```
using UnityEngine;
using UnityEngine.Rendering;

namespace UnityStandardAssets.CinematicEffects
{
    [ExecuteInEditMode]
    [RequireComponent(typeof(Camera))]
    [AddComponentMenu("Image Effects/Cinematic/Ambient Occlusion")]
#if UNITY_5_4_OR_NEWER
    [ImageEffectAllowedInSceneView]
#endif
    public partial class AmbientOcclusion : MonoBehaviour
    {
        #region Public Properties

        /// Effect settings.
        [SerializeField]
        public Settings settings = Settings.defaultSettings;

        /// Checks if the ambient-only mode is supported under the current settings.
        public bool isAmbientOnlySupported
        {
            get { return targetCamera.hdr && occlusionSource == OcclusionSource.GBuffer; }
        }

        /// Checks if the G-buffer is available
        public bool isGBufferAvailable
        {
            get { return targetCamera.actualRenderingPath == RenderingPath.DeferredShading; }
        }

        #endregion

        #region Private Properties

        // Properties referring to the current settings

        float intensity
        {
            get { return settings.intensity; }
        }
```

```
        float radius
        {
            get { return Mathf.Max(settings.radius, 1e-4f); }
        }

        SampleCount sampleCount
        {
            get { return settings.sampleCount; }
        }

        int sampleCountValue
        {
            get
            {
                switch (settings.sampleCount)
                {
                    case SampleCount.Lowest: return 3;
                    case SampleCount.Low:    return 6;
                    case SampleCount.Medium: return 12;
                    case SampleCount.High:   return 20;
                }
                return Mathf.Clamp(settings.sampleCountValue, 1, 256);
            }
        }

        OcclusionSource occlusionSource
        {
            get
            {
                if      (settings.occlusionSource      ==      OcclusionSource.GBuffer
&& !isGBufferAvailable)
                    // An unavailable source was chosen: fallback to DepthNormalsTexture.
                    return OcclusionSource.DepthNormalsTexture;
                else
                    return settings.occlusionSource;
            }
        }

        bool downsampling
        {
            get { return settings.downsampling; }
        }

        bool ambientOnly
```

```
        {
            get { return settings.ambientOnly && isAmbientOnlySupported; }
        }

        // AO shader
        Shader aoShader
        {
            get
            {
                if (_aoShader == null)
                    _aoShader                =                Shader.Find("Hidden/Image
Effects/Cinematic/AmbientOcclusion");
                return _aoShader;
            }
        }

        [SerializeField] Shader _aoShader;

        // Temporary aterial for the AO shader
        Material aoMaterial
        {
            get
            {
                if (_aoMaterial == null)
                    _aoMaterial                                                    =
ImageEffectHelper.CheckShaderAndCreateMaterial(aoShader);
                return _aoMaterial;
            }
        }

        Material _aoMaterial;

        // Command buffer for the AO pass
        CommandBuffer aoCommands
        {
            get
            {
                if (_aoCommands == null)
                {
                    _aoCommands = new CommandBuffer();
                    _aoCommands.name = "AmbientOcclusion";
                }
                return _aoCommands;
            }
```

```
}

CommandBuffer _aoCommands;

// Target camera
Camera targetCamera
{
    get { return GetComponent<Camera>(); }
}

// Property observer
PropertyObserver propertyObserver { get; set; }

// Reference to the quad mesh in the built-in assets
// (used in MRT blitting)
Mesh quadMesh
{
    get { return _quadMesh; }
}

[SerializeField] Mesh _quadMesh;

#endregion

#region Effect Passes

// Build commands for the AO pass (used in the ambient-only mode).
void BuildAOCommands()
{
    var cb = aoCommands;

    var tw = targetCamera.pixelWidth;
    var th = targetCamera.pixelHeight;
    var ts = downsampling ? 2 : 1;
    var format = RenderTextureFormat.R8;
    var rwMode = RenderTextureReadWrite.Linear;
    var filter = FilterMode.Bilinear;

    // AO buffer
    var m = aoMaterial;
    var rtMask = Shader.PropertyToID("_OcclusionTexture");
    cb.GetTemporaryRT(rtMask, tw / ts, th / ts, 0, filter, format, rwMode);

    // AO estimation
```

```
    cb.Blit((Texture)null, rtMask, m, 0);

    // Blur buffer
    var rtBlur = Shader.PropertyToID("_OcclusionBlurTexture");

    // Primary blur filter (large kernel)
    cb.GetTemporaryRT(rtBlur, tw, th, 0, filter, format, rwMode);
    cb.SetGlobalVector("_BlurVector", Vector2.right * 2);
    cb.Blit(rtMask, rtBlur, m, 1);
    cb.ReleaseTemporaryRT(rtMask);

    cb.GetTemporaryRT(rtMask, tw, th, 0, filter, format, rwMode);
    cb.SetGlobalVector("_BlurVector", Vector2.up * 2 * ts);
    cb.Blit(rtBlur, rtMask, m, 1);
    cb.ReleaseTemporaryRT(rtBlur);

    // Secondary blur filter (small kernel)
    cb.GetTemporaryRT(rtBlur, tw, th, 0, filter, format, rwMode);
    cb.SetGlobalVector("_BlurVector", Vector2.right * ts);
    cb.Blit(rtMask, rtBlur, m, 2);
    cb.ReleaseTemporaryRT(rtMask);

    cb.GetTemporaryRT(rtMask, tw, th, 0, filter, format, rwMode);
    cb.SetGlobalVector("_BlurVector", Vector2.up * ts);
    cb.Blit(rtBlur, rtMask, m, 2);
    cb.ReleaseTemporaryRT(rtBlur);

    // Combine AO to the G-buffer.
    var mrt = new RenderTargetIdentifier[] {
        BuiltinRenderTextureType.GBuffer0,      // Albedo, Occ
        BuiltinRenderTextureType.CameraTarget   // Ambient
    };
    cb.SetRenderTarget(mrt, BuiltinRenderTextureType.CameraTarget);
    cb.SetGlobalTexture("_OcclusionTexture", rtMask);
    cb.DrawMesh(quadMesh, Matrix4x4.identity, m, 0, 4);

    cb.ReleaseTemporaryRT(rtMask);
}

// Execute the AO pass immediately (used in the forward mode).
void ExecuteAOPass(RenderTexture source, RenderTexture destination)
{
    var tw = source.width;
    var th = source.height;
```

```
        var ts = downsampling ? 2 : 1;
        var format = RenderTextureFormat.R8;
        var rwMode = RenderTextureReadWrite.Linear;

        // AO buffer
        var m = aoMaterial;
        var rtMask = RenderTexture.GetTemporary(tw / ts, th / ts, 0, format, rwMode);

        // AO estimation
        Graphics.Blit((Texture)null, rtMask, m, 0);

        // Primary blur filter (large kernel)
        var rtBlur = RenderTexture.GetTemporary(tw, th, 0, format, rwMode);
        m.SetVector("_BlurVector", Vector2.right * 2);
        Graphics.Blit(rtMask, rtBlur, m, 1);
        RenderTexture.ReleaseTemporary(rtMask);

        rtMask = RenderTexture.GetTemporary(tw, th, 0, format, rwMode);
        m.SetVector("_BlurVector", Vector2.up * 2 * ts);
        Graphics.Blit(rtBlur, rtMask, m, 1);
        RenderTexture.ReleaseTemporary(rtBlur);

        // Secondary blur filter (small kernel)
        rtBlur = RenderTexture.GetTemporary(tw, th, 0, format, rwMode);
        m.SetVector("_BlurVector", Vector2.right * ts);
        Graphics.Blit(rtMask, rtBlur, m, 2);
        RenderTexture.ReleaseTemporary(rtMask);

        rtMask = RenderTexture.GetTemporary(tw, th, 0, format, rwMode);
        m.SetVector("_BlurVector", Vector2.up * ts);
        Graphics.Blit(rtBlur, rtMask, m, 2);
        RenderTexture.ReleaseTemporary(rtBlur);

        // Combine AO with the source.
        m.SetTexture("_OcclusionTexture", rtMask);

        if (!settings.debug)
            Graphics.Blit(source, destination, m, 3);
        else
            Graphics.Blit(source, destination, m, 5);

        RenderTexture.ReleaseTemporary(rtMask);
    }
```

```
        // Update the common material properties.
        void UpdateMaterialProperties()
        {
            var m = aoMaterial;
            m.shaderKeywords = null;

            m.SetFloat("_Intensity", intensity);
            m.SetFloat("_Radius", radius);
            m.SetFloat("_TargetScale", downsampling ? 0.5f : 1);

            // Occlusion source
            if (occlusionSource == OcclusionSource.GBuffer)
                m.EnableKeyword("_SOURCE_GBUFFER");
            else if (occlusionSource == OcclusionSource.DepthTexture)
                m.EnableKeyword("_SOURCE_DEPTH");
            else
                m.EnableKeyword("_SOURCE_DEPTHNORMALS");

            // Sample count
            if (sampleCount == SampleCount.Lowest)
                m.EnableKeyword("_SAMPLECOUNT_LOWEST");
            else
                m.SetInt("_SampleCount", sampleCountValue);
        }

        #endregion

        #region MonoBehaviour Functions

        void OnEnable()
        {
            // Check if the shader is supported in the current platform.
            if (!ImageEffectHelper.IsSupported(aoShader, true, false, this))
            {
                enabled = false;
                return;
            }

            // Register the command buffer if in the ambient-only mode.
            if (ambientOnly)
                targetCamera.AddCommandBuffer(CameraEvent.BeforeReflections,
aoCommands);

            // Enable depth textures which the occlusion source requires.
```

```
            if (occlusionSource == OcclusionSource.DepthTexture)
                targetCamera.depthTextureMode |= DepthTextureMode.Depth;

            if (occlusionSource != OcclusionSource.GBuffer)
                targetCamera.depthTextureMode |= DepthTextureMode.DepthNormals;
        }

        void OnDisable()
        {
            // Destroy all the temporary resources.
            if (_aoMaterial != null) DestroyImmediate(_aoMaterial);
            _aoMaterial = null;

            if (_aoCommands != null)
                targetCamera.RemoveCommandBuffer(CameraEvent.BeforeReflections,
_aoCommands);
            _aoCommands = null;
        }

        void Update()
        {
            if (propertyObserver.CheckNeedsReset(settings, targetCamera))
            {
                // Reinitialize all the resources by disabling/enabling itself.
                // This is not very efficient way but just works...
                OnDisable();
                OnEnable();

                // Build the command buffer if in the ambient-only mode.
                if (ambientOnly)
                {
                    aoCommands.Clear();
                    BuildAOCommands();
                }

                propertyObserver.Update(settings, targetCamera);
            }

            // Update the material properties (later used in the AO commands).
            if (ambientOnly) UpdateMaterialProperties();
        }

        [ImageEffectOpaque]
        void OnRenderImage(RenderTexture source, RenderTexture destination)
```

```
        {
            if (ambientOnly)
            {
                // Do nothing in the ambient-only mode.
                Graphics.Blit(source, destination);
            }
            else
            {
                // Execute the AO pass.
