

Mathematics of statistical decision making

and applications to bariatric surgery

Data science seminar M1-M2

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supervised by **Odalric-Ambrym Maillard** and **Philippe Preux**

February 21, 2024



Towards recommender systems in healthcare

Inria



Online advertising

NETFLIX

Home Series Films New & Popular My List Browse by Languages

We think you'll love these

DEMAIN
tout commence

TOP 10

Most Liked

GOOD WILL HUNTING

Top Pick

Online advertising

The image shows a screenshot of the Netflix website. At the top, the Netflix logo is on the left, followed by a navigation bar with links: Home, Series, Films, New & Popular, My List, and Browse by Languages. Below the navigation bar, there is a promotional banner with the text "We think you'll love these". This banner features a thumbnail for the movie "DEMAIN tout commence" (Top 10), which shows a man and a young girl. To the right of this thumbnail is another movie thumbnail for "GOOD WILL HUNTING", showing Matt Damon drawing a diagram on a chalkboard. A green oval has been drawn around the text "We think you'll love these".

NETFLIX

Home Series Films New & Popular My List Browse by Languages

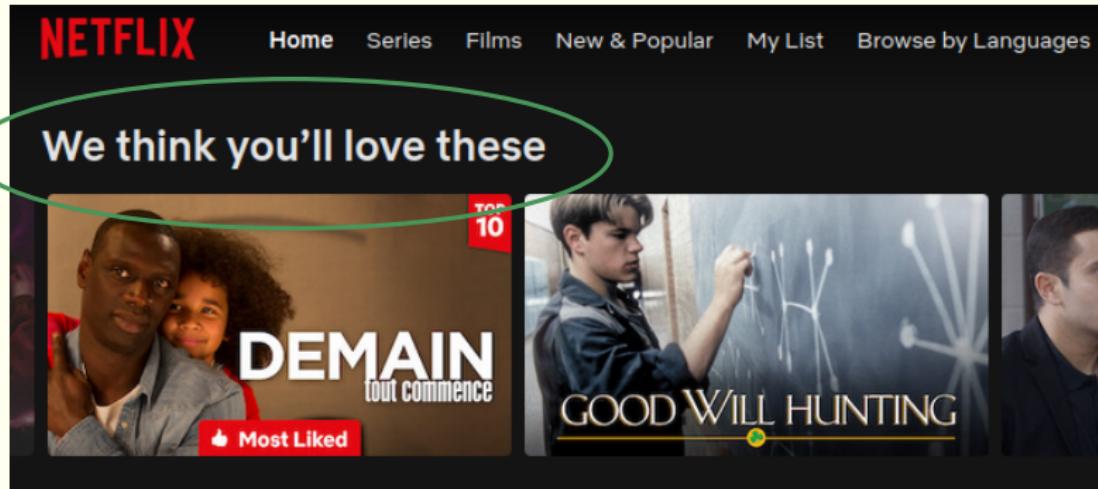
We think you'll love these

DEMAIN tout commence

GOOD WILL HUNTING

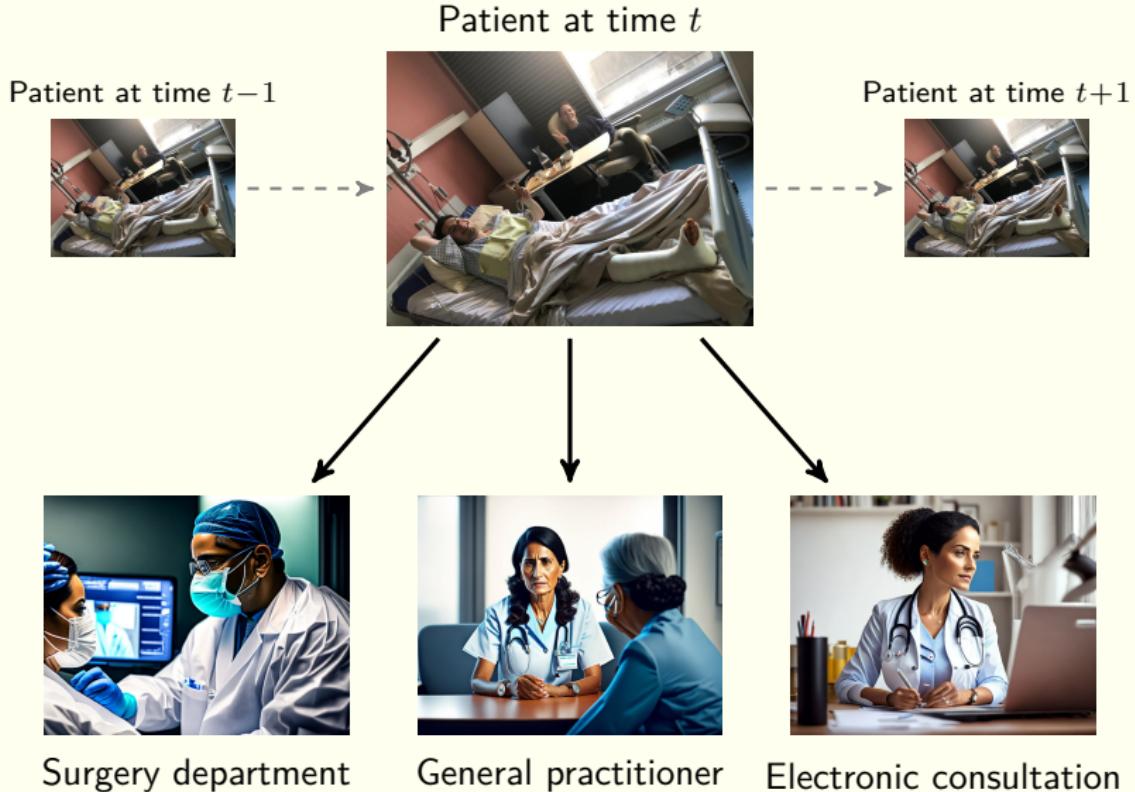
Most Liked

Online advertising

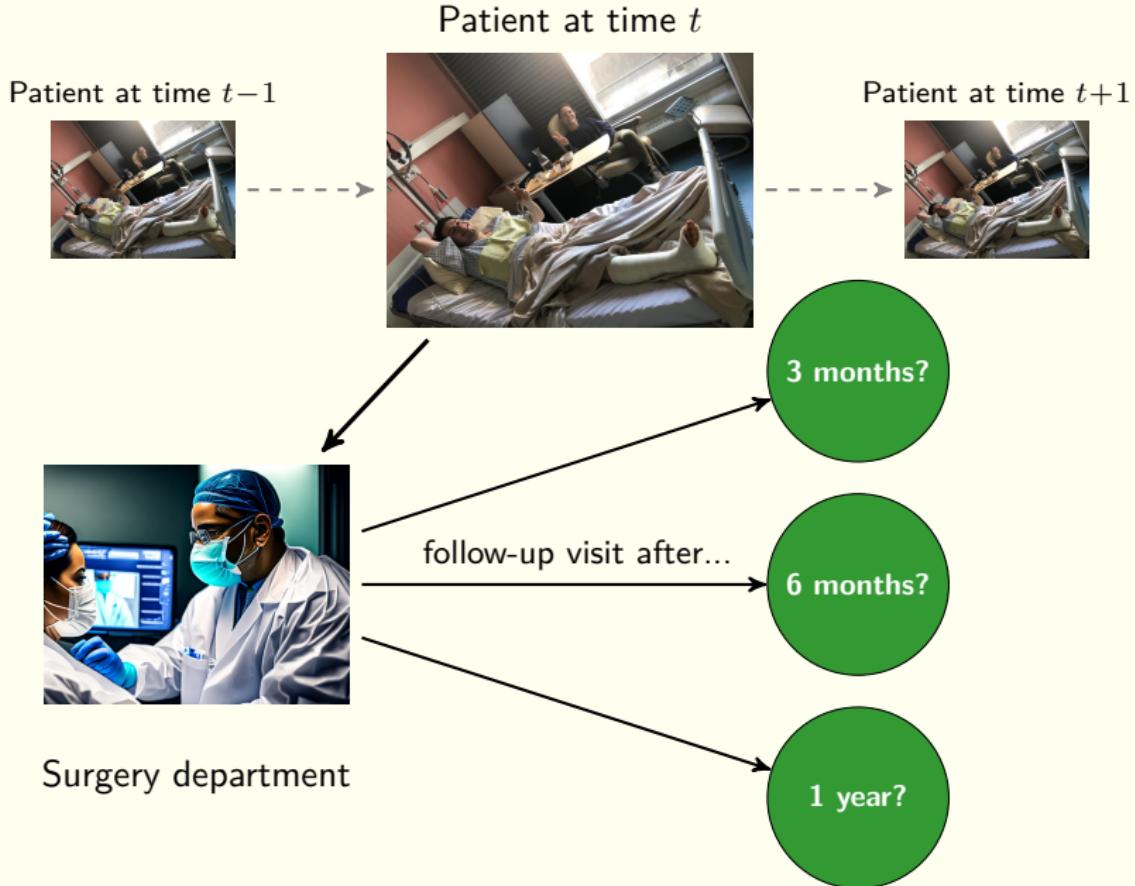


→ from online marketing to healthcare recommendations.

