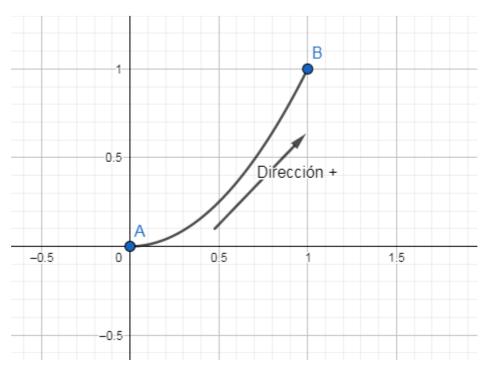
## Resolución TP8:

## Ejercicio 17-A-Modificado

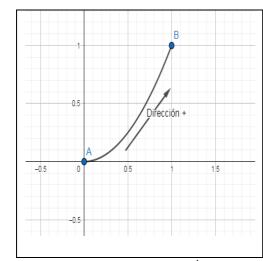
Sobre los campos conservativos (16-a, 16-d) verificar el resultado para la integral de línea para el recorrido:

$$\mathfrak{C}: \begin{cases} r(t) = (t, t^2) \\ 0 \le t \le 1 \end{cases}$$



Metodo I (Integración usual) -15-a

$$I = \int_{\mathfrak{C}} Fd\mathfrak{C} = \int_{t_0}^{t_f} F(r(t)) \cdot r'(t) dt$$



$$\mathbb{C}: \begin{cases} r(t) = (t, t^2) \\ 0 \le t \le 1 \end{cases}$$

$$F(x,y) = (2x + 2y, 2x + 2y)$$
  
$$F(r(t)) = (2t + 2t^2, 2t + 2t^2)$$

$$r'(t) = (1,2t)$$

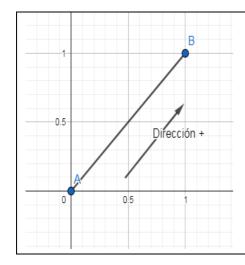
$$F(r(t)) \cdot r'(t) = 2t + 2t^2 + 4t^2 + 4t^3$$
  
$$F(r(t)) \cdot r'(t) = 2t + 6t^2 + 4t^3$$

$$I = \int_{\mathfrak{C}} F d\mathfrak{C} = \int_{t_0}^{t_f} F(r(t)) \cdot r'(t) dt = \int_{0}^{1} (2t + 6t^2 + 4t^3) dt$$

$$I = \int_{0}^{1} (2t + 6t^{2} + 4t^{3})dt = [t^{2} + 2t^{3} + t^{4}]_{0}^{1} = 4$$

Método II (Redefinir camino en un campo conservativo) -15-a

$$I = \int_{\mathfrak{C}} Fd\mathfrak{C} = \int_{t_0}^{t_f} F(r(t)) \cdot r'(t) dt$$



$$\mathfrak{C}: \begin{cases} r(t) = (t, t) \\ 0 \le t \le 1 \end{cases}$$

$$F(x,y) = (2x + 2y, 2x + 2y)$$
  
$$F(r(t)) = (2t + 2t, 2t + 2t) = (4t, 4t)$$

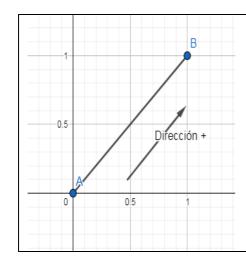
$$r'(t) = (1,1)$$

$$F(r(t)) \cdot r'(t) = 4t + 4t = 8t$$

$$I = \int_{\mathfrak{C}} F d\mathfrak{C} = \int_{t_0}^{t_f} F(r(t)) \cdot r'(t) dt = \int_{0}^{1} (8t) dt$$
$$I = \int_{0}^{1} (8t) dt = [4t^2]_{0}^{1} = 4$$

Método III (Método de función potencial) -15-a

$$F(x,y) = (2x + 2y, 2x + 2y) \rightarrow f(x,y) = x^2 + 2xy + y^2 + k$$



$$f(B) = f(1,1) = 1 \cdot 1^2 + 2 \cdot 1 \cdot 1 + 1 \cdot 1^2$$
  
$$f(B) = 4$$

$$f(A) = f(0,0) = 1 \cdot 0^2 + 2 \cdot 0 \cdot 0 + 1 \cdot 0^2$$
$$f(A) = 0$$

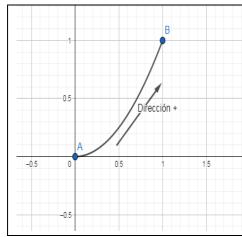
$$I = \int_{\mathbb{C}} Fd\mathfrak{C} = f(B) - f(A)$$