                UpdateMaterialProperties();
                ExecuteAOPass(source, destination);
            }
        }

        #endregion
    }
}
using System;
using UnityEngine;
using Object = UnityEngine.Object;

namespace UnityStandardAssets.Utility
{
    public class ActivateTrigger : MonoBehaviour
    {
        // A multi-purpose script which causes an action to occur when
        // a trigger collider is entered.
        public enum Mode
        {
            Trigger = 0,    // Just broadcast the action on to the target
            Replace = 1,    // replace target with source
            Activate = 2,   // Activate the target GameObject
            Enable = 3,     // Enable a component
            Animate = 4,    // Start animation on target
            Deactivate = 5  // Decativate target GameObject
        }

        public Mode action = Mode.Activate;         // The action to accomplish
        public Object target;                       // The game object to affect. If none,
the trigger work on this game object
        public GameObject source;
        public int triggerCount = 1;
        public bool repeatTrigger = false;
```

```
        private void DoActivateTrigger()
        {
            triggerCount--;

            if (triggerCount == 0 || repeatTrigger)
            {
                Object currentTarget = target ?? gameObject;
                Behaviour targetBehaviour = currentTarget as Behaviour;
                GameObject targetGameObject = currentTarget as GameObject;
                if (targetBehaviour != null)
                {
                    targetGameObject = targetBehaviour.gameObject;
                }

                switch (action)
                {
                    case Mode.Trigger:
                        if (targetGameObject != null)
                        {
                            targetGameObject.BroadcastMessage("DoActivateTrigger");
                        }
                        break;
                    case Mode.Replace:
                        if (source != null)
                        {
                            if (targetGameObject != null)
                            {
                                Instantiate(source,
targetGameObject.transform.position,
                                            targetGameObject.transform.rotation);
                                DestroyObject(targetGameObject);
                            }
                        }
                        break;
                    case Mode.Activate:
                        if (targetGameObject != null)
                        {
                            targetGameObject.SetActive(true);
                        }
                        break;
                    case Mode.Enable:
                        if (targetBehaviour != null)
                        {
```

```
                        targetBehaviour.enabled = true;
                    }
                    break;
                case Mode.Animate:
                    if (targetGameObject != null)
                    {
                        targetGameObject.GetComponent<Animation>().Play();
                    }
                    break;
                case Mode.Deactivate:
                    if (targetGameObject != null)
                    {
                        targetGameObject.SetActive(false);
                    }
                    break;
            }
        }
    }


    private void OnTriggerEnter(Collider other)
    {
        DoActivateTrigger();
    }
}
}
```

```
        // put together:

        if (v.z >= 0.0)
            sunShaftsMaterial.SetVector ("_SunColor", Vector4 (sunColor.r, sunColor.g,
sunColor.b, sunColor.a) * sunShaftIntensity);
        else
            sunShaftsMaterial.SetVector ("_SunColor", Vector4.zero); // no backprojection !
        sunShaftsMaterial.SetTexture ("_ColorBuffer", lrDepthBuffer);
        Graphics.Blit (source, destination, sunShaftsMaterial, (screenBlendMode ==
ShaftsScreenBlendMode.Screen) ? 0 : 4);

        RenderTexture.ReleaseTemporary (lrDepthBuffer);
        RenderTexture.ReleaseTemporary (secondQuarterRezColor);
    }

    // helper functions
```

```
	private function ClampBlurIterationsToSomethingThatMakesSense (its : int) : int {
		if (its < 1)
			return 1;
		else if (its > 4)
			return 4;
		else
			return its;
	}

}
#pragma strict

@CustomEditor (SunShafts)

class SunShaftsEditor extends Editor
{
	var serObj : SerializedObject;

	var sunTransform : SerializedProperty;
	var radialBlurIterations : SerializedProperty;
	var sunColor : SerializedProperty;
	var sunShaftBlurRadius : SerializedProperty;
	var sunShaftIntensity : SerializedProperty;
	var useSkyBoxAlpha : SerializedProperty;
	var useDepthTexture : SerializedProperty;
	var resolution : SerializedProperty;
	var screenBlendMode : SerializedProperty;
	var maxRadius : SerializedProperty;

	function OnEnable () {
		serObj = new SerializedObject (target);

		screenBlendMode = serObj.FindProperty("screenBlendMode");

		sunTransform = serObj.FindProperty("sunTransform");
		sunColor = serObj.FindProperty("sunColor");

		sunShaftBlurRadius = serObj.FindProperty("sunShaftBlurRadius");
		radialBlurIterations = serObj.FindProperty("radialBlurIterations");

		sunShaftIntensity = serObj.FindProperty("sunShaftIntensity");
		useSkyBoxAlpha = serObj.FindProperty("useSkyBoxAlpha");

		resolution =    serObj.FindProperty("resolution");
```

```
        maxRadius = serObj.FindProperty("maxRadius");

        useDepthTexture = serObj.FindProperty("useDepthTexture");
    }

    function OnInspectorGUI () {
        serObj.Update ();

        EditorGUILayout.BeginHorizontal();

        var oldVal : boolean = useDepthTexture.boolValue;
        EditorGUILayout.PropertyField (useDepthTexture, new GUIContent ("Rely on Z Buffer?"));
        if((target as SunShafts).camera)
            GUILayout.Label("Current camera mode: "+ (target as SunShafts).camera.depthTextureMode, EditorStyles.miniBoldLabel);

        EditorGUILayout.EndHorizontal();

        // depth buffer need
        /*
        var newVal : boolean = useDepthTexture.boolValue;
        if (newVal != oldVal) {
            if(newVal)
                (target as SunShafts).camera.depthTextureMode |= DepthTextureMode.Depth;
            else
                (target as SunShafts).camera.depthTextureMode &= ~DepthTextureMode.Depth;
        }
        */

        EditorGUILayout.PropertyField (resolution,  new GUIContent("Resolution"));
        EditorGUILayout.PropertyField (screenBlendMode, new GUIContent("Blend mode"));

        EditorGUILayout.Separator ();

        EditorGUILayout.BeginHorizontal();

        EditorGUILayout.PropertyField (sunTransform, new GUIContent("Shafts caster", "Chose a transform that acts as a root point for the produced sun shafts"));
        if((target as SunShafts).sunTransform && (target as SunShafts).camera) {
```

```
                if (GUILayout.Button("Center on " + (target as SunShafts).camera.name)) {
                    if (EditorUtility.DisplayDialog ("Move sun shafts source?", "The SunShafts caster named "+ (target as SunShafts).sunTransform.name +"\n will be centered along "+(target as SunShafts).camera.name+". Are you sure? ", "Please do", "Don't")) {
                        var ray : Ray = (target as SunShafts).camera.ViewportPointToRay(Vector3(0.5,0.5,0));
                        (target as SunShafts).sunTransform.position = ray.origin + ray.direction * 500.0;
                        (target as SunShafts).sunTransform.LookAt ((target as SunShafts).transform);
                    }
                }
            }

            EditorGUILayout.EndHorizontal();

            EditorGUILayout.Separator ();

            EditorGUILayout.PropertyField (sunColor,    new GUIContent ("Shafts color"));
            maxRadius.floatValue = 1.0f - EditorGUILayout.Slider ("Distance falloff", 1.0f - maxRadius.floatValue, 0.1, 1.0);

            EditorGUILayout.Separator ();

            sunShaftBlurRadius.floatValue = EditorGUILayout.Slider ("Blur size", sunShaftBlurRadius.floatValue, 1.0, 10.0);
            radialBlurIterations.intValue = EditorGUILayout.IntSlider ("Blur iterations", radialBlurIterations.intValue, 1, 3);

            EditorGUILayout.Separator ();

            EditorGUILayout.PropertyField (sunShaftIntensity,    new GUIContent("Intensity"));
            useSkyBoxAlpha.floatValue = EditorGUILayout.Slider ("Use alpha mask", useSkyBoxAlpha.floatValue, 0.0, 1.0);

            serObj.ApplyModifiedProperties();
        }
}
#pragma strict

@script ExecuteInEditMode
@script RequireComponent (Camera)
@script AddComponentMenu ("Image Effects/Tilt shift")
```

```
class TiltShift extends PostEffectsBase {
	public var tiltShiftShader : Shader;
	private var tiltShiftMaterial : Material = null;

	public var renderTextureDivider : int = 2;
	public var blurIterations : int = 2;
	public var enableForegroundBlur : boolean = true;
	public var foregroundBlurIterations : int = 2;
	public var maxBlurSpread : float = 1.5f;

	public var focalPoint : float = 30.0f;
	public var smoothness : float = 1.65f;

	public var visualizeCoc : boolean = false;

	// these values will be automatically determined

	private var start01 : float = 0.0f;
	private var distance01 : float = 0.2f;
	private var end01 : float = 1.0f;
	private var curve : float = 1.0f;

	function CheckResources () : boolean {
		CheckSupport (true);

		tiltShiftMaterial = CheckShaderAndCreateMaterial (tiltShiftShader, tiltShiftMaterial);

		if(!isSupported)
			ReportAutoDisable ();
		return isSupported;
	}

	function OnRenderImage (source : RenderTexture, destination : RenderTexture) {
		if(CheckResources()==false) {
			Graphics.Blit (source, destination);
			return;
		}

		var widthOverHeight : float = (1.0f * source.width) / (1.0f * source.height);
		var oneOverBaseSize : float = 1.0f / 512.0f;

		// clamp some values

		renderTextureDivider = renderTextureDivider < 1 ? 1 : renderTextureDivider;
```

```
            targetGameObject = targetBehaviour.gameObject;
        }

        switch (action)
        {
            case Mode.Trigger:
                if (targetGameObject != null)
                {
                    targetGameObject.BroadcastMessage("DoActivateTrigger");
                }
                break;
            case Mode.Replace:
                if (source != null)
                {
                    if (targetGameObject != null)
                    {
                        Instantiate(source,
targetGameObject.transform.position,
                                    targetGameObject.transform.rotation);
                        DestroyObject(targetGameObject);
                    }
                }
                break;
            case Mode.Activate:
                if (targetGameObject != null)
                {
                    targetGameObject.SetActive(true);
                }
                break;
            case Mode.Enable:
                if (targetBehaviour != null)
                {
                    targetBehaviour.enabled = true;
                }
                break;
            case Mode.Animate:
                if (targetGameObject != null)
                {
                    targetGameObject.GetComponent<Animation>().Play();
                }
                break;
            case Mode.Deactivate:
                if (targetGameObject != null)
                {
```

```
                                targetGameObject.SetActive(false);
                            }
                            break;
                        }
                    }
                }


                private void OnTriggerEnter(Collider other)
                {
                    DoActivateTrigger();
                }
            }
        }using System;
        using UnityEngine;
        using Random = UnityEngine.Random;

        namespace UnityStandardAssets.Vehicles.Aeroplane
        {
            [RequireComponent(typeof (AeroplaneController))]
            public class AeroplaneAiControl : MonoBehaviour
            {
                // This script represents an AI 'pilot' capable of flying the plane towards a
        designated target.
                // It sends the equivalent of the inputs that a user would send to the Aeroplane
        controller.
