

# Software Programming

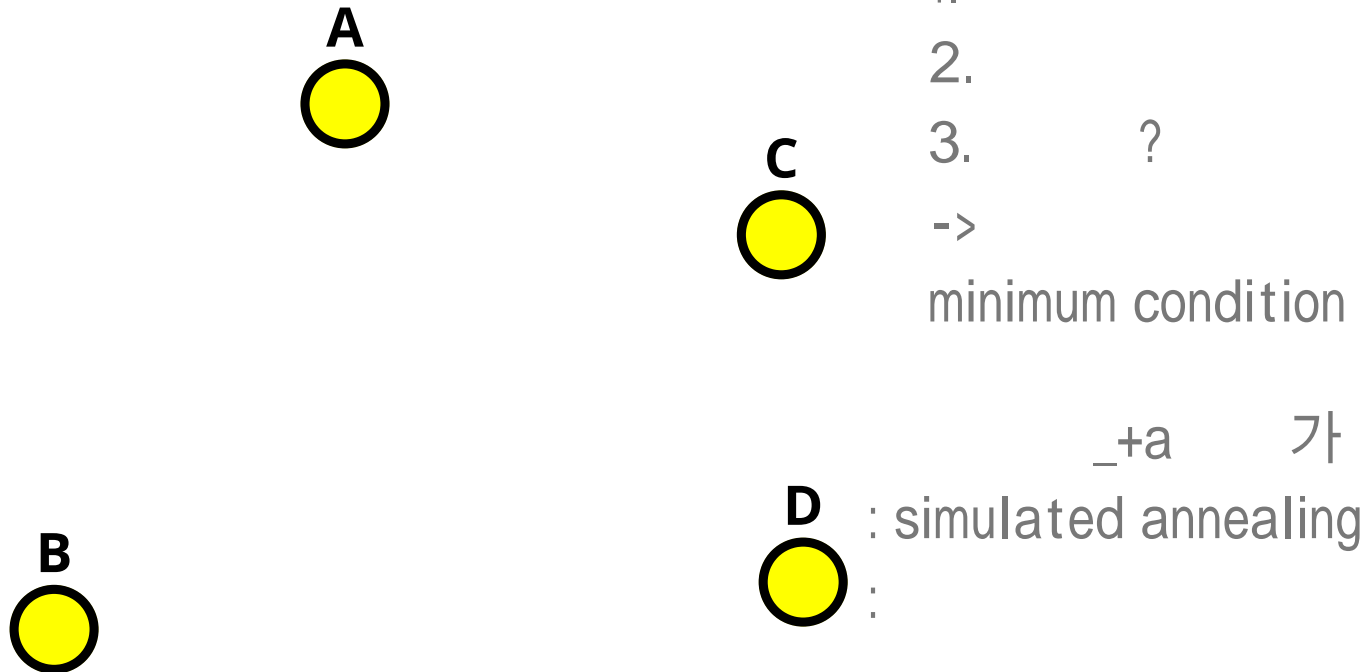
2019-2 SW프로그래밍 (YCS1002)

SWP11

# Traveling Salesman Problem

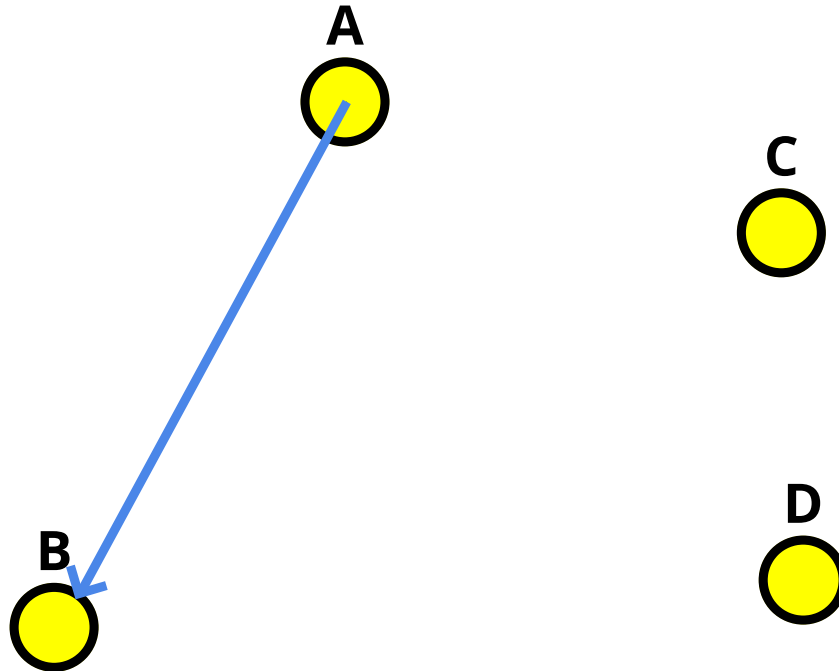
# Traveling Salesman Problem

- "Given a list of cities and the distances between each pair of cities, what is the shortest possible route that visits each city and returns to the origin city?"



