

# MA1301 Introductory Mathematics

## Chapter 4

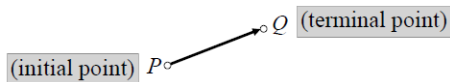
### Vectors

TAN BAN PIN

National University of Singapore

# Vectors - Definitions

A directed line segment PQ

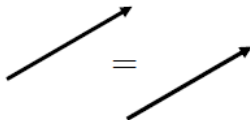


Direction: direction of the arrow

Magnitude: length of the line segment

Examples: velocity, gravitational force, magnetic field e.t.c.

Two vectors are equal if they have the same direction and length.

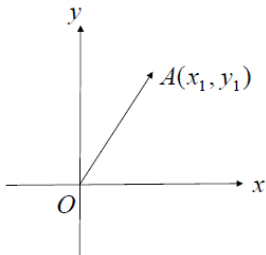


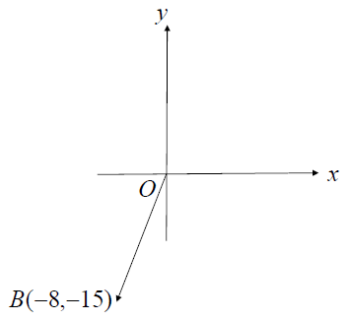
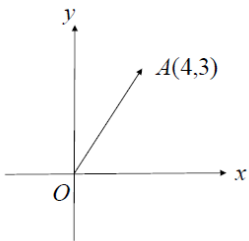
**Magnitude** of a vector  $\mathbf{a}$ , denoted by  $|\mathbf{a}|$  (or  $\|\mathbf{a}\|$ ) = length of vector  $\mathbf{a}$   
On the  $x - y$  plane, if  $A$  has coordinates  $(x_1, y_1)$  and  $O$  is the origin, then the position vector of  $A$ ,

$$\overrightarrow{OA} = \mathbf{a}$$

has magnitude

$$|\mathbf{a}| = \sqrt{x_1^2 + y_1^2}$$



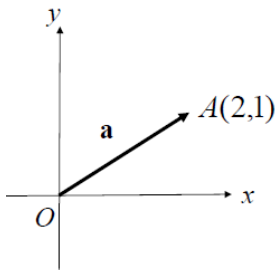


Let  $\lambda$  be a scalar.

$\lambda \mathbf{a}$  is the vector that is parallel to  $\mathbf{a}$  and has magnitude  $|\lambda||\mathbf{a}|$ .

$\lambda > 0 \Rightarrow \mathbf{a}$  and  $\lambda \mathbf{a}$  are in the same direction

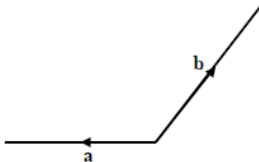
$\lambda < 0 \Rightarrow \mathbf{a}$  and  $\lambda \mathbf{a}$  are in the opposite direction



# Vector Addition and Subtraction

## Example

Draw  $\mathbf{a} + 2\mathbf{b}$ ,  $\frac{1}{2}\mathbf{a} - \mathbf{b}$ ,  $\mathbf{b} - \mathbf{a}$



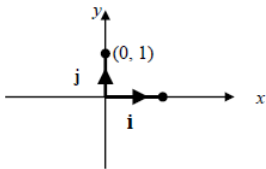
Given  $A(x_1, y_1)$  and  $B(x_2, y_2)$ ,

$$\text{Then } \overrightarrow{AB} = \overrightarrow{OB} - \overrightarrow{OA} = \begin{pmatrix} x_2 \\ y_2 \end{pmatrix} - \begin{pmatrix} x_1 \\ y_1 \end{pmatrix} = \begin{pmatrix} x_2 - x_1 \\ y_2 - y_1 \end{pmatrix}$$

Let the vectors  $\begin{pmatrix} 1 \\ 0 \end{pmatrix}$  and  $\begin{pmatrix} 0 \\ 1 \end{pmatrix}$  be denoted by  $\mathbf{i}$  and  $\mathbf{j}$  respectively.

Then, any vector  $\begin{pmatrix} x \\ y \end{pmatrix}$  can be expressed as

$$x\mathbf{i} + y\mathbf{j}$$





# Example

If  $\mathbf{u} = \mathbf{i} + \mathbf{j}$  and  $\mathbf{v} = \mathbf{i} - 6\mathbf{j}$ , find  $|2\mathbf{u} + \mathbf{v}|$ .

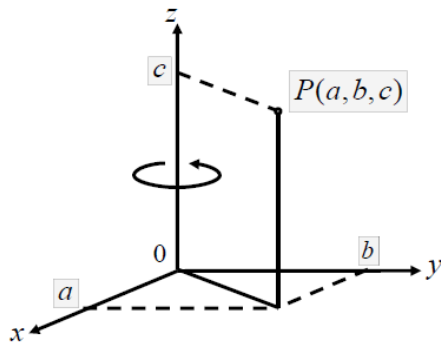
## Example

Given that  $P$  is  $(3, -2)$  and  $\overrightarrow{QP} = \begin{pmatrix} 2 \\ 0 \end{pmatrix}$ , find the point  $Q$ .