                [SerializeField] private float m_RollSensitivity = .2f;               // How sensitively the
        AI applies the roll controls
                [SerializeField] private float m_PitchSensitivity = .5f;              // How sensitively the
        AI applies the pitch controls
                [SerializeField] private float m_LateralWanderDistance = 5;         // The amount that
        the plane can wander by when heading for a target
                [SerializeField] private float m_LateralWanderSpeed = 0.11f;        // The speed at
        which the plane will wander laterally
                [SerializeField] private float m_MaxClimbAngle = 45;                // The maximum
        angle that the AI will attempt to make plane can climb at
                [SerializeField] private float m_MaxRollAngle = 45;                 // The maximum
        angle that the AI will attempt to u
                [SerializeField] private float m_SpeedEffect = 0.01f;               // This increases the
        effect of the controls based on the plane's speed.
                [SerializeField] private float m_TakeoffHeight = 20;                // the AI will fly
        straight and only pitch upwards until reaching this height
                [SerializeField] private Transform m_Target;                        // the target to
        fly towards
```

```
        private AeroplaneController m_AeroplaneController;    // The aeroplane controller
that is used to move the plane
        private float m_RandomPerlin;                         // Used for generating
random point on perlin noise so that the plane will wander off path slightly
        private bool m_TakenOff;                              // Has the plane taken
off yet


        // setup script properties
        private void Awake()
        {
            // get the reference to the aeroplane controller, so we can send move input to
it and read its current state.
            m_AeroplaneController = GetComponent<AeroplaneController>();

            // pick a random perlin starting point for lateral wandering
            m_RandomPerlin = Random.Range(0f, 100f);
        }


        // reset the object to sensible values
        public void Reset()
        {
            m_TakenOff = false;
        }


        // fixed update is called in time with the physics system update
        private void FixedUpdate()
        {
            if (m_Target != null)
            {
                // make the plane wander from the path, useful for making the AI seem
more human, less robotic.
                Vector3 targetPos = m_Target.position +
                                    transform.right*

(Mathf.PerlinNoise(Time.time*m_LateralWanderSpeed, m_RandomPerlin)*2 - 1)*
                                    m_LateralWanderDistance;

                // adjust the yaw and pitch towards the target
                Vector3 localTarget = transform.InverseTransformPoint(targetPos);
                float targetAngleYaw = Mathf.Atan2(localTarget.x, localTarget.z);
```

```
                float targetAnglePitch = -Mathf.Atan2(localTarget.y, localTarget.z);


                // Set the target for the planes pitch, we check later that this has not
passed the maximum threshold
                targetAnglePitch = Mathf.Clamp(targetAnglePitch,
-m_MaxClimbAngle*Mathf.Deg2Rad,
                                               m_MaxClimbAngle*Mathf.Deg2Rad);

                // calculate the difference between current pitch and desired pitch
                float changePitch = targetAnglePitch -
m_AeroplaneController.PitchAngle;

                // AI always applies gentle forward throttle
                const float throttleInput = 0.5f;

                // AI applies elevator control (pitch, rotation around x) to reach the target
angle
                float pitchInput = changePitch*m_PitchSensitivity;

                // clamp the planes roll
                float desiredRoll = Mathf.Clamp(targetAngleYaw,
-m_MaxRollAngle*Mathf.Deg2Rad, m_MaxRollAngle*Mathf.Deg2Rad);
                float yawInput = 0;
                float rollInput = 0;
                if (!m_TakenOff)
                {
                    // If the planes altitude is above m_TakeoffHeight we class this as
taken off
                    if (m_AeroplaneController.Altitude > m_TakeoffHeight)
                    {
                        m_TakenOff = true;
                    }
                }
                else
                {
                    // now we have taken off to a safe height, we can use the rudder and
ailerons to yaw and roll
                    yawInput = targetAngleYaw;
                    rollInput = -(m_AeroplaneController.RollAngle -
desiredRoll)*m_RollSensitivity;
                }

                // adjust how fast the AI is changing the controls based on the speed.
```

```
Faster speed = faster on the controls.
                    float currentSpeedEffect = 1 + (m_AeroplaneController.ForwardSpeed*m_SpeedEffect);
                    rollInput *= currentSpeedEffect;
                    pitchInput *= currentSpeedEffect;
                    yawInput *= currentSpeedEffect;

                    // pass the current input to the plane (false = because AI never uses air brakes!)
                    m_AeroplaneController.Move(rollInput, pitchInput, yawInput, throttleInput, false);
                }
                else
                {
                    // no target set, send zeroed input to the planeW
                    m_AeroplaneController.Move(0, 0, 0, 0, false);
                }
            }


            // allows other scripts to set the plane's target
            public void SetTarget(Transform target)
            {
                m_Target = target;
            }
        }
}using System;
using UnityEngine;

namespace UnityStandardAssets.Vehicles.Aeroplane
{
    public class AeroplaneAudio : MonoBehaviour
    {

        [Serializable]
        public class AdvancedSetttings // A class for storing the advanced options.
        {
            public float engineMinDistance = 50f; // The min distance of the engine audio source.
            public float engineMaxDistance = 1000f; // The max distance of the engine audio source.
            public float engineDopplerLevel = 1f; // The doppler level of the engine audio source.
            [Range(0f, 1f)] public float engineMasterVolume = 0.5f; // An overall control of
```

```
the engine sound volume.
        public float windMinDistance = 10f;                    // The min
distance of the wind audio source.
        public float windMaxDistance = 100f;                   // The max
distance of the wind audio source.
        public float windDopplerLevel = 1f;                    // The doppler
level of the wind audio source.
        [Range(0f, 1f)] public float windMasterVolume = 0.5f;  // An overall control
of the wind sound volume.
    }

    [SerializeField] private AudioClip m_EngineSound;                    //
Looped engine sound, whose pitch and volume are affected by the plane's throttle setting.
    [SerializeField] private float m_EngineMinThrottlePitch = 0.4f;      // Pitch of the
engine sound when at minimum throttle.
    [SerializeField] private float m_EngineMaxThrottlePitch = 2f;        // Pitch of
the engine sound when at maximum throttle.
    [SerializeField] private float m_EngineFwdSpeedMultiplier = 0.002f;  // Additional
multiplier for an increase in pitch of the engine from the plane's speed.
    [SerializeField] private AudioClip m_WindSound;                      //
Looped wind sound, whose pitch and volume are affected by the plane's velocity.
    [SerializeField] private float m_WindBasePitch = 0.2f;               // starting
pitch for wind (when plane is at zero speed)
    [SerializeField] private float m_WindSpeedPitchFactor = 0.004f;      // Relative
increase in pitch of the wind from the plane's speed.
    [SerializeField] private float m_WindMaxSpeedVolume = 100;           // the
speed the aircraft much reach before the wind sound reaches maximum volume.
    [SerializeField] private AdvancedSetttings m_AdvancedSetttings = new
AdvancedSetttings();// container to make advanced settings appear as rollout in inspector

    private AudioSource m_EngineSoundSource;  // Reference to the AudioSource for
the engine.
    private AudioSource m_WindSoundSource;    // Reference to the AudioSource
for the wind.
    private AeroplaneController m_Plane;      // Reference to the aeroplane
controller.
    private Rigidbody m_Rigidbody;


    private void Awake()
    {
        // Set up the reference to the aeroplane controller.
        m_Plane = GetComponent<AeroplaneController>();
        m_Rigidbody = GetComponent<Rigidbody>();
```

```
            // Add the audiosources and get the references.
            m_EngineSoundSource = gameObject.AddComponent<AudioSource>();
            m_EngineSoundSource.playOnAwake = false;
            m_WindSoundSource = gameObject.AddComponent<AudioSource>();
            m_WindSoundSource.playOnAwake = false;

            // Assign clips to the audiosources.
            m_EngineSoundSource.clip = m_EngineSound;
            m_WindSoundSource.clip = m_WindSound;

            // Set the parameters of the audiosources.
            m_EngineSoundSource.minDistance                                    =
m_AdvancedSetttings.engineMinDistance;
            m_EngineSoundSource.maxDistance                                    =
m_AdvancedSetttings.engineMaxDistance;
            m_EngineSoundSource.loop = true;
            m_EngineSoundSource.dopplerLevel                                   =
m_AdvancedSetttings.engineDopplerLevel;

            m_WindSoundSource.minDistance = m_AdvancedSetttings.windMinDistance;
            m_WindSoundSource.maxDistance = m_AdvancedSetttings.windMaxDistance;
            m_WindSoundSource.loop = true;
            m_WindSoundSource.dopplerLevel                                     =
m_AdvancedSetttings.windDopplerLevel;

            // call update here to set the sounds pitch and volumes before they actually
play
            Update();

            // Start the sounds playing.
            m_EngineSoundSource.Play();
            m_WindSoundSource.Play();
        }


        private void Update()
        {
            // Find what proportion of the engine's power is being used.
            var enginePowerProportion = Mathf.InverseLerp(0, m_Plane.MaxEnginePower,
m_Plane.EnginePower);

            // Set the engine's pitch to be proportional to the engine's current power.
```

```
                m_EngineSoundSource.pitch = Mathf.Lerp(m_EngineMinThrottlePitch,
m_EngineMaxThrottlePitch, enginePowerProportion);

                // Increase the engine's pitch by an amount proportional to the aeroplane's
forward speed.
                // (this makes the pitch increase when going into a dive!)
                m_EngineSoundSource.pitch                                        +=
m_Plane.ForwardSpeed*m_EngineFwdSpeedMultiplier;

                // Set the engine's volume to be proportional to the engine's current power.
                m_EngineSoundSource.volume = Mathf.InverseLerp(0,
m_Plane.MaxEnginePower*m_AdvancedSetttings.engineMasterVolume,
                                                                m_Plane.EnginePower);

                // Set the wind's pitch and volume to be proportional to the aeroplane's
forward speed.
                float planeSpeed = m_Rigidbody.velocity.magnitude;
                m_WindSoundSource.pitch = m_WindBasePitch +
planeSpeed*m_WindSpeedPitchFactor;
                m_WindSoundSource.volume = Mathf.InverseLerp(0,
m_WindMaxSpeedVolume, planeSpeed)*m_AdvancedSetttings.windMasterVolume;
            }
        }
}
using System;
using UnityEngine;

namespace UnityStandardAssets.Vehicles.Aeroplane
{
    [RequireComponent(typeof (Rigidbody))]
    public class AeroplaneController : MonoBehaviour
    {
        [SerializeField] private float m_MaxEnginePower = 40f;          // The maximum
output of the engine.
        [SerializeField] private float m_Lift = 0.002f;                 // The amount of lift
generated by the aeroplane moving forwards.
        [SerializeField] private float m_ZeroLiftSpeed = 300;           // The speed at
which lift is no longer applied.
        [SerializeField] private float m_RollEffect = 1f;               // The strength of
effect for roll input.
        [SerializeField] private float m_PitchEffect = 1f;              // The strength of
effect for pitch input.
        [SerializeField] private float m_YawEffect = 0.2f;              // The strength of
effect for yaw input.
```

```
        [SerializeField] private float m_BankedTurnEffect = 0.5f;        // The amount of turn from doing a banked turn.
        [SerializeField] private float m_AerodynamicEffect = 0.02f;      // How much aerodynamics affect the speed of the aeroplane.
        [SerializeField] private float m_AutoTurnPitch = 0.5f;           // How much the aeroplane automatically pitches when in a banked turn.
        [SerializeField] private float m_AutoRollLevel = 0.2f;           // How much the aeroplane tries to level when not rolling.
        [SerializeField] private float m_AutoPitchLevel = 0.2f;          // How much the aeroplane tries to level when not pitching.
