NYCU
Deep Learning Lab-1
Back Propagation

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Github : Lab1-BackPropagation

Content

Introduction

在本次作業中，實作了一個簡單的深度神經網路，並完成了 Forward Propagation 與 Back Propagation 的流程，以模擬模型的訓練過程。除此之外，也額外加入了多種 Activation Function 與 Optimizer，以觀察它們對模型訓練效果的影響與優化效果。

為了驗證模型的表現與泛化能力，訓練資料分別使用助教提供的 Linear Dataset 以及 XOR Dataset。本作業的主要目的是深入理解 Back Propagation 的運作原理與細節，並透過嘗試調整模型結構、參數以及 Hyperparameters（如 Learning rate、Activation Functions 與 Optimizer ）來優化訓練過程。

此外，透過實際實作與實驗，我們能更直觀地掌握深度學習中梯度下降的概念，並進一步了解不同設計選擇對於收斂速度與最終準確率的影響，為未來更複雜模型的開發打下基礎。

Implement Detail

Network Architecture

- Hidden Layer 程式碼：（Backward Pass 參考 Back Propagation 的程式碼）
  - Initialization：

```
# Fully connected layer class
class Linear_Layer:


    def __init__( self,input_size,output_size,activation="sigmoid",optimizer="SGD",momentum=0.9, ):

        self.input_size = input_size
        self.output_size = output_size
        # Initialize weights and bias (W , b)
        # Assume that the size of input vector is  n by 1
        # The size of weight matrix should be m by n, where m is the size of output vector


        self.weights = np.random.randn(input_size, output_size)

        self.bias = np.random.randn(1, output_size)

        self.input = None
        self.z = None  # The output of the layer before activation function is applied (z = Wx + b)
        self.a = None  # The output of the layer after activation function is applied (a = activation_function(z))

        self.activation = activation
        self.optimizer = optimizer  # optimizer for gradient descent
        self.momentum = momentum  # Momentum for optimizer
        self.v_weight = 0  # Velocity of weight for momentum optimizer
        self.v_bias = 0  # Velocity of bias for momentum optimizer
        self.total_grad_w = 0  # Total gradient of weight for Adagrad optimizer
        self.total_grad_b = 0  # Total gradient of bias for Adagrad optimizer
        self.epsilon = 1e-8  # smoothed value for adagrad optimizer in case of zero value of denominator
```

  - Forward ：

```
#   Forward pass: z = xW + b
def forward(self, x):
    self.input = x
    self.z = np.dot(x, self.weights) + self.bias

    if not self.activation:
        self.a = self.z
    else:
        self.a = activation_map[self.activation](self.z)

    return self.a
```

- Model 程式碼:
  - 使用 losses 儲存訓練過程的所有 loss value
  - 使用 layers 紀錄 model 的 Layer 架構
  - Initialization

```
class Model:

    def __init__(
        self,
        input_size=2,
        output_size=1,
        hidden_layers_size=10,
        activation="sigmoid",
        optimizer="SGD",
        learning_rate=0.01,
    ):
        self.activation = activation
        self.losses = []
        self.layers = []
        self.learning_rate = learning_rate
        # Build model
        self.layers.append(
            Linear_Layer(input_size, hidden_layers_size, activation,
                         optimizer))
        self.layers.append(
            Linear_Layer(hidden_layers_size, hidden_layers_size, activation,
                         optimizer))
        self.layers.append(
            Linear_Layer(hidden_layers_size, output_size, activation,
                         optimizer))
```

  - Forward ：

```
def forward(self, x):
    # Forward pass through all layers
    for layer in self.layers:
        x = layer.forward(x)

    return x
```

  - Backward ：

```
def backward(self, delta, learning_rate=0.01):
    # Backward pass
    for layer in reversed(self.layers):
        delta = layer.backward(delta, self.learning_rate)
```

Activation Functions

- 提供 Sigmoid、ReLU、Tanh 三種 Activation Functions 選擇
- 同時實作各 Activation functions 的微分以利之後計算梯度使用

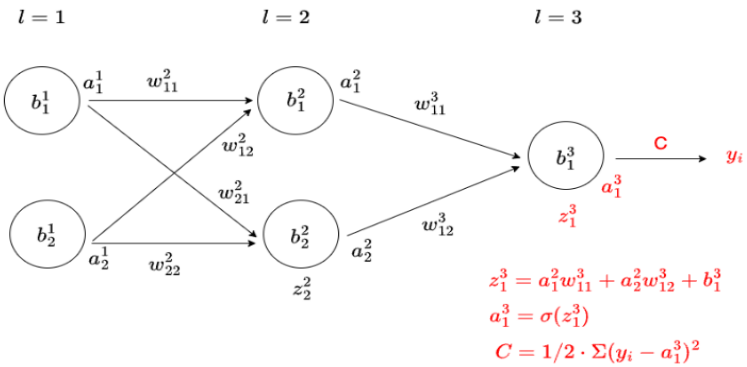
```python
# Activative functions and their derivatives
def sigmoid(x):
    return 1.0 / (1.0 + np.exp(-x))


def derivative_sigmoid(x):
    return np.multiply(x, 1.0 - x)


def relu(x):
    return np.maximum(0, x)


def derivative_relu(x):
    return np.where(x >= 0, 1, 0)


def tanh(x):
    return np.tanh(x)


def derivative_tanh(x):
    return 1.0 - np.square(np.tanh(x))
```

Backpropagation

- Loss Function 採用 MSE（Mean Squared Error）
- 計算各層梯度
- 根據梯度更新 Weights 與 Bias

符號定義

- C： ：Loss Function ，此模型中使用 Mean Square Error（MSE）
- σ ：Activation Function
- b^l ：第l 層的 bias
- w^l ：第l層的 weight
- z^l ：從第 $l-1$ 層 到第l層經由 weight 和 bias 運算後得到的結果
- a^l ：$\sigma(z^l)$ （圖片來源: [1]）
- δ^l ：$\frac{\partial C}{\partial z^l}$



對於每一層 Layer，我們需要去計算其δ 值。假設我們已知δ^l，我們可以藉由此值推導出 δ^{l-1}，根據連鎖律(Chain Rule)，$\delta^{l-1} = \frac{\partial C}{\partial z^{l-1}} = \frac{\partial C}{\partial z^l} \times \frac{\partial z^l}{\partial a^{l-1}} \times \frac{\partial a^{l-1}}{\partial z^{l-1}}$。

$\frac{\partial C}{\partial z^l}$ 即為 δ^l，為我們已知

$\frac{\partial z^l}{\partial a^{l-1}}$根據觀察可得知為$w^l$

$\frac{\partial a^{l-1}}{\partial z^{l-1}}$即為 $\sigma'(z^{l-1})$，σ'為 Activation function 之微分

