

# Financial Data Science

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# Vorlesung 5: Introduction to Time Series Analysis

# What are time series?

The main aspect of time series data compared to other data is **time**. Time series are thus data points collected over time: time will always be on the x-axis. Time is a crucial variable that **inherits important information** for the underlying data.



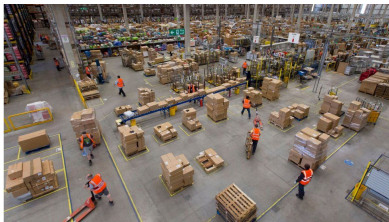
Data over time includes certain difficulties that are unique to time series data. Specifically designed models for time series data take care of these **aspects**:

- Trends
- Stationarity/Non-Stationarity
- Auto-correlation
- Seasonality or cycles
- Conditional variance

Time series modelling is **widely applied in different industries** ranging from finance to health care. Popular applications include:

- Economic forecasting (revenue, sales, demand ...)
- Financial modelling (stock prices, volatility, ...)
- Predicting customer behavior (user views, new users, ...)
- Anomaly detection (defect detection, ECG signals, ...)

**Example:** Amazon needs to predict the demand for **socks** in December 2022 in North Rhine-Westphalia, Germany.



- The company uses **time series modelling** to **forecast** the demand and thus the required inventory.
- The forecast is crucial to meet customer needs, lower shipping time and reduce inventory waste.
- Any large forecast errors lead to substantial declines in revenue and customer satisfaction.

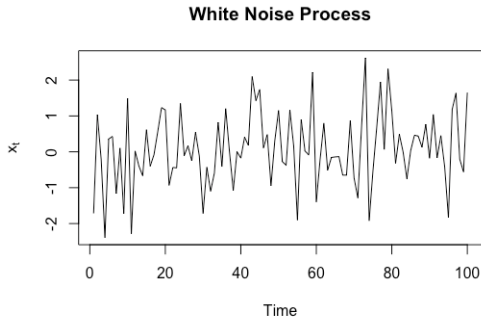
The time series models that we will look at:

- Autoregressive Model (AR)
- Moving Average Model (MA)
- ARMA
- AR Integrated MA (ARIMA)
- Seasonal ARIMA (SARIMA)
- AR Conditional Heteroskedasticity Model (ARCH)
- Generalized ARCH (GARCH)

We can use these models to analyze the time series and make **forecasts for the future**.

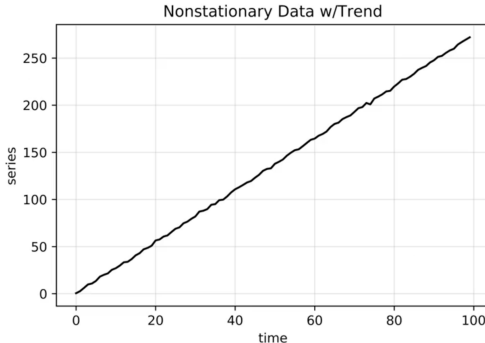
Most time series models require stationary time series data. A time series is **stationary** if it has these 3 properties:

- Constant mean
- Constant variance
- No periodic/seasonal component

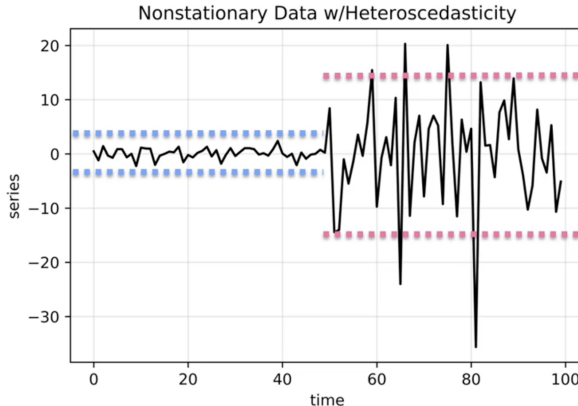




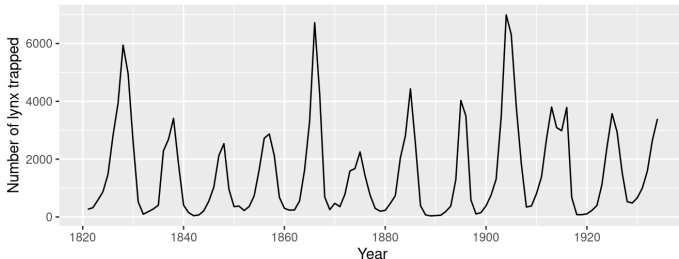
**No Constant Mean:** If the time series has an underlying **trend** (in this case increasing), the mean is not constant but changing throughout time.