        [SerializeField] private float m_AirBrakesEffect = 3f;           // How much the air brakes effect the drag.
        [SerializeField] private float m_ThrottleChangeSpeed = 0.3f;     // The speed with which the throttle changes.
        [SerializeField] private float m_DragIncreaseFactor = 0.001f; // how much drag should increase with speed.

        public float Altitude { get; private set; }                      // The aeroplane's height above the ground.
        public float Throttle { get; private set; }                      // The amount of throttle being used.
        public bool AirBrakes { get; private set; }                      // Whether or not the air brakes are being applied.
        public float ForwardSpeed { get; private set; }                  // How fast the aeroplane is traveling in it's forward direction.
        public float EnginePower { get; private set; }                   // How much power the engine is being given.
        public float MaxEnginePower{ get { return m_MaxEnginePower; }}   // The maximum output of the engine.
        public float RollAngle { get; private set; }
        public float PitchAngle { get; private set; }
        public float RollInput { get; private set; }
        public float PitchInput { get; private set; }
        public float YawInput { get; private set; }
        public float ThrottleInput { get; private set; }

        private float m_OriginalDrag;         // The drag when the scene starts.
        private float m_OriginalAngularDrag;  // The angular drag when the scene starts.
        private float m_AeroFactor;
        private bool m_Immobilized = false;   // used for making the plane uncontrollable, i.e. if it has been hit or crashed.
        private float m_BankedTurnAmount;
        private Rigidbody m_Rigidbody;
        WheelCollider[] m_WheelColliders;
```

```
    private void Start()
    {
        m_Rigidbody = GetComponent<Rigidbody>();
        // Store original drag settings, these are modified during flight.
        m_OriginalDrag = m_Rigidbody.drag;
        m_OriginalAngularDrag = m_Rigidbody.angularDrag;

        for (int i = 0; i < transform.childCount; i++ )
        {
            foreach (var componentsInChild in transform.GetChild(i).GetComponentsInChildren<WheelCollider>())
            {
                componentsInChild.motorTorque = 0.18f;
            }
        }
    }


    public void Move(float rollInput, float pitchInput, float yawInput, float throttleInput, bool airBrakes)
    {
        // transfer input parameters into properties.s
        RollInput = rollInput;
        PitchInput = pitchInput;
        YawInput = yawInput;
        ThrottleInput = throttleInput;
        AirBrakes = airBrakes;

        ClampInputs();

        CalculateRollAndPitchAngles();

        AutoLevel();

        CalculateForwardSpeed();

        ControlThrottle();

        CalculateDrag();

        CaluclateAerodynamicEffect();
```

```
            CalculateLinearForces();

            CalculateTorque();

            CalculateAltitude();
        }


        private void ClampInputs()
        {
            // clamp the inputs to -1 to 1 range
            RollInput = Mathf.Clamp(RollInput, -1, 1);
            PitchInput = Mathf.Clamp(PitchInput, -1, 1);
            YawInput = Mathf.Clamp(YawInput, -1, 1);
            ThrottleInput = Mathf.Clamp(ThrottleInput, -1, 1);
        }


        private void CalculateRollAndPitchAngles()
        {
            // Calculate roll & pitch angles
            // Calculate the flat forward direction (with no y component).
            var flatForward = transform.forward;
            flatForward.y = 0;
            // If the flat forward vector is non-zero (which would only happen if the plane
was pointing exactly straight upwards)
            if (flatForward.sqrMagnitude > 0)
            {
                flatForward.Normalize();
                // calculate current pitch angle
                var localFlatForward = transform.InverseTransformDirection(flatForward);
                PitchAngle = Mathf.Atan2(localFlatForward.y, localFlatForward.z);
                // calculate current roll angle
                var flatRight = Vector3.Cross(Vector3.up, flatForward);
                var localFlatRight = transform.InverseTransformDirection(flatRight);
                RollAngle = Mathf.Atan2(localFlatRight.y, localFlatRight.x);
            }
        }


        private void AutoLevel()
        {
            // The banked turn amount (between -1 and 1) is the sine of the roll angle.
            // this is an amount applied to elevator input if the user is only using the
```

```
banking controls,
                // because that's what people expect to happen in games!
                m_BankedTurnAmount = Mathf.Sin(RollAngle);
                // auto level roll, if there's no roll input:
                if (RollInput == 0f)
                {
                    RollInput = -RollAngle*m_AutoRollLevel;
                }
                // auto correct pitch, if no pitch input (but also apply the banked turn amount)
                if (PitchInput == 0f)
                {
                    PitchInput = -PitchAngle*m_AutoPitchLevel;
                    PitchInput                                                    -=
Mathf.Abs(m_BankedTurnAmount*m_BankedTurnAmount*m_AutoTurnPitch);
                }
            }


            private void CalculateForwardSpeed()
            {
                // Forward speed is the speed in the planes's forward direction (not the same
as its velocity, eg if falling in a stall)
                var                                localVelocity                                =
transform.InverseTransformDirection(m_Rigidbody.velocity);
                ForwardSpeed = Mathf.Max(0, localVelocity.z);
            }


            private void ControlThrottle()
            {
                // override throttle if immobilized
                if (m_Immobilized)
                {
                    ThrottleInput = -0.5f;
                }

                // Adjust throttle based on throttle input (or immobilized state)
                Throttle                =                Mathf.Clamp01(Throttle                +
ThrottleInput*Time.deltaTime*m_ThrottleChangeSpeed);

                // current engine power is just:
                EnginePower = Throttle*m_MaxEnginePower;
            }
```

```
        private void CalculateDrag()
        {
            // increase the drag based on speed, since a constant drag doesn't seem "Real" (tm) enough
            float extraDrag = m_Rigidbody.velocity.magnitude*m_DragIncreaseFactor;
            // Air brakes work by directly modifying drag. This part is actually pretty realistic!
            m_Rigidbody.drag = (AirBrakes ? (m_OriginalDrag + extraDrag)*m_AirBrakesEffect : m_OriginalDrag + extraDrag);
            // Forward speed affects angular drag - at high forward speed, it's much harder for the plane to spin
            m_Rigidbody.angularDrag = m_OriginalAngularDrag*ForwardSpeed;
        }


        private void CaluclateAerodynamicEffect()
        {
            // "Aerodynamic" calculations. This is a very simple approximation of the effect that a plane
            // will naturally try to align itself in the direction that it's facing when moving at speed.
            // Without this, the plane would behave a bit like the asteroids spaceship!
            if (m_Rigidbody.velocity.magnitude > 0)
            {
                // compare the direction we're pointing with the direction we're moving:
                m_AeroFactor = Vector3.Dot(transform.forward, m_Rigidbody.velocity.normalized);
                // multipled by itself results in a desirable rolloff curve of the effect
                m_AeroFactor *= m_AeroFactor;
                // Finally we calculate a new velocity by bending the current velocity direction towards
                // the the direction the plane is facing, by an amount based on this aeroFactor
                var newVelocity = Vector3.Lerp(m_Rigidbody.velocity, transform.forward*ForwardSpeed,

m_AeroFactor*ForwardSpeed*m_AerodynamicEffect*Time.deltaTime);
                m_Rigidbody.velocity = newVelocity;

                // also rotate the plane towards the direction of movement - this should be a very small effect, but means the plane ends up
                // pointing downwards in a stall
                m_Rigidbody.rotation = Quaternion.Slerp(m_Rigidbody.rotation,
```

```
Quaternion.LookRotation(m_Rigidbody.velocity, transform.up),

m_AerodynamicEffect*Time.deltaTime);
                }
            }


            private void CalculateLinearForces()
            {
                // Now calculate forces acting on the aeroplane:
                // we accumulate forces into this variable:
                var forces = Vector3.zero;
                // Add the engine power in the forward direction
                forces += EnginePower*transform.forward;
                // The direction that the lift force is applied is at right angles to the plane's
velocity (usually, this is 'up'!)
                var liftDirection = Vector3.Cross(m_Rigidbody.velocity,
transform.right).normalized;
                // The amount of lift drops off as the plane increases speed - in reality this
occurs as the pilot retracts the flaps
                // shortly after takeoff, giving the plane less drag, but less lift. Because we
don't simulate flaps, this is
                // a simple way of doing it automatically:
                var zeroLiftFactor = Mathf.InverseLerp(m_ZeroLiftSpeed, 0, ForwardSpeed);
                // Calculate and add the lift power
                var liftPower =
ForwardSpeed*ForwardSpeed*m_Lift*zeroLiftFactor*m_AeroFactor;
                forces += liftPower*liftDirection;
                // Apply the calculated forces to the the Rigidbody
                m_Rigidbody.AddForce(forces);
            }


            private void CalculateTorque()
            {
                // We accumulate torque forces into this variable:
                var torque = Vector3.zero;
                // Add torque for the pitch based on the pitch input.
                torque += PitchInput*m_PitchEffect*transform.right;
                // Add torque for the yaw based on the yaw input.
                torque += YawInput*m_YawEffect*transform.up;
                // Add torque for the roll based on the roll input.
                torque += -RollInput*m_RollEffect*transform.forward;
```

```
            // Add torque for banked turning.
            torque += m_BankedTurnAmount*m_BankedTurnEffect*transform.up;
            // The total torque is multiplied by the forward speed, so the controls have more effect at high speed,
            // and little effect at low speed, or when not moving in the direction of the nose of the plane
            // (i.e. falling while stalled)
            m_Rigidbody.AddTorque(torque*ForwardSpeed*m_AeroFactor);
        }


        private void CalculateAltitude()
        {
            // Altitude calculations - we raycast downwards from the aeroplane
            // starting a safe distance below the plane to avoid colliding with any of the plane's own colliders
            var ray = new Ray(transform.position - Vector3.up*10, -Vector3.up);
            RaycastHit hit;
            Altitude = Physics.Raycast(ray, out hit) ? hit.distance + 10 : transform.position.y;
        }


        // Immobilize can be called from other objects, for example if this plane is hit by a weapon and should become uncontrollable
        public void Immobilize()
        {
            m_Immobilized = true;
        }


        // Reset is called via the ObjectResetter script, if present.
        public void Reset()
        {
            m_Immobilized = false;
        }
    }
}using System;
using UnityEngine;

namespace UnityStandardAssets.Vehicles.Aeroplane
{
    public class AeroplaneControlSurfaceAnimator : MonoBehaviour
    {
```

```
[SerializeField] private float m_Smoothing = 5f; // The smoothing applied to the movement of control surfaces.
[SerializeField] private ControlSurface[] m_ControlSurfaces; // Collection of control surfaces.

private AeroplaneController m_Plane; // Reference to the aeroplane controller.


