

In [2]:

```
import pandas as pd
import cv2
import numpy as np
```

## Imported dataset

Facial Emotion Recognition dataset

In [3]:

```
dataset_path = 'fer2013.csv'
image_size=(48,48)
```

In [4]:

```
dataset_path
```

Out[4]:

```
'fer2013.csv'
```

## Load the data

In [10]:

```
def load_fer2013():
    data = pd.read_csv(dataset_path)
    pixels = data['pixels'].tolist()
    width, height = 48, 48
    faces = []
    for pixel_sequence in pixels:
        face = [int(pixel) for pixel in pixel_sequence.split(' ')]
        face = np.asarray(face).reshape(width, height)
        face = cv2.resize(face.astype('uint8'), image_size)
        faces.append(face.astype('float32'))
    faces = np.asarray(faces)
    faces = np.expand_dims(faces, -1)
    emotions = pd.get_dummies(data['emotion']).as_matrix()
    return faces, emotions
```

## Preprocessed the data

Converted the dataset in the range of 0 to 1 by diving each pixel by 255

In [11]:

```
def preprocess_input(x, v2=True):
    x = x.astype('float32')
    x = x / 255.0
    if v2:
        x = x - 0.5
        x = x * 2.0
    return x
```

## Model CNN

Imported all the required package Used 'relu' as an input for activation function Then used average pooling for dimension reduction. To increase the accuracy and decrease the time, we used Dropout method.

In [5]:

```
from keras.layers import Activation, Convolution2D, Dropout, Conv2D
from keras.layers import AveragePooling2D, BatchNormalization
from keras.layers import GlobalAveragePooling2D
from keras.models import Sequential
from keras.layers import Flatten
from keras.models import Model
from keras.layers import Input
from keras.layers import MaxPooling2D
from keras.layers import SeparableConv2D
from keras import layers
from keras.regularizers import l2
```

Using TensorFlow backend.

## CNN model implementation

Built various CNN model by changing the parameters. Dropped out 20 percent of total connections between the layers randomly. Used softmax as last layer for making predictions

In [6]:

[illegible]

```

        Conv2D(5, (3, 3), strides=(1, 1), kernel_regularizer=regularization,
              use_bias=False)(img_input)

    x = BatchNormalization()(x)
    x = Activation('relu')(x)
    x = Conv2D(5, (3, 3), strides=(1, 1), kernel_regularizer=regularization,
              use_bias=False)(x)

    x = BatchNormalization()(x)
    x = Activation('relu')(x)

    # module 1
    residual = Conv2D(8, (1, 1), strides=(2, 2),
                     padding='same', use_bias=False)(x)
    residual = BatchNormalization()(residual)

    x = SeparableConv2D(8, (3, 3), padding='same',
                       kernel_regularizer=regularization,
                       use_bias=False)(x)
    x = BatchNormalization()(x)
    x = Activation('relu')(x)
    x = SeparableConv2D(8, (3, 3), padding='same',
                       kernel_regularizer=regularization,
                       use_bias=False)(x)
    x = BatchNormalization()(x)

    x = MaxPooling2D((3, 3), strides=(2, 2), padding='same')(x)
    x = layers.add([x, residual])

    # module 2
    residual = Conv2D(16, (1, 1), strides=(2, 2),

```

```

        model.add(BatchNormalization())
        model.add(Activation('relu'))
        model.add(Dropout(.2))

    model.add(Convolution2D(filters=32, kernel_size=(5, 5), padding='same'))
    model.add(BatchNormalization())
    model.add(Convolution2D(filters=32, kernel_size=(5, 5),
                            strides=(2, 2), padding='same'))
    model.add(BatchNormalization())
    model.add(Activation('relu'))
    model.add(Dropout(.2))

    model.add(Convolution2D(filters=64, kernel_size=(3, 3), padding='same'))
    model.add(BatchNormalization())
    model.add(Convolution2D(filters=64, kernel_size=(3, 3),
                            strides=(2, 2), padding='same'))
    model.add(BatchNormalization())
    model.add(Activation('relu'))
    model.add(Dropout(.2))

    model.add(Convolution2D(filters=64, kernel_size=(1, 1), padding='same'))
    model.add(BatchNormalization())
    model.add(Convolution2D(filters=128, kernel_size=(3, 3),
                            strides=(2, 2), padding='same'))
    model.add(BatchNormalization())
    model.add(Activation('relu'))
    model.add(Dropout(.2))

    model.add(Convolution2D(filters=256, kernel_size=(1, 1), padding='same'))
    model.add(BatchNormalization())
    model.add(Convolution2D(filters=128, kernel_size=(3, 3),
                            strides=(2, 2), padding='same'))

    model.add(Convolution2D(filters=256, kernel_size=(1, 1), padding='same'))
    model.add(BatchNormalization())
    model.add(Convolution2D(filters=num_classes, kernel_size=(3, 3),
                            strides=(2, 2), padding='same'))

    model.add(Flatten())
    #model.add(GlobalAveragePooling2D())
    model.add(Activation('softmax', name='predictions'))
    return model

