# NYCU Deep Learning Lab-1 Back Propagation

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Github Link: Lab1-BackPropagation

## Introduction

在本次作業中,實作了一個簡單的深度神經網路,並完成了 Forward Propagation 與 Back Propagation 的流程,以模擬模型的訓練過程。除此之外,也額外加入了多種 Activation Function 與 Optimizer,以觀察它們對模型訓練效果的影響與優化效果。

為了驗證模型的表現與泛化能力,訓練資料分別使用助教提供的 Linear Dataset 以及 XOR Dataset。本作業的主要目的是深入理解 Back Propagation 的運作原理與細節,並透過嘗試調整模型結構、參數以及 Hyperparameters(如 Learning rate、Activation Functions 與 Optimizer )來優化訓練過程。

此外,透過實際實作與實驗,我們能更直觀地掌握深度學習中梯度下降的概念,並進一步了解不同設計選擇對於收斂速度與最終準確率的影響,為未來更複雜模型的開發打下基礎。

## Implement Detail

## Network Architecture

- Input Layer 含 2 個節點
- 兩層 Hidden Layer,可調整單元數
- Output Layer 含 1 個節點
- 全連接結構 (fully connected)

```
class Model:
   def __init__(
       self,
       input size=2,
       output_size=1,
      hidden_layers_size=10,
       activation="sigmoid",
       optimizer="SGD",
       self.losses = []
       self.layers = []
       # Build model
       self.layers.append(
           Linear_Layer(input_size, hidden_layers_size, activation, optimizer)
           Linear_Layer(hidden_layers_size, hidden_layers_size, activation, optimizer)
        self.layers.append(
           Linear_Layer(hidden_layers_size, output_size, activation, optimizer)
```

## **Activation Functions**

- 提供 Sigmoid、ReLU、Tanh 三種 Activation Funtions 選擇
- 同時實作各 Activation functions 的微分以利之後計算梯度使用

```
# Activative functions and their derivatives
def sigmoid(x):
    return 1.0 / (1.0 + np.exp(-x))

def derivative_sigmoid(x):
    return np.multiply(x, 1.0 - x)

def relu(x):
    return np.maximum(0, x)

def derivative_relu(x):
    return np.where(x >= 0, 1, 0)

def tanh(x):
    return np.tanh(x)

def derivative_tanh(x):
    return 1.0 - np.square(np.tanh(x))
```

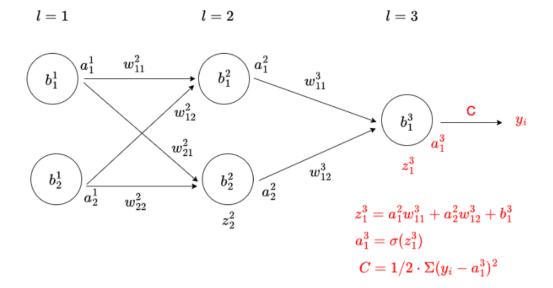
## **Backpropagation**

- Loss Function 採用 MSE (Mean Squared Error)
- 計算各層梯度
- 根據梯度更新 Weights 與 Bias

#### 符號定義

- C: : Loss Function ,此模型中使用 Mean Square Error (MSE)
- σ : Activation Function
- $b^l$ : 第l 層的 bias
- $w^l$ : 第l 層的 weight
- $z^l$ : 從第 l-1 層 到第l 層經由 weight 和 bias 運算後得到的結果
- $a^l : \sigma(z^l)$
- $\delta^l$  :  $\frac{\partial C}{\partial z^l}$

以下為圖例



對於每一層 Layer,我們需要去計算其 $\delta$  值。假設我們已知 $\delta^l$ ,我們可以藉由此值推導出  $\delta^{l-1}$ ,根據連鎖律(Chain Rule), $\delta^{l-1} = \frac{\partial C}{\partial z^{l-1}} = \frac{\partial C}{\partial z^l} \times \frac{\partial z^l}{\partial a^{l-1}} \times \frac{\partial a^{l-1}}{\partial z^{l-1}}$ 。  $\frac{\partial C}{\partial z^l}$  即為  $\delta^l$ ,為我們已知

$$\frac{\partial z^l}{\partial a^{l-1}}$$
根據觀察可得知為 $w^l$ 

$$rac{\partial a^{l-1}}{\partial z^{l-1}}$$
即為  $\sigma'$  (  $z^{l-1}$  ) ,  $\sigma'$  為 Activation function 之微分