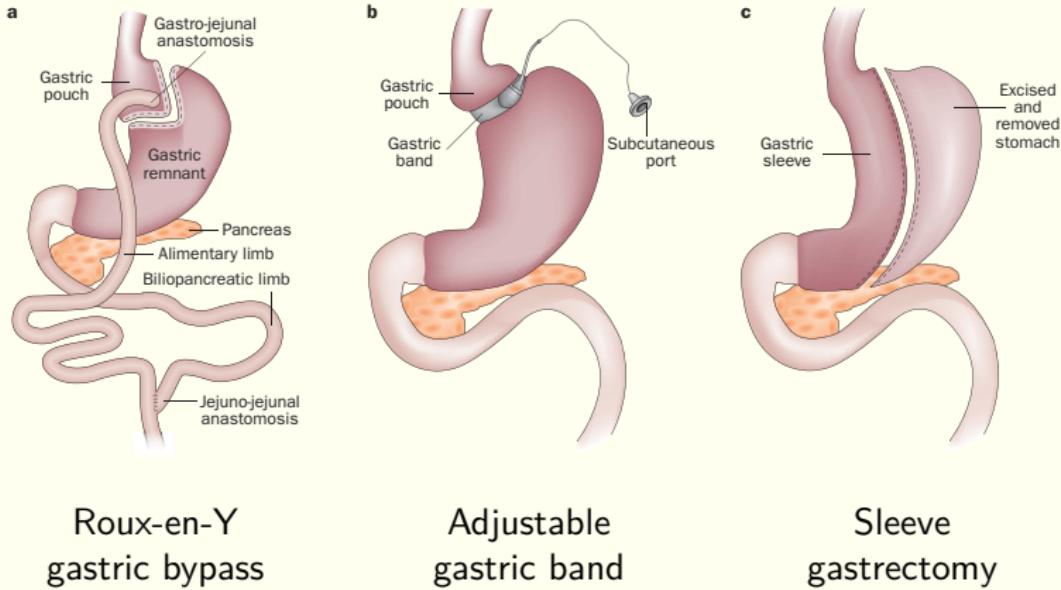
Postoperative follow-up: where to go?



Postoperative follow-up: when to go?



Bariatric surgery



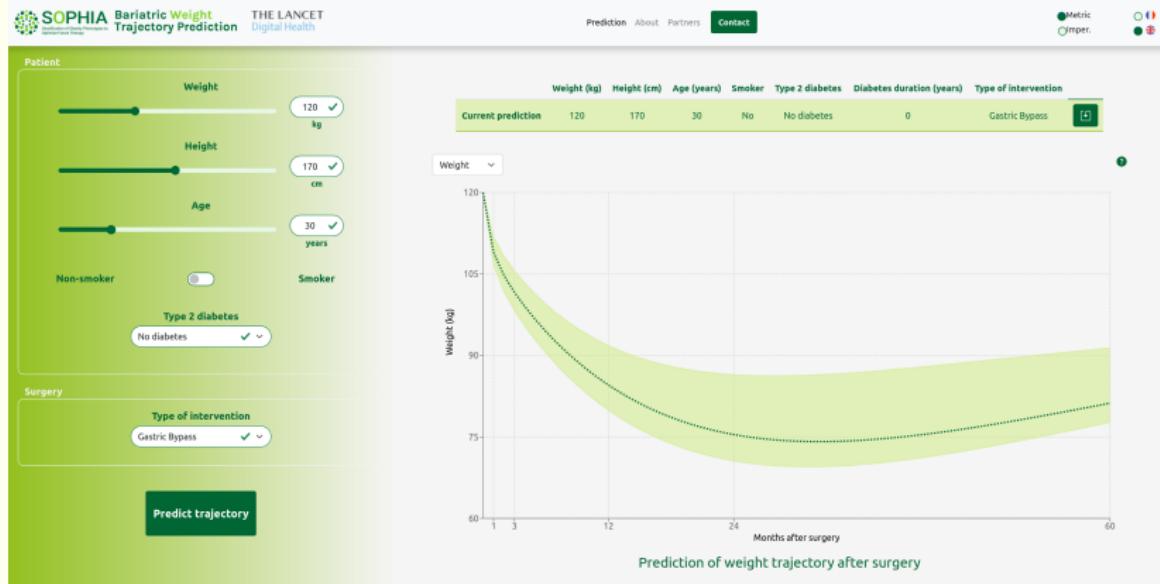
Roux-en-Y
gastric bypass

Adjustable
gastric band

Sleeve
gastrectomy

→ In France: 60 000 operations each year, 1% of adults.

Bariatric Weight Trajectory Prediction



<https://bwtp.univ-lille.fr/>

Bariatric Weight Trajectory Prediction

SOPHIA Bariatric Weight Trajectory Prediction THE DIGITAL

Patient

- Weight
- Height
- Age
- Non-smoker
- Type 2 diabetes
- No diabetes

Surgery

- Type of intervention
- Gastric Bypass

Predict trajectory

10k patients, 10 countries



Prediction of weight trajectory after surgery

<https://bwtp.univ-lille.fr/>

Bariatric Weight Trajectory Prediction



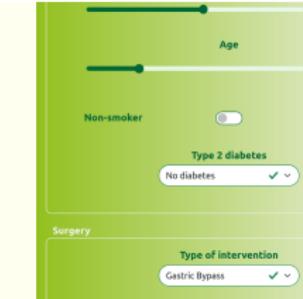
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<https://bwtp.univ-lille.fr/>