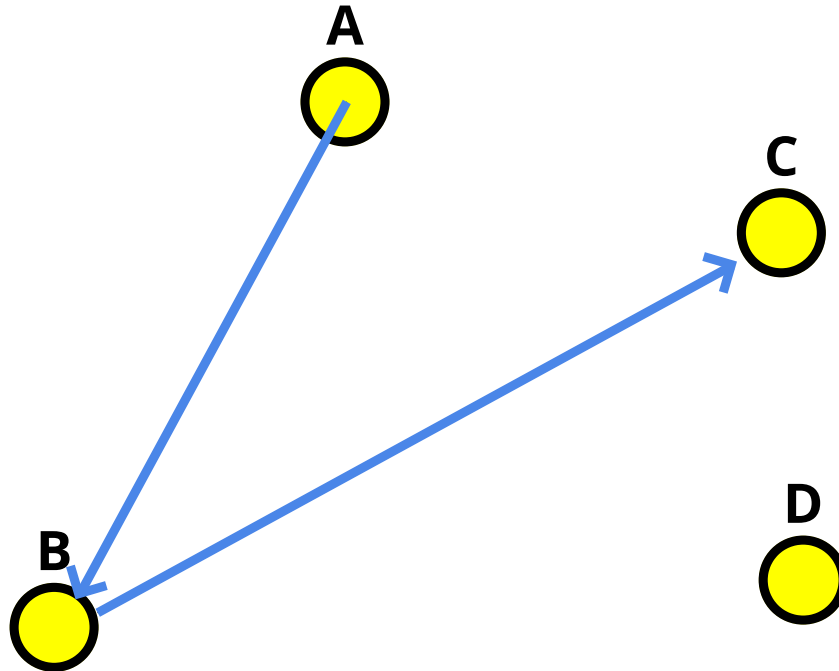
# Traveling Salesman Problem

Path: A-B



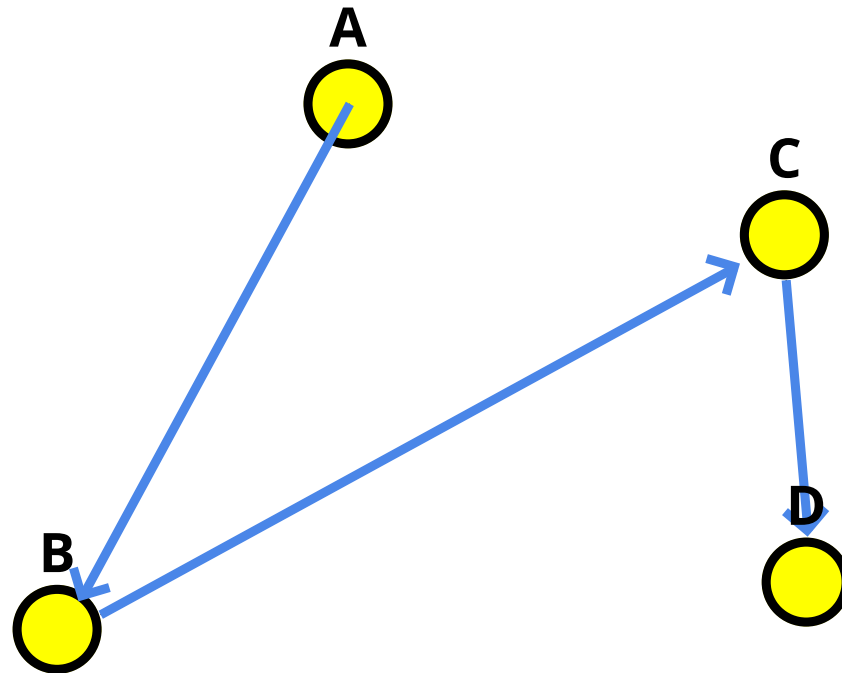
# Traveling Salesman Problem

Path: A-B-C



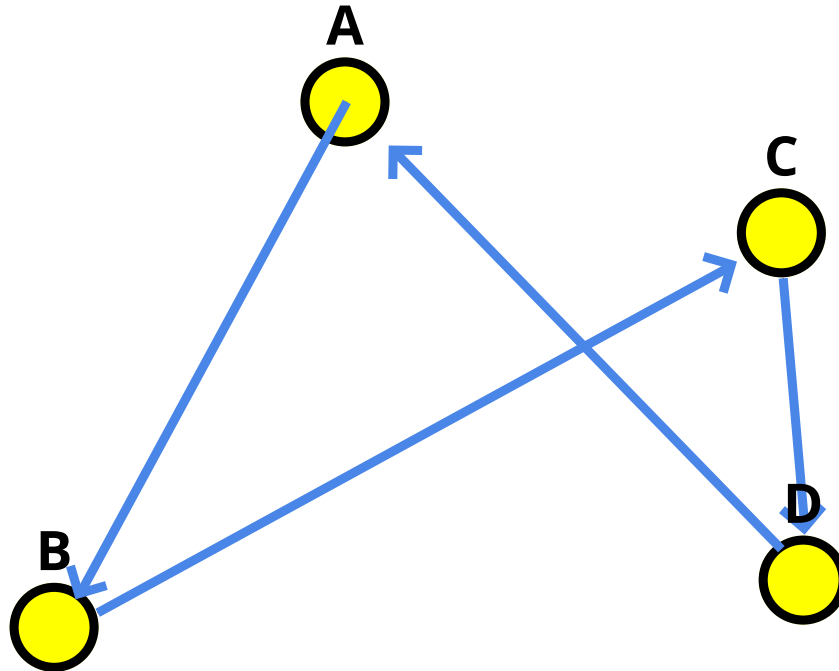
# Traveling Salesman Problem

Path: A-B-C-D



# Traveling Salesman Problem

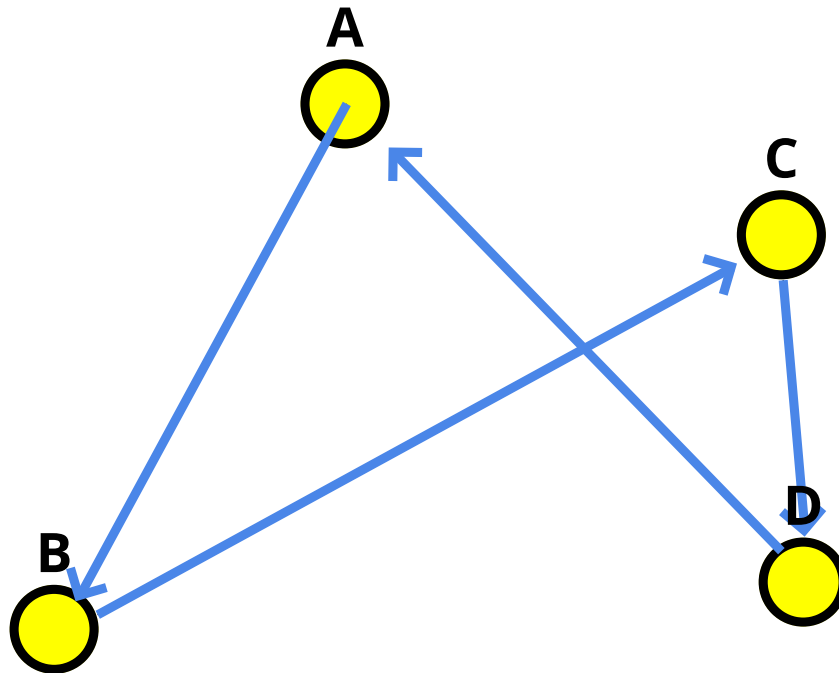
Path: A-B-C-D-A



# Traveling Salesman Problem

Path: A-B-C-D-A

**Shortest path?**

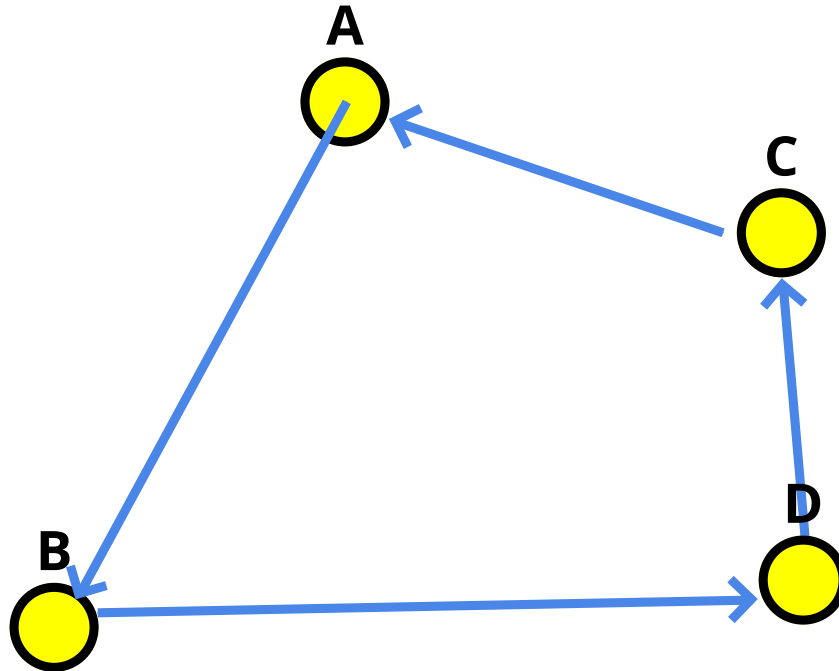


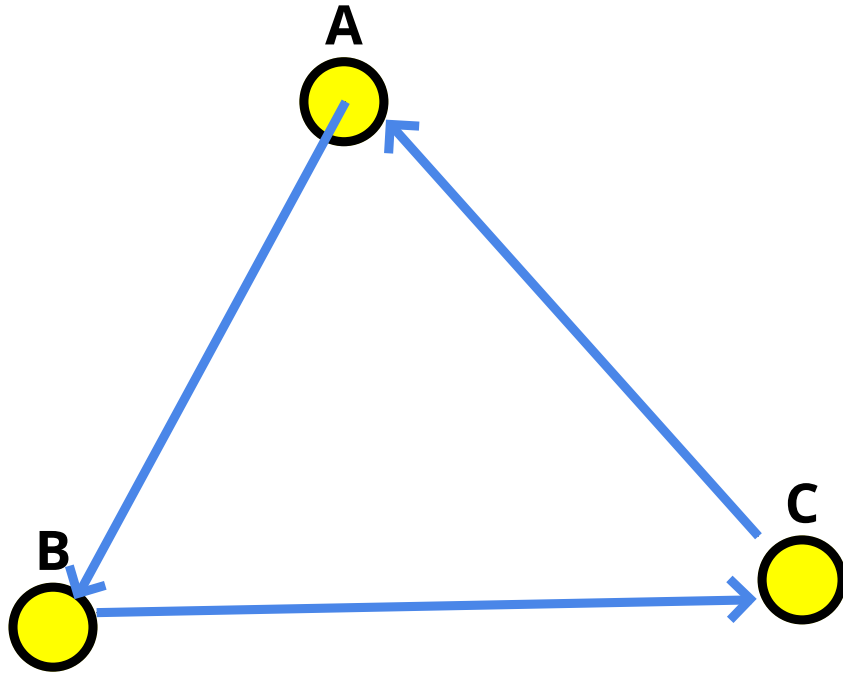


# Traveling Salesman Problem

Shortest path?

Path: A-B-D-C-A





A	B	C	A
A	C	B	A
B	A	C	B
B	C	A	B
C	A	B	C
C	B	A	C

$$3 \times 2 \times 1 = 3!$$

$$3 \text{ cities} = 3! = 6$$

$$4 \text{ cities} = 4! = 24$$

$$5 \text{ cities} = 5! = 120$$

$$50 \text{ cities} = 50! = 3.0414093e+64$$

50 cities =  $50! = 3.0414093e+64$

100,000,000,000 lightyears =  $9.46e+26$  meters

It is simply impossible.

## Traveling Salesman Problem Visualization

<https://www.youtube.com/embed/SC5CX8drAtU?enablejsapi=1>

# Implementation

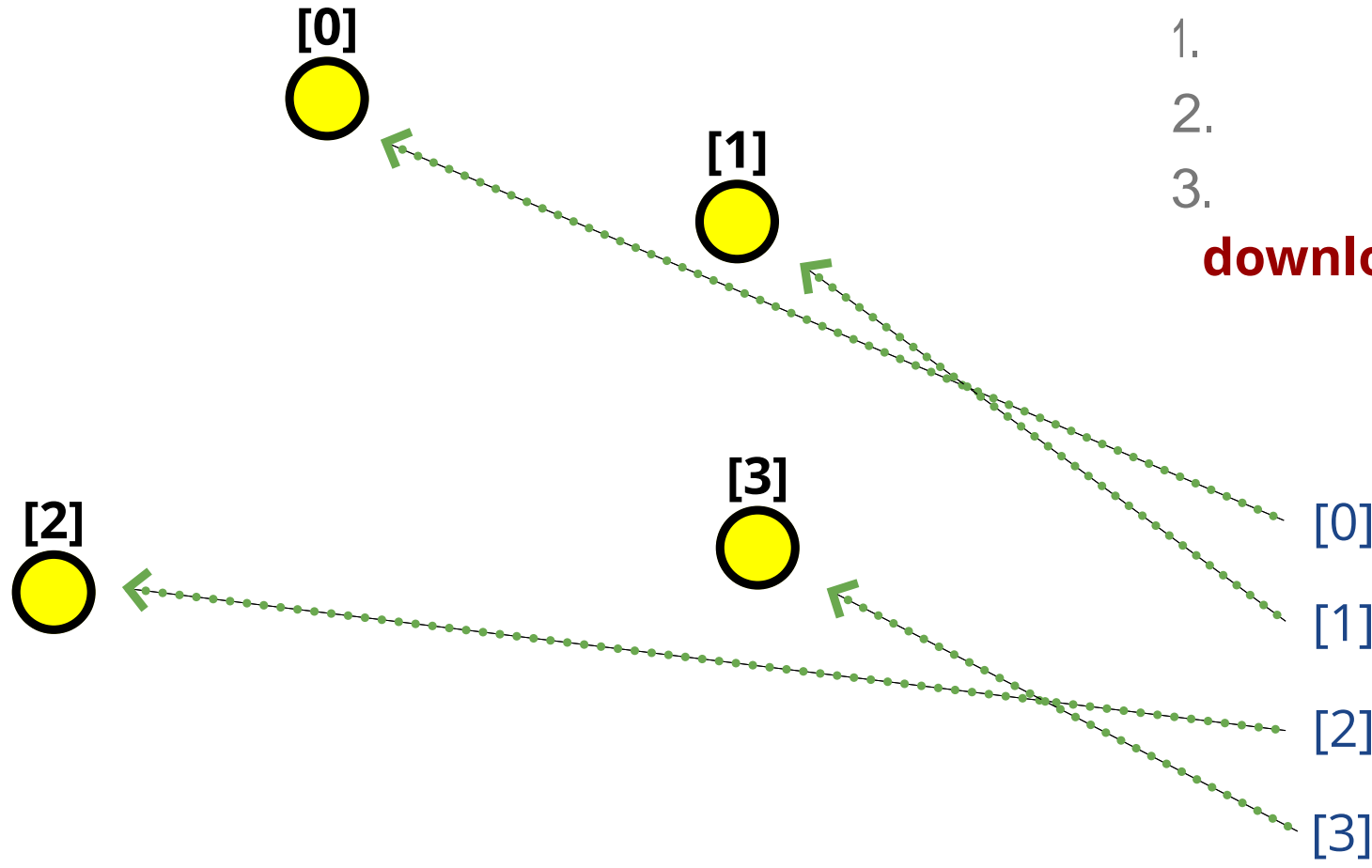
가

```
self.path = []
```

1.  
2.  
3.

downloaded list of cities

**self.nodes**




[0]	[ 0, -301.0, 187.0 ]
[1]	[ 1, 302.0, 14.0 ]
[2]	[ 2, 343.0, -138.0 ]
[3]	[ 3, -445.0, 136.0 ]


```
self.path = [0]
```

0
---


[0]



[1]



[2]



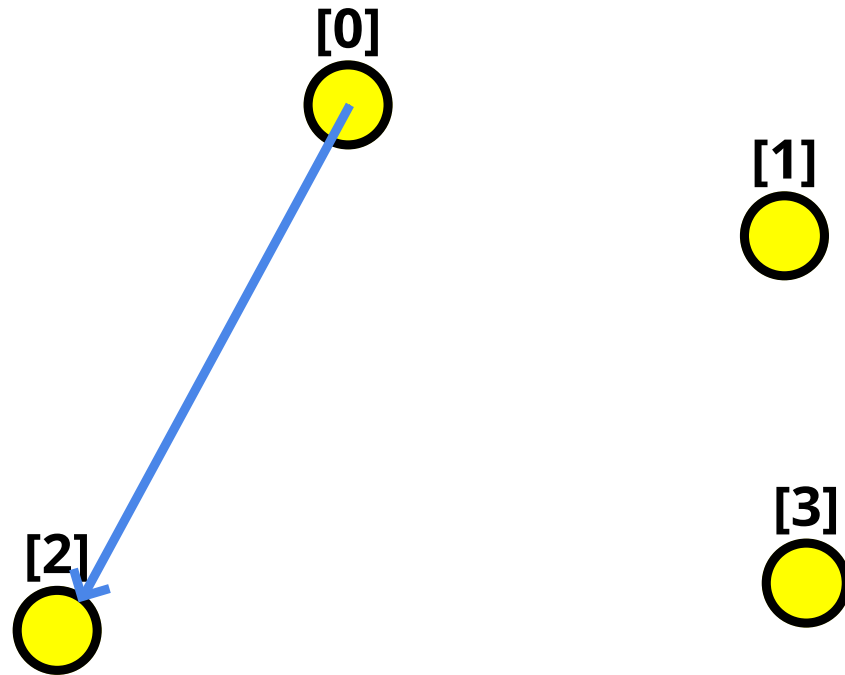
[3]



`self.nodes`

[0]	[ 0, -301.0, 187.0 ]
[1]	[ 1, 302.0, 14.0 ]
[2]	[ 2, 343.0, -138.0 ]
[3]	[ 3, -445.0, 136.0 ]