**No Constant Variance:** If the time series has a differing variance across observations, the series is called **heteroscedastic**, the variance is thus not constant throughout time.



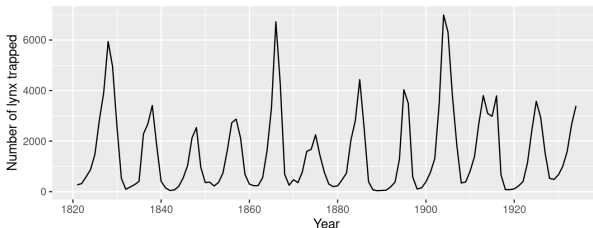
**Seasonal/Periodic Component:** Many time series experience **seasonality/cyclicity**. The variable is thus highly influenced by the current season/period/cycle.



**Autocorrelation** is a key concept and prevalent in most time series data. It means today's value is significantly dependent on (correlated with) some past value(s).

The time interval between the correlated values is called **lag**.

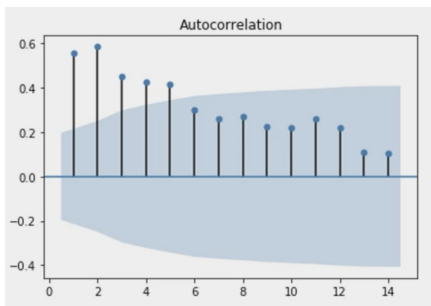
**Example:** If it rained yesterday, it is more likely to also rain today (this would imply a lag=1).



To check for autocorrelation, we can use a plot for the autocorrelation function: **ACF**.

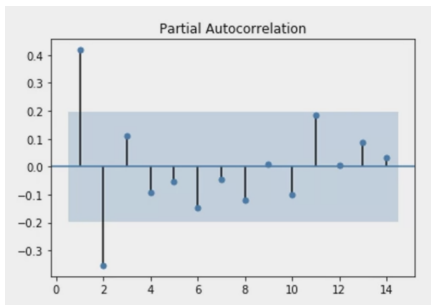
It shows the correlation between the variable and its past values.

The problem with the ACF is that it does not control for other lags. For example, the correlation between  $y_t$  and  $y_{t-3}$  is probably also influenced by  $y_{t-1}$  and  $y_{t-2}$ .



The partial autocorrelation function **PACF** also summarizes dependence on past values but it only measures partial results (controlling for other lags).

We can use the PACF plot to determine which lags to incorporate into our models. For example on this plot, we can see that only the two most recent values are statistically significant (lags 1 and 2).



The autoregressive (**AR**) model specifies that the variable linearly depends on its own **past values**.

An AR(**p**) model is assumed to depend on the **last p values**. For **p = 2**:

$$y_t = \phi_1 y_{t-1} + \phi_2 y_{t-2} + \omega_t,$$

where  $\phi_1$  and  $\phi_2$  are the regression coefficients and  $\omega_t$  is the **forecast error**, similar to an ordinary linear regression with  $y_{t-1}$  and  $y_{t-2}$  as the regressors.

To determine **p**, we can use the significant lags of the PACF.

The moving average (**MA**) model specifies that the variable linearly depends on **past forecast errors**.

An MA(**q**) model is assumed to depend on the **last q values** of the forecast errors. For **q = 2**:

$$y_t = c + \theta_1 \omega_{t-1} + \theta_2 \omega_{t-2} + \omega_t,$$

where  $\theta_1$  and  $\theta_2$  are the regression coefficients and  $\omega_{t-1}$  and  $\omega_{t-2}$  are the previous forecast errors.

To determine **q**, we can use the significant lags of the ACF.



# Let's practice!

## Notebooks:

- *AR Model*

## Data:

- `ice_cream.csv`

The **ARMA** model combines the aspects of the AR and the MA models.