Bariatric Weight Trajectory Prediction

THE LANCET Digital Health



10k patients, 10 countries



<https://bwtp.univ-lille.fr/>

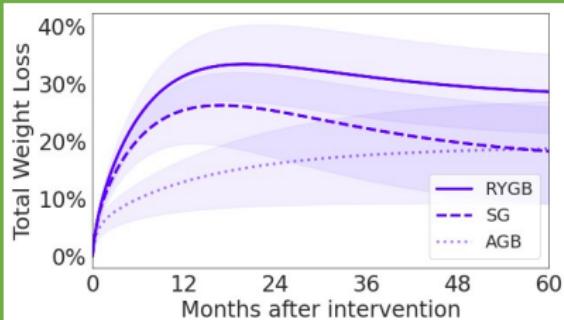
BWTP - training cohorts



ABOS

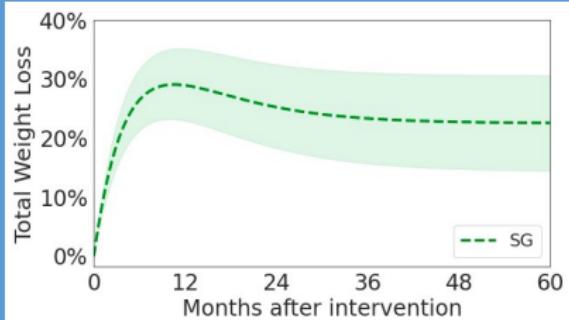
Prospective cohort
Retrospective study

- N=1147 (first intervention)
- > 500 baseline attributes

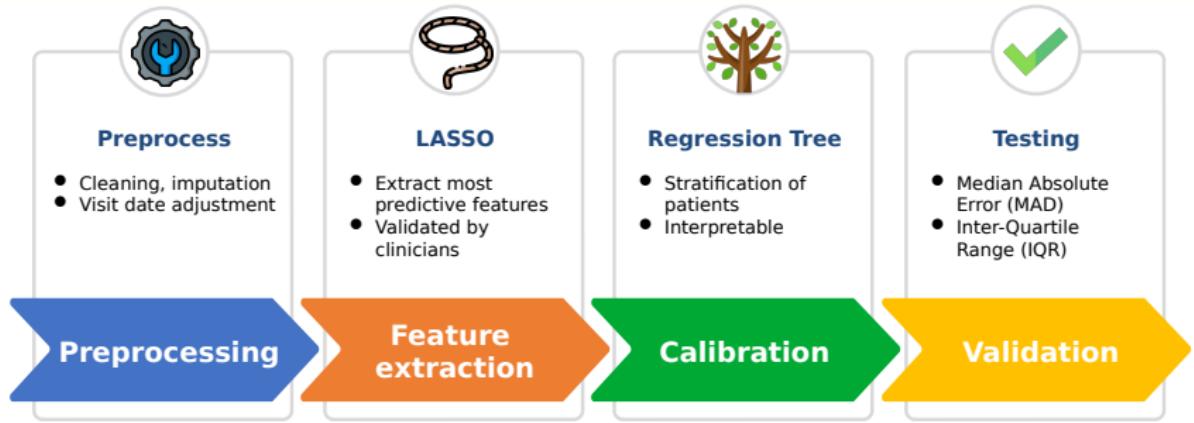


BAREVAL

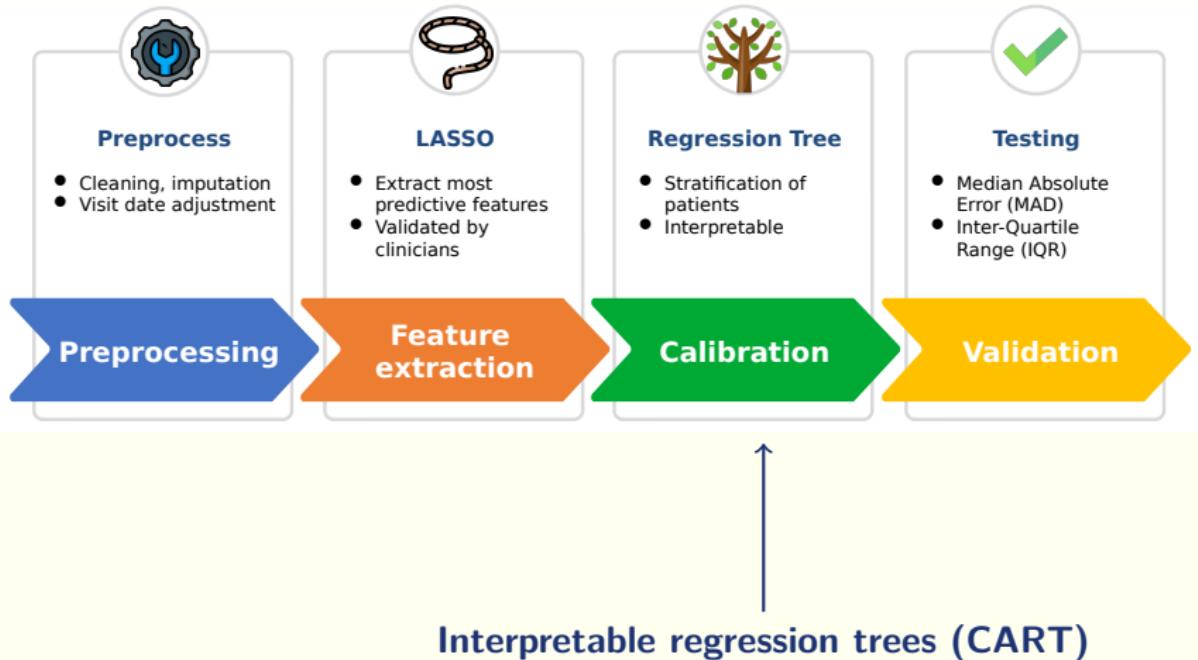
- N=348
- SG only



BWTP - prediction pipeline



BWTP - prediction pipeline

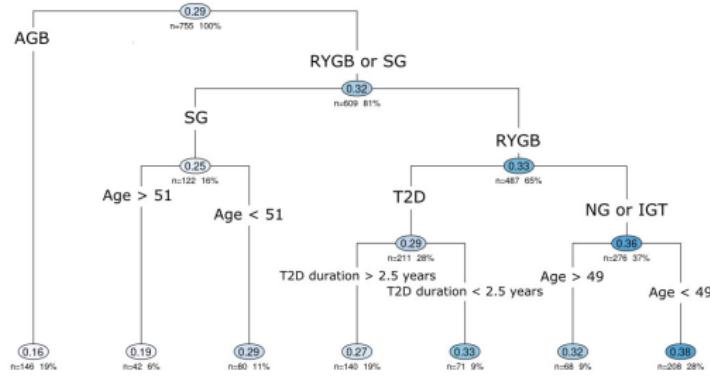


BWTP - prediction model

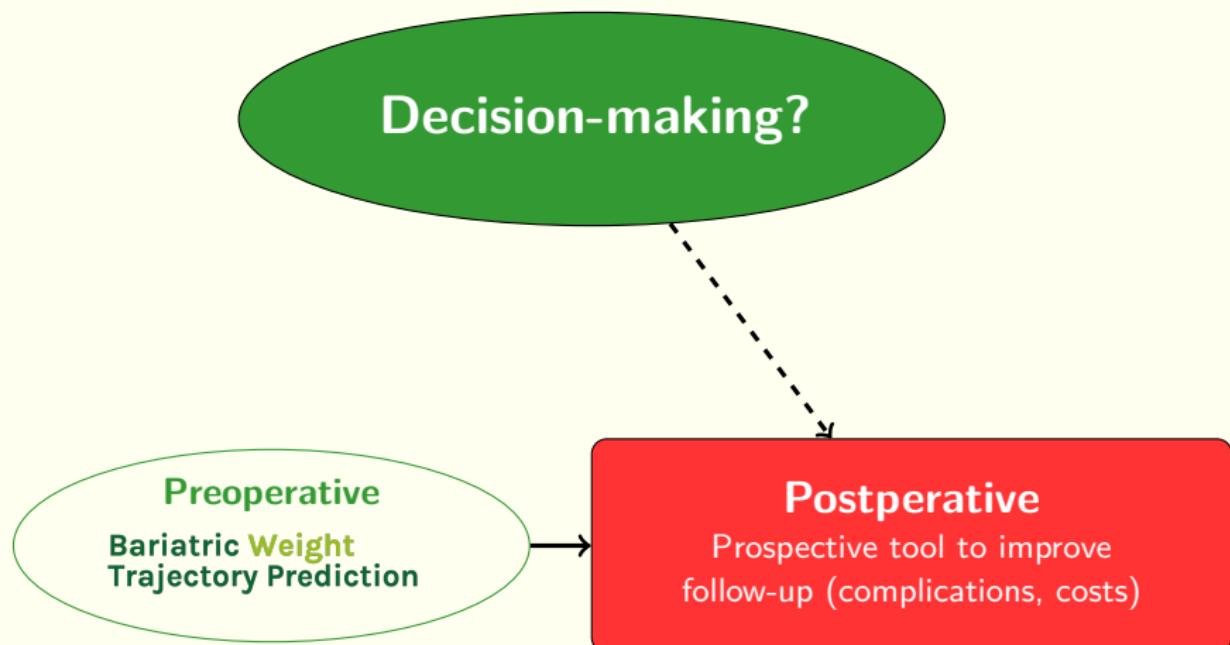
7 selected variables (among > 500)

- ✓ Weight
- ✓ Height
- ✓ Type of intervention
- ✓ Age
- ✓ Type II diabetes
- ✓ Diabetes duration
- ✓ Smoking

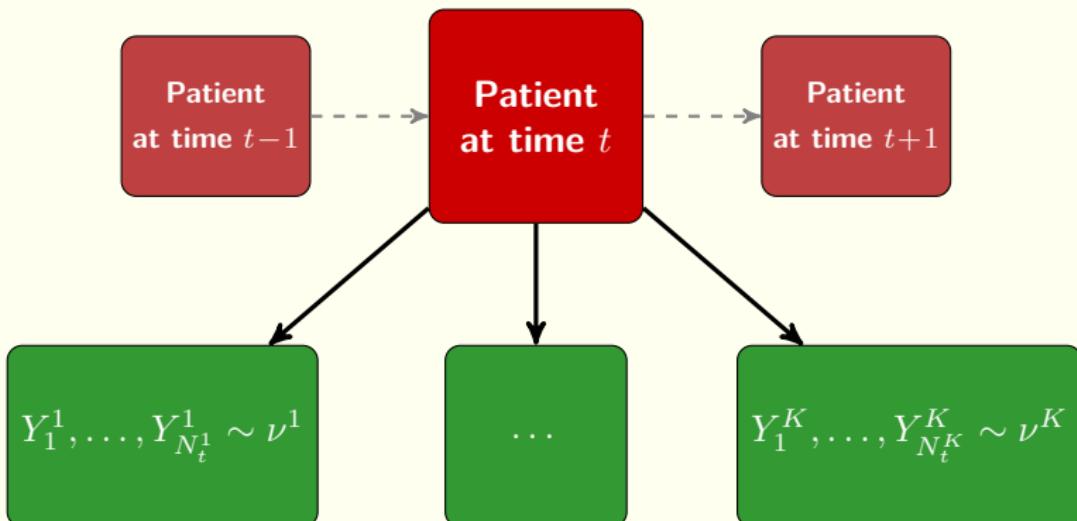
TWL Prediction at M24



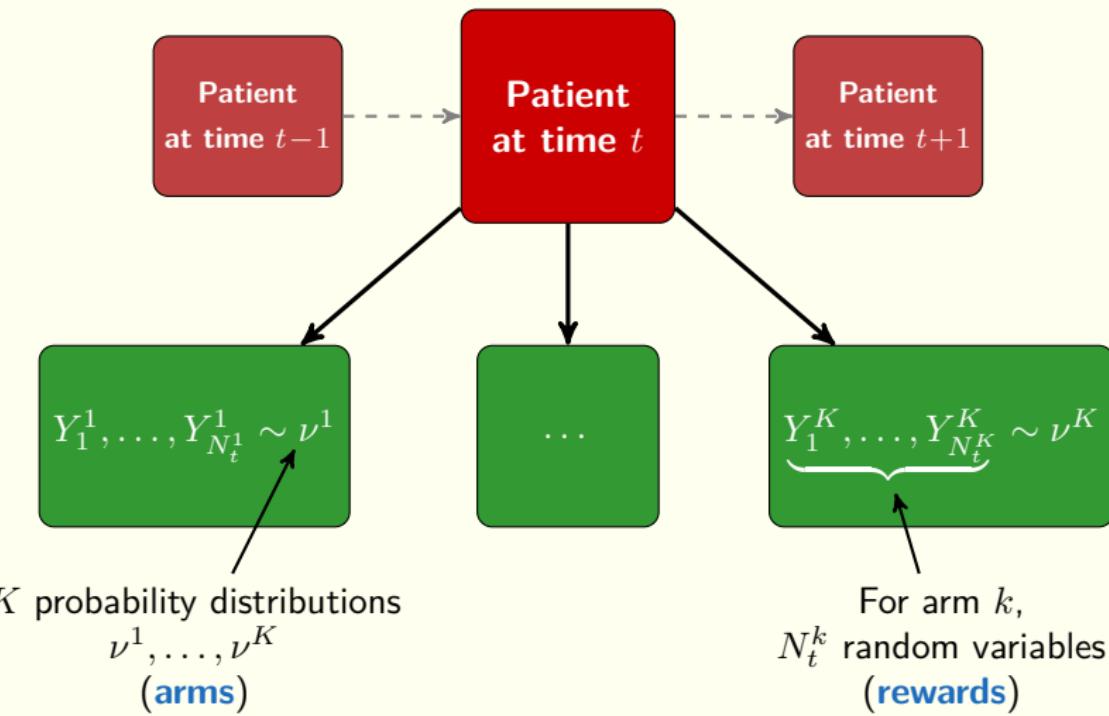
From preoperative to postoperative follow-up



