

# DIAGONALIZACIÓN DE MATRICES SIMÉTRICAS ( $A = A^T$ )

$$A = \begin{pmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 2 \end{pmatrix} \quad \lambda_1 = \lambda_2 = 1 \quad \lambda_3 = 4 \quad \text{autovalores}$$

$$\text{m.a.}(1) = 2 \quad \text{m.a.}(4) = 1$$

$$\lambda_1 = \lambda_2 = 1 \quad E_1 = \text{gen} \left\{ \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} \right\} \quad \text{mg}(1) = 2$$

$$\lambda_3 = 4 \quad E_4 = \text{gen} \left\{ \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right\} \quad \text{mg}(4) = 1 \quad B_{E_4} = \left\{ \begin{pmatrix} \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \end{pmatrix} \right\}$$

$$P = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ -1 & -1 & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 4 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ -1 & -1 & 1 \end{pmatrix}^{-1} \quad ; \quad A \text{ es diagonalizable.}$$

OBSERVACIONES:

$$\left\langle \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right\rangle = 0 \quad \left\langle \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right\rangle = 0 \quad \left\langle \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} \right\rangle \neq 0$$

$$v_1 = \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} \quad ; \quad v_2 = \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} - \frac{\left\langle \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right\rangle}{\left\langle \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right\rangle} \cdot \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} - \frac{1}{2} \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} = \begin{pmatrix} -\frac{1}{2} \\ 1 \\ -\frac{1}{2} \end{pmatrix}$$

$$B_{E_1} = \left\{ \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}, \begin{pmatrix} -\frac{1}{2} \\ 1 \\ -\frac{1}{2} \end{pmatrix} \right\} \quad ; \quad B_{E_4} = \left\{ \begin{pmatrix} \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \end{pmatrix}, \begin{pmatrix} -\frac{1}{\sqrt{6}} \\ \frac{2}{\sqrt{6}} \\ -\frac{1}{\sqrt{6}} \end{pmatrix} \right\}$$

$$\sqrt{\frac{1}{4} + 1 + \frac{1}{4}} = \sqrt{\frac{3}{2}} = \frac{\sqrt{6}}{2}$$

$$A = \underbrace{\begin{pmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{6}} & \frac{1}{\sqrt{3}} \\ 0 & \frac{2}{\sqrt{6}} & \frac{1}{\sqrt{3}} \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{3}} \end{pmatrix}}_{Q \text{ es ortogonal}} \cdot \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 4 \end{pmatrix} \cdot \begin{pmatrix} \frac{1}{\sqrt{2}} & 0 & -\frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{6}} & \frac{2}{\sqrt{6}} & -\frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} \end{pmatrix}$$

Q es ortogonal

$$Q^{-1} = Q^T$$

Diagonalización ortogonal.

PROP. 1: Los autov. de una matriz real simétrica son reales.

PROP. 2: Los autovectores de " " " asociados a autovalores distintos son ORTOGONALES

PROP. 3: Las matrices reales simétr. son diagonalizables siempre y admiten la diagonalización ortogonalmente.