```

```

def tiny_XCEPTION(input_shape, num_classes, l2_regularization=0.01):
    regularization = l2(l2_regularization)

    # base
    img_input = Input(input_shape)
    x = Conv2D(5, (3, 3), strides=(1, 1), kernel_regularizer=regularization,
              use_bias=False)(img_input)

    x = BatchNormalization()(x)
    x = Activation('relu')(x)
    x = Conv2D(5, (3, 3), strides=(1, 1), kernel_regularizer=regularization,
              use_bias=False)(x)

    x = BatchNormalization()(x)
    x = Activation('relu')(x)

    # module 1
    residual = Conv2D(8, (1, 1), strides=(2, 2),
                     padding='same', use_bias=False)(x)
    residual = BatchNormalization()(residual)

    x = SeparableConv2D(8, (3, 3), padding='same',
                       kernel_regularizer=regularization,
                       use_bias=False)(x)
    x = BatchNormalization()(x)
    x = Activation('relu')(x)
    x = SeparableConv2D(8, (3, 3), padding='same',
                       kernel_regularizer=regularization,
                       use_bias=False)(x)
    x = BatchNormalization()(x)

    x = MaxPooling2D((3, 3), strides=(2, 2), padding='same')(x)
    x = layers.add([x, residual])

    # module 2
    residual = Conv2D(16, (1, 1), strides=(2, 2),

```

```

        padding='same', use_bias=False) (x)
    residual = BatchNormalization() (residual)

    x = SeparableConv2D(16, (3, 3), padding='same',
                        kernel_regularizer=regularization,
                        use_bias=False) (x)
    x = BatchNormalization() (x)
    x = Activation('relu') (x)
    x = SeparableConv2D(16, (3, 3), padding='same',
                        kernel_regularizer=regularization,
                        use_bias=False) (x)
    x = BatchNormalization() (x)

    x = MaxPooling2D((3, 3), strides=(2, 2), padding='same') (x)
    x = layers.add([x, residual])

# module 3
residual = Conv2D(32, (1, 1), strides=(2, 2),
                  padding='same', use_bias=False) (x)
residual = BatchNormalization() (residual)

x = SeparableConv2D(32, (3, 3), padding='same',
                    kernel_regularizer=regularization,
                    use_bias=False) (x)
x = BatchNormalization() (x)
x = Activation('relu') (x)
x = SeparableConv2D(32, (3, 3), padding='same',
                    kernel_regularizer=regularization,
                    use_bias=False) (x)
x = BatchNormalization() (x)

x = MaxPooling2D((3, 3), strides=(2, 2), padding='same') (x)
x = layers.add([x, residual])

# module 4
residual = Conv2D(64, (1, 1), strides=(2, 2),
                  padding='same', use_bias=False) (x)
residual = BatchNormalization() (residual)

x = SeparableConv2D(64, (3, 3), padding='same',
                    kernel_regularizer=regularization,
                    use_bias=False) (x)
x = BatchNormalization() (x)
x = Activation('relu') (x)
x = SeparableConv2D(64, (3, 3), padding='same',
                    kernel_regularizer=regularization,
                    use_bias=False) (x)
x = BatchNormalization() (x)

x = MaxPooling2D((3, 3), strides=(2, 2), padding='same') (x)
x = layers.add([x, residual])

x = Conv2D(num_classes, (3, 3),
            #kernel_regularizer=regularization,
            padding='same') (x)
x = GlobalAveragePooling2D() (x)
output = Activation('softmax', name='predictions') (x)

model = Model(img_input, output)
return model

```

```

def mini_XCEPTION(input_shape, num_classes, l2_regularization=0.01):
    regularization = l2(l2_regularization)

    # base
    img_input = Input(input_shape)
    x = Conv2D(8, (3, 3), strides=(1, 1), kernel_regularizer=regularization,
              use_bias=False) (img_input)

    x = BatchNormalization() (x)
    x = Activation('relu') (x)
    x = Conv2D(8, (3, 3), strides=(1, 1), kernel_regularizer=regularization,
              use_bias=False) (x)

    x = BatchNormalization() (x)
    x = Activation('relu') (x)

# module 1

