

# PROJECT REPORT

## Road detection by radon transform and it's approximation

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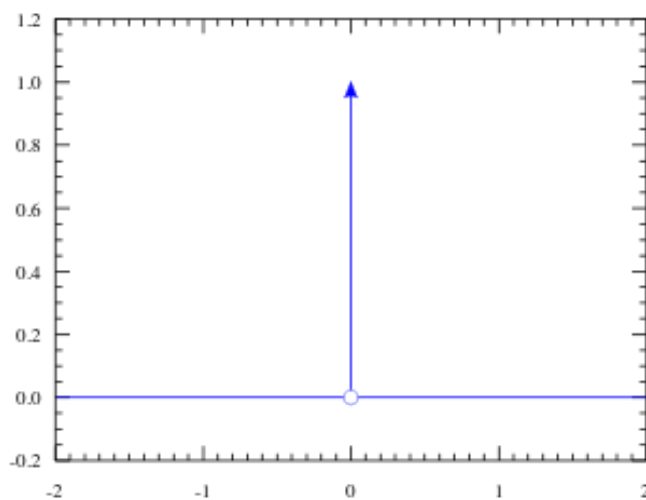
RADON TRANSFORM:

$$x = \mathcal{R} \\ = \int_{\mathbb{R}^2} y(s_1, s_2) \delta(\rho - s_1 \cos(\theta) - s_2 \sin(\theta)) ds_1 ds_2$$

Here  $y(s_1, s_2)$  is input image.

$\mathcal{R}$  is the radon.

$\rho - s_1 \cos(\theta) - s_2 \sin(\theta)$  is representing a line .

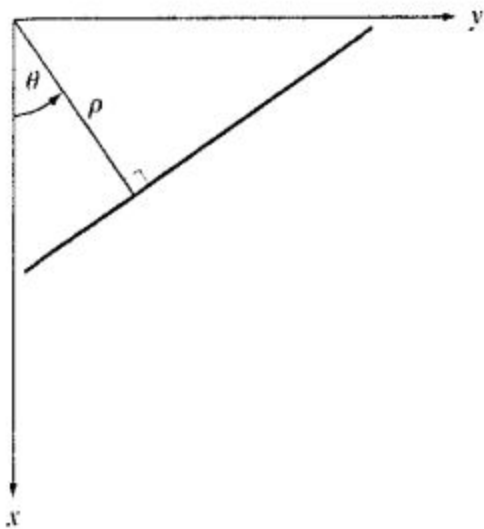


this is the dirac function so for all

$[\rho - s_1 \cos(\theta) - s_2 \sin(\theta) = 0$  we get  $\delta(\rho - s_1 \cos(\theta) - s_2 \sin(\theta)) ds_1 ds_2 =$

1. So what we are doing is integrating all the gray levels along the line  $[\rho - s_1 \cos(\theta) - s_2 \sin(\theta) = 0]$ .

So what we do in the discrete image is that as we can't have all  $\theta$  so we considered  $\theta$  from 0 to 179 and draw all the lines  $\theta = 0$  and all possible values of  $\rho$ . And we sum them all to get radon  $R(\rho, \theta)$  values.



Radon transform approximation:

$$y = Cx$$

$x$  is radon approximation.

$y$  input image.

$C$  weight.

$$(y_1, y_2, \dots, y_N) = C(x_1, x_2, \dots, x_N)$$

$J$  is Mean square error.

$$J = \| Y - CX \|^2$$

Below is the closed form solution.

