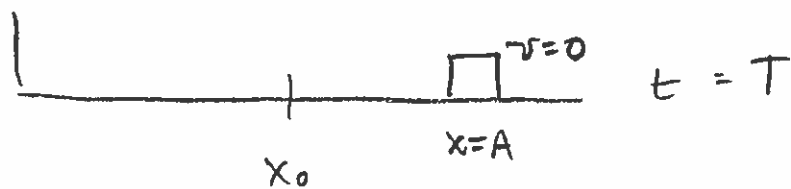
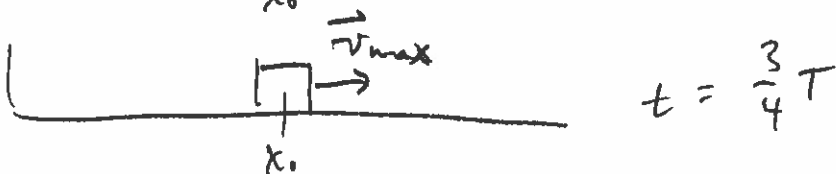
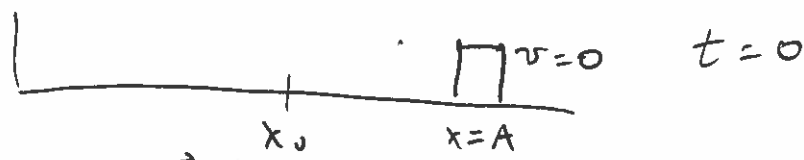


GW1:



a. $v_{max} \Rightarrow$ at equilibrium

$$t_1 = \frac{1}{4} T \quad t_2 = \frac{3}{4} T$$

b. $x=A \Rightarrow$ at original amplitude

$$t_1 = T \quad t_2 = 2T$$

c. $v=0 \rightarrow$ at either amplitude

$$t_1 = \frac{1}{2} T \quad t_2 = T$$

d. $E = K \Rightarrow U_s = 0$ at equilibrium

$$t_1 = \frac{1}{4} T \quad t_2 = \frac{3}{4} T$$

e. $E = U_s \Rightarrow K = 0 \Rightarrow$ at either amplitude

$$t_1 = \frac{1}{2} T \quad t_2 = T$$

Qw2: Need position as function of time

$$A = 0.30 \text{ m} \quad \frac{A}{2} = 0.15 \text{ m}$$

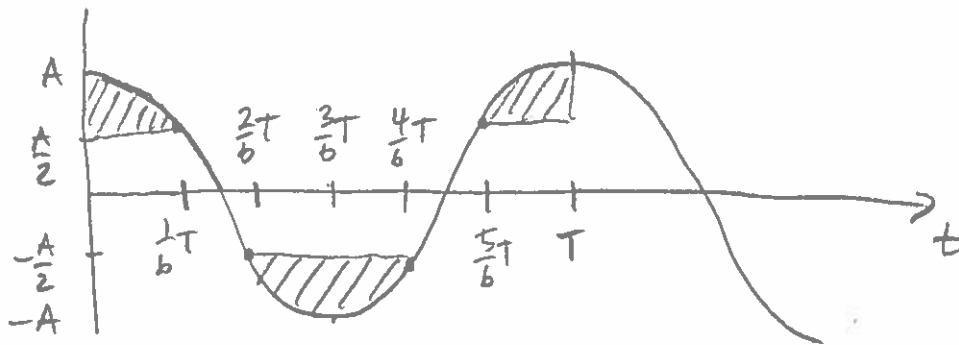
$$x(t) = A \cos \omega t$$

$$\frac{A}{2} = A \cos \omega t$$

$$\frac{1}{2} = \cos \omega t$$

$$\omega t = \cos^{-1}\left(\frac{1}{2}\right) = \frac{\pi}{3}$$

$$t = \frac{1}{3} \left(\frac{\pi}{\omega} \right) = \frac{1}{6} \left(\frac{2\pi}{\omega} \right) = \frac{1}{6} T$$



$$\text{Total time with } x > \frac{A}{2} = \frac{1}{6} T + \frac{1}{3} T + \frac{1}{6} T = \frac{2}{3} T$$

$$\text{Total time with } x < \frac{A}{2} = \frac{1}{6} T + \frac{1}{6} T = \frac{1}{3} T$$

$$G_{W3}: K = U_s$$

$$E = K + U_s = U_s + U_s = 2 U_s$$

$$\frac{1}{2} K A^2 = 2 \left(\frac{1}{2} K x^2 \right)$$

$$x^2 = \frac{A^2}{2}$$

$$x = \sqrt{\frac{A^2}{2}} = \frac{1}{\sqrt{2}} A = 0.707 A$$

EX1: a. NSL approach

$$\begin{aligned} |v_{\max}| &= \omega A \\ &= 20(0.4) \\ &= 8 \frac{\text{m}}{\text{s}} \end{aligned}$$

$$\omega = \sqrt{\frac{k}{m}} = \sqrt{\frac{200}{0.5}} = 20 \frac{\text{rad}}{\text{s}}$$

