

```
private void CaluclateAerodynamicEffect()
{
    // "Aerodynamic" calculations. This is a very simple approximation of
    the effect that a plane
    // will naturally try to align itself in the direction that it's facing
    when moving at speed.
    // Without this, the plane would behave a bit like the asteroids
    spaceship!
    if (m_Rigidbody.velocity.magnitude > 0)
    {
        // compare the direction we're pointing with the direction we're
        moving:
        m_AeroFactor = Vector3.Dot(transform.forward,
        m_Rigidbody.velocity.normalized);
        // multiplied by itself results in a desirable rolloff curve of the
        effect
        m_AeroFactor *= m_AeroFactor;
        // Finally we calculate a new velocity by bending the current
        velocity direction towards
        // the the direction the plane is facing, by an amount based on this
        aeroFactor
        var newVelocity = Vector3.Lerp(m_Rigidbody.velocity,
        transform.forward*ForwardSpeed,
        m_AeroFactor*ForwardSpeed*m_AerodynamicEffect*Time.deltaTime);
        m_Rigidbody.velocity = newVelocity;

        // also rotate the plane towards the direction of movement - this
        should be a very small effect, but means the plane ends up
        // pointing downwards in a stall
        m_Rigidbody.rotation = Quaternion.Slerp(m_Rigidbody.rotation,
        Quaternion.LookRotation(m_Rigidbody.velocity, transform.up),
        m_AerodynamicEffect*Time.deltaTime);
    }
}

private void CalculateLinearForces()
{
    // Now calculate forces acting on the aeroplane:
    // we accumulate forces into this variable:
    var forces = Vector3.zero;
```

```
// Add the engine power in the forward direction
forces += EnginePower*transform.forward;
// The direction that the lift force is applied is at right angles to
the plane's velocity (usually, this is 'up'!)
var liftDirection = Vector3.Cross(m_Rigidbody.velocity,
transform.right).normalized;
// The amount of lift drops off as the plane increases speed - in reality
this occurs as the pilot retracts the flaps
// shortly after takeoff, giving the plane less drag, but less lift.
Because we don't simulate flaps, this is
// a simple way of doing it automaticall

using System;
using System.Collections.Generic;
using UnityEngine;
#if UNITY_EDITOR
using UnityEditor;
#endif

namespace UnityStandardAssets.Utility
{
    public class AutomobileShaderSwitch : MonoBehaviour
    {
        [SerializeField] private ReplacementList m_ReplacementList;

        // Use this for initialization
        private void OnEnable()
        {
#if UNITY_IPHONE || UNITY_ANDROID || UNITY_WP8 || UNITY_BLACKBERRY
            var renderers = FindObjectsOfType<Renderer>();
            Debug.Log (renderers.Length+" renderers");
            var oldMaterials = new List<Material>();
            var newMaterials = new List<Material>();

            int materialsReplaced = 0;
            int materialInstancesReplaced = 0;

            foreach(ReplacementDefinition replacementDef in
m_ReplacementList.items)
            {
                foreach(var r in renderers)
                {
                    Material[] modifiedMaterials = null;
                    for(int n=0; n<r.sharedMaterials.Length; ++n)
                    {
```

```

        var material = r.sharedMaterials[n];
        if (material.shader == replacementDef.original)
        {
            if (modifiedMaterials == null)
            {
                modifiedMaterials = r.materials;
            }
            if (!oldMaterials.Contains(material))
            {
                oldMaterials.Add(material);
                Material newMaterial =
                (Material)Instantiate(material);
                newMaterial.shader = replacementDef.replacement;
                newMaterials.Add(newMaterial);
                ++materialsReplaced;
            }
            Debug.Log ("replacing "+r.gameObject.name+" renderer
            "+n+" with "+newMaterials[oldMaterials.IndexOf(material)].name);
            modifiedMaterials[n] =
            newMaterials[oldMaterials.IndexOf(material)];
            ++materialInstancesReplaced;
        }
    }
    if (modifiedMaterials != null)
    {
        r.materials = modifiedMaterials;
    }
}

Debug.Log (materialInstancesReplaced+" material instances replaced");
Debug.Log (materialsReplaced+" materials replaced");
for(int n=0; n<oldMaterials.Count; ++n)
{
    Debug.Log (oldMaterials[n].name+"
    ("oldMaterials[n].shader.name+"+" replaced with "+newMaterials[n].name+"
    ("newMaterials[n].shader.name+"));
}
#endif
}

[Serializable]
public class ReplacementDefinition
{

```

```
        public Shader original = null;
        public Shader replacement = null;
    }

    [Serializable]
    public class ReplacementList
    {
        public ReplacementDefinition[] items = new ReplacementDefinition[0];
    }
}

namespace UnityStandardAssets.Utility.Inspector
{
    #if UNITY_EDITOR
        [CustomPropertyDrawer(typeof (AutoMobileShaderSwitch.ReplacementList))]
        public class ReplacementListDrawer : PropertyDrawer
        {
            const float k_LineHeight = 18;
            const float k_Spacing = 4;

            public override void OnGUI(Rect position, SerializedProperty property,
GUIContent label)
            {
                EditorGUI.BeginProperty(position, label, property);

                float x = position.x;
                float y = position.y;
                float inspectorWidth = position.width;

                // Don't make child fields be indented
                var indent = EditorGUI.indentLevel;
                EditorGUI.indentLevel = 0;

                var items = property.FindPropertyRelative("items");
                var titles = new string[] { "Original", "Replacement", "" };
                var props = new string[] { "original", "replacement", "-" };
                var widths = new float[] { .45f, .45f, .1f };
                const float lineHeight = 18;
                bool changedLength = false;
                if (items.arraySize > 0)
                {
                    for (int i = -1; i < items.arraySize; ++i)
                    {
```

```

var item = items.GetArrayElementAtIndex(i);

float rowX = x;
for (int n = 0; n < props.Length; ++n)
{
    float w = widths[n]*inspectorWidth;

    // Calculate rects
    Rect rect = new Rect(rowX, y, w, lineHeight);
    rowX += w;

    if (i == -1)
    {
        // draw title labels
        EditorGUI.LabelField(rect, titles[n]);
    }
    else
    {
        if (props[n] == "-" || props[n] == "^" || props[n] ==
"v")
        {
            if (GUI.Button(rect, props[n]))
            {
                switch (props[n])
                {
                    case "-":
                        items.DeleteArrayElementAtIndex(i);
                        items.DeleteArrayElementAtIndex(i);
                        changedLength = true;
                        break;
                    case "v":
                        if (i > 0)
                        {
                            items.MoveArrayElement(i, i +
1);
                        }
                        break;
                    case "^":
                        if (i < items.arraySize - 1)
                        {
                            items.MoveArrayElement(i, i -
1);
                        }
                        break;
                }
            }
        }
    }
}

```

```

        }
    }
}
else
{
    SerializedProperty prop =
item.FindPropertyRelative(props[n]);
    EditorGUI.PropertyField(rect, prop,
GUIContent.none);
}
}

y += lineHeight + k_Spacing;
if (changedLength)
{
    break;
}
}

// add button
var addButtonRect = new Rect((x + position.width) -
widths[widths.Length - 1]*inspectorWidth, y,
widths[widths.Length
1]*inspectorWidth, lineHeight);
if (GUI.Button(addButtonRect, "+"))
{
    items.InsertArrayElementAtIndex(items.arraySize);
}

y += lineHeight + k_Spacing;

// Set indent back to what it was
EditorGUI.indentLevel = indent;
EditorGUI.EndProperty();
}

public override float GetPropertyHeight(SerializedProperty property,
GUIContent label)
{
    SerializedProperty items = property.FindPropertyRelative("items");
    float lineAndSpace = k_LineHeight + k_Spacing;

```

```
        return 40 + (items.arraySize*lineAndSpace) + lineAndSpace;
    }
}
#endif
}

using UnityEngine;
using UnityEngine.Rendering;

namespace UnityStandardAssets.CinematicEffects
{
    [ExecuteInEditMode]
    [RequireComponent(typeof(Camera))]
    [AddComponentMenu("Image Effects/Cinematic/Ambient Occlusion")]
    #if UNITY_5_4_OR_NEWER
        [ImageEffectAllowedInSceneView]
    #endif
    public partial class AmbientOcclusion : MonoBehaviour
    {
        #region Public Properties

        /// Effect settings.
        [SerializeField]
        public Settings settings = Settings.defaultSettings;

        /// Checks if the ambient-only mode is supported under the current settings.
        public bool isAmbientOnlySupported
        {
            get { return targetCamera.hdr && occlusionSource ==
OcclusionSource.GBuffer; }
        }

        /// Checks if the G-buffer is available
        public bool isGBufferAvailable
        {
            get { return targetCamera.actualRenderingPath ==
RenderingPath.DeferredShading; }
        }

        #endregion

        #region Private Properties

        // Properties referring to the current settings
```

```
float intensity
{
    get { return settings.intensity; }
}

float radius
{
    get { return Mathf.Max(settings.radius, 1e-4f); }
}

SampleCount sampleCount
{
    get { return settings.sampleCount; }
}

int sampleCountValue
{
    get
    {
        switch (settings.sampleCount)
        {
            case SampleCount.Lowest: return 3;
            case SampleCount.Low:    return 6;
            case SampleCount.Medium: return 12;
            case SampleCount.High:   return 20;
        }
        return Mathf.Clamp(settings.sampleCountValue, 1, 256);
    }
}

OcclusionSource occlusionSource
{
    get
    {
        if (settings.occlusionSource == OcclusionSource.GBuffer
            && !isGBufferAvailable)
            // An unavailable source was chosen: fallback to
            DepthNormalsTexture.
            return OcclusionSource.DepthNormalsTexture;
        else
            return settings.occlusionSource;
    }
}
```



```

        GUILayout.Label("Mapping HDR to LDR ranges since 1982", Editor
        if(mode.intValue>0)
        {
            EditorGUILayout.PropertyField (chromaticAberration, new GUIContent("
Tangential Aberration"));
            EditorGUILayout.PropertyField (axialAberration, new GUIContent(" Axial
Aberration"));
            luminanceDependency.floatValue = EditorGUILayout.Slider(" Contrast
Dependency", luminanceDependency.floatValue, 0.001f, 1.0f);
        }
        else
            EditorGUILayout.PropertyField (chromaticAberration, new GUIContent("
Chromatic Aberration"));

        serObj.ApplyModifiedProperties();
    }using UnityEngine;

[ExecuteInEditMode]
[AddComponentMenu("Image Effects/Vortex")]
public class VortexEffect : ImageEffectBase {
    public Vector2 radius = new Vector2(0.4F,0.4F);
    public float angle = 50;
    public Vector2 center = new Vector2(0.5F, 0.5F);

    // Called by camera to apply image effect
    void OnRenderImage (RenderTexture source, RenderTexture destination) {
        ImageEffects.RenderDistortion (material, source, destination, angle,
center, radius);
    }
}

}

}
}

using System;
using UnityEngine;

namespace UnityStandardAssets.Cameras
{
    public abstract class AbstractTargetFollower : MonoBehaviour
    {
        public enum UpdateType // The available methods of updating are:
        {