$$C = Y(X^T X)^{-1} X^T, \text{ when } pq > N;$$

$$C = YX^T (XX^T)^{-1}, \text{ when } pq < N;$$

$$X = C^{-1}Y$$

$$J = \| Y - CX \|^2$$

$$X = (C^T C)^{-1} C^T Y, \text{ when } mm > pq;$$

$$X = C^T (CC^T)^{-1} Y, \text{ when } mm < pq.$$

$$X = (C^T C + \alpha I)^{-1} C^T Y, \text{ when } mm > pq;$$

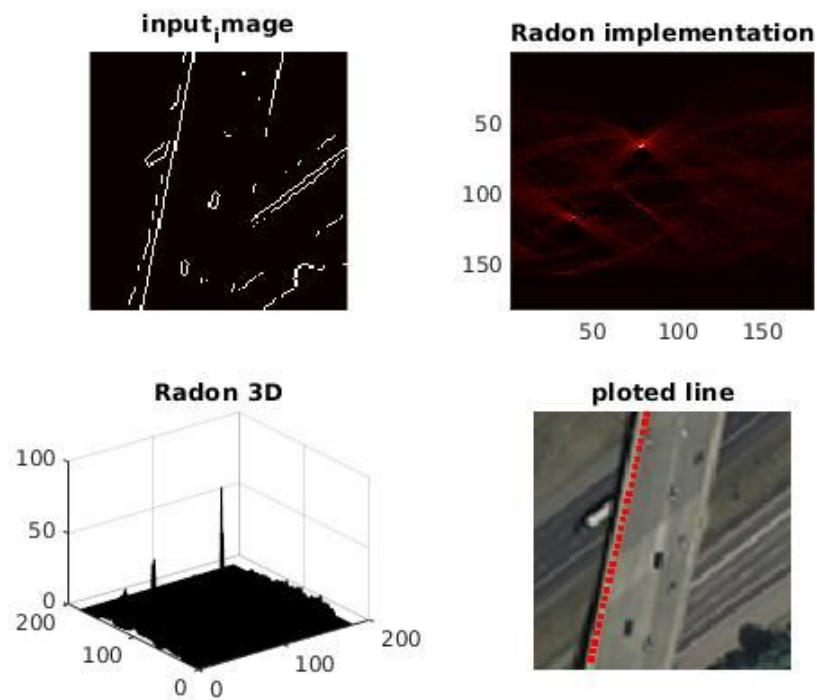
$$X = C^T (CC^T + \alpha I)^{-1} Y, \text{ when } mm < pq;$$

$$(x_1, x_2, \dots, x_N) = (C^T C + \alpha I)^{-1} C^T (y_1, y_2, \dots, y_N), \text{ when } mm > pq;$$

$$(x_1, x_2, \dots, x_N) = C^T (CC^T + \alpha I)^{-1} (y_1, y_2, \dots, y_N), \text{ when } mm < pq;$$

$$\hat{x} = \underset{x}{\operatorname{argmin}} \|y - Cx\|^2 + \alpha^2 \varphi(x)$$