下方圖片中的$delta$ 就是參照以上推導而計算出，知道δ 值後即可得知所有 weight 和 bias 的梯度，如下方證明，可知 bias 的梯度即為δ^l，weight 的梯度為$\delta^l \times a^l$。

$$\frac{\partial C}{\partial b^l} = \frac{\partial C}{\partial a^l} \times \frac{\partial a^l}{\partial z^l} \times \frac{\partial z^l}{\partial b^l} = \delta^l$$

$$\frac{\partial C}{\partial w^l} = \frac{\partial C}{\partial a^l} \times \frac{\partial a^l}{\partial z^l} \times \frac{\partial z^l}{\partial w^l} = \delta^l \times a^l$$

也就是下方程式碼 dW 和 db 的計算方式，該程式碼為 Linear_Layer 類別的 backward 實作

```
def backward(self, upstream_delta, learning_rate=0.01):
    # check whether the activation function is empty
    if not self.activation:
        delta = upstream_delta
        # If no activation function, delta is just upstream_delta
    else:
        delta = upstream_delta * derivative_activation_map[self.activation](self.a)

    # Calculate gradients of weights and bias
    dW = np.dot(self.input.T, delta)
    db = np.sum(delta)

    # Update weights and bias
    if self.optimizer == "SGD":
        self.weights -= dW * learning_rate
        self.bias -= db * learning_rate
    elif self.optimizer == "Adagrad":
        # For the purpose of best training, learning rate should be adjusted according to the gradients
        # If gradients are small, learning rate should be larger, vice versa
        self.total_grad_w += np.square(dW)
        self.total_grad_b += np.square(db)
        self.weights -= (
            dW * learning_rate / np.sqrt(self.total_grad_w + self.epsilon)
        )
        self.bias -= db * learning_rate / np.sqrt(self.total_grad_b + self.epsilon)
    elif self.optimizer == "Momentum":
        self.v_weight = self.momentum * self.v_weight + dW * learning_rate
        self.v_bias = self.momentum * self.v_bias + db * learning_rate
        self.weights -= self.v_weight
        self.bias -= self.v_bias

    return np.dot(delta, self.weights.T)  # Return delta for the previous layer
```

並在 Model 中對每一層 Layer 呼叫 backward function 實現 Back propagation

```
def backward(self, delta, learning_rate=0.01):
    # Backward pass
    for layer in reversed(self.layers):
        delta = layer.backward(delta, self.learning_rate)
```

Extra Implementation

- 支援多種 Optimizer，包括 SGD、Momentum、AdaGrad

  Optimizer 的實作可參考上方圖片

  - **SGD**：直接使用 Learning Rate 乘上梯度來更新 Weights

  - **Momentum**：透過累積梯度的速度向量（v_weight, v_bias），幫助模型跳脫 Local Mimimum 並讓收斂路徑更平滑。

    $$V_t \leftarrow \beta V_{t-1} - \eta \frac{\partial L}{\partial W}$$

    $$W \leftarrow W + V_t$$

    （圖片來源:[2]）

  - **Adagrad**：根據以往累積的梯度平方和來動態調整 Learning Rate。當某些參數需要較大或較小的更新時特別有幫助。

    $$W \leftarrow W - \eta \frac{1}{\sqrt{n+\epsilon}} \frac{\partial L}{\partial W}$$

    $$n = \sum_{r=1}^{t} (\frac{\partial L_r}{\partial W_r})^2$$

    $$W \leftarrow W - \eta \frac{1}{\sqrt{\sum_{r=1}^{t} (\frac{\partial L_r}{\partial W_r})^2 + \epsilon}} \frac{\partial L}{\partial W}$$

    （圖片來源:[2]）

- 可調整參數如 Learning Rate、Hidden Layer 點數、Activation Functions 類型等
- 加入 Early stop 以保留最佳模型參數以及預測結果

```python
if len(self.losses) > 0 and loss >= self.losses[-1]:
    # If the prediction of current model is worse than before
    cnt += 1
    # Skip the weight updating progress , keep the better weight of the model
    continue
else:
    # Reset the counting of early stop
    cnt = 0
    # Keep the best prediction
    output = cur_output
```