```

```
        FixedUpdate, // Update in FixedUpdate (for tracking rigidbodies).
        LateUpdate, // Update in LateUpdate. (for tracking objects that are
moved in Update)
        ManualUpdate, // user must call to update camera
    }

    [SerializeField] protected Transform m_Target;           // The target
object to follow
    [SerializeField] private bool m_AutoTargetPlayer = true; // Whether the
rig should automatically target the player.
    [SerializeField] private UpdateType m_UpdateType;       // stores the
selected update type

    protected Rigidbody targetRigidbody;

    protected virtual void Start()
    {
        // if auto targeting is used, find the object tagged "Player"
        // any class inheriting from this should call base.Start() to perform
this action!
        if (m_AutoTargetPlayer)
        {
            FindAndTargetPlayer();
        }
        if (m_Target == null) return;
        targetRigidbody = m_Target.GetComponent<Rigidbody>();
    }

    private void FixedUpdate()
    {
        // we update from here if updatetype is set to Fixed, or in auto mode,
        // if the target has a rigidbody, and isn't kinematic.
        if (m_AutoTargetPlayer && (m_Target == null
|| !m_Target.gameObject.activeSelf))
        {
            FindAndTargetPlayer();
        }
        if (m_UpdateType == UpdateType.FixedUpdate)
        {
            FollowTarget(Time.deltaTime);
        }
    }
}
```

```
private void LateUpdate()
{
    // we update from here if updatetype is set to Late, or in auto mode,
    // if the target does not have a rigidbody, or - does have a rigidbody
    but is set to kinematic.
    if (m_AutoTargetPlayer && (m_Target == null
|| !m_Target.gameObject.activeSelf))
    {
        FindAndTargetPlayer();
    }
    if (m_UpdateType == UpdateType.LateUpdate)
    {
        FollowTarget(Time.deltaTime);
    }
}

public void ManualUpdate()
{
    // we update from here if updatetype is set to Late, or in auto mode,
    // if the target does not have a rigidbody, or - does have a rigidbody
    but is set to kinematic.
    if (m_AutoTargetPlayer && (m_Target == null
|| !m_Target.gameObject.activeSelf))
    {
        FindAndTargetPlayer();
    }
    if (m_UpdateType == UpdateType.ManualUpdate)
    {
        FollowTarget(Time.deltaTime);
    }
}

protected abstract void FollowTarget(float deltaTime);

public void FindAndTargetPlayer()
{
    // auto target an object tagged player, if no target has been assigned
    var targetObj = GameObject.FindGameObjectWithTag("Player");
    if (targetObj)
    {
```

```
        SetTarget(targetObj.transform);
    }
}

public virtual void SetTarget(Transform newTransform)
{
    m_Target = newTransform;
}

public Transform Target
{
    get { return m_Target; }
}
}

}using System;
using UnityEngine;
using Object = UnityEngine.Object;

namespace UnityStandardAssets.Utility
{
    public class ActivateTrigger : MonoBehaviour
    {
        // A multi-purpose script which causes an action to occur when
        // a trigger collider is entered.
        public enum Mode
        {
            Trigger = 0,    // Just broadcast the action on to the target
            Replace = 1,    // replace target with source
            Activate = 2,   // Activate the target GameObject
            Enable = 3,     // Enable a component
            Animate = 4,    // Start animation on target
            Deactivate = 5  // Decativate target GameObject
        }

        public Mode action = Mode.Activate;    // The action to accomplish
        public Object target;                  // The game object to affect.
        If none, the trigger work on this game object
        public GameObject source;
        public int triggerCount = 1;
        public bool repeatTrigger = false;
    }
}
```

```
private void DoActivateTrigger()
{
    triggerCount--;

    if (triggerCount == 0 || repeatTrigger)
    {
        Object currentTarget = target ?? gameObject;
        Behaviour targetBehaviour = currentTarget as Behaviour;
        GameObject targetGameObject = currentTarget as GameObject;
        if (targetBehaviour != null)
        {
            targetGameObject = targetBehaviour.gameObject;
        }

        switch (action)
        {
            case Mode.Trigger:
                if (targetGameObject != null)
                {
                    targetGameObject.BroadcastMessage("DoActivateTrigger");
                }
                break;
            case Mode.Replace:
                if (source != null)
                {
                    if (targetGameObject != null)
                    {
                        Instantiate(source,
targetGameObject.transform.position,
targetGameObject.transform.rotation);
                        DestroyObject(targetGameObject);
                    }
                }
                break;
            case Mode.Activate:
                if (targetGameObject != null)
                {
                    targetGameObject.SetActive(true);
                }
                break;
            case Mode.Enable:
                if (targetBehaviour != null)
```

```

        {
            targetBehaviour.enabled = true;
        }
        break;
    case Mode.Animate:
        if (targetGameObject != null)
        {
            targetGameObject.GetComponent<Animation>().Play();
        }
        break;
    case Mode.Deactivate:
        if (targetGameObject != null)
        {
            targetGameObject.SetActive(false);
        }
        break;
    }
}

private void OnTriggerEnter(Collider other)
{
    DoActivateTrigger();
}

}using System;
using UnityEngine;
using Random = UnityEngine.Random;

namespace UnityStandardAssets.Vehicles.Aeroplane
{
    [RequireComponent(typeof (AeroplaneController))]
    public class AeroplaneAiControl : MonoBehaviour
    {
        // This script represents an AI 'pilot' capable of flying the plane towards
        a designated target.
        // It sends the equivalent of the inputs that a user would send to the
        Aeroplane controller.
        [SerializeField] private float m_RollSensitivity = .2f;           // How
sensitively the AI applies the roll controls
        [SerializeField] private float m_PitchSensitivity = .5f;         // How
sensitively the AI applies the pitch controls
        [SerializeField] private float m_LateralWanderDistance = 5;      // The

```

```
amount that the plane can wander by when heading for a target
    [SerializeField] private float m_LateralWanderSpeed = 0.11f;    // The
speed at which the plane will wander laterally
    [SerializeField] private float m_MaxClimbAngle = 45;            // The
maximum angle that the AI will attempt to make plane can climb at
    [SerializeField] private float m_MaxRollAngle = 45;            // The
maximum angle that the AI will attempt to u
    [SerializeField] private float m_SpeedEffect = 0.01f;          // This
increases the effect of the controls based on the plane's speed.
    [SerializeField] private float m_TakeoffHeight = 20;           // the AI
will fly straight and only pitch upwards until reaching this height
    [SerializeField] private Transform m_Target;                   // the
target to fly towards

    private AeroplaneController m_AeroplaneController; // The aeroplane
controller that is used to move the plane
    private float m_RandomPerlin;                               // Used for
generating random point on perlin noise so that the plane will wander off path
slightly
    private bool m_TakenOff;                                     // Has the plane taken
off yet

    // setup script properties
    private void Awake()
    {
        // get the reference to the aeroplane controller, so we can send move
input to it and read its current state.
        m_AeroplaneController = GetComponent<AeroplaneController>();

        // pick a random perlin starting point for lateral wandering
        m_RandomPerlin = Random.Range(0f, 100f);
    }

    // reset the object to sensible values
    public void Reset()
    {
        m_TakenOff = false;
    }

    // fixed update is called in time with the physics system update
    private void FixedUpdate()
```

```

    {
        if (m_Target != null)
        {
            // make the plane wander from the path, useful for making the AI
            seem more human, less robotic.
            Vector3 targetPos = m_Target.position +
                                transform.right*

(Mathf.PerlinNoise(Time.time*m_LateralWanderSpeed, m_RandomPerlin)*2 - 1)*
                                m_LateralWanderDistance;

            // adjust the yaw and pitch towards the target
            Vector3 localTarget =
transform.InverseTransformPoint(targetPos);
            float targetAngleYaw = Mathf.Atan2(localTarget.x, localTarget.z);
            float targetAnglePitch = -Mathf.Atan2(localTarget.y,
localTarget.z);

            // Set the target for the planes pitch, we check later that this
            has not passed the maximum threshold
            targetAnglePitch = Mathf.Clamp(targetAnglePitch,
-m_MaxClimbAngle*Mathf.Deg2Rad,
                                m_MaxClimbAngle*Mathf.Deg2Rad);

            // calculate the difference between current pitch and desired pitch
            float changePitch = targetAnglePitch -
m_AeroplaneController.PitchAngle;

            // AI always applies gentle forward throttle
            const float throttleInput = 0.5f;

            // AI applies elevator control (pitch, rotation around x) to reach
            the target angle
            float pitchInput = changePitch*m_PitchSensitivity;

            // clamp the planes roll
            float desiredRoll = Mathf.Clamp(targetAngleYaw,
-m_MaxRollAngle*Mathf.Deg2Rad, m_MaxRollAngle*Mathf.Deg2Rad);
            float yawInput = 0;
            float rollInput = 0;
            if (!m_TakenOff)
            {
                // If the planes altitude is above m_TakeoffHeight we class this

```



```

as taken off
        if (m_AeroplaneController.Altitude > m_TakeoffHeight)
        {
            m_TakenOff = true;
        }
    }
    else
    {
        // now we have taken off to a safe height, we can use the rudder
and ailerons to yaw and roll
        yawInput = targetAngleYaw;
        rollInput = -(m_AeroplaneController.RollAngle -
desiredRoll)*m_RollSensitivity;
    }

    // adjust how fast the AI is changing the controls based on the speed.
Faster speed = faster on the controls.
    float currentSpeedEffect = 1 +
(m_AeroplaneController.ForwardSpeed*m_SpeedEffect);
    rollInput *= currentSpeedEffect;
    pitchInput *= currentSpeedEffect;
    yawInput *= currentSpeedEffect;

    // pass the current input to the plane (false = because AI never
uses air brakes!)
    m_AeroplaneController.Move(rollInput, pitchInput, yawInput,
throttleInput, false);
}
else
{
    // no target set, send zeroed input to the planeW
    m_AeroplaneController.Move(0, 0, 0, 0, false);
}
}

// allows other scripts to set the plane's target
public void SetTarget(Transform target)
{
    m_Target = target;
}
}
}using System;
using UnityEngine;

