BERT: Pre-training of Deep Bidirectional Transformers for Language Understanding





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- Methods
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Language Model Pre-training

- Language model pre-training has been shown to be effective for improving many NLP tasks
- Two existing strategies
 - -> feature-based (ELMo): pre-trained representations as additional features
 - -> fine-tuning (GPT): minimal task-specific parameters, simply fine-tuning

Limitations of Current Techniques

- Standard language models are unidirectional
 - -> ELMo: independently trained left-to-right and right-to-left LMs
 - -> GPT: left-to-right LMs
- Unidirectional model restrict the power of the pre-trained representation

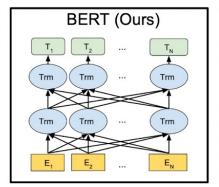
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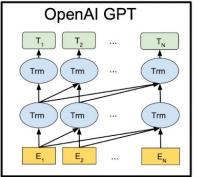
Goal

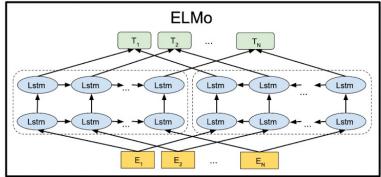
- Improve the fine-tuning based approaches
- Masked Language Model (MLM)
 - -> Randomly masks some of the input tokens and predict based on context
 - -> Allow to pre-train a deep bidirectional Transformer
- Next Sentence Prediction (NSP)

Comparison

Differences in Pre-training Model Architectures







- BERT: Bidirectional Transformer
- GPT: Left-to-right Transformer
- ELMo: Concatenation of left-to-right and right-to- left LSTM

Contributions

Contributions

- Demonstrate the importance of bidirectional pre-training
 - -> MLM enable pre-trained deep bidirectional representations
- First fine-tuning based model that achieves SOTA performance on a large suite of sentence-level and token-level tasks
 - -> Pre-trained representations reduce the need for heavy engineering

2 — Related Work

Unsupervised Feature-based Approaches

- Extracted feature is used as input to supervised training
- Word embeddings
 - -> Integral part of NLP, offering significant improvements
- ELMo
 - -> Extract context-sensitive features
 - -> Not deeply bidirectional(concatenation of left-to-right and right-to-left)

2. Related Work

Unsupervised Fine-tuning Approaches

- Use pre-train model and fine-tuning it
 - -> Few parameters need to be learned from scratch
- GPT
 - -> Left-to-right language modeling
 - -> Unidirectional

2. Related Work

3 — Methods

BERT Training Steps

- Pre-training
 - -> Training on unlabeled data
- Fine-tuning
 - -> BERT model is first initialized with the pre-trained parameters
 - -> Parameters are fine-tuned using labeled data from the downstream tasks

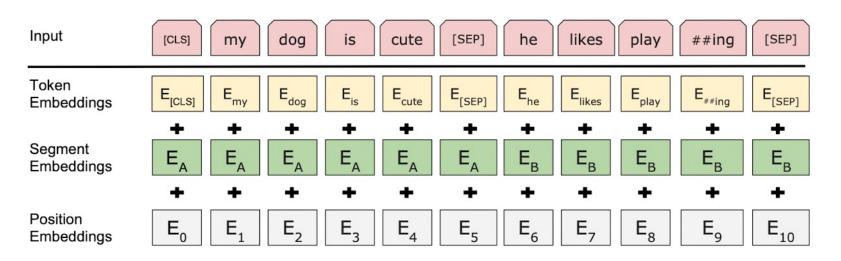
BERT Model Architecture

- Multi-layer bidirectional Transformer encoder based on Transformer
- Results on two model sizes
 - -> BERTBASE (L=12, H=768, A=12, Parameters=110M)
 - -> BERTLARGE (L=24, H=1024, A=16, Parameters=340M)
 - -> L: number of layers, H: hidden size, A: number of self-attention heads

Input Representations

- Input representation is able to represent both a single sentence and a pair of sentences in one token sequence
- A 'sequence' refers to the input token sequence to BERT, which may be a single sentence or two sentences packed together

Input Representations



Input embeddings are the sum of the token, segment, position embeddings.