```

```

# module 1
residual = Conv2D(16, (1, 1), strides=(2, 2),
                  padding='same', use_bias=False)(x)
residual = BatchNormalization()(residual)

x = SeparableConv2D(16, (3, 3), padding='same',
                    kernel_regularizer=regularization,
                    use_bias=False)(x)
x = BatchNormalization()(x)
x = Activation('relu')(x)
x = SeparableConv2D(16, (3, 3), padding='same',
                    kernel_regularizer=regularization,
                    use_bias=False)(x)
x = BatchNormalization()(x)

x = MaxPooling2D((3, 3), strides=(2, 2), padding='same')(x)
x = layers.add([x, residual])

# module 2
residual = Conv2D(32, (1, 1), strides=(2, 2),
                  padding='same', use_bias=False)(x)
residual = BatchNormalization()(residual)

x = SeparableConv2D(32, (3, 3), padding='same',
                    kernel_regularizer=regularization,
                    use_bias=False)(x)
x = BatchNormalization()(x)
x = Activation('relu')(x)
x = SeparableConv2D(32, (3, 3), padding='same',
                    kernel_regularizer=regularization,
                    use_bias=False)(x)
x = BatchNormalization()(x)

x = MaxPooling2D((3, 3), strides=(2, 2), padding='same')(x)
x = layers.add([x, residual])

# module 3
residual = Conv2D(64, (1, 1), strides=(2, 2),
                  padding='same', use_bias=False)(x)
residual = BatchNormalization()(residual)

x = SeparableConv2D(64, (3, 3), padding='same',
                    kernel_regularizer=regularization,
                    use_bias=False)(x)
x = BatchNormalization()(x)
x = Activation('relu')(x)
x = SeparableConv2D(64, (3, 3), padding='same',
                    kernel_regularizer=regularization,
                    use_bias=False)(x)
x = BatchNormalization()(x)

x = MaxPooling2D((3, 3), strides=(2, 2), padding='same')(x)
x = layers.add([x, residual])

# module 4
residual = Conv2D(128, (1, 1), strides=(2, 2),
                  padding='same', use_bias=False)(x)
residual = BatchNormalization()(residual)

x = SeparableConv2D(128, (3, 3), padding='same',
                    kernel_regularizer=regularization,
                    use_bias=False)(x)
x = BatchNormalization()(x)
x = Activation('relu')(x)
x = SeparableConv2D(128, (3, 3), padding='same',
                    kernel_regularizer=regularization,
                    use_bias=False)(x)
x = BatchNormalization()(x)

x = MaxPooling2D((3, 3), strides=(2, 2), padding='same')(x)
x = layers.add([x, residual])

x = Conv2D(num_classes, (3, 3),
            #kernel_regularizer=regularization,
            padding='same')(x)
x = GlobalAveragePooling2D()(x)
output = Activation('softmax', name='predictions')(x)

```

```

model = Model(img_input, output)
return model

def big_XCEPTION(input_shape, num_classes):
    img_input = Input(input_shape)
    x = Conv2D(32, (3, 3), strides=(2, 2), use_bias=False)(img_input)
    x = BatchNormalization(name='block1_conv1_bn')(x)
    x = Activation('relu', name='block1_conv1_act')(x)
    x = Conv2D(64, (3, 3), use_bias=False)(x)
    x = BatchNormalization(name='block1_conv2_bn')(x)
    x = Activation('relu', name='block1_conv2_act')(x)

    residual = Conv2D(128, (1, 1), strides=(2, 2),
                      padding='same', use_bias=False)(x)
    residual = BatchNormalization()(residual)

    x = SeparableConv2D(128, (3, 3), padding='same', use_bias=False)(x)
    x = BatchNormalization(name='block2_sepconv1_bn')(x)
    x = Activation('relu', name='block2_sepconv2_act')(x)
    x = SeparableConv2D(128, (3, 3), padding='same', use_bias=False)(x)
    x = BatchNormalization(name='block2_sepconv2_bn')(x)

    x = MaxPooling2D((3, 3), strides=(2, 2), padding='same')(x)
    x = layers.add([x, residual])

    residual = Conv2D(256, (1, 1), strides=(2, 2),
                      padding='same', use_bias=False)(x)
    residual = BatchNormalization()(residual)

    x = Activation('relu', name='block3_sepconv1_act')(x)
    x = SeparableConv2D(256, (3, 3), padding='same', use_bias=False)(x)
    x = BatchNormalization(name='block3_sepconv1_bn')(x)
    x = Activation('relu', name='block3_sepconv2_act')(x)
    x = SeparableConv2D(256, (3, 3), padding='same', use_bias=False)(x)
    x = BatchNormalization(name='block3_sepconv2_bn')(x)

    x = MaxPooling2D((3, 3), strides=(2, 2), padding='same')(x)
    x = layers.add([x, residual])
    x = Conv2D(num_classes, (3, 3),
               #kernel_regularizer=regularization,
               padding='same')(x)
    x = GlobalAveragePooling2D()(x)
    output = Activation('softmax', name='predictions')(x)

    model = Model(img_input, output)
    return model

if __name__ == "__main__":
    input_shape = (64, 64, 1)
    num_classes = 7
    #model = tiny_XCEPTION(input_shape, num_classes)
    #model.summary()
    #model = mini_XCEPTION(input_shape, num_classes)
    #model.summary()
    #model = big_XCEPTION(input_shape, num_classes)
    #model.summary()
    model = simple_CNN((48, 48, 1), num_classes)
    model.summary()

```

WARNING:tensorflow:From C:\Users\rosha\Anaconda3\lib\site-packages\tensorflow\python\framework\op\_def\_library.py:263: colocate\_with (from tensorflow.python.framework.ops) is deprecated and will be removed in a future version. Instructions for updating:  
Colocations handled automatically by placer.