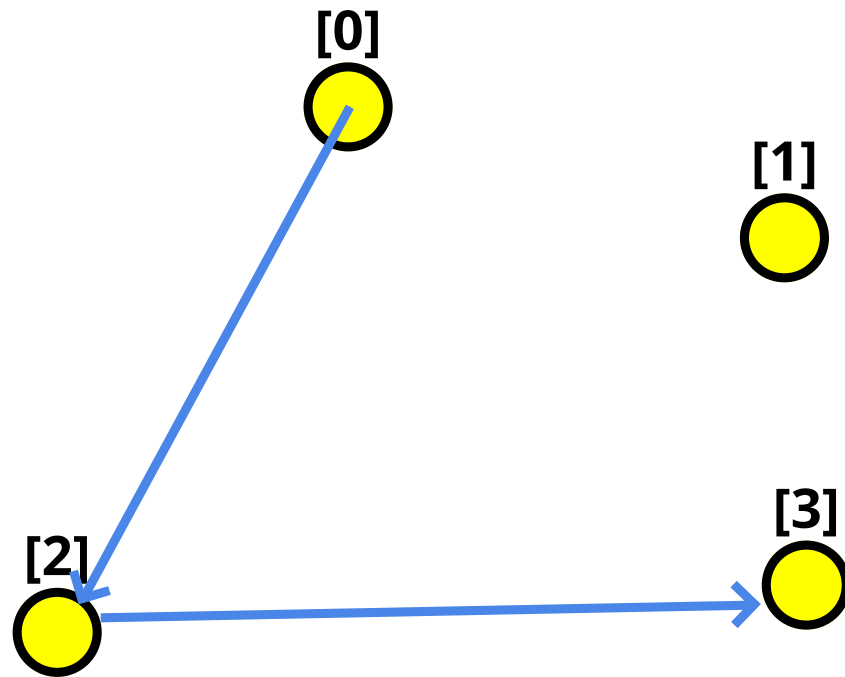


`self.path = [0,2]`

0
2

`self.nodes`

[0]	[ 0, -301.0, 187.0 ]
[1]	[ 1, 302.0, 14.0 ]
[2]	[ 2, 343.0, -138.0 ]
[3]	[ 3, -445.0, 136.0 ]

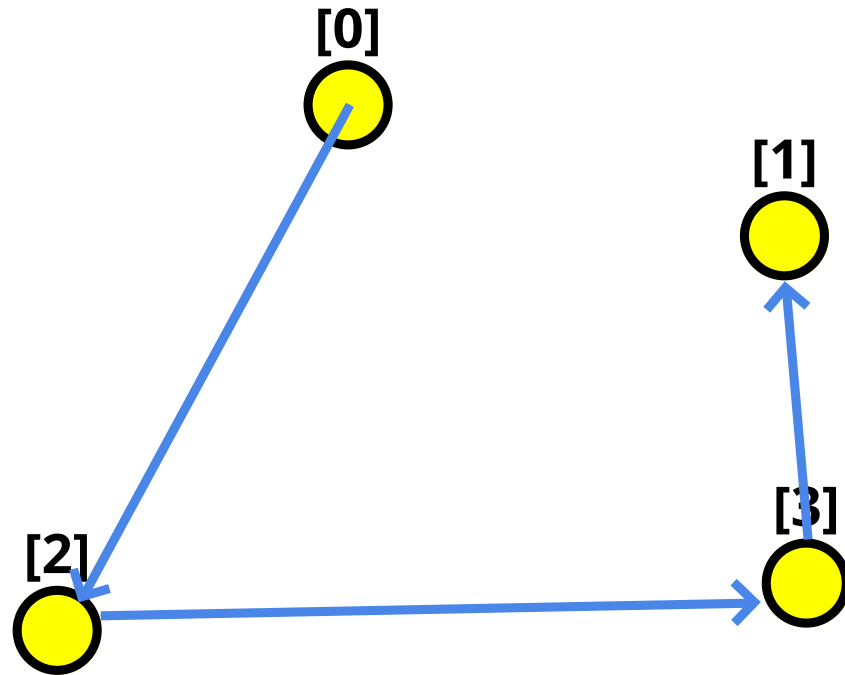


`self.path = [0, 2, 3]`

0
2
3

`self.nodes`

[0]	[ 0, -301.0, 187.0 ]
[1]	[ 1, 302.0, 14.0 ]
[2]	[ 2, 343.0, -138.0 ]
[3]	[ 3, -445.0, 136.0 ]



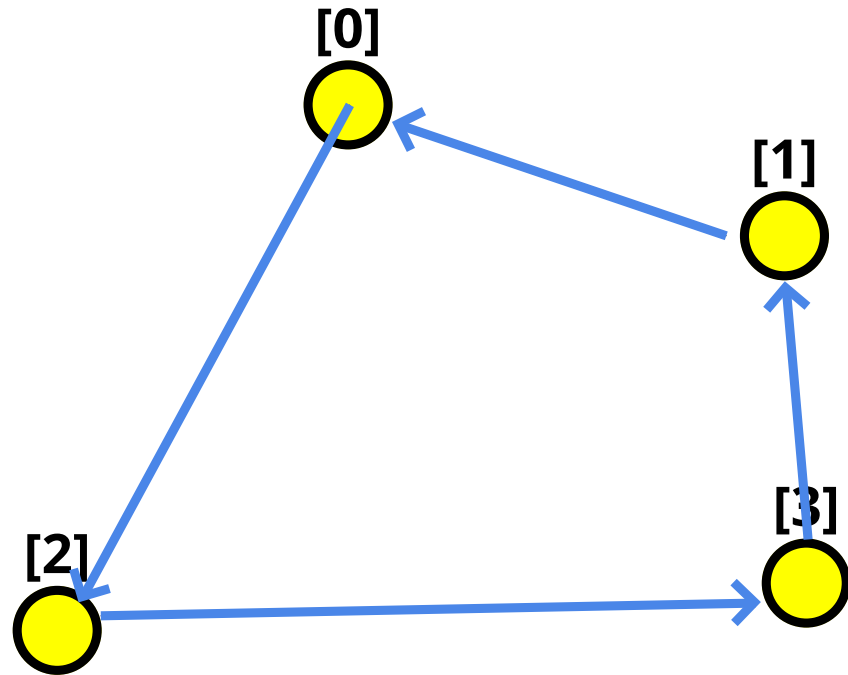
`self.path = [0, 2, 3, 1]`

0
2
3
1

`self.nodes`

[0]	[ 0, -301.0, 187.0 ]
[1]	[ 1, 302.0, 14.0 ]
[2]	[ 2, 343.0, -138.0 ]
[3]	[ 3, -445.0, 136.0 ]

`self.path = [0, 2, 3, 1, 0]`



path가

0
2
3
1
0

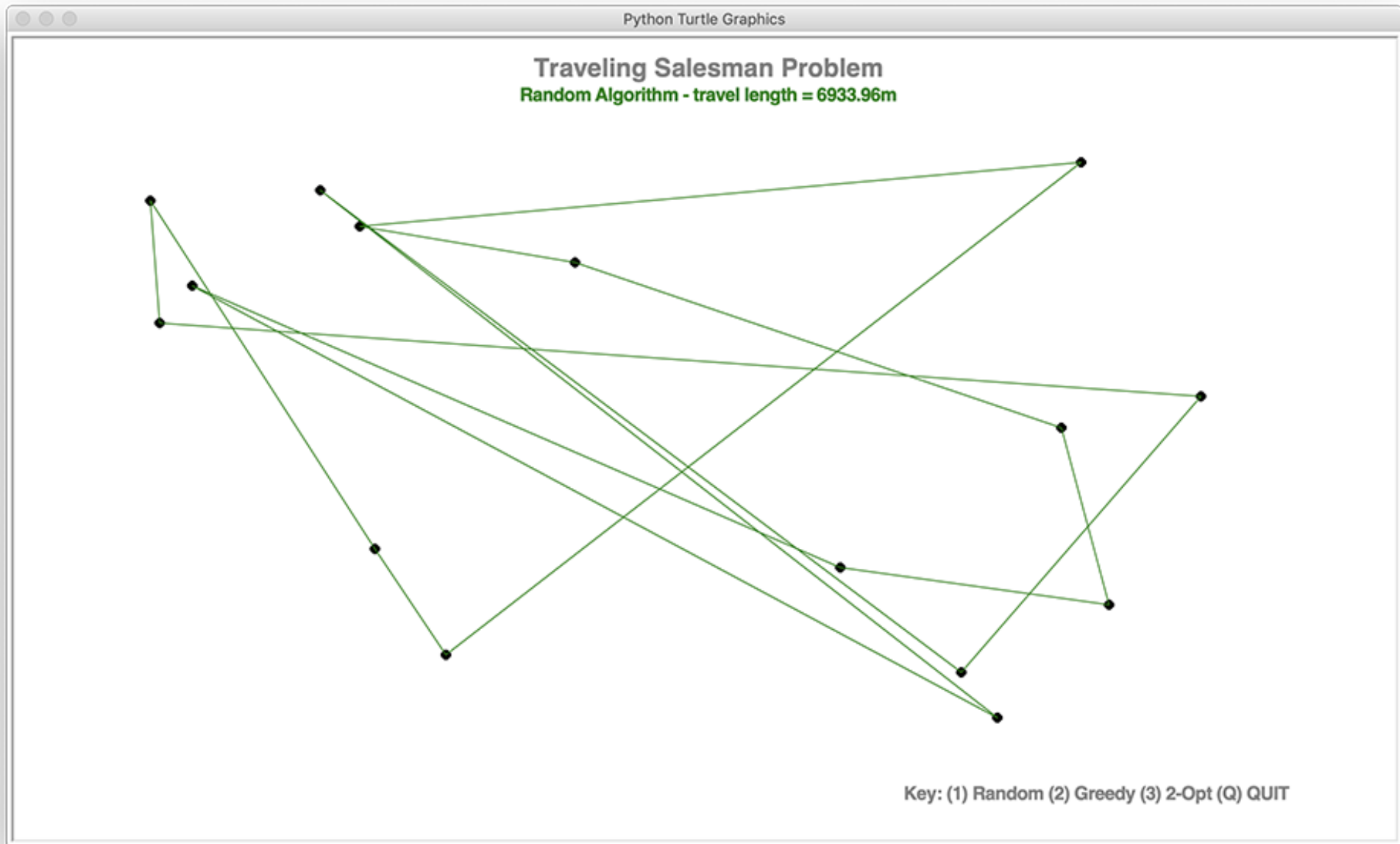
`self.nodes`

[0]	[ 0, -301.0, 187.0 ]
[1]	[ 1, 302.0, 14.0 ]
[2]	[ 2, 343.0, -138.0 ]
[3]	[ 3, -445.0, 136.0 ]

# Strategies for TSP

- Random Algorithm
- Greedy Algorithm
- 2-Opt Algorithm

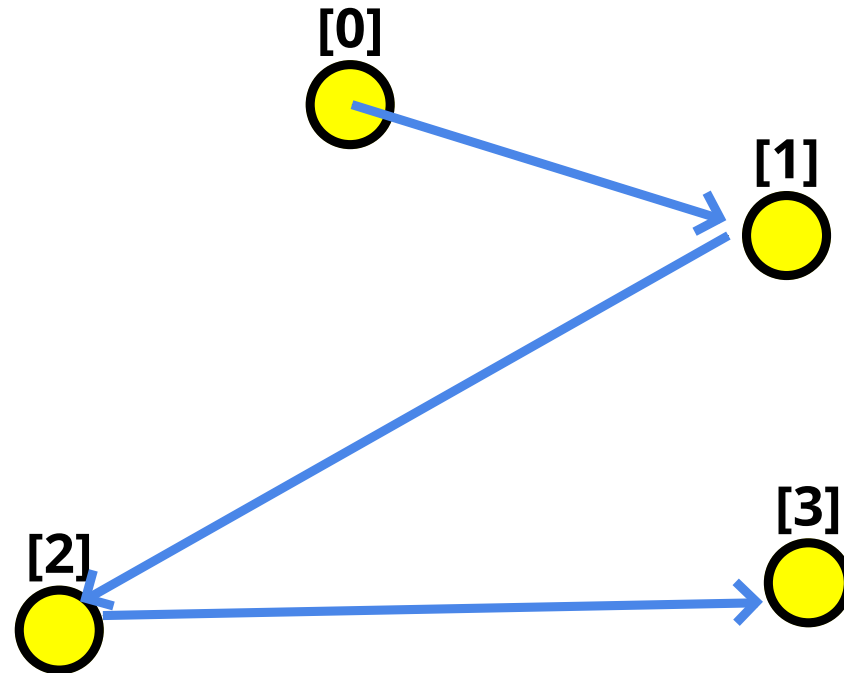
# Random Algorithm



```
self.path = [0,1,2,3]
```