private void Start()
{
    // Get the reference to the aeroplane controller.
    m_Plane = GetComponent<AeroplaneController>();

    // Store the original local rotation of each surface, so we can rotate relative to this
    foreach (var surface in m_ControlSurfaces)
    {
        surface.originalLocalRotation = surface.transform.localRotation;
    }
}


private void Update()
{
    foreach (var surface in m_ControlSurfaces)
    {
        switch (surface.type)
        {
            case ControlSurface.Type.Aileron:
                {
                    // Ailerons rotate around the x axis, according to the plane's roll input
                    Quaternion rotation = Quaternion.Euler(surface.amount*m_Plane.RollInput, 0f, 0f);
                    RotateSurface(surface, rotation);
                    break;
                }
            case ControlSurface.Type.Elevator:
                {
                    // Elevators rotate negatively around the x axis, according to the plane's pitch input
                    Quaternion rotation = Quaternion.Euler(surface.amount*-m_Plane.PitchInput, 0f, 0f);
                    RotateSurface(surface, rotation);
```

```
                    break;
                }
            case ControlSurface.Type.Rudder:
                {
                    // Rudders rotate around their y axis, according to the plane's yaw input
                    Quaternion rotation = Quaternion.Euler(0f, surface.amount*m_Plane.YawInput, 0f);
                    RotateSurface(surface, rotation);
                    break;
                }
            case ControlSurface.Type.RuddervatorPositive:
                {
                    // Ruddervators are a combination of rudder and elevator, and rotate
                    // around their z axis by a combination of the yaw and pitch input
                    float r = m_Plane.YawInput + m_Plane.PitchInput;
                    Quaternion rotation = Quaternion.Euler(0f, 0f, surface.amount*r);
                    RotateSurface(surface, rotation);
                    break;
                }
            case ControlSurface.Type.RuddervatorNegative:
                {
                    // ... and because ruddervators are "special", we need a negative version too. >_<
                    float r = m_Plane.YawInput - m_Plane.PitchInput;
                    Quaternion rotation = Quaternion.Euler(0f, 0f, surface.amount*r);
                    RotateSurface(surface, rotation);
                    break;
                }
            }
        }
    }


    private void RotateSurface(ControlSurface surface, Quaternion rotation)
    {
        // Create a target which is the surface's original rotation, rotated by the input.
        Quaternion target = surface.originalLocalRotation*rotation;

        // Slerp the surface's rotation towards the target rotation.
```

```
                surface.transform.localRotation =
Quaternion.Slerp(surface.transform.localRotation, target,

m_Smoothing*Time.deltaTime);
            }


            // This class presents a nice custom structure in which to define each of the plane's
contol surfaces to animate.
            // They show up in the inspector as an array.
            [Serializable]
            public class ControlSurface // Control surfaces represent the different flaps of the
aeroplane.
            {
                public enum Type // Flaps differ in position and rotation and are represented
by different types.
                {
                    Aileron, // Horizontal flaps on the wings, rotate on the x axis.
                    Elevator, // Horizontal flaps used to adjusting the pitch of a plane, rotate
on the x axis.
                    Rudder, // Vertical flaps on the tail, rotate on the y axis.
                    RuddervatorNegative, // Combination of rudder and elevator.
                    RuddervatorPositive, // Combination of rudder and elevator.
                }

                public Transform transform; // The transform of the control surface.
                public float amount; // The amount by which they can rotate.
                public Type type; // The type of control surface.

                [HideInInspector] public Quaternion originalLocalRotation; // The rotation of
the surface at the start.
            }
using System;
using UnityEngine;

namespace UnityStandardAssets.Vehicles.Aeroplane
{
    public class AeroplanePropellerAnimator : MonoBehaviour
    {
        [SerializeField] private Transform m_PropellorModel;
// The model of the the aeroplane's propellor.
        [SerializeField] private Transform m_PropellorBlur; //
The plane used for the blurred propellor textures.
        [SerializeField] private Texture2D[] m_PropellorBlurTextures; //
```

```
An array of increasingly blurred propellor textures.
        [SerializeField] [Range(0f, 1f)] private float m_ThrottleBlurStart = 0.25f;      // The point at which the blurred textures start.
        [SerializeField] [Range(0f, 1f)] private float m_ThrottleBlurEnd = 0.5f;          // The point at which the blurred textures stop changing.
        [SerializeField]          private          float          m_MaxRpm          =          2000;
// The maximum speed the propellor can turn at.

        private AeroplaneController m_Plane;              // Reference to the aeroplane controller.
        private int m_PropellorBlurState = -1;        // To store the state of the blurred textures.
        private const float k_RpmToDps = 60f;        // For converting from revs per minute to degrees per second.
        private Renderer m_PropellorModelRenderer;
        private Renderer m_PropellorBlurRenderer;


        private void Awake()
        {
            // Set up the reference to the aeroplane controller.
            m_Plane = GetComponent<AeroplaneController>();

            m_PropellorModelRenderer                                                    =
m_PropellorModel.GetComponent<Renderer>();
            m_PropellorBlurRenderer = m_PropellorBlur.GetComponent<Renderer>();

            // Set the propellor blur gameobject's parent to be the propellor.
            m_PropellorBlur.parent = m_PropellorModel;
        }


        private void Update()
        {
            // Rotate the propellor model at a rate proportional to the throttle.
            m_PropellorModel.Rotate(0,
m_MaxRpm*m_Plane.Throttle*Time.deltaTime*k_RpmToDps, 0);

            // Create an integer for the new state of the blur textures.
            var newBlurState = 0;

            // choose between the blurred textures, if the throttle is high enough
            if (m_Plane.Throttle > m_ThrottleBlurStart)
            {
```

```
                    var throttleBlurProportion = Mathf.InverseLerp(m_ThrottleBlurStart,
m_ThrottleBlurEnd, m_Plane.Throttle);
                    newBlurState =
Mathf.FloorToInt(throttleBlurProportion*(m_PropellorBlurTextures.Length - 1));
                }

                // If the blur state has changed
                if (newBlurState != m_PropellorBlurState)
                {
                    m_PropellorBlurState = newBlurState;

                    if (m_PropellorBlurState == 0)
                    {
                        // switch to using the 'real' propellor model
                        m_PropellorModelRenderer.enabled = true;
                        m_PropellorBlurRenderer.enabled = false;
                    }
                    else
                    {
                        // Otherwise turn off the propellor model and turn on the blur.
                        m_PropellorModelRenderer.enabled = false;
                        m_PropellorBlurRenderer.enabled = true;

                        // set the appropriate texture from the blur array
                        m_PropellorBlurRenderer.material.mainTexture =
m_PropellorBlurTextures[m_PropellorBlurState];
                    }
                }
            }
        }
}
using System;
using UnityEngine;
using UnityStandardAssets.CrossPlatformInput;

namespace UnityStandardAssets.Vehicles.Aeroplane
{
    [RequireComponent(typeof (AeroplaneController))]
    public class AeroplaneUserControl2Axis : MonoBehaviour
    {
        // these max angles are only used on mobile, due to the way pitch and roll input
are handled
        public float maxRollAngle = 80;
        public float maxPitchAngle = 80;
```

```
        // reference to the aeroplane that we're controlling
        private AeroplaneController m_Aeroplane;


        private void Awake()
        {
            // Set up the reference to the aeroplane controller.
            m_Aeroplane = GetComponent<AeroplaneController>();
        }


        private void FixedUpdate()
        {
            // Read input for the pitch, yaw, roll and throttle of the aeroplane.
            float roll = CrossPlatformInputManager.GetAxis("Horizontal");
            float pitch = CrossPlatformInputManager.GetAxis("Vertical");
            bool airBrakes = CrossPlatformInputManager.GetButton("Fire1");

            // auto throttle up, or down if braking.
            float throttle = airBrakes ? -1 : 1;
#if MOBILE_INPUT
            AdjustInputForMobileControls(ref roll, ref pitch, ref throttle);
#endif
            // Pass the input to the aeroplane
            m_Aeroplane.Move(roll, pitch, 0, throttle, airBrakes);
        }


        private void AdjustInputForMobileControls(ref float roll, ref float pitch, ref float
throttle)
        {
            // because mobile tilt is used for roll and pitch, we help out by
            // assuming that a centered level device means the user
            // wants to fly straight and level!

            // this means on mobile, the input represents the *desired* roll angle of the
aeroplane,
            // and the roll input is calculated to achieve that.
            // whereas on non-mobile, the input directly controls the roll of the aeroplane.

            float intendedRollAngle = roll*maxRollAngle*Mathf.Deg2Rad;
            float intendedPitchAngle = pitch*maxPitchAngle*Mathf.Deg2Rad;
            roll = Mathf.Clamp((intendedRollAngle - m_Aeroplane.RollAngle), -1, 1);
```

```
                pitch = Mathf.Clamp((intendedPitchAngle - m_Aeroplane.PitchAngle), -1, 1);

                // similarly, the throttle axis input is considered to be the desired absolute value, not a relative change to current throttle.
                float intendedThrottle = throttle*0.5f + 0.5f;
                throttle = Mathf.Clamp(intendedThrottle - m_Aeroplane.Throttle, -1, 1);
            }
        }
    }
    using System;
    using UnityEngine;
    using UnityStandardAssets.CrossPlatformInput;

    namespace UnityStandardAssets.Vehicles.Aeroplane
    {
        [RequireComponent(typeof (AeroplaneController))]
        public class AeroplaneUserControl4Axis : MonoBehaviour
        {
            // these max angles are only used on mobile, due to the way pitch and roll input are handled
            public float maxRollAngle = 80;
            public float maxPitchAngle = 80;

            // reference to the aeroplane that we're controlling
            private AeroplaneController m_Aeroplane;
            private float m_Throttle;
            private bool m_AirBrakes;
            private float m_Yaw;


            private void Awake()
            {
                // Set up the reference to the aeroplane controller.
                m_Aeroplane = GetComponent<AeroplaneController>();
            }


            private void FixedUpdate()
            {
                // Read input for the pitch, yaw, roll and throttle of the aeroplane.
                float roll = CrossPlatformInputManager.GetAxis("Mouse X");
                float pitch = CrossPlatformInputManager.GetAxis("Mouse Y");
                m_AirBrakes = CrossPlatformInputManager.GetButton("Fire1");
                m_Yaw = CrossPlatformInputManager.GetAxis("Horizontal");
```

```
                m_Throttle = CrossPlatformInputManager.GetAxis("Vertical");
#if MOBILE_INPUT
            AdjustInputForMobileControls(ref roll, ref pitch, ref m_Throttle);
#endif
                // Pass the input to the aeroplane
                m_Aeroplane.Move(roll, pitch, m_Yaw, m_Throttle, m_AirBrakes);
            }


            private void AdjustInputForMobileControls(ref float roll, ref float pitch, ref float
throttle)
            {
                // because mobile tilt is used for roll and pitch, we help out by
                // assuming that a centered level device means the user
                // wants to fly straight and level!

                // this means on mobile, the input represents the *desired* roll angle of the
aeroplane,
                // and the roll input is calculated to achieve that.
                // whereas on non-mobile, the input directly controls the roll of the aeroplane.