# The Cartesian Coordinate System

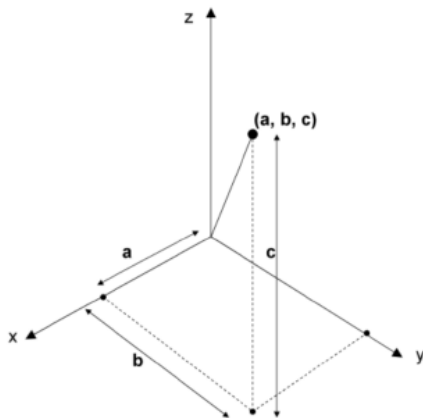
## Rectangular Coordinates

Right-handed coordinates system



If we rotate the  $x$ -axis counter-clockwise toward the  $y$ -axis, then a right-handed screw will move in the positive  $z$  direction.

# 3-D Coordinate System

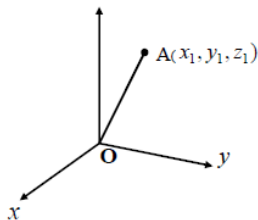


# Position vectors in 3-D Cartesian system

For any point  $A(x_1, y_1, z_1)$  the vector  $\overrightarrow{OA}$  = position vector of  $A$  with respect to  $O$ .

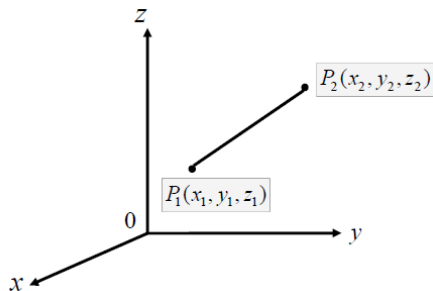
$$\overrightarrow{OA} = \begin{pmatrix} x_1 \\ y_1 \\ z_1 \end{pmatrix} = x_1\mathbf{i} + y_1\mathbf{j} + z_1\mathbf{k} \text{ where } \mathbf{i} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \mathbf{j} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \text{ and } \mathbf{k} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$|\overrightarrow{OA}| = \sqrt{x_1^2 + y_1^2 + z_1^2}$$



# The Cartesian Coordinate System

Distance between two points



For two points  $P_1(x_1, y_1, z_1)$  and  $P_2(x_2, y_2, z_2)$ , the length of  $P_1P_2$  is

$$|P_1P_2| = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$$

Two vectors  $\mathbf{a}$  and  $\mathbf{b}$  are  $// \Leftrightarrow \mathbf{a} = \lambda \mathbf{b}$  for some scalar  $\lambda \neq 0$ .

$A$ ,  $B$  and  $C$  are collinear (that is, they lie on the same straight line) if and only if

$$\overrightarrow{AB} // \overrightarrow{AC} \quad (// \overrightarrow{BC})$$

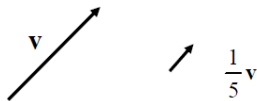


## Example

Given  $A(1, p, 3)$  and  $B(1, 5, -1)$ , find the possible values of  $p$  if  $|\overrightarrow{AB}| = 5$ .

# Unit Vectors

Vectors of length 1



Suppose  $\|\mathbf{v}\| = 5$ , then  $\frac{1}{5}\mathbf{v}$  will have length 1.

To find unit vector:  $\frac{1}{\|\mathbf{v}\|}\mathbf{v}$

# Example

Suppose  $\|\mathbf{v}\| = 5$ .

Find a vector with length 7 and in the direction  $\mathbf{v}$ .

# Unit Vectors

$\hat{a}$  = unit vector in the direction of  $\mathbf{a}$

Thus

$$\hat{a} = \frac{1}{|\mathbf{a}|} \mathbf{a},$$

in other words,

$\hat{a}$  is the vector  $//$   $\mathbf{a}$

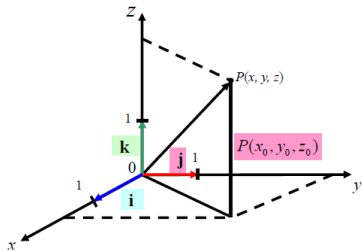
and **has magnitude 1**

$\mathbf{i}, \mathbf{j}, \mathbf{k}$  are unit vectors in the direction of  $x$ -,  $y$ - and  $z$ -axis respectively.

Note that:

every vector  $\begin{pmatrix} x \\ y \\ z \end{pmatrix}$  can be written as

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = x\mathbf{i} + y\mathbf{j} + z\mathbf{k}$$



# Example

Given  $A(2, -2, 1)$ ,  $B(-2, 1, 1)$ ,  $C(h, 3, k)$

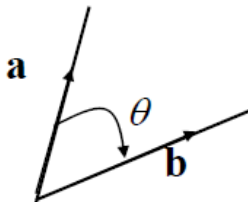
find

- (i)  $\hat{a}$
- (ii) the two vectors  $\parallel \mathbf{a}$  and having magnitude 18
- (iii) the values of  $h$  and  $k$ , given that  $A$ ,  $B$  and  $C$  are collinear.

# Scalar Product

$$\mathbf{a} \cdot \mathbf{b} = |\mathbf{a}||\mathbf{b}| \cos \theta$$

where  $\theta$  is the angle between  $\mathbf{a}$  and  $\mathbf{b}$ .



$$\mathbf{a} \cdot \mathbf{b} = \mathbf{b} \cdot \mathbf{a}$$

$$\lambda(\mathbf{a} \cdot \mathbf{b}) = (\lambda\mathbf{a}) \cdot \mathbf{b} = \mathbf{a} \cdot (\lambda\mathbf{b}) \text{ for any } \lambda \in \mathbb{R}.$$

$$\mathbf{a} \cdot (\mathbf{b} + \mathbf{c}) = \mathbf{a} \cdot \mathbf{b} + \mathbf{a} \cdot \mathbf{c}$$

$$\mathbf{a} \cdot \mathbf{a} = |\mathbf{a}|^2$$

$$\mathbf{a} \cdot \mathbf{b} = 0 \text{ if and only if } \mathbf{b} \perp \mathbf{a} \text{ for non-zero vectors } \mathbf{a} \text{ and } \mathbf{b}$$



## Example

The vectors  $\mathbf{p}$  and  $\mathbf{q}$  are such that  $|\mathbf{p}| = 5$ ,  $|\mathbf{q}| = 6$  and the angle between  $\mathbf{p}$  and  $\mathbf{q}$  is  $120^\circ$ .