```

```
namespace UnityStandardAssets.Vehicles.Aeroplane
{
    public class AeroplaneAudio : MonoBehaviour
    {
        [Serializable]
        public class AdvancedSettings // A class for storing the advanced options.
        {
            public float engineMinDistance = 50f; // The min
            distance of the engine audio source.
            public float engineMaxDistance = 1000f; // The max
            distance of the engine audio source.
            public float engineDopplerLevel = 1f; // The doppler
            level of the engine audio source.
            [Range(0f, 1f)] public float engineMasterVolume = 0.5f; // An overall
            control of the engine sound volume.
            public float windMinDistance = 10f; // The min
            distance of the wind audio source.
            public float windMaxDistance = 100f; // The max
            distance of the wind audio source.
            public float windDopplerLevel = 1f; // The doppler
            level of the wind audio source.
            [Range(0f, 1f)] public float windMasterVolume = 0.5f; // An overall
            control of the wind sound volume.
        }

        [SerializeField] private AudioClip m_EngineSound; //
        Looped engine sound, whose pitch and volume are affected by the plane's throttle
        setting.
        [SerializeField] private float m_EngineMinThrottlePitch = 0.4f; //
        Pitch of the engine sound when at minimum throttle.
        [SerializeField] private float m_EngineMaxThrottlePitch = 2f; //
        Pitch of the engine sound when at maximum throttle.
        [SerializeField] private float m_EngineFwdSpeedMultiplier = 0.002f; //
        Additional multiplier for an increase in pitch of the engine from the plane's speed.
        [SerializeField] private AudioClip m_WindSound; //
        Looped wind sound, whose pitch and volume are affected by the plane's velocity.
        [SerializeField] private float m_WindBasePitch = 0.2f; //
        starting pitch for wind (when plane is at zero speed)
        [SerializeField] private float m_WindSpeedPitchFactor = 0.004f; //
        Relative increase in pitch of the wind from the plane's speed.
        [SerializeField] private float m_WindMaxSpeedVolume = 100; //
        the speed the aircraft must reach before the wind sound reaches maximum volume.
    }
}
```

```
[SerializeField] private AdvancedSetttings m_AdvancedSetttings = new  
AdvancedSetttings(); // container to make advanced settings appear as rollout in  
inspector
```

```
private AudioSource m_EngineSoundSource; // Reference to the AudioSource  
for the engine.
```

```
private AudioSource m_WindSoundSource; // Reference to the AudioSource  
for the wind.
```

```
private AeroplaneController m_Plane; // Reference to the aeroplane  
controller.
```

```
private Rigidbody m_Rigidbody;
```

```
private void Awake()
```

```
{
```

```
    // Set up the reference to the aeroplane controller.
```

```
    m_Plane = GetComponent<AeroplaneController>();
```

```
    m_Rigidbody = GetComponent<Rigidbody>();
```

```
    // Add the audiosources and get the references.
```

```
    m_EngineSoundSource = gameObject.AddComponent<AudioSource>();
```

```
    m_EngineSoundSource.playOnAwake = false;
```

```
    m_WindSoundSource = gameObject.AddComponent<AudioSource>();
```

```
    m_WindSoundSource.playOnAwake = false;
```

```
    // Assign clips to the audiosources.
```

```
    m_EngineSoundSource.clip = m_EngineSound;
```

```
    m_WindSoundSource.clip = m_WindSound;
```

```
    // Set the parameters of the audiosources.
```

```
    m_EngineSoundSource.minDistance =  
m_AdvancedSetttings.engineMinDistance;
```

```
    m_EngineSoundSource.maxDistance =  
m_AdvancedSetttings.engineMaxDistance;
```

```
    m_EngineSoundSource.loop = true;  
    m_EngineSoundSource.dopplerLevel =  
m_AdvancedSetttings.engineDopplerLevel;
```

```
    m_WindSoundSource.minDistance = m_AdvancedSetttings.windMinDistance;
```

```
    m_WindSoundSource.maxDistance = m_AdvancedSetttings.windMaxDistance;
```

```
    m_WindSoundSource.loop = true;
```

```
    m_WindSoundSource.dopplerLevel =  
m_AdvancedSetttings.windDopplerLevel;
```

```

        // call update here to set the sounds pitch and volumes before they
        actually play
        Update();

        // Start the sounds playing.
        m_EngineSoundSource.Play();
        m_WindSoundSource.Play();
    }

    private void Update()
    {
        // Find what proportion of the engine's power is being used.
        var enginePowerProportion = Mathf.InverseLerp(0,
m_Plane.MaxEnginePower, m_Plane.EnginePower);

        // Set the engine's pitch to be proportional to the engine's current
        power.
        m_EngineSoundSource.pitch = Mathf.Lerp(m_EngineMinThrottlePitch,
m_EngineMaxThrottlePitch, enginePowerProportion);

        // Increase the engine's pitch by an amount proportional to the
        aeroplane's forward speed.
        // (this makes the pitch increase when going into a dive!)
        m_EngineSoundSource.pitch +=
m_Plane.ForwardSpeed*m_EngineFwdSpeedMultiplier;

        // Set the engine's volume to be proportional to the engine's current
        power.
        m_EngineSoundSource.volume = Mathf.InverseLerp(0,
m_Plane.MaxEnginePower*m_AdvancedSettings.engineMasterVolume,
m_Plane.EnginePower);

        // Set the wind's pitch and volume to be proportional to the aeroplane's
        forward speed.
        float planeSpeed = m_Rigidbody.velocity.magnitude;
        m_WindSoundSource.pitch = m_WindBasePitch +
planeSpeed*m_WindSpeedPitchFactor;
        m_WindSoundSource.volume = Mathf.InverseLerp(0, m_WindMaxSpeedVolume,
planeSpeed)*m_AdvancedSettings.windMasterVolume;
    }
}

```

```
using System;
using UnityEngine;

namespace UnityStandardAssets.Vehicles.Aeroplane
{
    [RequireComponent(typeof (Rigidbody))]
    public class AeroplaneController : MonoBehaviour
    {
        [SerializeField] private float m_MaxEnginePower = 40f;           // The
maximum output of the engine.
        [SerializeField] private float m_Lift = 0.002f;                 // The
amount of lift generated by the aeroplane moving forwards.
        [SerializeField] private float m_ZeroLiftSpeed = 300;           // The speed
at which lift is no longer applied.
        [SerializeField] private float m_RollEffect = 1f;              // The
strength of effect for roll input.
        [SerializeField] private float m_PitchEffect = 1f;             // The
strength of effect for pitch input.
        [SerializeField] private float m_YawEffect = 0.2f;             // The
strength of effect for yaw input.
        [SerializeField] private float m_BankedTurnEffect = 0.5f;       // The
amount of turn from doing a banked turn.
        [SerializeField] private float m_AerodynamicEffect = 0.02f;     // How much
aerodynamics affect the speed of the aeroplane.
        [SerializeField] private float m_AutoTurnPitch = 0.5f;          // How much
the aeroplane automatically pitches when in a banked turn.
        [SerializeField] private float m_AutoRollLevel = 0.2f;          // How much
the aeroplane tries to level when not rolling.
        [SerializeField] private float m_AutoPitchLevel = 0.2f;         // How much
the aeroplane tries to level when not pitching.
        [SerializeField] private float m_AirBrakesEffect = 3f;          // How much
the air brakes effect the drag.
        [SerializeField] private float m_ThrottleChangeSpeed = 0.3f;    // The speed
with which the throttle changes.
        [SerializeField] private float m_DragIncreaseFactor = 0.001f;    // how much
drag should increase with speed.

        public float Altitude { get; private set; }                    // The
aeroplane's height above the ground.
        public float Throttle { get; private set; }                    // The
amount of throttle being used.
        public bool AirBrakes { get; private set; }                    // Whether
or not the air brakes are being applied.
        public float ForwardSpeed { get; private set; }                // How fast
```

```

the aeroplane is traveling in it's forward direction.
    public float EnginePower { get; private set; }           // How much
power the engine is being given.
    public float MaxEnginePower{ get { return m_MaxEnginePower; }} // The
maximum output of the engine.
    public float RollAngle { get; private set; }
    public float PitchAngle { get; private set; }
    public float RollInput { get; private set; }
    public float PitchInput { get; private set; }
    public float YawInput { get; private set; }
    public float ThrottleInput { get; private set; }

    private float m_OriginalDrag;           // The drag when the scene starts.
    private float m_OriginalAngularDrag;    // The angular drag when the scene
starts.
    private float m_AeroFactor;
    private bool m_Immobilized = false;     // used for making the plane
uncontrollable, i.e. if it has been hit or crashed.
    private float m_BankedTurnAmount;
    private Rigidbody m_Rigidbody;
    WheelCollider[] m_WheelColliders;

    private void Start()
    {
        m_Rigidbody = GetComponent<Rigidbody>();
        // Store original drag settings, these are modified during flight.
        m_OriginalDrag = m_Rigidbody.drag;
        m_OriginalAngularDrag = m_Rigidbody.angularDrag;

        for (int i = 0; i < transform.childCount; i++ )
        {
            foreach (var componentsInChild in
transform.GetChild(i).GetComponentsInChildren<WheelCollider>())
            {
                componentsInChild.motorTorque = 0.18f;
            }
        }
    }

    public void Move(float rollInput, float pitchInput, float yawInput, float
throttleInput, bool airBrakes)
    {