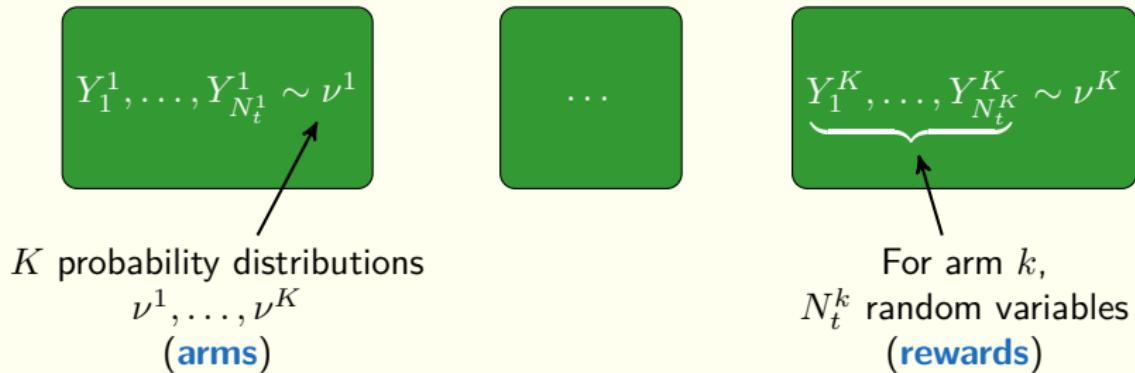
Stochastic bandit



Stochastic bandit



Stochastic bandits



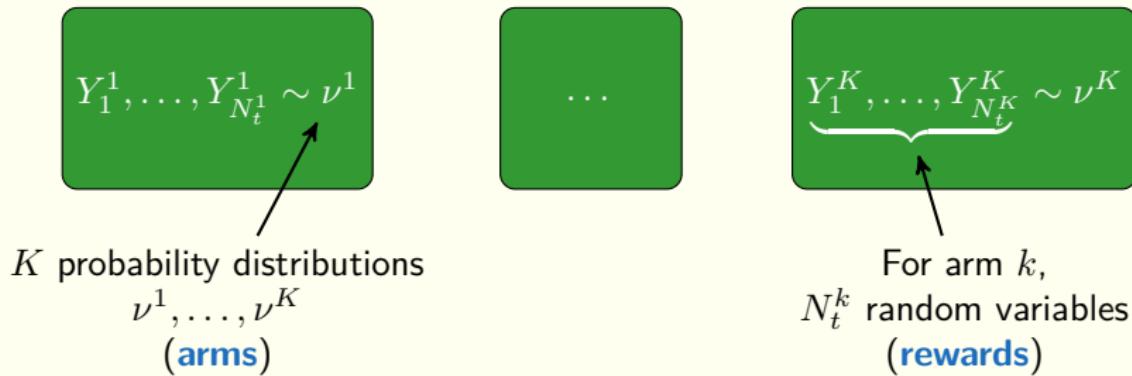
👉 Active sampling of arm π_t .

Score (e.g. expectation)

👉 Minimise **regret** $\mathcal{R}_T = \sum_{t=1}^T \max_{k \in [K]} \rho(\nu^k) - \rho(\nu^{\pi_t})$.

👉 **Contextual bandits**: features X help predict rewards Y .

Stochastic bandits



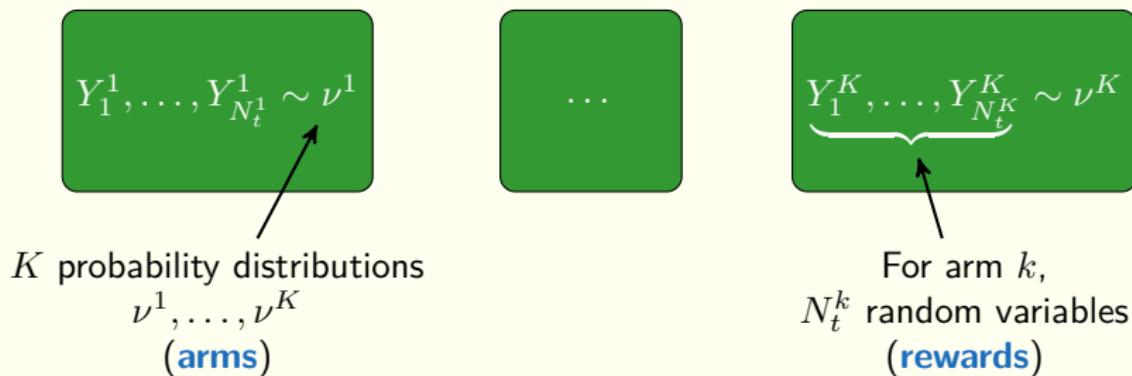
👍 Regret lower bound ($T \rightarrow +\infty$):

$$\mathcal{R}_T = \Omega(\sqrt{T}) \quad \text{or} \quad \mathcal{R}_T = \Omega(\log T).$$

Worst case

Instance-dependent

Exploration versus exploitation



Greed is **not** good!

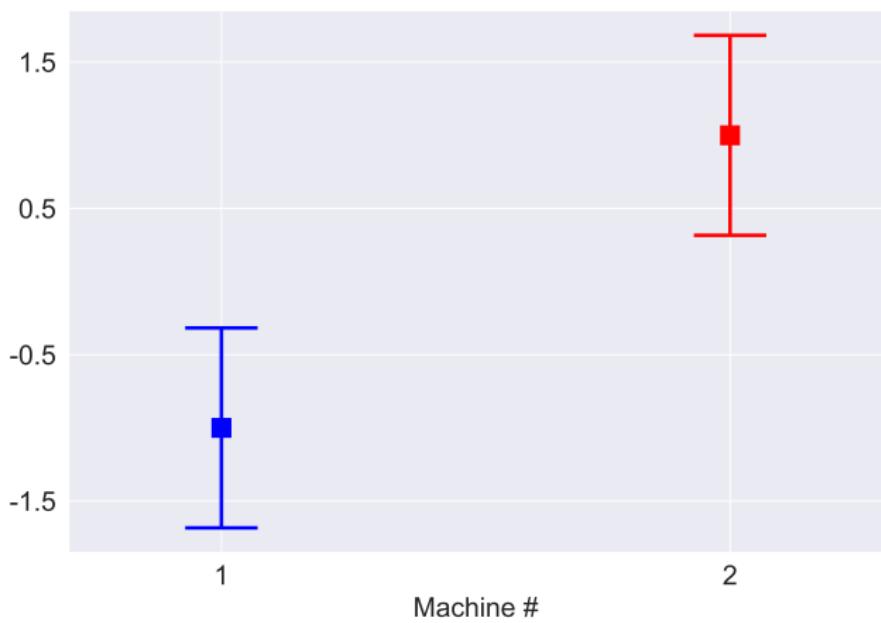
✗ $\pi_{t+1} \neq \operatorname{argmax}_{k \in [K]} \hat{\rho}_t^k$.

Need to **explore**:

- ✓ Deterministic:
 $\hat{\rho}_t^k + \text{confidence set.}$
- ✓ Randomised:
 $\hat{\rho}_t^k + \text{noise.}$



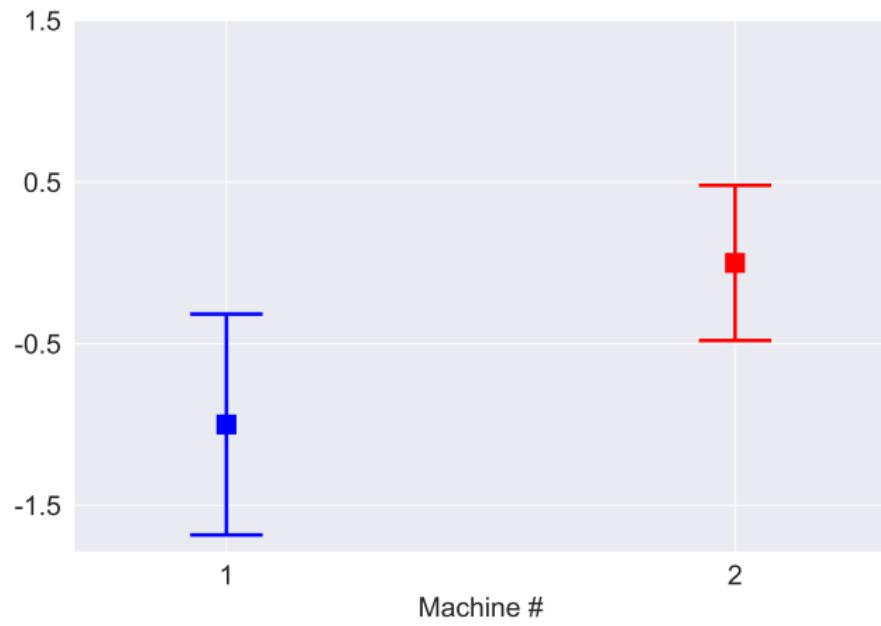
Deterministic exploration, a.k.a. *optimism*



Hospital: 5 patients. GP: 5 patients.

