Delta Rule

 $w_{ij} = w_{ij} + \Delta w_{ij} \times_{i} w_{ij}$ $\Delta w_{ij} = g e_{i} x_{i}$ $e_{j} = t - y_{inj}$ $y_{j} = y_{inj} \text{ (Linear Action function)}$

Note#

Generalized Delta Rule - Uses Sigmoid activation

.

Generalized Delta Rule

In case of sigmoid or logistic activation (Busany) $\phi(x) = \frac{1}{1+e}$ where x = steepness parameter

$$\phi(n) = \frac{1}{1+e^{-n}}$$

$$\phi'(n) = \phi(n) \cdot (1-\phi(n))$$

in ease of linear actuation

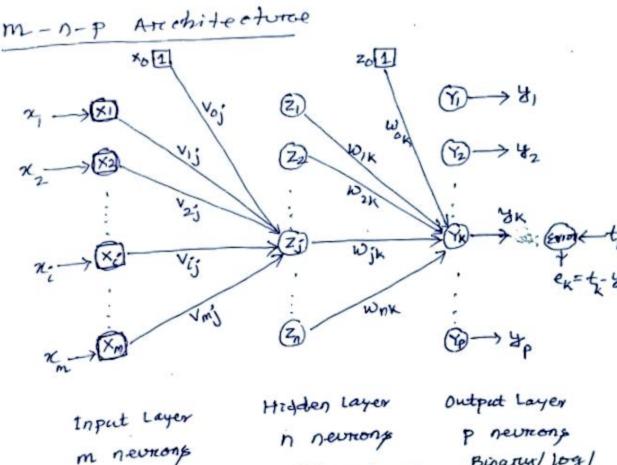
p(x) = 2

$$\phi'(m) = \frac{d}{dm}(m) = 1$$
 $S_j = e_j \phi'(m) = e_j \cdot i = e_j$

[S

wij = wij + 2 e, xi when we use linear activation function, the generalized delta rule becomes simple delta rule.

Network MLP / Back-propagation



m neurons Linear (Identity) Actionter

Binary [Log/ Tan-signoid Activation

Binary/log/ Tan-signord Activation

m - n - P Input triplen ordput forward pass input to Hidden Unit Z; (j= 1 ton) Zinj = Voj + ¿xi. Vij = Ex. Vij 0 = VX = V·X Output of the Hidden unit Zj Apply activation function over Zing Zi = f (Zinj) 11): Advation function. Input to output unit Yk (K= 1 to p) Yink = Wok + Ez, Wjk = Zzwijk = WZ = WZ output of output unit/Layer Apply actuation function. yk= f (Vink)

Error associated with output unit Yk

ek= tk-yk

tk: tanget

yk: computed output

Squared Error

- . squared error is minimized by the use of steepest descent/Gradient descent method.
- . Fore easy mathematical descivation, error of Kth output neuron can be written as

. Fore one training sample, error associated with output layer

Fore "T" training samples, total errors

in the prediction $E_{k} = \underbrace{\begin{cases} \xi \\ \xi \end{cases}}_{k=1} E_{k} = \underbrace{\begin{cases} \xi \\ \xi \end{cases}}_{k=1} (t_{k} - y_{k})^{2}$ tot $\underbrace{\begin{cases} \xi \\ \xi \end{cases}}_{k=1} E_{k} = \underbrace{\begin{cases} \xi \\ \xi \end{cases}}_{k=1} (t_{k} - y_{k})^{2}$

Backward Pass (Back-propagation of error)

Local Gradient / Error correction term) Back-propagated error from the output unit \$ (k = 1 to p)

change in weights and bias as per the Generalized Delta Rule (Steepest descent

$$W_{jk} = W_{jk} + \Delta W_{jk}$$

where $W_{jk} = 2.8_k Z_j$

This Sx is prof output layer is propagated to each hidden unit. (backwards)

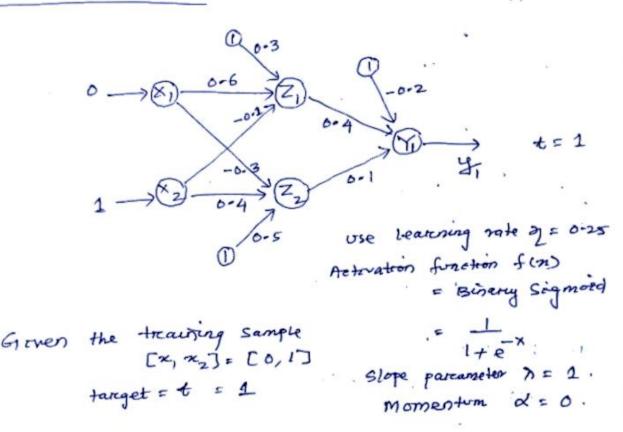
weighted sum of 8 at each hidden unit Z, (j=1 to n) from the output unity YK (K= 1 to P) Sinj = Zi Sk Wjk Loral Gradient / Propagated Error from hiddenger

