.