Geometric Transformation of 2D Object

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[1]: import numpy as np
     import matplotlib.pyplot as plt
[2]: def create triangle():
         return np.array([[0, 0], [1, 0], [0.5, 1], [0, 0]])
[3]: def translation(shape, tx, ty):
         translation_matrix = np.array([tx, ty])
         return shape + translation_matrix
[4]: def rotation(shape, angle_deg):
         angle_rad = np.radians(angle_deg)
         rotation matrix = np.array([[np.cos(angle_rad), -np.sin(angle_rad)],
                                     [np.sin(angle_rad), np.cos(angle_rad)]])
         return np.dot(shape, rotation_matrix.T)
[5]: def scaling(shape, sx, sy):
         scaling_matrix = np.array([[sx, 0], [0, sy]])
         return np.dot(shape, scaling_matrix.T)
[7]: def plot_shapes(original, translated, rotated, scaled):
         plt.figure(figsize=(6, 6))
         plt.plot(original[:, 0], original[:, 1], 'b-', label='Original')
         plt.plot(translated[:, 0], translated[:, 1], 'r-', label='Translated')
         plt.plot(rotated[:, 0], rotated[:, 1], 'g-', label='Rotated')
         plt.plot(scaled[:, 0], scaled[:, 1], 'm-', label='Scaled')
         plt.axhline(0, color='black',linewidth=0.5)
         plt.axvline(0, color='black',linewidth=0.5)
         plt.grid(color = 'gray', linestyle = '--', linewidth = 0.5)
         plt.legend()
         plt.title('Geometric Transformations')
         plt.axis('equal')
         plt.show()
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[8]: def main():
    triangle = create_triangle()

    translated_triangle = translation(triangle, 1, 1)
    rotated_triangle = rotation(triangle, 45)
    scaled_triangle = scaling(triangle, 2, 2)

    plot_shapes(triangle, translated_triangle, rotated_triangle, use scaled_triangle)
```

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[9]: if __name__ == "__main__": main()
```

Geometric Transformations