Calculate the exact value of

- (i)  $\mathbf{p} \cdot \mathbf{q}$                       (ii)  $(\mathbf{p} + 2\mathbf{q}) \cdot (2\mathbf{p} - \mathbf{q})$ .

# Example

$$\text{Let } \mathbf{u} = x_1\mathbf{i} + y_1\mathbf{j} + z_1\mathbf{k}$$

$$\mathbf{v} = x_2\mathbf{i} + y_2\mathbf{j} + z_2\mathbf{k}$$

$$\text{Then } \mathbf{u} \cdot \mathbf{v} = x_1x_2 + y_1y_2 + z_1z_2$$

# Example

Given  $A(3, -4, 0)$  and  $B(2, 2, -1)$ , find

(i)  $\overrightarrow{OA} \cdot \overrightarrow{OB}$

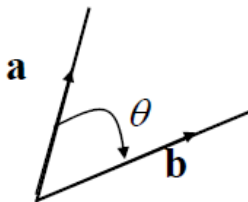
(ii)  $\overrightarrow{OA} \cdot \overrightarrow{BA}$ .

# Angle between vectors **a** and **b**

Formula:

$$\cos \theta = \frac{\mathbf{a} \cdot \mathbf{b}}{|\mathbf{a}||\mathbf{b}|} = \frac{x_1x_2 + y_1y_2 + z_1z_2}{\sqrt{x_1^2 + y_1^2 + z_1^2} \cdot \sqrt{x_2^2 + y_2^2 + z_2^2}}$$

where  $\mathbf{a} = x_1\mathbf{i} + y_1\mathbf{j} + z_1\mathbf{k}$  and  $\mathbf{b} = x_2\mathbf{i} + y_2\mathbf{j} + z_2\mathbf{k}$



## Example

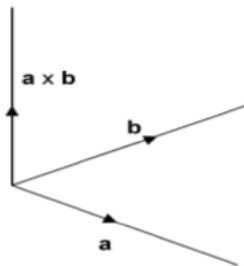
Given  $A(2, -2, 1)$ ,  $B(-2, 1, 2)$  and  $C(1, 0, -1)$ , calculate angle  $CBA$ .  
Hence, find the shortest distance between  $C$  and the line segment  $AB$ .

# Vector product

## Definition and properties

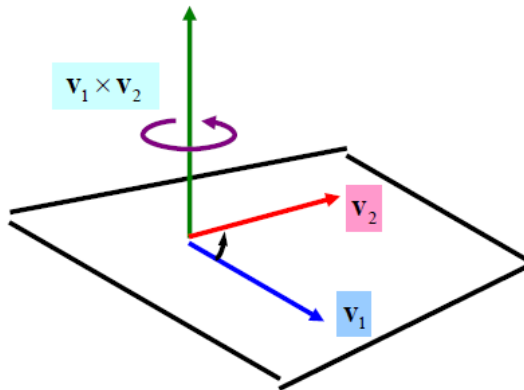
Vector Product of **a** and **b** , denoted by  **$\mathbf{a} \times \mathbf{b}$**  is defined as follows:

- (i)  **$\mathbf{a} \times \mathbf{b}$**  is perpendicular to both **a** and **b**
- (ii) direction of  **$\mathbf{a} \times \mathbf{b}$**  is given by the right-hand rule
- (iii)  **$|\mathbf{a} \times \mathbf{b}| = |\mathbf{a}||\mathbf{b}| \sin \theta$** , where  $\theta$  = angle between **a** and **b**



# Vector Product

$\mathbf{a} \times \mathbf{b}$  is perpendicular to both  $\mathbf{a}$  and  $\mathbf{b}$



Right hand

# Results

$$\mathbf{a} \times \mathbf{b} = -\mathbf{b} \times \mathbf{a}$$

$$\mathbf{a} \times \mathbf{a} = \mathbf{0}$$

$$\mathbf{i} \times \mathbf{j} = \mathbf{k}, \quad \mathbf{j} \times \mathbf{k} = \mathbf{i}, \quad \mathbf{k} \times \mathbf{i} = \mathbf{j}$$

$$\lambda(\mathbf{a} \times \mathbf{b}) = (\lambda\mathbf{a}) \times \mathbf{b} = \mathbf{a} \times (\lambda\mathbf{b}) \text{ for any scalar } \lambda$$

$$\mathbf{a} \times (\mathbf{b} + \mathbf{c}) = \mathbf{a} \times \mathbf{b} + \mathbf{a} \times \mathbf{c}$$



# Vector Product

## Method 1

$$\text{Let } \mathbf{v}_1 = \begin{pmatrix} x_1 \\ y_1 \\ z_1 \end{pmatrix} \text{ and } \mathbf{v}_2 = \begin{pmatrix} x_2 \\ y_2 \\ z_2 \end{pmatrix}.$$