Combining an **AR(2)** with **p=2** and an **MA(2)** with **q=2** leads to an **ARMA(2,2)** model:

$$y_t = \mu + \phi_1 y_{t-1} + \phi_2 y_{t-2} + \theta_1 \omega_{t-1} + \theta_2 \omega_{t-2} + \omega_t,$$

which thus depends on past observations values as well as past values of forecast errors.

The ARMA model assumes that the time series is **stationary**. We also need to check if the time series has a **seasonal** component, then we need to include a seasonal AR term.

We can test if a time series is stationary with the **augmented Dickey-Fuller test (ADF test)**.

- $H_0$ : A unit root is present (the time series is non-stationary).
- $H_1$ : The time series is stationary.

Thus we we want to reject the null-hypothesis ( $p\text{-value} < 0.05$ ).

If we find the time series to be non-stationary, we first have to make it stationary in order to apply the time series models that rely on this assumption.

We can often transform non-stationary series into stationary series by **differencing**. Differencing is done by subtracting the previous value from each observation.

**Example:** Stock prices are non-stationary (but **integrated** instead). By differencing we go from stock prices to stock returns. Stock returns are usually stationary.

The differencing can be done manually, to then apply i.e. the ARMA model. Or we can directly use the **ARIMA** model that does this automatically.

The auto regressive integrated moving average model (**ARIMA**) is an ARMA model designed to deal with **integrated** data. The model is denoted by  $\text{ARIMA}(\mathbf{p}, \mathbf{d}, \mathbf{q})$  with:

- the order of the AR model **p**.
- the number of times to difference the data **d**.
- the order of the MA model **q**.

**d** is the number of times to perform a lag-1 difference on the integrated data  $Y_t$ .

### Example:

$$\mathbf{d=1} : y_t = Y_t - Y_{t-1}$$

$$\mathbf{d=2} : y_t = (Y_t - Y_{t-1}) - (Y_{t-1} - Y_{t-2})$$

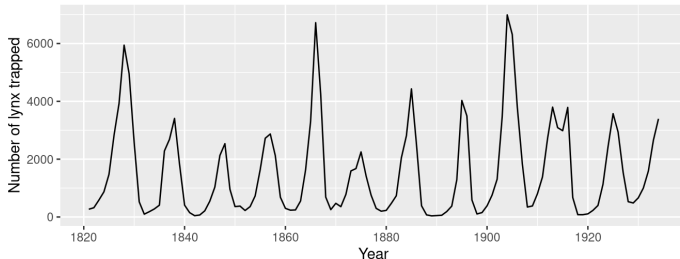
If the time series has a seasonal component, we can use the Seasonal ARIMA (**SARIMA**). It is used to remove seasonal components.

The model is denoted by **SARIMA**(**p,d,q**)(**P,D,Q**)<sub>M</sub>. P, D and Q are the equivalent p, d and q of the ARIMA model but are applied seasonally with the frequency *M*.

**Example:** If there is a yearly seasonal trend and the data is given monthly, **m** should be set to **12**. Seasonal trends can then be removed with **D = 1**, and if there is interdependence of the seasonal data we can for example also set **P=1** and/or **Q=1**.

We can identify if seasonal components are present by:

- ACF and PACF plots
- Seasonal subplots
- Intuition



# Let's practice!

## Notebooks:

- *SARIMA*

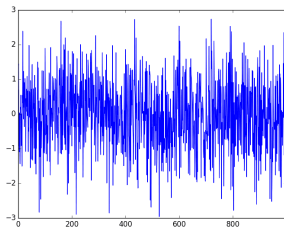
## Data:

- `champagne.csv`



To evaluate the fit of the applied model, we should:

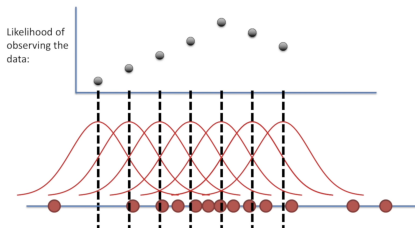
- examine the residuals: residuals should resemble **white noise** with a mean of 0.
- examine the forecast errors: MSE, MAE, ... (be wary of overfitting)
- examine the **likelihood** of the function
- examine **information criteria**: AIC and BIC (penalize overfitting by taking into account the amount of parameters)



Let's say we have:

- some observed data points (sample):  $x_1, x_2, x_3, \dots$
- a set of probability distributions (functions) which could have generated the data. A distribution is denoted by  $\theta$ .