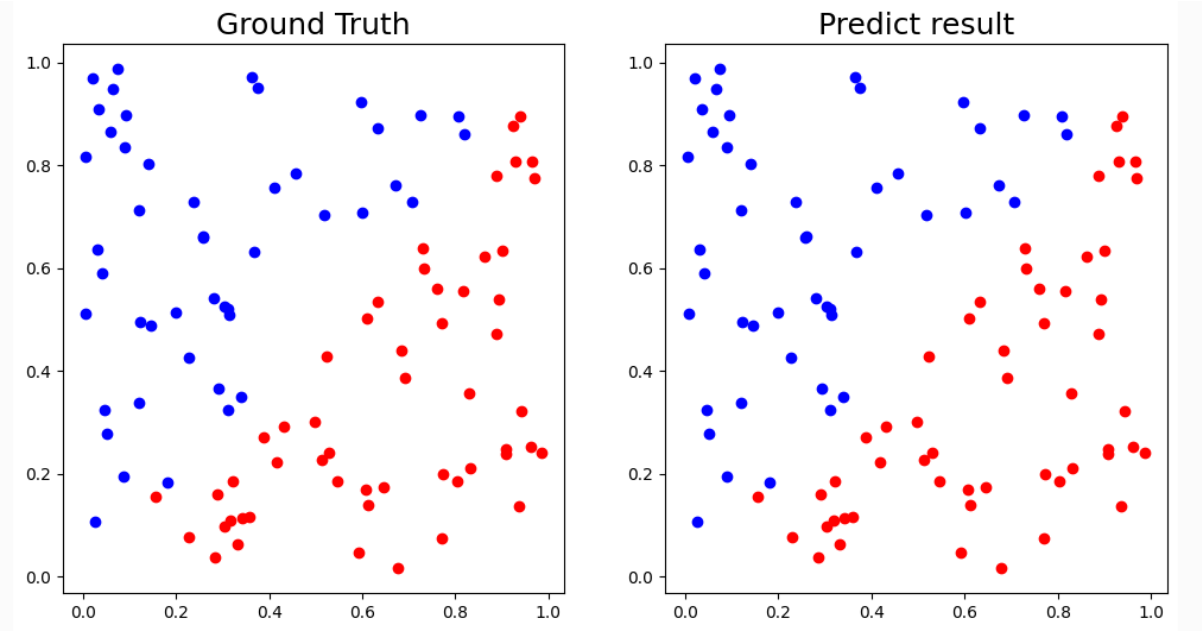
Experimental Results

Screenshot and comparison figure

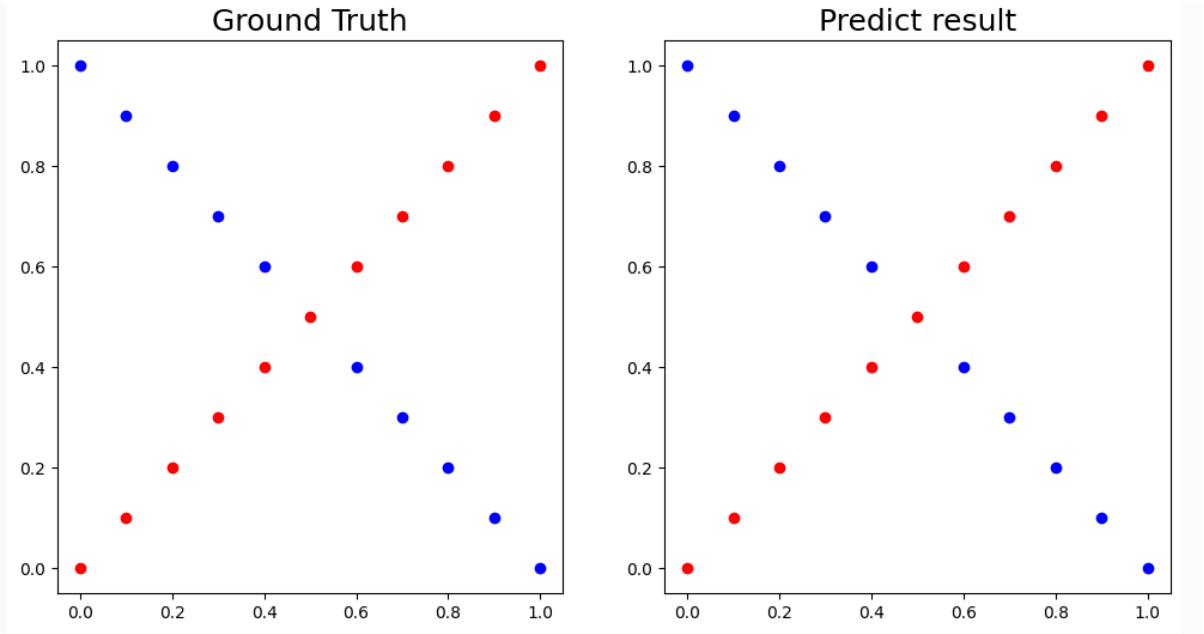
Hyperparameters

Activation Function	Optimizer	Learning Rate	Hidden_Units	Epochs
sigmoid	Adagrad	0.01	10	200000

Linear



XOR



Show the accuracy of your prediction

Hyperparameters

Activation Function	Optimizer	Learning Rate	Hidden_Units	Epochs
sigmoid	Adagrad	0.01	10	200000

Linear Dataset

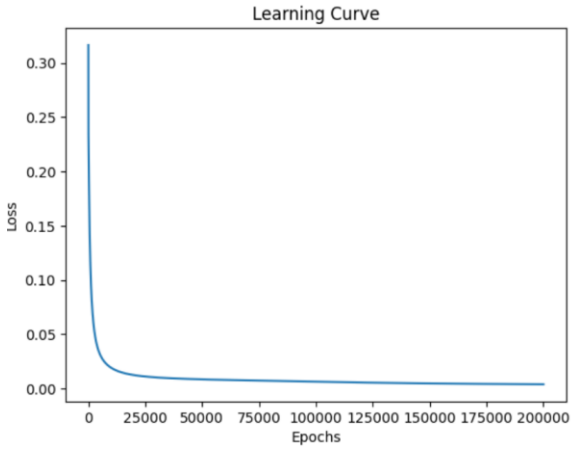
```
Iter86 |       Ground Truth: [0] |      Predict: [1.02858064e-05] |
Iter87 |       Ground Truth: [0] |      Predict: [4.19457328e-05] |
Iter88 |       Ground Truth: [0] |      Predict: [1.32200751e-05] |
Iter89 |       Ground Truth: [0] |      Predict: [4.64427017e-05] |
Iter90 |       Ground Truth: [0] |      Predict: [1.01875439e-05] |
Iter91 |       Ground Truth: [0] |      Predict: [6.59757665e-05] |
Iter92 |       Ground Truth: [0] |      Predict: [0.06922087] |
Iter93 |       Ground Truth: [1] |      Predict: [0.99999807] |
Iter94 |       Ground Truth: [0] |      Predict: [9.51350791e-05] |
Iter95 |       Ground Truth: [0] |      Predict: [4.25082399e-05] |
Iter96 |       Ground Truth: [1] |      Predict: [0.9999989] |
Iter97 |       Ground Truth: [0] |      Predict: [8.24585126e-05] |
Iter98 |       Ground Truth: [1] |      Predict: [0.93402683] |
Iter99 |       Ground Truth: [1] |      Predict: [0.99991112] |
Iter100 |       Ground Truth: [0] |      Predict: [0.00603146] |
Loss = 0.0040 Accuracy = 100.00%
```

XOR Dataset

```
Iter10 |        Ground Truth: [1] |      Predict: [0.95607026] |
Iter11 |        Ground Truth: [0] |      Predict: [0.05239608] |
Iter12 |        Ground Truth: [0] |      Predict: [0.02101065] |
Iter13 |        Ground Truth: [1] |      Predict: [0.9510509] |
Iter14 |        Ground Truth: [0] |      Predict: [0.00976467] |
Iter15 |        Ground Truth: [1] |      Predict: [0.99983074] |
Iter16 |        Ground Truth: [0] |      Predict: [0.0060062] |
Iter17 |        Ground Truth: [1] |      Predict: [0.99996463] |
Iter18 |        Ground Truth: [0] |      Predict: [0.00414463] |
Iter19 |        Ground Truth: [1] |      Predict: [0.99997695] |
Iter20 |        Ground Truth: [0] |      Predict: [0.00305483] |
Iter21 |        Ground Truth: [1] |      Predict: [0.99997975] |
Loss = 0.0004 Accuracy = 100.00%
```

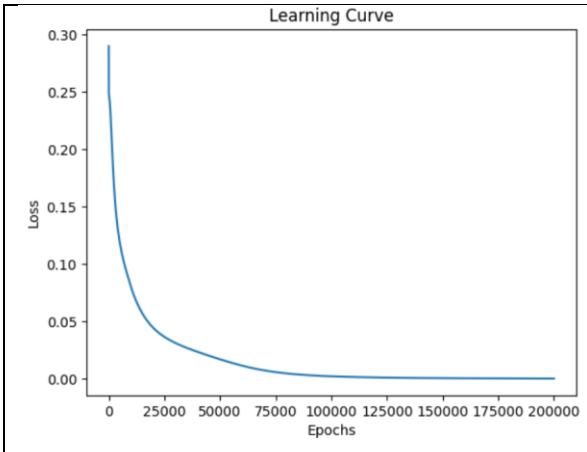
Learning curve (loss-epoch curve)