下方圖片中的 $\delta$  值就是參照以上推倒而計算出,知道 $\delta$  值後即可得知所有 weight 和 bias 的梯度。

$$\frac{\partial C}{\partial b^{l}} = \frac{\partial C}{\partial a^{l}} \times \frac{\partial a^{l}}{\partial z^{l}} \times \frac{\partial z^{l}}{\partial b^{l}} = \delta^{l}$$

$$\frac{\partial C}{\partial w^{l}} = \frac{\partial C}{\partial a^{l}} \times \frac{\partial a^{l}}{\partial z^{l}} \times \frac{\partial z^{l}}{\partial w^{l}} = \delta^{l} \times a^{l}$$

也就是下方程式碼 dW 和 db 的計算方式

```
def backward(self, upstream_delta, learning_rate=0.01):
   # check whether the activation function is empty
    if not self.activation:
       delta = upstream delta
       # If no activation function, delta is just upstream delta
   else:
       delta = upstream delta * derivative activation map[self.activation](self.a)
   # Calculate gradients of weights and bias
   dW = np.dot(self.input.T, delta)
   db = np.sum(delta)
    # Update weights and bias
    if self.optimizer == "SGD":
       self.weights -= dW * learning_rate
       self.bias -= db * learning_rate
   elif self.optimizer == "Adagrad":
       # For the purpose of best training, learning rate should be adjusted according to the gradients
       # If gradients are small, learning rate should be larger, vice versa
       self.total_grad_w += np.square(dW)
        self.total grad b += np.square(db)
        self.weights -= (
           dW * learning_rate / np.sqrt(self.total_grad_w + self.epsilon)
       self.bias -= db * learning_rate / np.sqrt(self.total_grad_b + self.epsilon)
    elif self.optimizer == "Momentum":
       self.v_weight = self.momentum * self.v_weight + dW * learning_rate
        self.v_bias = self.momentum * self.v_bias + db * learning_rate
        self.weights -= self.v weight
        self.bias -= self.v bias
   return np.dot(delta, self.weights.T) # Return delta for the previous layer
```

## Extra Implementation

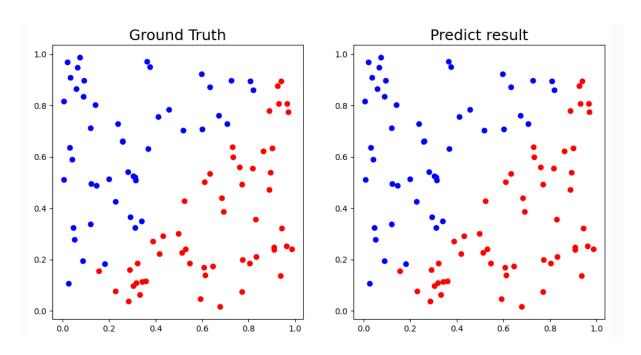
• 支援多種 Optimizer,包括 SGD、Momentum、AdaGrad

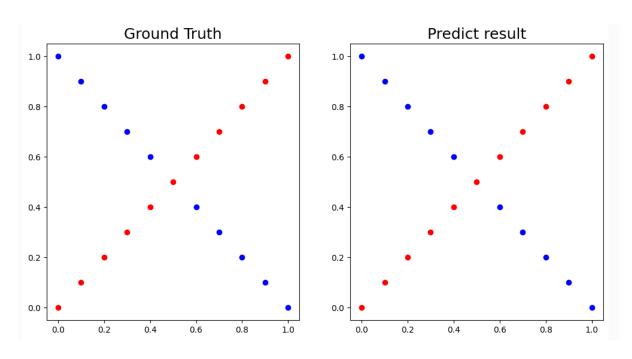
Optimizer 的實作可參考上方圖片

- o SGD:直接使用 Learning Rate 乘上梯度來更新 Weights。
- o Momentum:透過累積梯度的速度向量(v\_weight, v\_bias),幫助模型跳脫 局部最小值並讓收斂路徑更平滑。
- Adagrad:根據以往累積的梯度平方和來動態調整 Learning Rate。當某些 參數需要較大或較小的更新時特別有幫助。
- 可調整參數如 Learning Rate、Hidden Laver 點數、Activation Functions 類型等

