#### DELFT UNIVERSITY OF TECHNOLOGY

FACULTY OF AEROSPACE ENGINEERING ROTOR / WAKE AERODYNAMICS - AE4135

## Rotor / wake Aerodynamics Assignment 1: Blade Element Theory

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Nomenlacture

```
angle of attack at blade element (-)
                   blade twist angle at blade element (-)
                   tip speed ratio (-)
                   fluid density (kg \cdot m<sup>-3</sup>)
                   circulation at blade element (m^2 \cdot s^{-1})
                   perceived-wind inflow-angle at blade element (-)
                   rotor rotational velocity (rad \cdot s<sup>-1</sup>)
                   axial induction factor (-)
                   azimuthal induction factor (-)
                   blade element chord (m)
                   drag coefficient (-)
             C_d
             C_l
                  lift coefficient (-)
                   thrust coefficient (-)
            C_T
                   drag force per unit span (N \cdot m^{-1})
          Drag
                  lift force per unit span (N \cdot m^{-1})
           Lift
                   azimuthal/tangential force per unit span (N \cdot m^{-1})
          F_{\rm azim}
                   axial force per unit span (N \cdot m^{-1})
          F_{\text{axial}}
                   number of blades (-)
        N_{\rm blades}
                    axial velocity perceived by blade element, axial velocity at rotor (m \cdot s^{-1})
V_{\text{axial}} = U_{\text{rotor}}
                   velocity perceived by blade element (m \cdot s^{-1})
                   azimuthal/tangential velocity perceived by blade element (m \cdot s^{-1})
           V_{\rm tan}
```

Table 2.1: Wind turbine geometrical specifications

Variable	Value
Radius (R)	50 [m]
Number of Blades	3
Blade starts at	$0.2~\mathrm{r/R}$
Twist	14*(1-r/R) [degrees]
Blade Pitch	-2 [degrees]
Chord Distribution	3*(1-r/R)+1 [m]
Airfoil	DU 95-W-180
Rotor yaw angle	0, 15 and 30 [degrees]

Table 2.2: Wind turbine operational specifications

Variable	Value
Wind speed (U0)	10 [m/s]
Tip speed ratio $(\lambda)$	6, 8, 10
Rotor yaw angle	0, 15, 30 [degrees]

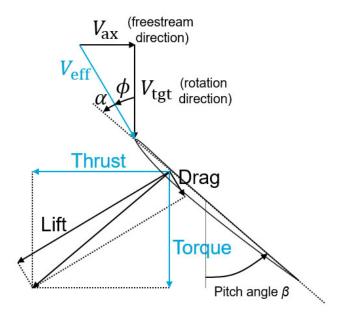


Figure 2.1: Caption

### Flow diagram of the code

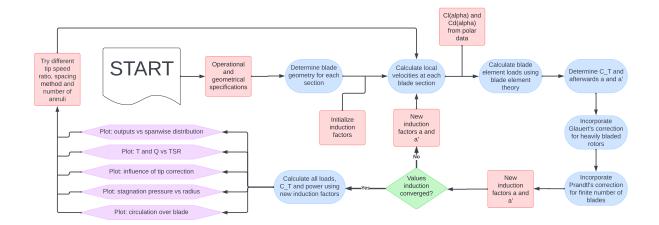


Figure 3.1: Flow diagram of the code

#### 3.1 Assumptions

- Steady Flow: the flow characteristics are assumed to be independent of time.
- Inviscid Flow: the flow is assumed to be inviscid. This means no viscous effects are taken into account.
- Incompressible Flow: the flow is assumed to be incompressible. This means the density throughout the streamtube is constant. This enables the use of Bernoulli's equation in locations of a continuous pressure distribution. This also results in the product of area and flow velocity being constant over the flow.
- 2D Flow: it is assumed that the flow characteristics can accurately be modeled using 2 dimensional flow characteristics.
- Constant Internal Energy: it is assumed that the internal energy within the streamtube is constant so there no radiation, convection or conduction occurring.
- Independent annulus: the annuli are considered independently of one another. In reality, flow characteristics on one annulus will influence the characteristics on another (cross flow), this effect is ignored.
- Circular Discs: the actuator disc in the model is assumed to be of circular shape. In reality slight changes in the shape could occur, these are neglected.
- Root-section: it is assumed that the root section till r/R = 0.2 has no influence on the performance of the turbine and can be neglected.