Linear




```
Epoch 1000, Loss: 0.1064
Epoch 2000, Loss: 0.0658
Epoch 3000, Loss: 0.0480
Epoch 4000, Loss: 0.0383
Epoch 5000, Loss: 0.0322
Epoch 6000, Loss: 0.0280
Epoch 7000, Loss: 0.0249
Epoch 8000, Loss: 0.0226
Epoch 9000, Loss: 0.0208
Epoch 10000, Loss: 0.0193
Epoch 11000, Loss: 0.0181
Epoch 12000, Loss: 0.0170
Epoch 13000, Loss: 0.0162
Epoch 14000, Loss: 0.0154
Epoch 15000, Loss: 0.0148
Epoch 16000, Loss: 0.0142
Epoch 17000, Loss: 0.0137
Epoch 18000, Loss: 0.0133
Epoch 19000, Loss: 0.0129
Epoch 20000, Loss: 0.0125
Epoch 21000, Loss: 0.0122
```

XOR




```
Epoch 1000, Loss: 0.2225
Epoch 2000, Loss: 0.1807
Epoch 3000, Loss: 0.1510
Epoch 4000, Loss: 0.1318
Epoch 5000, Loss: 0.1186
Epoch 6000, Loss: 0.1084
Epoch 7000, Loss: 0.1002
Epoch 8000, Loss: 0.0932
Epoch 9000, Loss: 0.0866
Epoch 10000, Loss: 0.0800
Epoch 11000, Loss: 0.0744
Epoch 12000, Loss: 0.0694
Epoch 13000, Loss: 0.0650
Epoch 14000, Loss: 0.0610
Epoch 15000, Loss: 0.0575
Epoch 16000, Loss: 0.0543
Epoch 17000, Loss: 0.0514
Epoch 18000, Loss: 0.0489
Epoch 19000, Loss: 0.0466
Epoch 20000, Loss: 0.0445
```

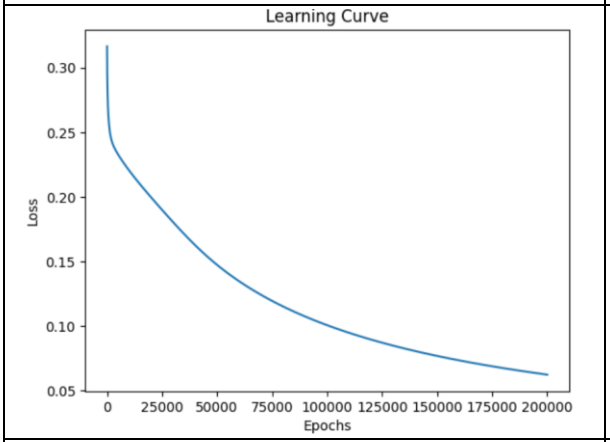
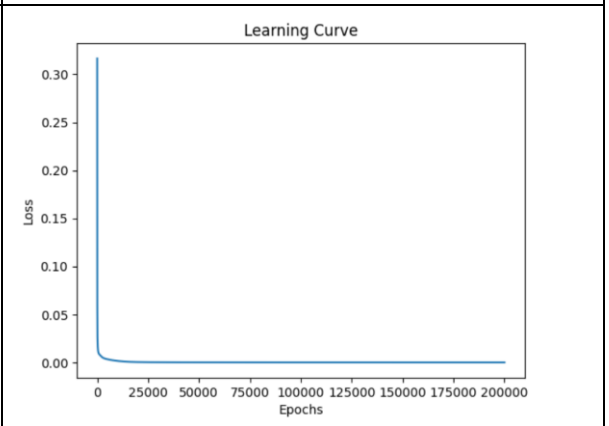
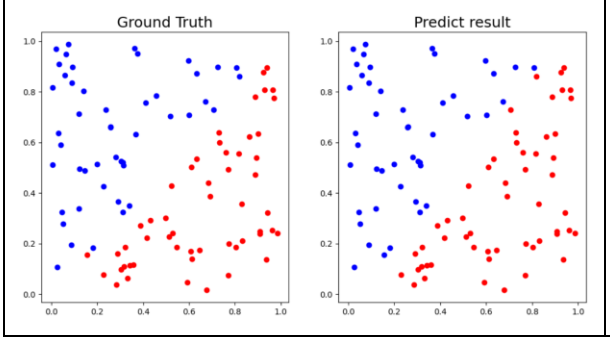
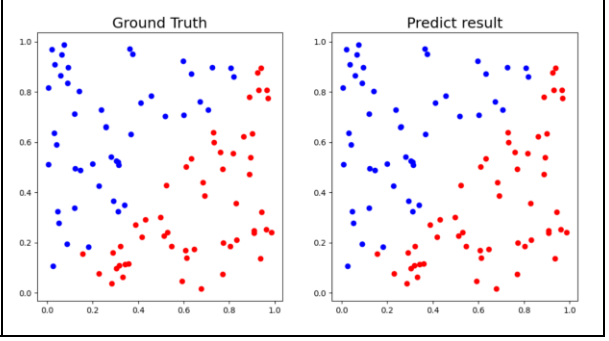
Discussions