Then their **vector product** or **cross product** is the vector

$$\begin{aligned} \mathbf{v}_1 \times \mathbf{v}_2 &= \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ x_1 & y_1 & z_1 \\ x_2 & y_2 & z_2 \end{vmatrix} \\ &= (y_1 z_2 - y_2 z_1) \mathbf{i} - (x_1 z_2 - x_2 z_1) \mathbf{j} + (x_1 y_2 - x_2 y_1) \mathbf{k} \end{aligned}$$

---

$$\begin{array}{ccc} \text{Recall that } \begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc & \begin{vmatrix} y_1 & z_1 \\ y_2 & z_2 \end{vmatrix} = y_1 z_2 - y_2 z_1 & \\ & + \quad - \quad + & \\ & \mathbf{i} \quad \mathbf{j} \quad \mathbf{k} & \end{array}$$

Let

$$\mathbf{u} = x_1\mathbf{i} + y_1\mathbf{j} + z_1\mathbf{k}$$

$$\mathbf{v} = x_2\mathbf{i} + y_2\mathbf{j} + z_2\mathbf{k}$$

Find

$$\mathbf{u} \times \mathbf{v}$$

$$\begin{pmatrix} x_1 \\ y_1 \\ z_1 \end{pmatrix} \times \begin{pmatrix} x_2 \\ y_2 \\ z_2 \end{pmatrix} = \begin{pmatrix} y_1 z_2 - z_1 y_2 \\ -(x_1 z_2 - x_2 z_1) \\ x_1 y_2 - x_2 y_1 \end{pmatrix}$$

Diagram illustrating the components of the cross product  $\mathbf{u} \times \mathbf{v}$  using  $2 \times 2$  determinants:

- The first component is  $y_1 z_2 - z_1 y_2$ , which is the determinant  $\begin{vmatrix} y_1 & y_2 \\ z_1 & z_2 \end{vmatrix} = y_1 z_2 - y_2 z_1$ .
- The second component is  $-(x_1 z_2 - x_2 z_1)$ , which is the negative of the determinant  $\begin{vmatrix} x_1 & x_2 \\ z_1 & z_2 \end{vmatrix} = x_1 z_2 - x_2 z_1$ .
- The third component is  $x_1 y_2 - x_2 y_1$ , which is the determinant  $\begin{vmatrix} x_1 & x_2 \\ y_1 & y_2 \end{vmatrix} = x_1 y_2 - x_2 y_1$ .

These are the so-called determinants of  $2 \times 2$  square matrices

# Vector Product - Example

Let  $\mathbf{v}_1 = \begin{pmatrix} 2 \\ 1 \\ 2 \end{pmatrix}$  and  $\mathbf{v}_2 = \begin{pmatrix} 3 \\ -1 \\ -3 \end{pmatrix}$ .

$$\begin{aligned} \mathbf{v}_1 \times \mathbf{v}_2 &= \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 2 & 1 & 2 \\ 3 & -1 & -3 \end{vmatrix} \\ &= -\mathbf{i} + 12\mathbf{j} - 5\mathbf{k} \end{aligned}$$

Recall that  $\begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc$

+	-	+
<b>i</b>	<b>j</b>	<b>k</b>

# Vector Product - Example

$$\text{Let } \mathbf{v}_1 = \begin{pmatrix} 2 \\ 1 \\ 2 \end{pmatrix} \text{ and } \mathbf{v}_2 = \begin{pmatrix} 3 \\ -1 \\ -3 \end{pmatrix}.$$

$$\begin{aligned} \mathbf{v}_1 \times \mathbf{v}_2 &= \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 2 & 1 & 2 \\ 3 & -1 & -3 \end{vmatrix} \\ &= -\mathbf{i} + 12\mathbf{j} - 5\mathbf{k} \end{aligned}$$

$$\text{Recall that } \begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc \qquad \begin{matrix} + & - & + \\ \mathbf{i} & \mathbf{j} & \mathbf{k} \end{matrix}$$

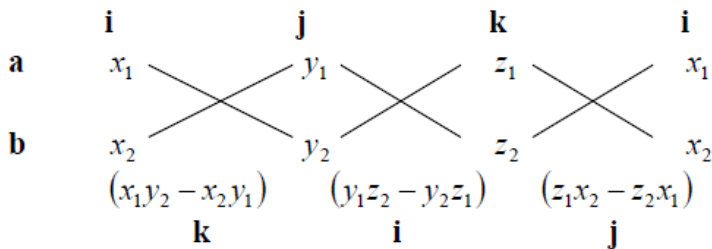
# Example

$$(\mathbf{i} + 2\mathbf{j} - 3\mathbf{k}) \times (2\mathbf{i} - \mathbf{j} - \mathbf{k}) =$$

**Homework:**  $\begin{pmatrix} 1 \\ -1 \\ 3 \end{pmatrix} \times \begin{pmatrix} -1 \\ 2 \\ -1 \end{pmatrix}$

**Answer:**  $\begin{pmatrix} -5 \\ -2 \\ 1 \end{pmatrix}$

## Method 2 ('Shoe-lace' method)



**Example**

$$\begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} \times \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix}$$

# Applications of vector products

$$\text{Area of triangle } ABC = \frac{1}{2} |\overrightarrow{CA} \times \overrightarrow{CB}|$$

$$\text{Area of triangle } ABC = \frac{1}{2} |\mathbf{a} \times \mathbf{b} + \mathbf{b} \times \mathbf{c} + \mathbf{c} \times \mathbf{a}|$$

