CIS 4930.006S20/CIS 6930.013S20: Computational Methods for Imaging and Vision

Spring 2021 Homework #1

The University of South Florida

Department of Computer Science and Engineering

Tampa, FL

Assigned: January 27, 2021 **Due:** February 8, 2021

1 Gaussian Elimination

Our aim is to solve the system of linear equations Ax = y. (General conditions for the existence of a solution are given in **FSP Appendix 2.B.1.**) Comment on whether a solution to each of the following systems of equations exists, and, if it does, find it. (a)

$$\mathbf{A} = \begin{bmatrix} 1 & 0 & 3 \\ 4 & 5 & 2 \\ -1 & -1 & 2 \end{bmatrix}, \quad \mathbf{y} = \begin{bmatrix} 10 \\ 20 \\ 3 \end{bmatrix}.$$

(b)
$$\mathbf{A} = \begin{bmatrix} 1 & 0 & 2 \\ 4 & 5 & 8 \\ -1 & -1 & -2 \end{bmatrix}, \quad \mathbf{y} = \begin{bmatrix} 7 \\ 38 \\ -9 \end{bmatrix}.$$

(c)
$$\mathbf{A} = \begin{bmatrix} 1 & 0 & 2 \\ 4 & 5 & 8 \\ -1 & -1 & -2 \end{bmatrix}, \quad \mathbf{y} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}.$$

2 Eigenvalues and Eigenvectors (Linear algebra refresher)

Let

$$\mathbf{A} = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$$
 and $\mathbf{B} = \begin{bmatrix} \alpha & \beta \\ \beta & \alpha \end{bmatrix}$.

- (a) Find the eigenvalues and unit-norm eigenvectors of **A**. Are the eigenvectors orthogonal? Check your answer with a using Matlab.
- (b) Compute the determinant of A, i.e. det A. Is A invertible? If it is, give its inverse; if not, say why.
- (c) Find eigenvalues and unit-norm eigenvectors of **B**. For $\alpha \in \{0,1,2,3\}$ and $\beta \in [-3,3]$, plot the eigenvalues of **B** (using Matlab). (This will be four pairs of curves that are functions of one variable.)
- (d) Compute the determinant of **B**. When is **B** invertible? For $(\alpha, \beta) \in [0, 5]^2$, plot det **B** (with a computer, using Matlab). (This will be a surface plot of a function of two variables.)

3 Multiplication by an orthogonal matrix

Consider the vector space \mathbb{R}^n with standard norm and standard inner product. Prove that (a) multiplication by an orthogonal matrix U preserves lengths, that is,

$$\|\mathbf{U}\mathbf{x}\| = \|\mathbf{x}\|,$$

for any x.

(b) multiplication by an orthogonal matrix U preserves angles, that is,

$$\langle \mathbf{U}\mathbf{x}, \mathbf{U}\mathbf{y} \rangle = \langle \mathbf{x}, \mathbf{y} \rangle,$$

for any x and y.

4 Bases and frames of \mathbb{R}^2

Given the following sets of vectors:

$$\Phi_1 = \{\varphi_{1,0}, \, \varphi_{1,1}\} = \left\{ \begin{bmatrix} \frac{1}{2} \\ \frac{\sqrt{3}}{2} \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\} \tag{1}$$

$$\Phi_2 = \{\varphi_{2,0}, \, \varphi_{2,1}, \, \varphi_{2,2}, \, \varphi_{2,3}\} = \left\{ \begin{bmatrix} \frac{1}{2\sqrt{2}} \\ \frac{\sqrt{3}}{2\sqrt{2}} \end{bmatrix}, \begin{bmatrix} -\frac{\sqrt{3}}{2\sqrt{2}} \\ \frac{1}{2\sqrt{2}} \end{bmatrix}, \begin{bmatrix} \frac{1}{\sqrt{2}} \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ \frac{1}{\sqrt{2}} \end{bmatrix} \right\}$$
(2)