Try different learning rates

Fixed Hyperparameters

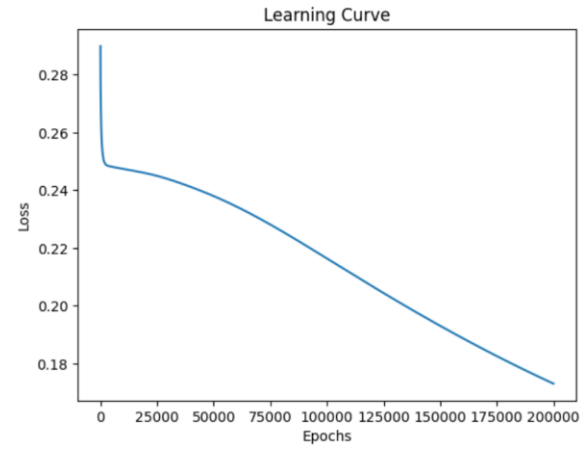
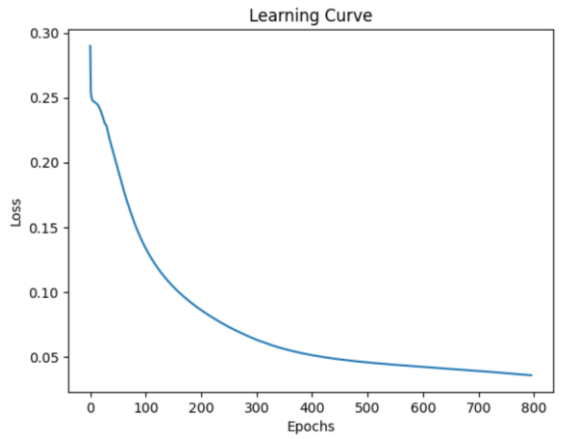
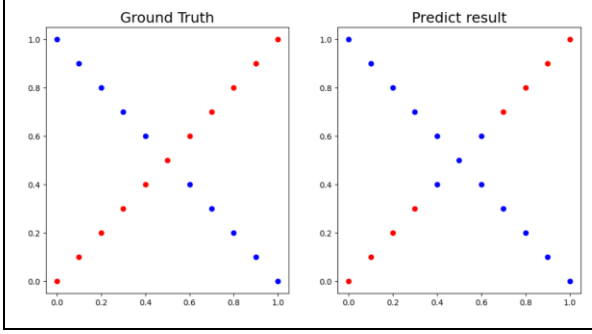
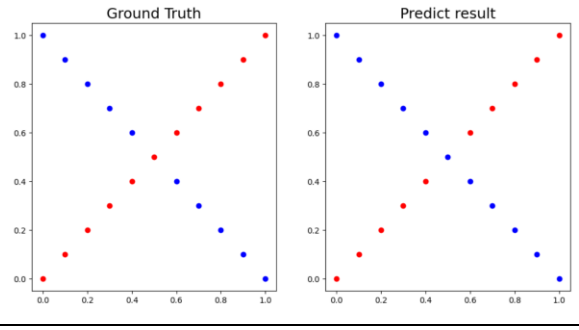
Activation Function	Optimizer	Hidden_Units	Epochs
sigmoid	Adagrad	10	200000

Linear

Learning Rate 0.001	Learning Rate 0.1
	
	

可以觀察到，當 learning_rate 較小時，梯度更新速度較為緩滿，也導致準確率有些微下降的情況。learning_rate 較大時，梯度更新速度會快上許多，準確率仍保持 100%。並且，在 Linear Dataset 中，learning rate 對準確率的影響並不大。

XOR

Learning Rate 0.001	Learning Rate 0.1
	
	

在 XOR Dataset 中，learning rate 對於訓練的影響就相比 Linear 較為明顯，首先，同樣地，learning rate 對於 loss 的影響相同，learning rate 大，loss 下降速度較快而且較為陡峭，learning rate 小，loss 下降速度慢且平緩。顯著的是，在此 Dataset 中，小的 learning rate 相較於 learning rate 較大的值，擁有較差的準確率

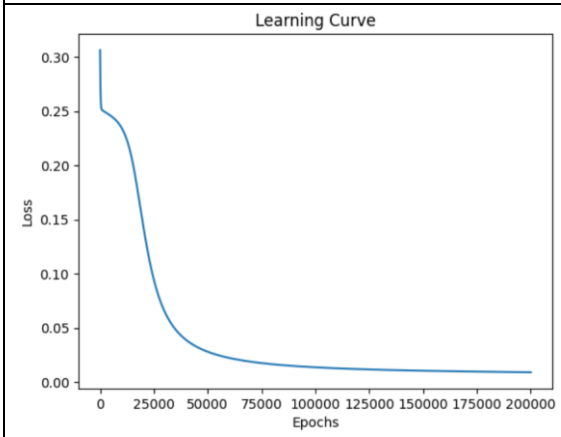
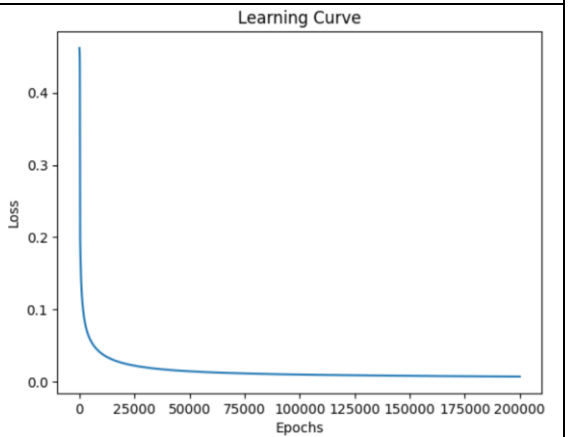
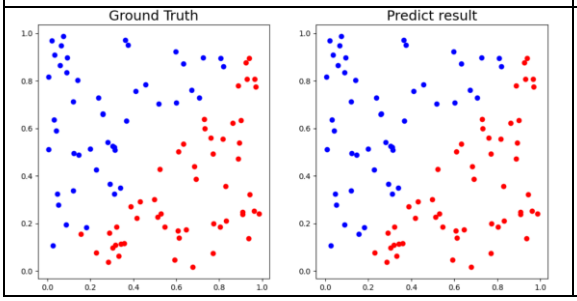
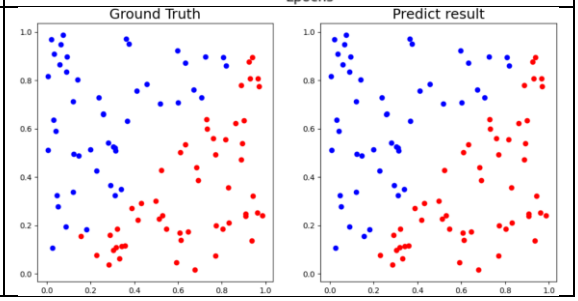
Try different numbers of hidden units

Fixed Hyperparameters

在這裡使用 SGD optimizer，以觀察到更明顯的 loss 變化

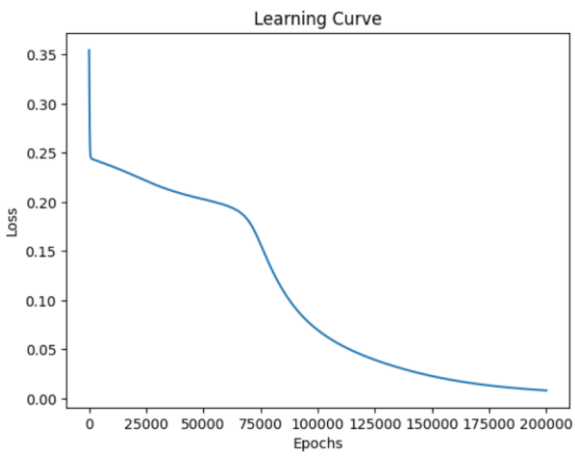
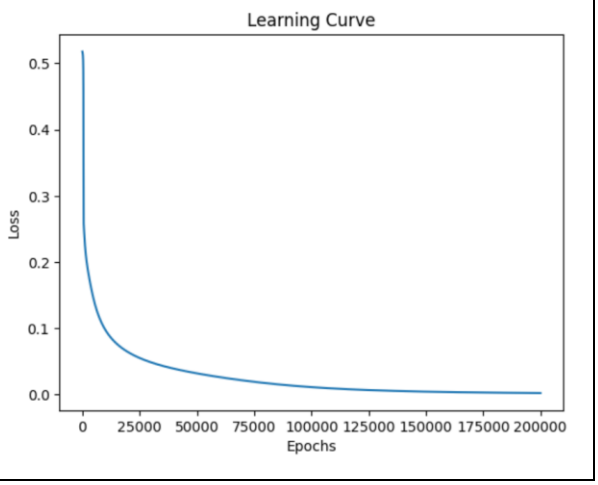
Activation Function	Optimizer	Learning Rate	Epochs
sigmoid	SGD	0.01	200000