Sinj f (Zinj) weight updates

vij = vij + Dvij

Dvoj = 28, xi

Note # output layer weight updates Modified Generalized DeHa Rule momentum constant. $\omega_{jk}^{(t)} + \alpha \Delta \omega_{jk}^{(t-1)} + \Delta \omega_{jk}^{(t)}$. DWjk = 7 Skz, output layer Where local gradient . X: momentum constant of: Learning rate t: time stamp / itercation of higher rate of learning, But unstable. (Oscillatory) Slower rate of leaving, But Stable. of with &, higher rate of Learning + Stable. (Quick convergence + less oscillation) Hidden Layer weight updates $V_{ij}^{(t+1)} = V_{ij}^{(t)} + \Delta \Delta V_{ij}^{(t-1)} + \Delta V_{ij}^{(t)}$ DVij = 7 Sjai hidden Layer local pradient



Foreward pass Hidden Layer calculation

Fraction

$$Z_{in1} = 1 \cdot v_{01} + x_{1} \cdot v_{11} + x_{2} \cdot v_{2} = 1$$

$$= 1 \cdot 0.3 + 0.0.6 + 1 \times -0.1 = 0.2$$

$$Z_{in2} = 1 \cdot v_{02} + x_{1} \cdot v_{12} + x_{2} \cdot v_{22}$$

$$= 1 \cdot 0.5 + 0 \times -0.3 + 1 \times 0.4 = 0.9$$

Applying activation function to ealerlate the output of hedden layer. $Z_{1} = f\left(Z_{1}, 1\right) = \frac{1}{1+e^{-2in}} = \frac{1}{1+e^{-0.2}} = 0.5498$ $Z_{2} = f\left(Z_{1}, 1\right) = \frac{1}{1+e^{-2in}} = \frac{1}{1+e^{-0.2}} = 0.7109$

Output Layer calculation

output $y_{in1} = 1 - \omega_{01} + z_1 - \omega_{11} + z_2 \omega_{21}$ $z_{in1} = 1 - \omega_{01} + z_1 - \omega_{11} + z_2 \omega_{21}$ $z_{in1} = 1 - \omega_{02} + \delta - 5498 \cdot \delta - 4 + \delta - 7109 * \delta - 1 = \delta - 69$

Squared From : (1-0.5227)2

Backwared pass

output layer calculation

8, = (+,-4,) f'(4in) Local

Gradient Error convertion 5 (1-0.5227) 8, (1-8,) output s (1-0-5227) 0.5227 (1-0.5227)

0- 1191

weight convertion DW01 = 7.8,-1 = 0-25 + 0-1191 +1 = 0.02978 2.8,21 = 0.25 + 0-1191 + 0-5498

= 0-0164 DW21 = 2: 8, 22 = 0.25 # 0.1191 \$ 0.7109 1 0.02117

Wor (new) = Wor (019) + DWG = -0-2 + 0-0298 \$ = -0-17022 Wir (new) = Wir (074) + DWG = 0-4 + 0-0164 = 0-4164 W21 (news = W21 (019) + DW21 = 0-1+0-02117=0-12117

Hidden Layer ealculation Local Gradient/ Error propagation from hidden layere (j= 1 to 2) S; = Sinj f'(Zinj) Sunj = & Sk. Wjk = S. Wj1 Sing & S. . Wil = 0-1191 x 0.4 = 0.04764 Sinz = 8, - W21 = 0-1191 x 0-1 = 0-01191 S, = Sin1 . f(zin1) = Sin1 . z, (1-z,) = 0.04764+ 0.5498 (1-0.5498) c 0-2475 0.0118 S2 = Sinz. f'(Zinz) = Sinz Z2 (1-Z2) 0-1191 * 0-7109 (1-0-7109) E 0-00245

$$S_{2} = S_{0,2} \cdot 3 (1-0.7)$$

$$= 0.00245$$

$$= 0.00245$$

$$\Delta V_{01} = 2 S_{1} \cdot 1 = 0.25 * 0.0118 = 0.00295$$

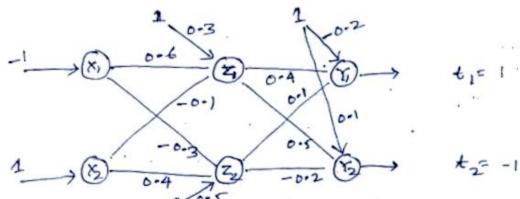
$$\Delta V_{11} = 2 S_{1} \cdot 2 = 0.25 * 0.0118 * 0 = 0$$