WARNING:tensorflow:From C:\Users\rosha\Anaconda3\lib\site-packages\keras\backend\tensorflow\_backend.py:3445: calling dropout (from tensorflow.python.ops.nn\_ops) with keep\_prob is deprecated and will be removed in a future version. Instructions for updating:  
Please use `rate` instead of `keep\_prob`. Rate should be set to `rate = 1 - keep\_prob`.

Layer (type)	Output Shape	Param #
image_array (Conv2D)	(None, 48, 48, 16)	800

batch_normalization_1	(Batch Normalization)	(None, 48, 48, 16)	64
conv2d_1	(Conv2D)	(None, 48, 48, 16)	12560
batch_normalization_2	(Batch Normalization)	(None, 48, 48, 16)	64
activation_1	(Activation)	(None, 48, 48, 16)	0
average_pooling2d_1	(Average Pooling)	(None, 24, 24, 16)	0
dropout_1	(Dropout)	(None, 24, 24, 16)	0
conv2d_2	(Conv2D)	(None, 24, 24, 32)	12832
batch_normalization_3	(Batch Normalization)	(None, 24, 24, 32)	128
conv2d_3	(Conv2D)	(None, 24, 24, 32)	25632
batch_normalization_4	(Batch Normalization)	(None, 24, 24, 32)	128
activation_2	(Activation)	(None, 24, 24, 32)	0
average_pooling2d_2	(Average Pooling)	(None, 12, 12, 32)	0
dropout_2	(Dropout)	(None, 12, 12, 32)	0
conv2d_4	(Conv2D)	(None, 12, 12, 64)	18496
batch_normalization_5	(Batch Normalization)	(None, 12, 12, 64)	256
conv2d_5	(Conv2D)	(None, 12, 12, 64)	36928
batch_normalization_6	(Batch Normalization)	(None, 12, 12, 64)	256
activation_3	(Activation)	(None, 12, 12, 64)	0
average_pooling2d_3	(Average Pooling)	(None, 6, 6, 64)	0
dropout_3	(Dropout)	(None, 6, 6, 64)	0
conv2d_6	(Conv2D)	(None, 6, 6, 128)	73856
batch_normalization_7	(Batch Normalization)	(None, 6, 6, 128)	512
conv2d_7	(Conv2D)	(None, 6, 6, 128)	147584
batch_normalization_8	(Batch Normalization)	(None, 6, 6, 128)	512
activation_4	(Activation)	(None, 6, 6, 128)	0
average_pooling2d_4	(Average Pooling)	(None, 3, 3, 128)	0
dropout_4	(Dropout)	(None, 3, 3, 128)	0
conv2d_8	(Conv2D)	(None, 3, 3, 256)	295168
batch_normalization_9	(Batch Normalization)	(None, 3, 3, 256)	1024
conv2d_9	(Conv2D)	(None, 3, 3, 7)	16135
global_average_pooling2d_1	(Global Average Pooling)	(None, 7)	0
predictions	(Activation)	(None, 7)	0
=====			
Total params: 642,935			
Trainable params: 641,463			
Non-trainable params: 1,472			

## Train the model

In [7]:

```
from keras.callbacks import CSVLogger, ModelCheckpoint, EarlyStopping
```

```
from keras.callbacks import ReduceLROnPlateau
from keras.preprocessing.image import ImageDataGenerator
#from load_and_process import load_fer2013
#from load_and_process import preprocess_input
#from models.cnn import mini_XCEPTION
from sklearn.model_selection import train_test_split
```

# Input Parameters

In [9]:

```
batch_size = 32
num_epochs = 35
input_shape = (48, 48, 1)
validation_split = .2
verbose = 1
num_classes = 7
patience = 50
```

In [10]:

```
data_generator = ImageDataGenerator(
    featurewise_center=False,
    featurewise_std_normalization=False,
    rotation_range=10,
    width_shift_range=0.1,
    height_shift_range=0.1,
    zoom_range=.1,
    horizontal_flip=True)
```

In [11]:

```
# model parameters/compilation
model = mini_XCEPTION(input_shape, num_classes)
model.compile(optimizer='adam', loss='categorical_crossentropy',
              metrics=['accuracy'])
model.summary()
```

