

#### Politecnico di Milano





#### **Home Challenge #4**

Simulate a Wireless Sensor Network with TOSSIM

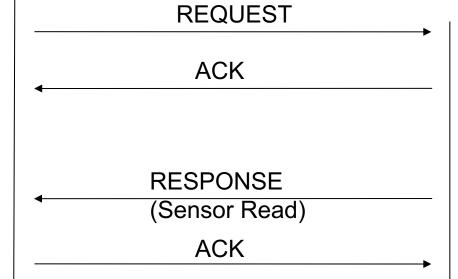


# Send/ACK example





REQUEST	V
REQUEST	
REQUEST	
	<b>X</b>



MOTE #2 BOOT





#### What to do



- Simulate 2 motes talking between each others
- Mote #1 sends periodic request (REQ) messages to mote #2 containing:
  - Message type: REQ
  - An incremental counter
- The request has periodicity 1000ms



### What to do



- Only on receipt of a request, mote #2 sends back a reply (RESP) message with:
  - Message type: RESP
  - The counter sent by mote #1
  - A value read from the fake sensor
- Fake sensor is just a module which return a random number, you don't need to modify it



#### What to do



- Each message, REQ and RESP, must be acknowledged using the <u>TinyOS</u> <u>built in ACK module</u>
- Upon receipt of the ACK of the a REQ message:
  - Mote #1 stops to send requests
  - The exercise is done!
- Use the module PacketAcknowledgements to send the ACK, don't reimplement it!

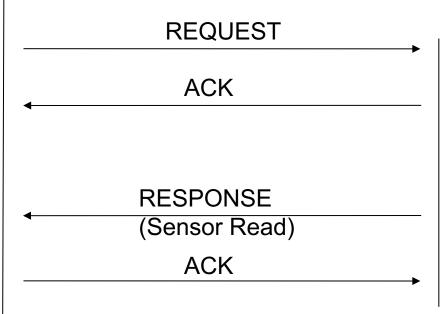


# Send/ACK example



Y	REQUEST	
V	REQUEST	
	REQUEST	
X		





MOTE #2 BOOT (at time 5)



DONE!



## PacketAcknowledgements



- Read the documentation
- Available at /home/user/Desktop/tinyosmain/doc/nesdoc/telosb/index.html

#### **Commands**

command error\_t <u>noAck(message\_t \*msg)</u>

Tell a protocol that when it sends this packet, it should not use synchronous acknowledgments.

command error\_t <u>requestAck</u>(message\_t \*msg)

Tell a protocol that when it sends this packet, it should use synchronous acknowledgments.

command bool <u>wasAcked</u>(message\_t \*msg)

Tell a caller whether or not a transmitted packet was acknowledged.



# **Template**



- In the folder SendACK\_template there's a draft of the code to fill in
- Try to use as much as possible that draft
- Files to modify:
  - SendAck.h
  - SendAckAppC.nc
  - SendAckC.nc

```
//******************* AMSend interface ***************//
event void AMSend.sendDone(message_t* buf,error_t err) {
    /* This event is triggered when a message is sent... */
    /*
    * STEPS:
    * 1. Check if the packet is sent
    * 2. Check if ack is received (Read the docs!)
    * 2a. If yes stop the timer, the program is done
    * 2b. Otherwise: send again a request
    * Always: use debug statements
    */
}
```



#### Simulation



#### Simulate it with TOSSIM

- Mote #1 at time 0
- Mote #2 after 5 seconds



# Message structure



- Only one message type containing:
  - msg\_type: REQ/RESP
  - msg\_counter: incremental integer
  - value: value from the fake sensor





- 1) Create the message structure
- 2) Choose which modules you'll use
- 3) Write the modules in the ...AppC.n and in the ...C.nc files
- 4) Wire the modules in the ...AppC.nc file
- 5) Implement the logic in the ...C.nc file





- Run the code often to check syntax or compiler errors, not only at the end!
- Use a lot of debug statements (DBG/DBG\_CLEAR)
- Read the docs
- Use the examples seen before as scheme
- Think!



#### **Commands**



- Compile the mote's code
  - make micaz sim
- Run the simulation
  - python RunSimulationScript.py
- Before run a simulation, recompile the code of the mote if you have modified it