0
1
2
3

`list( range(n) )` can make a path

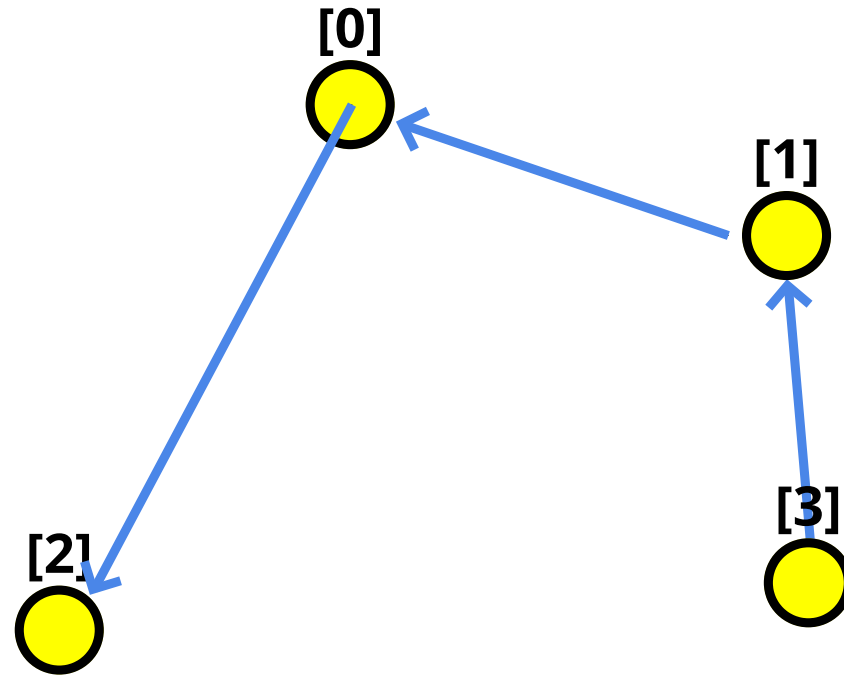




**path** = [3,1,0,2]

3
1
0
2

shuffle the path using `random.shuffle( path )`

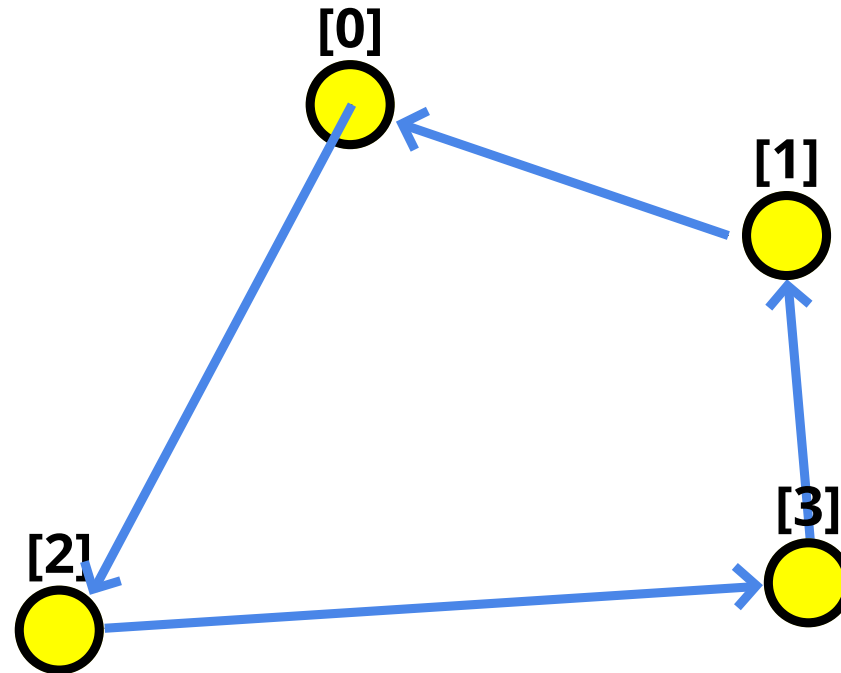


`path = [3, 1, 0, 2, 3]`

3
1
0
2
3

– append

Lastly, add `path[0]` to close the path



```
path = list(range(10))  
print('path:', path)
```

```
path: [0, 1, 2, 3, 4, 5, 6, 7, 8, 9]
```

```
import random
```

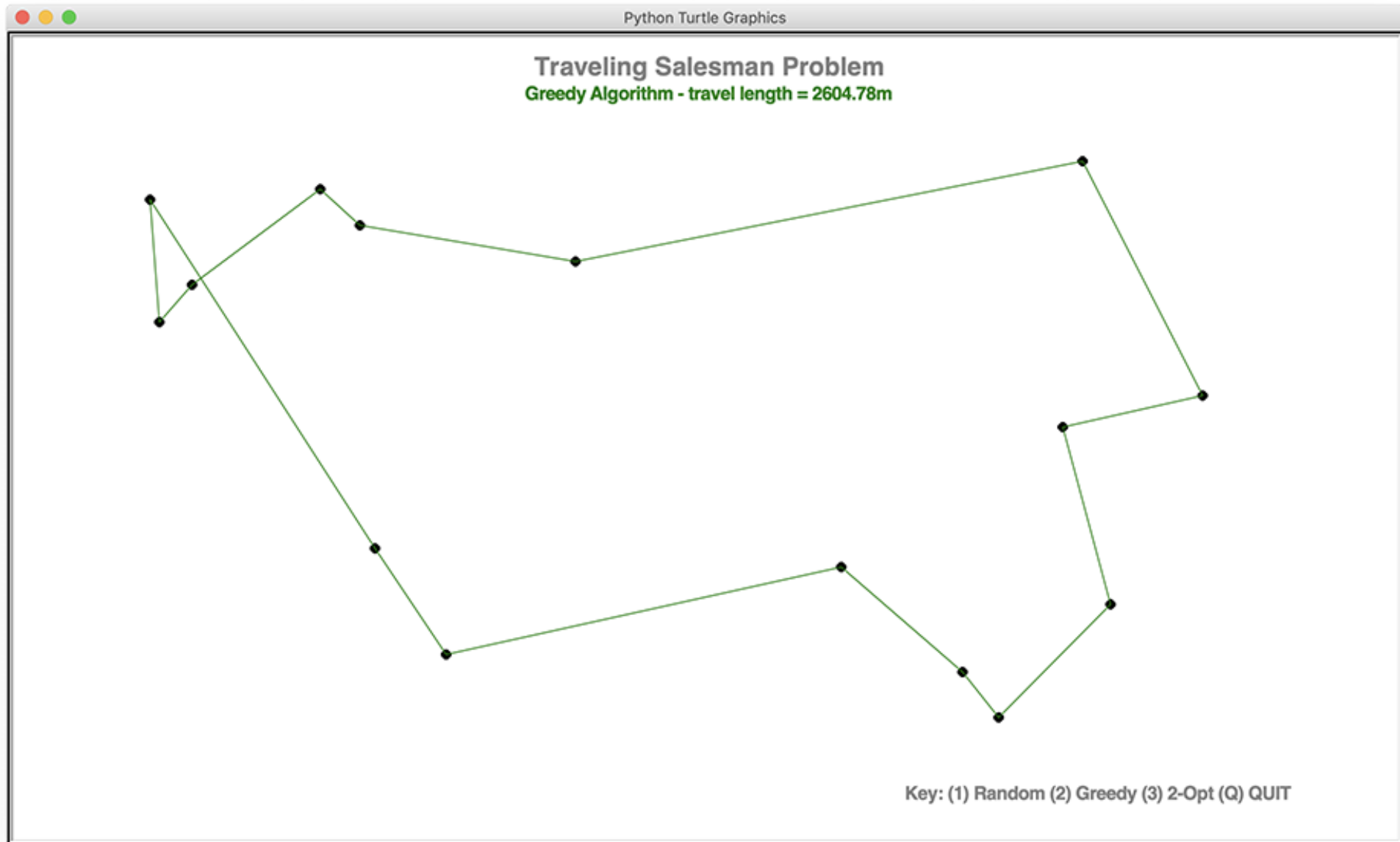
```
random.shuffle(path)  
print('path:', path)
```

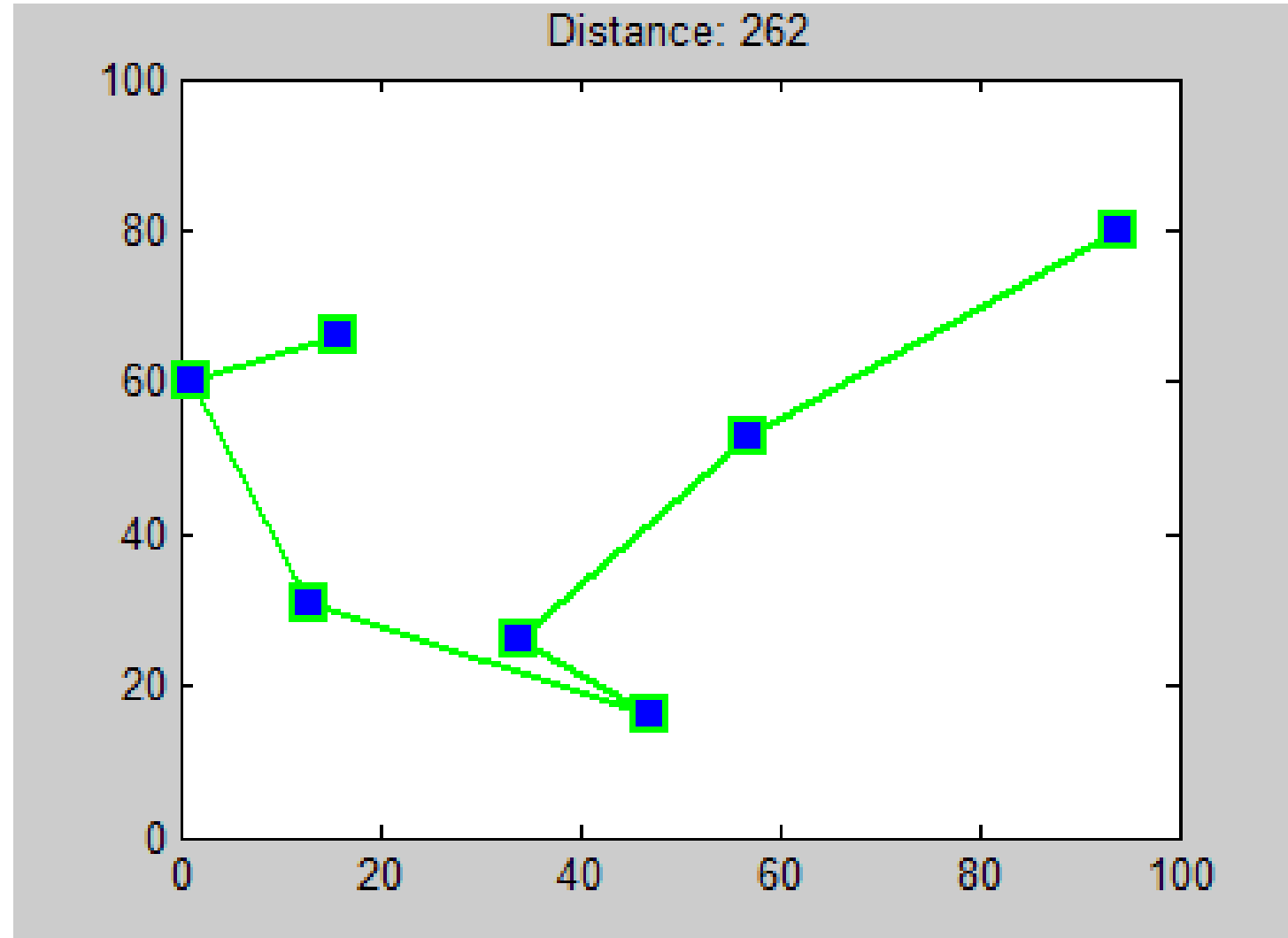
```
path: [3, 4, 9, 0, 6, 2, 1, 7, 5, 8]
```

```
path.append( path[0] ) # return to the first city  
print('path:', path)
```

```
path: [3, 4, 9, 0, 6, 2, 1, 7, 5, 8, 3]
```

