Brand Maps & PCA

1. Build brand maps for car brands for the client's brand - Infinity.

```
rm(list=ls(all=TRUE))

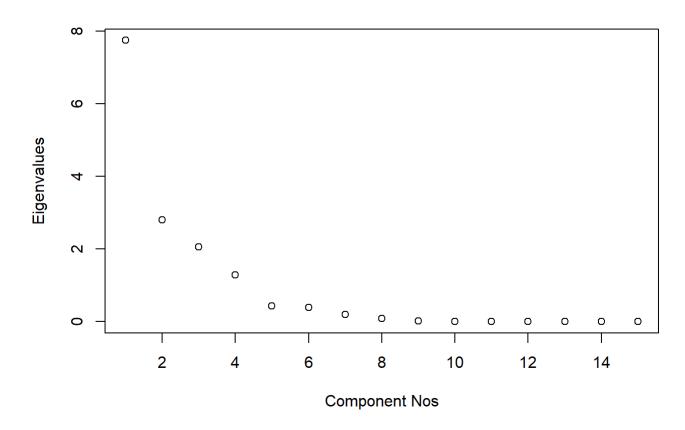
cars <- read.csv("Cars_Data.csv", header=T)

y <- cars[,17]
x <- as.matrix(cars[,2:16])
data <- cbind(y,x)
cor_mat = cor(x)

out1 <- eigen(cor_mat) # eigen decomposition of correlation matrix
va <- out1$values # eigenvalues
ve <- out1$vectors # eigenvector</pre>
```

2. Determine how many factors to retain?

```
# scree plot
plot(va, ylab = "Eigenvalues", xlab = "Component Nos")
```



```
ego <- va[va > 1]  # eigenvalues > 1
nn <- nrow(as.matrix(ego))  # number of factors to retain
print(paste("Factors to retain : ", nn))</pre>
```

```
## [1] "Factors to retain : 4"
```

3. Assign names to the retained factors

```
##
## Call:
## lm(formula = v \sim z)
##
## Residuals:
                                       5
                        3
##
## -0.11977 -0.11788
##
## Coefficients:
             Estimate Std. Error t value Pr(>|t|)
## (Intercept) 2.18458
                       0.43161 5.061 0.003895 **
## z1
             -0.68944
                       0.07258 -9.499 0.000219 ***
## z2
             -0.28516
                       0.11920 -2.392 0.062209 .
## z3
              0.46138
                       0.11900 3.877 0.011675 *
## z4
              0.21219
                       0.21267 0.998 0.364205
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
## Residual standard error: 0.303 on 5 degrees of freedom
## Multiple R-squared: 0.9742, Adjusted R-squared: 0.9536
## F-statistic: 47.21 on 4 and 5 DF, p-value: 0.0003671
```

```
# Since estimates should be positive, flipping the eigenvectors for Z1 and Z2

out4 <- out3

out4[,1] <- (-1)*out4[,1]
 out4[,2] <- (-1)*out4[,2]

z = x %*% out4

pref_reg = lm(y ~ z)

summary(pref_reg)</pre>
```

```
##
## Call:
## lm(formula = y \sim z)
##
## Residuals:
       1
             2
                     3 4 5 6 7
##
       9
## -0.11977 -0.11788
##
## Coefficients:
##
           Estimate Std. Error t value Pr(>|t|)
## (Intercept) 2.18458
                   0.43161 5.061 0.003895 **
## z1
            0.68944
                   0.07258 9.499 0.000219 ***
            0.28516   0.11920   2.392   0.062209 .
## z2
## z3
            ## z4
            0.21219 0.21267 0.998 0.364205
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 0.303 on 5 degrees of freedom
## Multiple R-squared: 0.9742, Adjusted R-squared: 0.9536
## F-statistic: 47.21 on 4 and 5 DF, p-value: 0.0003671
```

```
# eliminating Z4 as is it not significant

out4 <- out4[,1:3]

out4</pre>
```

```
[,3]
##
                      [,1]
                                [,2]
## Attractive
                 0.3262814 0.0000000 0.0000000
## Quiet
                 0.3173818 0.0000000 0.0000000
## Unreliable
                 0.0000000 0.4011014 0.0000000
## Poorly.Built -0.3319244 0.0000000 0.0000000
## Interesting
                 0.0000000 0.0000000 -0.4290683
## Sporty
                 0.0000000 -0.4288285
                                      0.0000000
## Uncomfortable 0.0000000 0.0000000 0.0000000
## Roomy
                 0.0000000 0.3789204 0.0000000
## Easy.Service 0.0000000 -0.4279673 0.0000000
## Prestige
                 0.3322855 0.0000000 0.0000000
## Common
                 0.0000000 0.0000000 0.0000000
## Economical
                 0.0000000 0.0000000
                                      0.6642165
## Successful
                 0.3155394 0.0000000
                                      0.0000000
## AvantGarde
                 0.0000000 0.0000000 0.0000000
## Poor.Value
                 0.0000000 0.0000000 -0.4710589
```

