## Algorithmic Human-Robot Interaction

HRI 2019 Papers

Experiment Design

**CSCI 7000** 

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## Looking Ahead

3/26	Tuesday:	Spring Break
3/28	Thursday:	Spring Break
4/2	Tuesday:	ROS, Computer Vision and Robot Control
4/4	Thursday:	HRI 2019 Papers, Evaluation Workshop
4/9	Tuesday:	<b>Explainable AI and In-progress Project Presentations</b>
4/11	Thursday:	Explainable AI and XAI Papers
4/16	Tuesday:	(Inverse) Reinforcement Learning
4/18	Thursday:	(Inverse) Reinforcement Learning and RL Papers
4/23	Tuesday:	Guest Lecture – Dr. Alessandro Roncone

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# Papers coming up: **xAl**

Explanation-based Reward Coaching to Improve Human Performance via Reinforcement Learning by Tabrez et al.

Pro:

Con: Shivendra Agrawal

Improving Robot Controller Transparency Through Autonomous Policy Explanation by Hayes and Shah

Pro:

Con:

PRO:
Chandan Naik
Shohei Wakayama
Shruthi Sukumar

CON:

Ashwin Vasan Jack Kawell

# Papers for Today: HRI 2019

Transfer depends on Acquisition: Analyzing Manipulation Strategies for Robotic Feeding by Gallenberger et al.

Pro: Shivendra Agrawal

Con: Karthik Palavalli

Balanced Information Gathering and Goal-Oriented Actions in Shared Autonomy by Brooks et al.

Pro: Matthew Luebbers

Con: N/A

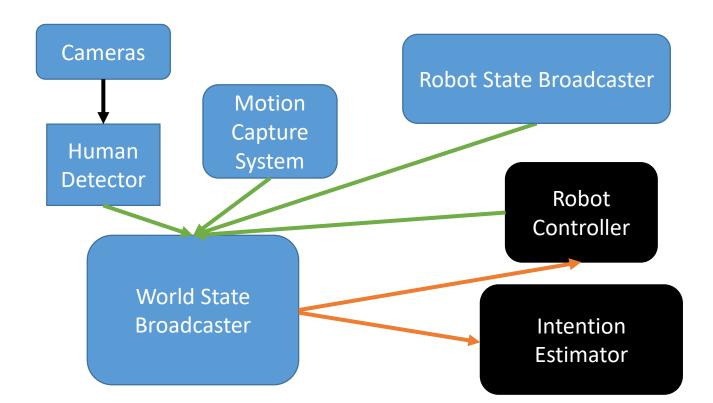




### Designing Your System

What is the state your system acts within? What are the features, and where do they come from?

Modular design is essential!



### Writing Your Paper

Plenty of good examples from weekly readings!

How would a class like this present *your* work?

Anticipate the cons, take ownership of them!

Be very clear when defining the conditions under which your solution applies.

## Designing Your Evaluation

### **Evaluation Design:**

What are your hypotheses about your system?
How will you test them?
What are you trying to prove with this work?

### **Experiment Design:**

Do you need human subjects?
Are your conditions likely to test your hypotheses?
Within-subjects or between-subjects?

#### **Protocol design:**

Someone not on your project should be able to run your experiment with this script!