- Sensors:
 To check and measure distance between cars/obstacles in front, behind and alongside.
- Cameras:
 To provide 360° image of
 surroundings, pedestrians, traffic
 lights and other moving objects
- Batteries/Motors:
 Powers and drives the vehicle
- Interior:
 Intuitive display to present visual of sensor and radar data and GPS traffic data to support self-driving.
- CPU:
 Processes data from all sensors, radar,
 GPS etc to perform systematic and discreet processes as well as present to the interior display units for the passengers and vehicle automation.
- GPS:
 Gathers GPS data for calcualting distances, routes and traffic alerts.

