# DS-GA 3001.001/002 Probabilistic Time Series Analysis Lab 1: ACF, CCF, AR, MA

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#### **Logistics**

- Online Section: Colin Bredenberg, W 9:00-9:50am
  - Zoom meeting code: 983 3177 9428
- Blended Section In-Person: Ashwin Siripurapu, W 3:30-4:20pm
  - 60 FA, Room 150
- Blended Section Online: Jiyuan (Rupert) Lu, W 3:30-4:20pm
  - Zoom meeting code: 942 1755 0183

#### **Course Materials**

- Git repo: https://github.com/savinteachingorg/pTSAFall2020
- Piazza
  - Ask questions and get answers from course staff, other students
- NYU Classes
  - View recorded lectures and lab sections

Please turn in your completed lab1.ipynb notebook on NYU Classes before 09/22/2020 11:59 pm.

Your work will be evaluated based on the code and plots. You don't need to write down your answers to these questions in the text blocks.

#### python dependency

- Python >= 3.6
- Oumpy >= 1.13.3
- Pandas >= 0.20.3
- Statsmodels >= 0.8.0

#### basic models

White Noise

$$X_t \sim N(0, \sigma^2)$$

Moving Average

$$v_t = \frac{1}{3}(w_{t-1} + w_t + w_{t+1})$$

Autoregressive

$$x_t = x_{t-1} - .9x_{t-2} + w_t$$

## basic measures of dependency

autocovariance

$$\gamma_{\mathcal{X}}(s,t) = cov(x_s, x_t) = E[(x_s - \mu_s)(x_t - \mu_t)]$$

cross-covariance

$$\gamma_{xy}(s,t) = cov(x_s, y_t) = E[(x_s - \mu_x)(y_t - \mu_y)]$$

autocorrelation

$$\rho(s,t) = \frac{\gamma(s,t)}{\sqrt{\gamma(s,s)\gamma(t,t)}}$$

crosscorrelation

$$\rho_{xy}(s,t) = \frac{\gamma_{xy}(s,t)}{\sqrt{\gamma_x(s,s)\gamma_y(t,t)}}$$

## basic measures of dependency - empirical

autocovariance

$$\widehat{\gamma_x}(h) = \frac{1}{n} \sum_{t=1}^{n-h} (x_{t+h} - \bar{x})(x_t - \bar{x})$$

cross-covariance

$$\widehat{\gamma_{xy}}(h) = \frac{1}{n} \sum_{t=1}^{n-h} (x_{t+h} - \bar{x})(y_t - \bar{y})$$

autocorrelation

$$\hat{\rho}(h) = \frac{\hat{\gamma}(h)}{\hat{\gamma}(0)}$$

crosscorrelation

$$\hat{\rho}_{xy}(h) = \frac{\hat{\gamma}_{xy}(h)}{\sqrt{\hat{\gamma}_x(0)\hat{\gamma}_y(0)}}$$

## **ACF**

exercise of part I. autocorrelation function

- A) implement the ACF
- B) ACF of white noise

## ACF of moving average models

Given a Moving Average process  $x_t = w_{t-1} + 2w_t + w_{t+1}$ , where  $w_t$  are independent with zero means and variance  $\sigma_w^2$ , determine the autocorrelation function (ACF).

## ACF of moving average models

Given a Moving Average process  $x_t = w_{t-1} + 2w_t + w_{t+1}$ , where  $w_t$  are independent with zero means and variance  $\sigma_w^2$ , determine the autocorrelation function (ACF).

- First of all, we need to calculate the autovariance  $\gamma(t+h,t) = cov[(w_{t+h-1} + 2w_{t+h} + w_{t+h+1}), (w_{t-1} + 2w_t + w_{t+1})].$
- Note that because of the independent property of  $w_t$ ,  $cov(w_s, w_t) = \begin{cases} 0 & s \neq t \\ \sigma_w^2 & s = t \end{cases}$
- We can separate the cov of two sums into the sum of several bi-variate covariances

$$cov(aX + bY, cW + dV) = ac * cov(X, W) + ad * cov(X, V) + bc * cov(Y, W) + bd * cov(Y, V)$$