                float intendedRollAngle = roll*maxRollAngle*Mathf.Deg2Rad;
                float intendedPitchAngle = pitch*maxPitchAngle*Mathf.Deg2Rad;
                roll = Mathf.Clamp((intendedRollAngle - m_Aeroplane.RollAngle), -1, 1);
                pitch = Mathf.Clamp((intendedPitchAngle - m_Aeroplane.PitchAngle), -1, 1);
            }
        }
}using System;
using UnityEngine;

namespace UnityStandardAssets.Effects
{
    [RequireComponent(typeof (SphereCollider))]
    public class AfterburnerPhysicsForce : MonoBehaviour
    {
        public float effectAngle = 15;
        public float effectWidth = 1;
        public float effectDistance = 10;
        public float force = 10;

        private Collider[] m_Cols;
        private SphereCollider m_Sphere;
```

```
        private void OnEnable()
        {
            m_Sphere = (GetComponent<Collider>() as SphereCollider);
        }


        private void FixedUpdate()
        {
            m_Cols = Physics.OverlapSphere(transform.position + m_Sphere.center,
m_Sphere.radius);
            for (int n = 0; n < m_Cols.Length; ++n)
            {
                if (m_Cols[n].attachedRigidbody != null)
                {
                    Vector3 localPos =
transform.InverseTransformPoint(m_Cols[n].transform.position);
                    localPos = Vector3.MoveTowards(localPos, new Vector3(0, 0,
localPos.z), effectWidth*0.5f);
                    float angle = Mathf.Abs(Mathf.Atan2(localPos.x,
localPos.z)*Mathf.Rad2Deg);
                    float falloff = Mathf.InverseLerp(effectDistance, 0,
localPos.magnitude);
                    falloff *= Mathf.InverseLerp(effectAngle, 0, angle);
                    Vector3 delta = m_Cols[n].transform.position - transform.position;

m_Cols[n].attachedRigidbody.AddForceAtPosition(delta.normalized*force*falloff,

Vector3.Lerp(m_Cols[n].transform.position,

transform.TransformPoint(0, 0, localPos.z),

0.1f));
                }
            }
        }


        private void OnDrawGizmosSelected()
        {
            //check for editor time simulation to avoid null ref
            if(m_Sphere == null)
                m_Sphere = (GetComponent<Collider>() as SphereCollider);

            m_Sphere.radius = effectDistance*.5f;
```

```
                m_Sphere.center = new Vector3(0, 0, effectDistance*.5f);
                var directions = new Vector3[] {Vector3.up, -Vector3.up, Vector3.right, -Vector3.right};
                var perpDirections = new Vector3[] {-Vector3.right, Vector3.right, Vector3.up, -Vector3.up};
                Gizmos.color = new Color(0, 1, 0, 0.5f);
                for (int n = 0; n < 4; ++n)
                {
                    Vector3 origin = transform.position + transform.rotation*directions[n]*effectWidth*0.5f;

                    Vector3 direction =
                        transform.TransformDirection(Quaternion.AngleAxis(effectAngle, perpDirections[n])*Vector3.forward);

                    Gizmos.DrawLine(origin, origin + direction*m_Sphere.radius*2);
                }
            }
        }
    }
    using System;
    using UnityEngine;

    namespace UnityStandardAssets.Characters.ThirdPerson
    {
        [RequireComponent(typeof (UnityEngine.AI.NavMeshAgent))]
        [RequireComponent(typeof (ThirdPersonCharacter))]
        public class AICharacterControl : MonoBehaviour
        {
            public UnityEngine.AI.NavMeshAgent agent { get; private set; }                // the navmesh agent required for the path finding
            public ThirdPersonCharacter character { get; private set; } // the character we are controlling
            public Transform target;                                                    // target to aim for


            private void Start()
            {
                // get the components on the object we need ( should not be null due to require component so no need to check )
                agent = GetComponentInChildren<UnityEngine.AI.NavMeshAgent>();
                character = GetComponent<ThirdPersonCharacter>();
```

```
            agent.updateRotation = false;
            agent.updatePosition = true;
        }


        private void Update()
        {
            if (target != null)
                agent.SetDestination(target.position);

            if (agent.remainingDistance > agent.stoppingDistance)
                character.Move(agent.desiredVelocity, false, false);
            else
                character.Move(Vector3.zero, false, false);
        }


        public void SetTarget(Transform target)
        {
            this.target = target;
        }
    }
}using UnityEngine.PostProcessing;

namespace UnityEditor.PostProcessing
{
    using Settings = AmbientOcclusionModel.Settings;

    [PostProcessingModelEditor(typeof(AmbientOcclusionModel))]
    public class AmbientOcclusionModelEditor : PostProcessingModelEditor
    {
        SerializedProperty m_Intensity;
        SerializedProperty m_Radius;
        SerializedProperty m_SampleCount;
        SerializedProperty m_Downsampling;
        SerializedProperty m_ForceForwardCompatibility;
        SerializedProperty m_AmbientOnly;
        SerializedProperty m_HighPrecision;

        public override void OnEnable()
        {
            m_Intensity = FindSetting((Settings x) => x.intensity);
            m_Radius = FindSetting((Settings x) => x.radius);
            m_SampleCount = FindSetting((Settings x) => x.sampleCount);
```

```
            m_Downsampling = FindSetting((Settings x) => x.downsampling);
            m_ForceForwardCompatibility = FindSetting((Settings x) =>
x.forceForwardCompatibility);
            m_AmbientOnly = FindSetting((Settings x) => x.ambientOnly);
            m_HighPrecision = FindSetting((Settings x) => x.highPrecision);
        }

        public override void OnInspectorGUI()
        {
            EditorGUILayout.PropertyField(m_Intensity);
            EditorGUILayout.PropertyField(m_Radius);
            EditorGUILayout.PropertyField(m_SampleCount);
            EditorGUILayout.PropertyField(m_Downsampling);
            EditorGUILayout.PropertyField(m_ForceForwardCompatibility);
            EditorGUILayout.PropertyField(m_HighPrecision,
EditorGUIHelper.GetContent("High Precision (Forward)"));

            using (new
EditorGUI.DisabledGroupScope(m_ForceForwardCompatibility.boolValue))
                EditorGUILayout.PropertyField(m_AmbientOnly,
EditorGUIHelper.GetContent("Ambient Only (Deferred + HDR)"));
        }
    }
}
using System;
using UnityEngine;

namespace UnityStandardAssets.ImageEffects
{
    public enum AAMode
    {
        FXAA2 = 0,
        FXAA3Console = 1,
        FXAA1PresetA = 2,
        FXAA1PresetB = 3,
        NFAA = 4,
        SSAA = 5,
        DLAA = 6,
    }

    [ExecuteInEditMode]
    [RequireComponent(typeof (Camera))]
    [AddComponentMenu("Image Effects/Other/Antialiasing")]
    public class Antialiasing : PostEffectsBase
```

```
{
    public AAMode mode = AAMode.FXAA3Console;

    public bool showGeneratedNormals = false;
    public float offsetScale = 0.2f;
    public float blurRadius = 18.0f;

    public float edgeThresholdMin = 0.05f;
    public float edgeThreshold = 0.2f;
    public float edgeSharpness = 4.0f;

    public bool dlaaSharp = false;

    public Shader ssaaShader;
    private Material ssaa;
    public Shader dlaaShader;
    private Material dlaa;
    public Shader nfaaShader;
    private Material nfaa;
    public Shader shaderFXAAPreset2;
    private Material materialFXAAPreset2;
    public Shader shaderFXAAPreset3;
    private Material materialFXAAPreset3;
    public Shader shaderFXAAII;
    private Material materialFXAAII;
    public Shader shaderFXAAIII;
    private Material materialFXAAIII;


    public Material CurrentAAMaterial()
    {
        Material returnValue = null;

        switch (mode)
        {
            case AAMode.FXAA3Console:
                returnValue = materialFXAAIII;
                break;
            case AAMode.FXAA2:
                returnValue = materialFXAAII;
                break;
            case AAMode.FXAA1PresetA:
                returnValue = materialFXAAPreset2;
                break;
```

```
                case AAMode.FXAA1PresetB:
                    returnValue = materialFXAAPreset3;
                    break;
                case AAMode.NFAA:
                    returnValue = nfaa;
                    break;
                case AAMode.SSAA:
                    returnValue = ssaa;
                    break;
                case AAMode.DLAA:
                    returnValue = dlaa;
                    break;
                default:
                    returnValue = null;
                    break;
            }

            return returnValue;
        }


        public override bool CheckResources()
        {
            CheckSupport(false);

            materialFXAAPreset2 = CreateMaterial(shaderFXAAPreset2,
materialFXAAPreset2);
            materialFXAAPreset3 = CreateMaterial(shaderFXAAPreset3,
materialFXAAPreset3);
            materialFXAAII = CreateMaterial(shaderFXAAII, materialFXAAII);
            materialFXAAIII = CreateMaterial(shaderFXAAIII, materialFXAAIII);
            nfaa = CreateMaterial(nfaaShader, nfaa);
            ssaa = CreateMaterial(ssaaShader, ssaa);
            dlaa = CreateMaterial(dlaaShader, dlaa);

            if (!ssaaShader.isSupported)
            {
                NotSupported();
                ReportAutoDisable();
            }

            return isSupported;
        }
```

```
        public void OnRenderImage(RenderTexture source, RenderTexture destination)
        {
            if (CheckResources() == false)
            {
                Graphics.Blit(source, destination);
                return;
            }

            // ----------------------------------------------------------------
            // FXAA antialiasing modes

            if (mode == AAMode.FXAA3Console && (materialFXAAIII != null))
            {
                materialFXAAIII.SetFloat("_EdgeThresholdMin", edgeThresholdMin);
                materialFXAAIII.SetFloat("_EdgeThreshold", edgeThreshold);
                materialFXAAIII.SetFloat("_EdgeSharpness", edgeSharpness);

                Graphics.Blit(source, destination, materialFXAAIII);
            }
            else if (mode == AAMode.FXAA1PresetB && (materialFXAAPreset3 != null))
            {
                Graphics.Blit(source, destination, materialFXAAPreset3);
            }
            else if (mode == AAMode.FXAA1PresetA && materialFXAAPreset2 != null)
            {
                source.anisoLevel = 4;
                Graphics.Blit(source, destination, materialFXAAPreset2);
                source.anisoLevel = 0;
            }
            else if (mode == AAMode.FXAA2 && materialFXAAII != null)
            {
                Graphics.Blit(source, destination, materialFXAAII);
            }
            else if (mode == AAMode.SSAA && ssaa != null)
            {
                //
----------------------------------------------------------------
                // SSAA antialiasing
                Graphics.Blit(source, destination, ssaa);
            }
            else if (mode == AAMode.DLAA && dlaa != null)
            {
                //
```

```
------------------------------------------------------------
                    // DLAA antialiasing

                    source.anisoLevel = 0;
                    RenderTexture interim = RenderTexture.GetTemporary(source.width,
source.height);
                    Graphics.Blit(source, interim, dlaa, 0);
                    Graphics.Blit(interim, destination, dlaa, dlaaSharp ? 2 : 1);
                    RenderTexture.ReleaseTemporary(interim);
                }
                else if (mode == AAMode.NFAA && nfaa != null)
                {
                    //
------------------------------------------------------------
                    // nfaa antialiasing

                    source.anisoLevel = 0;

                    nfaa.SetFloat("_OffsetScale", offsetScale);
                    nfaa.SetFloat("_BlurRadius", blurRadius);

                    Graphics.Blit(source, destination, nfaa, showGeneratedNormals ? 1 : 0);
                }
                else
                {
                    // none of the AA is supported, fallback to a simple blit
                    Graphics.Blit(source, destination);
                }
            }
        }
}using System;

namespace UnityEngine.PostProcessing
{
    [Serializable]
    public class AntialiasingModel : PostProcessingModel
    {
        public enum Method
        {
            Fxaa,
            Taa
        }

        // Most settings aren't exposed to the user anymore, presets are enough. Still, I'm
```

```
leaving
        // the tooltip attributes in case an user wants to customize each preset.