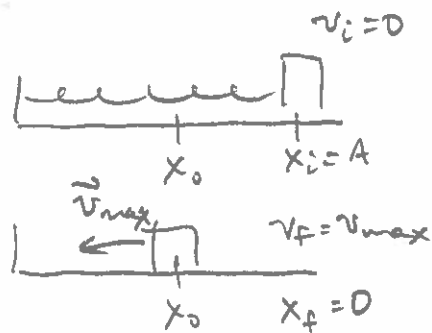
COE approach

$$k_i + U_{si} = k_f + U_{sf}$$

$$0 + \frac{1}{2} k A^2 = \frac{1}{2} m v_{\max}^2 + 0$$

$$v_{\max}^2 = \frac{k}{m} A^2$$

$$v_{\max} = \sqrt{\frac{k}{m} A^2} = \sqrt{\frac{k}{m}} A = \omega A = 8 \frac{\text{m}}{\text{s}}$$



b. $|v(t)| = \omega A \sin \omega t$

$$\frac{1}{2} v_{\max} = \omega A \sin \omega t$$

$$\frac{1}{2} \omega A = \omega A \sin \omega t$$

$$\sin \omega t = \frac{1}{2}$$

$$\omega t = \sin^{-1}\left(\frac{1}{2}\right) = \frac{\pi}{6}$$

$$t = \frac{\pi}{6\omega} = \frac{\pi}{6 \cdot 20} = 0.0262 \text{ s}$$

c. $|a_{\max}| = \omega^2 A$

$$= (20)^2 (0.4)$$

$$= 160 \frac{\text{m}}{\text{s}^2}$$

d. For speed:

$$K_i + U_{si} = K_f + U_{sf}$$

$$0 + \frac{1}{2} k A^2 = \frac{1}{2} m v_f^2 + \frac{1}{2} k \left(\frac{1}{2} A\right)^2$$

$$v_f^2 = \frac{k}{m} \left(A^2 - \frac{1}{4} A^2 \right) = \frac{k}{m} \left(\frac{3}{4} A^2 \right) = \omega^2 \left(\frac{3}{4} A^2 \right)$$

$$v_f = \sqrt{\omega^2 \left(\frac{3}{4} A^2 \right)} = \frac{\sqrt{3}}{2} \omega A$$

$$= \frac{\sqrt{3}}{2} (20)(0.4)$$

$$= 6.93 \frac{\text{m}}{\text{s}}$$

For acceleration

$$\sum F_x = m a_x$$

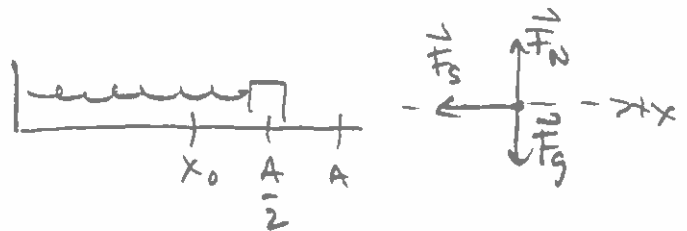
$$-kx = ma$$

$$a = -\frac{k}{m} \left(\frac{A}{2} \right) = -\omega^2 \left(\frac{A}{2} \right)$$

$$= -(20)^2 \left(\frac{0.4}{2} \right)$$

$$= -80 \frac{\text{m}}{\text{s}^2}$$

$$|\vec{a}| = 80 \frac{\text{m}}{\text{s}^2}$$



$$\begin{aligned}
 e. \quad K &= \frac{1}{2} m v^2 \\
 &= \frac{1}{2} (0.5) (6.93)^2 \\
 &= 12 \text{ J}
 \end{aligned}$$

$$\begin{aligned}
 U_s &= \frac{1}{2} k x^2 \\
 &= \frac{1}{2} k \left(\frac{1}{2} A \right)^2 \\
 &= \frac{1}{2} (200) \left(\frac{1}{2} \cdot 0.4 \right)^2 \\
 &= 4 \text{ J}
 \end{aligned}$$

$$E = K + U_s = 12 + 4 = 16 \text{ J}$$

$$\begin{aligned}
 \text{Check: } E &= \frac{1}{2} k A^2 \\
 &= \frac{1}{2} (200) (0.4)^2 \\
 &= 16 \text{ J}
 \end{aligned}$$