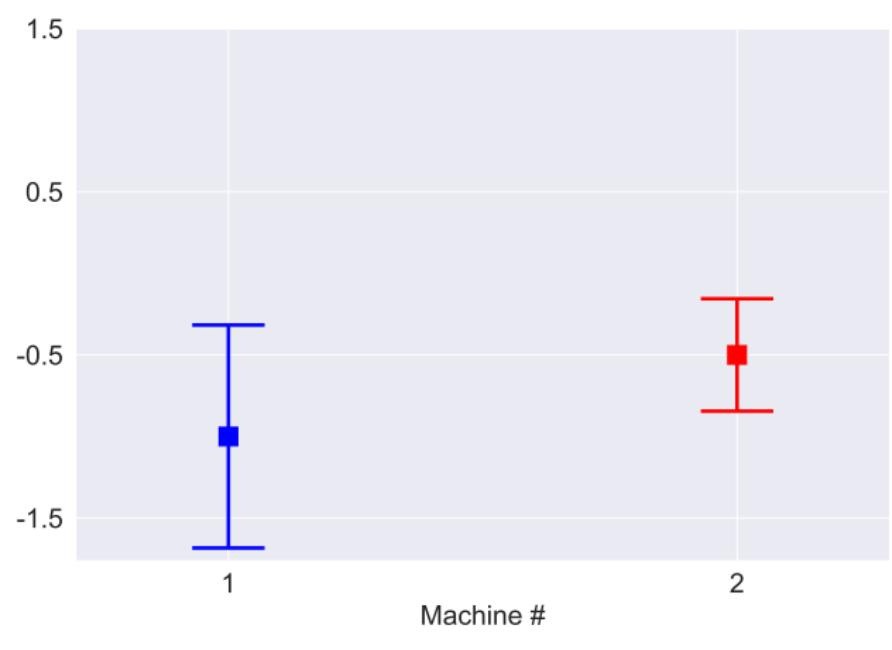
👉 Play the highest confidence bar.

Deterministic exploration, a.k.a. *optimism*



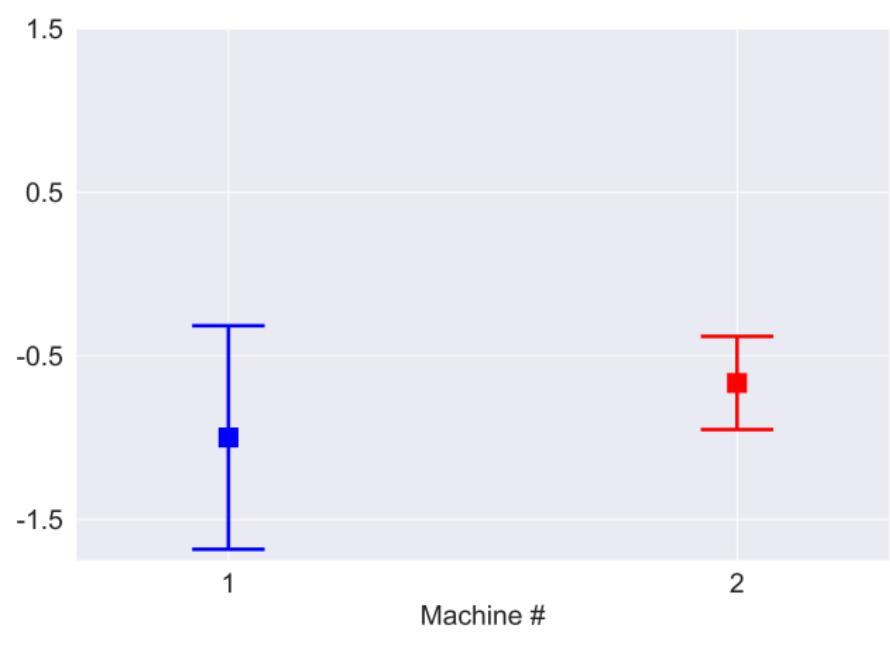
Hospital: 5 patients. GP: 10 patients.

Deterministic exploration, a.k.a. *optimism*



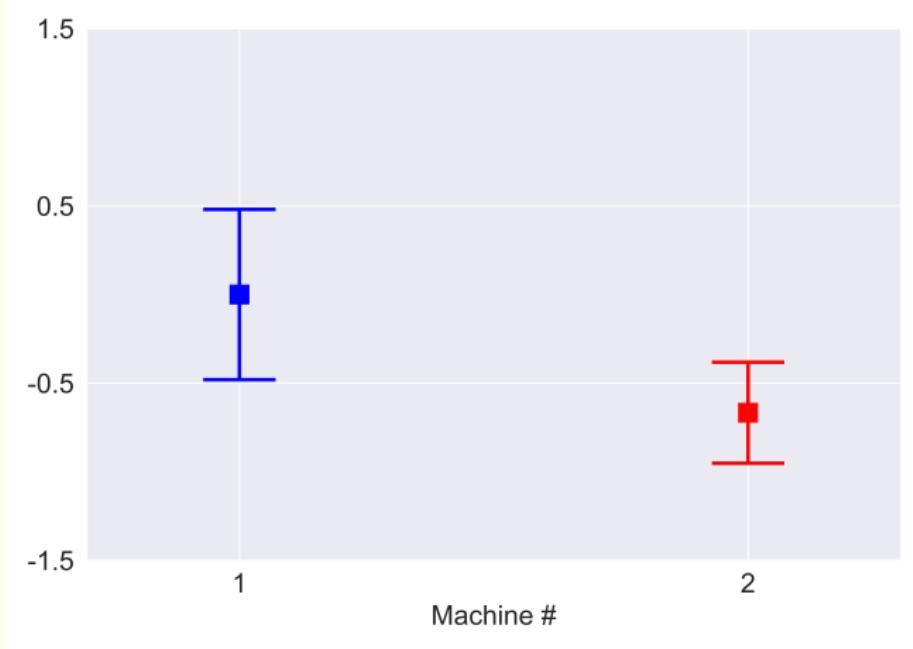
Hospital: 5 patients. GP: 20 patients.

Deterministic exploration, a.k.a. *optimism*



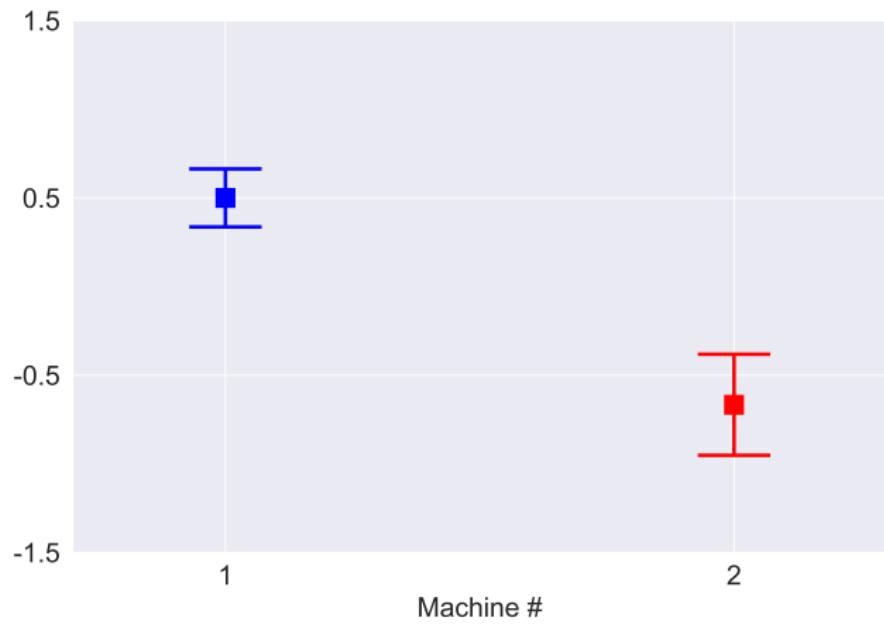
Hospital: 5 patients. GP: 30 patients.

Deterministic exploration, a.k.a. *optimism*



Hospital: 10 patients. GP: 30 patients.

Deterministic exploration, a.k.a. *optimism*



Hospital: 100 patients. GP: 30 patients.

👍 Correctly fixed the initial mistake!

Challenges of healthcare recommendations



Online advertising

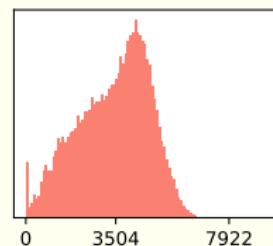
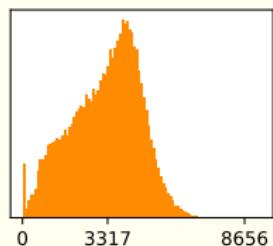
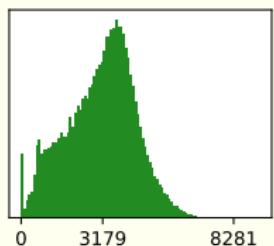
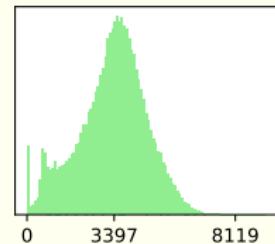
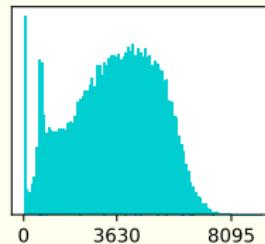
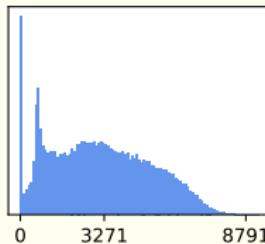
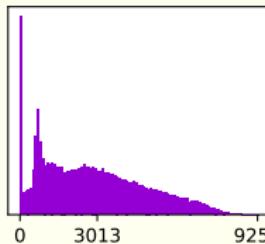
- ✓ Huge volume of data.
- ✓ Easy to model
(Bernoulli, logistic...).
- ✓ Limited risks ($\rho = \mathbb{E}$).

