

# Sampling from tri-linear residual

- Usual expectation:

$$E[z(x)] = \int z(x) S(x) dx$$

$$E[\bar{z}] = \langle \bar{z} \rangle$$

- Estimator:  $\bar{z} = \frac{1}{N} \sum_{i=1}^N z_i(x)$

$$E[\bar{z}] = \frac{1}{N} \sum_{i=1}^N E[z_i(x)] = \frac{1}{N} \cdot N \langle z \rangle = \langle z \rangle$$

- Importance Sampling:

$$E[z(x)] = \int z(x) \left( \frac{S(x)}{S^*(x)} \right) S^*(x) dx$$

← same expectation as  $S(x) z(x)$

$$E[\bar{z}] = \frac{1}{N} \sum_{i=1}^N E\left[z(x) \left( \frac{S(x)}{S^*(x)} \right)\right] = \frac{1}{N} \cdot N \langle z \rangle = \langle z \rangle$$

- In residual MC, we compute  $z(x)$  and then multiply by  $\|r(x)\|_1$ . Lets say  $S(x) \neq \frac{r(x)}{\|r(x)\|_1} = \frac{r(x)}{R_1}$

- So:

$$\|r\|_1 \cdot E[z(x)] = \|r\|_1 \int z(x) S(x) dx = \int z(x) |r| S(x) dx$$

- In reality,  $r(x)$  has a  $\pm$  part, so we use a weight that is negative if  $r(x) < 0$

$$\|r\|_1 \cdot E[z(x)] = \|r\|_1 \int z(x) \left( \frac{S(x)}{|S(x)|} \right) |S(x)| dx$$

\* where  $|S(x)|$  is positive, not a norm.

$$= \|r\|_1 \int z(x) S(x) dx$$

• What if we just move  $w(x)$  inside weight

$$\|w\|_1 \cdot E[z(x)] \stackrel{?}{=} \int z(x) \left( \frac{w(x)}{|S(x)|} \right) |S(x)| dx \quad \text{No}$$

$$= \int z(x) \left( \frac{S(x) \cdot \|w\|_1}{|S(x)|} \right) |S(x)| dx$$

$$\checkmark = \|w\|_1 \int z(x) \left( \frac{S(x)}{|S(x)|} \right) |S(x)| dx$$

or