# Greedy Algorithm



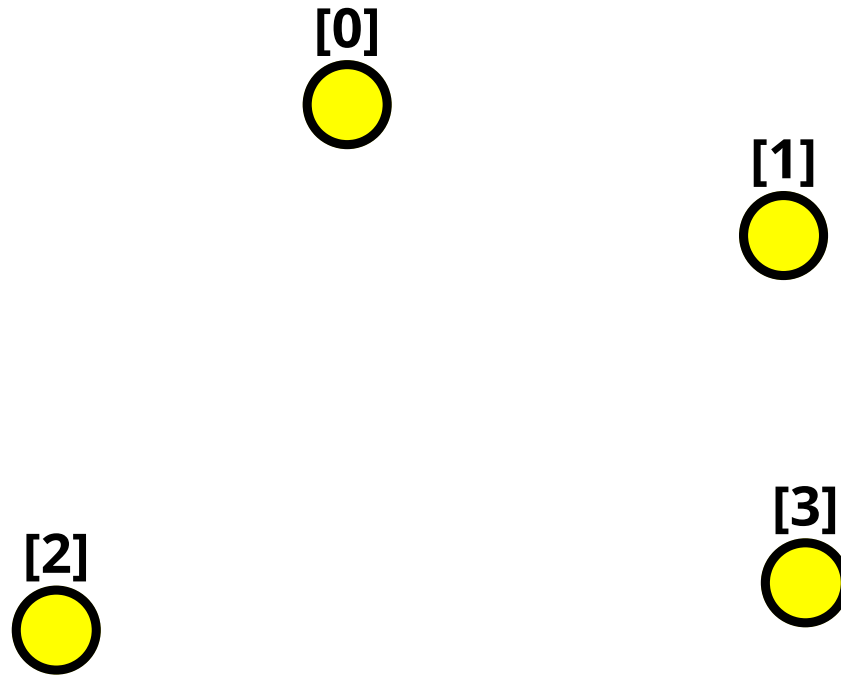


<https://upload.wikimedia.org/wikipedia/commons/2/23/Nearestneighbor.gif>

```
pool = [0, 1, 2, 3]
```

```
path = []
```

Initial path is **empty**

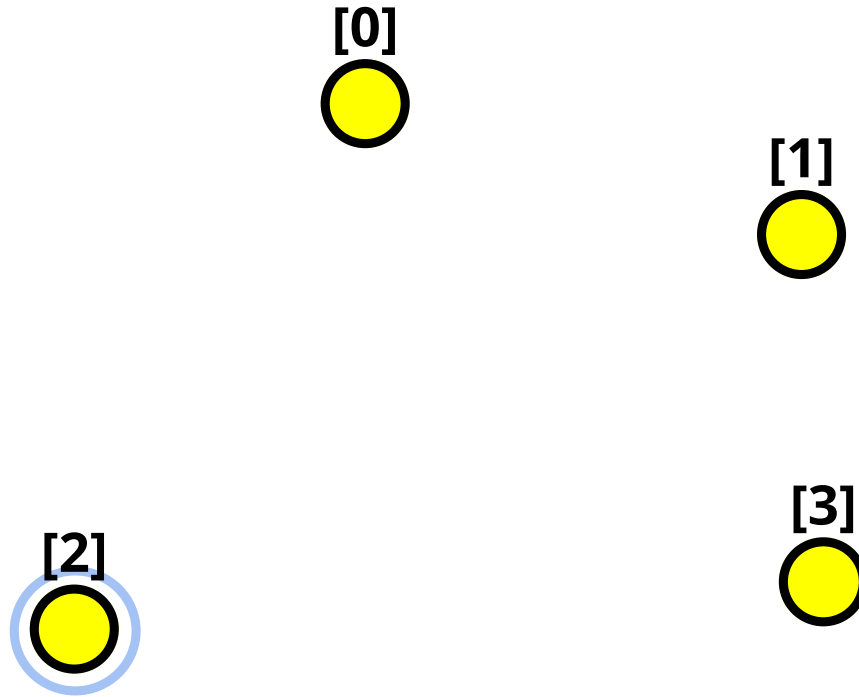


```
pool = [0, 1, 3]
```

```
path = [2]
```

2
---

**Pop** a city randomly from the pool  
and **append** to the path



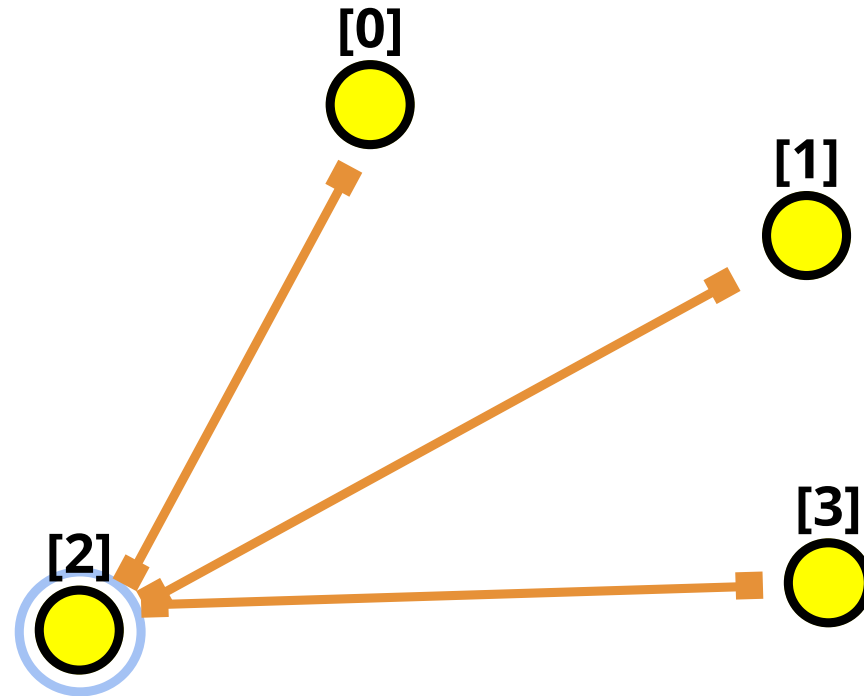


`pool = [0, 1, 3]`

`path = [2]`

2

Find the **nearest city** from the **last city** in the **pool**

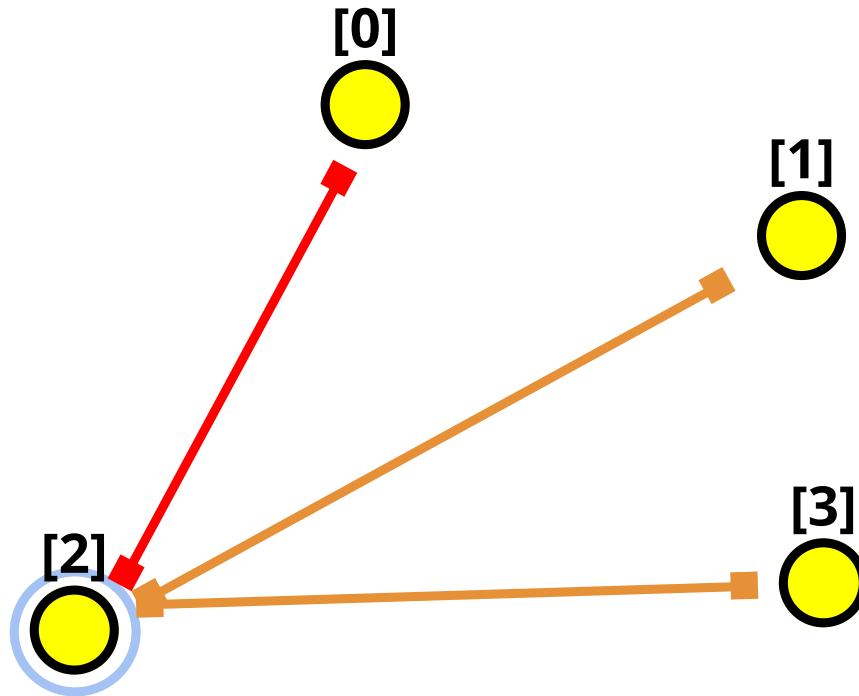


```
pool = [0, 1, 3]
```

```
path = [2]
```