```

```
// transfer input parameters into properties.s
RollInput = rollInput;
PitchInput = pitchInput;
YawInput = yawInput;
ThrottleInput = throttleInput;
AirBrakes = airBrakes;

ClampInputs();

CalculateRollAndPitchAngles();

AutoLevel();

CalculateForwardSpeed();

ControlThrottle();

CalculateDrag();

CaluclateAerodynamicEffect();

CalculateLinearForces();

CalculateTorque();

CalculateAltitude();
}

private void ClampInputs()
{
    // clamp the inputs to -1 to 1 range
    RollInput = Mathf.Clamp(RollInput, -1, 1);
    PitchInput = Mathf.Clamp(PitchInput, -1, 1);
    YawInput = Mathf.Clamp(YawInput, -1, 1);
    ThrottleInput = Mathf.Clamp(ThrottleInput, -1, 1);
}

private void CalculateRollAndPitchAngles()
{
    // Calculate roll & pitch angles
    // Calculate the flat forward direction (with no y component).
    var flatForward = transform.forward;
```

```

        flatForward.y = 0;
        // If the flat forward vector is non-zero (which would only happen if
the plane was pointing exactly straight upwards)
        if (flatForward.sqrMagnitude > 0)
        {
            flatForward.Normalize();
            // calculate current pitch angle
            var localFlatForward =
transform.InverseTransformDirection(flatForward);
            PitchAngle = Mathf.Atan2(localFlatForward.y,
localFlatForward.z);
            // calculate current roll angle
            var flatRight = Vector3.Cross(Vector3.up, flatForward);
            var localFlatRight =
transform.InverseTransformDirection(flatRight);
            RollAngle = Mathf.Atan2(localFlatRight.y, localFlatRight.x);
        }
    }

    private void AutoLevel()
    {
        // The banked turn amount (between -1 and 1) is the sine of the roll
angle.
        // this is an amount applied to elevator input if the user is only using
the banking controls,
        // because that's what people expect to happen in games!
        m_BankedTurnAmount = Mathf.Sin(RollAngle);
        // auto level roll, if there's no roll input:
        if (RollInput == 0f)
        {
            RollInput = -RollAngle*m_AutoRollLevel;
        }
        // auto correct pitch, if no pitch input (but also apply the banked turn
amount)
        if (PitchInput == 0f)
        {
            PitchInput = -PitchAngle*m_AutoPitchLevel;
            PitchInput -=
Mathf.Abs(m_BankedTurnAmount*m_BankedTurnAmount*m_AutoTurnPitch);
        }
    }
}

```



```

private void CalculateForwardSpeed()
{
    // Forward speed is the speed in the planes's forward direction (not
the same as its velocity, eg if falling in a stall)
    var localVelocity =
transform.InverseTransformDirection(m_Rigidbody.velocity);
    ForwardSpeed = Mathf.Max(0, localVelocity.z);
}

private void ControlThrottle()
{
    // override throttle if immobilized
    if (m_Immobilized)
    {
        ThrottleInput = -0.5f;
    }

    // Adjust throttle based on throttle input (or immobilized state)
    Throttle = Mathf.Clamp01(Throttle +
ThrottleInput*Time.deltaTime*m_ThrottleChangeSpeed);

    // current engine power is just:
    EnginePower = Throttle*m_MaxEnginePower;
}

private void CalculateDrag()
{
    // increase the drag based on speed, since a constant drag doesn't seem
"Real" (tm) enough
    float extraDrag =
m_Rigidbody.velocity.magnitude*m_DragIncreaseFactor;
    // Air brakes work by directly modifying drag. This part is actually
pretty realistic!
    m_Rigidbody.drag = (AirBrakes ? (m_OriginalDrag +
extraDrag)*m_AirBrakesEffect : m_OriginalDrag + extraDrag);
    // Forward speed affects angular drag - at high forward speed, it's much
harder for the plane to spin
    m_Rigidbody.angularDrag = m_OriginalAngularDrag*ForwardSpeed;
}

private void CaluclateAerodynamicEffect()

```

```
{
    // "Aerodynamic" calculations. This is a very simple approximation of
the effect that a plane
    // will naturally try to align itself in the direction that it's facing
when moving at speed.
    // Without this, the plane would behave a bit like the asteroids
spaceship!
    if (m_Rigidbody.velocity.magnitude > 0)
    {
        // compare the direction we're pointing with the direction we're
moving:
        m_AeroFactor = Vector3.Dot(transform.forward,
m_Rigidbody.velocity.normalized);
        // multiplied by itself results in a desirable rolloff curve of the
effect
        m_AeroFactor *= m_AeroFactor;
        // Finally we calculate a new velocity by bending the current
velocity direction towards
        // the the direction the plane is facing, by an amount based on this
aeroFactor
        var newVelocity = Vector3.Lerp(m_Rigidbody.velocity,
transform.forward*ForwardSpeed,

m_AeroFactor*ForwardSpeed*m_AerodynamicEffect*Time.deltaTime);
        m_Rigidbody.velocity = newVelocity;

        // also rotate the plane towards the direction of movement - this
should be a very small effect, but means the plane ends up
        // pointing downwards in a stall
        m_Rigidbody.rotation = Quaternion.Slerp(m_Rigidbody.rotation,

Quaternion.LookRotation(m_Rigidbody.velocity, transform.up),

m_AerodynamicEffect*Time.deltaTime);
    }
}

private void CalculateLinearForces()
{
    // Now calculate forces acting on the aeroplane:
    // we accumulate forces into this variable:
    var forces = Vector3.zero;
    // Add the engine power in the forward direction
```

```

        forces += EnginePower*transform.forward;
        // The direction that the lift force is applied is at right angles to
the plane's velocity (usually, this is 'up'!)
        var liftDirection = Vector3.Cross(m_Rigidbody.velocity,
transform.right).normalized;
        // The amount of lift drops off as the plane increases speed - in reality
this occurs as the pilot retracts the flaps
        // shortly after takeoff, giving the plane less drag, but less lift.
Because we don't simulate flaps, this is
        // a simple way of doing it automatically:
        var zeroLiftFactor = Mathf.InverseLerp(m_ZeroLiftSpeed, 0,
ForwardSpeed);
        // Calculate and add the lift power
        var liftPower =
ForwardSpeed*ForwardSpeed*m_Lift*zeroLiftFactor*m_AeroFactor;
        forces += liftPower*liftDirection;
        // Apply the calculated forces to the the Rigidbody
        m_Rigidbody.AddForce(forces);
    }

```

```

private void CalculateTorque()
{
    // We accumulate torque forces into this variable:
    var torque = Vector3.zero;
    // Add torque for the pitch based on the pitch input.
    torque += PitchInput*m_PitchEffect*transform.right;
    // Add torque for the yaw based on the yaw input.
    torque += YawInput*m_YawEffect*transform.up;
    // Add torque for the roll based on the roll input.
    torque += -RollInput*m_RollEffect*transform.forward;
    // Add torque for banked turning.
    torque += m_BankedTurnAmount*m_BankedTurnEffect*transform.up;
    // The total torque is multiplied by the forward speed, so the controls
have more effect at high speed,
    // and little effect at low speed, or when not moving in the direction
of the nose of the plane
    // (i.e. falling while stalled)
    m_Rigidbody.AddTorque(torque*ForwardSpeed*m_AeroFactor);
}

```

```

private void CalculateAltitude()
{

```

```
// Altitude calculations - we raycast downwards from the aeroplane
// starting a safe distance below the plane to avoid colliding with any
of the plane's own colliders
var ray = new Ray(transform.position - Vector3.up*10, -Vector3.up);
RaycastHit hit;
Altitude = Physics.Raycast(ray, out hit) ? hit.distance + 10 :
transform.position.y;
}

// Immobilize can be called from other objects, for example if this plane
is hit by a weapon and should become uncontrollable
public void Immobilize()
{
    m_Immobilized = true;
}

// Reset is called via the ObjectResetter script, if present.
public void Reset()
{
    m_Immobilized = false;
}
}
}using System;
using UnityEngine;

namespace UnityStandardAssets.Vehicles.Aeroplane
{
    public class AeroplaneControlSurfaceAnimator : MonoBehaviour
    {
        [SerializeField] private float m_Smoothing = 5f; // The smoothing applied
to the movement of control surfaces.
        [SerializeField] private ControlSurface[] m_ControlSurfaces; //
Collection of control surfaces.

        private AeroplaneController m_Plane; // Reference to the aeroplane
controller.

        private void Start()
        {
            // Get the reference to the aeroplane controller.
            m_Plane = GetComponent<AeroplaneController>();
        }
    }
}
```

```

        // Store the original local rotation of each surface, so we can rotate
relative to this
        foreach (var surface in m_ControlSurfaces)
        {
            surface.originalLocalRotation = surface.transform.localRotation;
        }
    }

    private void Update()
    {
        foreach (var surface in m_ControlSurfaces)
        {
            switch (surface.type)
            {
                case ControlSurface.Type.Aileron:
                {
                    // Ailerons rotate around the x axis, according to the
plane's roll input
                    Quaternion rotation =
Quaternion.Euler(surface.amount*m_Plane.RollInput, 0f, 0f);
                    RotateSurface(surface, rotation);
                    break;
                }
                case ControlSurface.Type.Elevator:
                {
                    // Elevators rotate negatively around the x axis,
according to the plane's pitch input
                    Quaternion rotation =
Quaternion.Euler(surface.amount*-m_Plane.PitchInput, 0f, 0f);
                    RotateSurface(surface, rotation);
                    break;
                }
                case ControlSurface.Type.Rudder:
                {
                    // Rudders rotate around their y axis, according to the
plane's yaw input
                    Quaternion rotation = Quaternion.Euler(0f,
surface.amount*m_Plane.YawInput, 0f);
                    RotateSurface(surface, rotation);
                    break;
                }
                case ControlSurface.Type.RuddervatorPositive:

```

```

        {
            // Ruddervators are a combination of rudder and
elevador, and rotate
            // around their z axis by a combination of the yaw and
pitch input

            float r = m_Plane.YawInput + m_Plane.PitchInput;
Quaternion rotation = Quaternion.Euler(0f, 0f,
surface.amount*r);

            RotateSurface(surface, rotation);
            break;
        }
        case ControlSurface.Type.RuddervatorNegative:
        {
            // ... and because ruddervators are "special", we need
a negative version too. >_<
            float r = m_Plane.YawInput - m_Plane.PitchInput;
Quaternion rotation = Quaternion.Euler(0f, 0f,
surface.amount*r);

            RotateSurface(surface, rotation);
            break;
        }
    }
}

private void RotateSurface(ControlSurface surface, Quaternion rotation)
{
    // Create a target which is the surface's original rotation, rotated
by the input.
    Quaternion target = surface.originalLocalRotation*rotation;

    // Slerp the surface's rotation towards the target rotation.
    surface.transform.localRotation =
Quaternion.Slerp(surface.transform.localRotation, target,
m_Smoothing*Time.deltaTime);
}

// This class presents a nice custom structure in which to define each of
the plane's control surfaces to animate.
// They show up in the inspector as an array.
[Serializable]