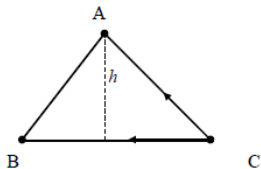
## Example

Find the area of triangle  $ABC$  given  $A = (1, 2, 3)$ ,  $B = (2, 4, 6)$  and  $C = (-2, 3, -4)$



Shortest distance  $h$  from  $A$  to  $BC$  is

$$h = \frac{|\overrightarrow{CA} \times \overrightarrow{CB}|}{|\overrightarrow{CB}|} = \frac{|\mathbf{a} \times \mathbf{b} + \mathbf{b} \times \mathbf{c} + \mathbf{c} \times \mathbf{a}|}{|\mathbf{b} - \mathbf{c}|}$$



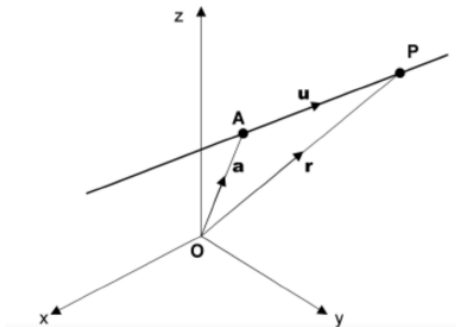
# Lines in 3-D Space

# Lines In Three-dimensional Space

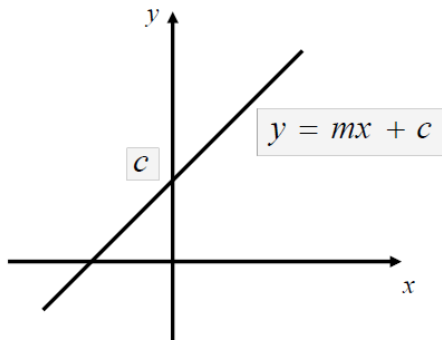
The line  $L$  passes through a point  $A$  and is parallel to a vector  $\mathbf{u}$  has vector equation

$$\mathbf{r} = \overbrace{\mathbf{a}}^{\text{point}} + \lambda \overbrace{\mathbf{u}}^{\text{direction vector}}$$

where  $\lambda \in \mathbb{R}$



# Linear Equation in 2 Variables



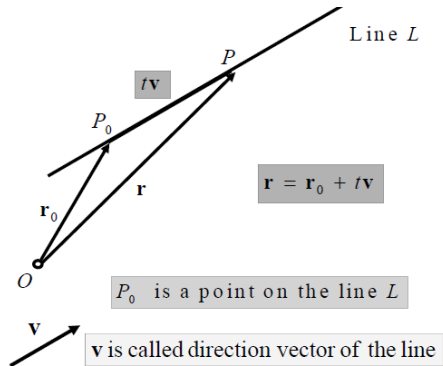
To determine a line, we need

gradient  $m$

$y$ -intercept  $c$

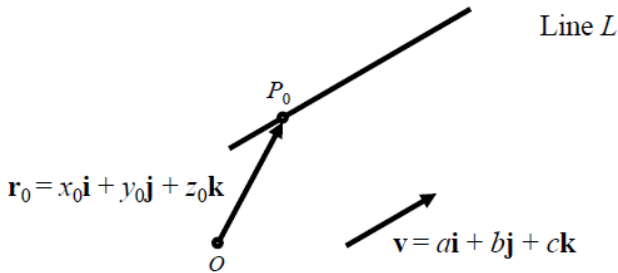
# Vector Equation of a Line

Find the equation of the line  $L$



Different values of  $t$  gives different points on the line  $L$ .

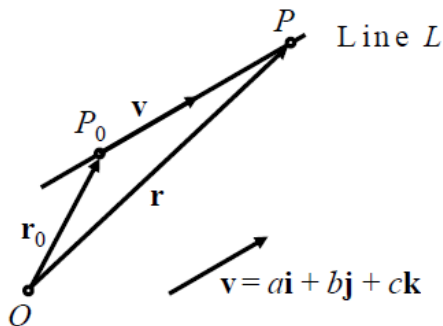
Find the equation of the line  $L$



The point  $P_0$  bring you to the line  $L$ .

# Vector Equation of a Line

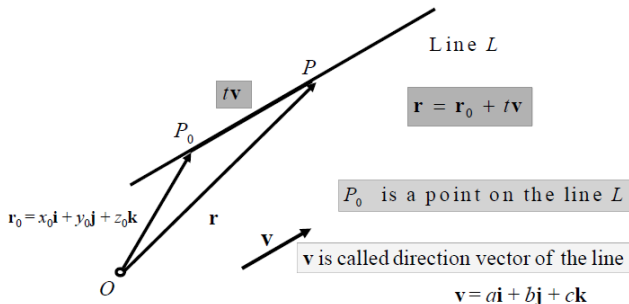
Let  $P(x, y, z)$  be any point on  $L$  with position vector  $\mathbf{r}$ .



If you walk in the direction parallel to  $\mathbf{v}$ , then you will be always on the line  $L$ .

In this way, you can reach any point on the line  $L$ .

Find the equation of the line  $L$



Then a **vector equation** of  $L$  is

$$\mathbf{r} = (x_0\mathbf{i} + y_0\mathbf{j} + z_0\mathbf{k}) + t(a\mathbf{i} + b\mathbf{j} + c\mathbf{k})$$

or

$$\mathbf{r}(t) = \mathbf{r}_0 + t\mathbf{v}$$



# Parametric Equation of a Line

$$\begin{aligned}\text{Write } \mathbf{r} &= x\mathbf{i} + y\mathbf{j} + z\mathbf{k} \\ &= (x_0\mathbf{i} + y_0\mathbf{j} + z_0\mathbf{k}) + t(a\mathbf{i} + b\mathbf{j} + c\mathbf{k}).\end{aligned}$$

Equating, we have

$$\begin{cases} x = x_0 + at \\ y = y_0 + bt \\ z = z_0 + ct \end{cases}$$

which are the parametric equations of the line  $L$ .