Input Embeddings

- Token Embeddings
 - -> Represent each individual token in the input sentence
- Segment Embeddings
 - -> Differentiate between the two sentences in pair of sentences
- Position Embeddings
 - -> Represent the position of each word in input sentence

Token Embeddings

- WordPiece embeddings with a 30,000 token vocabulary
- First token of sequence is a special classification token [CLS]
 - -> Represent the entire sentence in a single vector
- Special token [SEP] separate a single sequence into sentence pairs
 - -> Represent the position of each word in input sentence

Training

- Pre-training
 - -> MLM, NSP
 - -> BooksCorpus, English Wikipedia
- Fine-tuning
 - -> Simply plug in the task-specific inputs into BERT
 - -> Only new parameters are classification layer weights

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- Some percentage of the input tokens is masked randomly
- Only predict the masked words
 - -> Final hidden vectors are fed into an output softmax
- Train a deep bidirectional representation

- 15% of tokens are masked at random in each sequence
 - -> 80% of token is replaced with [MASK]
 - -> 10% of token is replaced with random
 - -> 10% of token is unchanged
- Train a deep bidirectional representation

Ma	sking Ra	ates	Dev Set Results				
MASK SAME RND MNLI			MNLI	NER			
			Fine-tune	Fine-tune	Feature-based		
80%	10%	10%	84.2	95.4	94.9		
100%	0%	0%	84.3	94.9	94.0		
80%	0%	20%	84.1	95.2	94.6		
80%	20%	0%	84.4	95.2	94.7		
0%	20%	80%	83.7	94.8	94.6		
0%	0%	100%	83.6	94.9	94.6		

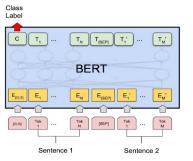
- Reduce the mismatch betweenpre-training and fine-tuning
- Introducing noise and forcing the model to generalize well
 - the context without difficulty of having to predict missing token

Next Sentence Prediction

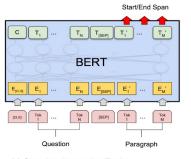
- Train a model to understand the relationship between two sentences
 - -> Can't directly trained by language modeling
- Pe-train for a binarized next sentence prediction task
 - -> Sentence A and B for each pre-training example
 - -> 50% of B is actual next sentence, and 50% of B is random sentence
- [CLS] token is used for next sentence prediction

Fine-tuning

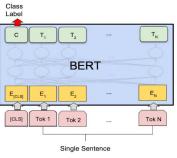
Fine-tuning



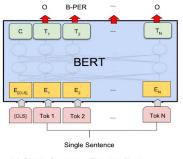
(a) Sentence Pair Classification Tasks: MNLI, QQP, QNLI, STS-B, MRPC, RTE. SWAG



(c) Question Answering Tasks: SQuAD v1.1



(b) Single Sentence Classification Tasks: SST-2. CoLA



(d) Single Sentence Tagging Tasks: CoNLL-2003 NER

- The type of input of the model
 and the output token depend on
 the task
- Single Sentence vs Sentence Pair
- [CLS] vs Word Tokens

4 Experiments

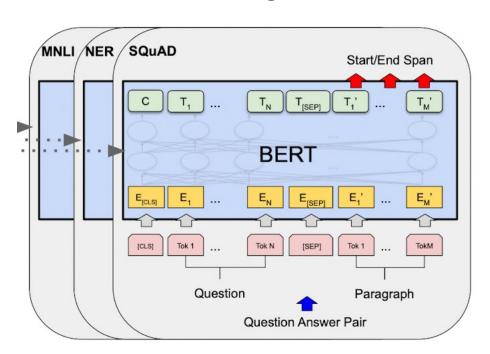
General Language Understanding Evaluation (GLUE)

System	MNLI-(m/mm)	QQP	QNLI	SST-2	CoLA	STS-B	MRPC	RTE	Average
	392k	363k	108k	67k	8.5k	5.7k	3.5k	2.5k	-
Pre-OpenAI SOTA	80.6/80.1	66.1	82.3	93.2	35.0	81.0	86.0	61.7	74.0
BiLSTM+ELMo+Attn	76.4/76.1	64.8	79.8	90.4	36.0	73.3	84.9	56.8	71.0
OpenAI GPT	82.1/81.4	70.3	87.4	91.3	45.4	80.0	82.3	56.0	75.1
BERT _{BASE}	84.6/83.4	71.2	90.5	93.5	52.1	85.8	88.9	66.4	79.6
$BERT_{LARGE}$	86.7/85.9	72.1	92.7	94.9	60.5	86.5	89.3	70.1	82.1

- Collection of diverse natural language understanding tasks
- BERTBASE and BERTLARGE outperform all systems on all tasks

4. Experiments

Question Answering



- Start vector: S, End vector: E
- Probability of word i being the
 start of the answer span is
 computed as dot-product between