# **Experimental Results**

## Screenshot and comparison figure





## Show the accuracy of your prediction

## Hyperparameters

Activation Function	Optimizer	Learning Rate	Hidden_Units
tanh	SGD	0.01	10

#### Linear Dataset

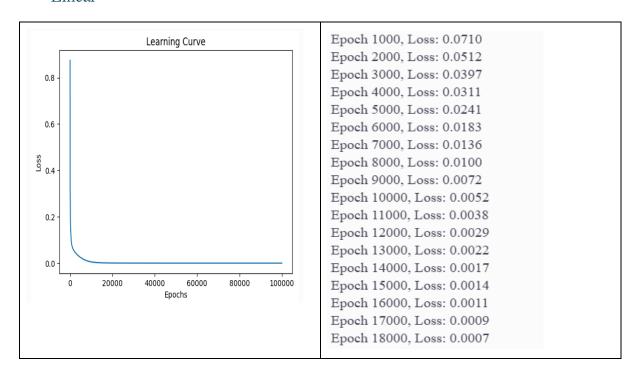
```
Ground Truth: [U]
iter88
                                 Predict: [0.02985598] |
           Ground Truth: [0] |
                                 Predict: [-0.00030772] |
Iter89
Iter90
           Ground Truth: [0]
                                 Predict: [-0.10596692] |
Iter91
           Ground Truth: [0] |
                                 Predict: [0.01921551] |
           Ground Truth: [0] |
                                 Predict: [0.15833155] |
Iter92
           Ground Truth: [1]
                                 Predict: [0.99975412] |
Iter93
Iter94
           Ground Truth: [0] |
                                 Predict: [-0.00655765] |
Iter95
           Ground Truth: [0] |
                                 Predict: [0.00890729] |
Iter96
           Ground Truth: [1]
                                 Predict: [0.99854244] |
                                 Predict: [0.00630843] |
           Ground Truth: [0] |
Iter97
Iter98
           Ground Truth: [1]
                                 Predict: [0.91700917] |
           Ground Truth: [1]
                                 Predict: [0.99966345] |
Iter99
            Ground Truth: [0] |
                                   Predict: [-0.06874714] |
Iter100
Loss = 0.0060 Accuracy = 100.00%
```

#### **XOR** Dataset

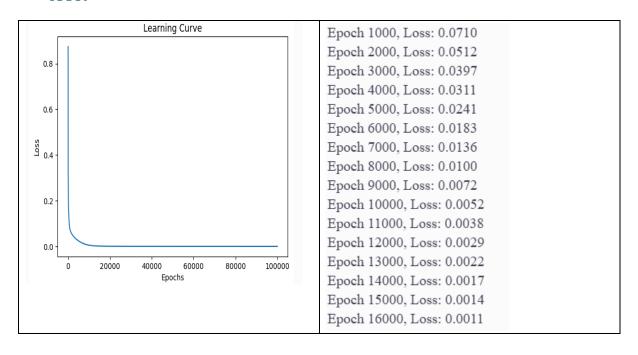
```
Iter13
           Ground Truth: |1||
                                 Predict: [0.99260072]
           Ground Truth: [0]
Iter14
                                 Predict: [0.0029742] |
Iter15
           Ground Truth: [1]
                                 Predict: [0.99988569] |
           Ground Truth: [0]
Iter16
                                 Predict: [-0.00441735]
           Ground Truth: [1]
Iter17
                                 Predict: [0.99993517] |
Iter18
           Ground Truth: [0]
                                 Predict: [0.00217426] |
Iter19
           Ground Truth: [1]
                                 Predict: [0.99992022] |
Iter20
           Ground Truth: [0]
                                 Predict: [0.00027366] |
Iter21
           Ground Truth: [1]
                                 Predict: [0.99988022] |
Loss = 0.0000 Accuracy = 100.00%
```