Vector equation of line  $L$  (denoted by  $\mathbf{r}$ ) passing through

$$A(x_0, y_0, z_0)$$

and parallel to

$$\mathbf{u} = d\mathbf{i} + e\mathbf{j} + f\mathbf{k}$$

$$\mathbf{r} = \mathbf{a} + \lambda\mathbf{u} \quad (\lambda \in \mathbb{R})$$

$$\mathbf{r} = x\mathbf{i} + y\mathbf{j} + z\mathbf{k}$$

$$= (x_0\mathbf{i} + y_0\mathbf{j} + z_0\mathbf{k}) + \lambda(d\mathbf{i} + e\mathbf{j} + f\mathbf{k})$$

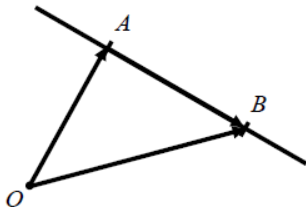
$$= (x_0 + \lambda d)\mathbf{i} + (y_0 + \lambda e)\mathbf{j} + (z_0 + \lambda f)\mathbf{k}$$

$$\mathbf{r} = \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} x_0 \\ y_0 \\ z_0 \end{pmatrix} + \lambda \begin{pmatrix} d \\ e \\ f \end{pmatrix}$$

## Example

The points  $A$  and  $B$  have position vectors  $-3\mathbf{i} + 2\mathbf{j} - 3\mathbf{k}$  and  $\mathbf{i} - \mathbf{j} + 4\mathbf{k}$  respectively. Write down the parametric equations of the line passing through  $A$  and  $B$ .

$$\begin{aligned}\overrightarrow{AB} &= (\mathbf{i} - \mathbf{j} + 4\mathbf{k}) - (-3\mathbf{i} + 2\mathbf{j} - 3\mathbf{k}) \\ &= 4\mathbf{i} - 3\mathbf{j} + 7\mathbf{k}\end{aligned}$$



We may take  $\mathbf{v} = \overrightarrow{AB}$  as the direction vector of line  $AB$ .  
The vector equation is

$$\mathbf{r} = (-3\mathbf{i} + 2\mathbf{j} - 3\mathbf{k}) + t(4\mathbf{i} - 3\mathbf{j} + 7\mathbf{k}).$$

## Example

The vector equation is

$$\mathbf{r} = (-3\mathbf{i} + 2\mathbf{j} - 3\mathbf{k}) + t(4\mathbf{i} - 3\mathbf{j} + 7\mathbf{k}).$$

Write  $\mathbf{r} = x\mathbf{i} + y\mathbf{j} + z\mathbf{k}$

Hence the parametric equations of line the passing through  $A$  and  $B$  are

$$\begin{cases} x = -3 + 4t \\ y = 2 - 3t \\ z = -3 + 7t \end{cases}$$

## Example

Find the vector equation of the line that passes through  $A(1, 2, 3)$  and // to the vector  $\begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix}$ . Does the point  $C(-8, -3, 0)$  lie on this line?

# Example

Find the vector equation of the line that passes through  $A(1, 2, 3)$  and  $B(3, 4, 6)$ . Show that the point  $D(9, 10, 15)$  lies on this line.

## Intersecting Lines and Skew Lines

Given 2 lines

$$\mathbf{r} = \begin{pmatrix} a_1 \\ b_1 \\ c_1 \end{pmatrix} + \lambda \begin{pmatrix} r_1 \\ s_1 \\ t_1 \end{pmatrix} \text{ and } \mathbf{r} = \begin{pmatrix} a_2 \\ b_2 \\ c_2 \end{pmatrix} + \lambda \begin{pmatrix} r_2 \\ s_2 \\ t_2 \end{pmatrix}$$

there are four possibilities:

- They are coincident/identical
- They are parallel, not coincident
- They are non-parallel and intersecting
- They are non-parallel and non-intersecting (skew lines)



## Example

Find the position vector of the point of intersection of  $L_1$  and  $L_2$ .

$$L_1 : \mathbf{r} = \mathbf{i} + t_1(\mathbf{i} + 2\mathbf{j} + 3\mathbf{k}),$$

$$L_2 : \mathbf{r} = (2\mathbf{i} + \mathbf{j}) + t_2(3\mathbf{i} + \frac{9}{2}\mathbf{j} + \frac{9}{2}\mathbf{k}).$$

Eliminating  $\mathbf{r}$  from the vector equations of  $L_1$  and  $L_2$ , we get

$$\boxed{\mathbf{i}} + \boxed{t_1(\mathbf{i})} + 2\mathbf{j} + 3\mathbf{k} = (\boxed{2\mathbf{i}} + \mathbf{j}) + \boxed{t_2(3\mathbf{i})} + \frac{9}{2}\mathbf{j} + \frac{9}{2}\mathbf{k}.$$

Hence it follows that

$$\boxed{1 + t_1 = 2 + 3t_2}, \quad 2t_1 = 1 + \frac{9}{2}t_2, \quad 3t_1 = \frac{9}{2}t_2$$

from which we obtain  $t_1 = -1$  and  $t_2 = -\frac{2}{3}$ .