The likelihood is a function  $L(\theta|x_1, x_2, x_3, \dots)$  that gives us the probability (likelihood) of observing the sample  $(x_1, x_2, x_3, \dots)$  when the data is extracted from the probability distribution  $\theta$ .



In order to choose the model orders  $(p,d,q)$  and evaluate the fit while taking into account the problem of **overfitting**, we can use the information criteria.

Each model has a log likelihood ( $l$ ), a number of parameters ( $k$ ) and a number of samples used for fitting ( $n$ ). Then we calculate:

- Akaike Information Criterion: **AIC** =  $2k - 2l$
- Bayesian Information Criterion: **BIC** =  $\log(n)k - 2l$

AIC and BIC are not exclusive to time series models but are also used to evaluate other models, particularly other machine learning models.

# Let's practice!

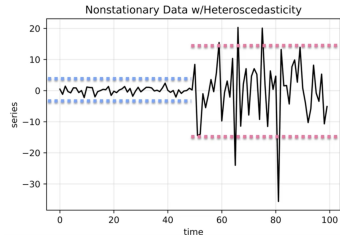
## Notebooks:

- *Model Selection*

## Data:

- `catfish.csv`

The SARIMA model with its transformations can handle time series data with trends (non-constant mean) and seasonality. But the models we have seen so far can not yet handle **heteroscedasticity** (non-constant/changing variance).



If we evaluate our model and the residuals do not resemble white noise but instead we can see different levels of variance, our model does not fit well. We need to use other models that take this into account.

The Autoregressive Conditional Heteroscedasticity (**ARCH**) model can deal with **heteroscedasticity** by taking into account past variances of the error terms.

The ARCH( $p$ ) model estimates the current error term by taking into account the past  $p$  (squared) error terms. An ARCH(2) model is denoted by:

$$\epsilon_t = w_t \sqrt{\alpha_0 + \alpha_1 \epsilon_{t-1}^2 + \alpha_2 \epsilon_{t-2}^2}$$

The Generalized Autoregressive Conditional Heteroscedasticity (**GARCH**) model extends the ARCH model by adding a moving average parameter (similar to ARMA compared to AR). GARCH is a better fit for modeling time series data when the data exhibits heteroscedasticity but also **volatility clustering**.

The GARCH( $p, q$ ) model estimates the current error term by taking into account the past  $p$  (squared) error terms and the past  $q$  variances. A GARCH(1,1) model is denoted by:

$$\sigma_t^2 = w + \alpha_0 + \alpha \epsilon_{t-1}^2 + \beta \sigma_{t-1}^2$$

GARCH models can only be applied to forecast the variance with conditional heteroscedasticity. Thus, the GARCH model **cannot predict negative values**.

We can try to transform the series accordingly to mimic volatility. For example: transform prices to returns and then square the returns to have only positive values.

We can also apply it to, for example, model the (squared) residuals after we applied another appropriate model (i.e. OLS, AR, ARMA, ...). If we see that residuals are not yet white noise but exhibit clustered volatility, the GARCH model can be a good fit to forecast the variance of the residuals and further improve our model.



The GARCH model has **many real world applications** that mostly require a forecast of volatility.

## Examples:

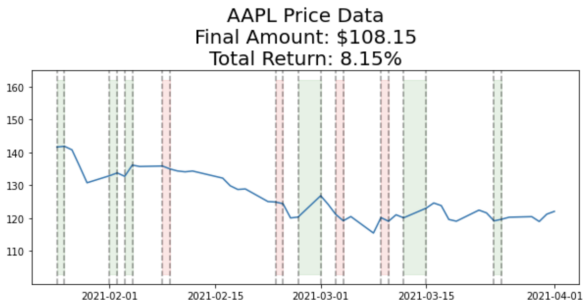
- Price volatility forecasting (stocks, commodities, forex, ...)
- Variance forecasting (inflation, interest rates, ...)
- Option pricing
- High frequency trading
- Risk modelling

# Let's practice!

## Notebooks:

- *GARCH SP500*

Let's use a time series model to predict prices and program an automated trading bot.



If we find a fitting model that can predict if a stock goes either **up** or **down** the next day with a consistent **accuracy above 50%**, we can make guaranteed profit.

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