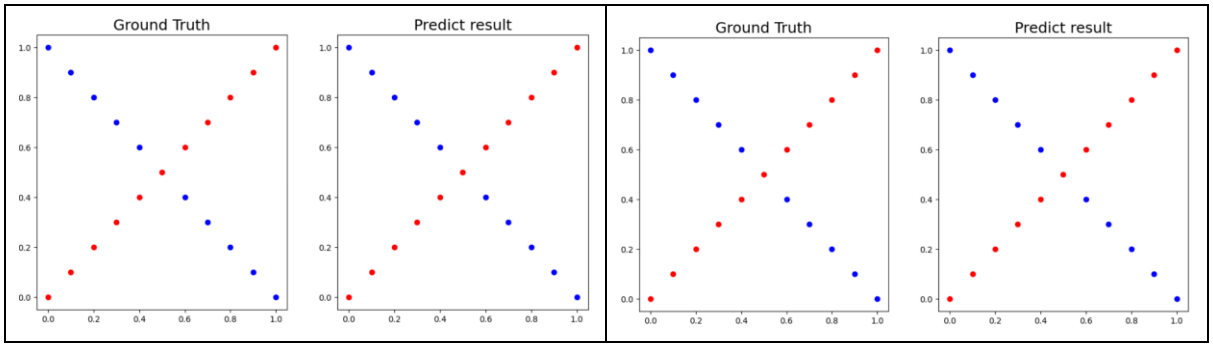
Linear

Hidden Layer 5	Hidden Layer 50
	
	

在 Linear Dataset 中，模型準確率沒有明顯的差異，但是可以明顯感覺到 hidden_layer 數增加時，訓練模型時間也明顯上升。再者，從 learning_curve 可以看出，當層數越多時，模型的 loss 下降也比較穩定且迅速。

XOR

Hidden Layer 5	Hidden Layer 50
	



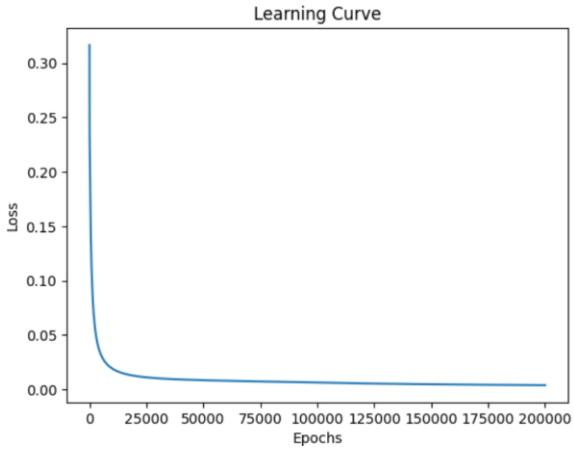
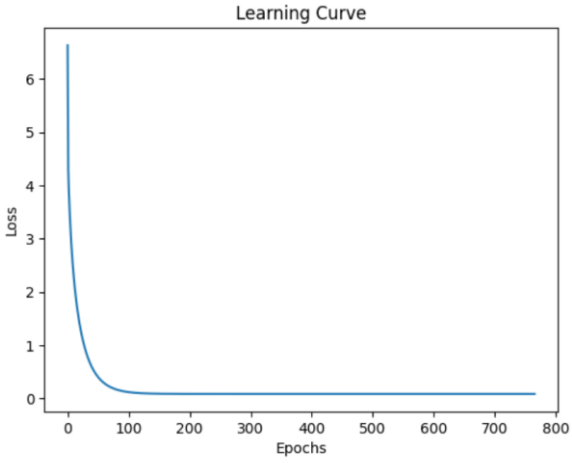
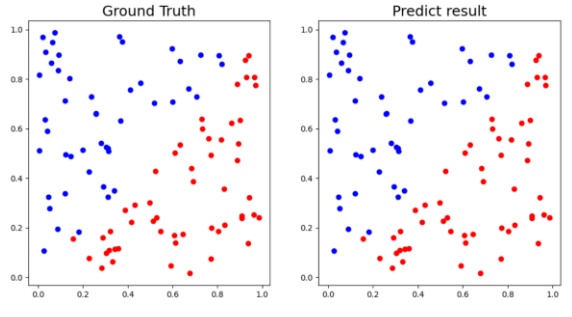
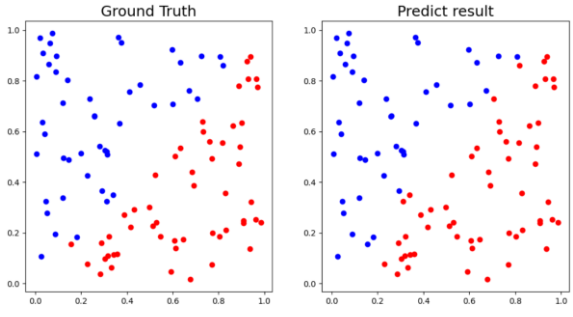
在 XOR Dataset 中，準確率在這兩種實驗 hidden layer 沒有明顯的差異，但可以看出較多的 hidden layer 對於模型訓練較為快速、穩定。