$$I = 4 - 0$$

$$I = 4$$

## Metodo I (Integración usual) -15-d

$$I = \int_{\mathfrak{C}} Fd\mathfrak{C} = \int_{t_0}^{t_f} F(r(t)) \cdot r'(t) dt$$



$$\mathfrak{C}: \begin{cases} r(t) = (t, t^2) \\ 0 \le t \le 1 \end{cases}$$

 $F(x,y) = (y - \pi y sen(\pi x y), x - \pi x sen(\pi x y))$  $F(r(t)) = (t^2 - \pi t^2 sen(\pi t^3), t - \pi t sen(\pi t^3))$ 

$$r'(t) = (1,2t)$$

 $F(r(t)) \cdot r'(t) = t^2 - \pi t^2 sen(\pi t^3) + 2t^2 - 2\pi t^2 sen(\pi t^3)$  $F(r(t)) \cdot r'(t) = 3t^2 - 3\pi t^2 sen(\pi t^3)$ 

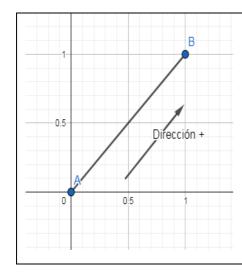
$$I = \int_{\mathfrak{C}} Fd\mathfrak{C} = \int_{t_0}^{t_f} F(r(t)) \cdot r'(t) dt = \int_{0}^{1} (3t^2 - 3\pi t^2 sen(\pi t^3)) dt$$

$$I = \int_{0}^{1} (3t^{2} - 3\pi t^{2} sen(\pi t^{3})) dt = [t^{3} + cos(\pi t^{3})]_{0}^{1}$$

$$I = [t^3 + \cos(\pi t^3)]_0^1 = \left(1 + \underbrace{\cos(\pi)}_{-1}\right) - \left(0 + \underbrace{\cos(0)}_{1}\right) = -1$$

Método II (Redefinir camino en un campo conservativo) -15-d

$$I = \int_{\mathfrak{C}} Fd\mathfrak{C} = \int_{t_0}^{t_f} F(r(t)) \cdot r'(t) dt$$



$$\mathfrak{C}: \begin{cases} r(t) = (t, t) \\ 0 \le t \le 1 \end{cases}$$

 $F(x,y) = (y - \pi y sen(\pi x y), x - \pi x sen(\pi x y))$  $F(r(t)) = (t - \pi t sen(\pi t^2), t - \pi t sen(\pi t^2))$ 

$$r'(t) = (1,1)$$

$$F(r(t)) \cdot r'(t) = t - \pi t sen(\pi t^2) + t - \pi t sen(\pi t^2)$$
  
$$F(r(t)) \cdot r'(t) = 2t - 2\pi t sen(\pi t^2)$$

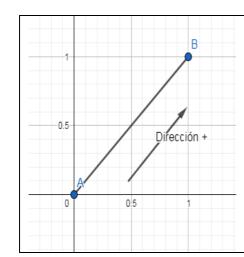
$$I = \int_{\mathfrak{C}} Fd\mathfrak{C} = \int_{t_0}^{t_f} F(r(t)) \cdot r'(t) dt = \int_{0}^{1} (2t - 2\pi t sen(\pi t^2)) dt$$

$$I = \int_{0}^{1} (2t - 2\pi t sen(\pi t^{2})) dt = [t^{2} + \cos(\pi t^{2})]_{0}^{1}$$

$$I = [t^2 + \cos(\pi t^2)]_0^1 = \left(1 + \underbrace{\cos(\pi)}_{-1}\right) - \left(0 + \underbrace{\cos(0)}_{1}\right) = -1$$

## Método III (Método de función potencial) -15-d

$$F(x,y) = (y - \pi y sen(\pi xy), x - \pi x sen(\pi xy)) \rightarrow f(x,y) = xy + \cos(\pi xy) + k$$



$$f(B) = f(1,1) = 1 \cdot 1 + \cos(\pi \cdot 1 \cdot 1)$$
  
$$f(B) = 1 - 1 = 0$$

$$f(A) = f(0,0) = 0 \cdot 0 + \cos (\pi \cdot 0 \cdot 0)$$
  
$$f(A) = 0 + 1 = 1$$

$$I = \int_{\mathbb{C}} Fd\mathfrak{C} = f(B) - f(A)$$
$$I = 0 - 1$$
$$I = -1$$