#### 4.1 Reference Data (for cl(alpha) and cd(alpha))

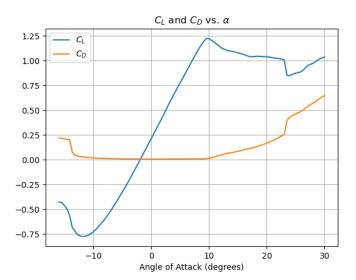


Figure 4.1: Lift Curve and Drag Curve

#### 4.2 Corrections

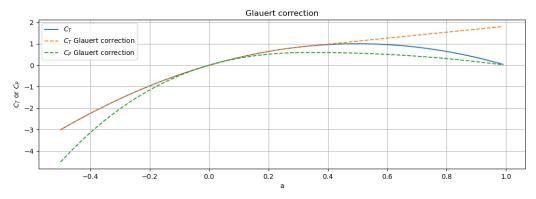


Figure 4.2: Glauert correction

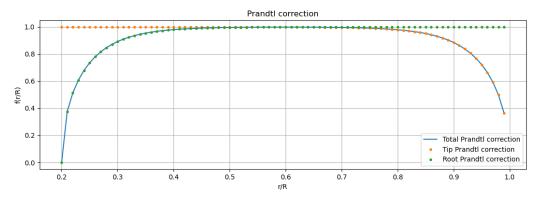


Figure 4.3: Prandtl correction

#### 4.3 Angles

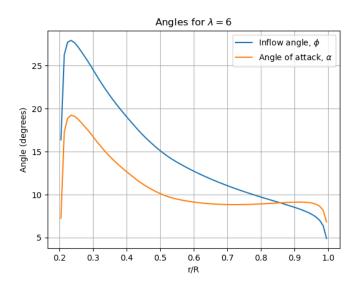


Figure 4.4: Span-wise distribution of Angle of Attack and Inflow Angle for Tip Speed Ratio of 6

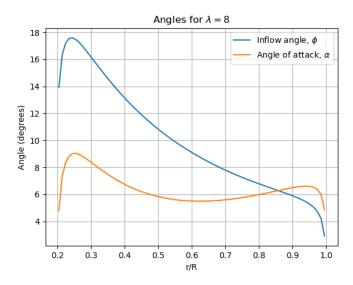


Figure 4.5: Span-wise distribution of Angle of Attack and Inflow Angle for Tip Speed Ratio of 8

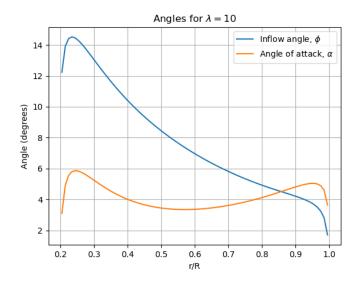


Figure 4.6: Span-wise distribution of Angle of Attack and Inflow Angle for Tip Speed Ratio of 10

#### 4.4 Induction factors

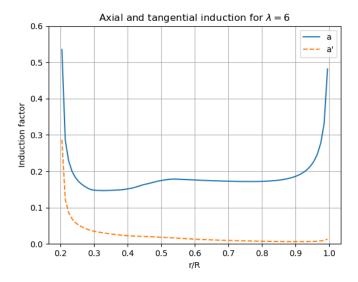


Figure 4.7: Span-wise distribution for Axial and Tangential Induction for Tip Speed Ratio of 6

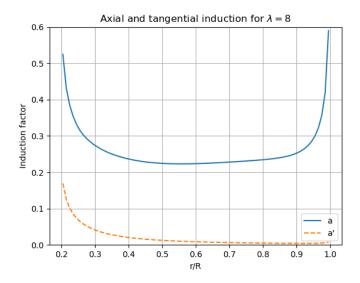


Figure 4.8: Span-wise distribution for Axial and Tangential Induction for Tip Speed Ratio of 8

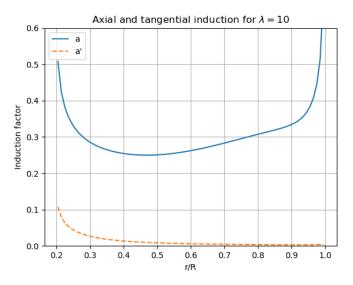


Figure 4.9: Span-wise distribution for Axial and Tangential Induction for Tip Speed Ratio of 10