Names

Z1 - Premium

Z2 - Unreliable

Z3 - Value for Money

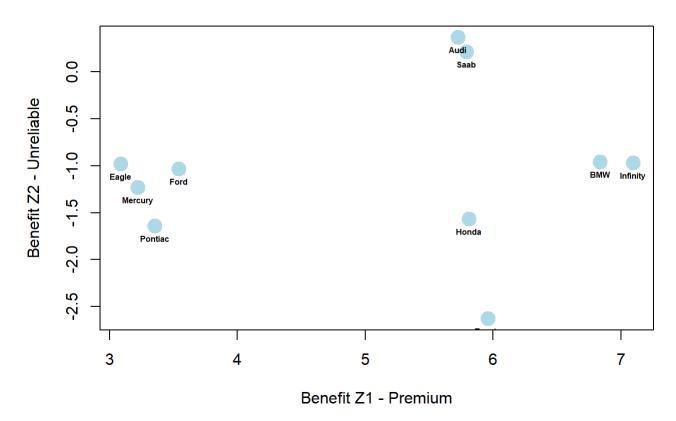
4. Compute the angles of iso-preference line and ideal vector arrow

Brand Maps

```
Z1 = z[,1]
Z2 = z[,2]
z.out = cbind(Z1, Z2)
rownames(z.out) = cars[,1]

plot(Z1, Z2, main = "Brands in Z1 and Z2 space", xlab = "Benefit Z1 - Premium", ylab = "Benefit Z2 - Unreliable", col = "lig
htblue", pch = 19, cex = 2) # Brand Map in Z1-Z2 space
text(z.out, labels = row.names(z.out), font = 2, cex = 0.5, pos = 1) # labeling brands
```

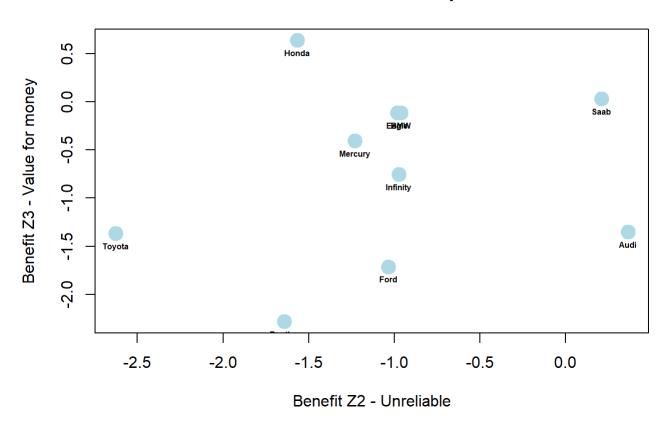
Brands in Z1 and Z2 space



```
Z3 = z[,3]
z1.out = cbind(Z2, Z3)
rownames(z1.out) = cars[,1]

plot(Z2, Z3, main = "Brands in Z2 and Z3 space", xlab = "Benefit Z2 - Unreliable", ylab = "Benefit Z3 - Value for money", co
l = "lightblue", pch = 19, cex = 2) # Brand Map in Z2-Z3 space
text(z1.out, labels = row.names(z1.out), font = 2, cex = 0.5, pos = 1) # labeling brands
```

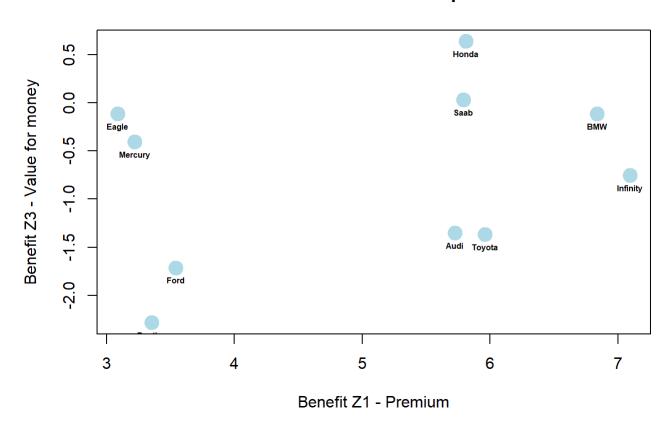
Brands in Z2 and Z3 space



```
z2.out = cbind(Z1, Z3)
rownames(z2.out) = cars[,1]

plot(Z1, Z3, main = "Brands in Z1 and Z3 space", xlab = "Benefit Z1 - Premium", ylab = "Benefit Z3 - Value for money", col =
"lightblue", pch = 19, cex = 2) # Brand Map in Z1-Z2 space
text(z2.out, labels = row.names(z2.out), font = 2, cex = 0.5, pos = 1) # labeling brands
```