Find the position vector of the point of intersection of  $L_1$  and  $L_2$ .

$$L_1 : \mathbf{r} = \mathbf{i} + t_1(\mathbf{i} + 2\mathbf{j} + 3\mathbf{k}),$$

$$L_2 : \mathbf{r} = (2\mathbf{i} + \mathbf{j}) + t_2(3\mathbf{i} + \frac{9}{2}\mathbf{j} + \frac{9}{2}\mathbf{k}).$$

Putting  $t_1 = -1$  into the vector equation of  $L_1$ , we obtain

$$\mathbf{r} = \mathbf{i} + (-1)(\mathbf{i} + 2\mathbf{j} + 3\mathbf{k}) = -2\mathbf{j} - 3\mathbf{k}.$$

So the position vector of the point of intersection  $P$  of the two lines is

$$\overrightarrow{OP} = -2\mathbf{j} - 3\mathbf{k}.$$

# Example

Determine whether the following pair of lines intersect. If they do, find the position vector of their point of intersection.

(i)  $\mathbf{r} = 2\mathbf{i} + 5\mathbf{k} + s(\mathbf{i} - \mathbf{j} + 2\mathbf{k})$

$$\mathbf{r} = 3\mathbf{i} - 2\mathbf{j} + t(-3\mathbf{i} + 3\mathbf{j} - 6\mathbf{k})$$

(ii)  $\mathbf{r} = \mathbf{i} + \mathbf{j} + 2\mathbf{k} + s(-\mathbf{i} + 2\mathbf{j} + 3\mathbf{k})$

$$\mathbf{r} = \mathbf{i} + 3\mathbf{j} + 10\mathbf{k} + t(-3\mathbf{i} + 4\mathbf{j} + \mathbf{k})$$

(iii)  $\mathbf{r} = 2\mathbf{i} + \mathbf{j} + 2\mathbf{k} + s(-\mathbf{i} + 2\mathbf{j} + 3\mathbf{k})$

$$\mathbf{r} = \mathbf{i} + 3\mathbf{j} + 4\mathbf{k} + t(-3\mathbf{i} + \mathbf{k})$$

# Example

$$\begin{aligned} \text{(i) } \mathbf{r} &= 2\mathbf{i} + 5\mathbf{k} + s(\mathbf{i} - \mathbf{j} + 2\mathbf{k}) \\ \mathbf{r} &= 3\mathbf{i} - 2\mathbf{j} + t(-3\mathbf{i} + 3\mathbf{j} - 6\mathbf{k}) \end{aligned}$$

# Example

$$(ii) \mathbf{r} = \mathbf{i} + \mathbf{j} + 2\mathbf{k} + s(-\mathbf{i} + 2\mathbf{j} + 3\mathbf{k})$$

$$\mathbf{r} = \mathbf{i} + 3\mathbf{j} + 10\mathbf{k} + t(-3\mathbf{i} + 4\mathbf{j} + \mathbf{k})$$

# Example

$$\begin{aligned}\text{(iii)} \quad \mathbf{r} &= 2\mathbf{i} + \mathbf{j} + 2\mathbf{k} + s(-\mathbf{i} + 2\mathbf{j} + 3\mathbf{k}) \\ \mathbf{r} &= \mathbf{i} + 3\mathbf{j} + 4\mathbf{k} + t(-3\mathbf{i} + \mathbf{k})\end{aligned}$$

*Skew* lines are lines on different parallel planes

## Example

Show that  $L_1$  and  $L_3$  are skew, i.e., do not intersect each other.

$$L_1 : \mathbf{r} = \mathbf{i} + t_1(\mathbf{i} + 2\mathbf{j} + 3\mathbf{k}),$$

$$L_3 : \mathbf{r} = (2\mathbf{i} + \mathbf{j}) + t_3(3\mathbf{i} + \mathbf{j}).$$

Eliminating  $\mathbf{r}$  from the vector equations of  $L_1$  and  $L_3$ , we get

$$\mathbf{i} + t_1(\mathbf{i} + 2\mathbf{j} + 3\mathbf{k}) = (2\mathbf{i} + \mathbf{j}) + t_3(3\mathbf{i} + \mathbf{j}).$$

Hence it follows that

$$1 + t_1 = 2 + 3t_3, \quad 2t_1 = 1 + t_3, \quad 3t_1 = 0.$$

Solving the first two equations above gives  $t_1 = \frac{2}{5}$  but the last equation says  $t_1 = 0$ , thus there is a contradiction.

So there is no solution to the equations and we conclude that  $L_1$  and  $L_3$  do not intersect.



# Foot of Perpendicular and Shortest Distance From a Point to a Line

## Exmample

Find the position vector of the foot of perpendicular from  $P(1, -4, 13)$  to the line

$$\mathbf{r} = \begin{pmatrix} 1 - 2s \\ 2 - 3s \\ 3 + 4s \end{pmatrix}, s \in \mathbb{R}$$

# Planes In Three-dimensional Space

# Planes In Three-dimensional Space

Let a vector perpendicular to a given plane be denoted by  $\mathbf{n}$ . We call this a normal vector to the plane.

Fix a point  $A$  on the plane and let  $P$  be any point on the plane. Let the position vectors of  $A$  and  $P$  be  $\mathbf{a}$  and  $\mathbf{r}$ .

Then, the vector  $\overrightarrow{AP}$  is perpendicular to the normal vector  $\mathbf{n}$ . Hence,

$$(\mathbf{r} - \mathbf{a}) \cdot \mathbf{n} = 0$$

or

$$\mathbf{r} \cdot \mathbf{n} = \mathbf{a} \cdot \mathbf{n}$$

This is the vector equation of the plane.