Healthcare

- ✗ Slow and scarce data.
- ✗ Nonparametric models.
- ✗ Risky.

Example distributions

Grain yield distributions (=rewards)



I. Efficient deterministic exploration

- 👉 Quantify uncertainty for the score ρ from i.i.d. Y_1, \dots, Y_N .
- ❓ Confidence sets: $\forall n \in \mathbb{N}, \mathbb{P}(\rho \in \widehat{\Theta}_n) \geq 1 - \delta$ (e.g. $\delta = 5\%$).

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 - ✖ p-hacking: incompatible with random (active, data-dependent) N .

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✖️ p-hacking: incompatible with random (active, data-dependent) N .
- ✓ Anytime valid confidence sequence:

$$\forall \text{ stopping time } N, \mathbb{P}(\rho \in \widehat{\Theta}_N) \geq 1 - \delta.$$

I. Concentration bounds

Method	Assumption	Variance adaptive	Random N
t -test	Gaussian (or $N \rightarrow +\infty$)	✓	✗
Method of mixtures (MM) supermartingale inequality	Sub-Gaussian	✗	✓

- Robbins and Pitman. Application of the method of mixtures to quadratic forms in normal variates. 1949.
Peña, Lai, and Shao. Self-normalized processes: Limit theory and statistical applications. 2009.

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Method of mixtures (MM) supermartingale inequality	Sub-Gaussian	✗	✓
Bregman MM	Exp. families	✓	✓
Empirical Chernoff MM	Second order sub-Gaussian	✓	✓

Robbins and Pitman. Application of the method of mixtures to quadratic forms in normal variates. 1949.
Peña, Lai, and Shao. Self-normalized processes: Limit theory and statistical applications. 2009.

I. Bregman concentration

Parameter

Exponential family: $p_\theta(y) = h(y) \exp(\langle \theta, F(y) \rangle - \mathcal{L}(\theta)).$

Feature function

Log-partition function

Bregman divergence:

$$\mathcal{B}(\theta', \theta) = \mathcal{L}(\theta') - \mathcal{L}(\theta) - \langle \theta' - \theta, \nabla \mathcal{L}(\theta) \rangle = \text{KL}(p_\theta \parallel p_{\theta'}).$$

Family	Known anytime valid concentration
Bernoulli, Gaussian (known variance)	✓
Gaussian, Chi-square, Poisson, Pareto, etc.	✗

I. Bregman concentration

$$\widehat{\Theta}_n^\delta = \left\{ \theta_0 \in \Theta : (n + c) \mathcal{B}_{\mathcal{L}} \left(\theta_0, \widehat{\theta}_{n,c}(\theta_0) \right) \leq \log \frac{1}{\delta} + \gamma_{n,c}(\theta_0) \right\}$$

is an anytime valid confidence sequence for this exponential family.

I. Bregman concentration

Regularised estimator

$$\hat{\theta}_{n,c}(\theta_0) = (\nabla \mathcal{L})^{-1} \left(\frac{1}{n+c} \left(\sum_{j=1}^n F(Y_j) + c \nabla \mathcal{L}(\theta_0) \right) \right)$$

$$\hat{\Theta}_n^\delta = \left\{ \theta_0 \in \Theta : (n+c) \mathcal{B}_{\mathcal{L}} \left(\theta_0, \hat{\theta}_{n,c}(\theta_0) \right) \leq \log \frac{1}{\delta} + \gamma_{n,c}(\theta_0) \right\}$$

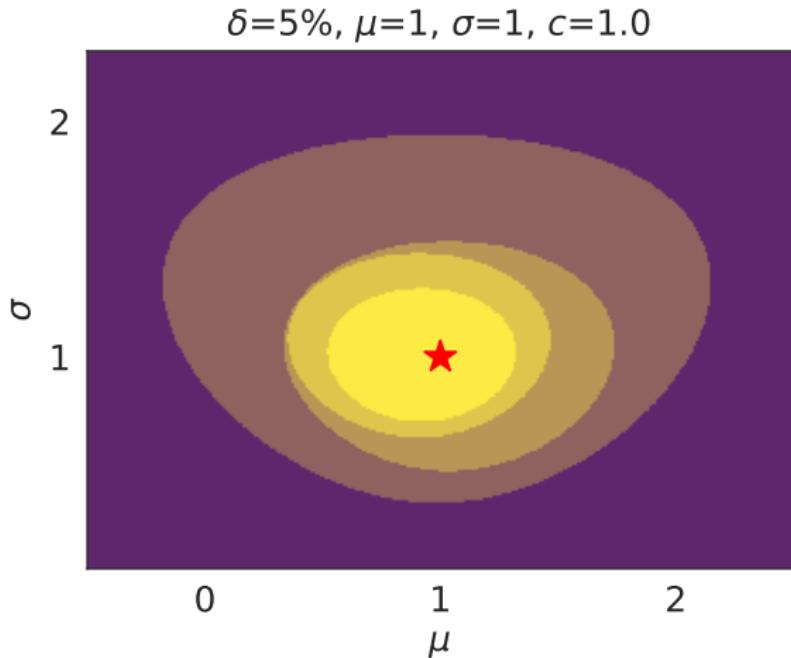
Bregman divergence

Bregman information gain

$$\gamma_{n,c}(\theta_0) = \log \left(\frac{\int_{\Theta} \exp(-c \mathcal{B}_{\mathcal{L}}(\theta', \theta_0)) d\theta'}{\int_{\Theta} \exp(-(n+c) \mathcal{B}_{\mathcal{L}}(\theta', \hat{\theta}_{n,c}(\theta_0))) d\theta'} \right)$$

is an anytime valid confidence sequence for this exponential family.

I. Bregman concentration



Challenges of healthcare recommendations



Online advertising

- ✓ Huge volume of data.
- ✓ Easy to model
(Bernoulli, logistic...).
- ✓ Limited risks ($\rho = \mathbb{E}$).



Healthcare

- ✓ Slow and scarce data.
- ✗ Nonparametric models.
- ✗ Risky.

II. Nonparametric: bootstrapping from data only

👉 Greedy policy:

$$\pi_{t+1} = \operatorname{argmax}_{k \in [K]} \frac{1}{N_t^k} \sum_{j=1}^{N_t^k} Y_j^k.$$

Empirical average



II. Nonparametric: bootstrapping from data only

👍 Greedy policy:

$$\pi_{t+1} = \operatorname{argmax}_{k \in [K]} \sum_{j=1}^{N_t^k} w_{j,t}^k Y_j^k.$$

Empirical average

$$w_{j,t}^k = \frac{1}{N_t^k}$$

II. Nonparametric: bootstrapping from data only

👉 Greedy policy with fictitious rewards:

$$\pi_{t+1} = \operatorname{argmax}_{k \in [K]} \sum_{j=1}^{N_t^k} w_{j,t}^k Y_j^k + \tilde{w}_t^k \tilde{Y}_t^k.$$

Empirical average
Fictitious reward

$$w_{j,t}^k, \tilde{w}_t^k = \frac{1}{N_t^k + 1}$$

II. Nonparametric: bootstrapping from data only

Randomised greedy policy with fictitious rewards:

$$\pi_{t+1} = \operatorname{argmax}_{k \in [K]} \sum_{j=1}^{N_t^k} w_{j,t}^k Y_j^k + \tilde{w}_t^k \tilde{Y}_t^k.$$

$w_{j,t}^k, \tilde{w}_t^k \in [0, 1]$ random

$$\sum_{j=1}^{N_t^k} w_{j,t}^k + \tilde{w}_t^k = 1$$

Randomised average

Fictitious reward

II. Nonparametric: bootstrapping from data only

Nonparametric Thompson sampling:

$$\pi_{t+1} = \operatorname{argmax}_{k \in [K]} \sum_{j=1}^{N_t^k} w_{j,t}^k Y_j^k + \tilde{w}_t^k \tilde{Y}_t^k.$$

$w_{j,t}^k, \tilde{w}_t^k \sim \operatorname{Dir}(1, \dots, 1)$
(uniform distribution on the simplex)

Dirichlet average

Fictitious reward
(\approx reward upper bound)

Kveton, Szepesvari, et al. [ICML](#), 2019.

Riou and Honda. [ALT](#), 2020.

II. Nonparametric: bootstrapping from data only

Nonparametric Thompson sampling:

$$\pi_{t+1} = \operatorname{argmax}_{k \in [K]} \sum_{j=1}^{N_t^k} w_{j,t}^k Y_j^k + \tilde{w}_t^k \tilde{Y}_t^k.$$

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Dirichlet average

Fictitious reward
(\approx reward upper bound)

Beyond bounded rewards (with known bounds)?

Kveton, Szepesvari, et al. [ICML](#), 2019.

Riou and Honda. [ALT](#), 2020.