```

```

        public class ControlSurface // Control surfaces represent the different
        flaps of the aeroplane.
        {
            public enum Type // Flaps differ in position and rotation and are
            represented by different types.
            {
                Aileron, // Horizontal flaps on the wings, rotate on the x axis.
                Elevator, // Horizontal flaps used to adjusting the pitch of a plane,
                rotate on the x axis.
                Rudder, // Vertical flaps on the tail, rotate on the y axis.
                RuddervatorNegative, // Combination of rudder and elevator.
                RuddervatorPositive, // Combination of rudder and elevator.
            }

            public Transform transform; // The transform of the control surface.
            public float amount; // The amount by which they can rotate.
            public Type type; // The type of control surface.

            [HideInInspector] public Quaternion originalLocalRotation; // The
            rotation of the surface at the start.
        }
using System;
using UnityEngine;

namespace UnityStandardAssets.Vehicles.Aeroplane
{
    public class AeroplanePropellerAnimator : MonoBehaviour
    {
        [SerializeField] private Transform m_PropellorModel;
        // The model of the the aeroplane's propellor.
        [SerializeField] private Transform m_PropellorBlur;
        // The plane used for the blurred propellor textures.
        [SerializeField] private Texture2D[] m_PropellorBlurTextures;
        // An array of increasingly blurred propellor textures.
        [SerializeField] [Range(0f, 1f)] private float m_ThrottleBlurStart = 0.25f;
        // The point at which the blurred textures start.
        [SerializeField] [Range(0f, 1f)] private float m_ThrottleBlurEnd = 0.5f;
        // The point at which the blurred textures stop changing.
        [SerializeField] private float m_MaxRpm = 2000;
        // The maximum speed the propellor can turn at.

        private AeroplaneController m_Plane; // Reference to the aeroplane
        controller.
        private int m_PropellorBlurState = -1; // To store the state of the

```

```
blurred textures.

    private const float k_RpmToDps = 60f;    // For converting from revs per
minute to degrees per second.
    private Renderer m_PropellorModelRenderer;
    private Renderer m_PropellorBlurRenderer;

    private void Awake()
    {
        // Set up the reference to the aeroplane controller.
        m_Plane = GetComponent<AeroplaneController>();

        m_PropellorModelRenderer =
m_PropellorModel.GetComponent<Renderer>();
        m_PropellorBlurRenderer = m_PropellorBlur.GetComponent<Renderer>();

        // Set the propellor blur gameobject's parent to be the propellor.
        m_PropellorBlur.parent = m_PropellorModel;
    }

    private void Update()
    {
        // Rotate the propellor model at a rate proportional to the throttle.
        m_PropellorModel.Rotate(0,
m_MaxRpm*m_Plane.Throttle*Time.deltaTime*k_RpmToDps, 0);

        // Create an integer for the new state of the blur textures.
        var newBlurState = 0;

        // choose between the blurred textures, if the throttle is high enough
        if (m_Plane.Throttle > m_ThrottleBlurStart)
        {
            var throttleBlurProportion =
Mathf.InverseLerp(m_ThrottleBlurStart, m_ThrottleBlurEnd, m_Plane.Throttle);
            newBlurState =
Mathf.FloorToInt(throttleBlurProportion*(m_PropellorBlurTextures.Length - 1));
        }

        // If the blur state has changed
        if (newBlurState != m_PropellorBlurState)
        {
            m_PropellorBlurState = newBlurState;
        }
    }
}
```



```
        if (m_PropellorBlurState == 0)
        {
            // switch to using the 'real' propellor model
            m_PropellorModelRenderer.enabled = true;
            m_PropellorBlurRenderer.enabled = false;
        }
        else
        {
            // Otherwise turn off the propellor model and turn on the blur.
            m_PropellorModelRenderer.enabled = false;
            m_PropellorBlurRenderer.enabled = true;

            // set the appropriate texture from the blur array
            m_PropellorBlurRenderer.material.mainTexture =
m_PropellorBlurTextures[m_PropellorBlurState];
        }
    }
}

}

using System;
using UnityEngine;
using UnityStandardAssets.CrossPlatformInput;

namespace UnityStandardAssets.Vehicles.Aeroplane
{
    [RequireComponent(typeof (AeroplaneController))]
    public class AeroplaneUserControl2Axis : MonoBehaviour
    {
        // these max angles are only used on mobile, due to the way pitch and roll
input are handled
        public float maxRollAngle = 80;
        public float maxPitchAngle = 80;

        // reference to the aeroplane that we're controlling
        private AeroplaneController m_Aeroplane;

        private void Awake()
        {
            // Set up the reference to the aeroplane controller.
            m_Aeroplane = GetComponent<AeroplaneController>();
        }
    }
}
```

```
private void FixedUpdate()
{
    // Read input for the pitch, yaw, roll and throttle of the aeroplane.
    float roll = CrossPlatformInputManager.GetAxis("Horizontal");
    float pitch = CrossPlatformInputManager.GetAxis("Vertical");
    bool airBrakes = CrossPlatformInputManager.GetButton("Fire1");

    // auto throttle up, or down if braking.
    float throttle = airBrakes ? -1 : 1;
#if MOBILE_INPUT
    AdjustInputForMobileControls(ref roll, ref pitch, ref throttle);
#endif

    // Pass the input to the aeroplane
    m_Aeroplane.Move(roll, pitch, 0, throttle, airBrakes);
}

private void AdjustInputForMobileControls(ref float roll, ref float pitch,
ref float throttle)
{
    // because mobile tilt is used for roll and pitch, we help out by
    // assuming that a centered level device means the user
    // wants to fly straight and level!

    // this means on mobile, the input represents the *desired* roll angle
of the aeroplane,
    // and the roll input is calculated to achieve that.
    // whereas on non-mobile, the input directly controls the roll of the
aeroplane.

    float intendedRollAngle = roll*maxRollAngle*Mathf.Deg2Rad;
    float intendedPitchAngle = pitch*maxPitchAngle*Mathf.Deg2Rad;
    roll = Mathf.Clamp((intendedRollAngle - m_Aeroplane.RollAngle), -1,
1);
    pitch = Mathf.Clamp((intendedPitchAngle - m_Aeroplane.PitchAngle), -1,
1);

    // similarly, the throttle axis input is considered to be the desired
absolute value, not a relative change to current throttle.
    float intendedThrottle = throttle*0.5f + 0.5f;
    throttle = Mathf.Clamp(intendedThrottle - m_Aeroplane.Throttle, -1,
1);
}
```

```
    }  
}  
using System;  
using UnityEngine;  
using UnityStandardAssets.CrossPlatformInput;  
  
namespace UnityStandardAssets.Vehicles.Aeroplane  
{  
    [RequireComponent(typeof (AeroplaneController))]  
    public class AeroplaneUserControl4Axis : MonoBehaviour  
    {  
        // these max angles are only used on mobile, due to the way pitch and roll  
input are handled  
        public float maxRollAngle = 80;  
        public float maxPitchAngle = 80;  
  
        // reference to the aeroplane that we're controlling  
        private AeroplaneController m_Aeroplane;  
        private float m_Throttle;  
        private bool m_AirBrakes;  
        private float m_Yaw;  
  
        private void Awake()  
        {  
            // Set up the reference to the aeroplane controller.  
            m_Aeroplane = GetComponent<AeroplaneController>();  
        }  
  
        private void FixedUpdate()  
        {  
            // Read input for the pitch, yaw, roll and throttle of the aeroplane.  
            float roll = CrossPlatformInputManager.GetAxis("Mouse X");  
            float pitch = CrossPlatformInputManager.GetAxis("Mouse Y");  
            m_AirBrakes = CrossPlatformInputManager.GetButton("Fire1");  
            m_Yaw = CrossPlatformInputManager.GetAxis("Horizontal");  
            m_Throttle = CrossPlatformInputManager.GetAxis("Vertical");  
#if MOBILE_INPUT  
            AdjustInputForMobileControls(ref roll, ref pitch, ref m_Throttle);  
#endif  
            // Pass the input to the aeroplane  
            m_Aeroplane.Move(roll, pitch, m_Yaw, m_Throttle, m_AirBrakes);  
        }  
    }  
}
```

```
private void AdjustInputForMobileControls(ref float roll, ref float pitch,
ref float throttle)
{
    // because mobile tilt is used for roll and pitch, we help out by
    // assuming that a centered level device means the user
    // wants to fly straight and level!

    // this means on mobile, the input represents the *desired* roll angle
of the aeroplane,
    // and the roll input is calculated to achieve that.
    // whereas on non-mobile, the input directly controls the roll of the
aeroplane.

    float intendedRollAngle = roll*maxRollAngle*Mathf.Deg2Rad;
    float intendedPitchAngle = pitch*maxPitchAngle*Mathf.Deg2Rad;
    roll = Mathf.Clamp((intendedRollAngle - m_Aeroplane.RollAngle), -1,
1);
    pitch = Mathf.Clamp((intendedPitchAngle - m_Aeroplane.PitchAngle), -1,
1);
}
}
}using System;
using UnityEngine;

namespace UnityStandardAssets.Effects
{
    [RequireComponent(typeof (SphereCollider))]
    public class AfterburnerPhysicsForce : MonoBehaviour
    {
        public float effectAngle = 15;
        public float effectWidth = 1;
        public float effectDistance = 10;
        public float force = 10;

        private Collider[] m_Cols;
        private SphereCollider m_Sphere;

        private void OnEnable()
        {
            m_Sphere = (GetComponent<Collider>() as SphereCollider);
        }
    }
}
```

```
private void FixedUpdate()
{
    m_Cols = Physics.OverlapSphere(transform.position + m_Sphere.center,
    m_Sphere.radius);
    for (int n = 0; n < m_Cols.Length; ++n)
    {
        if (m_Cols[n].attachedRigidbody != null)
        {
            Vector3 localPos =
            transform.InverseTransformPoint(m_Cols[n].transform.position);
            localPos = Vector3.MoveTowards(localPos, new Vector3(0, 0,
            localPos.z), effectWidth*0.5f);
            float angle = Mathf.Abs(Mathf.Atan2(localPos.x,
            localPos.z)*Mathf.Rad2Deg);
            float falloff = Mathf.InverseLerp(effectDistance, 0,
            localPos.magnitude);
            falloff *= Mathf.InverseLerp(effectAngle, 0, angle);
            Vector3 delta = m_Cols[n].transform.position -
            transform.position;

            m_Cols[n].attachedRigidbody.AddForceAtPosition(delta.normalized*force*falloff,

            Vector3.Lerp(m_Cols[n].transform.position,

            transform.TransformPoint(0, 0, localPos.z),

            0.1f));
        }
    }
}

private void OnDrawGizmosSelected()
{
    //check for editor time simulation to avoid null ref
    if(m_Sphere == null)
        m_Sphere = (GetComponent<Collider>() as SphereCollider);

    m_Sphere.radius = effectDistance*.5f;
    m_Sphere.center = new Vector3(0, 0, effectDistance*.5f);
    var directions = new Vector3[] {Vector3.up, -Vector3.up, Vector3.right,
    -Vector3.right};
}
```

```

        var perpDirections = new Vector3[] { -Vector3.right, Vector3.right,
Vector3.up, -Vector3.up };
        Gizmos.color = new Color(0, 1, 0, 0.5f);
        for (int n = 0; n < 4; ++n)
        {
            Vector3 origin = transform.position +
transform.rotation*directions[n]*effectWidth*0.5f;

            Vector3 direction =

transform.TransformDirection(Quaternion.AngleAxis(effectAngle,
perpDirections[n])*Vector3.forward);

            Gizmos.DrawLine(origin, origin + direction*m_Sphere.radius*2);
        }
    }
}
using System;
using UnityEngine;

namespace UnityStandardAssets.Characters.ThirdPerson
{
    [RequireComponent(typeof (UnityEngine.AI.NavMeshAgent))]
    [RequireComponent(typeof (ThirdPersonCharacter))]
    public class AICharacterControl : MonoBehaviour
    {
        public UnityEngine.AI.NavMeshAgent agent { get; private set; }
        // the navmesh agent required for the path finding
        public ThirdPersonCharacter character { get; private set; } // the character
we are controlling
        public Transform target; // target to
aim for

        private void Start()
        {
            // get the components on the object we need ( should not be null due
to require component so no need to check )
            agent = GetComponentInChildren<UnityEngine.AI.NavMeshAgent>();
            character = GetComponent<ThirdPersonCharacter>();

            agent.updateRotation = false;
            agent.updatePosition = true;