Layer (type)	Output Shape	Param #	Connected to
input_1 (InputLayer)	(None, 48, 48, 1)	0	
conv2d_10 (Conv2D)	(None, 46, 46, 8)	72	input_1[0][0]
batch_normalization_10 (BatchNo	(None, 46, 46, 8)	32	conv2d_10[0][0]
activation_5 (Activation)	(None, 46, 46, 8)	0	batch_normalization_10[0][0]
conv2d_11 (Conv2D)	(None, 44, 44, 8)	576	activation_5[0][0]
batch_normalization_11 (BatchNo	(None, 44, 44, 8)	32	conv2d_11[0][0]
activation_6 (Activation)	(None, 44, 44, 8)	0	batch_normalization_11[0][0]
separable_conv2d_1 (SeparableCo	(None, 44, 44, 16)	200	activation_6[0][0]
batch_normalization_13 (BatchNo	(None, 44, 44, 16)	64	separable_conv2d_1[0][0]
activation_7 (Activation)	(None, 44, 44, 16)	0	batch_normalization_13[0][0]
separable_conv2d_2 (SeparableCo	(None, 44, 44, 16)	400	activation_7[0][0]
batch_normalization_14 (BatchNo	(None, 44, 44, 16)	64	separable_conv2d_2[0][0]
conv2d_12 (Conv2D)	(None, 22, 22, 16)	128	activation_6[0][0]
max_pooling2d_1 (MaxPooling2D)	(None, 22, 22, 16)	0	batch_normalization_14[0][0]
batch_normalization_12 (BatchNo	(None, 22, 22, 16)	64	conv2d_12[0][0]
conv2d_13 (Conv2D)	(None, 22, 22, 16)	0	max_pooling2d_1[0][0]



add_1 (Add)	(None, 22, 22, 16)	0	max_pooling2d_1[0][0] batch_normalization_12[0][0]
separable_conv2d_3 (SeparableCo	(None, 22, 22, 32)	656	add_1[0][0]
batch_normalization_16 (BatchNo	(None, 22, 22, 32)	128	separable_conv2d_3[0][0]
activation_8 (Activation)	(None, 22, 22, 32)	0	batch_normalization_16[0][0]
separable_conv2d_4 (SeparableCo	(None, 22, 22, 32)	1312	activation_8[0][0]
batch_normalization_17 (BatchNo	(None, 22, 22, 32)	128	separable_conv2d_4[0][0]
conv2d_13 (Conv2D)	(None, 11, 11, 32)	512	add_1[0][0]
max_pooling2d_2 (MaxPooling2D)	(None, 11, 11, 32)	0	batch_normalization_17[0][0]
batch_normalization_15 (BatchNo	(None, 11, 11, 32)	128	conv2d_13[0][0]
add_2 (Add)	(None, 11, 11, 32)	0	max_pooling2d_2[0][0] batch_normalization_15[0][0]
separable_conv2d_5 (SeparableCo	(None, 11, 11, 64)	2336	add_2[0][0]
batch_normalization_19 (BatchNo	(None, 11, 11, 64)	256	separable_conv2d_5[0][0]
activation_9 (Activation)	(None, 11, 11, 64)	0	batch_normalization_19[0][0]
separable_conv2d_6 (SeparableCo	(None, 11, 11, 64)	4672	activation_9[0][0]
batch_normalization_20 (BatchNo	(None, 11, 11, 64)	256	separable_conv2d_6[0][0]
conv2d_14 (Conv2D)	(None, 6, 6, 64)	2048	add_2[0][0]
max_pooling2d_3 (MaxPooling2D)	(None, 6, 6, 64)	0	batch_normalization_20[0][0]
batch_normalization_18 (BatchNo	(None, 6, 6, 64)	256	conv2d_14[0][0]
add_3 (Add)	(None, 6, 6, 64)	0	max_pooling2d_3[0][0] batch_normalization_18[0][0]
separable_conv2d_7 (SeparableCo	(None, 6, 6, 128)	8768	add_3[0][0]
batch_normalization_22 (BatchNo	(None, 6, 6, 128)	512	separable_conv2d_7[0][0]
activation_10 (Activation)	(None, 6, 6, 128)	0	batch_normalization_22[0][0]
separable_conv2d_8 (SeparableCo	(None, 6, 6, 128)	17536	activation_10[0][0]
batch_normalization_23 (BatchNo	(None, 6, 6, 128)	512	separable_conv2d_8[0][0]
conv2d_15 (Conv2D)	(None, 3, 3, 128)	8192	add_3[0][0]
max_pooling2d_4 (MaxPooling2D)	(None, 3, 3, 128)	0	batch_normalization_23[0][0]
batch_normalization_21 (BatchNo	(None, 3, 3, 128)	512	conv2d_15[0][0]
add_4 (Add)	(None, 3, 3, 128)	0	max_pooling2d_4[0][0] batch_normalization_21[0][0]
conv2d_16 (Conv2D)	(None, 3, 3, 7)	8071	add_4[0][0]
global_average_pooling2d_2 (Glo	(None, 7)	0	conv2d_16[0][0]
predictions (Activation)	(None, 7)	0	global_average_pooling2d_2[0][0]
=====			
Total params: 58,423			
Trainable params: 56,951			
Non-trainable params: 1,472			

In [18]:

```
faces, emotions = load_fer2013()
faces, emotions
```

```
C:\Users\rosha\Anaconda3\lib\site-packages\ipykernel_launcher.py:13: FutureWarning: Method
.as_matrix will be removed in a future version. Use .values instead.
del sys.path[0]
```