II. Regret guarantees for Dirichlet sampling

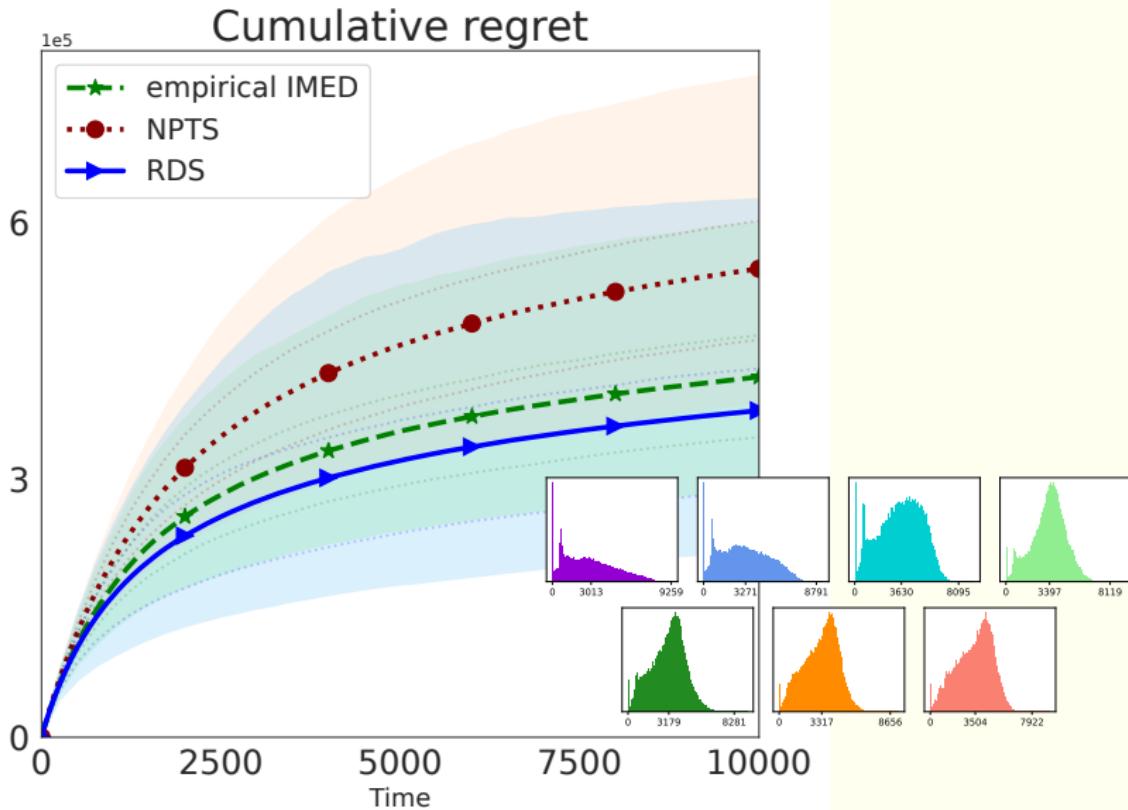
$$\pi_{t+1} = \operatorname{argmax}_{k \in [K]} \sum_{j=1}^{N_t^k} w_{j,t}^k Y_j^k + \tilde{w}_t^k \tilde{Y}_t^k.$$

👉 Regret guarantees (instance-dependent)

- ✓ Optimal in several settings
(bounded, bounded detectable, semibounded + quantile condition)

💡 **Light tailed:** $\mathcal{R}_T = \mathcal{O}(\log(T) \log \log(T))$.

II. Dirichlet sampling



Challenges of healthcare recommendations



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Healthcare

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III. From risk-neutral to risk-aware

Non-contextual bandits:

- ▶ Maillard. Robust risk-averse stochastic multi-armed bandits.
ALT, 2013.
- ▶ Baudry, Gautron, et al. Optimal Thompson sampling strategies
for support-aware CVAR bandits.
ICML, 2021a.

Contextual bandits?

III. From risk-neutral to risk-aware

Classical linear bandit $Y = \langle \theta^*, X \rangle + \text{ zero-mean noise:}$

$$\widehat{\theta}_{t+1} = \min_{\theta \in \Theta} \sum_{s=1}^t (Y_s - \langle \theta, X_s \rangle)^2 \quad + \quad \text{exploration}.$$

↑
Estimator of
 $\rho(\nu) = \mathbb{E}_\nu [Y | X]$

III. From risk-neutral to risk-aware

Classical linear bandit $Y = \langle \theta^*, X \rangle + \text{ zero-mean noise:}$

$$\widehat{\theta}_{t+1} = \min_{\theta \in \Theta} \sum_{s=1}^t \mathcal{L}(Y_s, \langle \theta, X_s \rangle) \quad + \quad \text{exploration.}$$

Estimator of

$$\rho(\nu) = \min_{\theta} \mathbb{E}_{\nu} [\mathcal{L}(Y, \langle \theta, X \rangle) | X]$$

(M-estimator)

$$\mathcal{L}(y, \xi) = (y - \xi)^2$$

III. From risk-neutral to risk-aware

👉 Elicitable risk measure linear bandit $Y \approx \langle \theta^*, X \rangle +$ zero ρ -noise:

$$\widehat{\theta}_{t+1} = \min_{\theta \in \Theta} \sum_{s=1}^t \mathcal{L}(Y_s, \langle \theta, X_s \rangle) \quad + \text{ exploration.}$$

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\mathcal{L} (strongly) convex mapping

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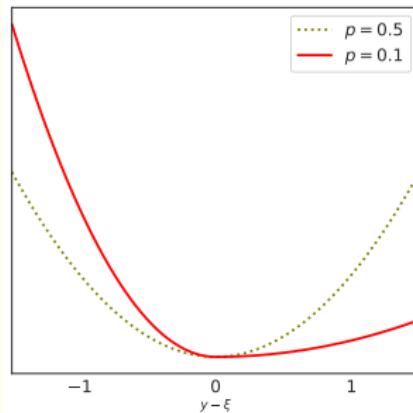
Estimator of

$$\rho(\nu) = \min_{\theta} \mathbb{E}_{\nu} [\mathcal{L}(Y, \langle \theta, X \rangle) | X]$$

(M-estimator)

\mathcal{L} (strongly) convex mapping

Expectile: $\mathcal{L}(y, \xi) = |p - \mathbf{1}_{y < \xi}| (y - \xi)^2$
(\neq loss for negative and positive rewards).



III. Risk-aware policies

↳ Deterministic exploration:

$$\pi_{t+1} = \operatorname{argmax}_x \langle \hat{\theta}_{t+1}, x \rangle + \text{UCB}(x),$$

Worst case: $\mathcal{R}_T = \tilde{\mathcal{O}}(\sqrt{T}).$

↳ Randomised Dirichlet exploration:

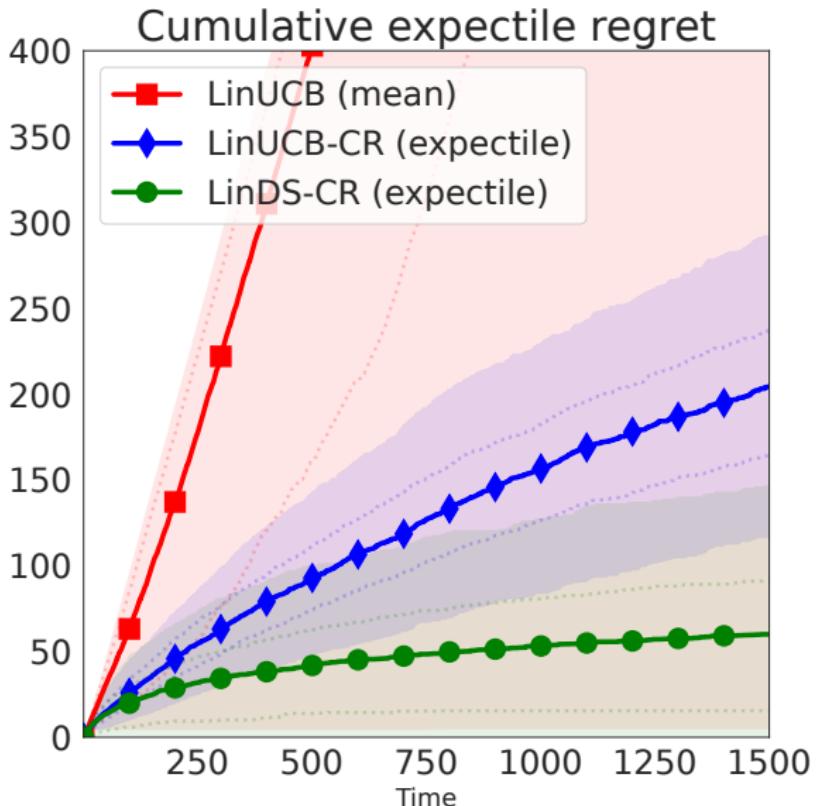
$$\tilde{\theta}_{t+1} = \min_{\theta \in \Theta} \sum_{s=1}^t w_s^t \mathcal{L}(Y_s, \langle \theta, X_s \rangle) + \tilde{w}_{t+1}^t \mathcal{L}\left(\tilde{Y}, \langle \theta, \tilde{X} \rangle\right),$$

$$\pi_{t+1} = \operatorname{argmax}_x \langle \tilde{\theta}_{t+1}, x \rangle,$$

Worst case: $\mathcal{R}_T \stackrel{?}{=} \tilde{\mathcal{O}}(\sqrt{T}).$

Linear Gaussian Thompson sampling?
(strong approximation of weighted bootstrap)