        #region FXAA Settings
        public enum FxaaPreset
        {
            ExtremePerformance,
            Performance,
            Default,
            Quality,
            ExtremeQuality
        }

        [Serializable]
        public struct FxaaQualitySettings
        {
            [Tooltip("The amount of desired sub-pixel aliasing removal. Effects the sharpeness of the output.")]
            [Range(0f, 1f)]
            public float subpixelAliasingRemovalAmount;

            [Tooltip("The minimum amount of local contrast required to qualify a region as containing an edge.")]
            [Range(0.063f, 0.333f)]
            public float edgeDetectionThreshold;

            [Tooltip("Local contrast adaptation value to disallow the algorithm from executing on the darker regions.")]
            [Range(0f, 0.0833f)]
            public float minimumRequiredLuminance;

            public static FxaaQualitySettings[] presets =
            {
                // ExtremePerformance
                new FxaaQualitySettings
                {
                    subpixelAliasingRemovalAmount = 0f,
                    edgeDetectionThreshold = 0.333f,
                    minimumRequiredLuminance = 0.0833f
                },

                // Performance
                new FxaaQualitySettings
                {
```

```
                subpixelAliasingRemovalAmount = 0.25f,
                edgeDetectionThreshold = 0.25f,
                minimumRequiredLuminance = 0.0833f
            },

            // Default
            new FxaaQualitySettings
            {
                subpixelAliasingRemovalAmount = 0.75f,
                edgeDetectionThreshold = 0.166f,
                minimumRequiredLuminance = 0.0833f
            },

            // Quality
            new FxaaQualitySettings
            {
                subpixelAliasingRemovalAmount = 1f,
                edgeDetectionThreshold = 0.125f,
                minimumRequiredLuminance = 0.0625f
            },

            // ExtremeQuality
            new FxaaQualitySettings
            {
                subpixelAliasingRemovalAmount = 1f,
                edgeDetectionThreshold = 0.063f,
                minimumRequiredLuminance = 0.0312f
            }
        };
    }

    [Serializable]
    public struct FxaaConsoleSettings
    {
        [Tooltip("The amount of spread applied to the sampling coordinates while sampling for subpixel information.")]
        [Range(0.33f, 0.5f)]
        public float subpixelSpreadAmount;

        [Tooltip("This value dictates how sharp the edges in the image are kept; a higher value implies sharper edges.")]
        [Range(2f, 8f)]
        public float edgeSharpnessAmount;
```

```
        [Tooltip("The minimum amount of local contrast required to qualify a region as containing an edge.")]
        [Range(0.125f, 0.25f)]
        public float edgeDetectionThreshold;

        [Tooltip("Local contrast adaptation value to disallow the algorithm from executing on the darker regions.")]
        [Range(0.04f, 0.06f)]
        public float minimumRequiredLuminance;

        public static FxaaConsoleSettings[] presets =
        {
            // ExtremePerformance
            new FxaaConsoleSettings
            {
                subpixelSpreadAmount = 0.33f,
                edgeSharpnessAmount = 8f,
                edgeDetectionThreshold = 0.25f,
                minimumRequiredLuminance = 0.06f
            },

            // Performance
            new FxaaConsoleSettings
            {
                subpixelSpreadAmount = 0.33f,
                edgeSharpnessAmount = 8f,
                edgeDetectionThreshold = 0.125f,
                minimumRequiredLuminance = 0.06f
            },

            // Default
            new FxaaConsoleSettings
            {
                subpixelSpreadAmount = 0.5f,
                edgeSharpnessAmount = 8f,
                edgeDetectionThreshold = 0.125f,
                minimumRequiredLuminance = 0.05f
            },

            // Quality
            new FxaaConsoleSettings
            {
                subpixelSpreadAmount = 0.5f,
                edgeSharpnessAmount = 4f,
```

```
                edgeDetectionThreshold = 0.125f,
                minimumRequiredLuminance = 0.04f
            },

            // ExtremeQuality
            new FxaaConsoleSettings
            {
                subpixelSpreadAmount = 0.5f,
                edgeSharpnessAmount = 2f,
                edgeDetectionThreshold = 0.125f,
                minimumRequiredLuminance = 0.04f
            }
        };
    }

    [Serializable]
    public struct FxaaSettings
    {
        public FxaaPreset preset;

        public static FxaaSettings defaultSettings
        {
            get
            {
                return new FxaaSettings
                {
                    preset = FxaaPreset.Default
                };
            }
        }
    }
    #endregion

    #region TAA Settings
    [Serializable]
    public struct TaaSettings
    {
        [Tooltip("The diameter (in texels) inside which jitter samples are spread. Smaller values result in crisper but more aliased output, while larger values result in more stable but blurrier output.")]
        [Range(0.1f, 1f)]
        public float jitterSpread;

        [Tooltip("Controls the amount of sharpening applied to the color buffer.")]
```

```
        [Range(0f, 3f)]
        public float sharpen;

        [Tooltip("The blend coefficient for a stationary fragment. Controls the percentage of history sample blended into the final color.")]
        [Range(0f, 0.99f)]
        public float stationaryBlending;

        [Tooltip("The blend coefficient for a fragment with significant motion. Controls the percentage of history sample blended into the final color.")]
        [Range(0f, 0.99f)]
        public float motionBlending;

        public static TaaSettings defaultSettings
        {
            get
            {
                return new TaaSettings
                {
                    jitterSpread = 0.75f,
                    sharpen = 0.3f,
                    stationaryBlending = 0.95f,
                    motionBlending = 0.85f
                };
            }
        }
    }
    #endregion

    [Serializable]
    public struct Settings
    {
        public Method method;
        public FxaaSettings fxaaSettings;
        public TaaSettings taaSettings;

        public static Settings defaultSettings
        {
            get
            {
                return new Settings
                {
                    method = Method.Fxaa,
                    fxaaSettings = FxaaSettings.defaultSettings,
```

```
                                taaSettings = TaaSettings.defaultSettings
                            };
                        }
                    }
                }

                [SerializeField]
                Settings m_Settings = Settings.defaultSettings;
                public Settings settings
                {
                    get { return m_Settings; }
                    set { m_Settings = value; }
                }

                public override void Reset()
                {
                    m_Settings = Settings.defaultSettings;
                }
            }
        }
        using UnityEngine;
        using UnityEngine.PostProcessing;

        namespace UnityEditor.PostProcessing
        {
            using Method = AntialiasingModel.Method;
            using Settings = AntialiasingModel.Settings;

            [PostProcessingModelEditor(typeof(AntialiasingModel))]
            public class AntialiasingModelEditor : PostProcessingModelEditor
            {
                SerializedProperty m_Method;

                SerializedProperty m_FxaaPreset;

                SerializedProperty m_TaaJitterSpread;
                SerializedProperty m_TaaSharpen;
                SerializedProperty m_TaaStationaryBlending;
                SerializedProperty m_TaaMotionBlending;

                static string[] s_MethodNames =
                {
                    "Fast Approximate Anti-aliasing",
                    "Temporal Anti-aliasing"
```

```
        };

        public override void OnEnable()
        {
            m_Method = FindSetting((Settings x) => x.method);

            m_FxaaPreset = FindSetting((Settings x) => x.fxaaSettings.preset);

            m_TaaJitterSpread = FindSetting((Settings x) => x.taaSettings.jitterSpread);
            m_TaaSharpen = FindSetting((Settings x) => x.taaSettings.sharpen);
            m_TaaStationaryBlending = FindSetting((Settings x) =>
x.taaSettings.stationaryBlending);
            m_TaaMotionBlending = FindSetting((Settings x) =>
x.taaSettings.motionBlending);
        }

        public override void OnInspectorGUI()
        {
            m_Method.intValue = EditorGUILayout.Popup("Method", m_Method.intValue,
s_MethodNames);

            if (m_Method.intValue == (int)Method.Fxaa)
            {
                EditorGUILayout.PropertyField(m_FxaaPreset);
            }
            else if (m_Method.intValue == (int)Method.Taa)
            {
                if (QualitySettings.antiAliasing > 1)
                    EditorGUILayout.HelpBox("Temporal Anti-Aliasing doesn't work
correctly when MSAA is enabled.", MessageType.Warning);

                EditorGUILayout.LabelField("Jitter", EditorStyles.boldLabel);
                EditorGUI.indentLevel++;
                EditorGUILayout.PropertyField(m_TaaJitterSpread,
EditorGUIHelper.GetContent("Spread"));
                EditorGUI.indentLevel--;

                EditorGUILayout.Space();

                EditorGUILayout.LabelField("Blending", EditorStyles.boldLabel);
                EditorGUI.indentLevel++;
                EditorGUILayout.PropertyField(m_TaaStationaryBlending,
EditorGUIHelper.GetContent("Stationary"));
                EditorGUILayout.PropertyField(m_TaaMotionBlending,
```

```
EditorGUIHelper.GetContent("Motion"));
                    EditorGUI.indentLevel--;

                    EditorGUILayout.Space();

                    EditorGUILayout.PropertyField(m_TaaSharpen);
                }
            }
        }
}
using System.Collections;
using System.Collections.Generic;
using UnityEngine;
using UnityEngine.UI;
using UnityEngine.SceneManagement;


public class AsyncLoad : MonoBehaviour {

    // public Image FG;
    public Text tishi_ui;
    public Text progressText;
    public Transform jiazai;
    string[] tishi=new string[5];
    private static string NextScene;
    public Sprite[] BG_ImageList;
    public Image BG;
    public static void LoadingScene(string sceneName)
    {
        NextScene = sceneName;
        SceneManager.LoadScene("AsyncLoad");
    }
    bool n=true;
    // Use this for initialization

    void Start()
    {
        BG.sprite = BG_ImageList[Random.Range(0, 5)];

        tishi[0] = "温馨小提示：浮动螺母用于配合螺丝钉的安装，以便于固定螺钉。";
        tishi[1] = "温馨小提示：U 与 U 之间的分界线作为计算设备安装空间的参考点。";
        tishi[2] = "温馨小提示：在使用功率超过特定瓦数的用电设备前，必须得到上级主
管批准，并在保证线路安全的基础上使用。";
        tishi[3] = "温馨小提示：工作人员离开工作区域前，应保证工作区域内保存的重要
```

```
文件、资料、设备、数据处于安全保护状态。";
        tishi[4] = "温馨小提示：在使用功率超过特定瓦数的用电设备前，必须得到上级主管批准，并在保证线路安全的基础上使用。";

        tishi_ui.text = tishi[Random.Range(0,5)];

    }
    void Update()
    {
        progressText.text = (int)(currentProgress * 100) + "%";
        jiazai.Rotate(new Vector3(0, 0, 1), -Time.deltaTime * 300);
        if(n)
        {
            n = false;
            StartCoroutine(Load());
        }

    }

    AsyncOperation async;
    float currentProgress = 0;
    IEnumerator Load()
    {

        async = SceneManager.LoadSceneAsync(NextScene);
        async.allowSceneActivation = false;//不允许场景激活

        while (!async.isDone)//加载是否完成
        {
            if (async.progress >= 0.9F)
            {
                break;
            }
            if (currentProgress < async.progress)//加载的进度
            {
                currentProgress += 0.01F;

            }
            yield return new WaitForEndOfFrame();
            //FG.fillAmount = currentProgress;
        }
        while (currentProgress < 1F)
        {
            currentProgress += 0.01F;
```

```
                yield return new WaitForEndOfFrame();
                //FG.fillAmount = currentProgress;
            }
            async.allowSceneActivation = true;//允许场景激活
            async = null;
            NextScene = string.Empty;
            yield return async;
        }



}

using System;
using UnityEngine;
#if UNITY_EDITOR

#endif

namespace UnityStandardAssets.Cameras
{
    [ExecuteInEditMode]
    public class AutoCam : PivotBasedCameraRig
    {
        [SerializeField] private float m_MoveSpeed = 3; // How fast the rig will move to keep up with target's position
        [SerializeField] private float m_TurnSpeed = 1; // How fast the rig will turn to keep up with target's rotation
        [SerializeField] private float m_RollSpeed = 0.2f;// How fast the rig will roll (around Z axis) to match target's roll.