## RADON TRANSFORM AND APPROXIMATION RESULT

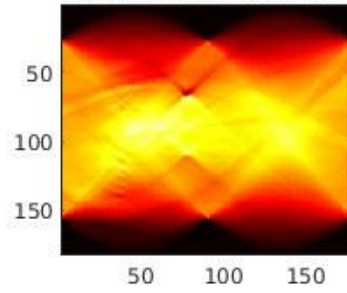


RADON TRANSFORM FOR EDGE IMAGE

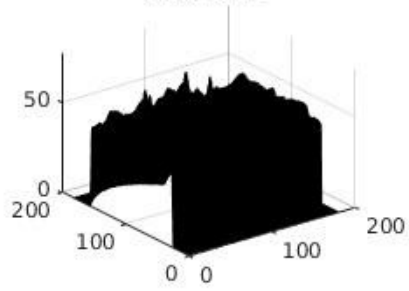
**input\_image**



**Radon implementation**



**Radon 3D**



**plotted line**

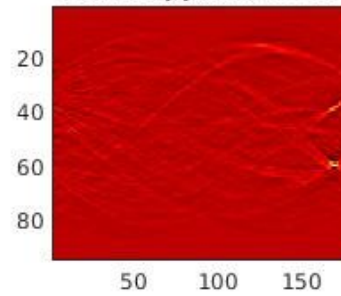


RADON TRANSFORM OF GRAY IMAGE

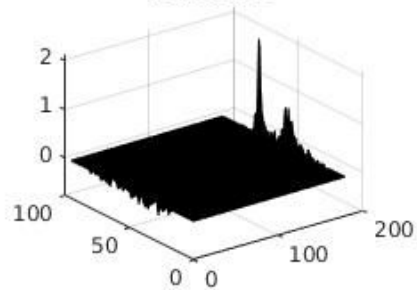
**input image**



**radon apporximation**



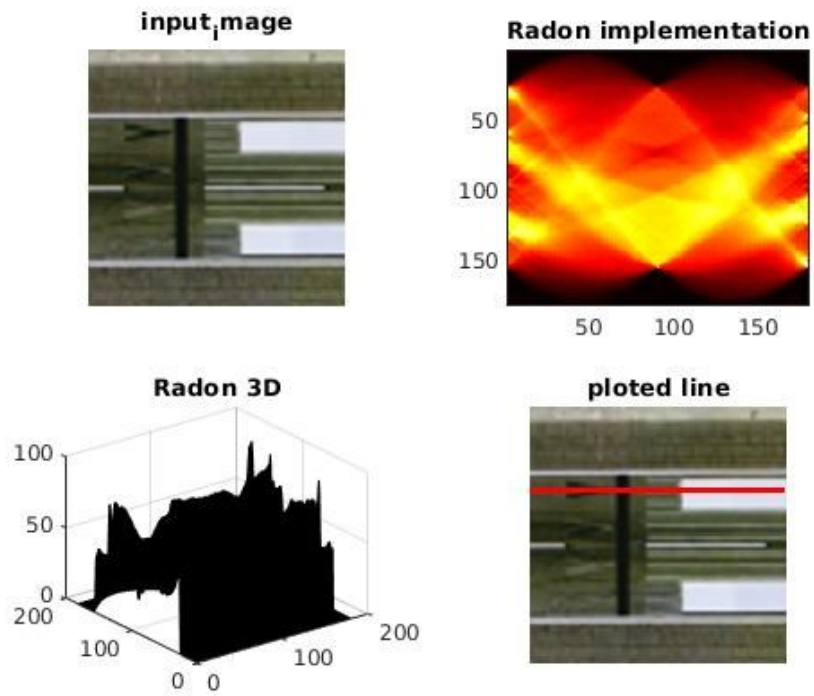
**radon 3 D**



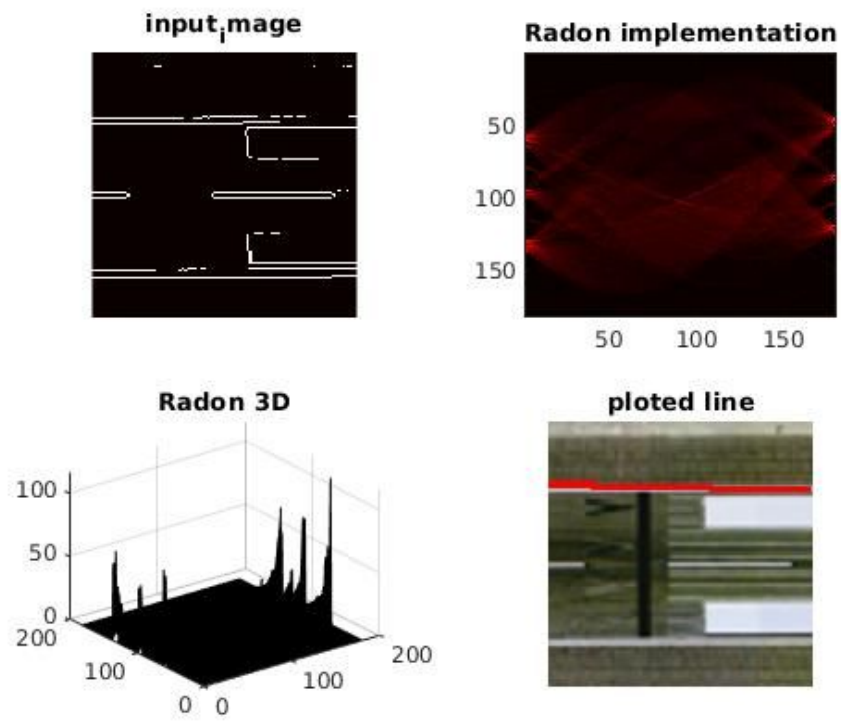
**ploted line**



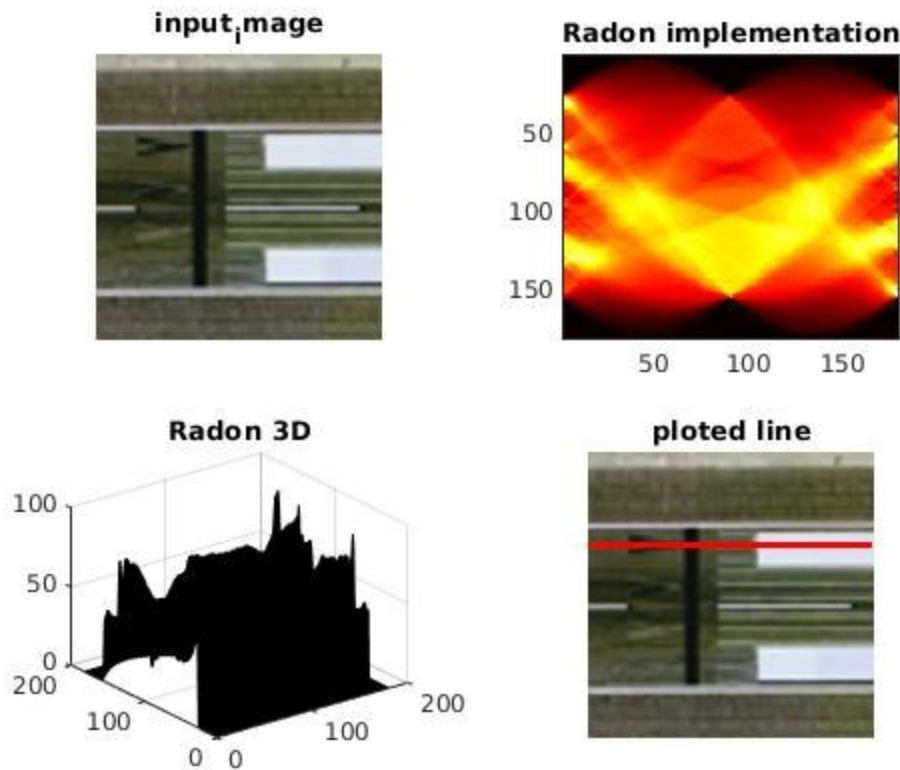
RADON APPROXIMATION RESULT



RADON TRANSFORM OF GRAY IMAGE



RADON TRANSFORM OF EDGE IMAGE



RADON APPROXIMATION RESULT

## CODE

RADON TRANSFORM:

Step 1 : read the image.

Step 2: convert to gray scale or edge detected image.

Step 3: rotate from 0 to 180 and those rotated image along the columns  
And join all those 180 columns to get radon transform.

Step 4: Sort all those values in the radon transform while preserving the  $\rho, \theta$  values.

Step 5: get Maximum value of  $\rho, \theta$  and draw the line on the image.

RADON APPROXIMATION:

Step 1: We used 1200 flatten edge images as training data and their radon transform as label.

Step 2: We applied closed loop MSE solution to get the weights coefficient.

Step 3: To get the radon approximation of images we multiply edge image to weight coefficients.