Brands in Z1 and Z3 space



Slopes of iso-preference and ideal vector

```
b1 = as.vector(coef(pref_reg)[2])
b2 = as.vector(coef(pref_reg)[3])
slope.iso.preference = - b1/b2
slope.ideal.vector = b2/b1

# Angles of iso-preference and ideal vector

angle.iso.preference = atan(slope.iso.preference)*180/pi
angle.ideal.vector = atan(slope.ideal.vector)*180/pi
print(paste("angle.iso.preference : ", angle.iso.preference))
```

```
## [1] "angle.iso.preference : -67.5297112315307"
```

```
print(paste("angle.ideal.vector : ", angle.ideal.vector))
```

```
## [1] "angle.ideal.vector : 22.4702887684693"
```

For Z2 and Z3

```
b3 = as.vector(coef(pref_reg)[4])
slope.iso.preference = - b2/b3
slope.ideal.vector = b3/b2

# Angles of iso-preference and ideal vector

angle.iso.preference = atan(slope.iso.preference)*180/pi
angle.ideal.vector = atan(slope.ideal.vector)*180/pi
print(paste("angle.iso.preference : ", angle.iso.preference))
```

```
## [1] "angle.iso.preference : -31.7182997006912"
```

```
print(paste("angle.ideal.vector : ", angle.ideal.vector))
```

```
## [1] "angle.ideal.vector : 58.2817002993088"
```

For Z1 and Z3

```
slope.iso.preference = - b1/b3
slope.ideal.vector = b3/b1

# Angles of iso-preference and ideal vector

angle.iso.preference = atan(slope.iso.preference)*180/pi
angle.ideal.vector = atan(slope.ideal.vector)*180/pi
print(paste("angle.iso.preference : ", angle.iso.preference))
```

```
## [1] "angle.iso.preference : -56.2092740146157"
```

```
print(paste("angle.ideal.vector : ", angle.ideal.vector))
```

```
## [1] "angle.ideal.vector : 33.7907259853843"
```