Try without activation functions

Fixed Hyperparameters

Hidden Layer	Optimizer	Learning Rate	Epochs
10	Adagrad	0.01	200000

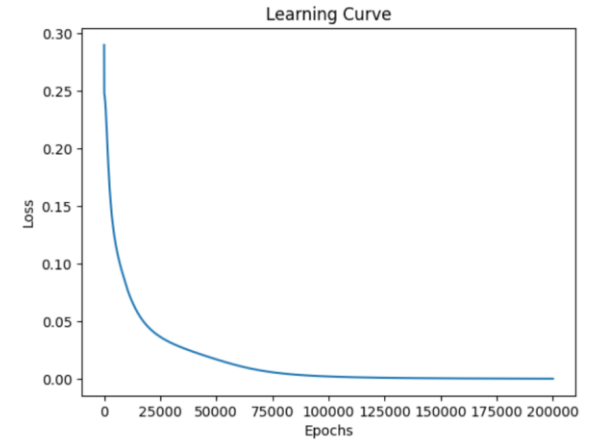
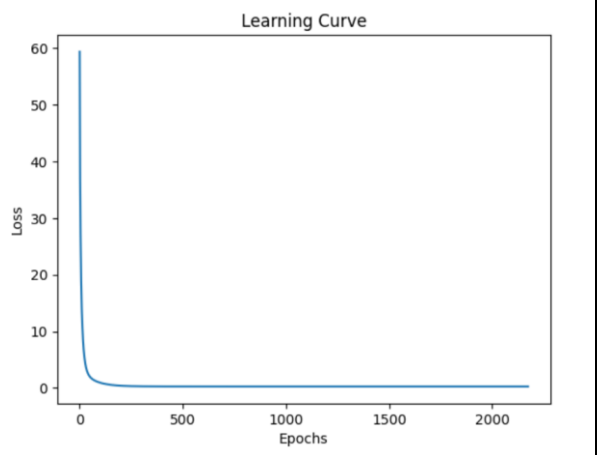
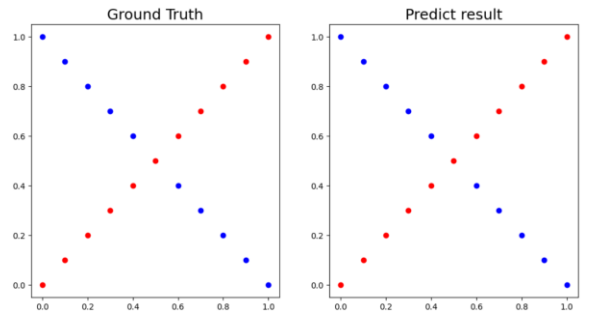
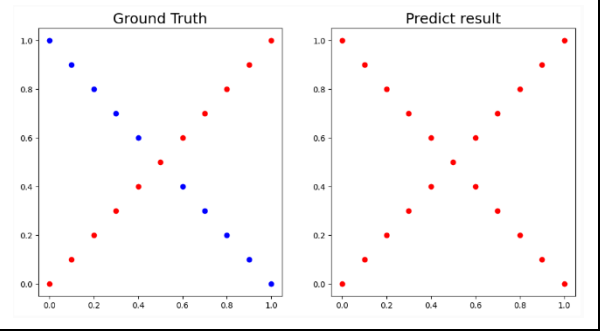
Linear

With Activation Function (Sigmoid)	Without Activation Function
	
	

沒有 Activation Function 在 Linear Dataset 影響不大，但可以看出影響了 loss 值

大小，但經過的 epoch 數較多也能有不錯的訓練效果。相較於有 Activation Function，沒有使用 Activation Function 的準確率也下降了些許。

XOR

With Activation Function (Sigmoid)	Without Activation Function
	
	

相較於 Linear Dataset，有無 Activation Function 對於 XOR Dataset 的影響明顯提升，沒有 Activation Function 基本上 Train 不了 model。

Extra Implementation Discussions

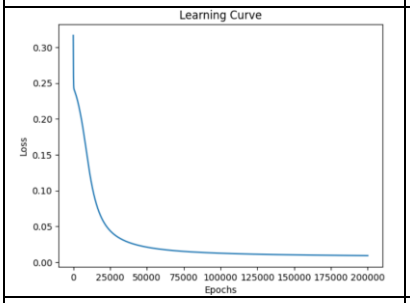
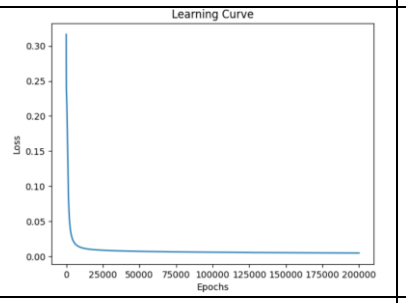
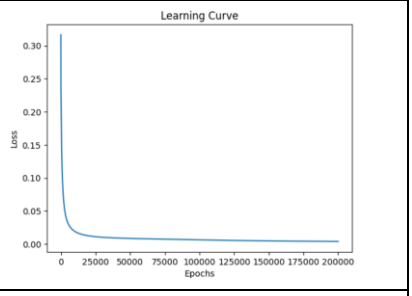
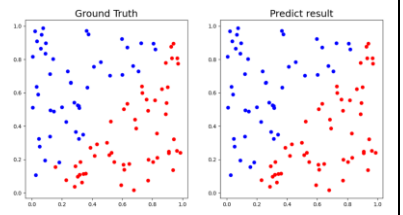
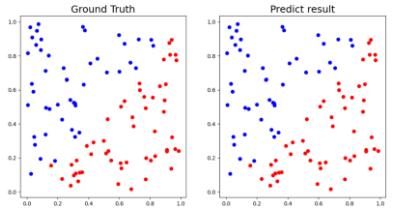
Try different optimizers

除了一般的 SGD，在本次作業中我額外實作了 Adagrad 以及 Momentum，下面會比較使用其他 optimizer 對於訓練的影響

Fixed Hyperparameters

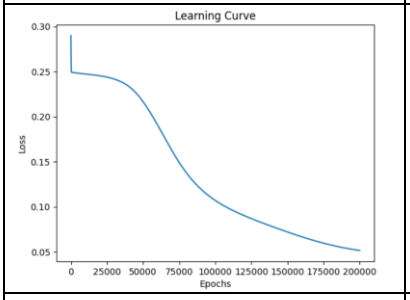
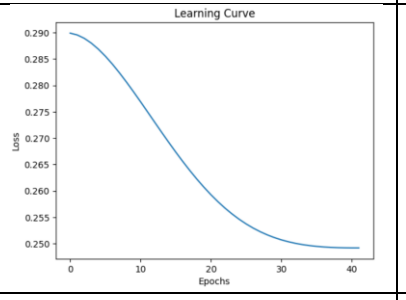
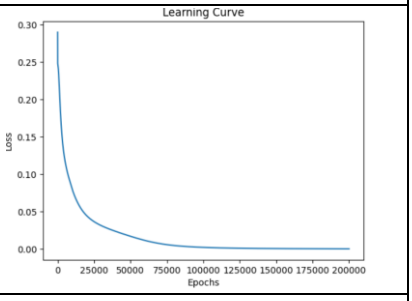
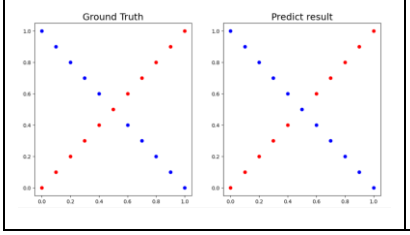
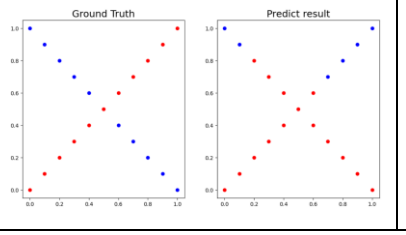
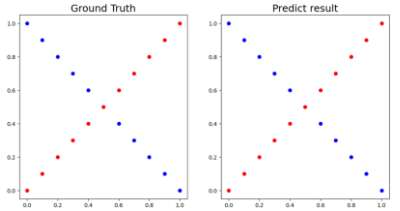
Hidden Layer	Activation Function	Learning Rate	Epochs
10	Sigmoid	0.01	200000