## Learning curve (loss-epoch curve)

#### Linear



#### XOR

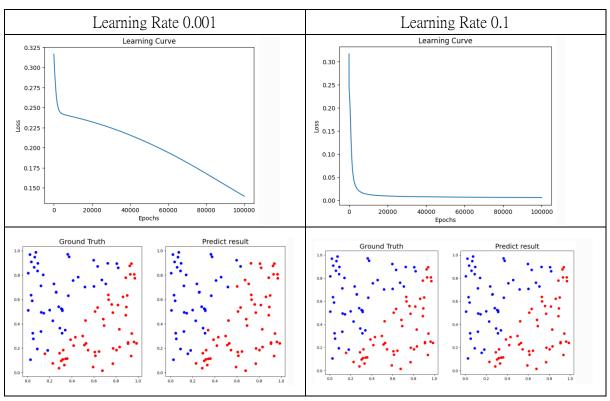


## **Discussions**

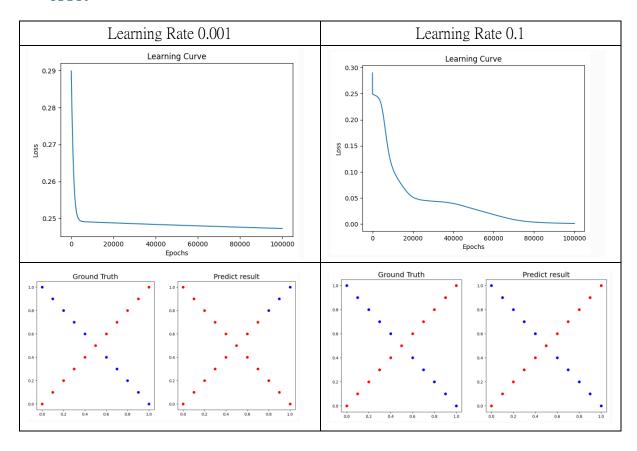
## Try different learning rates

#### Fixed Hyperparameters

Activation Function	Optimizer	Hidden_Units
sigmoid	SGD	10



可以觀察到,當 learning\_rate 較小時,梯度更新速度較為緩滿,也導致準確率有些微下降的情況。learning\_rate 較大時,梯度更新速度會快上許多,準確率仍保持 100%,在 Linear Dataset 中,learning rate 對準確率的影響並不大。



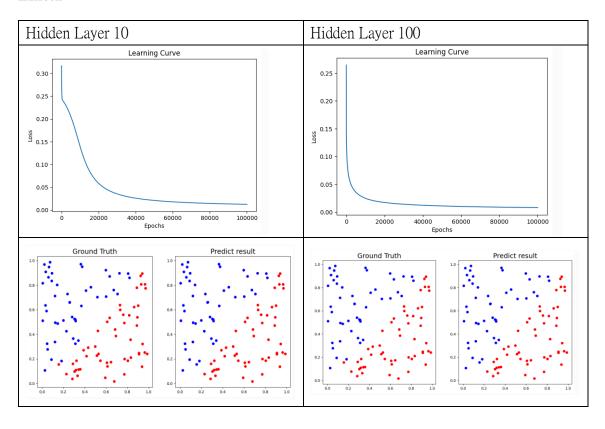
在 XOR Dataset 中,learning rate 對於訓練的影響就相比 Linear 較為明顯,首先,同樣地,learning rate 對於 loss 的影響相同,learning rate 大,loss 下降速度較快而且較為陡峭,learning rate 小,loss 下降速度慢且平緩。顯著的是,在此Dataset 中,小的 learning rate 只能達到準確率約 38%,learning rate 數值大時卻能達到 100%。

