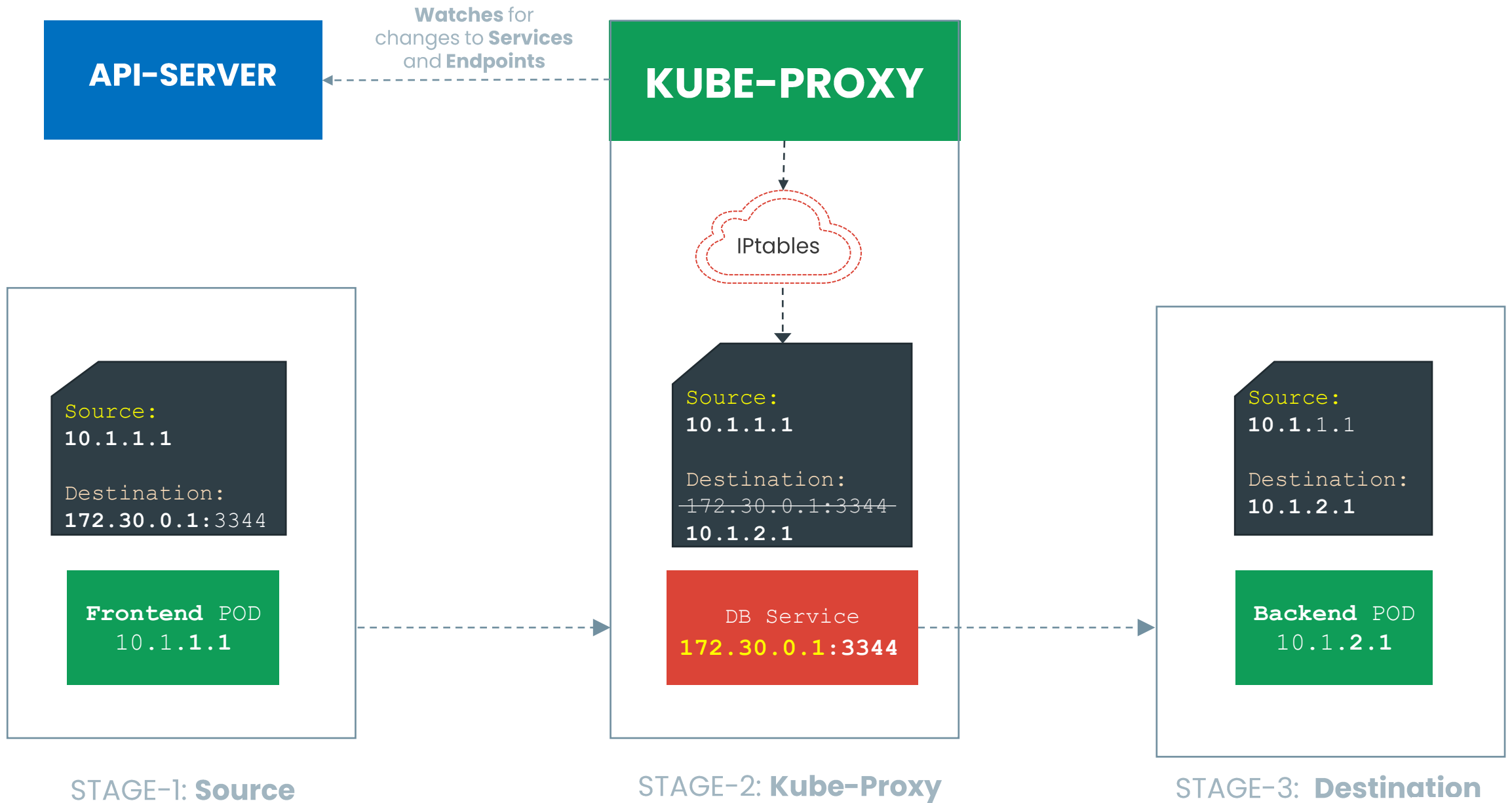




# Pod-to-Service Communication





## COMMUNICATION BETWEEN PODS ON **ACROSS NODES**