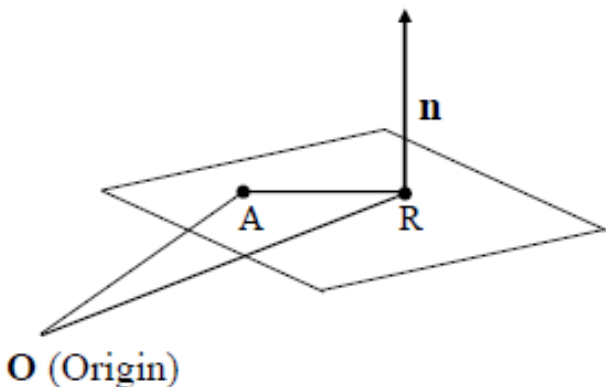
The normal vector  $\mathbf{n}$  can be found from

$$\mathbf{n} = \mathbf{u} \times \mathbf{v}$$

where  $\mathbf{u}$  and  $\mathbf{v}$  are any vectors that are parallel to the plane and  $\mathbf{u}$  is **NOT** parallel to  $\mathbf{v}$ .

$A$  is a given point on plane with normal  $\mathbf{n}$

$R$  is any point on plane



# Example

Find the equation, in the form  $\mathbf{r} \cdot \mathbf{n} = d$ , of the plane which

(i) is perpendicular to the vector  $4\mathbf{i} + 3\mathbf{j} + 5\mathbf{k}$  and which contains the point  $(2, -2, 0)$

(ii) passes through  $A(1, 2, 3)$ ,  $B(2, 2, -1)$  and  $C(0, 0, 1)$

(iii) contains  $A(3, 4, 5)$  and line  $L : \mathbf{r} = 4\mathbf{i} + 3\mathbf{j} + 5\mathbf{k} + \mu(-\mathbf{i} + 2\mathbf{j} - 3\mathbf{k})$

# Cartesian Equation of Plane

A Cartesian equation of the plane  $\mathbf{r} \cdot \mathbf{n} = d$  is

$$ax + by + cz = d$$

where  $\mathbf{n} = a\mathbf{i} + b\mathbf{j} + c\mathbf{k}$  and  $\mathbf{r} = x\mathbf{i} + y\mathbf{j} + z\mathbf{k}$

For example:

$$\mathbf{r} \cdot (2\mathbf{i} - 3\mathbf{j} + 5\mathbf{k}) = 6$$

Cartesian equation:

# Intersection Between Lines and Planes

$\mathbf{r} = \mathbf{a} + \lambda \mathbf{u}$  meets  $\mathbf{r} \cdot \mathbf{n} = d$  provided they are not parallel, i.e.  $\mathbf{u} \cdot \mathbf{n} \neq 0$

## Example

Find the position vector of the point of intersection of the line

$\mathbf{r} = 2\mathbf{i} + 3\mathbf{j} + 4\mathbf{k} + \mu(\mathbf{i} + \mathbf{j} + \mathbf{k})$  and the plane  $\Pi : \mathbf{r} \cdot \begin{pmatrix} 1 \\ 0 \\ -2 \end{pmatrix} = 3$ .

## Example

Given that the line  $\mathbf{r} = 2\mathbf{i} + 3\mathbf{j} + 4\mathbf{k} + \mu(\mathbf{i} + \mathbf{j} + \mathbf{k})$  lies entirely on the plane  $x + 2y + pz = q$ , find the values of  $p$  and  $q$ .



# Acute Angle Between Planes

Let  $\mathbf{n}_1, \mathbf{n}_2$  be normal vectors to the planes

$$\cos \theta = \left| \frac{\mathbf{n}_1 \cdot \mathbf{n}_2}{|\mathbf{n}_1| |\mathbf{n}_2|} \right|.$$

## Example

Calculate the acute angle between the planes:

$$\Pi_1 : 3x - 4y + 5z = 6 \quad \text{and} \quad \Pi_2 : \mathbf{r} \cdot \begin{pmatrix} 1 \\ 0 \\ -2 \end{pmatrix} = 3.$$

# Acute Angle Between Line and Plane

**u**: direction vector of line

**n**: normal vector of plane

$$\sin \theta = \left| \frac{\mathbf{u} \cdot \mathbf{n}}{|\mathbf{u}| |\mathbf{n}|} \right|.$$

## Example

Calculate the angle between the line  $\mathbf{r} = 2\mathbf{i} + 3\mathbf{j} + 4\mathbf{k} + \mu(\mathbf{i} + \mathbf{j} + \mathbf{k})$  and the plane  $3x - 4y + 5z = 6$ .

# Intersection of Two Planes

Suppose two non-parallel planes

$$\Pi_1 : \mathbf{r} \cdot \mathbf{n}_1 = d_1 \quad \text{and} \quad \Pi_2 : \mathbf{r} \cdot \mathbf{n}_2 = d_2$$

intersect along the line  $L$ .

Vector equation of  $L$ :

$$\mathbf{r} = \mathbf{a} + \lambda(\mathbf{n}_1 \times \mathbf{n}_2), \quad (\lambda \in \mathbb{R})$$

where  $\mathbf{a}$  is the position vector of a point on both planes

# Example

Find the line of intersection between:

$$\mathbf{r} \cdot (\mathbf{i} - 2\mathbf{j} + 5\mathbf{k}) = 1 \quad \text{and} \quad 3x + 2y - 7z = 11.$$