$$\Phi_3 = \{\varphi_{3,0}, \varphi_{3,1}\} = \left\{ \begin{bmatrix} \frac{1}{2} \\ \frac{\sqrt{3}}{2} \end{bmatrix}, \begin{bmatrix} -\frac{\sqrt{3}}{2} \\ \frac{1}{2} \end{bmatrix} \right\}$$
(3)

$$\Phi_4 = \{\varphi_{4,0}, \varphi_{4,1}, \varphi_{4,2}\} = \left\{ \begin{bmatrix} 1\\0 \end{bmatrix}, \begin{bmatrix} \frac{1}{\sqrt{2}}\\\frac{1}{\sqrt{2}} \end{bmatrix}, \begin{bmatrix} 0\\1 \end{bmatrix} \right\} \tag{4}$$

For each of the sets of vectors, Φ_1 and Φ_3 , do the following:

- (a) Write the matrix representation for the set, that is, the synthesis operator associated with the set.
- (b) Find the dual basis. Sketch (in other words, draw the arrows that represent each vector of) the original sets and their duals.
- (c) Specify whether it is an orthonormal basis.
- (d) For $\mathbf{x} = [2, 0]^T$, write down the projection coefficients, $\alpha_{i,k} = \langle x, \widetilde{\varphi}_{i,k} \rangle$.
- (e) For the same **x**, verify the expansion formula $\Phi \widetilde{\Phi}^T = \mathbf{I}$.
- (f) Specify whether the expansion preserves the norm, that is, whether it is true that $\|\mathbf{x}\| = \sum_{k} |\alpha_{i,k}|^2$.

For each of the sets of vectors, Φ_2 and Φ_4 , write the matrix representation for the set, that is, the synthesis operator associated with the set.

5 Inner product

True or False, two vectors, say f(t) and g(t), are **orthogonal** if their inner product is zero. Using your response to the above prove that $f(t) = \sin(\pi nt)$ and $g(t) = \sin(\pi mt)$ are orthogonal in the Hilbert space $\mathcal{L}^2[-1, +1]$, for any integers $n \neq m$ (i.e., when $n, m \in \mathbb{Z}$ and $n \neq m$).

6 Inner product computation by expansion sequences

Let α and β be sequences in $\ell^2(\mathbb{N})$. Then, the functions

$$f(t) = \alpha_0 + \sum_{k=1}^{\infty} \alpha_k \sqrt{2} \cos(2\pi kt),$$

$$g(t) = \beta_0 + \sum_{k=1}^{\infty} \beta_k \sqrt{2} \cos(2\pi kt),$$

are in $\mathcal{L}^2\left(\left[-\frac{1}{2},+\frac{1}{2}\right]\right)$. Demonstrate that the standard inner product between the functions, f(t) and g(t) can be written as the standard inner product between the sequences α and β . That is, show that $\langle f(t),g(t)\rangle=\langle \alpha,\beta\rangle$.

Given the above results, write down (or derive, if you want) the norms of f(t) and g(t), i.e. write down ||f(t)|| and ||g(t)||.

7 Linear Independence (Optional, for extra credit.)

Find the values of the parameter $a \in \mathbb{C}$ such that the following set is linearly independent:

$$U = \left\{ \begin{bmatrix} 0 & a^2 \\ 0 & \mathbf{j} \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 1 & a - 1 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ \mathbf{j}a & 1 \end{bmatrix} \right\}.$$

For a = j, express the matrix

$$\begin{bmatrix} 0 & 5 \\ 2 & j-2 \end{bmatrix}$$

as a linear combination of the elements of U. [Note that j denotes the imaginary unit, i.e. $j = \sqrt{-1}$, so that $cj \times dj = c \times d \times j^2 = c \times d \times -1 = -cd$.]

8 Vector space \mathbb{C}^n (Optional, for extra credit.)

Prove that \mathbb{C}^n is a vector space. Note: the symbol \mathbb{C} means we are dealing with complex numbers. Thus, a vector $\mathbf{x} \in \mathbb{C}^n$ means that \mathbf{x} is a vector with n entries and each of its entry is a complex number.