2

This is the **nearest one**

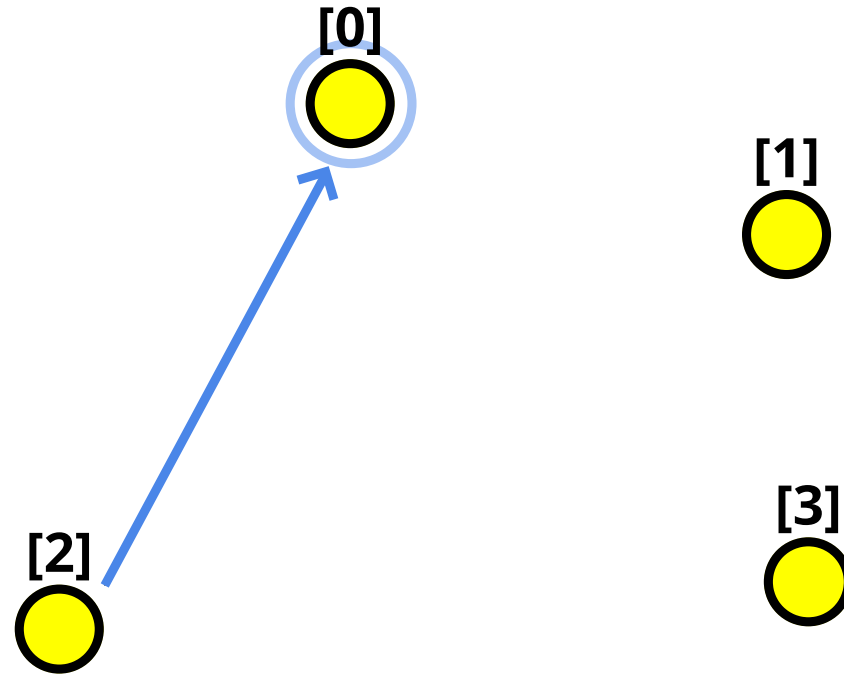


`pool = [1, 3]`

`path = [2, 0]`

2
0

**Pop** the nearest city from the pool  
and **append** to the path

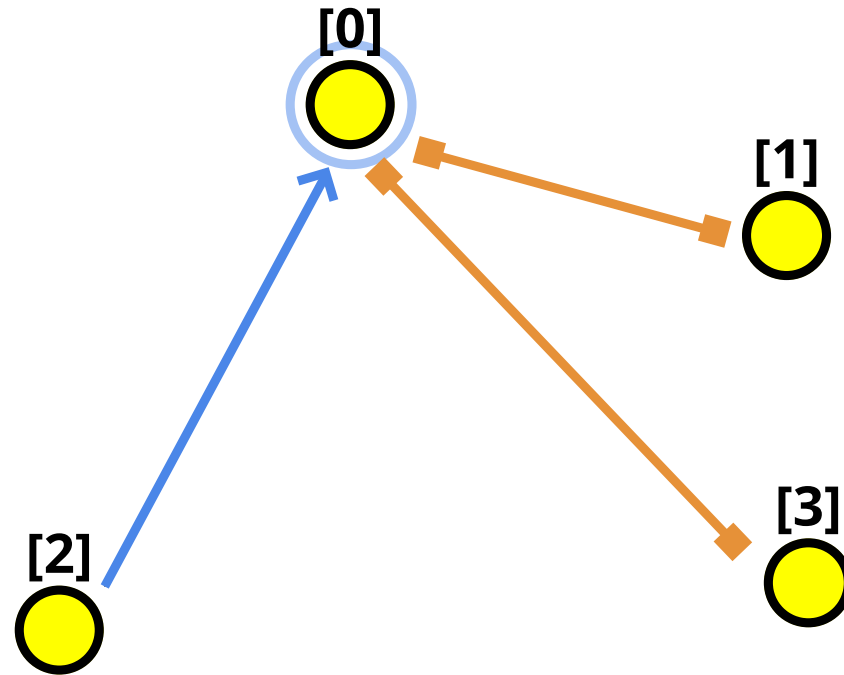


`pool = [1, 3]`

`path = [2, 0]`

2
0

Find the **nearest city** from the **last city** in the **pool**

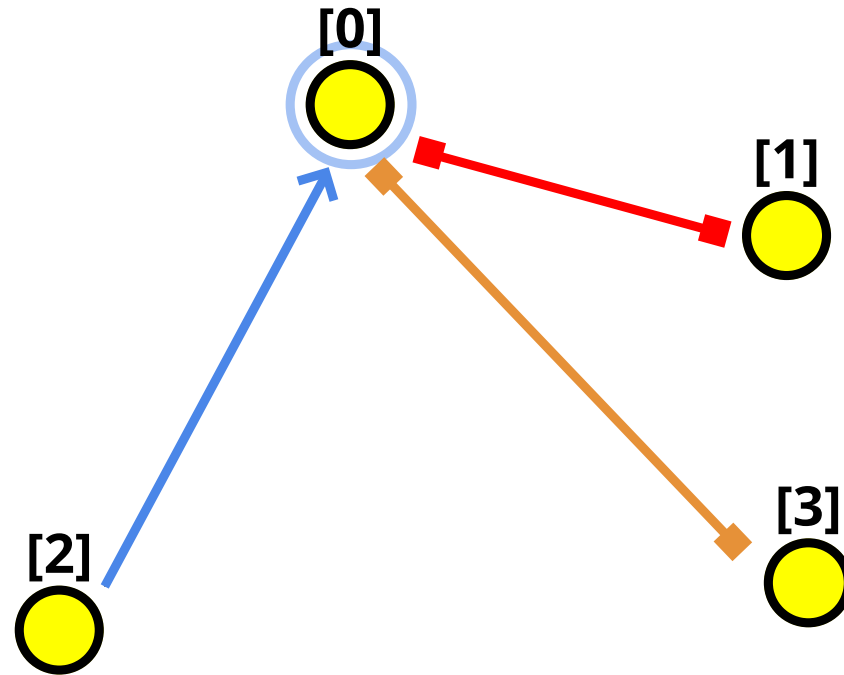


`pool = [1, 3]`

`path = [2, 0]`

2
0

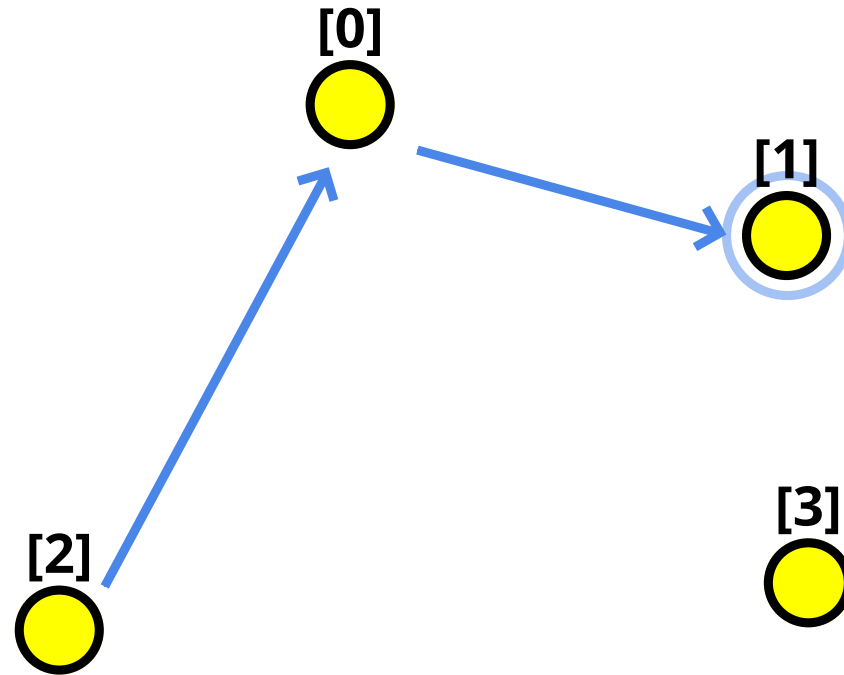
This is the **nearest one**



```
pool = [3]  
path = [2, 0, 1]
```

2
0
1

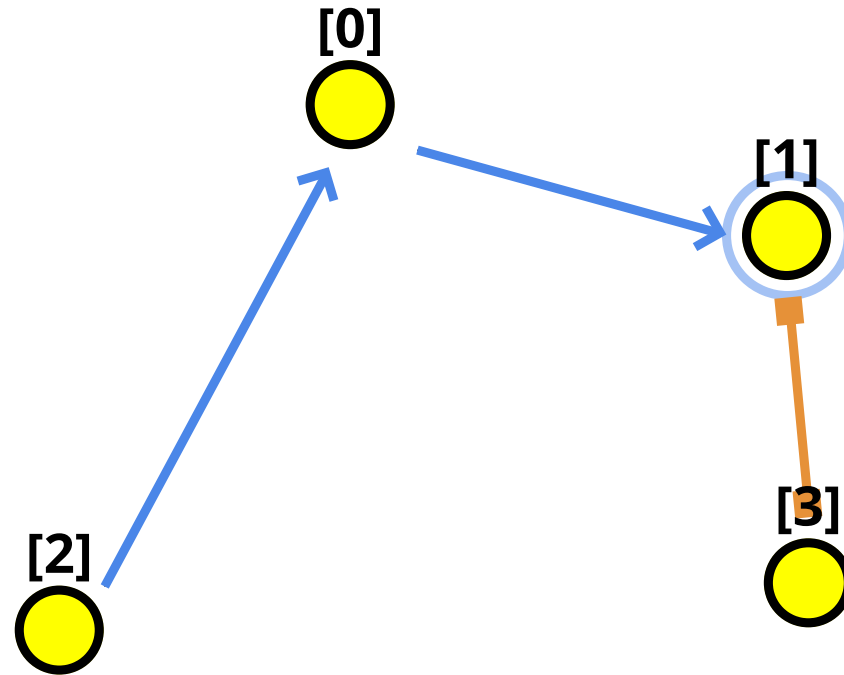
**Pop** the nearest city from the pool  
and **append** to the path



```
pool = [3]  
path = [2, 0, 1]
```

2
0
1

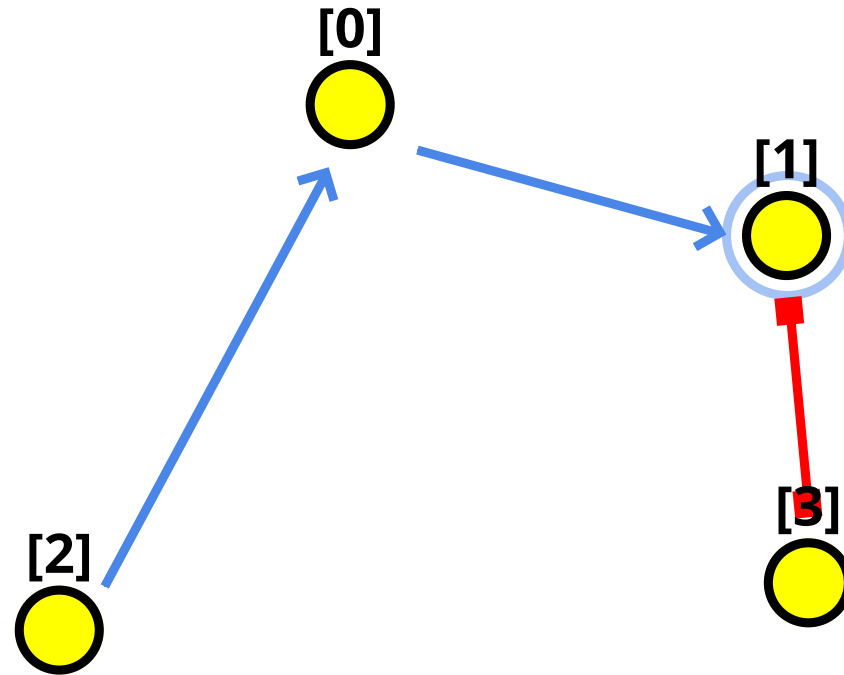
Find the **nearest city** from the **last city** in the **pool**



```
pool = [3]  
path = [2, 0, 1]
```

2
0
1

This is the **nearest one**

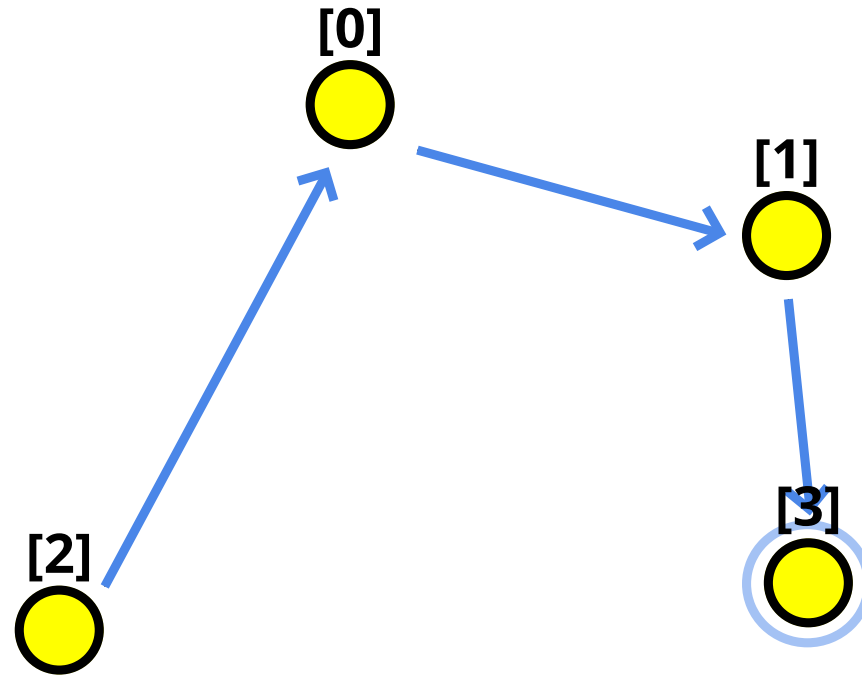




```
pool = []  
path = [2, 0, 1, 3]
```

2
0
1
3

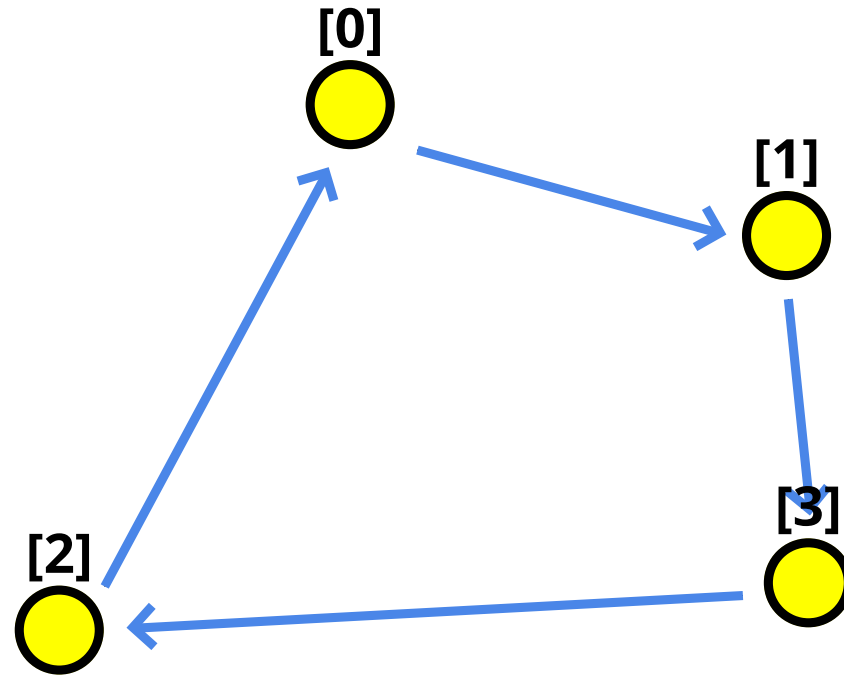
**Pop** the nearest city from the pool  
and **append** to the path



```
pool = []  
path = [2, 0, 1, 3, 2]
```