Out[18]:

```
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           [ 52.],
           [ 43.],
           [ 41.]],

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           [ 58.],
           ...,
           [ 56.],
           [ 52.],
           [ 44.]],

          [[ 50.],
           [ 43.],
           [ 54.],
           ...,
           [ 49.],
           [ 56.],
           [ 47.]],

          ...,

          [[ 91.],
           [ 65.],
           [ 42.],
           ...,
           [ 72.],
           [ 56.],
           [ 43.]],

          [[ 77.],
           [ 82.],
           [ 79.],
           ...,
           [105.],
           [ 70.],
           [ 46.]],

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           [ 72.],
           [ 84.],
           ...,
           [106.],
           [109.],
           [ 82.]]]],

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           ...,
           [129.],
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           ...,
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          [[151.],
           [151.],
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```

```
....,  
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....,  
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[[[ 30.],
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[ 40.]],

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[ 50.],
[ 44.]]],
```

```
[ 28.],
[ 30.],
...,
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[ 54.],
[ 37.]],

...,

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 [110.],
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 [ 35.],
 [ 30.],
 [ 30.]],

[[102.],
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 [ 29.]],

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 [ 30.],
 [ 28.]]],

[[[ 19.],
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 [ 14.],
 ...,
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 [ 95.],
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 [ 94.],
 [ 90.]],

[[ 10.],
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 [ 10.],
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 [ 95.]],

...,

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 [ 55.],
 [ 64.],
 [ 95.]],

[[ 15.],
 [ 15.],
 [ 13.],
 ...,
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 [171.],
 [192.]],

[[ 16.],
 ...,
 [ 16.],
```

```

[ 14.],
[ 13.],
...,
[189.],
[199.],
[201.]]]], dtype=float32), array([[1, 0, 0, ..., 0, 0, 0],
[1, 0, 0, ..., 0, 0, 0],
[0, 0, 1, ..., 0, 0, 0],
...,
[1, 0, 0, ..., 0, 0, 0],
[0, 0, 0, ..., 0, 0, 0],
[0, 0, 1, ..., 0, 0, 0]], dtype=uint8))

```

In [19]:

```
faces = preprocess_input(faces)
```

In [20]:

```
num_samples, num_classes = emotions.shape
num_samples, num_classes
```

Out[20]:

```
(35887, 7)
```

## Compile the model

Splited the data into 80% as training data and 20% as testing data. Trained the model by 35 number of epochs. Used xtest data as validation dataset.

In [21]:

```

xtrain, xtest, ytrain, ytest = train_test_split(faces, emotions, test_size=0.2, shuffle=True)
model.fit_generator(data_generator.flow(xtrain, ytrain,
                                         batch_size),
                    steps_per_epoch=len(xtrain) / batch_size,
                    epochs=num_epochs, verbose=1,
                    validation_data=(xtest, ytest))

```

WARNING:tensorflow:From C:\Users\rosha\Anaconda3\lib\site-packages\tensorflow\python\ops\math\_ops.py:3066: to\_int32 (from tensorflow.python.ops.math\_ops) is deprecated and will be removed in a future version.

Instructions for updating:

Use tf.cast instead.

Epoch 1/35

898/897 [=====] - 759s 845ms/step - loss: 1.7620 - acc: 0.3348 - val\_loss: 1.7058 - val\_acc: 0.4198

Epoch 2/35

898/897 [=====] - 730s 813ms/step - loss: 1.5030 - acc: 0.4337 - val\_loss: 1.6158 - val\_acc: 0.4100

Epoch 3/35

898/897 [=====] - 732s 815ms/step - loss: 1.3918 - acc: 0.4762 - val\_loss: 1.3649 - val\_acc: 0.4928

Epoch 4/35

898/897 [=====] - 730s 813ms/step - loss: 1.3181 - acc: 0.5068 - val\_loss: 1.3208 - val\_acc: 0.4974

Epoch 5/35

898/897 [=====] - 730s 813ms/step - loss: 1.2741 - acc: 0.5232 - val\_loss: 1.2893 - val\_acc: 0.5171

Epoch 6/35

898/897 [=====] - 732s 815ms/step - loss: 1.2433 - acc: 0.5357 - val\_loss: 1.3610 - val\_acc: 0.4950

Epoch 7/35

898/897 [=====] - 730s 813ms/step - loss: 1.2144 - acc: 0.5405 - val\_loss: 1.1786 - val\_acc: 0.5665

Epoch 8/35

898/897 [=====] - 731s 814ms/step - loss: 1.1844 - acc: 0.5573 - val\_loss: 1.1845 - val\_acc: 0.5699

Epoch 9/35

898/897 [=====] - 731s 814ms/step - loss: 1.1657 - acc: 0.5615 -