```

```
    }

    private void Update()
    {
        if (target != null)
            agent.SetDestination(target.position);

        if (agent.remainingDistance > agent.stoppingDistance)
            character.Move(agent.desiredVelocity, false, false);
        else
            character.Move(Vector3.zero, false, false);
    }

    public void SetTarget(Transform target)
    {
        this.target = target;
    }
}

}using UnityEngine.PostProcessing;

namespace UnityEditor.PostProcessing
{
    using Settings = AmbientOcclusionModel.Settings;

    [PostProcessingModelEditor(typeof(AmbientOcclusionModel))]
    public class AmbientOcclusionModelEditor : PostProcessingModelEditor
    {
        SerializedProperty m_Intensity;
        SerializedProperty m_Radius;
        SerializedProperty m_SampleCount;
        SerializedProperty m_Downsampling;
        SerializedProperty m_ForceForwardCompatibility;
        SerializedProperty m_AmbientOnly;
        SerializedProperty m_HighPrecision;

        public override void OnEnable()
        {
            m_Intensity = FindSetting((Settings x) => x.intensity);
            m_Radius = FindSetting((Settings x) => x.radius);
            m_SampleCount = FindSetting((Settings x) => x.sampleCount);
            m_Downsampling = FindSetting((Settings x) => x.downsampling);
            m_ForceForwardCompatibility = FindSetting((Settings x) =>
```

```

x.forceForwardCompatibility);
    m_AmbientOnly = FindSetting((Settings x) => x.ambientOnly);
    m_HighPrecision = FindSetting((Settings x) => x.highPrecision);
}

public override void OnInspectorGUI()
{
    EditorGUILayout.PropertyField(m_Intensity);
    EditorGUILayout.PropertyField(m_Radius);
    EditorGUILayout.PropertyField(m_SampleCount);
    EditorGUILayout.PropertyField(m_Downsampling);
    EditorGUILayout.PropertyField(m_ForceForwardCompatibility);
    EditorGUILayout.PropertyField(m_HighPrecision,
EditorGUILayoutHelper.GetContent("High Precision (Forward)"));

    using (new
EditorGUI.DisabledGroupScope(m_ForceForwardCompatibility.boolValue))
        EditorGUILayout.PropertyField(m_AmbientOnly,
EditorGUILayoutHelper.GetContent("Ambient Only (Deferred + HDR)"));
}
}
}
using System;
using UnityEngine;

namespace UnityStandardAssets.ImageEffects
{
    public enum AAMode
    {
        FXAA2 = 0,
        FXAA3Console = 1,
        FXAA1PresetA = 2,
        FXAA1PresetB = 3,
        NFAA = 4,
        SSAA = 5,
        DLAA = 6,
    }

    [ExecuteInEditMode]
    [RequireComponent(typeof(Camera))]
    [AddComponentMenu("Image Effects/Other/Antialiasing")]
    public class Antialiasing : PostEffectsBase
    {
        public AAMode mode = AAMode.FXAA3Console;
    }
}

```



```
public bool showGeneratedNormals = false;
public float offsetScale = 0.2f;
public float blurRadius = 18.0f;

public float edgeThresholdMin = 0.05f;
public float edgeThreshold = 0.2f;
public float edgeSharpness = 4.0f;

public bool dlaaSharp = false;

public Shader ssaaShader;
private Material ssaa;
public Shader dlaaShader;
private Material dlaa;
public Shader nfaaShader;
private Material nfaa;
public Shader shaderFXAAPreset2;
private Material materialFXAAPreset2;
public Shader shaderFXAAPreset3;
private Material materialFXAAPreset3;
public Shader shaderFXAAII;
private Material materialFXAAII;
public Shader shaderFXAAIII;
private Material materialFXAAIII;

public Material CurrentAAMaterial()
{
    Material returnValue = null;

    switch (mode)
    {
        case AAMode.FXAA3Console:
            returnValue = materialFXAAIII;
            break;
        case AAMode.FXAA2:
            returnValue = materialFXAAII;
            break;
        case AAMode.FXAA1PresetA:
            returnValue = materialFXAAPreset2;
            break;
        case AAMode.FXAA1PresetB:
            returnValue = materialFXAAPreset3;
```

```
        break;
    case AAMode.NFAA:
        returnValue = nfaa;
        break;
    case AAMode.SSAA:
        returnValue = ssaa;
        break;
    case AAMode.DLAA:
        returnValue = dlaa;
        break;
    default:
        returnValue = null;
        break;
}

return returnValue;
}

public override bool CheckResources()
{
    CheckSupport(false);

    materialFXAAPreset2 = CreateMaterial(shaderFXAAPreset2,
materialFXAAPreset2);
    materialFXAAPreset3 = CreateMaterial(shaderFXAAPreset3,
materialFXAAPreset3);
    materialFXAAII = CreateMaterial(shaderFXAAII, materialFXAAII);
    materialFXAAIII = CreateMaterial(shaderFXAAIII, materialFXAAIII);
    nfaa = CreateMaterial(nfaaShader, nfaa);
    ssaa = CreateMaterial(ssaaShader, ssaa);
    dlaa = CreateMaterial(dlaaShader, dlaa);

    if (!ssaaShader.isSupported)
    {
        NotSupported();
        ReportAutoDisable();
    }

    return isSupported;
}

public void OnRenderImage(RenderTexture source, RenderTexture
```

```
destination)
{
    if (CheckResources() == false)
    {
        Graphics.Blit(source, destination);
        return;
    }

    // -----
    // FXAA antialiasing modes

    if (mode == AAMode.FXAA3Console && (materialFXAAIII != null))
    {
        materialFXAAIII.SetFloat("_EdgeThresholdMin",
edgeThresholdMin);
        materialFXAAIII.SetFloat("_EdgeThreshold", edgeThreshold);
        materialFXAAIII.SetFloat("_EdgeSharpness", edgeSharpness);

        Graphics.Blit(source, destination, materialFXAAIII);
    }
    else if (mode == AAMode.FXAA1PresetB && (materialFXAAPreset3 != null))
    {
        Graphics.Blit(source, destination, materialFXAAPreset3);
    }
    else if (mode == AAMode.FXAA1PresetA && materialFXAAPreset2 != null)
    {
        source.anisoLevel = 4;
        Graphics.Blit(source, destination, materialFXAAPreset2);
        source.anisoLevel = 0;
    }
    else if (mode == AAMode.FXAA2 && materialFXAAII != null)
    {
        Graphics.Blit(source, destination, materialFXAAII);
    }
    else if (mode == AAMode.SSAA && ssaa != null)
    {
        //
        -----

        // SSAA antialiasing
        Graphics.Blit(source, destination, ssaa);
    }
    else if (mode == AAMode.DLAA && dlaa != null)
    {
        //
```

```
        // DLAA antialiasing

        source.anisoLevel = 0;
        RenderTexture interim = RenderTexture.GetTemporary(source.width,
source.height);
        Graphics.Blit(source, interim, dlaa, 0);
        Graphics.Blit(interim, destination, dlaa, dlaaSharp ? 2 : 1);
        RenderTexture.ReleaseTemporary(interim);
    }
    else if (mode == AAMode.NFAA && nfaa != null)
    {
        //

        // nfaa antialiasing

        source.anisoLevel = 0;

        nfaa.SetFloat("_OffsetScale", offsetScale);
        nfaa.SetFloat("_BlurRadius", blurRadius);

        Graphics.Blit(source, destination, nfaa, showGeneratedNormals ?
1 : 0);
    }
    else
    {
        // none of the AA is supported, fallback to a simple blit
        Graphics.Blit(source, destination);
    }
}

}using System;

namespace UnityEngine.PostProcessing
{
    [Serializable]
    public class AntialiasingModel : PostProcessingModel
    {
        public enum Method
        {
            Fxaa,
            Taa
        }
    }
}
```

```
// Most settings aren't exposed to the user anymore, presets are enough.
Still, I'm leaving
// the tooltip attributes in case an user wants to customize each preset.

#region FXAA Settings
public enum FxaaPreset
{
    ExtremePerformance,
    Performance,
    Default,
    Quality,
    ExtremeQuality
}

[Serializable]
public struct FxaaQualitySettings
{
    [Tooltip("The amount of desired sub-pixel aliasing removal. Effects the
sharpeness of the output.")]
    [Range(0f, 1f)]
    public float subpixelAliasingRemovalAmount;

    [Tooltip("The minimum amount of local contrast required to qualify a
region as containing an edge.")]
    [Range(0.063f, 0.333f)]
    public float edgeDetectionThreshold;

    [Tooltip("Local contrast adaptation value to disallow the algorithm
from executing on the darker regions.")]
    [Range(0f, 0.0833f)]
    public float minimumRequiredLuminance;

    public static FxaaQualitySettings[] presets =
    {
        // ExtremePerformance
        new FxaaQualitySettings
        {
            subpixelAliasingRemovalAmount = 0f,
            edgeDetectionThreshold = 0.333f,
            minimumRequiredLuminance = 0.0833f
        },

        // Performance
        new FxaaQualitySettings
```

```
{
    subpixelAliasingRemovalAmount = 0.25f,
    edgeDetectionThreshold = 0.25f,
    minimumRequiredLuminance = 0.0833f
},

// Default
new FxaaQualitySettings
{
    subpixelAliasingRemovalAmount = 0.75f,
    edgeDetectionThreshold = 0.166f,
    minimumRequiredLuminance = 0.0833f
},

// Quality
new FxaaQualitySettings
{
    subpixelAliasingRemovalAmount = 1f,
    edgeDetectionThreshold = 0.125f,
    minimumRequiredLuminance = 0.0625f
},

// ExtremeQuality
new FxaaQualitySettings
{
    subpixelAliasingRemovalAmount = 1f,
    edgeDetectionThreshold = 0.063f,
    minimumRequiredLuminance = 0.0312f
}
};
}

[Serializable]
public struct FxaaConsoleSettings
{
    [Tooltip("The amount of spread applied to the sampling coordinates while sampling for subpixel information.")]
    [Range(0.33f, 0.5f)]
    public float subpixelSpreadAmount;

    [Tooltip("This value dictates how sharp the edges in the image are kept; a higher value implies sharper edges.")]
    [Range(2f, 8f)]
    public float edgeSharpnessAmount;
```

```
[Tooltip("The minimum amount of local contrast required to qualify a
region as containing an edge.")]
[Range(0.125f, 0.25f)]
public float edgeDetectionThreshold;

[Tooltip("Local contrast adaptation value to disallow the algorithm
from executing on the darker regions.")]
[Range(0.04f, 0.06f)]
public float minimumRequiredLuminance;

public static FxaaConsoleSettings[] presets =
{
    // ExtremePerformance
    new FxaaConsoleSettings
    {
        subpixelSpreadAmount = 0.33f,
        edgeSharpnessAmount = 8f,
        edgeDetectionThreshold = 0.25f,
        minimumRequiredLuminance = 0.06f
    },

    // Performance
    new FxaaConsoleSettings
    {
        subpixelSpreadAmount = 0.33f,
        edgeSharpnessAmount = 8f,
        edgeDetectionThreshold = 0.125f,
        minimumRequiredLuminance = 0.06f
    },

    // Default
    new FxaaConsoleSettings
    {
        subpixelSpreadAmount = 0.5f,
        edgeSharpnessAmount = 8f,
        edgeDetectionThreshold = 0.125f,
        minimumRequiredLuminance = 0.05f
    },

    // Quality
    new FxaaConsoleSettings
    {
        subpixelSpreadAmount = 0.5f,
```

```

        edgeSharpnessAmount = 4f,
        edgeDetectionThreshold = 0.125f,
        minimumRequiredLuminance = 0.04f
    },

    // ExtremeQuality
    new FxaaConsoleSettings
    {
        subpixelSpreadAmount = 0.5f,
        edgeSharpnessAmount = 2f,
        edgeDetectionThreshold = 0.125f,
        minimumRequiredLuminance = 0.04f
    }
};
}

[Serializable]
public struct FxaaSettings
{
    public FxaaPreset preset;

    public static FxaaSettings defaultSettings
    {
        get
        {
            return new FxaaSettings
            {
                preset = FxaaPreset.Default
            };
        }
    }
}

#endregion

#region TAA Settings
[Serializable]
public struct TaaSettings
{
    [Tooltip("The diameter (in texels) inside which jitter samples are
spread. Smaller values result in crisper but more aliased output, while larger values
result in more stable but blurrier output.")
    [Range(0.1f, 1f)]
    public float jitterSpread;
}