2
0
1
3
2

**Append** the first city to the last to close the path



while , pool 0

```
pool = list(range(10))  
path = []
```

```
print('pool:', pool)  
print('path:', path)
```

```
pool: [0, 1, 2, 3, 4, 5, 6, 7, 8, 9]  
path: []
```

```
city = pool.pop(3) # the first city  
path.append( city )
```

```
print('pool:', pool)  
print('path:', path)
```

```
pool: [0, 1, 2, 4, 5, 6, 7, 8, 9]  
path: [3]
```

```
city = pool.pop(5) # the second city  
path.append( city )
```

```
print('pool:', pool)  
print('path:', path)
```

```
pool: [0, 1, 2, 4, 5, 7, 8, 9]  
path: [3, 6]
```

```
city = pool.pop(0)
path.append( city )
```

```
print('pool:', pool)
print('path:', path)
```

```
pool: [9]
path: [3, 6, 0, 1, 2, 4, 5, 7, 8]
```

```
city = pool.pop(0) # the last city
path.append( city )
```

```
print('pool:', pool)
print('path:', path)
```

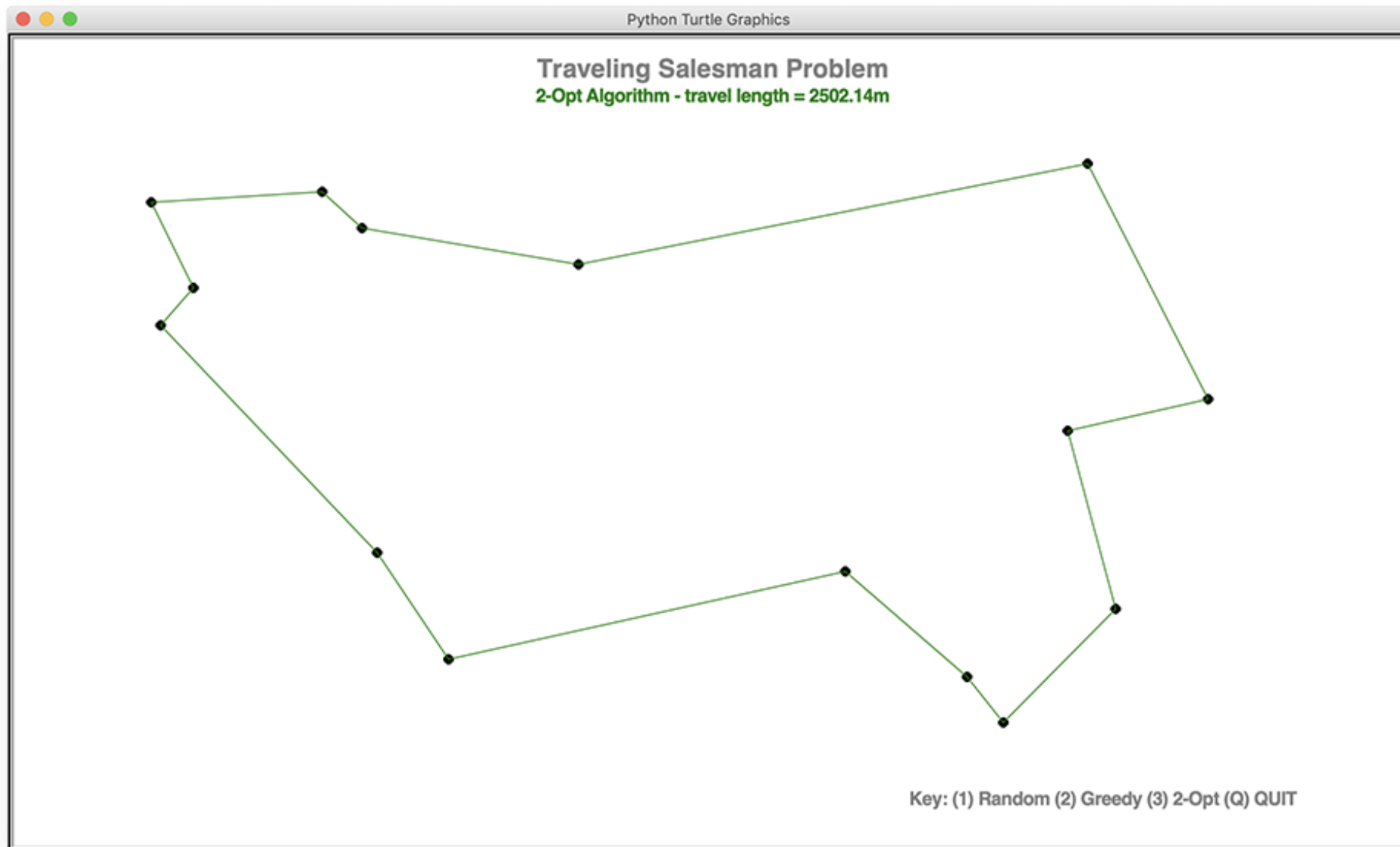
```
pool: []
path: [3, 6, 0, 1, 2, 4, 5, 7, 8, 9]
```

```
path.append( path[0] ) # return to the first city
```

```
print('path:', path)
```

```
path: [3, 6, 0, 1, 2, 4, 5, 7, 8, 9, 3]
```

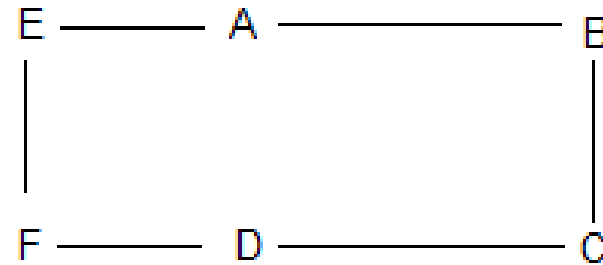
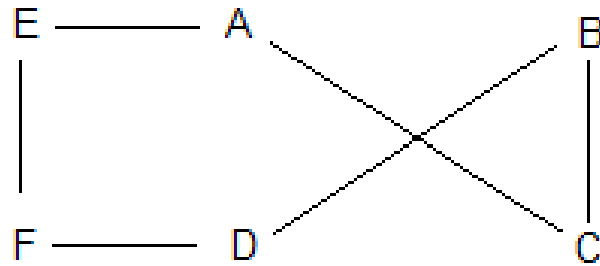
# 2-Opt Algorithm



# 2-Opt Algorithm

1. Make a complete path (random / greedy)
2. Apply a 'swap'
3. Keep the path if the changed version is shorter.
4. Repeat the process 2-3

-> 가



It works because it removes crossings

# 2-Opt Swap

1. take **start** to **path[i-1]** and add them in order to new\_route
2. take **path[i]** to **path[k-1]** and add them in **reverse** order to new\_route
3. take **path[k]** to **end** and add them in order to new\_route

**example route:** A ==> B ==> C ==> D ==> E ==> F ==> G ==> H ==> A

example i = 3, example k = 7

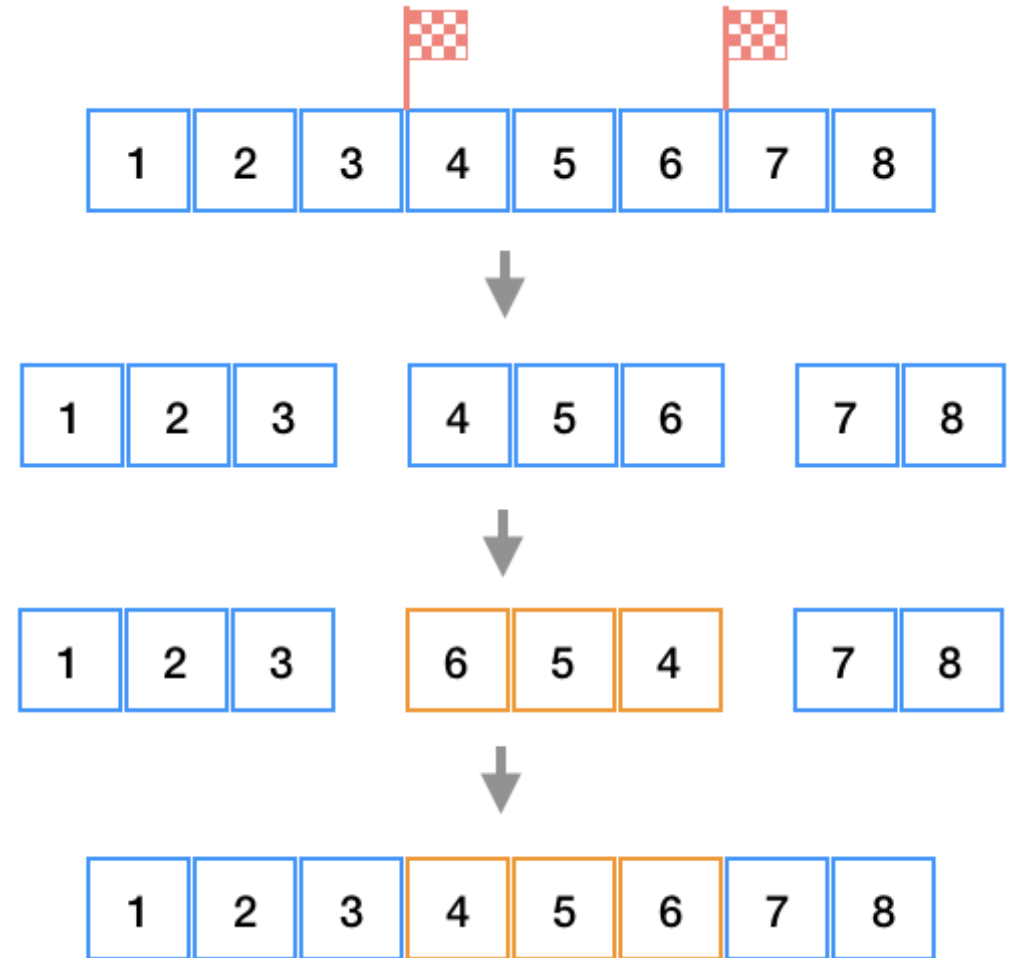
**new\_route:**

1. **A ==> B ==> C**      D,E,F,G      swap
2. A ==> B ==> C ==> **G ==> F ==> E ==> D**
3. A ==> B ==> C ==> G ==> F ==> E ==> D ==> **H ==> A**



# 2-Opt Swap

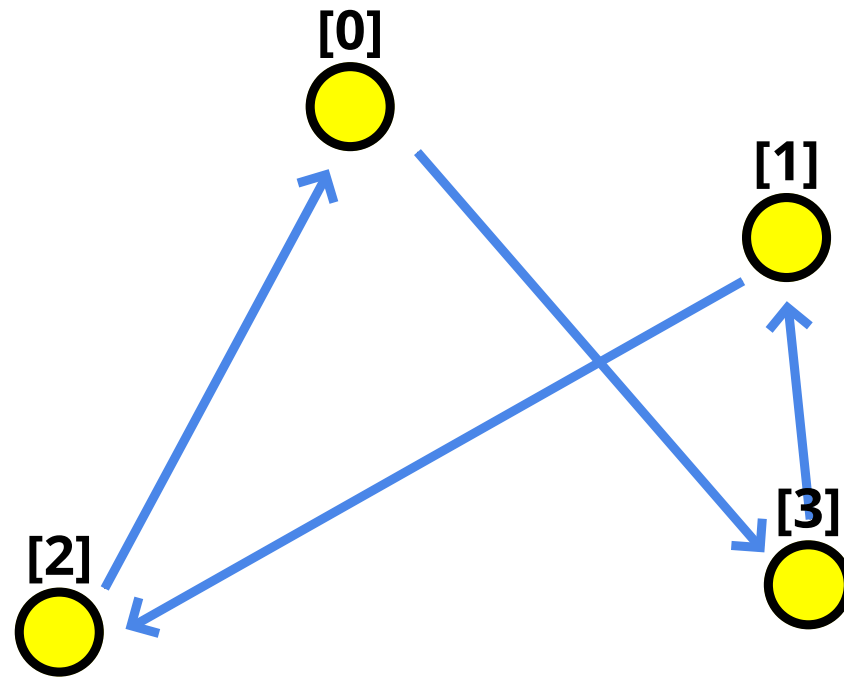
1. Slice a path to **path1**, **path2**, **path3**
2. Reverse the **path2**
3. Concatenate path1 + **path2** + path3



