

## Formula Sheet

### 1. Vectors

$$\begin{aligned}\|\mathbf{v}\| &= \sqrt{v_1^2 + v_2^2 + v_3^2} \\ \mathbf{u} \cdot \mathbf{v} &= u_1v_1 + u_2v_2 + u_3v_3 = \|\mathbf{u}\|\|\mathbf{v}\|\cos\theta \\ \mathbf{u} \times \mathbf{v} &= \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \end{vmatrix}, \quad \|\mathbf{u} \times \mathbf{v}\| = \|\mathbf{u}\|\|\mathbf{v}\|\sin\theta \\ \text{proj}_{\mathbf{u}} \mathbf{v} &= \frac{\mathbf{v} \cdot \mathbf{u}}{\|\mathbf{u}\|^2} \mathbf{u}\end{aligned}$$

### 2. Lines and planes

If  $P = (x_0, y_0, z_0)$ , then:

- line through  $P$  with direction  $\mathbf{d}$ :  $\langle x, y, z \rangle = \langle x_0, y_0, z_0 \rangle + t\mathbf{d}$
- plane through  $P$  with normal  $\mathbf{n}$ :  $\mathbf{n} \cdot \langle x - x_0, y - y_0, z - z_0 \rangle = 0$

### 3. Vector functions

$$\begin{aligned}\mathbf{r}'(t) &= \frac{d}{dt} \langle x(t), y(t), z(t) \rangle = \langle x'(t), y'(t), z'(t) \rangle \\ \text{arc length} &= \int_a^b \|\mathbf{r}'(t)\| dt \\ \text{curvature} &= \frac{\|\mathbf{r}'(t) \times \mathbf{r}''(t)\|}{\|\mathbf{r}'(t)\|^3}\end{aligned}$$

### 4. Multivariable functions

#### Gradient and directional derivatives:

$$\begin{aligned}\nabla f &= \langle f_x, f_y, f_z \rangle \\ \nabla f &\text{ points in direction of fastest increase of } f \\ \nabla f &\text{ is orthogonal to the level surface} \\ D_{\mathbf{u}}f &= \nabla f \cdot \mathbf{u}\end{aligned}$$

#### Tangent planes:

- graph of  $f(x, y)$ :  $f_x(x_0, y_0)(x - x_0) + f_y(x_0, y_0)(y - y_0) - (z - f(x_0, y_0)) = 0$
- level surface  $F(x, y, z) = 0$ :  $\nabla F(x_0, y_0, z_0) \cdot \langle x - x_0, y - y_0, z - z_0 \rangle = 0$

**Chain rule:** If  $z = f(x, y)$  and  $x = g(s, t)$ ,  $y = h(s, t)$ , then

$$\frac{\partial z}{\partial s} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial s}, \quad \frac{\partial z}{\partial t} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial t}$$

### 5. Optimization

**Second derivative test:** Let  $f$  be a twice-differentiable function, and let

$$H_f = \begin{bmatrix} f_{xx} & f_{xy} \\ f_{yx} & f_{yy} \end{bmatrix}.$$

If  $\nabla f(x, y) = \mathbf{0}$ , then:

- (a)  $f$  has a relative maximum at  $(x, y)$  if  $\det(H_f(x, y)) > 0$  with  $f_{xx}(x, y) < 0$  or  $f_{yy}(x, y) < 0$ ;
- (b)  $f$  has a relative minimum at  $(x, y)$  if  $\det(H_f(x, y)) > 0$  with  $f_{xx}(x, y) > 0$  or  $f_{yy}(x, y) > 0$ ;
- (c)  $f$  has a saddle point at  $(x, y)$  if  $\det(H_f(x, y)) < 0$ ;
- (d) no conclusion may be drawn if  $\det(H_f(x, y)) = 0$ .

## 6. Double and triple integration

**Polar coordinates:**

$$x = r \cos \theta, \quad y = r \sin \theta, \quad dA = r dr d\theta$$

**Cylindrical coordinates:**

$$x = r \cos \theta, \quad y = r \sin \theta, \quad z = z, \quad dV = r dz dr d\theta$$

**Spherical coordinates:**

$$x = \rho \sin \phi \cos \theta, \quad y = \rho \sin \phi \sin \theta, \quad z = \rho \cos \phi, \quad dV = \rho^2 \sin(\phi) d\rho d\theta d\phi$$

## 7. Vector fields

**Line integrals:**

$$\int_C f ds = \int_a^b f(\mathbf{r}(t)) \|\mathbf{r}'(t)\| dt, \quad \int_C \mathbf{F} \cdot d\mathbf{r} = \int_a^b \mathbf{F}(\mathbf{r}(t)) \cdot \mathbf{r}'(t) dt$$

**Surface integrals:**

If  $\Sigma$  is parametrized by  $\mathbf{r}(s, t)$ :

$$\int_{\Sigma} f dS = \iint_R f(\mathbf{r}(s, t)) \|\mathbf{r}_s \times \mathbf{r}_t\| dA$$

If  $\Sigma$  is the graph of  $g(x, y)$ :

$$\int_{\Sigma} f dS = \iint_R f(x, y, g(x, y)) \sqrt{\|\nabla g\|^2 + 1} dA$$

Flux:

$$\int_{\Sigma} \mathbf{F} \cdot \mathbf{n} dS$$

**Curl and divergence:**

$$\operatorname{curl} \mathbf{F} = \nabla \times \mathbf{F}, \quad \operatorname{div} = \nabla \cdot \mathbf{F}$$

**Unit normal vector:**

- graph of  $g(x, y)$ :  $\mathbf{n} = \pm \frac{\langle -g_x, -g_y, 1 \rangle}{\sqrt{\|\nabla g\|^2 + 1}}$
- surface parametrized by  $\mathbf{r}(s, t)$ :  $\mathbf{n} = \pm \frac{\mathbf{r}_s \times \mathbf{r}_t}{\|\mathbf{r}_s \times \mathbf{r}_t\|}$