III. Risk-aware policies



Challenges of healthcare recommendations



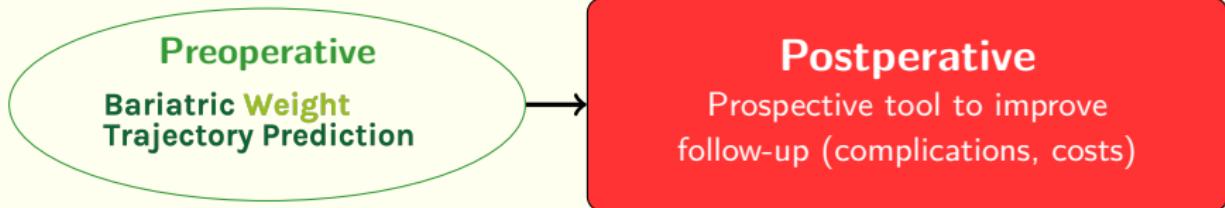
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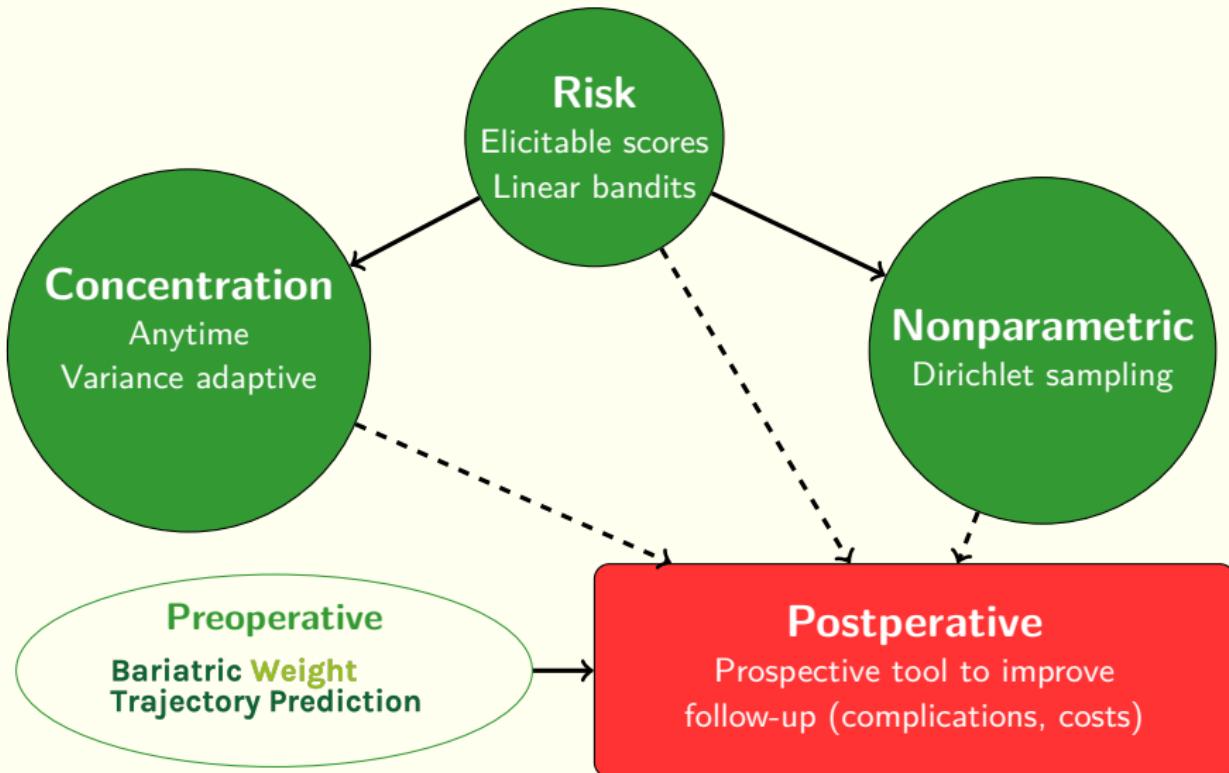
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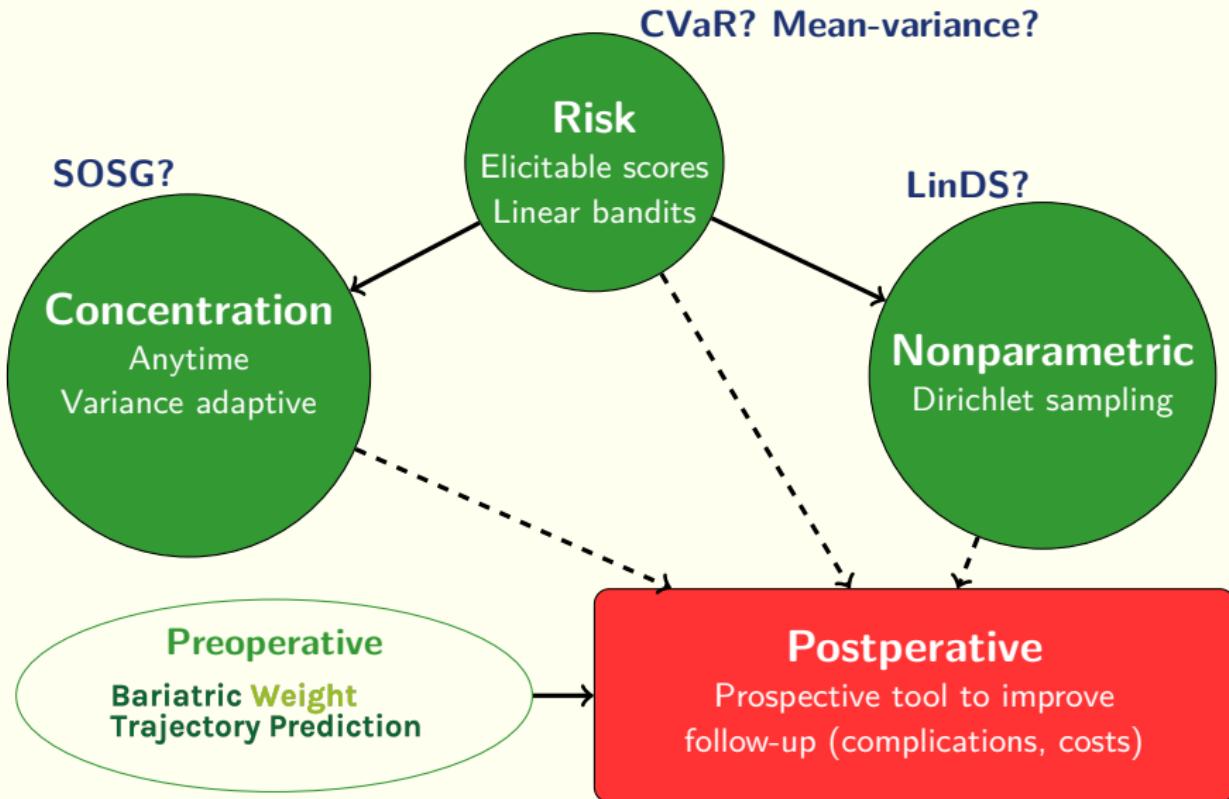
Conclusion and future works



Conclusion and future works



Conclusion and future works



Contributions in medical sciences

Publications in peer-reviewed journals

- PS, Pierre Bauvin, Violeta Raverdy, Julien Teigny, Hélène Verkindt, Maxence Debert, Philippe Preux, François Pattou, et al. Development and validation of an interpretable machine learning based calculator for predicting 5 year-weight trajectories after bariatric surgery: a multinational retrospective cohort SOPHIA study.
The Lancet Digital Health, 2023
- Robert Caiazzo, Pierre Bauvin, Camille Marciniak, PS, et al. Impact of robotic assistance on complications in bariatric surgery at expert laparoscopic surgery centers. a retrospective comparative study with propensity score.
Annals of Surgery, 2023



Contributions in statistics and machine learning

Publications in peer-reviewed international conferences with proceedings

- ❑ Sayak Ray Chowdhury, PS, Odalric-Ambrym Maillard, and Aditya Gopalan. [Bregman deviations of generic exponential families.](#)
In [Conference On Learning Theory](#), 2023
- ❑ PS and Odalric-Ambrym Maillard. [Risk-aware linear bandits with convex loss.](#)
In [International Conference on Artificial Intelligence and Statistics](#), 2023
- ❑ Dorian Baudry, PS, and Odalric-Ambrym Maillard. [From optimality to robustness: Adaptive re-sampling strategies in stochastic bandits.](#)
[Advances in Neural Information Processing Systems](#), 2021b

Workshop presentations in peer-reviewed international conferences

- ❑ PS and Odalric-Ambrym Maillard. [Risk-aware linear bandits with convex loss.](#)
In [European Workshop on Reinforcement Learning](#), 2022 (poster)

Ongoing

- ❑ PS. [Empirical chernoff concentration: beyond bounded distributions](#)
- ❑ PS, Romain Gautron, Odalric-Ambrym Maillard, Marc Corbeels, Chandra A. Madramootooe, and Nitin Joshi. [Quantifying the uncertainty of crop management decisions based on crop model simulations](#)

Software contributions

💻 Bariatric Weight Trajectory Prediction

<https://bwtp.univ-lille.fr>



💻 rlberry

<https://github.com/rlberry-py/rlberry>

💻 concentration-lib

<https://pypi.org/project/concentration-lib>



Questions