**path = [2, 0, 3, 1, 2]**

2
0
3
1
2

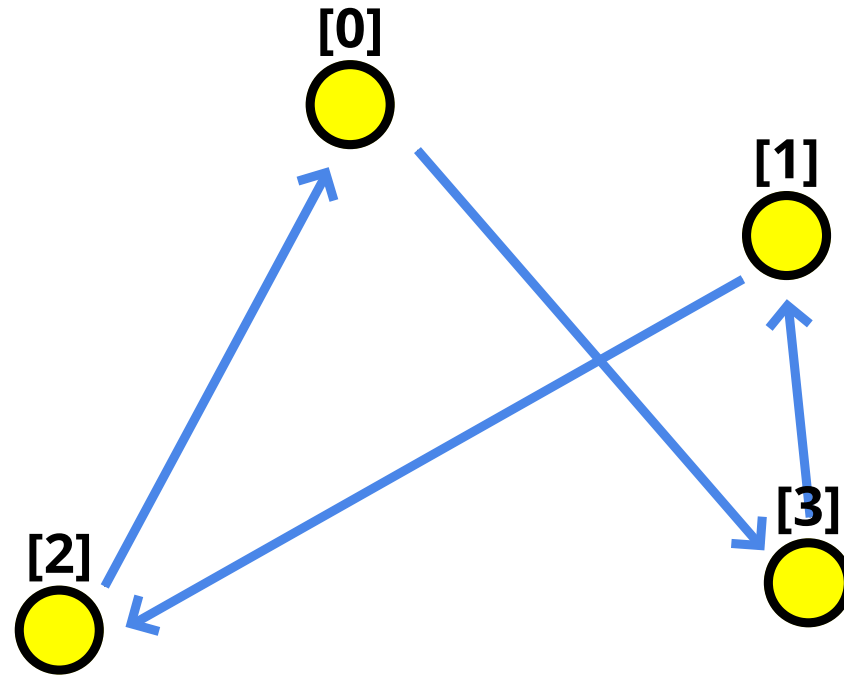
an Initial path



```
path1 = [2,0], path2 = [3,1], path3 = [2]  
path = [2,0,3,1,2]
```

2
0
3
1
2

set **i**, **k** randomly (**i** = 2, **k** = 4)  
slice the path into path1, **path2**, path3

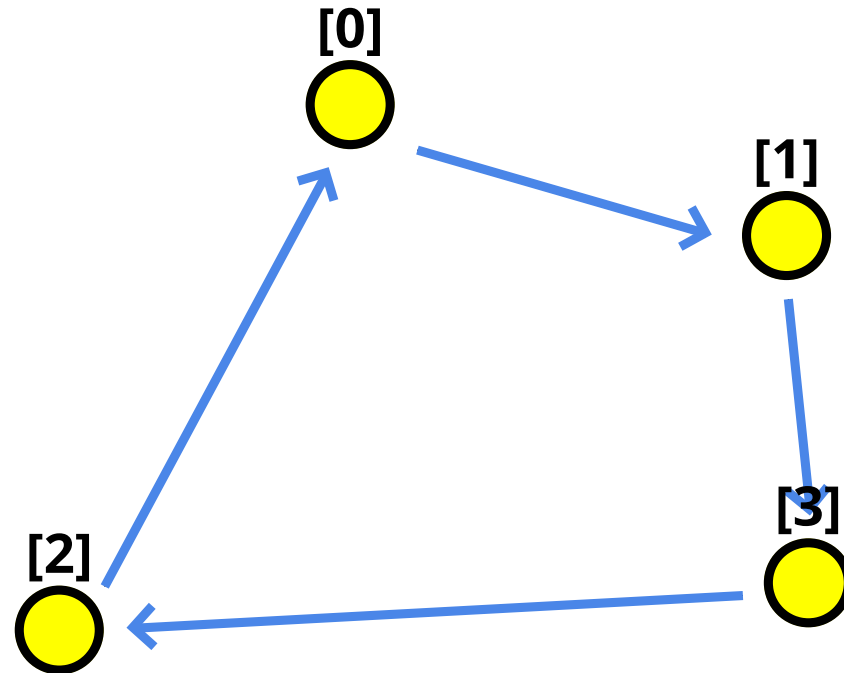


```
path1 = [2,0], path2 = [1,3], path3 = [2]  
path = [2,0,1,3,2]
```

2
0
1
3
2

reverse **path2**

new\_path = path1+**path2**+path3



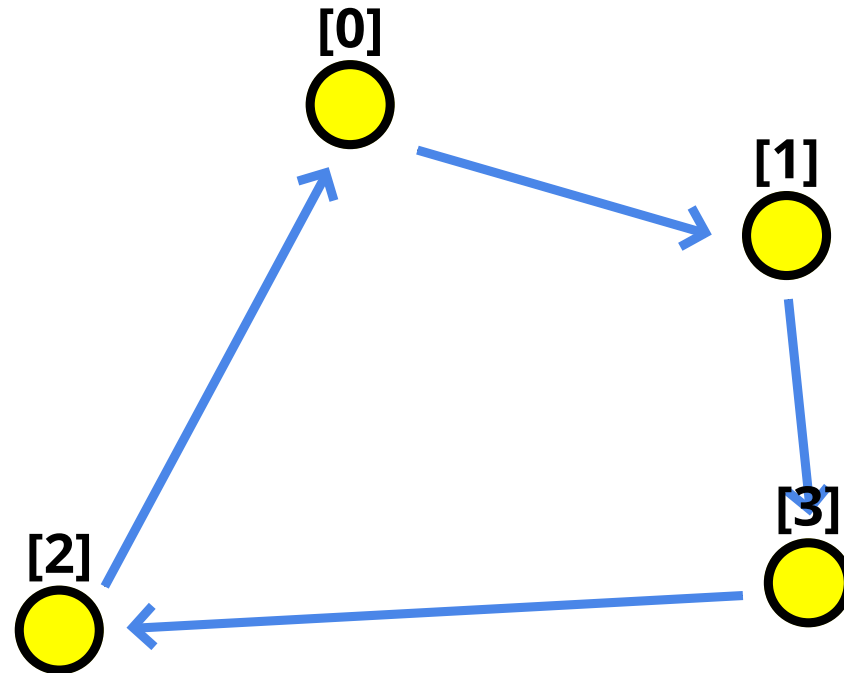
```
calc_path_length(path) > calc_path_length(path_new)
```

**path** = [2, 0, 1, 3, 2]

2
0
1
3
2

path = new\_path

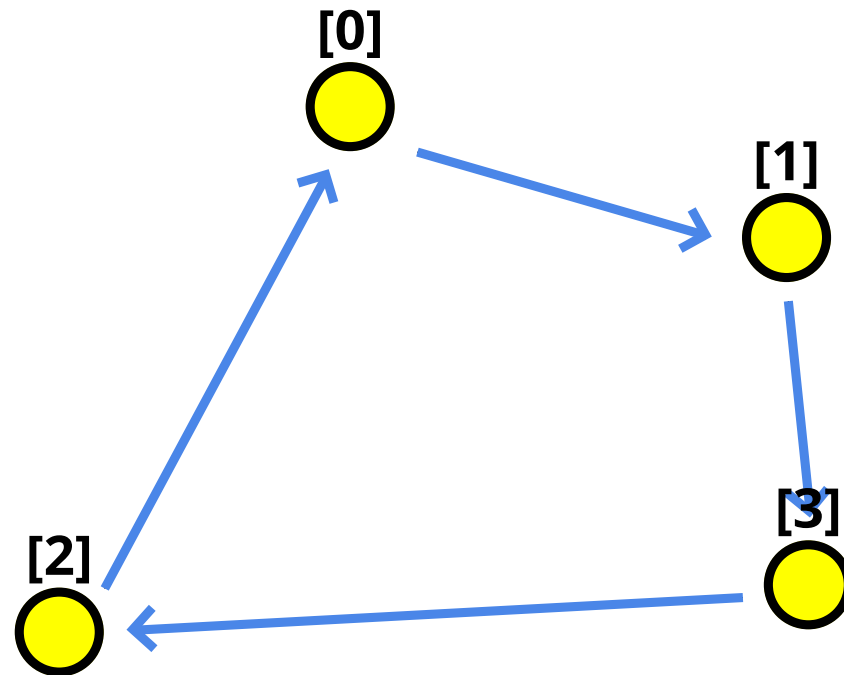
if the new\_path is shorter than the path



**path = [2, 0, 1, 3, 2]**

2
0
1
3
2

Repeat N times



```
1 path = list(range(10))
2 path.append( path[0] )
3
4 print('path:', path)
```

```
path: [0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 0]
```

```
1 i = random.randint(1, len(path)-2) # Edit this
2 k = random.randint(i, len(path)-2) # Edit this
3 print(i, k)
```

```
1 7
```

```
1 path1 = path[:i]
2 path2 = path[i:k]
3 path3 = path[k:]
4
5 print('path1:', path1)
6 print('path2:', path2)
7 print('path3:', path3)
```

```
path1: [0]
path2: [1, 2, 3, 4, 5, 6]
path3: [7, 8, 9, 0]
```

```
1 print('path2:', path2)
2
3 path2.reverse()
4
5 print('path2:', path2)
```

```
path2: [1, 2, 3, 4, 5, 6]
path2: [6, 5, 4, 3, 2, 1]
```

```
1 path = path1 + path2 + path3
2
3 print('path:', path)
```

```
path: [0, 6, 5, 4, 3, 2, 1, 7, 8, 9, 0]
```



# Code

## Random Algorithm

```
1      # Random Algorithm
2      def make_random_path(self):
3
4          # make a path containing all nodes
5          result = [] # EDIT THIS
6
7          # shuffle
8              # EDIT THIS
9
10         # return to the first city
11         if len(result) > 0:
12             result.append( result[0] )
13
14         # update with the new path
15         self.set_new_path( result, 'Random Algorithm' )
```

# Greedy Algorithm

```
1  # Greedy Algorithm
2  def make_greedy_path(self):
3
4      # make a pool containing all nodes
5      pool = list(range(len(self.nodes)))
6
7      result = []
8
9      # pop the first node from the pool and append to the result
10     # EDIT THIS
11
12     # while there are any remaining node
13     while len( pool ) > 0:
14
15         # initialize min_dist and min_index
16         min_dist = None
17         min_index = None
18
19         # for every remaining nodes
20         for i in range(len(pool)):
21
22             # get the most recently added node
23             node1 = 0 # EDIT THIS
24             # the current remaining node
25             node2 = 0 # EDIT THIS
26             # calculate the distance between two ( using self.calc_dist() )
```

## 2-Opt Algorithm

```
1      # 2-Opt Algorithm
2      def make_2opt_path(self):
3
4          # make a path
5          self.make_random_path()
6
7          # loop 100 times
8          for i in range(100):
9
10             # modify the current path
11
12             # select random two node indices
13             i = 0 # EDIT THIS
14             k = 0 # EDIT THIS
15
16             # slice the path with three segments (path1, path2, path3)
17             path1 = [] # EDIT THIS
18             path2 = [] # EDIT THIS
19             path3 = [] # EDIT THIS
20
```

# Submit

- **Deadline: 9 December (Mon) 23:55 pm**
- Modify the given code and submit as **tsp\_201812345.py**
- Put comments in your codes
- Visual competition(optional): ( )
  - submit a screen recording (e.g. **tsp\_201812345.mp4**)
    - Screen recording tools
      - Windows: Bandicam (반디캠) 10-15sec 가
      - Mac OS: shift-cmd-5

# TSP Competition

- **10 December (Tue) class time**
- **Performance Competition**
  - 3 rounds
  - round time: **60 sec**
- **Visual Competition**
  - Audience evaluation

# Q&A