• When s = t, we have

$$\gamma(t,t) = cov[(w_{t-1} + 2w_t + w_{t+1}), (w_{t-1} + 2w_t + w_{t+1})]$$

$$= cov(w_{t-1}, w_{t-1}) + cov(2w_t, 2w_t) + cov(w_{t+1}, w_{t+1})$$

$$= \sigma_w^2 + 4\sigma_w^2 + \sigma_w^2$$

$$= 6\sigma_w^2$$

• When  $s = t \pm 1$ , we have

$$\gamma(t+1,t) = cov[(w_t + 2w_{t+1} + w_{t+2}), (w_{t-1} + 2w_t + w_{t+1})]$$

$$= cov(w_t, 2w_t) + cov(2w_{t+1}, w_{t+1})$$

$$= 2\sigma_w^2 + 2\sigma_w^2$$

$$= 4\sigma_w^2$$

• When  $s = t \pm 2$ , we have

$$\gamma(t+2,t) = cov[(w_{t+1} + 2w_{t+2} + w_{t+3}), (w_{t-1} + 2w_t + w_{t+1})]$$

$$= cov(w_{t+1}, w_{t+1})$$

$$= \sigma_w^2$$

• Therefore, our autocovariance is a function of lag h = s - t:

$$\gamma(h) = \begin{cases} 6\sigma_w^2 & h = 0\\ 4\sigma_w^2 & h = \pm 1\\ \sigma_w^2 & h = \pm 2 \end{cases}$$

• Using the definition of autocorrelation function (ACF), we have

$$\rho(h) = \frac{\gamma_x(h)}{\gamma_x(0)} = \begin{cases} 1 & h = 0\\ \frac{2}{3} & h = \pm 1\\ \frac{1}{6} & h = \pm 2 \end{cases}$$

## ACF of moving average models

exercise of part I. autocorrelation function

C) ACF of moving average

# ACF of signal in noise

exercise of part I. autocorrelation function

D) ACF of signal in noise

#### **CCF**

Suppose that series  $y_t$  is linearly determined by series  $x_t$  with a lag l:  $y_t = Ax_{t-l} + w_t$ . How can we determine the value of l?

### **CCF**

 $\rho_{xy}(h)$  gives us the dependency of the two series on each other with different time lags h

 $\rho_{\chi\gamma}(h)$  will reach its maximum when h=l

→ we can determine the lag l from the max/min of the CCF plot

## CCF of signal in noise

exercise of part II. crosscorrelation function

- A) CCF of signal with noise
- B) CCF of data

current value is a linear function of past values

**Definition 3.1** An autoregressive model of order p, abbreviated AR(p), is of the form

$$x_t = \phi_1 x_{t-1} + \phi_2 x_{t-2} + \dots + \phi_p x_{t-p} + w_t, \tag{3.1}$$

where  $x_t$  is stationary,  $w_t \sim wn(0, \sigma_w^2)$ , and  $\phi_1, \phi_2, \ldots, \phi_p$  are constants  $(\phi_p \neq 0)$ .

ACF of an AR(1) is

$$\rho(h) = \frac{\gamma(h)}{\gamma(0)} = \phi^h$$

ACF of an AR(2)?

ACF of an AR(2)?

Suppose  $x_t = \phi_1 x_{t-1} + \phi_2 x_{t-2} + w_t$  is a causal AR(2) process. Multiply each side of the model by  $x_{t-h}$  for h > 0, and take expectation:

$$E(x_t x_{t-h}) = \phi_1 E(x_{t-1} x_{t-h}) + \phi_2 E(x_{t-2} x_{t-h}) + E(w_t x_{t-h}).$$

The result is

$$\gamma(h) = \phi_1 \gamma(h-1) + \phi_2 \gamma(h-2), \quad h = 1, 2, \dots$$
 (3.38)

In (3.38), we used the fact that  $E(x_t) = 0$  and for h > 0,

$$E(w_t x_{t-h}) = E\left(w_t \sum_{j=0}^{\infty} \psi_j w_{t-h-j}\right) = 0.$$

Divide (3.38) through by  $\gamma(0)$  to obtain the difference equation for the ACF of the process:

$$\rho(h) - \phi_1 \rho(h-1) - \phi_2 \rho(h-2) = 0, \quad h = 1, 2, \dots$$
 (3.39)

now compute  $\rho(1)$  and  $\rho(2)$ 

exercise of part III. AR

- determine p given ACF and PCF
- fit AR(p)
- use p datapoints to predict tsteps into the future
- plot ACF and PCF of AR(p) model
- relate AR(p) parameters to ACF of data for lag 0 to p

## moving average models

filered white noise

average over previous and following value

$$v_t = \frac{1}{3}(w_{t-1} + w_t + w_{t+1})$$

## moving average models

exercise of part IV. moving average

look at two processes and try to predict whether they are the same or not then look at ACFs

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