#### 4.5 Forces

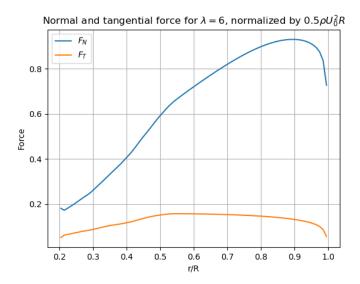


Figure 4.10: Normalized Normal and Tangential Force for Tip Speed Ratio of  $6\,$ 

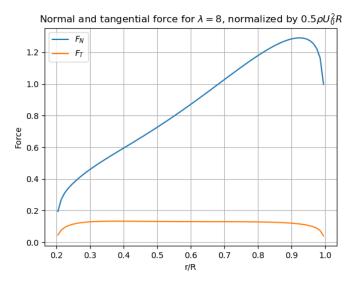


Figure 4.11: Normalized Normal and Tangential Force for Tip Speed Ratio of 8

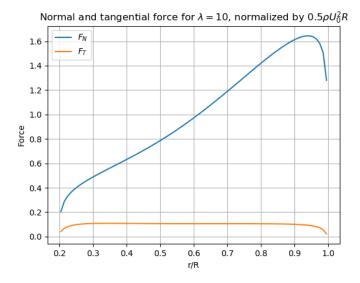


Figure 4.12: Normalized Normal and Tangential Force for Tip Speed Ratio of 10

#### 4.6 Circulation

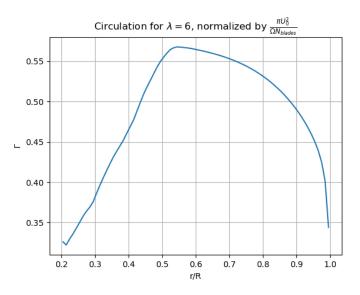


Figure 4.13: Normilzed Circulation for Tip Speed Ratio of 6

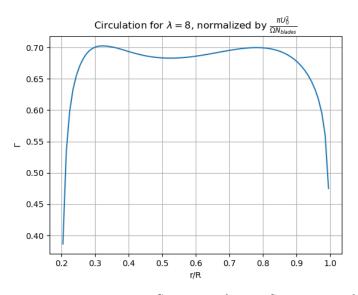


Figure 4.14: Normilzed Circulation for Tip Speed Ratio of 8

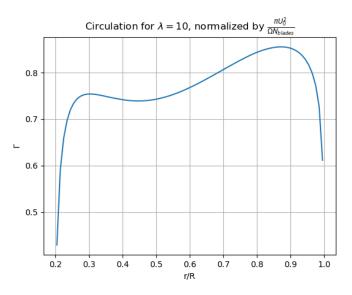


Figure 4.15: Normilzed Circulation for Tip Speed Ratio of 10

#### 4.7 Static Pressure

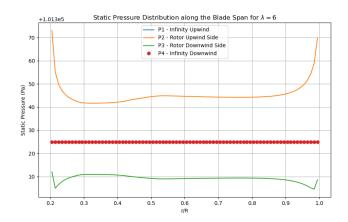


Figure 4.16: Span-wise Static Pressure Distribution for Tip Speed Ratio of 6

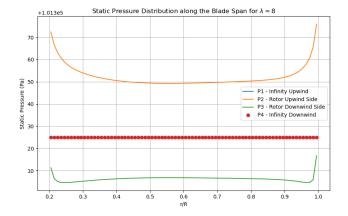


Figure 4.17: Span-wise Static Pressure Distribution for Tip Speed Ratio of 8

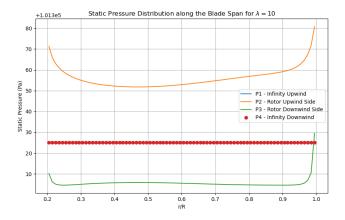


Figure 4.18: Span-wise Static Pressure Distribution for Tip Speed Ratio of 10

#### 4.8 Total pressure

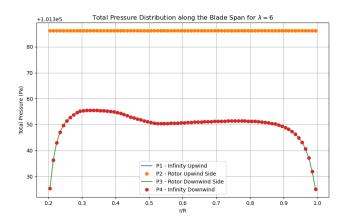