Linear

SGD	Momemtum	Adagrad
		
		

Optimizer 對於 Linear Dataset 的準確率沒有太大的影響，但可以看出與其使用單純的 SGD，其他兩者的 Loss 下降速度較快。

XOR

SGD	Momemtum	Adagrad
		
		

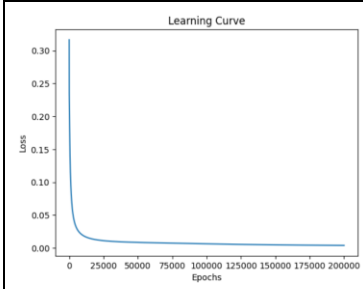
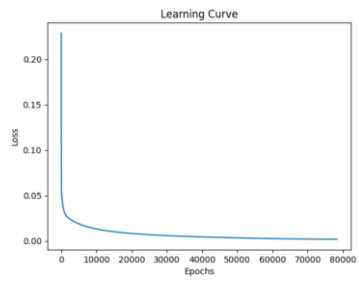
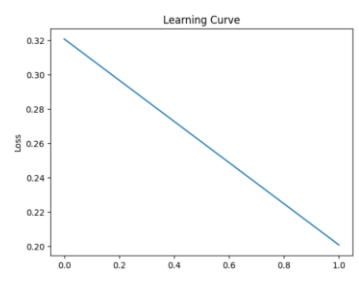
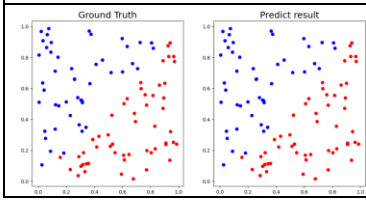
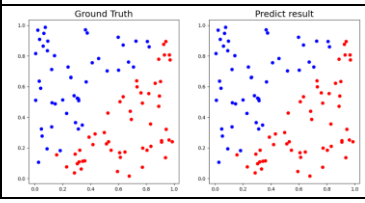
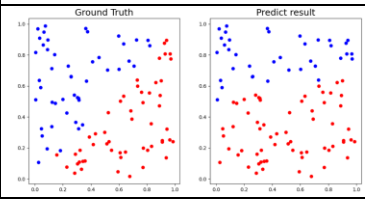
Optimizer 對於 XOR Dataset 的影響較大，除了影響 loss 下降幅度較大，同時也影響了準確率，在此實驗 Adagrad 擁有較好的訓練效果

Try different activation functions

Fixed Hyperparameters

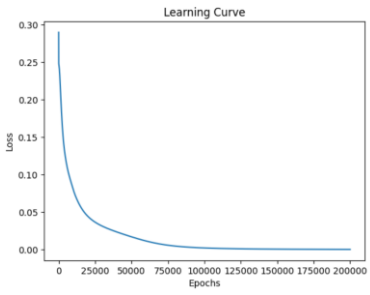
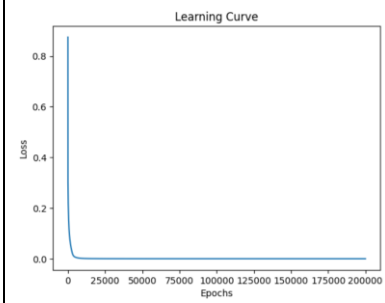
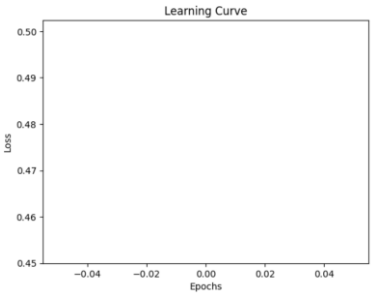
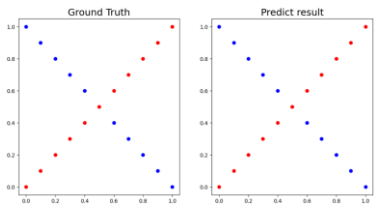
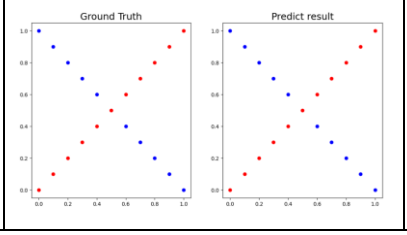
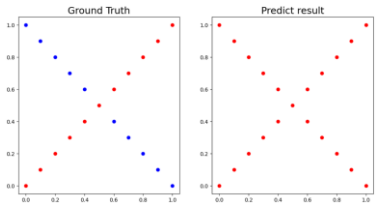
Hidden Layer	Optimizer	Learning Rate	Epochs
10	Adagrad	0.01	200000

Linear

Sigmoid	Tanh	Relu
		
		

可以觀察到使用 tanh 和 sigmoid 訓練效果均不錯，使用 relu 反而無法訓練 Model。

XOR

Sigmoid	Tanh	Relu
		
		

與 Linear Dataset 差不多，但 Relu 基本上完全 Train 不了 Mode

Questions

A. What are the purposes of activation functions?

使得訓練出來的模型不會只是線性函數，使用可微分的 activation function，可以經由多層神經元的疊加產生非線性效果，使神經網路能夠解決更困難的問題。

B. What if the learning rate is too large or too small?

當 learning rate 太小時，參數更新幅度太小，導致訓練速度非常緩慢，可能需要非常多次迭代才能收斂，亦或者卡在 Local Minimum 而導致無法找到最佳解。

當 learning rate 太大時，參數更新幅度過大，可能導致 loss 函數震盪甚至發散，無法收斂到最小值。

C. What are the purposes of weights and biases in a neural network?

Weight 決定 Neurons 之間的連結的強度並控制輸入對於輸出的影響程度，Bias 能夠移動 Model Function，，兩者都能調整 Model Function 的形狀以及位置，增加模型的靈活性。

Reference

[1] https://datasciocean.tech/deep-learning-core-concept/backpropagation-explain/

[2] https://medium.com/%E9%9B%9E%E9%9B%9E%E8%88%87%E5%85%94%E5%85%94%E7%9A%84%E5%B7%A5%E7%A8%8B%E4%B8%96%E7%95%8C/%E6%A9%9F%E5%99%A8%E5%AD%B8%E7%BF%92ml-note-sgd-momentum-adagrad-adam-optimizer-f20568c968db