## Try different numbers of hidden units

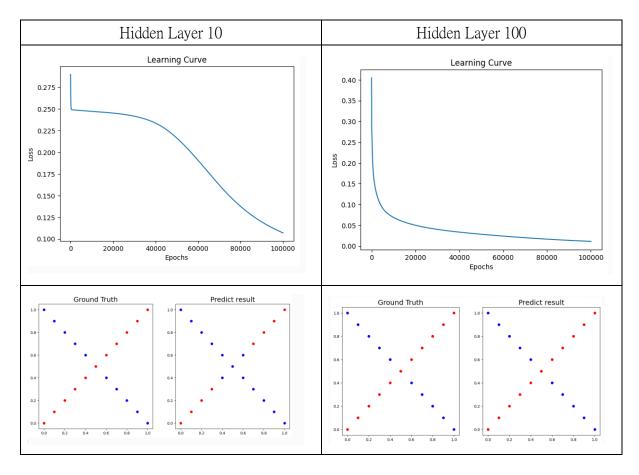
## Fixed Hyperparameters

Activation Function	Optimizer	Learning Rate
sigmoid	SGD	0.01

## Linear



在 Linear Dataset 中,訓練結果沒有明顯的差異,但是可以明顯感覺到 hidden\_layer 數增加時,訓練模型時間也明顯上升。再者,從 learning\_curve 可以看出,當層數越多時,模型的 loss 下降也比較穩定。



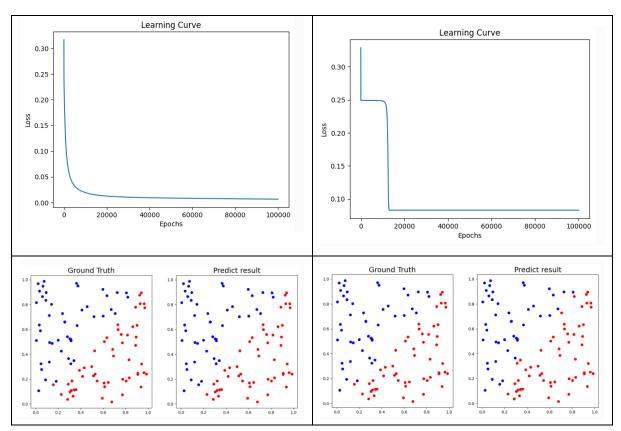
相較於 Linear Dataset,提高 hidden layer 層數對於 XOR Dataset 有更好的訓練效果,能觀察到,層數較多,loss 能明顯下降,準確率也明顯提升。

## Try without activation functions

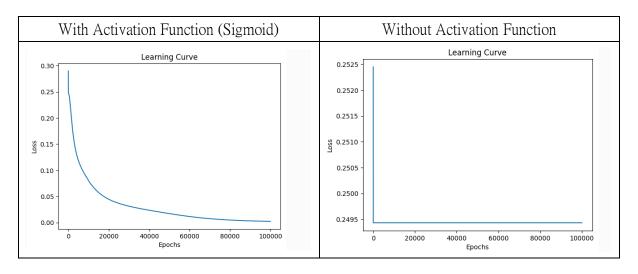
## Fixed Hyperparameters

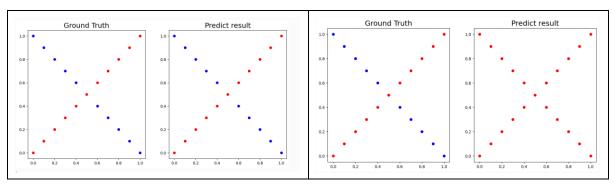
Hidden Layer	Optimizer	Learning Rate
10	Adagrad	0.01

With Activation Function (Sigmoid)	Without Activation Function
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沒有 Activation Function 在 Linear Dataset 影響不大,但可以看出影響了 loss 下降變得不穩定,相較於有 Activation Function,沒有使用 Activation Function 的準確率也下降了些許。





相較於 Linear Dataset,有無 Activation Function 對於 XOR Dataset 的影響非常大,沒有 Activation Function 基本上 Train 不了 model。