5. Find 95% confidence interval for the angle of the ideal vector using data bootstrap method.

```
angle <- list()</pre>
r <- nrow(data)
set.seed(876)
# Do Data Bootstrap 1000 times to get 95% CI for R^2
for(i in 1:1000) {
   tryCatch({
              data.star <- data[sample(r, r, replace = T),] # create (y^*, x^*) by resampling rows in original data matrix
            ystar <- data.star[,1]</pre>
            xstar <- data.star[,2:16]</pre>
            cor mat = cor(xstar)
            o1 <- eigen(cor_mat) # eigen decomposition of correlation matrix
            va <- o1$values
                                        # eigenvalues
            ve <- o1$vectors
            ego <- va[va > 1]
                                                        # eigenvalues > 1
            n <- nrow(as.matrix(ego))</pre>
            o2 <- ve[,1:n]
                                                    # eigenvectors associated with the retained factors
            o3 <- ifelse(abs(o2) < 0.3, 0, o2) # ignore small values < 0.3
            rownames(o3) <- c("Attractive", "Quiet", "Unreliable", "Poorly.Built", "Interesting", "Sporty", "Uncomfortable",
"Roomy",
                                "Easy.Service", "Prestige", "Common", "Economical", "Successful", "AvantGarde", "Poor.Value"
                                            # Component Scores; coordinates of the brands in the map
            zstar = xstar %*% o3
            pref reg star = lm(ystar ~ zstar)
                                                   # Preference Regression to estimate how benefits drive overall preferenc
es = f(benefits)
            # flipping o3 if coefficients are negative
            for (j in 2:length(coef(pref_reg_star))){
              if(coef(pref reg star)[j] < 0){</pre>
                03[,j-1] = (-1)*03[,j-1]
              }
            # new model
            zstar = xstar %*% o3
            pref reg star = lm(ystar ~ zstar)
            # finding significant coefficients
```

```
cf <- data.frame(summary(pref_reg_star)$coef) # collecting coefficients
cf <- cf[-1,] # removing intercept
a <- cf[cf[,4] <= .05, 1] # taking significant coefficients only

# making sure that there are more than 1 significant variable
if(length(a) > 1){
    b <- t(combn(a, 2)) # creating pairs
    c <- c()

# calculating angle
for (k in 1:nrow(b)) {
    c <- c(c, atan(b[k,2]/b[k,1])*180/pi)
}

# saving the output
angle[[i]] <- c
}, error=function(e){})</pre>
```

```
## Warning in summary.lm(pref reg star): essentially perfect fit: summary may be
## unreliable
## Warning in summary.lm(pref reg star): essentially perfect fit: summary may be
## unreliable
## Warning in summary.lm(pref reg star): essentially perfect fit: summary may be
## unreliable
## Warning in summary.lm(pref reg_star): essentially perfect fit: summary may be
## unreliable
## Warning in summary.lm(pref reg star): essentially perfect fit: summary may be
## unreliable
## Warning in summary.lm(pref reg star): essentially perfect fit: summary may be
## unreliable
## Warning in summary.lm(pref reg star): essentially perfect fit: summary may be
## unreliable
## Warning in summary.lm(pref reg star): essentially perfect fit: summary may be
## unreliable
## Warning in summary.lm(pref_reg_star): essentially perfect fit: summary may be
## unreliable
## Warning in summary.lm(pref reg star): essentially perfect fit: summary may be
## unreliable
## Warning in summary.lm(pref reg star): essentially perfect fit: summary may be
## unreliable
## Warning in summary.lm(pref reg star): essentially perfect fit: summary may be
## unreliable
## Warning in summary.lm(pref_reg_star): essentially perfect fit: summary may be
## unreliable
```

```
## Warning in summary.lm(pref reg star): essentially perfect fit: summary may be
## unreliable
## Warning in summary.lm(pref reg star): essentially perfect fit: summary may be
## unreliable
## Warning in summary.lm(pref reg star): essentially perfect fit: summary may be
## unreliable
## Warning in summary.lm(pref reg star): essentially perfect fit: summary may be
## unreliable
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## unreliable
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## unreliable
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## unreliable
## Warning in summary.lm(pref reg star): essentially perfect fit: summary may be
## unreliable
## Warning in summary.lm(pref reg star): essentially perfect fit: summary may be
## unreliable
## Warning in summary.lm(pref reg star): essentially perfect fit: summary may be
## unreliable
## Warning in summary.lm(pref reg star): essentially perfect fit: summary may be
## unreliable
## Warning in summary.lm(pref reg star): essentially perfect fit: summary may be
## unreliable
```

```
## Warning in summary.lm(pref reg star): essentially perfect fit: summary may be
## unreliable
## Warning in summary.lm(pref reg star): essentially perfect fit: summary may be
## unreliable
## Warning in summary.lm(pref reg star): essentially perfect fit: summary may be
## unreliable
## Warning in summary.lm(pref reg star): essentially perfect fit: summary may be
## unreliable
## Warning in summary.lm(pref reg star): essentially perfect fit: summary may be
## unreliable
## Warning in summary.lm(pref reg star): essentially perfect fit: summary may be
## unreliable
## Warning in summary.lm(pref reg star): essentially perfect fit: summary may be
## unreliable
# removing nulls and converting it to data frame
```

```
# removing nulls and converting it to data frame

df <- plyr::ldply(angle, rbind)

df <- df[,colSums(is.na(df))<nrow(df)]</pre>
```

printing the confidence intervals for each pair of signficant betas.

```
for (i in 1:ncol(df)){
    print(paste("For pair : ", i))
    print(quantile(df[,i], probs = c(0.025, 0.975), na.rm = TRUE))
    print(paste("mean : ", mean(df[,i], na.rm = TRUE)))
}
```

```
## [1] "For pair : 1"
##
       2.5%
               97.5%
   4.45337 50.68285
## [1] "mean : 25.5694442549705"
## [1] "For pair : 2"
##
        2.5%
                 97.5%
   3.921029 54.509593
## [1] "mean : 27.981349621021"
## [1] "For pair : 3"
##
        2.5%
                 97.5%
## 7.146867 75.734755
## [1] "mean : 46.0685047089444"
## [1] "For pair : 4"
##
        2.5%
                 97.5%
   5.413237 83.393219
## [1] "mean : 45.7872411258584"
## [1] "For pair : 5"
        2.5%
                 97.5%
##
   4.482864 83.213689
## [1] "mean : 44.1959489869967"
## [1] "For pair : 6"
        2.5%
                 97.5%
## 4.095385 81.598240
## [1] "mean : 43.723438541603"
```

6. Recommend to Infinity's managers what they should do to improve their product design

We got three brand maps -

1. Premium vs unreliable - In this brand map, BMW is infinity's close competitor - with ideal vector at 22 degrees which leans towards premium feature.

Thus, infinity should work on premium cars which are attractive and well built.

2. unreliable vs value for money - In this brand map, Mercury, BMW, Eagle are infinity's close competitor - with ideal vector at 58 degrees which leans towards value for money feature.

Thus infinity should focus on economical and good value cars.

3. Premium vs value for money - In this brand map, BMW is infinity's close competitor - with ideal vector at 33 degrees which leans towards premium feature.

Thus, infinity should work on premium cars which are attractive and well built.