```
val_loss: 1.1728 - val_acc: 0.5610
Epoch 10/35
898/897 [=====] - 732s 815ms/step - loss: 1.1515 - acc: 0.5682 -
val_loss: 1.1915 - val_acc: 0.5619
Epoch 11/35
898/897 [=====] - 730s 813ms/step - loss: 1.1350 - acc: 0.5759 -
val_loss: 1.2300 - val_acc: 0.5493
Epoch 12/35
898/897 [=====] - 731s 814ms/step - loss: 1.1276 - acc: 0.5737 -
val_loss: 1.1354 - val_acc: 0.5715
Epoch 13/35
898/897 [=====] - 732s 815ms/step - loss: 1.1153 - acc: 0.5816 -
val_loss: 1.1654 - val_acc: 0.5699
Epoch 14/35
898/897 [=====] - 732s 815ms/step - loss: 1.1049 - acc: 0.5862 -
val_loss: 1.1572 - val_acc: 0.5861
Epoch 15/35
898/897 [=====] - 731s 814ms/step - loss: 1.0943 - acc: 0.5877 -
val_loss: 1.1551 - val_acc: 0.5745
Epoch 16/35
898/897 [=====] - 731s 815ms/step - loss: 1.0810 - acc: 0.5928 -
val_loss: 1.1195 - val_acc: 0.5933
Epoch 17/35
898/897 [=====] - 733s 817ms/step - loss: 1.0754 - acc: 0.5976 -
val_loss: 1.1067 - val_acc: 0.5914
Epoch 18/35
898/897 [=====] - 734s 817ms/step - loss: 1.0677 - acc: 0.5971 -
val_loss: 1.0827 - val_acc: 0.6000
Epoch 19/35
898/897 [=====] - 734s 817ms/step - loss: 1.0621 - acc: 0.6020 -
val_loss: 1.0697 - val_acc: 0.6066
Epoch 20/35
898/897 [=====] - 742s 826ms/step - loss: 1.0563 - acc: 0.6060 -
val_loss: 1.1106 - val_acc: 0.5906
Epoch 21/35
898/897 [=====] - 732s 815ms/step - loss: 1.0530 - acc: 0.6040 -
val_loss: 1.0672 - val_acc: 0.6032
Epoch 22/35
898/897 [=====] - 731s 815ms/step - loss: 1.0443 - acc: 0.6094 -
val_loss: 1.1238 - val_acc: 0.5865
Epoch 23/35
898/897 [=====] - 731s 814ms/step - loss: 1.0375 - acc: 0.6114 -
val_loss: 1.0879 - val_acc: 0.6002
Epoch 24/35
898/897 [=====] - 732s 815ms/step - loss: 1.0295 - acc: 0.6170 -
val_loss: 1.0691 - val_acc: 0.6052
Epoch 25/35
898/897 [=====] - 732s 815ms/step - loss: 1.0261 - acc: 0.6148 -
val_loss: 1.1269 - val_acc: 0.5946
Epoch 26/35
898/897 [=====] - 731s 814ms/step - loss: 1.0256 - acc: 0.6148 -
val_loss: 1.1123 - val_acc: 0.5970
Epoch 27/35
898/897 [=====] - 732s 815ms/step - loss: 1.0204 - acc: 0.6173 -
val_loss: 1.1333 - val_acc: 0.5750
Epoch 28/35
898/897 [=====] - 731s 814ms/step - loss: 1.0131 - acc: 0.6211 -
val_loss: 1.1156 - val_acc: 0.6004
Epoch 29/35
898/897 [=====] - 732s 815ms/step - loss: 1.0058 - acc: 0.6248 -
val_loss: 1.1046 - val_acc: 0.5897
Epoch 30/35
898/897 [=====] - 731s 815ms/step - loss: 1.0110 - acc: 0.6230 -
val_loss: 1.1054 - val_acc: 0.5996
Epoch 31/35
898/897 [=====] - 730s 813ms/step - loss: 0.9985 - acc: 0.6289 -
val_loss: 1.0338 - val_acc: 0.6204
Epoch 32/35
898/897 [=====] - 732s 815ms/step - loss: 0.9978 - acc: 0.6260 -
val_loss: 1.0474 - val_acc: 0.6106
Epoch 33/35
898/897 [=====] - 732s 815ms/step - loss: 0.9910 - acc: 0.6312 -
val_loss: 1.0498 - val_acc: 0.6190
Epoch 34/35
898/897 [=====] - 731s 815ms/step - loss: 0.9896 - acc: 0.6291 -
val_loss: 1.0605 - val_acc: 0.6089
Epoch 35/35
.....
```

```
898/897 [=====] - 733s 816ms/step - loss: 0.9897 - acc: 0.6281 -  
val_loss: 1.0230 - val_acc: 0.6258
```

```
Out[21]:
```

```
<keras.callbacks.History at 0x1f313f20208>
```

```
In [51]:
```

```
xtrain.shape
```

```
Out[51]:
```

```
(28709, 48, 48, 1)
```

```
In [48]:
```

```
ytrain.shape
```

```
Out[48]:
```

```
(28709, 7)
```

```
In [ ]:
```

```
In [ ]:
```

## Call model

```
In [12]:
```

```
from keras.preprocessing.image import img_to_array  
import imutils  
import cv2  
from keras.models import load_model  
import numpy as np
```

## Parametersfor loading data and images

```
In [13]:
```

```
# parameters for loading data and images  
detection_model_path = 'haarcascade_frontalface_default.xml'  
emotion_model_path = '_mini_XCEPTION.102-0.66.hdf5'
```

```
In [14]:
```

```
# loading models  
face_detection = cv2.CascadeClassifier(detection_model_path)  
emotion_classifier = load_model(emotion_model_path, compile=False)  
EMOTIONS = ["angry" ,"disgust","scared", "happy", "sad", "surprised",  
            "neutral"]
```

## Test the data using Computer vision

The dataset was tested on real time images by using computer vision. Based on the probabilities, each emotion is classified.