        [SerializeField] private bool m_FollowVelocity = false;// Whether the rig will rotate in the direction of the target's velocity.
        [SerializeField] private bool m_FollowTilt = true; // Whether the rig will tilt (around X axis) with the target.
        [SerializeField] private float m_SpinTurnLimit = 90;// The threshold beyond which the camera stops following the target's rotation. (used in situations where a car spins out, for example)
        [SerializeField] private float m_TargetVelocityLowerLimit = 4f;// the minimum velocity above which the camera turns towards the object's velocity. Below this we use the object's forward direction.
        [SerializeField] private float m_SmoothTurnTime = 0.2f; // the smoothing for the camera's rotation

        private float m_LastFlatAngle; // The relative angle of the target and the rig from
```

```
the previous frame.
        private float m_CurrentTurnAmount; // How much to turn the camera
        private float m_TurnSpeedVelocityChange; // The change in the turn speed velocity
        private Vector3 m_RollUp = Vector3.up;// The roll of the camera around the z axis
( generally this will always just be up )


        protected override void FollowTarget(float deltaTime)
        {
            // if no target, or no time passed then we quit early, as there is nothing to do
            if (!(deltaTime > 0) || m_Target == null)
            {
                return;
            }

            // initialise some vars, we'll be modifying these in a moment
            var targetForward = m_Target.forward;
            var targetUp = m_Target.up;

            if (m_FollowVelocity && Application.isPlaying)
            {
                // in follow velocity mode, the camera's rotation is aligned towards the
object's velocity direction
                // but only if the object is traveling faster than a given threshold.

                if (targetRigidbody.velocity.magnitude > m_TargetVelocityLowerLimit)
                {
                    // velocity is high enough, so we'll use the target's velocty
                    targetForward = targetRigidbody.velocity.normalized;
                    targetUp = Vector3.up;
                }
                else
                {
                    targetUp = Vector3.up;
                }
                m_CurrentTurnAmount = Mathf.SmoothDamp(m_CurrentTurnAmount, 1,
ref m_TurnSpeedVelocityChange, m_SmoothTurnTime);
            }
            else
            {
                // we're in 'follow rotation' mode, where the camera rig's rotation follows
the object's rotation.

                // This section allows the camera to stop following the target's rotation
```

```
when the target is spinning too fast.
                    // eg when a car has been knocked into a spin. The camera will resume
following the rotation
                    // of the target when the target's angular velocity slows below the
threshold.
                    var currentFlatAngle = Mathf.Atan2(targetForward.x,
targetForward.z)*Mathf.Rad2Deg;
                    if (m_SpinTurnLimit > 0)
                    {
                        var targetSpinSpeed = Mathf.Abs(Mathf.DeltaAngle(m_LastFlatAngle,
currentFlatAngle))/deltaTime;
                        var desiredTurnAmount = Mathf.InverseLerp(m_SpinTurnLimit,
m_SpinTurnLimit*0.75f, targetSpinSpeed);
                        var turnReactSpeed = (m_CurrentTurnAmount >
desiredTurnAmount ? .1f : 1f);
                        if (Application.isPlaying)
                        {
                            m_CurrentTurnAmount =
Mathf.SmoothDamp(m_CurrentTurnAmount, desiredTurnAmount,
                                                ref
m_TurnSpeedVelocityChange, turnReactSpeed);
                        }
                        else
                        {
                            // for editor mode, smoothdamp won't work because it uses
deltaTime internally
                            m_CurrentTurnAmount = desiredTurnAmount;
                        }
                    }
                    else
                    {
                        m_CurrentTurnAmount = 1;
                    }
                    m_LastFlatAngle = currentFlatAngle;
                }

                // camera position moves towards target position:
                transform.position = Vector3.Lerp(transform.position, m_Target.position,
deltaTime*m_MoveSpeed);

                // camera's rotation is split into two parts, which can have independend speed
settings:
                // rotating towards the target's forward direction (which encompasses its 'yaw'
and 'pitch')
```

```
                if (!m_FollowTilt)
                {
                    targetForward.y = 0;
                    if (targetForward.sqrMagnitude < float.Epsilon)
                    {
                        targetForward = transform.forward;
                    }
                }
                var rollRotation = Quaternion.LookRotation(targetForward, m_RollUp);

                // and aligning with the target object's up direction (i.e. its 'roll')
                m_RollUp = m_RollSpeed > 0 ? Vector3.Slerp(m_RollUp, targetUp,
m_RollSpeed*deltaTime) : Vector3.up;
                transform.rotation = Quaternion.Lerp(transform.rotation, rollRotation,
m_TurnSpeed*m_CurrentTurnAmount*deltaTime);
            }
        }
}



using System;
using System.Collections.Generic;
using UnityEngine;
#if UNITY_EDITOR
using UnityEditor;
#endif

namespace UnityStandardAssets.Utility
{
    public class AutoMobileShaderSwitch : MonoBehaviour
    {
        [SerializeField] private ReplacementList m_ReplacementList;

        // Use this for initialization
        private void OnEnable()
        {
#if UNITY_IPHONE || UNITY_ANDROID || UNITY_WP8 || UNITY_TIZEN
            var renderers = FindObjectsOfType<Renderer>();
            Debug.Log (renderers.Length+" renderers");
            var oldMaterials = new List<Material>();
            var newMaterials = new List<Material>();

            int materialsReplaced = 0;
```

```
        int materialInstancesReplaced = 0;

        foreach(ReplacementDefinition replacementDef in m_ReplacementList.items)
        {
            foreach(var r in renderers)
            {
                Material[] modifiedMaterials = null;
                for(int n=0; n<r.sharedMaterials.Length; ++n)
                {
                    var material = r.sharedMaterials[n];
                    if (material.shader == replacementDef.original)
                    {
                        if (modifiedMaterials == null)
                        {
                            modifiedMaterials = r.materials;
                        }
                        if (!oldMaterials.Contains(material))
                        {
                            oldMaterials.Add(material);
                            Material newMaterial = (Material)Instantiate(material);
                            newMaterial.shader = replacementDef.replacement;
                            newMaterials.Add(newMaterial);
                            ++materialsReplaced;
                        }
                        Debug.Log ("replacing "+r.gameObject.name+" renderer
"+n+" with "+newMaterials[oldMaterials.IndexOf(material)].name);
                        modifiedMaterials[n]                                    =
newMaterials[oldMaterials.IndexOf(material)];
                        ++materialInstancesReplaced;
                    }
                }
                if (modifiedMaterials != null)
                {
                    r.materials = modifiedMaterials;
                }
            }
        }
        Debug.Log (materialInstancesReplaced+" material instances replaced");
        Debug.Log (materialsReplaced+" materials replaced");
        for(int n=0; n<oldMaterials.Count; ++n)
        {
            Debug.Log                                   (oldMaterials[n].name+"
("+oldMaterials[n].shader.name+")"+"    replaced    with    "+newMaterials[n].name+"
("+newMaterials[n].shader.name+")");
```

```
            }
#endif
        }


        [Serializable]
        public class ReplacementDefinition
        {
            public Shader original = null;
            public Shader replacement = null;
        }

        [Serializable]
        public class ReplacementList
        {
            public ReplacementDefinition[] items = new ReplacementDefinition[0];
        }
    }
}

namespace UnityStandardAssets.Utility.Inspector
{
#if UNITY_EDITOR
    [CustomPropertyDrawer(typeof (AutoMobileShaderSwitch.ReplacementList))]
    public class ReplacementListDrawer : PropertyDrawer
    {
        const float k_LineHeight = 18;
        const float k_Spacing = 4;

        public override void OnGUI(Rect position, SerializedProperty property, GUIContent
label)
        {
            EditorGUI.BeginProperty(position, label, property);

            float x = position.x;
            float y = position.y;
            float inspectorWidth = position.width;

            // Don't make child fields be indented
            var indent = EditorGUI.indentLevel;
            EditorGUI.indentLevel = 0;

            var items = property.FindPropertyRelative("items");
            var titles = new string[] {"Original", "Replacement", ""};
```

```
var props = new string[] {"original", "replacement", "-"};
var widths = new float[] {.45f, .45f, .1f};
const float lineHeight = 18;
bool changedLength = false;
if (items.arraySize > 0)
{
    for (int i = -1; i < items.arraySize; ++i)
    {
        var item = items.GetArrayElementAtIndex(i);

        float rowX = x;
        for (int n = 0; n < props.Length; ++n)
        {
            float w = widths[n]*inspectorWidth;

            // Calculate rects
            Rect rect = new Rect(rowX, y, w, lineHeight);
            rowX += w;

            if (i == -1)
            {
                // draw title labels
                EditorGUI.LabelField(rect, titles[n]);
            }
            else
            {
                if (props[n] == "-" || props[n] == "^" || props[n] == "v")
                {
                    if (GUI.Button(rect, props[n]))
                    {
                        switch (props[n])
                        {
                            case "-":
                                items.DeleteArrayElementAtIndex(i);
                                items.DeleteArrayElementAtIndex(i);
                                changedLength = true;
                                break;
                            case "v":
                                if (i > 0)
                                {
                                    items.MoveArrayElement(i, i + 1);
                                }
                                break;
                            case "^":
```

```
                                        if (i < items.arraySize - 1)
                                        {
                                            items.MoveArrayElement(i, i - 1);
                                        }
                                        break;
                                    }
                                }
                            }
                            else
                            {
                                SerializedProperty prop = item.FindPropertyRelative(props[n]);
                                EditorGUI.PropertyField(rect, prop, GUIContent.none);
                            }
                        }
                    }

                    y += lineHeight + k_Spacing;
                    if (changedLength)
                    {
                        break;
                    }
                }
            }

            // add button
            var addButtonRect = new Rect((x + position.width) - widths[widths.Length - 1]*inspectorWidth, y,
                                         widths[widths.Length - 1]*inspectorWidth, lineHeight);
            if (GUI.Button(addButtonRect, "+"))
            {
                items.InsertArrayElementAtIndex(items.arraySize);
            }

            y += lineHeight + k_Spacing;

            // Set indent back to what it was
            EditorGUI.indentLevel = indent;
            EditorGUI.EndProperty();
        }


        public override float GetPropertyHeight(SerializedProperty property, GUIContent
```

```
label)
            {
                SerializedProperty items = property.FindPropertyRelative("items");
                float lineAndSpace = k_LineHeight + k_Spacing;
                return 40 + (items.arraySize*lineAndSpace) + lineAndSpace;
            }
        }
#endif
}
```