Ti and S followed by a softmax

$$P_i = \frac{e^{S \cdot T_i}}{\sum_j e^{S \cdot T_j}}$$

- Score of candidate span from *i* to *j*

$$S \cdot T_i + E \cdot T_j$$

SQuAD v1.1

System	D	ev	Test		
,	EM	F1	EM	F1	
Top Leaderboard System	s (Dec	10th,	2018)		
Human		-	82.3	91.2	
#1 Ensemble - nlnet	-	-	86.0	91.7	
#2 Ensemble - QANet	-	-	84.5	90.5	
Publishe	ed				
BiDAF+ELMo (Single)	-	85.6	-	85.8	
R.M. Reader (Ensemble)	81.2	87.9	82.3	88.5	
Ours				100	
BERT _{BASE} (Single)	80.8	88.5	-	-	
BERT _{LARGE} (Single)	84.1	90.9	-1	-	
BERT _{LARGE} (Ensemble)	85.8	91.8	- :	-	
BERT _{LARGE} (Sgl.+TriviaQA)	84.2	91.1	85.1	91.8	
$BERT_{LARGE}$ (Ens.+TriviaQA)	86.2	92.2	87.4	93.2	

- Collection of 100k crowdsourced
 question/answer pairs
- Input question and passage are represented as singled sequence

4. Experiments

Benchmark

SQuAD v2.0

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System	D	Dev		Test	
	EM	F1	EM	F1	
Top Leaderboard System	ns (Dec	10th,	2018)		
Human	86.3	89.0	86.9	89.5	
#1 Single - MIR-MRC (F-Net	t) -	-1	74.8	78.0	
#2 Single - nlnet	-	-	74.2	77.1	
Publisl	ned				
unet (Ensemble)	-	-	71.4	74.9	
SLQA+ (Single)	-		71.4	74.4	
Our	S				
BERT _{LARGE} (Single)	78.7	81.9	80.0	83.1	

Allowing for the possibility that no answer exist

 Probability space for the start and end answer span positions include the position of the [CLS]

 Compare the score of the noanswer span (with threshold) with the best non-null span

4. Experiments

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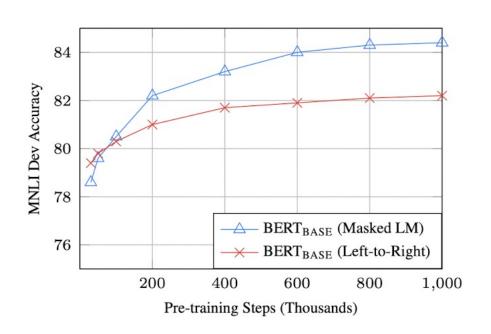
SWAG

System	Dev	Test
ESIM+GloVe	51.9	52.7
ESIM+ELMo	59.1	59.2
OpenAI GPT	-	78.0
BERT _{BASE}	81.6	-
$BERT_{LARGE}$	86.6	86.3
Human (expert) [†]	-	85.0
Human (5 annotations) [†]	-	88.0

 Given a sentence, task is to choose the most plausible continuation among four choices

 For fine-tuning, construct four input sequences, each containing the concatenation of given sentence and a possible continuation

Ablation Studies



 MNLI Dev accuracy after finetuning from a checkpoint that has been pre-trained for k steps

5. Ablation Studies

Effect of pre-training tasks

Next Sentence Prediction

	Dev Set						
Tasks	MNLI-m	QNLI	MRPC	SST-2	SQuAD		
	(Acc)	(Acc)	(Acc)	(Acc)	(F1)		
BERT _{BASE}	84.4	88.4	86.7	92.7	88.5		
No NSP	83.9	84.9	86.5	92.6	87.9		
LTR & No NSP	82.1	84.3	77.5	92.1	77.8		
+ BiLSTM	82.1	84.1	75.7	91.6	84.9		

- No NSP

-> Only MLM

- LTR & NO NSP

-> Only Left-to-Right LM (GPT)

5. Ablation Studies

Model Size

Hyperparams Dev Set Accuracy						
#L	#H	#A	LM (ppl)	MNLI-m	MRPC	SST-2
3	768	12	5.84	77.9	79.8	88.4
6	768	3	5.24	80.6	82.2	90.7
6	768	12	4.68	81.9	84.8	91.3
12	768	12	3.99	84.4	86.7	92.9
12	1024	16	3.54	85.7	86.9	93.3
24	1024	16	3.23	86.6	87.8	93.7

Demonstrate that scaling to
 extreme model sizes also leads to
 large improvements on very small
 scale tasks, provided that the model
 has been sufficiently pre-trained

5. Ablation Studies

6 — Conclusion

Summary

- Unsupervised pre-training is an integral part of many language understanding systems
- Major contribution is generalizing these findings to deep bidirectional architectures, allowing the same pre-trained model to successfully tackle a broad set of NLP tasks.

6. Conclusion



Thanks!

Any questions?