```



```
        [Tooltip("Controls the amount of sharpening applied to the color  
buffer.")]  
        [Range(0f, 3f)]  
        public float sharpen;
```

```
        [Tooltip("The blend coefficient for a stationary fragment. Controls the  
percentage of history sample blended into the final color.")]  
        [Range(0f, 0.99f)]  
        public float stationaryBlending;
```

```
        [Tooltip("The blend coefficient for a fragment with significant motion.  
Controls the percentage of history sample blended into the final color.")]  
        [Range(0f, 0.99f)]  
        public float motionBlending;
```

```
        public static TaaSettings defaultSettings  
        {  
            get  
            {  
                return new TaaSettings  
                {  
                    jitterSpread = 0.75f,  
                    sharpen = 0.3f,  
                    stationaryBlending = 0.95f,  
                    motionBlending = 0.85f  
                };  
            }  
        }  
    }  
#endregion
```

```
[Serializable]  
public struct Settings  
{  
    public Method method;  
    public FxaaSettings fxaaSettings;  
    public TaaSettings taaSettings;  
  
    public static Settings defaultSettings  
    {  
        get  
        {  
            return new Settings  
            {
```

```
        method = Method.Fxaa,
        fxaaSettings = FxaaSettings.defaultSettings,
        taaSettings = TaaSettings.defaultSettings
    };
    }
}

[SerializeField]
Settings m_Settings = Settings.defaultSettings;
public Settings settings
{
    get { return m_Settings; }
    set { m_Settings = value; }
}

public override void Reset()
{
    m_Settings = Settings.defaultSettings;
}
}

using UnityEngine;
using UnityEngine.PostProcessing;

namespace UnityEditor.PostProcessing
{
    using Method = AntialiasingModel.Method;
    using Settings = AntialiasingModel.Settings;

    [PostProcessingModelEditor(typeof(AntialiasingModel))]
    public class AntialiasingModelEditor : PostProcessingModelEditor
    {
        SerializedProperty m_Method;

        SerializedProperty m_FxaaPreset;

        SerializedProperty m_TaaJitterSpread;
        SerializedProperty m_TaaSharpen;
        SerializedProperty m_TaaStationaryBlending;
        SerializedProperty m_TaaMotionBlending;

        static string[] s_MethodNames =
        {
```

```
        "Fast Approximate Anti-aliasing",
        "Temporal Anti-aliasing"
    };

    public override void OnEnable()
    {
        m_Method = FindSetting((Settings x) => x.method);

        m_FxaaPreset = FindSetting((Settings x) => x.fxaaSettings.preset);

        m_TaaJitterSpread = FindSetting((Settings x) =>
x.taaSettings.jitterSpread);
        m_TaaSharpen = FindSetting((Settings x) => x.taaSettings.sharpen);
        m_TaaStationaryBlending = FindSetting((Settings x) =>
x.taaSettings.stationaryBlending);
        m_TaaMotionBlending = FindSetting((Settings x) =>
x.taaSettings.motionBlending);
    }

    public override void OnInspectorGUI()
    {
        m_Method.intValue = EditorGUILayout.Popup("Method",
m_Method.intValue, s_MethodNames);

        if (m_Method.intValue == (int)Method.Fxaa)
        {
            EditorGUILayout.PropertyField(m_FxaaPreset);
        }
        else if (m_Method.intValue == (int)Method.Taa)
        {
            if (QualitySettings.antiAliasing > 1)
                EditorGUILayout.HelpBox("Temporal Anti-Aliasing doesn't work
correctly when MSAA is enabled.", MessageType.Warning);

            EditorGUILayout.LabelField("Jitter", EditorStyles.boldLabel);
            EditorGUI.indentLevel++;
            EditorGUILayout.PropertyField(m_TaaJitterSpread,
EditorGUILayoutHelper.GetContent("Spread"));
            EditorGUI.indentLevel--;

            EditorGUILayout.Space();

            EditorGUILayout.LabelField("Blending", EditorStyles.boldLabel);
            EditorGUI.indentLevel++;
```

```
        EditorGUILayout.PropertyField(m_TaaStationaryBlending,
EditorGUIHelper.GetContent("Stationary"));
        EditorGUILayout.PropertyField(m_TaaMotionBlending,
EditorGUIHelper.GetContent("Motion"));
        EditorGUI.indentLevel--;

        EditorGUILayout.Space();

        EditorGUILayout.PropertyField(m_TaaSharpen);
    }
}

using System.Collections;
using System.Collections.Generic;
using UnityEngine;
using UnityEngine.UI;
using UnityEngine.SceneManagement;

public class AsyncLoad : MonoBehaviour {

    // public Image FG;
    public Text tishi_ui;
    public Text progressText;
    public Transform jiazai;
    string[] tishi=new string[5];
    private static string NextScene;
    public Sprite[] BG_ImageList;
    public Image BG;
    public static void LoadingScene(string sceneName)
    {
        NextScene = sceneName;
        SceneManager.LoadScene("AsyncLoad");
    }
    bool n=true;
    // Use this for initialization

    void Start()
    {
        BG.sprite = BG_ImageList[Random.Range(0, 5)];

        tishi[0] = "温馨小提示：浮动螺母用于配合螺丝钉的安装，以便于固定螺钉。";
        tishi[1] = "温馨小提示：U 与 U 之间的分界线作为计算设备安装空间的参考点。";
```

```
”;  
    tishi[2] = “温馨小提示：在使用功率超过特定瓦数的用电设备前，必须得到上级  
主管批准，并在保证线路安全的基础上使用。”;  
    tishi[3] = “温馨小提示：工作人员离开工作区域前，应保证工作区域内保存的重  
要文件、资料、设备、数据处于安全保护状态。”;  
    tishi[4] = “温馨小提示：在使用功率超过特定瓦数的用电设备前，必须得到上级  
主管批准，并在保证线路安全的基础上使用。”;  
  
    tishi_ui.text = tishi[Random.Range(0, 5)];  
  
}  
void Update()  
{  
    progressText.text = (int)(currentProgress * 100) + “%”;  
    jiazai.Rotate(new Vector3(0, 0, 1), -Time.deltaTime * 300);  
    if(n)  
    {  
        n = false;  
        StartCoroutine(Load());  
    }  
  
}  
  
AsyncOperation async;  
float currentProgress = 0;  
IEnumerator Load()  
{  
  
    async = SceneManager.LoadSceneAsync(NextScene);  
    async.allowSceneActivation = false;//不允许场景激活  
  
    while (!async.isDone)//加载是否完成  
    {  
        if (async.progress >= 0.9F)  
        {  
            break;  
        }  
        if (currentProgress < async.progress)//加载的进度  
        {  
            currentProgress += 0.01F;  
        }  
        yield return new WaitForEndOfFrame();  
        //FG.fillAmount = currentProgress;  
    }  
}
```

```
    }
    while (currentProgress < 1F)
    {
        currentProgress += 0.01F;
        yield return new WaitForEndOfFrame();
        //FG.fillAmount = currentProgress;
    }
    async.allowSceneActivation = true;//允许场景激活
    async = null;
    NextScene = string.Empty;
    yield return async;
}

}

using System;
using UnityEngine;
#if UNITY_EDITOR

#endif

namespace UnityStandardAssets.Cameras
{
    [ExecuteInEditMode]
    public class AutoCam : PivotBasedCameraRig
    {
        [SerializeField] private float m_MoveSpeed = 3; // How fast the rig will
        move to keep up with target's position
        [SerializeField] private float m_TurnSpeed = 1; // How fast the rig will
        turn to keep up with target's rotation
        [SerializeField] private float m_RollSpeed = 0.2f;// How fast the rig will
        roll (around Z axis) to match target's roll.
        [SerializeField] private bool m_FollowVelocity = false;// Whether the rig
        will rotate in the direction of the target's velocity.
        [SerializeField] private bool m_FollowTilt = true; // Whether the rig will
        tilt (around X axis) with the target.
        [SerializeField] private float m_SpinTurnLimit = 90;// The threshold beyond
        which the camera stops following the target's rotation. (used in situations where
        a car spins out, for example)
        [SerializeField] private float m_TargetVelocityLowerLimit = 4f;// the
        minimum velocity above which the camera turns towards the object's velocity. Below
        this we use the object's forward direction.
```

```
[SerializeField] private float m_SmoothTurnTime = 0.2f; // the smoothing
for the camera's rotation
```

```
private float m_LastFlatAngle; // The relative angle of the target and the
rig from the previous frame.
```

```
private float m_CurrentTurnAmount; // How much to turn the camera
```

```
private float m_TurnSpeedVelocityChange; // The change in the turn speed
velocity
```

```
private Vector3 m_RollUp = Vector3.up; // The roll of the camera around the
z axis ( generally this will always just be up )
```

```
protected override void FollowTarget(float deltaTime)
```

```
{
```

```
    // if no target, or no time passed then we quit early, as there is nothing
to do
```

```
    if (!(deltaTime > 0) || m_Target == null)
```

```
    {
```

```
        return;
```

```
    }
```

```
    // initialise some vars, we'll be modifying these in a moment
```

```
    var targetForward = m_Target.forward;
```

```
    var targetUp = m_Target.up;
```

```
    if (m_FollowVelocity && Application.isPlaying)
```

```
    {
```

```
        // in follow velocity mode, the camera's rotation is aligned towards
the object's velocity direction
```

```
        // but only if the object is traveling faster than a given threshold.
```

```
        if (targetRigidbody.velocity.magnitude >
m_TargetVelocityLowerLimit)
```

```
        {
```

```
            // velocity is high enough, so we'll use the target's velocity
```

```
            targetForward = targetRigidbody.velocity.normalized;
```

```
            targetUp = Vector3.up;
```

```
        }
```

```
    else
```

```
    {
```

```
        targetUp = Vector3.up;
```

```
    }
```

```
    m_CurrentTurnAmount = Mathf.SmoothDamp(m_CurrentTurnAmount, 1,
ref m_TurnSpeedVelocityChange, m_SmoothTurnTime);
```

```

    }
    else
    {
        // we're in 'follow rotation' mode, where the camera rig's rotation
        follows the object's rotation.

        // This section allows the camera to stop following the target's
        rotation when the target is spinning too fast.
        // eg when a car has been knocked into a spin. The camera will resume
        following the rotation
        // of the target when the target's angular velocity slows below the
        threshold.
        var currentFlatAngle = Mathf.Atan2(targetForward.x,
        targetForward.z)*Mathf.Rad2Deg;
        if (m_SpinTurnLimit > 0)
        {
            var targetSpinSpeed =
            Mathf.Abs(Mathf.DeltaAngle(m_LastFlatAngle, currentFlatAngle))/deltaTime;
            var desiredTurnAmount = Mathf.InverseLerp(m_SpinTurnLimit,
            m_SpinTurnLimit*0.75f, targetSpinSpeed);
            var turnReactSpeed = (m_CurrentTurnAmount >
            desiredTurnAmount ? .1f : 1f);
            if (Application.isPlaying)
            {
                m_CurrentTurnAmount =
                Mathf.SmoothDamp(m_CurrentTurnAmount, desiredTurnAmount,
                ref
                m_TurnSpeedVelocityChange, turnReactSpeed);
            }
            else
            {
                // for editor mode, smoothdamp won't work because it uses
                deltaTime internally
                m_CurrentTurnAmount = desiredTurnAmount;
            }
        }
        else
        {
            m_CurrentTurnAmount = 1;
        }
        m_LastFlatAngle = currentFlatAngle;
    }

    // camera position moves towards target position:

```



```

        transform.position = Vector3.Lerp(transform.position,
m_Target.position, deltaTime*m_MoveSpeed);

        // camera's rotation is split into two parts, which can have independent
speed settings:
        // rotating towards the target's forward direction (which encompasses
its 'yaw' and 'pitch')
        if (!m_FollowTilt)
        {
            targetForward.y = 0;
            if (targetForward.sqrMagnitude < float.Epsilon)
            {
                targetForward = transform.forward;
            }
        }
        var rollRotation = Quaternion.LookRotation(targetForward, m_RollUp);

        // and aligning with the target object's up direction (i.e. its 'roll')
        m_RollUp = m_RollSpeed > 0 ? Vector3.Slerp(m_RollUp, targetUp,
m_RollSpeed*deltaTime) : Vector3.up;
        transform.rotation = Quaternion.Lerp(transform.rotation,
rollRotation, m_TurnSpeed*m_CurrentTurnAmount*deltaTime);
    }
}
}
}

```

```

using System;
using System.Collections.Generic;
using UnityEngine;
#if UNITY_EDITOR
using UnityEditor;
#endif

```

```

namespace UnityStandardAssets.Utility
{
    public class AutoMobileShaderSwitch : MonoBehaviour
    {
        [SerializeField] private ReplacementList m_ReplacementList;

        // Use this for initialization
        private void OnEnable()
        {

```

```

#if UNITY_IPHONE || UNITY_ANDROID || UNITY_WP8 || UNITY_TIZEN
    var renderers = FindObjectsOfType<Renderer>();
    Debug.Log (renderers.Length+" renderers");
    var oldMaterials = new List<Material>();
    var newMaterials = new List<Material>();

    int materialsReplaced = 0;
    int materialInstancesReplaced = 0;

    foreach(ReplacementDefinition replacementDef in
m_ReplacementList.items)
    {
        foreach(var r in renderers)
        {
            Material[] modifiedMaterials = null;
            for(int n=0; n<r.sharedMaterials.Length; ++n)
            {
                var material = r.sharedMaterials[n];
                if (material.shader == replacementDef.original)
                {
                    if (modifiedMaterials == null)
                    {
                        modifiedMaterials = r.materials;
                    }
                    if (!oldMaterials.Contains(material))
                    {
                        oldMaterials.Add(material);
                        Material newMaterial =
(Material)Instantiate(material);
                        newMaterial.shader = replacementDef.replacement;
                        newMaterials.Add(newMaterial);
                        ++materialsReplaced;
                    }
                    Debug.Log ("replacing "+r.gameObject.name+" renderer
"+n+" with "+newMaterials[oldMaterials.IndexOf(material)].name);
                    modifiedMaterials[n] =
newMaterials[oldMaterials.IndexOf(material)];
                    ++materialInstancesReplaced;
                }
            }
        }
        if (modifiedMaterials != null)
        {
            r.materials = modifiedMaterials;
        }
    }
}

```

```

        }
    }
    Debug.Log (materialInstancesReplaced+" material instances replaced");
    Debug.Log (materialsReplaced+" materials replaced");
    for(int n=0; n<oldMaterials.Count; ++n)
    {
        Debug.Log (oldMaterials[n].name+"
("+oldMaterials[n].shader.name+" "+ replaced with "+newMaterials[n].name+"
("+newMaterials[n].shader.name+" "));
    }
#endif
}

[Serializable]
public class ReplacementDefinition
{
    public Shader original = null;
    public Shader replacement = null;
}

[Serializable]
public class ReplacementList
{
    public ReplacementDefinition[] items = new ReplacementDefinition[0];
}

}

namespace UnityStandardAssets.Utility.Inspector
{
    #if UNITY_EDITOR
    [CustomPropertyDrawer(typeof (AutoMobileShaderSwitch.ReplacementList))]
    public class ReplacementListDrawer : PropertyDrawer
    {
        const float k_LineHeight = 18;
        const float k_Spacing = 4;

        public override void OnGUI(Rect position, SerializedProperty property,
GUIContent label)
        {
            EditorGUI.BeginProperty(position, label, property);

            float x = position.x;

```

[illegible]

```

        items.DeleteArrayElementAtIndex(i);
        changedLength = true;
        break;
    case "v":
        if (i > 0)
        {
            items.MoveArrayElement(i, i +
1);

        }
        break;
    case "^":
        if (i < items.arraySize - 1)
        {
            items.MoveArrayElement(i, i -
1);

        }
        break;
    }
}
}
else
{
    SerializedProperty prop =
item.FindPropertyRelative(props[n]);
    EditorGUI.PropertyField(rect, prop,
GUIContent.none);
}
}
}

y += lineHeight + k_Spacing;
if (changedLength)
{
    break;
}
}
}

// add button
var addButtonRect = new Rect((x + position.width) -
widths[widths.Length - 1]*inspectorWidth, y,
widths[widths.Length
1]*inspectorWidth, lineHeight);
if (GUI.Button(addButtonRect, "+"))

```

```
        {
            items.InsertArrayElementAtIndex(items.arraySize);
        }

        y += lineHeight + k_Spacing;

        // Set indent back to what it was
        EditorGUI.indentLevel = indent;
        EditorGUI.EndProperty();
    }

    public override float GetPropertyHeight(SerializedProperty property,
GUIContent label)
    {
        SerializedProperty items = property.FindPropertyRelative("items");
        float lineAndSpace = k_LineHeight + k_Spacing;
        return 40 + (items.arraySize*lineAndSpace) + lineAndSpace;
    }
}
#endif
}
```