DV21 = 78, x2 = 0.25 + 0.0118 # 1 = 0.00295 DV02 = 282.1 = 6.25 # 0.00245 #1 = 0.0006125 DV12 = 2822, = 0.25 # 0.00245 # 0 = 0 DV22 = 282. x2 = 0-25 + 0-00245 x1 = 0-8006125

Vo (new) = Vo (old) + DV01 = 0.3 +0.00295 = 0.30295 VII (new) = VII (Old) + DVII = 0-6+ 0 = 0-6

Backpropagation practice problem

Find the new weights using back-propagation network shown below



The network is presented with the input pattern [-1, 1] and targets [+1, -1].

Use learning rate 0.25 and beplabiple

bipolar segmoidal actuation for both hidden

and output layer.

Activation function
$$f(n) = \frac{1-e}{1+e^{-\lambda x}}$$
(Bipblan assignoid)

Let 7 = 1 (Slope param)

Derervatione of f(x), $f'(x) = \frac{\lambda}{2} (1+f(a))(1-f(a))$ = 0.5 (1+f(a))(1-f(a))

Goven the input sample [0x, n2] = [-1,1] tangety [t1, t2] = [1, -1]. Foreward pass Hidden layer calculation Input to Z, neuron, Zin1 = Vo1 + 2, V11 + 22 21 = 0.3 + (-1)-(06) + 1x -0-1 = -0.4

input to Zz;

Zaz = Voz + 21 V12 + 72 V22 = 0.5 + (-1). (-0.3) + 1 x 0.4 = 1.2

output of Z1

Z1 = f(Z1,1) = f(-0.4) = 1-e = -0.1974 $Z_2 = f(Z_{012}) = f(1.2) = \frac{1-e^{-1.2}}{1+e^{-1.2}} = 0.537$ output of Zz

In vector Motalian:

× [17-bias] V [0-3 0.5]
0-6-0-3
-0-1 0-4 triput to hodder layer (VX)

[0-3 0.6 -0-) * [-1] = [-0-4] 0-5 -0-3 0-4] 283 [1] = [1-2] output of hadden layer

[21]= (5 (-6.4)] = for19 py [-0.1974] [22] = (5) (-0.1974) = [0.537]

output layer calculation

Yinz = Word + Z1. 1011 + Z2. 1021.

= -0-2 + (-0-1974) * 0-4 + 0-537 + 0-1

= -0.22526

input to Y2

Yinz = Woz + Z, W12 + Z2. W22

= 0-1 + (-0.1974).(0.5) + (0.537).(-0.2)

= - 0.1061

output of YI

4, = f(4in1) = f(-0-22526) = -0-1122

oretput of 42

y2 = f (302) = f(-0.1061) = -0.053

Backward Pass

Local gradient of cutput layer

$$S_{1}^{(0)} = (t_{1} - t_{1}) f'(t_{0})$$

$$= (1 - t_{1}) t'(t_{0})$$

$$= (1 - t_{1}) t'(t_{0})$$

$$= (1 - t_{2}) t'(t_{0})$$

$$= (-1 - t_{2}) t'(t_{0})$$

$$=$$

Backward Pass Local gradient of hidden layer for neuron 21 Sin 1 = Sio, w11 + Sio, w12 c 0.5491 + 0.4 + -0.4728 + 0.5 = -0-0165 for neuron 22 Sinz = S, . W2, + S2 . W22 = 0.5491 * 0.1 + -0.4728 # -0.2 c. 0-1493 Si = Sing f (Zin) = Sing f (Zin) -0.0165 0-21964 . 0.5 (1+21) (1-21) 0.0165 + 0.5 (1+1-0.1974))(1-(-0.1974)) - 0.0079 S2 = Sun 2 · f (Zin2) 0-1493.0.5. (1+22) (1-22) F 6-1493 + 0.5 + (1+ 0.537) (1-0.537) \$ 0.053134

```
charge in weights between input and
       hodden layer:
Abras = AVO1 = 2.8, (4) 1 = 0.25 # -0.0079 =1
       DV11 = 28, 10, 20, = 0.25 # -0-0079 # -1
       DV21 = 2 8, - 2 = 0.025 + -0.0079 + 1
    D beas = DV02 = 2. 82. 1 = 0.25 + 0.053134 +1
           AV12 = 2.82 , x1 = 0.25 + 0.053134 + -1
          DV22 = 2. 82 (h). 262 = 0.25 + 0.053134 + 1
     final weights can be computed as below
             With (new) = Wix (old) + DWgk.
              Vij (new) = Voj (old) + DVoj
```