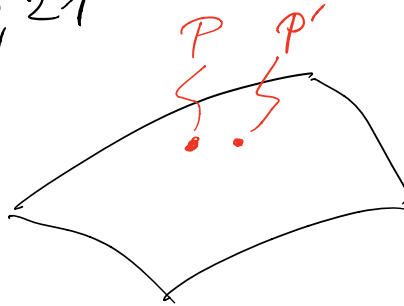


# RECAP: DIFFERENTIAL GEOMETRY

Hartle, § 7, 20, 21

Manifold  $\mathcal{M}$

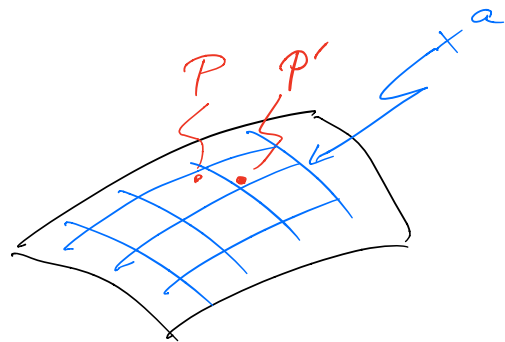


- Diff Geo deals with properties of  $\mathcal{M}$  which are independent of coordinates: "geometric" objects/properties.  
e.g. points, distances, gradients, Laplacian
- Often need coordinates to represent objects.

$$x^a, \quad a = 0, 1, \dots, d-1 \quad d = \text{dimension of } \mathcal{M}$$

- Point  $P$  represented by its coords  $x^a$   
nearby  $P'$  by  $x^a + dx^a$   
(squared)

- Distance between  $P$  and  $P'$ :



$$\boxed{ds^2 = g_{ab} dx^a dx^b} \quad (1)$$

Line-element

sum convention  $\rightarrow \sum_{a,b=0}^{d-1} g_{ab} dx^a dx^b$

- (1) generalizes Pythagoras
- Matrix  $g_{ab}$  can change from point to point  $g_{ab}$  = "Metric tensor"
- $P, P'$  and distance  $ds$  indep't of coordinates ("invariant")

• Coordinate trafo  $x^a \rightarrow x^{a'}$  to some other coords  $x^{a'}$

$f(x^{a'})$   
 $df = \frac{\partial f}{\partial x^{a'}} dx^{a'}$   
 $a' = 0$

$x^a(x^{a'})$   
 $dx^a = \frac{\partial x^a}{\partial x^{a'}} dx^{a'} \quad (2)$

$ds^2$  unchanged:

$$ds^2 = g_{ab} dx^a dx^b = g_{ab} \frac{\partial x^a}{\partial x^{a'}} \frac{\partial x^b}{\partial x^{b'}} dx^{a'} dx^{b'}$$

$$\stackrel{!}{=} g_{a'b'} dx^{a'} dx^{b'}$$

works iff  $\boxed{g_{a'b'} = g_{ab} \frac{\partial x^a}{\partial x^{a'}} \frac{\partial x^b}{\partial x^{b'}}} \quad (3)$  Transformation law of metric tensor  $g_{ab}$ .

# Tensors

Hartle §20

- geometric objects on  $\mathcal{M}$
- pragmatically, defined by trafo properties like (3).
- formally, defined as certain linear operators.  
e.g. vector field  $\vec{V}$  on  $\mathcal{M}$  is a directional derivative:

$$\vec{V} = V^a \frac{\partial}{\partial x^a}$$

This induces a linear map

$$(f: \mathcal{M} \rightarrow \mathbb{R}) \longrightarrow (g: \mathcal{M} \rightarrow \mathbb{R}) : g = V^a \frac{\partial f}{\partial x^a}.$$

Under coord trafo

$$\vec{V} = V^a \frac{\partial}{\partial x^a} = V^a \frac{\partial x^{a'}}{\partial x^a} \frac{\partial}{\partial x^{a'}} = V^{a'} \frac{\partial}{\partial x^{a'}}$$

iff  $V^{a'} = V^a \frac{\partial x^{a'}}{\partial x^a}$

geometric object  $\vec{V}(x^a) = V^a(x^a) \frac{\partial}{\partial x^a}$  basis

components

Trafo law of vector

$$\underline{g}(x^a) = g_{ab}(x^a) dx^a dx^b$$

basis  $\{ dx^a dx^b / a=0, \dots, d-1, b=0, \dots, d-1 \}$

## in General Relativity

$d = 4$  space-time

$g_{ab}$  has signature  $-+++$  everywhere



pseudo-Riemannian manifold

Minkowski-metric in special relativity

$$ds^2 = -dt^2 + dx^2 + dy^2 + dz^2$$

special case  $g_{\alpha\beta} = \begin{pmatrix} -1 & 0 & 0 & 0 \\ 0 & +1 & 0 & 0 \\ 0 & 0 & +1 & 0 \\ 0 & 0 & 0 & +1 \end{pmatrix}$

Light cones



line element  $ds^2$  invariant  $\Rightarrow$  light cone structure invariant

• Upper/lower indices

$V^a$

$g_{ab}$

- a.k.a. contravariant/covariant

- Transform differently under coord. trafo

$$V^a \rightarrow V^{a'} = \frac{\partial x^{a'}}{\partial x^a} V^a$$

$$W_b \rightarrow W_{b'} = \frac{\partial x^b}{\partial x^{b'}} W_b$$

one Jacobian per index

$$g_{a'b'} = \frac{\partial x^a}{\partial x^{a'}} \frac{\partial x^b}{\partial x^{b'}} g_{ab}$$

- Contraction between one upper + one lower index invariant:

$$V^a W_a \rightarrow V^{a'} W_{a'} = V^a \frac{\partial x^{a'}}{\partial x^a} \frac{\partial x^b}{\partial x^{a'}} W_b = V^a W_a$$

$\vec{V} \cdot \vec{W}$

$$= \underline{\underline{1}} = \delta_a^b \quad d \times d \text{ identity matrix}$$

Jacobian of inverse coord. trafo = inverse of Jacobian

$$\underbrace{\frac{\partial x^{a'}}{\partial x^a}}_{d \times d \text{ matrix}} = \left( \underbrace{\frac{\partial x^a}{\partial x^{a'}}}_{d \times d \text{ matrix}} \right)^{-1} \quad \text{matrix inverse}$$

- Therefore Einstein sum convention only between up+lo index

- lower an index w/ metric:

$$V_b = V^a g_{ab}$$

- raise index with inverse metric  $g^{ab} := (g_{ab})^{-1}$

$$w^b = g^{ab} w_a$$

matrix inverse  
↖  
↗  
dx dx matrix

- in contractions,  $g_{ab}$  &  $g^{ab}$  cancel each other

$$\underline{\underline{V_b w^b}} = V^a \underbrace{g_{ab} g^{cb}}_{\underline{\underline{1}} = \delta_a^c} w_c = \underline{\underline{V^a w_a}}$$

identity matrix

$$V^a \underbrace{\delta_a^c}_{= w_a} w_c = V^a w_a$$