```
In [ ]:
```



```

# starting video streaming
cv2.namedWindow('Emotion_Recognition')
camera = cv2.VideoCapture(0)
while True:
    frame = camera.read()[1]
    #reading the frame
    frame = imutils.resize(frame,width=700)
    gray = cv2.cvtColor(frame, cv2.COLOR_BGR2GRAY)
    faces = face_detection.detectMultiScale(gray,scaleFactor=1.1,minNeighbors=5,minSize=(30,30),flags=cv2.CASCADE_SCALE_IMAGE)

    canvas = np.zeros((250, 300, 3), dtype="uint8")
    frameClone = frame.copy()
    if len(faces) > 0:
        faces = sorted(faces, reverse=True,
            key=lambda x: (x[2] - x[0]) * (x[3] - x[1]))[0]
        (fX, fY, fW, fH) = faces
        # Extract the ROI of the face from the grayscale image, resize it to a fixed 28
        # x28 pixels, and then prepare
        # the ROI for classification via the CNN
        roi = gray[fY:fY + fH, fX:fX + fW]
        roi = cv2.resize(roi, (64, 64))
        roi = roi.astype("float") / 255.0
        roi = img_to_array(roi)
        roi = np.expand_dims(roi, axis=0)

        preds = emotion_classifier.predict(roi)[0]
        emotion_probability = np.max(preds)
        label = EMOTIONS[preds.argmax()]

        for (i, (emotion, prob)) in enumerate(zip(EMOTIONS,preds)):
            # construct the label text
            text = "{}: {:.2f}%".format(emotion, prob * 100)

            # draw the label + probability bar on the canvas
            # emoji_face = feelings_faces[np.argmax(preds)]

            w = int(prob * 300)
            cv2.rectangle(canvas, (7, (i * 35) + 5),
                (w, (i * 35) + 35), (0, 0, 255), -1)
            cv2.putText(canvas, text, (10, (i * 35) + 23),
                cv2.FONT_HERSHEY_SIMPLEX, 0.45,
                (255, 255, 255), 2)
            cv2.putText(frameClone, label, (fX, fY - 10),
                cv2.FONT_HERSHEY_SIMPLEX, 0.45, (0, 0, 255), 2)
            cv2.rectangle(frameClone, (fX, fY), (fX + fW, fY + fH),
                (0, 0, 255), 2)

            for c in range(0, 3):
                frame[200:320, 10:130, c] = emoji_face[:, :, c] * \
                    (emoji_face[:, :, 3] / 255.0) + frame[200:320,
                    10:130, c] * (1.0 - emoji_face[:, :, 3] / 255.0)

            cv2.imshow('your_face', frameClone)
            cv2.imshow("Probabilities", canvas)
            if cv2.waitKey(1) & 0xFF == ord('q'):
                break

camera.release()
cv2.destroyAllWindows()

```

## Description and Conclusion

### CNN

The main advantage of CNN compared to its predecessors is that it automatically detects the important features without any human supervision. CNN is also computationally efficient. It uses special convolution and pooling operations and performs parameter sharing. Convolution The main building block of CNN is the convolutional layer. Convolution is a mathematical operation to merge two sets of information. In our case the convolution is applied on the input data using a convolution filter to produce a feature map

On the left side is the input to the convolution layer, for example the input image. On the right is the convolution filter, also called the kernel, we will use these terms interchangeably. This is called a 3x3 convolution due to the shape of the filter. We perform multiple convolutions on an input, each using a different filter and resulting in a distinct feature map. For any kind of neural network to be powerful, it needs to contain non-linearity. We again pass the result of the convolution operation through relu activation function. So the values in the final feature maps are not actually the sums, but the relu function applied to them. Stride specifies how much we move the convolution filter at each step. By default the value is 1.

## Pooling

After a convolution operation we usually perform pooling to reduce the dimensionality. type of pooling is max pooling which just takes the max value in the pooling window. Average pooling which just takes the avg of all the values in the pooling window. Then we flatten the output of the final pooling layer to a vector and that becomes the input to the fully connected layer.

## Fully Connected Layer(FC)

Fully connected layer involves weights, biases, and neurons. It connects neurons in one layer to neurons in another layer. It is used to classify images between different category by training.

## Softmax / Logistic Layer

Softmax or Logistic layer is the last layer of CNN. It resides at the end of FC layer. Logistic is used for binary classification and softmax is for multi-classification.(gives 7 outputs in our case)

## Output Layer

Output layer contains the label which is in the form of one-hot encoded.

## Accuracy

The model accuracy is 63% and its highest when compared with Random Forest and Nearest Neighbor.

In [ ]: