

ow/ in a newton slave

Right preconditioned

1. Construct new source  $\chi$  cross  $X$ 's

2. Perform initial sweep to produce  $b$

3. GMRES returns  $v^e$

3a. Perform DSA solve to approximate  $L^{-1}$ , i.e.

$$\psi^e = F^{-1} v^e, \quad F^{-1} \text{ is DSA matrix solve}$$

3b. Build scattering source based on  $\psi^e$ , call it  $S\phi_v^e$

3c. Sweep  $v^{e+1/2} = L^{-1} S\phi_v^e$  (no  $q$  here)

$$3d. v^{e+1} = (v^e - v^{e+1/2})$$

3e. GMRES computes new  $v^e$

$$4. \boxed{\psi = F^{-1} v}$$

1.-2 (same)

2a. Solve  $b^* = F^{-1} b$ , pass  $b^*$  to krylow

3. GMRES returns  $v^e$

3a. Build scattering source based on  $v^e$ , call it  $S\phi_v^e$

3b. Sweep  $v^{e+1/2} = L^{-1} S\phi_v^e$  (no  $q$  here)

$$3c. v^{e+2/3} = v^e - v^{e+1/2}$$

$$3d. v^{e+1} = F^{-1} v^{e+2/3}$$

$$4. \boxed{\psi = v}$$

# Preconditioned Krylov

## • GMRES for SZ:

$$L \tilde{y}^{(k+1)} = S \tilde{y}^{(k)} + Q$$

$$L \tilde{y}^{(k+1)} - M S D \tilde{y}^{(k)} = Q$$

$$(I - \underbrace{L^{-1} M S D}_{\text{sweep}}) \tilde{y} = L^{-1} Q$$

$$A \tilde{y} = b = L^{-1} Q$$

M: moment to discrete  
D: discrete to moment

initial pass to GMRES

## • Preconditioned Sam, want approximate inverse (right preconditioner)

$$(A \underbrace{F^{-1}}_Y) \underbrace{(F \tilde{y})}_Y = b$$

$$(A F^{-1}) V = b$$

• GMRES produces vector  $v^e$ . Solve

So  $F V = v^e$  for  $V$ , pass  $V$  to operator  $A$

• Apply  $A$  to  $V$  (i.e.,  $V - (\text{sweep on scattering source})$ ).

• Now just need to design full algorithm.

## • Left preconditioned:

$$(F^{-1} A) \tilde{y} = F^{-1} b$$

• Apply  $F^{-1}$  to  $b$  before passing to GMRES

• Solve  $F \tilde{V}^{(k+1)} = v^e$  after  $A$  has been applied

↑ DSA matrix