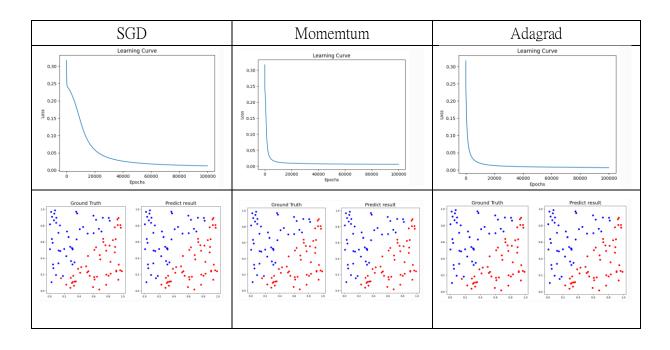
## Extra Implementation Discussions

#### Try different optimizers

除了一般的 SGD,在本次作業中我額外實作了 Adagrad 以及 Momentum,下面會比較使用其他 optimizer 對於訓練的影響

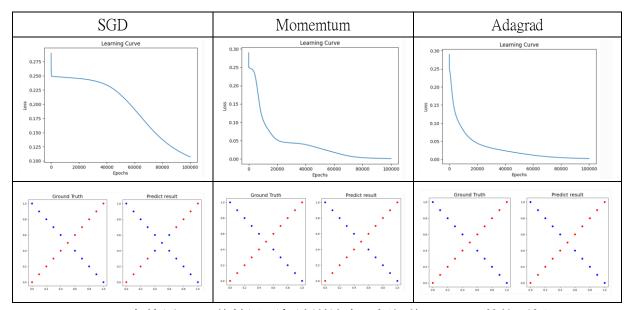
Fixed Hyperparameters

Hidden Layer	Activation Function	Learning Rate
10	Sigmoid	0.01



Optimizer 對於 Linear Dataset 的準確率沒有太大的影響,但可以看出與其使用單純的 SGD,其他兩者的 Loss 下降速度較快。

#### XOR

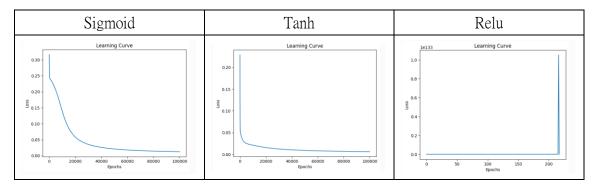


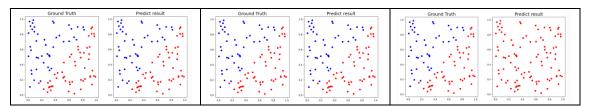
XOR Dataset 在使用 SGD 的情況下無法訓練出一個好的 Model,其他兩個 Optimizer 反而能讓 Model 準確率達到 100%

## Try different activation functions

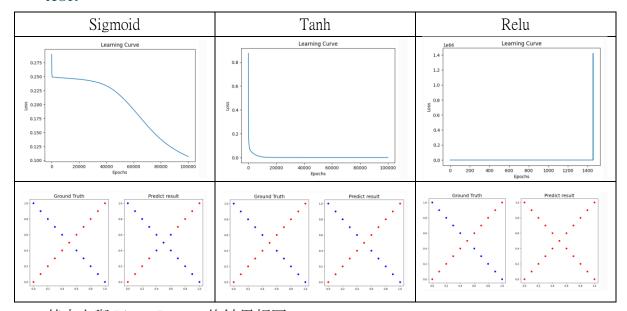
#### Fixed Hyperparameters

Hidden Layer	Optimizer	Learning Rate
10	SGD	0.01





可以觀察到使用 tanh 的效果最好,使用 relu 反而無法訓練 Model,Sigmoid 能訓練 出不錯的 Model,但相較於 tanh 略遜了一點。



基本上與 Linear Dataset 的結果相同

## Questions

#### A. What are the purposes of activation functions? (3%)

使得訓練出來的模型不會只是線性函數,使用可微分的 activation function,可以經由多層神經元的疊加產生非線性效果,使神經網路能夠逼近複雜的實際數據分布,解決更困難的分類或回歸問題。

## B. What if the learning rate is too large or too small? (3%)

當 learning rate 太小時,參數更新幅度太小,導致訓練速度非常緩慢,可能需要非常多次迭代才能收斂。

當 learning rate 太大時,參數更新幅度過大,可能導致 loss 函數震盪甚至發散,無法收斂到最小值。

## C. What are the purposes of weights and biases in a neural network? (3%)

Weight 決定神經元之間的連結的強度並控制輸入對於輸出的影響程度, Bias 能夠移動 Activation Functions, 增加模型的靈活性,兩者都能調整模型函數的形狀以 Fitting 實際 數據分布。

# Reference

[1] https://datasciocean.tech/deep-learning-core-concept/backpropagation-explain/