Figure 4.19: Span-wise Total Pressure Distribution for Tip Speed Ratio of  $6\,$ 

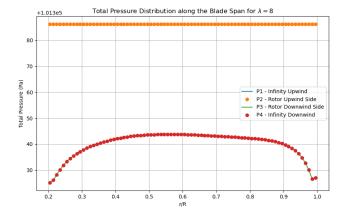


Figure 4.20: Span-wise Total Pressure Distribution for Tip Speed Ratio of 8

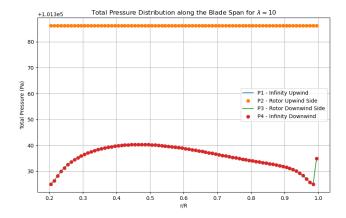


Figure 4.21: Span-wise Total Pressure Distribution for Tip Speed Ratio of 10

#### 4.9 Thrust and torque vs TSR

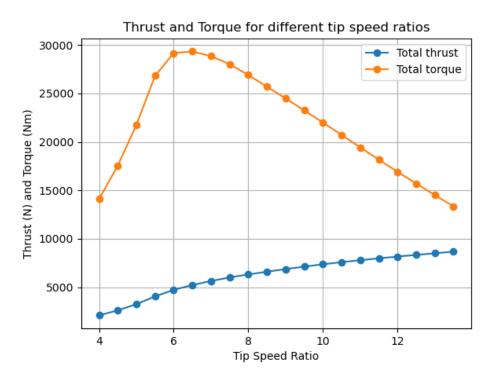


Figure 4.22: Thrust and Torque function of Tip Speed Ratio

#### 4.10 Thrust vs number of annuli

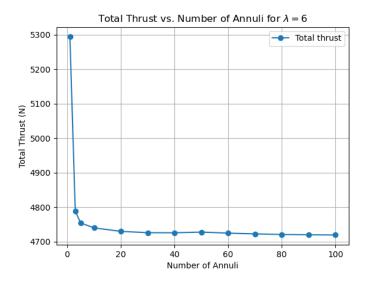


Figure 4.23: Thrust function of Annuli for Tip Speed Ratio of 6

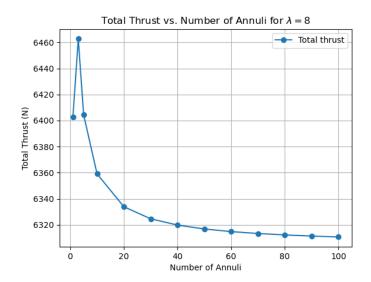


Figure 4.24: Thrust function of Annuli for Tip Speed Ratio of 8

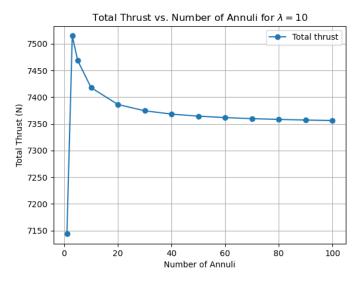


Figure 4.25: Thrust function of Annuli for Tip Speed Ratio of 10

#### 4.11 Effect of spacing method on convergence

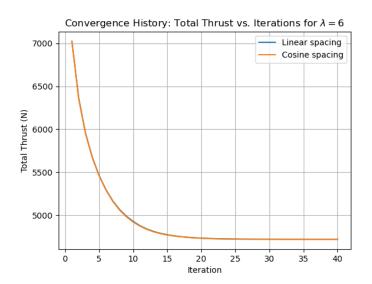


Figure 4.26: Thrust Convergence for Tip Speed Ratio of 6

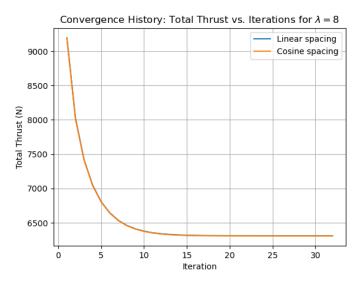


Figure 4.27: Thrust Convergence for Tip Speed Ratio of 8

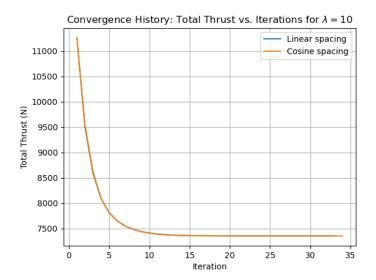


Figure 4.28: Thrust Convergence for Tip Speed Ratio of 10

# Conclusion 5

# Python Script 6